# Structural Measures for Games and Process Control in the Branch Learning Model

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#### Abstract

Process control problems can be modeled as closed recursive games. Learning strategies for such games is equivalent to the concept of learning infinite recursive branches for recursive trees. We use this branch learning model to measure the difficulty of learning and synthesizing process controllers. We also measure the difference between several process learning criteria, and their difference to controller synthesis. As measure we use the information content (i.e. the Turing degree) of the oracle which a machine need to get the desired power.

The investigated learning criteria are finite, EX-, BC-, Weak BCand online learning. Finite, EX- and BC-style learning are well known from inductive inference, while weak BC- and online learning came up with the new notion of branch (i.e. process) learning. For all considered criteria — including synthesis — we also solve the questions of their trivial degrees, their omniscient degrees and with some restrictions their inference degrees. While most of the results about finite, EX- and BC-style branch learning can be derived from inductive inference, new techniques had to be developed for online learning, weak BC-style learning and synthesis, and for the comparisons of all process learning criteria with the power of controller synthesis.

### 1 Introduction

Kummer and Ott [13] have developed a theoretical model of learning winning strategies for closed recursive games [7]. Closed recursive games are games of infinite duration and a special kind of Gale-Stewart games (see e.g. [28]). These kind of games are especially interesting since process control problems can be interpreted as such games [18, 27, 29]. The closed games correspond to the control problems with safety conditions, which say that the process may never reach a "bad" state [30]. An example of such a control problem is a temperature controller which has to hold the temperature in a room between  $t_{\min}$  and  $t_{\max}$ .

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Luzeaux, Martin and Zavidovique[17, 19, 20] have developed a different theoretical model of learning to control processes. An advantage of the game approach is that the setting can be shown to be equivalent to branch learning [13]. Here the learner has to find an infinite recursive branch of an infinite recursive tree. This yields a very easy model which allows a clearer theory. A further difference between the two models is that Kummer and Ott use the standard model of data input and the well known learning criteria from inductive inference while Luzeaux et al. introduce new settings for this.

The classical approach to process control is synthesis [8]: First, develop a complete mathematical model of the process. From this model compute the corresponding controller. The efforts to write chess programs, for example, can also be classified as a synthesis problem, since the rules of the game (i.e. a program for the game tree) are completely known in advance. The synthesis problem has also been investigated theoretically for infinite games, e.g. in [4, 12, 15, 21, 29]. This classical approach fails for the control problems appearing in modern applications from, for example, robotics and manufacturing [2, 16, 23, 31]: E.g. very often the tasks to be controlled are too complex or just not completely known (e.g. robots in unknown environment, a chemical plant where not everything is accessible to measurement or completely modeled,  $\ldots$ ) so that a complete mathematical model cannot be developed. Additionally, the synthesis of controllers only works well for more easy control problems. This has led to the application of machine learning techniques in process control [2, 22, 26, 31], taking into account that one can get more and more data over time about the processes to control.

Our concern is the theoretical foundation of these phenomena, i.e. the power of learning in process control, and the comparison of learning and controller synthesis. Here, the game model — or even better the more easy and equivalent branch learning model — allows a rigorous mathematical study of these phenomena. In recursion theoretic terminology controller synthesis is called *uniform computation* (*Uni*). In [13] it was shown that to uniformly compute and to (*EX*-)learn controllers are incomparable tasks. Moreover, there are processes for which one can learn controllers, but it is not possible to learn a complete model of the process, and vice versa. But how big is the gap between learning and uniform computation? Is there a possibility to measure the difference between these two constructive approaches?

In this paper we answer these questions in terms of oracle measures [9, 14]. Oracles improve the power of machines. Which information content do oracles need such the oracle learning machines capture uniform computation, and vice versa? The information content of a oracle is just it's Turing degree. We study this question for different learning criteria: finite (FIN-), EX-, BC- and Weak BC- (WBC-) style learning. The above are offline versions of learning, i.e. the learner outputs programs intended to control a process. We also study an online version of process learning — introduced in [13] — in which the learning machine directly outputs control actions.

Besides the comparison of different criteria — like uniform computation versus learning, or offline versus online learning — we also investigate the classical question of oracle learning: which oracles are trivial, i.e., which oracles do not help; which oracles are omniscient, i.e., which allow to find an infinite recursive branch on every tree which has one; how do the inference degrees look like, i.e., for which A and B does  $Crit[A] \subseteq Crit[B]$  hold. (For the meaning of Crit[A]see the definitions below in this paper). Many learning criteria have direct counterparts in branch learning. The inference degrees of the counterparts of FIN and EX are very similar to the original ones. But this is already different at BC: BC has two counterparts (*BranchBC* and *BranchWBC*) and furthermore the inference-degrees of both are a very different from that of BC: Other than BC none of them has a low omniscient oracle and *BranchWBC* has even only recursive trivial oracles. The new criteria *BranchOnl* behaves similar as finite learning. For *Uni* and *BranchWBC* new techniques had to be developed to answer the above questions.

It is fundamental that uniform computation is not captured by learning, since the identity function is trivially computable, while it is one of the most fundamental problems of learning (namely, the  $REC \in Crit$ ? problem). This is confirmed by our results by giving exact oracle measures: We show for all learning criteria that if it is possible to capture uniform computation by using an oracle, then this oracle has to be very powerful: It is impossible for finite and online branch learning at all. For EX- and BC-style branch learning we need oracles which are omniscient for this branch learning criteria. And in the case of Weak BC-branch learning the oracles have to be omniscient for the class BC in the classical setting of learning functions.

On the other side EX-, BC- and WBC-learning are not included in uniform computation for more involved reasons. We will see that an  $\emptyset'$ -oracle, which is a whole Turing jump below the omniscient Uni-degree, suffice to capture EX and BC-style learning. Nevertheless, this also shows that the advantage of learning over computation can be measured to correspond to a whole Turing jump. And weak BC-learning is in fact so powerful, that the distance correspond to two Turing jumps, which means that only omniscient oracles give synthesizing machines as much power.

We have already mentioned the technical advantage of the branch learning model [13]. Therefore the body of this paper is written in the terminology of branch learning. The relation between branch, game and process learning is the following: game learning is just a mathematical model of process learning, and branch learning is equivalent to strategy learning for closed recursive games. The following figure shows the correspondence between the different notions:

Problem:	Process	Game	Tree
Solution:	Controller	Strategy	Branch

The problem of finding infinite recursive branches of recursive trees is of independent interest in recursion theory [7, 24]. In [11] it is studied to which extend (in the sense of so called k-selectors) infinite recursive branches of trees can be computed uniformly. This approach was combined with inductive inference in [5]. Here the learner receives input/output examples of f and as additional information an index of a tree T such that f is a branch of T.

#### 2 Notation and Definitions

The natural numbers are denoted by  $\omega$ . We identify sets  $A \subseteq \omega$  with their characteristic function. #A denotes the cardinality of  $A \subseteq \omega$ .

We are using an acceptable programming system  $\varphi_0, \varphi_1, \ldots$ ; the function computed by the *e*-th program within *s* steps is denoted by  $\varphi_{e,s}$ .  $W_e := dom(\varphi_e)$ is the *e*-th recursively enumerable set. We write  $W_{e,s}$  for  $dom(\varphi_{e,s}) \cap \{0, \ldots, s\}$ . *REC* is the set of all total recursive functions. Turing reducibility is denoted by  $\leq_T$ . If *A* is a set, then *A'* is the halting problem relative to *A*, that is  $\{e: \varphi_e^A(e) \downarrow\}$ . The halting problem  $\emptyset'$  is denoted by *K*. *A* is high iff  $K' \leq_T A'$ . *A* is low if  $A' \leq_T K$ . *A* is called *PA-complete* relative to *B* if every partial *B*-recursive 0, 1-valued function has a total *A*-recursive extension. For  $B \equiv_T \emptyset$ this is equivalent to the original definition which states that *A* is in the Turing degree of a complete extension of Peano Arithmetic (see [24]).

For strings  $\sigma, \tau \in \omega^*$ ,  $\sigma \leq \tau$  means that  $\sigma$  is an initial segment of  $\tau$ .  $|a_1 \dots a_n| = n$  denotes the length of a string  $a_1 \dots a_n \in \omega^*$ . Strings  $\sigma \in \omega^*$  are identified with their "code numbers" according to some fixed coding of  $\omega^*$ . Total Functions  $f: \omega \to \omega$  are identified with the infinite string  $f(0)f(1) \dots$ . We write  $f \upharpoonright n$  for the string  $f(0) \dots f(n-1)$ .

 $T \subseteq \omega^*$  is a *tree* if T is closed under initial segments. If  $T \subseteq \{0,1\}^*$  then T is called a *binary* tree. Elements of a tree are called *nodes*. If  $M \subseteq \omega^* \cup \omega^{\omega}$ is a set of finite and infinite strings, then the prefix closure  $Pref(M) := \{\sigma \leq \alpha : \alpha \in M\}$  is a tree. We often will define trees by only specifying such a set  $M. \ \alpha \in \omega^{\omega}$  is an infinite branch of T, if  $\{\sigma : \sigma \leq \alpha\} \subseteq T$ . In this paper we are only interested in the class TREE of all recursive trees which have an infinite recursive branch. Note that according to our conventions an infinite recursive branch of T is just an recursive function f with  $\{f \mid n : n \in \omega\} \subseteq T$ .

The branch learning model in [13] uses binary trees. One can show that the theory remains the same if it is based on recursive trees over  $\omega$ :

**Theorem 2.1.** For all criteria  $Crit_1, Crit_2$  which we consider in this paper and all oracles A, B, if  $Crit_1[A] \not\subseteq Crit_2[B]$ , then there is a class of recursive binary trees witnessing this fact.

The proof will be given in Section 8. Since we have discovered that it makes the proofs in this paper more simple, we base the definitions on arbitrary trees.

EX, FIN, and BC denote the classes of sets  $S \subseteq REC$  which are identifiable by explanation, finitely identifiable by explanation and behaviorally correctly identifiable, respectively. The exact definitions for the different learning criteria are the direct counterparts to those given shortly in the context of branch learning. For background from inductive inference see e.g. [3, 9, 10, 25]. Remaining recursion theoretic notation is from [24].

#### 3 Finite and Online Branch Learning

At first we define the notion of branch learning machines [13]. In the world of process control you may think of a learner which has two copies of the process

to control. The first one is for experimentation  $(P_E)$  the second for application of the guessed controllers. We are considering machines without time and space bounds. Therefore we can assume that the machine may in the limit try all possible action sequences infinitely often on  $P_E$ . A sensor signals the respond of  $P_e$  to the learner.  $P_E$  may respond in different ways on the same action sequence due to indeterminism or disturbance by the environment. As a kind of fairness condition we assume that as long as there are possible respond sequences these will eventually appear. As a consequence we can assume that the learner gets an enumeration of all action/respond-sequences as input.

This assumption may seem a little bit strong, since the learner gets in the limit the whole information about the process. But note that the main content of our theorems is that something is *not* learnable. Thus, the significance of these results even grow if we base them on this strong input model.

While games such as chess and Go have finite game trees, these game trees are too large for exhaustive search. Thus, one has to come up with a strategy by only inspecting some part of the game tree. Similarly, the following definitions fix the question whether one can find a controller by only inspecting a finite amount of the process' behaviour (i.e. the corresponding infinite game tree).

We emphasize again that by the equivalence theorems in [13] in the following definitions the infinite recursive trees correspond to control problems (or infinite games), and the infinite recursive branches to the correct controllers (or winning strategies).

**Definition 3.1.** As learner we consider Turing machines  $M^A$  which have access to an oracle A and converge for every oracle and every input. These machines are intended to learn an infinite recursive branch of a tree  $T \in TREE$ . As input we feed the characteristic function of T into  $M^A$  such that  $M^A$  outputs a sequence of guesses  $h_0h_1...$ , where each  $h_n$  is computed from  $f \upharpoonright n$ , i.e.,  $h_n = M^A(T \upharpoonright n)$ . The guesses  $h_n$  should describe some infinite recursive branch of T according to the given learning criterion. The machine may also output a special symbol "?" to indicate that it has yet not seen enough data to make up its mind.

In the offline versions of branch learning (e.g. BranchFin below) the output of the learner is interpreted as a program for an infinite recursive branch of T, while in the online version the output is directly interpreted as nodes of an infinite recursive branch of T:

**Definition 3.2.**  $M^A$  finitely A-branch learns a tree T if on input T the machine  $M^A$  produces a sequence of guesses ?...?eee... such that  $\varphi_e$  is an infinite recursive branch of T.

A class of trees  $\mathcal{C}$  is finitely A-branch learnable  $(\mathcal{C} \in BranchFin[A])$  if there is a machine  $M^A$  which finitely branch learns every  $T \in \mathcal{C}$ .

We write BranchFin for  $BranchFin[\emptyset]$ . Analogously, for the other criteria considered in this paper we write Crit instead of  $Crit[\emptyset]$ .

**Definition 3.3.**  $M^A$  online A-branch learns a tree T if on input T the machine  $M^A$  produces a sequence of guesses  $? \dots ?b_0? \dots ?b_1? \dots$  such that  $b_0b_1 \dots$  is an

infinite recursive branch of T. We will say that the machine *enumerates* the branch  $b_0b_1...$ 

A class of trees  $\mathcal{C}$  is finitely A-online learnable  $(\mathcal{C} \in BranchOnl[A])$  if there is a machine  $M^A$  which online branch learns every  $T \in \mathcal{C}$ .

The following observation holds for all criteria which we consider in this paper, since queries to an oracle A can be simulated by any oracle  $B \ge_T A$ . But we only state it explicitly for *BranchOnl*:

**Fact 3.4.**  $A \leq_T B \implies BranchOnl[A] \subseteq BranchOnl[B].$ 

From [13] we know that  $BranchFin \subset BranchOnl$ . The following theorems show that this relation relativizes. This also indicates that online learning behaves in some sense similar as finite learning.

**Theorem 3.5.**  $BranchFin[A] \subseteq BranchOnl[B] \iff A \leq_T B$ .

*Proof.* Assume  $A \leq_T B$  and  $C \in BranchFin[A]$  via  $M^A$ . Then the following procedure online A-branch learns every  $T \in C$  which implies  $C \in BranchFin[B]$  by Fact 3.4:

On input  $T \upharpoonright 0, T \upharpoonright 1, \ldots$  wait until  $M^A$  outputs it's first real guess e. Then enumerate the branch  $\varphi_e$ .

For the other direction consider the class of trees

 $\mathcal{C} := \{ xT \colon T \in TREE \land A(x)^{\omega} \text{ is an infinite branch of } T \}.$ 

Clearly,  $\mathcal{C} \in BranchFin[A]$ : Having seen x output a program for  $xA(x)^{\omega}$ . Now assume that  $\mathcal{C}$  is in BranchOnl[B] via  $M^B$ . We claim that the following procedure decides A in B:

On input x apply the tree  $T := x(0^{\omega} + 1^{\omega})$  to  $M^B$ . Wait until  $M^B$  enumerates the second node  $b_1$ . Output  $b_1$ .

Since  $T \in \mathcal{C}$  the machine  $M^B$  will eventually enumerate a second node  $b_1$ . Then the output  $b_1$  is correct, i.e.  $b_1 = A(x)$ : Otherwise  $M^B$  would fail on some tree  $x((1 - A(x))^n + A(x)^\omega)$  which is in  $\mathcal{C}$ .

From Theorem 3.5 it follows that the *BranchFin* and *BranchOnl* inference degrees coincide with the Turing degrees:

**Corollary 3.6.**  $A \leq_T B \iff BranchFin[A] \subseteq BranchFin[B] \iff BranchOnl[A] \subseteq BranchOnl[B]$ 

*Proof.* If  $BranchFin[A] \subseteq BranchFin[B]$  or  $BranchOnl[A] \subseteq BranchOnl[B]$ then  $BranchFin[A] \subseteq BranchOnl[B]$  by Theorem 3.5 and again by Theorem 3.5 we get  $A \leq_T B$ . The other implications follow from Fact 3.4.

Thus, the trivial degree of *BranchFin* and *BranchOnl* is the degree of  $\emptyset$ .

In contrast to Theorem 3.5 there is no oracle A such that BranchFin[A] captures BranchOnl. This demonstrates that besides some similarities online learning is still a much more powerful concept than finite learning:

**Definition 3.7.** For  $f \in REC$  let  $T_f := \{f(0)f(1)...\}$  be the tree which consists exactly of the infinite branch f.

**Theorem 3.8.** BranchOnl  $\not\subseteq$  BranchFin[A] for all  $A \subseteq \omega$ .

*Proof.* The theorem follows from inductive inference since  $\{T_f : f \in REC\}$  is in *BranchOnl*: Given  $T \upharpoonright (n + 1)$  such that *n* codes the string  $b_0 \ldots b_k$ , enumerate  $b_k$  if T(n) = 1, otherwise enumerate "?". But from  $\{T_f : f \in REC\} \in$ *BranchFin*[A] it follows that  $REC \in FIN[A]$  which is known to be impossible.

As a corollary from Theorem 3.8 it follows that *BranchFin* has no omniscient degree.

## 4 Uniform computation

In this section we study the synthesis of controllers from complete models of the processes:

**Definition 4.1.** Infinite recursive branches can be *computed uniformly in A* for a class  $C \subseteq TREE$  ( $C \in Uni[A]$ ), if there is a partial A-recursive function g such that

 $(\forall e)(\forall T \in \mathcal{C})[T = \varphi_e \implies g(e) \downarrow \land \varphi_{g(e)} \text{ is an infinite branch of } T].$ 

In [13] it was shown that BranchOnl is strictly included in Uni. We now prove that it is impossible to overcome this gap by any oracle A. For the proof we introduce certain families of trees which we will use also later in this paper:

**Definition 4.2.** For  $f \in REC$  we define the tree

 $R_f := \{ef(e)a_0a_1 \dots a_n \colon (\forall m \le n)[a_m = \mu s[\varphi_{e,s}(m) \downarrow = f(m)]]\}.$ 

For  $S \subseteq REC$  we set  $\mathcal{B}(S) := \{R_f : f \in S\}$ . Note, that eb is in  $R_f$  iff b = f(e).

**Lemma 4.3.** For every f the tree  $R_f$  is recursive and has infinite recursive branches extending e iff  $\varphi_e = f$ . Indices for f,  $R_f$  and infinite recursive branches of  $R_f$  can be computed uniformly from each other. Moreover, enumerations of f and  $R_f$  can be translated effectively into each other, i.e., there are computable functions  $g_1, \ldots, g_4$  such that  $f(n) = g_1(R_f | g_2(n))$  and  $R_f(n) = g_3(f | g_4(n))$ .

**Theorem 4.4.** Uni  $\not\subseteq$  BranchOnl[A] for all  $A \subseteq \omega$ .

*Proof.* From Lemma 4.3 it follows that  $\mathcal{B}(REC)$  is in Uni. If  $\mathcal{B}(REC)$  were in *BranchOnl*[A] via  $M^A$  then *REC* would be in *FIN*[A] by the following algorithm, which yields a contradiction:

From the input f(0)f(1)... compute an enumeration of  $R_f$  and feed it into  $M^A$ . Wait until  $M^A$  enumerates the first node  $b_0$  of an infinite recursive branch of  $R_f$ . Output  $b_0$ .

By Lemma 4.3 the output  $b_0$  is an index of f.

Thus, like finite learning, *BranchOnl* also has no omniscient degree.

Compared to BranchFin[A] uniform computation behaves similar as online learning, at least for  $A \leq K$ :

**Theorem 4.5.** For all  $A \leq_T K$ : BranchFin $[A] \subseteq Uni[B] \iff A \leq_T B$ .

*Proof.* The proof of *BranchFin*  $\subseteq$  *Uni* in [13] relativizes for  $A \leq_T B$ .

So, it remains to show the only if part. Since  $A \leq_T K$ , by the Limit Lemma there exists a computable  $u: \omega^2 \to \omega$  such that  $A = \lambda x . \lim_{s \to \infty} u(x, s)$ . Consider the class  $\mathcal{C}$  of all trees  $T_x$  where

$$T_x := \{xia_0a_1 \dots a_n : i \in \{0, 1\} \land a_0 < a_1 < \dots < a_n \land (\forall m \le n)[u(x, a_m) = i]\}.$$

Obviously, C is in BranchFin[A]. Now assume  $C \in Uni[B]$  via some partial B-recursive function g. We choose an  $h \in REC$  with  $T_x = \varphi_{h(x)}$  for all x. Then  $\lambda x. \varphi_{g(h(x))}(1)$  decides A relative in B.

The omniscient degree of Uni has already been solved in [13]:

Fact 4.6.  $TREE \in Uni[A] \iff A \geq_T K'$ .

The more difficult part  $(\Rightarrow)$  follows also from Theorem 7.8 below.

A corollary of Theorem 4.5 is that the degree-structure of Uni below K coincides with the Turing degrees:

**Corollary 4.7.** If  $A \leq_T K$  then:  $Uni[A] \subseteq Uni[B] \iff A \leq_T B$ .

This result can even be strengthened as the following Theorems show:

**Theorem 4.8.** (1)  $Uni[A] = Uni \iff A$  recursive.

(2) If  $B \not\geq_T K$  then:  $Uni[A] \subseteq Uni[B] \iff A \leq_T B$ .

*Proof.* Since (1) follows from (2), we only have to prove (2):

 $(\Leftarrow)$ : Follows from Fact 3.4.

 $(\Rightarrow)$ : Since every Turing degree contains a retracable set, we assume w.l.o.g. that A is retracable. Now, to get  $A \leq_T B$  it suffices to show that A is r.e. in B. We set

$$T_{x,y} := \{xy0^s \colon y \notin K_s\} \cup \{xyz^\omega \colon z > 0 \land y \in K_z\}$$

and consider the class

$$\mathcal{C} := \{ T_{x,y} \colon (x \in A \land y \notin K) \lor (x \notin A \land y \in K) \}.$$

C is in Uni[A]:

From an index e of a tree  $T_{x,y} \in C$  first extract x and y. If  $x \in A$ then we know that  $y \notin K$ . Thus  $xy0^{\omega}$  is an infinite recursive branch of  $T_{x,y}$ . If  $x \notin A$  it follows  $y \in K$ . Then  $xyz^{\omega}$  with  $z = \mu s[y \in K_s]$ is an infinite recursive branch of  $T_{x,y}$ . Since  $Uni[A] \subseteq Uni[B]$  the class  $\mathcal{C}$  is also in Uni[B] via some (partial) machine  $M^B$ . We choose an computable  $h: \omega^2 \to \omega$  with  $(\forall x, y)[\varphi_{h(x,y)} = T_{x,y}]$ . Consider the set

$$X := \{x : (\exists s, y) [ y \in K_s \land xy0 \preceq \varphi_{M^B_s(h(x,y)),s}] \}$$

of all x such that for some  $y \in K$  the machine  $M^B$  on input  $T_{x,y}$  outputs a branch (or a partial function) beginning with xy0. X is recursively enumerable in B. We claim that A = X:

If  $x \notin A$  then for all  $y \in K$  the machine  $M^B$  will on input  $T_{x,y}$  output a branch beginning with xyz for some z > 0 since  $T_{x,y} \in \mathcal{C}$  and  $T_{x,y}$  has no infinite branch beginning with xy0. Therefore x is not in X. It follows that  $X \subseteq A$ .

Now let  $x \in A$ . Then for all  $y \notin K$  the machine  $M^B$  will on input  $T_{x,y}$ output a branch beginning with xy0 since  $T_{x,y} \in \mathcal{C}$  and  $xy0^{\omega}$  is the only infinite recursive branch of  $T_{x,y}$ . Assume that there is no  $y \in K$  such that  $M^B$  on input  $T_{x,y}$  outputs an i with  $xy0 \preceq \varphi_i$ . Then  $\overline{K} = \{y : (\exists s) [xy0 \preceq \varphi_{M_s^B(h(x,y)),s}]\}$  and thus  $\overline{K}$  is r.e. in B. Since K is r.e. it follows  $K \leq_T B$  which contradicts the assumption  $K \not\leq_T B$ . Hence, there is an  $y \in K$  with  $xy0 \preceq \varphi_{M^B(h(x,y))}$  which implies  $x \in X$ . We get  $A \subseteq X$  which completes the proof of A = X.

Thus, A is r.e. in B and, since A is retracable, A is in fact Turing reducible to B.

By using different trees the above proof can be adapted to cover the case  $A, B \geq_T K$ :

**Theorem 4.9.** For all  $A, B \ge_T K$ :  $Uni[A] \subseteq Uni[B] \iff A \le_T B$  or  $B \ge_T K'$ .

*Proof.* ( $\Leftarrow$ ): Follows from Fact 3.4 and Fact 4.6.

 $(\Rightarrow)$ : Assume that  $B \not\geq_T K'$  and w.l.o.g. that A is retracable. We define

$$\begin{split} T_{\text{fin}}^e &:= \{k^n \colon \#W_{e,n} < k\},\\ T_{\inf}^e &:= \{0a_0a_1 \dots a_n \colon (\forall m \le n) [\#W_e > m \land a_m = \mu s [\#W_{e,s} > m]]\},\\ T_e &:= T_{\text{fin}}^e \cup T_{\text{inf}}^e. \end{split}$$

 $T_{\text{fin}}^e$  has an infinite recursive branch iff  $W_e$  is finite and  $T_{\text{inf}}^e$  has an infinite branch iff  $W_e$  is infinite. Thus, all  $T_e$  have an infinite recursive branch. Moreover, if  $\beta$  is an infinite recursive branch of  $T_e$  then  $\beta(0) = 0$  iff  $W_e$  is infinite.

Set  $T_{x,y} := xyT_y$ . Fin := {e:  $W_e$  finite} and Inf := {e:  $W_e$  infinite} are the index sets of the finite and infinite r.e. sets, respectively. We consider the class

$$\mathcal{C} := \{ T_{x,y} \colon (x \in A \land y \in Fin) \lor (x \notin A \land y \in Inf) \}.$$

C is in Uni[A]:

From an index e of a tree  $T_{x,y} \in C$  first extract x and y. If  $x \in A$ then we know that  $y \in Fin$ . Since  $A \geq_T K$ , we can use a K-oracle to compute a number k with  $(\forall n) [\#W_{y,n} < k]$ . Then  $xyk^{\omega}$  is an infinite recursive branch of  $T_{x,y}$ . If  $x \notin A$  it follows that  $y \in Inf$ . Then  $xya_0a_1 \ldots$  with  $a_m = \mu s [\#W_{y,s} > m]$  for  $m = 0, 1, \ldots$  is an infinite recursive branch of  $T_{x,y}$ . Since  $Uni[A] \subseteq Uni[B]$  the class  $\mathcal{C}$  is also in Uni[B] via some (partial) machine  $M^B$ . We choose an computable  $h: \omega^2 \to \omega$  with  $(\forall x, y)[\varphi_{h(x,y)} = T_{x,y}]$ . Since Fin is r.e. in K there is a B-recursive approximation  $(Fin_s)_{s\in\omega}$  of Fin. Consider the set

$$X := \{x \colon (\exists s, y) [ y \in Fin_s \land xy0 \preceq \varphi_{M^B_s(h(x,y)),s}] \}$$

of all x such that for some  $y \in Fin$  the machine  $M^B$  on input  $T_{x,y}$  outputs a branch (or a partial function) beginning with xy0. X is recursively enumerable in B. We claim that A = X:

If  $x \notin A$  then for all  $y \in Fin$  the machine  $M^B$  will on input  $T_{x,y}$  output a branch beginning with xyk for some k > 0 since  $T_{x,y} \in \mathcal{C}$  and  $T_{x,y}$  has no infinite branch beginning with xy0. Therefore x is not in X. It follows that  $X \subseteq A$ .

Now let  $x \in A$ . Then for all  $y \in Inf$  the machine  $M^B$  will on input  $T_{x,y}$ output a branch beginning with xy0 since  $T_{x,y} \in C$  and  $xy0^{\omega}$  is the only infinite recursive branch of  $T_{x,y}$ . Assume that there is no  $y \in Fin$  such that  $M^B$  on input  $T_{x,y}$  outputs an i with  $xy0 \leq \varphi_i$ . Then  $Inf = \{y : (\exists s)[xy0 \leq \varphi_{M_s^B(h(x,y)),s}]\}$ which implies that Inf is r.e. in B. Since Fin is r.e. in K, and thus r.e. in B, it follows  $K' \equiv Inf \leq_T B$  which contradicts the assumption  $K' \not\leq_T B$ . Hence, there is an  $y \in K$  with  $xy0 \leq \varphi_{M^B(h(x,y))}$  which implies  $x \in X$ . We get  $A \subseteq X$ which completes the proof of A = X.

Thus, A is r.e. in B and, since A is retracable, A is in fact Turing reducible to B.

In summary, except the case  $(A|_T K \land B \ge_T K)$ , we were able to prove that  $Uni[A] \subseteq Uni[B]$  iff  $A \le_T B$  or  $B \ge_T K'$ . The following theorem shows that this proposition indeed does not hold for arbitrary A, B:

**Theorem 4.10.** There are oracles A and B not above K' such that  $Uni[A] \subseteq Uni[B]$  but  $A \not\leq_T B$ . In fact, even  $A \not\leq_T B'$  can be achieved.

*Proof.* There are uncountably many Turing degrees above K which are hyperimmune-free relative to K, i.e., every total function computed relative to such a degree is dominated by a total function computable relative to K. Thus there is some oracle A' which is hyperimmune-free relative to K but is not below K''. A' is (Turing equivalent to) the jump of some oracle A by the jump inversion Theorem [24, Theorem V.2.24]; moreover, this A can be chosen such that  $A' \equiv_T A \oplus K$ . Thus,  $A \not\leq_T K''$  since otherwise  $A' \equiv_T A \oplus K \leq_T K''$ .

By an relativization of the Low Basis Theorem to K [24, Theorem V.5.32] there is an oracle B such that B is PA-complete relative to K and  $K <_T B <_T K'$ . Now these oracles A and B satisfy the required properties:

(i) A and B are not above K': K' and any degree above it are hyperimmune relative to K; thus  $A \geq_T K$ . Furthermore  $B \geq_T K'$  by the choice of B.

(ii)  $A \not\leq_T B$ : This also follows from the choice of A and B. A is not below K'' by the choice of A and since  $B \leq_T K'$ , A is not below B and also not below B'.

(iii)  $Uni[A] \subseteq Uni[B]$ : Let  $\mathcal{C} \in Uni[A]$  via a partial A-recursive function. Then this function has a total extension f relative to A'. By the choice of A', f has a K-recursive majorant g. Thus, every tree  $T \in \mathcal{C}$  given as  $\varphi_e$  has an infinite branch with an index below g(e). Now let

$$h(i,s) = \max\{x : (\forall y < x) [\varphi_{i,s}(y) \downarrow] \land \varphi_i \upharpoonright x \in \varphi_e\}.$$

Note that  $\varphi_i$  is an infinite branch of T iff h(i, s) converges to  $\infty$  for  $s \to \infty$ . Since B is PA-complete in K, the oracle B has an algorithm B(e, j) which solves the following problem:

B(e, j) outputs always a number  $i \leq j$  such that h(i, s) converges to  $\infty$  whenever some index below j has this property.

So B(e, j) finds always an index of some infinite branch of T whenever this tree has such a branch with index below j. Taking now B(e, g(e)), this algorithm outputs an index for an infinite branch of  $\varphi_e$  whenever some index below g(e)identifies such a branch — and this is true for all trees  $\varphi_e \in S$ . Thus,  $S \in Uni[B]$ and  $Uni[A] \subseteq Uni[B]$ .

From Theorems 3.5 and 4.5 we get:

**Corollary 4.11.** For all  $A \leq_T K$ : BranchOnl[A]  $\subseteq$  Uni[B]  $\implies A \leq_T B$ .

We will now show that the other direction in Corollary 4.5 does not hold in general, i.e. that the inclusion  $BranchOnl \subseteq Uni$  from [13] does not relativize. The intuitive reason is that the Uni-machine can only ask finitely many queries to its oracle while the BranchOnl-machine may ask infinitely many queries during the enumeration of a branch.

**Theorem 4.12.** For all PA-complete A: BranchOnl[A]  $\subseteq$  Uni[B]  $\iff$   $K' \leq_T B$ , i.e. TREE  $\in$  Uni[B].

*Proof.* Kummer and Stephan [14] have constructed a family of 0, 1-valued functions  $\{\varphi_{q(i)}\}_{i \in \omega}$   $(g \in REC)$  such that

- $1^{i}0 \leq \varphi_{g(i)},$
- $\varphi_{q(i)}(x)$  is undefined for at most one x,
- if  $W_i$  is finite and  $\varphi_e$  is a total extension of  $\varphi_{g(i)}$  then  $e \ge \#W_i$ .

For every *i* we define a recursive *binary* tree  $T_i$  according to

$$T_i := \{a_0 \dots a_n \colon 1^i 0 \preceq a_0 \dots a_n \land (\forall m \leq n) [\neg (\varphi_{q(i),n}(m) \downarrow \neq a_m)] \}.$$

Note that the only infinite recursive branches of  $T_i$  are the total recursive 0, 1-valued extensions of  $\varphi_{q(i)}$ .

Consider the recursive function  $f(i, \sigma)$  which checks simultaneously whether the subtrees above  $\sigma 0$  or  $\sigma 1$  in  $T_i$  are finite and outputs (1-j) if it detects first that the subtree above  $\sigma j$  is finite for  $j \in \{0, 1\}$ .  $f(i, \sigma)$  is undefined if none of the two subtrees is finite. Since A is PA-complete there is a 0, 1-valued A-recursive extension h of  $f(i, \sigma)$ . Thus, we have for all  $\sigma$ :

 $\{\tau \in T_i : \sigma \preceq \tau\}$  infinite  $\implies \{\tau \in T_i : \sigma h(i, \sigma) \preceq \tau\}$  infinite.

Now,  $C := \{T_i : i \in \omega\}$  is in BranchOnl[A] via a machine  $M^A$  which simply follows the A-recursive function h after it has decoded i from the beginning of the input tree.

Assume now that C is in Uni[B] via some partial *B*-recursive function  $\psi$ . Then the index set  $Inf := \{i \in \omega : W_i \text{ infinite}\}$  is r.e. in *B*, since  $Inf = \{i : (\exists s) [\#W_{i,s} > \psi(u(i))]\}$  where  $u \in REC$  with  $(\forall i) [T_i = \varphi_{u(i)}]$ . Note, that  $range(u) \subseteq dom(\psi)$ . If  $W_i$  is infinite then clearly there is an *s* with  $\#W_{i,s} > \psi(u(i))$ . And if there exists an *s* with  $\#W_{i,s} > \psi(u(i))$  then  $W_i$  must be infinite since  $\varphi_{\psi(u(i))}$  is a total extension of  $\varphi_{q(i)}$ .

It remains to show that  $Fin = \{i : W_i \text{ finite}\}$  — the complement of Inf — is also r.e. in B. It is well known that Fin is r.e. in K. Therefore it suffices to prove  $K \leq_T B$ .

Let  $W_{v(x)} := \{s \colon x \notin K_s\} \ (v \in REC)$ . Then for all x the Uni[B]-procedure  $\psi$  computes an index  $e := \psi(u(v(x)))$  for an infinite recursive branch of  $T_{v(x)}$  with:

 $x \in K \iff W_{v(x)}$  finite  $\iff \#W_{v(x)} \le e \iff x \in K_e$ .

# 5 Uniform Computation via Total Functions

In the definition of Uni[A] (Definition 4.1) we allowed the uniform computation procedure to be partial, i.e. the procedure may not converge on inputs which are not indices for a tree in the class under consideration. Certainly, this is a natural approach since it abstracts from strange inputs. Actually, for the class Uni (i.e. A recursive) there is no difference if we require that the uniform computation procedures should be total. In this case, every uniform computation procedure is simply a computable program transformation, which can always be made total by using, e.g., the  $S_n^m$ -Theorem. But for non-recursive oracles the two notions does not coincide as we will see shortly. We also give further examples in this section which show that the variant of Uni, where the uniform computation procedures are required to be total, behaves very differently than Uni.

**Definition 5.1.**  $C \subseteq TREE$  is in TUni[A] if  $C \in Uni[A]$  via some total A-recursive function.

Let us first write down some simple observations:

Fact 5.2. (1)  $TUni[A] \subseteq Uni[A]$ ,

- (2) TUni = Uni,
- (3)  $Uni[A] \subseteq TUni[A'].$

(3) holds since for every partial A-recursive function g one can check relative in A' whether  $g(e) \downarrow$ .

The following theorem shows that the omniscient degree of TUni is one Turing jump higher than that of Uni:

**Theorem 5.3.**  $TREE \in TUni[A] \iff A \geq_T K''$ .

*Proof.* ( $\Leftarrow$ ): By Fact 4.6 the class *TREE* is in Uni[K'] via some partial function  $f \leq_T K'$ . We set

$$g := \lambda e. \begin{cases} 0 & \text{if } f(e) \uparrow, \\ f(e) & \text{otherwise.} \end{cases}$$

Then, g is total, recursive in K'' and g uniformly computes infinite recursive branches for *TREE*.

 $(\Rightarrow)$ : Define

$$T_e := \{ka_0 \dots a_n : (\forall m \le n) [a_m = \mu s[\{k, \dots, k+m\} \in W_{e,s}]]\}.$$

 $T_e$  contains infinite recursive branches iff  $W_e$  is cofinite. Moreover, if  $\beta \in REC$ is an infinite branch of  $T_e$  then  $\max \overline{W_e} < \beta(0)$ . It follows that  $\mathcal{C} := \{T_e : W_e \text{ cofinite}\}$  is a subclass of *TREE*. Assume, that *TREE*  $\in$  *TUni*[*A*] via the total function  $f \leq_T A$ . Then, we have also  $\mathcal{C} \in TUni[A]$  via f. Define  $g \in REC$  according to  $\varphi_{g(k)} := \lambda m . \mu s[\{k, \ldots, k+m\} \in W_{e,s}]$ . Thus,  $\max \overline{W_e} < k$  iff  $\varphi_{g(k)}$  is total. We choose an  $h \in REC$  with  $(\forall e)[\varphi_{u(e)} = T_e]$ . Now, if  $W_e$  is cofinite then  $\varphi_{f(u(e))}$  is an infinite recursive branch of  $T_e$ , thus,  $k := \varphi_{f(u(e))}(0)$  is defined and  $\varphi_{g(k)}$  is total. Otherwise, if  $W_e$  is coinfinite then either  $k := \varphi_{f(u(e))}(0)$  is undefined or, if it is defined, then  $\varphi_{g(k)}$  is not total. At all we get

$$(\forall e)[W_e \text{ is cofinite } \iff k \coloneqq \varphi_{f(u(e))}(0) \text{ is defined and } \varphi_{g(k)} \text{ is total.}]$$

The test on the right side is recursive in  $A \oplus K'$ . Note, that we use the totality of f here. But K' is Turing reducible to A by Fact 4.6, since *TREE* is also in Uni[A] via f, i.e.  $A \oplus K' \equiv_T A$ . At all we get  $K'' \equiv_T \{e : W_e \text{ cofinite}\} \leq_T A \oplus K' \equiv_T A$ .

It follows from Theorem 5.3 that  $Uni[K'] \not\subseteq TUni[K']$ . The corresponding result also holds for the oracle K:

**Theorem 5.4.**  $Uni[K] \not\subseteq TUni[K]$ .

*Proof.* Let  $f \leq_T K$  be a partial 0,1-valued function which has no total K-recursive extension. Since f is partial recursive in K, by the Limit Lemma there is a total recursive  $h: \omega^2 \to \omega$  with  $f = \lambda x . \lim_{s \to \infty} h(x, s)$  and a so called modulus function  $m \leq_T K$  satisfying  $(\forall s \geq m(x))[h(x, s) = f(x)]$ . Let

$$T_x := \{x \, i \, k^n \colon i \in \{0, 1\} \land (\forall m \le n) [h(x, k+m) = i]\}.$$

For all  $x \in dom(f)$  the tree  $T_x$  has an infinite recursive branch  $\beta \succeq xi$  iff i = f(x). We set  $\mathcal{C} := \{T_x : x \in dom(f)\}$ . Since  $xf(x)m(x)^{\omega}$  is an infinite recursive branch of  $T_x$  for all  $x \in dom(f)$ , the class  $\mathcal{C}$  is in Uni[K].

Assume now that  $\mathcal{C} \in TUni[K]$  via some total function  $g \leq_T K$ . Let  $h \in REC$  with  $(\forall x)[\varphi_{h(x)} = T_x]$  be given. Consider the function

$$F := \lambda x. \begin{cases} \varphi_{g(h(x))}(1) & \text{if } \varphi_{g(h(x))}(1) \downarrow, \\ 0 & \text{otherwise.} \end{cases}$$

Since g is total, the test whether  $\varphi_{g(h(x))}(1)$  is defined is recursive in K. Thus, F is a total K-recursive function. If  $x \in dom(f)$  then  $\varphi_{g(h(x))}$  is an infinite recursive branch of  $T_x$  which implies  $\varphi_{g(h(x))}(1) \downarrow = f(x)$ . I.e. F is a total K-recursive extension of f, which is a contradiction.

Note that Uni[K''] = Uni[K'] while  $TUni[K''] \not\subseteq TUni[K']$ . Furthermore, Theorem 4.10 generalizes to TUni since it actually shows that TUni[A'] is contained in TUni[B]. Thus it provides a counterexample to a generalization of Theorem 4.9 to TUni. So the following holds:

**Theorem 5.5.** The structures " $Uni[A] \subseteq Uni[B]$ " and " $TUni[A] \subseteq TUni[B]$ " are incomparable: There are  $A_1, B_1$  with  $Uni[A_1] \subseteq Uni[B_1]$ ,  $TUni[A_1] \not\subseteq$  $TUni[B_1]$  and  $A_2, B_2$  with  $Uni[A_2] \not\subseteq Uni[B_2]$  and  $TUni[A_2] \subseteq TUni[B_2]$ .

Nevertheless, Theorem 4.8 can be generalized to TUni:

**Theorem 5.6.** (1)  $TUni[A] = TUni \iff A$  recursive.

(2) If  $B \not\geq_T K$  then:  $TUni[A] \subseteq TUni[B] \iff A \leq_T B$ .

Sketch of proof. If  $x \ge 1$  we write  $\overline{\log}(x)$  for the unique *n* with  $2^n \le x < 2^{n+1}$ . Adapt the trees  $T_{x,y}$  and the class  $\mathcal{C}$  of Theorem 4.8 in the following way:

$$T_{x,y} := \{xy0^s : \overline{\log}(y) \notin K_s\} \cup \{xyz^{\omega} : z > 0 \land \overline{\log}(y) \in K_z\},\$$
$$\mathcal{C} := \{T_{x,y} : A(\overline{\log}(x)) \neq K(\overline{\log}(y)) \land \\\overline{\log}(x) \le 2^{e+100} \text{ for all programs } e \text{ of } T_{x,y}\}.$$

Note, that the Uni[A] procedure in the proof of Theorem 4.8 on input  $T_{x,y}$ uses A only to compute A(x). There is a total function  $g \in REC$  such that  $x \leq g(e)$  for all indices e of trees  $T_{x,y} \in C$ . This allows to adapt the old procedure of Theorem 4.8 to TUni[A]: The TUni[A]-learner generates an index which contains the finite string  $A \upharpoonright g(e)$  and simulates the whole Uni[A]-learning procedure as part of the program execution. If this simulation fails by querying some x beyond g(e) then it knows that e is not an index of some tree in Cand just stops to do anything, in the other case it simulates the function whose index is generated by the Uni[A]-learner.

The rest of the proof can be adapted to work also for the new definitions of  $T_{x,y}$  and  $\mathcal{C}$ . Hereby, the set X is now defined as follows:

$$\begin{aligned} X := \{a : (\exists s, b) [b \in K_s \land xy0 \preceq \varphi_{M_s^B(h(x,y)),s} \\ \text{for the majority of all } x, y \text{ with } a = \overline{\log}(x) \land b = \overline{\log}(y) \}. \end{aligned}$$

#### 6 EX-style Branch Learning

Of course, finite learning is a very restricted kind of learning. The learner gets more power if he only has to (syntactically) learn a controller *in the limit* [10]:

**Definition 6.1.**  $M^A EX[A]$ -branch learns a tree T if on input T the machine  $M^A$  produces a sequence of guesses  $h_0h_1 \ldots h_n eee \ldots$  such that  $\varphi_e$  is an infinite recursive branch of T.

A class of trees  $\mathcal{C}$  is EX[A]-branch learnable ( $\mathcal{C} \in BranchEx$ ) if there is a machine  $M^A$  which EX[A]-branch learns every  $T \in \mathcal{C}$ .

The following results can be obtained by modifying the proofs from the corresponding results in inductive inference [1, 9, 14]. As in [9] we write  $\mathcal{G}(A)$  if  $A \leq_T G \leq_T K$  for some 1-generic set G, i.e. if A is either recursive or has the same degree as a 1-generic Turing degree below K.

**Fact 6.2.** 1.  $A \leq_T K \implies BranchFin[A] \subset BranchEx$ .

- 2. For all A:  $BranchEx_1 \not\subseteq BranchFin[A]$ , where  $BranchEx_1$  means EXbranch learnable with at most one mind change.
- 3.  $BranchEx[A] = BranchEx \iff \mathcal{G}(A)$ .
- 4.  $TREE \in BranchEx[A] \iff A$  is high.
- 5. For all r.e. A:  $BranchEx[A] \subseteq BranchEx[B] \iff A \leq_T B$  or B is high.

From [13] we know that BranchEx is incomparable with BranchOnl and Uni. In analogy to the case of Uni (Theorem 4.4) it is also impossible to capture  $BranchEx_1$  by BranchOnl[A] for any oracle A:

**Theorem 6.3.** For all A:  $BranchEx_1 \not\subseteq BranchOnl[A]$ .

*Proof.* Consider the class  $\mathcal{C} := \{T \in TREE : 0^{\omega} \text{ or } 1^{\omega} \text{ is a branch of } T\}$ .  $\mathcal{C}$  is in *BranchEx*<sub>1</sub>: output a program for  $0^{\omega}$  until you find an *m* with  $T(0^m) = 0$ . Then output a program for  $1^{\omega}$ .

But a BranchOnl[A]-learner  $M^A$  for C will eventually output a first node on input  $0^n + 1^n$  because  $0^{\omega} + 1^{\omega} \in C$ . This node will be the same for  $0^n + 1^{\omega}$ and  $0^{\omega} + 1^n$ . Thus, on one of the two trees  $M^A$  fails to enumerate an infinite recursive branch.

It is fundamental that Uni and BranchOnl are not included in BranchEx: The class  $\{T_f : f \in REC\}$  (see Definition 3.7) is in  $Uni \cap BranchOnl$  but not in BranchEx since REC is not in EX. This fundamental difference between learning in the limit on the one side and online learning and uniform computation on the other side is emphasized by the following result, which shows that only omniscient oracles enable BranchEx to overcome this difference.

**Theorem 6.4.** A high  $\iff$  Uni  $\subseteq$  BranchEx[A]  $\iff$  BranchOnl  $\subseteq$  BranchEx[A].

*Proof.* If A is high then  $Uni \subseteq BranchEx[A] = TREE$  by Fact 6.2.4 and if  $Uni \subseteq BranchEx[A]$  then  $BranchOnl \subseteq BranchEx[A]$  since  $BranchOnl \subset Uni$  [13].

If BranchOnl is included in BranchEx[A] then  $\{T_f : f \in REC\}$  is in BranchEx[A]. This implies  $REC \in EX[A]$  and thus A high [9].

On the other side there are EX-branch learnable classes of trees for which infinite recursive branches cannot be computed uniformly. But in contrast to Theorem 6.4 Uni does not need an omniscient oracle to capture BranchEx:

**Corollary 6.5.**  $BranchEx \subseteq Uni[A] \iff K \leq_T A.$ 

*Proof.* If  $BranchEx \subseteq Uni[A]$  then  $BranchFin[K] \subseteq Uni[A]$  (Fact 6.2.1) which implies  $K \leq_T A$  by Theorem 4.5. The other direction follows from [13, Proposition 19].

In analogy to the results about omniscient degrees, the oracles which give TUni as much power as BranchEx are again one Turing jump higher than that of Uni:

**Theorem 6.6.**  $BranchEx \subseteq TUni[A] \iff K' \leq_T A.$ 

*Proof.* ( $\Leftarrow$ ) follows from Corollary 6.5 and Fact 5.2.3:

$$BranchEx \subseteq Uni[K] \subseteq TUni[K'].$$

For the other direction we slightly modify the trees  $T_{\text{fin}}^e$  of Theorem 5.3 and code e into the beginning of the trees:

$$T_e := \{ek^s : \#W_{e,s} \le k\}.$$

Recall that  $T_e$  has an infinite recursive branch iff  $W_e$  is finite, and  $\#W_e \leq \beta(1)$  for every infinite branch of  $T_e$ . The class  $\mathcal{C} := \{T_e \colon W_e \text{ is finite}\}$  is in *BranchEx*:

First, decode e from the input. Then, in stage n output a program for  $ek^{\omega}$  where  $k = \#W_{e,n}$ 

If  $W_e$  is finite — i.e.  $T_e \in \mathcal{C}$  — then there exists an s with  $W_e = W_{e,s}$ . Thus, in all stage  $n \geq s$  the procedure will output the same program which computes an infinite recursive branch of  $T_e$ .

By hypothesis we get  $C \in TUni[A]$  via some total  $g \leq_T A$ . Now the following algorithm decides  $Fin = \{e : W_e \text{ finite}\}$ :

- (i) Input: e
- (ii) Compute an index i of  $T_e$ .
- (iii) Let j := g(i), i.e. an index of an infinite branch of  $T_e$  in the case that  $W_e$  is finite.
- (iv) Compute  $k := \varphi_j(1)$  if defined.
- (v) If  $k = \varphi_j(1)$  is undefined or there is an s with  $\#W_{e,s} > k$  then output " $W_e$  is infinite", otherwise output " $W_e$  is finite".

If  $W_e$  is finite then  $k = \varphi_j(1)$  is defined and  $k \ge \#W_e$ . Thus, in this case the algorithm terminates with output " $W_e$  is finite".

If  $W_e$  is infinite then, if  $k = \varphi_j(1)$  defined, there is an s with  $\#W_{e,s} > k$ . Thus, in this case the algorithm terminates with output " $W_e$  is infinite".

Let us now analyze the complexity of the algorithm. Step (iii) uses the oracle A, and the steps (iv) and (v) are recursive in K. Since  $BranchEx \subseteq TUni[A] \subseteq Uni[A]$  we can conclude from Corollary 6.5 that  $K \leq_T A$ . Thus, the algorithm is recursive in A and  $K' \equiv_T Fin \leq_T A$ .

Note, that Theorem 5.4 can also be obtained as a direct conclusion from Corollary 6.5 and Theorem 6.6.

## 7 BC- and Weak BC-style Branch Learning

In contrast to EX-style learning in BC-style learning the learner has only to converge *semantically* to a correct controller. Note, that there may be many correct controllers. This is the reason why there are two notions of BC-style branch learning, while there exists only one notion of BC-style function learning.

**Definition 7.1.**  $M^A BC[A]$ -branch learns a tree T if on input T the machine  $M^A$  produces a sequence of guesses  $h_0h_1...$  such that there is an infinite recursive branch f of T with  $\varphi_{h_n} = f$  for almost all n.

 $M^A$  weakly BC[A]- or WBC[A]-branch learns T if  $\varphi_{h_n}$  is an infinite recursive branch of T for almost all n.

 $\mathcal{C} \in BranchBC[A]$  and  $\mathcal{C} \in BranchWBC[A]$  for classes  $\mathcal{C} \subseteq TREE$  are defined similar to the previous definitions (e.g.  $\mathcal{C} \in BranchEx[A]$  in Definition 6.1).

As in the case of finite versus EX-style branch learning it follows directly from  $EX \subset BC$  that  $BranchEx \subset BranchBC$ . The weak version of BC-style learning does not appear in classical inductive inference since there is only one target object — namely the input object itself. It was proven in [13] that  $BranchBC \subset BranchWBC$ .

For the omniscient BC degrees there is no nice characterization known in inductive inference. And the results in [9] suggest that there exists no nice one. Therefore it is remarkable that such a characterization exists for BranchBCand BranchWBC:

**Theorem 7.2.** A is high  $\iff$  TREE  $\in$  BranchBC[A]  $\iff$  TREE  $\in$  BranchWBC[A].

*Proof.* Fact 6.2.4 already states: If A is high then  $TREE \in BranchEx[A]$ . Since the inclusion  $BranchEx \subseteq BranchBC \subseteq BranchWBC$  relativizes to A, any high oracle is omniscient for BranchBC and BranchWBC, too. The trees from [13, Proposition 21] can be used to prove the reverse directions.

We now summarize the facts which follow from results in inductive inference by modifications of the corresponding proofs [9, 14]: **Fact 7.3.** 1. A high  $\iff$  BranchBC  $\subseteq$  BranchEx[A].

- 2.  $BranchEx[A] \subseteq BranchBC \iff \mathcal{G}(A)$ .
- 3.  $BranchBC[A] = BranchBC \iff \mathcal{G}(A)$ .
- 4. For all r.e. A, B: BranchBC[A]  $\subseteq$  BranchBC[B]  $\iff A \leq_T B$  or B high.

In Theorem 6.4 we have seen that we need omniscient oracles A to capture Uniand BranchOnl by BranchEx[A]. The following result shows that oracles Awith  $REC \in BC[A]$  suffices to capture BranchOnl by BranchBC[A] and both, BranchOnl and Uni, by BranchWBC[A]. This demonstrates the power of BCand even more the power of BranchWBC (capturing both), since only high oracles are omniscient for BranchBC and BranchWBC (Theorem 7.2) — but there are low sets A with  $REC \in BC[A]$  ([9]).

**Theorem 7.4.** The following are equivalent:

- (1)  $REC \in BC[A],$
- (2)  $BranchOnl \subseteq BranchBC[A]$ ,
- (3)  $BranchOnl \subseteq BranchWBC[A]$ ,
- (4)  $Uni \subseteq Branch WBC[A].$

*Proof.* (1)  $\Rightarrow$  (2): Assume  $C \in BranchOnl$  via M. On input  $T \in C$  enumerate an infinite branch of T via M and BC[A]-learns an index for it.

 $(2) \Rightarrow (3)$ : Obvious, since  $BranchBC[A] \subseteq BranchWBC[A]$ .

(3)  $\Rightarrow$  (1): From  $\{T_f : f \in REC\} \in Uni \subseteq Branch WBC[A]$  (see Definition 3.7) we directly get  $REC \in BC[A]$ .

 $(1) \Rightarrow (4)$ : Assume  $\mathcal{C} \in Uni$  via g. On input  $T \in \mathcal{C}$  we BC[A]-learn an index for T, say by the sequence of guesses  $h_1h_2...$  Then  $g(h_1)g(h_2)...$  is a sequence of guesses such that almost all compute an infinite recursive branch of T.

 $(4) \Rightarrow (3)$ : Obvious, since  $BranchOnl \subset Uni$ .

Note that in the proof of  $(1) \Rightarrow (4)$  we can not conclude  $Uni \subseteq BranchBC$  since the sequence  $h_1, h_2, \ldots$  may converge to different indices for T, and the branch computed by g may depend on the indices for T, which g receives as input.

The following theorem shows that we actually need an omniscient oracle A to capture Uni by BranchBC[A]. This gives a measure for the advantage of WBC-style over BC-style branch learning. This advantage of WBC-style over BC-style branch learning is additionally demonstrated by the result that for capturing BranchWBC by BranchBC[A] also an omniscient oracle A is needed. As a corollary we get the existence of classes in Uni such that the uniform computation of branches depends on the index of the input tree.

**Theorem 7.5.** A is high  $\iff$   $Uni \subseteq BranchBC[A] \iff$   $BranchWBC \subseteq$ BranchBC[A]. *Proof.* Since high oracles are omniscient for BranchBC (Theorem 7.2) we only have to show that  $Uni \subseteq BranchBC[A]$  and  $BranchWBC \subseteq BranchBC[A]$  imply A high.

Assume that A is not high. Then there is a family of recursive functions  $S \in BC - EX[A]$  ([14]). We consider the class  $\mathcal{B}(S)$  (see Definition 4.2).  $\mathcal{B}(S)$  is in Uni by Lemma 4.3.  $\mathcal{B}(S)$  is also in Branch WBC:

From the input  $R_f(0), R_f(1), \ldots$  extract an enumeration  $f(0), f(1), \ldots$  for f. Apply the *BC*-learner on f which yields a sequence  $h_0h_1\ldots$  of guesses for f such that almost all guesses are correct. By Lemma 4.3 there is a  $g \in REC$  with  $(\forall e)(\forall f)[\varphi_e = f \implies \varphi_{g(e)}$  is an infinite recursive branch of  $R_f$ . Thus,  $g(h_0)g(h_1)\ldots$  is a sequence of guesses such that almost all compute an infinite recursive branch or  $R_f$ .

Assume  $\mathcal{B}(S) \in BranchBC[A]$  via  $M^A$ . We will show that this implies  $S \in EX[A]$  which is a contradiction:

Translate the input sequence  $f(0), f(1), \ldots$  for  $f \in S$  into an enumeration  $R_f(0), R_f(1), \ldots$  (Lemma 4.3). By Applying  $M^A$  to  $R_f \upharpoonright 0, R_f \upharpoonright 1, \ldots$  we get a sequence of guesses  $h_0h_1 \ldots$  which BC[A]-converges to an infinite recursive branch of  $R_f$ . Let  $k(n) := \max\{m \leq n : \varphi_{h_m,n}(0) \downarrow\}$ . Then  $(\varphi_{h_{k(n)}}(0))_{n \in \omega} EX[A]$ -converges to an index for f by Lemma 4.3.

**Corollary 7.6.** There exists a class  $C \in Uni$  such that for all g with  $C \in Uni$  via g:

$$(\exists T \in \mathcal{C})(\exists i, j) [i \neq j \land \varphi_i = \varphi_j = T \land \varphi_{g(i)} \neq \varphi_{g(j)}].$$

In Corollary 6.5 we have seen that  $BranchEx \subseteq Uni[A]$  iff  $A \ge_T K$ . This result also holds for *BC*-branch learning by the analogous proof, since Proposition 19 from [13] actually states  $BranchBC \subseteq Uni[K]$ :

**Corollary 7.7.** BranchBC  $\subseteq$  Uni[A]  $\iff$   $A \geq_T K$ .

What oracle do we need to capture BranchWBC by Uni[A]? The power of WBC-style branch learning appears most clearly under this "Uni-oracle measure". The gap between capturing BranchBC and BranchWBC by Uni[A] is a whole Turing jump. BranchWBC is so powerful that only omniscient oracles give Uni[A] as much power:

**Theorem 7.8.** Branch WBC  $\subseteq$  Uni[A]  $\iff$   $A \geq_T K'$ .

*Proof.* ( $\Leftarrow$ ) follows by Fact 4.6. For the direction ( $\Rightarrow$ ) we define

$$T_e := \{eka_0 \dots a_n \colon (\forall m \le n) [(\#W_{e,m} \le k \implies a_m = 0) \land \\ (\#W_{e,m} > k \implies \#W_e \ge m \land a_m = \mu t [\#W_{e,t} \ge m])]\}.$$

Let  $U_k^e := \{\sigma : ek\sigma \in T_e\}$  be the subtree above ek. If  $\#W_e \le k$  then  $U_k = 0^{\omega}$ . If  $\#W_e > k$  then  $U_k$  contains an infinite recursive branch iff  $W_e$  is infinite.

The class  $\mathcal{C} := \{T_e : e \in \omega\}$  is in *BranchWBC*:

Wait until you can decode e from the enumeration of  $T_e$ . Then output in stage s a program for  $eka_0a_1...$  where  $k = \#W_{e,s}$  and  $a_m = \mu t [\#W_{e,m} \le k \lor \#W_{e,t} \ge m].$  If  $W_e$  is finite then there is an s with  $W_e = W_{e,s}$ . Thus, for  $k = \#W_{e,s}$  we have  $U_k = 0^{\omega}$  and all guesses from stage s on will compute the branch  $ek0^{\omega}$ . If  $W_e$  is infinite then every  $ekU_k$  contains an infinite recursive branch and every guess computes such a branch. (Note that in this case the learner produces infinitely many different branches.)

Since  $BranchWBC \subseteq Uni[A]$  there is a partial A-recursive g with  $\mathcal{C} \in Uni[A]$  via g. We choose an  $h \in REC$  with  $T_e = \varphi_{h(e)}$  for all e. Note, that  $range(h) \subseteq dom(g)$ . Then  $Inf = \{e : W_e \text{ infinite}\}$  is recursively enumerable in A, since  $Inf = \{e : (\exists s) [\#W_{e,s} > \varphi_{g(h(e))}(1)]\}$ . Let  $k = \varphi_{g(h(e))}(1)$ . If  $k > \#W_{e,s}$  then  $ekU_k$  contains an infinite recursive branch, since  $\mathcal{C} \in Uni$  via g. Then  $W_e$  must be infinite because of  $\#W_{e,s} > k$ . And if  $W_e$  is infinite then there certainly exists an s with  $\#W_{e,s} > \varphi_{g(h(e))}(1)$ .

Since  $BranchBC \subseteq BranchWBC \subseteq Uni[A]$  we get  $K \leq_T A$  by Corollary 7.7. The index set  $Fin = \{e : W_e \text{ finite}\}$  is recursively enumerable in K and thus also r.e. in A. I.e. Inf and the complement of Inf are r.e. in A which implies  $A \geq_T Inf \equiv_T K'$ .

A similar result can be obtained for the comparison of *BranchWBC* with *TUni*:

**Theorem 7.9.** Branch WBC  $\subseteq$  TUni[A]  $\iff$   $A \geq_T K''$ .

*Proof.* ( $\Leftarrow$ ) follows by Theorem 5.3. For the other direction we slightly modify the trees of Theorem 5.3 by coding *e* into the beginning of  $T_e$ :

 $T_e := \{eka_0 \dots a_n : (\forall m \le n) [a_m = \mu s[\{k, \dots, k+m\} \in W_{e,s}]]\}.$ 

Recall that  $T_e$  contains infinite recursive branches iff  $W_e$  is cofinite, and that every infinite recursive branch  $\beta$  of  $T_e$  satisfies  $\max \overline{W_e} < \beta(1)$ . The class  $\mathcal{C} := \{T_e : W_e \text{ cofinite}\}$  is in *BranchWBC*:

Decode e from the input. Then in stage n output a program for  $\beta_n := ena_0a_1 \dots$  where  $a_m = \mu s[\{n, \dots, n+m\} \in W_{e,s}].$ 

If the input tree  $T_e$  is in  $\mathcal{C}$  — i.e.  $\overline{W_e}$  is cofinite — then almost all  $\beta_n$  are infinite branches of  $T_e$ .

By hypothesis we get  $\mathcal{C} \in TUni[A]$  via some total  $g \leq_T A$ . Since  $TUni[A] \subseteq Uni[A]$  it follows  $A \geq_T K'$  by Fact 4.6. Let  $h \in REC$  with  $(\forall e)[\varphi_{h(e)} = T_e]$  be given. Then  $W_e$  is cofinite iff

- (i)  $\varphi_{q(h(e))}$  is total and
- (ii)  $\varphi_{q(h(e))}$  is an branch of  $T_e$ .

Note, that we use the totality of g since g(h(e)) converges for all e not only for e with  $W_e$  cofinite, i.e.  $T_e \in \mathcal{C}$ . The index g(h(e)) is computable in A. Step (i) is recursive in  $K' \leq_T A$  and step (ii) is recursive in  $K <_T A$ . At all it follows  $K'' \equiv_T \{e \colon W_e \text{ cofinite}\} \leq_T A$ .

In summary, BranchBC and BranchWBC have the same omniscient degrees and behave similar when compared to BranchOnl. But in the comparisons with Uni the two BC-style branch learning notions behave very different. The two notions differ also with respect to the the trivial degree: **Theorem 7.10.** 1. Branch  $WBC[A] = Branch WBC \iff A$  is recursive.

2. For all  $A \leq_T K$ : Branch  $WBC[A] \subseteq Branch WBC[B] \iff A \leq_T B$  or B high.

*Proof of (2).* ( $\Leftarrow$ ): Follows from 3.4 and Theorem 7.2.

 $(\Rightarrow)$ : Since  $A \leq_T K$ , by the Limit Lemma there is a total computable function  $u: \omega^2 \to \omega$  with  $A = \lambda x$ .  $\lim_{s\to\infty} u(x,s)$ . Let  $f \in REC$  be given. We combine the constructions of the trees  $R_f$  in 4.2 and the trees  $T_x$  in Theorem 4.5 to define recursive trees  $Q_f$ :

$$Q_f := \{ ef(e)a_0 \dots a_e b_0 \dots b_n \colon (\forall m \le n) \\ [b_m = \mu t[t > b_{m-1} \land \varphi_{e,t}(m) \downarrow = f(m) \land (\forall x \le e)[u(x,t) = a_x]]] \}.$$

Hereby, we set  $b_{-1} = -1$ .  $Q_f$  has an infinite recursive branch  $\beta$  with  $e \leq \beta$  iff  $\varphi_e = f$ , in which case the infinite recursive branch  $\beta \geq e$  is unique and  $eA(0) \dots A(e) \leq \beta$ .

Assume that B is not high. Then there is a family of recursive functions  $S \in BC - EX[A]$  ([14]). We consider the class  $\mathcal{C} := \{Q_f : f \in S\}$ . Analogously to the trees  $R_f$  (Lemma 4.3) one can effectively translate an enumeration of  $Q_f$  into an enumeration of f. Moreover, from f one can compute uniformly in A an infinite recursive branch of  $Q_f$ :

Given the index e of f output a program for  $e\varphi_e(e)A(0)\ldots A(e)b_0b_1\ldots$ where  $b_m := (\mu t > b_{m-1})[\varphi_{e,t}(m) \downarrow \land (\forall x \leq e)[u(x,t) = A(x)]].$ 

Note, that in contrast to the trees  $R_f$ , here we need the oracle A to compute from f an infinite recursive branch of  $Q_f$ . Now, one shows  $C \in Branch WBC[A]$ similar as in the proof of  $\mathcal{B}(S) \in Branch WBC$  (Theorem 7.2): Translate the enumeration for  $Q_f$  into one for f. From this enumeration BC-learn an index for f. On the resulting sequence of guesses for f apply the above A-recursive procedure for uniform computation of infinite branches.

Since  $BranchWBC[A] \subseteq BranchWBC[B]$  the class  $\mathcal{C}$  is also in BranchWBC[B] via some machine  $M^B$ .

Assume that  $M^B$  converges on all  $T \in \mathcal{C}$  to a finite set of infinite recursive branches, i.e.  $\{\varphi_{M^B(T \upharpoonright n}) : n \in \omega\}$  is finite for all  $T \in \mathcal{C}$ . Then the machine

$$N^{B}(T \upharpoonright n) := M^{B}(T \upharpoonright \max\{m \le n : \varphi_{M^{B}(T \upharpoonright m), n}(0) \downarrow\}),$$

where  $\max \emptyset = 0$  by convention, converges for all  $Q_f$  to a finite set of programs for f, i.e. there is an  $n_0$  such that  $\{N^B(Q_f \upharpoonright n) : n \ge n_0\}$  is a finite set of programs, which compute infinite recursive branches of  $Q_f$ . Since enumerations for f can be effectively translated into enumerations for  $Q_f$ , and  $\varphi_{\beta(0)} = f$  for every infinite recursive branch of  $Q_f$ , it follows that  $S \in FEx[B] = EX[B]$  (see [6]), which is a contradiction.

Hence, there is a tree  $T \in \mathcal{C}$  such that  $M^B$  converges on T to an infinite set of infinite recursive branches of T, i.e.  $\{\varphi_{M^B(T \upharpoonright n)} : n \in \omega\}$  is infinite. We choose an  $n_0$  such that  $M^B(T \upharpoonright n)$  is an infinite recursive branch for all  $n \ge n_0$ . By definition, the tree T has for all e at most one infinite recursive branch  $\beta$ 

with  $e \leq \beta$ . Thus, for each  $x \in \omega$  there is an  $n \geq n_0$  such that  $\varphi_{M^B(T \upharpoonright n)}(0) \geq x$ . Setting  $s(x) := \mu n \ge n_0 [\varphi_{M^B(T \mid n)}(0) \ge x]$  the procedure  $\lambda x . \varphi_{M^B(T \mid s(x))}(x+2)$ decides A relative in B, i.e.  $A \leq_T B$ . 

*Proof of (1).* Branch WBC[A] = Branch WBC implies BC[A] = BC via the trees  $T_f$  from Definition 3.7:

$$S \in BC[A]$$
  

$$\implies \{T_f \colon f \in S\} \in BranchBC[A] \subseteq BranchWBC[A] = BranchWBC$$
  

$$\implies S \in BC.$$

Thus,  $\mathcal{G}(A)$  and in particular  $A \leq_T K$  holds. By (2) we get  $A \leq_T \emptyset$ .

#### 

#### 8 Equivalence between binary and arbitrary trees

When we consider the concept of branch learning as a model for process learning, it seems more natural to define the trees over a finite alphabet. This is because the states of the process and the actions of the controller actually are bounded. It is clear that trees over a finite alphabet can always be coded as trees over  $\{0, 1\}$ . But in theoretical considerations proofs often get more simple if we work with arbitrary trees, i.e. trees over the infinite alphabet  $\omega$ . In this section we show that it does not matter whether we base the definition on arbitrary trees or on binary trees.  $TREE_{0,1} := \{T \in TREE : T \text{ is a binary tree}\}$ denotes the set of all binary trees in TREE. We will use the following well known fact (see e.g. [24, Proposition V.5.25]):

Fact 8.1. There is an infinite recursive binary tree  $\tilde{T}$  without infinite recursive branches.  $\widetilde{T}$  has infinitely many leafs (i.e.  $\sigma \in \widetilde{T}$  with  $\sigma 0, \sigma 1 \notin \widetilde{T}$ ). The set  $L := \{\sigma : \sigma \text{ is a leaf of } \widetilde{T}\}$  is decidable, thus there is an effective enumeration of L without repetitions, which we denote by  $\sigma_0, \sigma_1, \ldots$ 

**Theorem 8.2.** For all  $\mathcal{C} \subseteq TREE$ , there is a class  $\mathcal{B} \subseteq TREE_{0,1}$ , such that for all criteria Crit, which we consider in this paper, and all oracles A:

$$\mathcal{B} \in Crit[A] \iff \mathcal{C} \in Crit[A].$$

*Proof.* For an arbitrary  $T \in TREE$  let

 $S_T := \{ \sigma_{a_0} \dots \sigma_{a_n} \tau \colon a_0 \dots a_n \in T \land \tau \in \widetilde{T} \text{ but } \tau \text{ is not a leaf of } \widetilde{T} \}.$ 

 $S_T$  is recursive: To decide  $\sigma \in S_T$  first compute the decomposition  $\sigma =$  $\sigma_{a_0} \dots \sigma_{a_n} \tau$  such that no prefix of  $\tau$  is in L. This decomposition is computable and unique, since L is decidable and there are no  $\sigma', \sigma'' \in L$  with  $\sigma' \prec \sigma''$ . If  $\sigma' \in L$  then  $\sigma' = \sigma_a$  for  $a = \mu k [\sigma_k = \sigma']$ . Now,  $\sigma \in L$  iff  $a_0 \dots a_n \in T$  and  $\tau \in \widetilde{T}.$ 

If  $a_0a_1...$  is an infinite recursive branch of T, then clearly  $\sigma_{a_0}\sigma_{a_1}...$  is an infinite recursive branch of  $S_T$ . And if  $\beta$  is an infinite branch of  $S_T$  then either

•  $\beta = \sigma_{a_0}\sigma_{a_1}\dots$  for an infinite branch  $a_0a_1\dots$  of T.  $\beta$  is recursive iff  $a_0 a_1 \ldots$  is recursive.

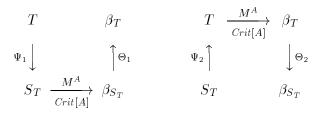


Figure 1: Reductions between T and  $S_T$ .

• or  $\beta = \sigma_{a_0} \dots \sigma_{a_n} \gamma$  for a *non*recursive infinite branch  $\gamma$  of  $\widetilde{T}$ , in which case  $\beta$  is also not recursive.

It follows that  $S_T$  is in  $TREE_{0,1}$ . We set  $\mathcal{B} := \{S_T : T \in \mathcal{C}\}.$ 

The idea of the proof is to reduce the Crit[A]-procedures for  $\mathcal{B}$  and  $\mathcal{C}$  to each other as illustrated in Figure 1. E.g., assume  $\mathcal{B} \in Crit[A]$  via  $M^A$ . From  $M^A$ we can build an Crit[A]-procedure for  $\mathcal{C}$  by translating an input tree  $T \in \mathcal{C}$  into the tree  $S_T$  (transformation  $\Psi_1$ ). On  $S_T$  we apply the machine  $M^A$  which yields an infinite recursive branch  $\beta_{S_T}$  of  $S_T$ . From the branch  $\beta_{S_T}$  we then compute an infinite recursive branch  $\beta_T$  of T (transformation  $\Theta_1$ ). The reduction for the other direction (reducing  $\mathcal{B}$  to  $\mathcal{C}$ ) works analogously.

Therefore, we have to show that the transformations  $\psi_i$  and  $\Theta_i$  can be done effectively according the the requirements of the different criteria. In general we say that  $Y_X$  can be *computed uniformly* from  $X \in \mathcal{X}$ , where  $X \in \mathcal{X}$  and  $Y_X$ are decidable sets, if there is a partial recursive function g such that

$$(\forall e)(\forall X \in \mathcal{X})[\varphi_e = X \implies g(e) \downarrow \land \varphi_{g(e)} = Y_X].$$

Enumerations of (the characteristic functions of) sets  $X \in \mathcal{X}$  can be translated effectively into enumerations of (the characteristic functions of)  $Y_X$  if there are computable functions  $h_1, h_2$  such that for all  $X \in \mathcal{X}$  and all  $n \in \omega$ :

$$Y_X(n) = h_1(X \restriction h_2(n))$$

All learning criteria require that the transformations  $\psi_i$  translate enumerations of T and  $S_T$  effectively into each other. Uni requires that T and  $S_T$  can be computed uniformly from each other. For the output transformations  $\Theta_i$  only *BranchOnl* requires translation of enumerations. All other criteria need uniform computations between  $\beta_T$  and  $\beta_{S_T}$ .

If enumerations for  $X \in \mathcal{X}$  can be translated effectively into enumerations for  $Y_X$ , then  $Y_X$  can obviously also be computed uniformly from X. Thus, it remains to show the statements about effective translations of enumerations.

It follows from the decision procedure for  $S_T$  described above that given the value of  $T(a_0...a_n)$  one can compute  $S_T(\sigma)$  — where  $\sigma = \sigma_{a_0}...\sigma_{a_n}\tau$  is decomposed as above. Thus, an enumeration of T can effectively be translated into an enumeration for  $S_T$ .

The converse — that an enumeration of  $S_T$  can be be translated effectively into an enumeration of T — holds since

$$a_0 \dots a_n \in T \iff \sigma_{a_0} \dots \sigma_{a_n} \in S_T.$$

It directly follows from the above argumentation about the infinite branches of T and  $S_T$  that the enumerations of infinite recursive branches of T and  $S_T$  can be translated effectively into each other.

Theorem 2.1 from Section 2 directly follows from the above theorem.

**Acknowledgements:** We would like to thank John Case, Martin Kummer and Martin Riedmiller for helpful discussions and comments.

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