Statistics for Engineering and Information Science

Series Editors M. Jordan, S.L. Lauritzen, J.F. Lawless, V. Nair

Springer Science+Business Media, LLC

#### Statistics for Engineering and Information Science

Akaike and Kitagawa: The Practice of Time Series Analysis. Cowell, Dawid, Lauritzen, and Spiegelhalter: Probabilistic Networks and Expert Systems.

Fine: Feedforward Neural Network Methodology.

Hawkins and Olwell: Cumulative Sum Charts and Charting for Quality Improvement.

Vapnik: The Nature of Statistical Learning Theory, Second Edition.

Vladimir N. Vapnik

# The Nature of Statistical Learning Theory

Second Edition

With 50 Illustrations



Vladimir N. Vapnik AT&T Labs–Research Room 3-130 100 Schultz Drive Red Bank, NJ 07701 USA vlad@research.att.com

Series Editors Michael Jordan Department of Computer Science University of California, Berkeley Berkeley, CA 94720 USA Jerald F. Lawless

Department of Statistics University of Waterloo Waterloo, Ontario N2L 3G1 Canada Steffen L. Lauritzen Department of Mathematical Sciences Aalborg University DK-9220 Aalborg Denmark Vijay Nair Department of Statistics University of Michigan Ann Arbor, MI 48109 USA

Library of Congress Cataloging-in-Publication Data Vapnik, Vladimir Naumovich. The nature of statistical learning theory/Vladimir N. Vapnik. — 2nd ed. p. cm. — (Statistics for engineering and information science) Includes bibliographical references and index. ISBN 978-1-4419-3160-3 ISBN 978-1-4757-3264-1 (eBook) DOI 10.1007/978-1-4757-3264-1 1. Computational learning theory. 2. Reasoning. I. Title. II, Series. Q325.7.V37 1999 006.3'1'015195—dc21 99-39803

Printed on acid-free paper.

© 2000, 1995 Springer Science+Business Media New York Originally published by Springer-Verlag New York, Inc. in 2000 Softcover reprint of the hardcover 2nd edition 2000

All rights reserved. This work may not be translated or copied in whole or in part without the written permission of the publisher Springer Science+Business Media, LLC, except for brief excerpts in connection with reviews or scholarly analysis. Use in connection with any form of information storage and retrieval, electronic adaptation, computer software, or by similar or dissimilar methodology now known or hereafter developed is forbidden. The use of general descriptive names, trade names, trademarks, etc., in this publication, even if the former are not especially identified, is not to be taken as a sign that such names, as understood by the Trade Marks and Merchandise Marks Act, may accordingly be used freely by anyone.

Production managed by Frank M<sup> $\circ$ </sup>Guckin; manufacturing supervised by Erica Bresler. Photocomposed copy prepared from the author's L<sup>A</sup>T<sub>E</sub>X files.

987654321

ISBN 978-1-4419-3160-3

In memory of my mother

### Preface to the Second Edition

Four years have passed since the first edition of this book. These years were "fast time" in the development of new approaches in statistical inference inspired by learning theory.

During this time, new function estimation methods have been created where a high dimensionality of the unknown function does not always require a large number of observations in order to obtain a good estimate. The new methods control generalization using capacity factors that do not necessarily depend on dimensionality of the space.

These factors were known in the VC theory for many years. However, the practical significance of capacity control has become clear only recently after the appearance of support vector machines (SVM). In contrast to classical methods of statistics where in order to control performance one decreases the dimensionality of a feature space, the SVM dramatically increases dimensionality and relies on the so-called large margin factor.

In the first edition of this book general learning theory including SVM methods was introduced. At that time SVM methods of learning were brand new, some of them were introduced for a first time. Now SVM margin control methods represents one of the most important directions both in theory and application of learning.

In the second edition of the book three new chapters devoted to the SVM methods were added. They include generalization of SVM method for estimating real-valued functions, direct methods of learning based on solving (using SVM) multidimensional integral equations, and extension of the empirical risk minimization principle and its application to SVM.

The years since the first edition of the book have also changed the general

philosophy in our understanding the of nature of the induction problem. After many successful experiments with SVM, researchers became more determined in criticism of the classical philosophy of generalization based on the principle of Occam's razor.

This intellectual determination also is a very important part of scientific achievement. Note that the creation of the new methods of inference could have happened in the early 1970: All the necessary elements of the theory and the SVM algorithm were known. It took twenty-five years to reach this intellectual determination.

Now the analysis of generalization from the pure theoretical issues become a very practical subject, and this fact adds important details to a general picture of the developing computer learning problem described in the first edition of the book.

Red Bank, New Jersey August 1999 Vladimir N. Vapnik

### Preface to the First Edition

Between 1960 and 1980 a revolution in statistics occurred: Fisher's paradigm, introduced in the 1920s and 1930s was replaced by a new one. This paradigm reflects a new answer to the fundamental question:

What must one know a priori about an unknown functional dependency in order to estimate it on the basis of observations?

In Fisher's paradigm the answer was very restrictive—one must know almost everything. Namely, one must know the desired dependency up to the values of a finite number of parameters. Estimating the values of these parameters was considered to be the problem of dependency estimation.

The new paradigm overcame the restriction of the old one. It was shown that in order to estimate dependency from the data, it is sufficient to know some general properties of the set of functions to which the unknown dependency belongs.

Determining general conditions under which estimating the unknown dependency is possible, describing the (inductive) principles that allow one to find the best approximation to the unknown dependency, and finally developing effective algorithms for implementing these principles are the subjects of the new theory.

Four discoveries made in the 1960s led to the revolution:

- (i) Discovery of regularization principles for solving ill-posed problems by Tikhonov, Ivanov, and Phillips.
- (ii) Discovery of nonparametric statistics by Parzen, Rosenblatt, and Chentsov.

#### x Preface to the First Edition

- (iii) Discovery of the law of large numbers in functional space and its relation to the learning processes by Vapnik and Chervonenkis.
- (iv) Discovery of algorithmic complexity and its relation to inductive inference by Kolmogorov, Solomonoff, and Chaitin.

These four discoveries also form a basis for any progress in studies of learning processes.

The problem of learning is so general that almost any question that has been discussed in statistical science has its analog in learning theory. Furthermore, some very important general results were first found in the framework of learning theory and then reformulated in the terms of statistics.

In particular, learning theory for the first time stressed the problem of *small sample statistics*. It was shown that by taking into account the size of the sample one can obtain better solutions to many problems of function estimation than by using the methods based on classical statistical techniques.

Small sample statistics in the framework of the new paradigm constitutes an advanced subject of research both in statistical learning theory and in theoretical and applied statistics. The rules of statistical inference developed in the framework of the new paradigm should not only satisfy the existing asymptotic requirements but also guarantee that one does one's best in using the available restricted information. The result of this theory is new methods of inference for various statistical problems.

To develop these methods (which often contradict intuition), a comprehensive theory was built that includes:

- (i) Concepts describing the necessary and sufficient conditions for consistency of inference.
- (ii) Bounds describing the generalization ability of learning machines based on these concepts.
- (iii) Inductive inference for small sample sizes, based on these bounds.
- (iv) Methods for implementing this new type of inference.

Two difficulties arise when one tries to study statistical learning theory: a technical one and a conceptual one—to understand the proofs and to understand the nature of the problem, its philosophy.

To overcome the technical difficulties one has to be patient and persistent in following the details of the formal inferences.

To understand the nature of the problem, its spirit, and its philosophy, one has to see the theory as a whole, not only as a collection of its different parts. Understanding the nature of the problem is extremely important because it leads to searching in the right direction for results and prevents searching in wrong directions.

The goal of this book is to describe the nature of statistical learning theory. I would like to show how abstract reasoning implies new algorithms. To make the reasoning easier to follow, I made the book short.

I tried to describe things as simply as possible but without conceptual simplifications. Therefore, the book contains neither details of the theory nor proofs of the theorems (both details of the theory and proofs of the theorems can be found (partly) in my 1982 book *Estimation of Dependencies Based on Empirical Data* (Springer) and (in full) in my book *Statistical Learning Theory* (J. Wiley, 1998)). However, to describe the ideas without simplifications I needed to introduce new concepts (new mathematical constructions) some of which are nontrivial.

The book contains an introduction, five chapters, informal reasoning and comments on the chapters, and a conclusion.

The introduction describes the history of the study of the learning problem which is not as straightforward as one might think from reading the main chapters.

Chapter 1 is devoted to the setting of the learning problem. Here the general model of minimizing the risk functional from empirical data is introduced.

Chapter 2 is probably both the most important one for understanding the new philosophy and the most difficult one for reading. In this chapter, the conceptual theory of learning processes is described. This includes the concepts that allow construction of the necessary and sufficient conditions for consistency of the learning processes.

Chapter 3 describes the nonasymptotic theory of bounds on the convergence rate of the learning processes. The theory of bounds is based on the concepts obtained from the conceptual model of learning.

Chapter 4 is devoted to a theory of small sample sizes. Here we introduce inductive principles for small sample sizes that can control the generalization ability.

Chapter 5 describes, along with classical neural networks, a new type of universal learning machine that is constructed on the basis of small sample sizes theory.

Comments on the chapters are devoted to describing the relations between classical research in mathematical statistics and research in learning theory.

In the conclusion some open problems of learning theory are discussed.

The book is intended for a wide range of readers: students, engineers, and scientists of different backgrounds (statisticians, mathematicians, physicists, computer scientists). Its understanding does not require knowledge of special branches of mathematics. Nevertheless, it is not easy reading, since the book does describe a (conceptual) forest even if it does not consider the (mathematical) trees.

In writing this book I had one more goal in mind: I wanted to stress the practical power of abstract reasoning. The point is that during the last few years at different computer science conferences, I heard reiteration of the following claim:

Complex theories do not work, simple algorithms do.

One of the goals of this book is to show that, at least in the problems of statistical inference, this is not true. I would like to demonstrate that in this area of science a good old principle is valid:

Nothing is more practical than a good theory.

The book is not a survey of the standard theory. It is an attempt to promote a certain point of view not only on the problem of learning and generalization but on theoretical and applied statistics as a whole.

It is my hope that the reader will find the book interesting and useful.

#### AKNOWLEDGMENTS

This book became possible due to the support of Larry Jackel, the head of the Adaptive System Research Department, AT&T Bell Laboratories.

It was inspired by collaboration with my colleagues Jim Alvich, Jan Ben, Yoshua Bengio, Bernhard Boser, Léon Bottou, Jane Bromley, Chris Burges, Corinna Cortes, Eric Cosatto, Joanne DeMarco, John Denker, Harris Drucker, Hans Peter Graf, Isabelle Guyon, Patrick Haffner, Donnie Henderson, Larry Jackel, Yann LeCun, Robert Lyons, Nada Matic, Urs Mueller, Craig Nohl, Edwin Pednault, Eduard Säckinger, Bernhard Schölkopf, Patrice Simard, Sara Solla, Sandi von Pier, and Chris Watkins.

Chris Burges, Edwin Pednault, and Bernhard Schölkopf read various versions of the manuscript and improved and simplified the exposition.

When the manuscript was ready I gave it to Andrew Barron, Yoshua Bengio, Robert Berwick, John Denker, Federico Girosi, Ilia Izmailov, Larry Jackel, Yakov Kogan, Esther Levin, Vincent Mirelly, Tomaso Poggio, Edward Reitman, Alexander Shustorovich, and Chris Watkins for remarks. These remarks also improved the exposition.

I would like to express my deep gratitude to everyone who helped make this book.

Red Bank, New Jersey March 1995 Vladimir N. Vapnik

## Contents

Preface to the Second Edition	vii
Preface to the First Edition	ix
Introduction: Four Periods in the Research of the	
Learning Problem	1
Rosenblatt's Perceptron (The 1960s)	1
Construction of the Fundamentals of Learning Theory	
$(The 1960s-1970s)  \dots  \dots  \dots  \dots  \dots  \dots  \dots  \dots  \dots  $	7
Neural Networks (The 1980s)	11
Returning to the Origin (The 1990s)	14
Chapter 1 Setting of the Learning Problem	17
1.1 Function Estimation Model	17
1.2 The Problem of Risk Minimization	18
1.3 Three Main Learning Problems	18
1.3.1 Pattern Recognition	19
1.3.2 Regression Estimation	19
1.3.3 Density Estimation (Fisher–Wald Setting)	19
1.4 The General Setting of the Learning Problem	20
1.5 The Empirical Risk Minimization (ERM) Inductive Principle	20
1.6 The Four Parts of Learning Theory	21
Informal Reasoning and Comments — 1	23

	1.7		lassical Paradigm of Solving Learning Problems	23
		1.7.1	Density Estimation Problem (Maximum	
			Likelihood Method)	24
			Pattern Recognition (Discriminant Analysis) Problem	24
			Regression Estimation Model	25
			Narrowness of the ML Method	26
	1.8	-	rametric Methods of Density Estimation	27
			Parzen's Windows	27
			The Problem of Density Estimation Is Ill-Posed	28
	1.9	Main F	Principle for Solving Problems Using a Restricted Amount	
		of Inf	ormation	30
	1.10	) Mode	el Minimization of the Risk Based on Empirical Data .	31
		1.10.1	Pattern Recognition	31
		1.10.2	Regression Estimation	31
			B Density Estimation	32
	1.11		astic Approximation Inference	33
C	hapt	er 2 C	onsistency of Learning Processes	35
	2.1		lassical Definition of Consistency and	
			oncept of Nontrivial Consistency	36
	2.2		ey Theorem of Learning Theory	38
			Remark on the ML Method	39
	2.3		ary and Sufficient Conditions for	
	2.0		rm Two-Sided Convergence	40
			Remark on Law of Large Numbers and	10
		2.0.1	Its Generalization	41
		2.3.2	Entropy of the Set of Indicator Functions	42
			Entropy of the Set of Real Functions	43
			Conditions for Uniform Two-Sided Convergence	45
	24		ary and Sufficient Conditions for Uniform	10
	2.1		Bided Convergence	45
	2.5		y of Nonfalsifiability	47
	2.0		Kant's Problem of Demarcation and	TI
		2.0.1	Popper's Theory of Nonfalsifiability	47
	9 <i>G</i>	Theer	ems on Nonfalsifiability	49
	2.0			
		2.6.1	Case of Complete (Popper's) Nonfalsifiability	50
		2.6.2	Theorem on Partial Nonfalsifiability	50
	<b>.</b> -	2.6.3	0	52
	2.7	Three	Milestones in Learning Theory	55
In	forn	nal Re	asoning and Comments — 2	59
	2.8	The B	asic Problems of Probability Theory and Statistics	60
		2.8.1	Axioms of Probability Theory	60
	2.9	Two N	Addes of Estimating a Probability Measure	63

2.10 Strong Mode Estimation of Probability Measures and	
the Density Estimation Problem	65
2.11 The Glivenko–Cantelli Theorem and its Generalization	66
2.11 The Grivenko-Canteni Theorem and its Generalization	67
2.12 Mathematical Theory of Induction	07
Chapter 3 Bounds on the Rate of Convergence of	
Learning Processes	69
3.1 The Basic Inequalities	70
3.2 Generalization for the Set of Real Functions	72
3.3 The Main Distribution–Independent Bounds	75
3.4 Bounds on the Generalization Ability of Learning Machines	76
3.5 The Structure of the Growth Function	78
3.6 The VC Dimension of a Set of Functions	80
3.7 Constructive Distribution–Independent Bounds	83
3.8 The Problem of Constructing Rigorous	
(Distribution–Dependent) Bounds	85
	_
Informal Reasoning and Comments — 3	87
3.9 Kolmogorov–Smirnov Distributions	87
3.10 Racing for the Constant	89
3.11 Bounds on Empirical Processes	90
Chapter 4 Controlling the Generalization Ability of	
Learning Processes	93
4.1 Structural Risk Minimization (SRM) Inductive Principle	94
4.2 Asymptotic Analysis of the Rate of Convergence	97
4.3 The Problem of Function Approximation in Learning Theory	99
4.4 Examples of Structures for Neural Nets	101
4.5 The Problem of Local Function Estimation	103
4.6 The Minimum Description Length (MDL) and	
SRM Principles	104
4.6.1 The MDL Principle	106
4.6.2 Bounds for the MDL Principle	107
4.6.3 The SRM and MDL Principles	108
4.6.4 A Weak Point of the MDL Principle	110
8	111
4.7 Methods for Solving Ill-Posed Problems	112
4.8 Stochastic Ill-Posed Problems and the Problem of	
Density Estimation	113
4.9 The Problem of Polynomial Approximation of the Regression	115
4.10 The Problem of Capacity Control	116
4.10.1 Choosing the Degree of the Polynomial	116
4.10.2 Choosing the Best Sparse Algebraic Polynomial	117
4.10.3 Structures on the Set of Trigonometric Polynomials	118

4.10.4 The Problem of Features Selection	119
4.11 The Problem of Capacity Control and Bayesian Inference .	119
4.11.1 The Bayesian Approach in Learning Theory	119
4.11.2 Discussion of the Bayesian Approach and Capacity	
Control Methods	121
Chapter 5 Methods of Pattern Recognition	123
5.1 Why Can Learning Machines Generalize?	123
5.2 Sigmoid Approximation of Indicator Functions	125
5.3 Neural Networks	126
5.3.1 The Back-Propagation Method	126
5.3.2 The Back-Propagation Algorithm	130
5.3.3 Neural Networks for the Regression	100
Estimation Problem	130
5.3.4 Remarks on the Back-Propagation Method	130
5.4 The Optimal Separating Hyperplane	131
5.4.1 The Optimal Hyperplane	131
5.4.2 $\Delta$ -margin hyperplanes	132
5.5 Constructing the Optimal Hyperplane	133
5.5.1 Generalization for the Nonseparable Case	136
5.6 Support Vector (SV) Machines	138
5.6.1 Generalization in High-Dimensional Space	139
5.6.2 Convolution of the Inner Product	140
5.6.3 Constructing SV Machines	141
5.6.4 Examples of SV Machines	141
5.7 Experiments with SV Machines	146
5.7.1 Example in the Plane	146
5.7.2 Handwritten Digit Recognition	147
5.7.3 Some Important Details	151
5.8 Remarks on SV Machines	154
5.9 SVM and Logistic Regression	156
5.9.1 Logistic Regression	156
5.9.2 The Risk Function for SVM	159
5.9.3 The SVM <sub>n</sub> Approximation of the Logistic Regression	160
5.10. Ensemble of the SVM	163
5.10.1 The AdaBoost Method	164
5.10.2 The Ensemble of SVMs	
	107
Informal Reasoning and Comments — 5	171
5.11 The Art of Engineering Versus Formal Inference	171
5.12 Wisdom of Statistical Models	174
5.13 What Can One Learn from Digit Recognition Experiments?	176
5.13.1 Influence of the Type of Structures and	
Accuracy of Capacity Control	177

5.13.2 SRM Principle and the Proble	m of	
Feature Construction		8
5.13.3 Is the Set of Support Vectors a	a Robust	
Characteristic of the Data? .		9
Chapter 6 Methods of Function Estimati		
6.1 $\varepsilon$ -Insensitive Loss-Function		
6.2 SVM for Estimating Regression Functi		
6.2.1 SV Machine with Convolved In		
6.2.2 Solution for Nonlinear Loss Fun		
6.2.3 Linear Optimization Method .		
6.3 Constructing Kernels for Estimating R		0
6.3.1 Kernels Generating Expansion of		
Orthogonal Polynomials		
6.3.2 Constructing Multidimensional		
6.4 Kernels Generating Splines		
6.4.1 Spline of Order <i>d</i> With a Finite		4
6.4.2 Kernels Generating Splines Wit		
Infinite Number of Nodes		
6.5 Kernels Generating Fourier Expansions		
6.5.1 Kernels for Regularized Fourier		7
6.6 The Support Vector ANOVA Decomp		~
Approximation and Regression Estima		
6.7 SVM for Solving Linear Operator Equa		
6.7.1 The Support Vector Method .		
6.8 Function Approximation Using the SV		1
6.8.1 Why Does the Value of $\varepsilon$ Control		_
Number of Support Vectors?		
6.9 SVM for Regression Estimation		
6.9.1 Problem of Data Smoothing		
6.9.2 Estimation of Linear Regression		
6.9.3 Estimation Nonlinear Regression	$1 \text{ Functions } \dots $	j
Informal Reasoning and Comments — 6	219	
6.10 Loss Functions for the Regression	215	,
•		)
6.11 Loss Functions for Robust Estimators		
6.12 Support Vector Regression Machine		
0.12 Support vector Regression Machine		)
Chapter 7 Direct Methods in Statistical 1	Learning Theory 225	ś
7.1 Problem of Estimating Densities, Cond		,
Probabilities, and Conditional Densities		3
7.1.1 Problem of Density Estimation:		
7.1.2 Problem of Conditional Probabi	-	
7.1.3 Problem of Conditional Density	5	
1.1.0 1 robicin of Conditional Delisity	Loumation	,

7.3       Glivenko-Cantelli Theorem       230         7.4       Ill-Posed Problems       232         7.4       Ill-Posed Problems       233         7.5       Three Methods of Solving Ill-Posed Problems       235         7.5.1       The Residual Principle       236         7.6       Main Assertions of the Theory of Ill-Posed Problems       237         7.6.1       Deterministic Ill-Posed Problems       237         7.6.2       Stochastic Ill-Posed Problem       238         7.7       Nonparametric Methods of Density Estimation       240         7.7.1       Consistency of the Solution of the Density       240         7.7.2       The Parzen's Estimators       241         7.8       SVM Solution of the Density Estimation Problem       244         7.8.1       The SVM Density Estimation       249         7.9.2       Conditional Probability Estimation       249         7.9.1       Approximately Defined Operator       251         7.9.2       SVM Method for Conditional Probability Estimation       253         7.10       Estimation of Conditional Density and Regression       256         7.10       Estimation of Conditional Density and Regression       256         7.11.2       One Can Use Both Labeled (Trainin	7.2 Solving an Approximately Determined Integral Equation	229
7.4       Ill-Posed Problems       233         7.5       Three Methods of Solving Ill-Posed Problems       235         7.5.1       The Residual Principle       236         7.5.1       The Residual Principle       236         7.6.1       Deterministic Ill-Posed Problems       237         7.6.2       Stochastic Ill-Posed Problem       238         7.7       Nonparametric Methods of Density Estimation       240         7.7.1       Consistency of the Solution of the Density       Estimation Problem       240         7.7.2       The Parzen's Estimators       241       7.8       SVM Solution of the Density Estimation Problem       244         7.8.1       The SVM Density Estimate: Summary       247       7.8.2       Comparison of the Parzen's and the SVM methods       248         7.9.2       Conditional Probability Estimation       249       7.9.1       Approximately Defined Operator       251         7.9.2       SVM Method for Conditional Probability Estimation       253       7.10       Estimation of Conditional Probability Estimate:       258         7.10       Estimation of Conditional Density and Regression       258       7.11.2       One Can Use a Good Estimate of the Unknown Density       258         7.11.2       One Can Use Both Labeled (Training) and Unlabeled <td>7.3 Glivenko-Cantelli Theorem</td> <td>230</td>	7.3 Glivenko-Cantelli Theorem	230
7.5       Three Methods of Solving Ill-Posed Problems       235         7.5.1       The Residual Principle       236         7.6       Main Assertions of the Theory of Ill-Posed Problems       237         7.6.1       Deterministic Ill-Posed Problems       237         7.6.2       Stochastic Ill-Posed Problem       238         7.7       Nonparametric Methods of Density Estimation       240         7.7.1       Consistency of the Solution of the Density       240         7.7.2       The Parzen's Estimators       241         7.8       SVM Solution of the Density Estimation Problem       244         7.8.1       The SVM Density Estimation Problem       244         7.8.2       Comparison of the Parzen's and the SVM methods       248         7.9       Conditional Probability Estimation       243         7.9.1       Approximately Defined Operator       251         7.9.2       SVM Conditional Probability Estimation       258         7.10       Estimation of Conditional Density and Regression       256         7.11       One Can Use a Good Estimate of the       Unknown Density       258         7.11.1       One Can Use a Good Estimate of the       259       259         7.11.3       Method for Obtaining Sparse Solutions of the Ill- <b< td=""><td>7.3.1 Kolmogorov-Smirnov Distribution</td><td>232</td></b<>	7.3.1 Kolmogorov-Smirnov Distribution	232
7.5.1 The Residual Principle       236         7.6 Main Assertions of the Theory of Ill-Posed Problems       237         7.6.1 Deterministic Ill-Posed Problems       237         7.6.2 Stochastic Ill-Posed Problem       238         7.7 Nonparametric Methods of Density Estimation       240         7.7.1 Consistency of the Solution of the Density       240         7.7.2 The Parzen's Estimators       240         7.7.2 The Parzen's Estimators       241         7.8 SVM Solution of the Density Estimation Problem       244         7.8.1 The SVM Density Estimate: Summary       247         7.8.2 Comparison of the Parzen's and the SVM methods       248         7.9 Conditional Probability Estimation       249         7.9.1 Approximately Defined Operator       253         7.9.2 SVM Method for Conditional Probability Estimation       253         7.10 Estimation of Conditional Density and Regression       256         7.10 Estimation of Conditional Density and Regression       258         7.11.1 One Can Use a Good Estimate of the Unknown Density       258         7.11.2 One Can Use Both Labeled (Training) and Unlabeled (Test) Data       259         7.11.3 Method for Obtaining Sparse Solutions of the Ill- Posed Problems       262         7.12 Three Elements of a Scientific Theory       261         7	7.4 Ill-Posed Problems	233
7.6Main Assertions of the Theory of Ill-Posed Problems2377.6.1Deterministic Ill-Posed Problems2387.6.2Stochastic Ill-Posed Problem2387.7Nonparametric Methods of Density Estimation2407.7.1Consistency of the Solution of the Density Estimation Problem2407.7.2The Parzen's Estimators2417.8SVM Solution of the Density Estimation Problem2447.8.1The SVM Density Estimate: Summary2477.8.2Comparison of the Parzen's and the SVM methods2487.9.2Gonditional Probability Estimation2497.9.1Approximately Defined Operator2517.9.2SVM Method for Conditional Probability Estimation2557.10Estimation of Conditional Probability Estimate: Summary2557.10Estimation of Conditional Density and Regression2567.11.2One Can Use a Good Estimate of the Unknown Density2587.11.2One Can Use Both Labeled (Trainig) and Unlabeled (Test) Data2597.11.3Method for Obtaining Sparse Solutions of the Ill- Posed Problems2627.12Three Elements of a Scientific Theory2617.12.2Theory of Ill-Posed Problems2627.13Stochastic Ill-Posed Problems2627.14Three Elements of a Scientific Theory2617.12.2Theory of Ill-Posed Problems2627.13Stochastic Ill-Posed Problems2627.14The Vicinal Risk Minimization Principle and th	7.5 Three Methods of Solving Ill-Posed Problems	235
7.6.1Deterministic Ill-Posed Problems2377.6.2Stochastic Ill-Posed Problem2387.7Nonparametric Methods of Density Estimation2407.7.1Consistency of the Solution of the Density2407.7.2The Parzen's Estimators2417.8SVM Solution of the Density Estimation Problem2447.8.1The SVM Density Estimatics2477.8.2Comparison of the Parzen's and the SVM methods2487.9Conditional Probability Estimation2497.9.1Approximately Defined Operator2517.9.2SVM Method for Conditional Probability Estimation2557.10Estimation of Conditional Probability Estimate: Summary2557.10Estimation of Conditional Density and Regression2567.11.2One Can Use a Good Estimate of the Unknown Density2587.11.2One Can Use Both Labeled (Training) and Unlabeled (Test) Data2597.12Three Elements of a Scientific Theory2617.12.1Problems2627.13Stochastic Ill-Posed Problems2627.13Stochastic Ill-Posed Problems2627.13Stochastic Ill-Posed Problems263Chapter 8The Vicinal Risk Minimization Principle2678.1Hard Vicinity Function2698.1.2Soft Vicinity Function2708.2VKMStochastic Ill-Posed2708.3Hard Vicinity Function2708.4Stochastic Ill-Fosed Problems	7.5.1 The Residual Principle	236
7.6.2Stochastic Ill-Posed Problem2387.7Nonparametric Methods of Density Estimation2407.7.1Consistency of the Solution of the Density2407.7.1Consistency of the Solution of the Density2417.8SVM Solution of the Density Estimators2417.8SVM Solution of the Density Estimation Problem2447.8.1The SVM Density Estimate: Summary2477.8.2Comparison of the Parzen's and the SVM methods2487.9Conditional Probability Estimation2497.9.1Approximately Defined Operator2517.9.2SVM Method for Conditional Probability Estimation2557.10Estimation of Conditional Probability Estimate: Summary2557.10Estimation of Conditional Density and Regression2567.11Remarks2587.11.1One Can Use a Good Estimate of the Unknown Density2597.11.3Method for Obtaining Sparse Solutions of the Ill- Posed Problems2597.12Three Elements of a Scientific Theory2617.12.1Problem of Density Estimation2627.12Theory of Ill-Posed Problems2627.13Stochastic Ill-Posed Problems263Chapter 8 The Vicinal Risk Minimization Principle and the SVMs2678.1Hard Vicinity Function2698.1.2Soft Vicinity Function2698.1.2Soft Vicinity Function2617.13Hard Vicinity Function2627.14	7.6 Main Assertions of the Theory of Ill-Posed Problems	237
7.7       Nonparametric Methods of Density Estimation       240         7.7.1       Consistency of the Solution of the Density Estimation Problem       240         7.7.2       The Parzen's Estimators       241         7.8       SVM Solution of the Density Estimation Problem       244         7.8.1       The SVM Density Estimate: Summary       247         7.8.2       Comparison of the Parzen's and the SVM methods       248         7.9       Conditional Probability Estimation       249         7.9.1       Approximately Defined Operator       251         7.9.2       SVM Method for Conditional Probability Estimation       253         7.9.3       The SVM Conditional Probability Estimate:       255         7.10       Estimation of Conditional Density and Regression       256         7.11       Remarks       258         7.11.1       One Can Use a Good Estimate of the Unknown Density       258         7.11.2       One Can Use Both Labeled (Training) and Unlabeled (Test) Data       259         7.11.3       Method for Obtaining Sparse Solutions of the Ill- Posed Problems       262         7.12       Theory of Ill-Posed Problems       262         7.13       Stochastic Ill-Posed Problems       262         7.13       Stochastic Ill-Posed Problems	7.6.1 Deterministic Ill-Posed Problems	237
7.7.1       Consistency of the Solution of the Density       240         7.7.2       The Parzen's Estimators       241         7.8       SVM Solution of the Density Estimation Problem       244         7.8.1       The SVM Density Estimation Problem       247         7.8.2       Comparison of the Parzen's and the SVM methods       248         7.9       Conditional Probability Estimation       249         7.9.1       Approximately Defined Operator       251         7.9.2       SVM Method for Conditional Probability Estimation       253         7.9.3       The SVM Conditional Probability Estimate:       255         7.10       Estimation of Conditional Density and Regression       256         7.11       Remarks       258         7.11.1       One Can Use a Good Estimate of the       258         7.11.2       One Can Use Both Labeled (Training) and Unlabeled       (Test) Data       259         7.11.3       Method for Obtaining Sparse Solutions of the Ill-       Posed Problems       259         7.12       Three Elements of a Scientific Theory       261       7.12.1       Problem of Density Estimation       262         7.12.1       Problem of Density Estimation       262       263       264         7.13       Stochastic Ill-Pose	7.6.2 Stochastic Ill-Posed Problem	238
Estimation Problem2407.7.2 The Parzen's Estimators2417.8 SVM Solution of the Density Estimation Problem2447.8.1 The SVM Density Estimate: Summary2477.8.2 Comparison of the Parzen's and the SVM methods2487.9 Conditional Probability Estimation2497.9.1 Approximately Defined Operator2517.9.2 SVM Method for Conditional Probability Estimation2537.9.3 The SVM Conditional Probability Estimation2567.10 Estimation of Conditional Density and Regression2567.11 Remarks2587.11.2 One Can Use a Good Estimate of the Unknown Density2587.11.2 One Can Use Both Labeled (Training) and Unlabeled (Test) Data2597.11.3 Method for Obtaining Sparse Solutions of the Ill- Posed Problems2627.12 Three Elements of a Scientific Theory2617.12.1 Problem of Density Estimation2627.13 Stochastic Ill-Posed Problems263Chapter 8 The Vicinal Risk Minimization Principle and the SVMs2678.1 The Vicinal Risk Minimization Principle2678.1.1 Hard Vicinity Function2698.1.2 Soft Vicinal Kernels2708.2 VRM Method for the Pattern Recognition Problem2718.3 Examples of Vicinal Kernels2758.3.1 Hard Vicinity Functions276	7.7 Nonparametric Methods of Density Estimation	<b>240</b>
7.7.2 The Parzen's Estimators       241         7.8 SVM Solution of the Density Estimation Problem       244         7.8.1 The SVM Density Estimate: Summary       247         7.8.2 Comparison of the Parzen's and the SVM methods       248         7.9 Conditional Probability Estimation       249         7.9.1 Approximately Defined Operator       251         7.9.2 SVM Method for Conditional Probability Estimation       253         7.9.3 The SVM Conditional Probability Estimate:       255         7.10 Estimation of Conditional Density and Regression       256         7.11 Remarks       258         7.11.1 One Can Use a Good Estimate of the       1000000000000000000000000000000000000	7.7.1 Consistency of the Solution of the Density	
7.8       SVM Solution of the Density Estimation Problem       244         7.8.1       The SVM Density Estimate: Summary       247         7.8.2       Comparison of the Parzen's and the SVM methods       248         7.9       Conditional Probability Estimation       249         7.9.1       Approximately Defined Operator       251         7.9.2       SVM Method for Conditional Probability Estimation       253         7.9.3       The SVM Conditional Probability Estimate:       255         7.10       Estimation of Conditional Density and Regression       256         7.11       Remarks       258         7.11.1       One Can Use a Good Estimate of the       258         7.11.2       One Can Use Both Labeled (Training) and Unlabeled       259         7.11.3       Method for Obtaining Sparse Solutions of the Ill-       259         7.12       Three Elements of a Scientific Theory       261         7.12.1       Problem of Density Estimation       262         7.13       Stochastic Ill-Posed Problems       262         7.14       Theory of Ill-Posed Problems       262         7.15       Theory of Ill-Posed Problems       262         7.16       Stochastic Ill-Posed Problems       262         7.13       Stocha		240
7.8.1 The SVM Density Estimate: Summary       247         7.8.2 Comparison of the Parzen's and the SVM methods       248         7.9 Conditional Probability Estimation       249         7.9.1 Approximately Defined Operator       251         7.9.2 SVM Method for Conditional Probability Estimation       253         7.9.3 The SVM Conditional Probability Estimation       255         7.10 Estimation of Conditional Density and Regression       256         7.11 Remarks       258         7.11.1 One Can Use a Good Estimate of the       Unknown Density         Unknown Density       258         7.11.2 One Can Use Both Labeled (Training) and Unlabeled       (Test) Data         (Test) Data       259         7.11.3 Method for Obtaining Sparse Solutions of the Ill- Posed Problems       259         7.12 Three Elements of a Scientific Theory       261         7.12.1 Problem of Density Estimation       262         7.13 Stochastic Ill-Posed Problems       263         Chapter 8 The Vicinal Risk Minimization Principle and the SVMs       267         8.1 The Vicinal Risk Minimization Principle       267         8.1.2 Soft Vicinity Function       270         8.2 VRM Method for the Pattern Recognition Problem       271         8.3 Examples of Vicinal Kernels       275	7.7.2 The Parzen's Estimators	241
7.8.2 Comparison of the Parzen's and the SVM methods       248         7.9 Conditional Probability Estimation       249         7.9.1 Approximately Defined Operator       251         7.9.2 SVM Method for Conditional Probability Estimation       253         7.9.3 The SVM Conditional Probability Estimation       255         7.10 Estimation of Conditional Density and Regression       256         7.11 Remarks       258         7.11.1 One Can Use a Good Estimate of the       Unknown Density         Unknown Density       258         7.11.2 One Can Use Both Labeled (Training) and Unlabeled       (Test) Data         (Test) Data       259         7.11.3 Method for Obtaining Sparse Solutions of the Ill- Posed Problems       259         7.12 Three Elements of a Scientific Theory       261         7.12.1 Problem of Density Estimation       262         7.13 Stochastic Ill-Posed Problems       263         Chapter 8 The Vicinal Risk Minimization Principle and the SVMs         8.1 The Vicinal Risk Minimization Principle       267         8.1.1 Hard Vicinity Function       269         8.1.2 Soft Vicinity Function       270         8.2 VRM Method for the Pattern Recognition Problem       271         8.3 Examples of Vicinal Kernels       275	7.8 SVM Solution of the Density Estimation Problem	<b>244</b>
7.9 Conditional Probability Estimation       249         7.9.1 Approximately Defined Operator       251         7.9.2 SVM Method for Conditional Probability Estimation       253         7.9.3 The SVM Conditional Probability Estimation       255         7.10 Estimation of Conditional Density and Regression       256         7.11 Remarks       258         7.11.1 One Can Use a Good Estimate of the       258         7.11.2 One Can Use Both Labeled (Training) and Unlabeled       259         7.11.3 Method for Obtaining Sparse Solutions of the Ill-       259         7.12 Three Elements of a Scientific Theory       261         7.12 Three Elements of a Scientific Theory       262         7.13 Stochastic Ill-Posed Problems       262         7.13 Stochastic Ill-Posed Problems       263         Chapter 8 The Vicinal Risk Minimization Principle and the SVMs         8.1 The Vicinal Risk Minimization Principle       267         8.1.1 Hard Vicinity Function       269         8.1.2 Soft Vicinity Function       270         8.2 VRM Method for the Pattern Recognition Problem       271         8.3 Examples of Vicinal Kernels       275         8.3.1 Hard Vicinity Functions       275	7.8.1 The SVM Density Estimate: Summary	247
7.9.1 Approximately Defined Operator       251         7.9.2 SVM Method for Conditional Probability Estimation       253         7.9.3 The SVM Conditional Probability Estimate:       255         7.10 Estimation of Conditional Density and Regression       256         7.11 Remarks       258         7.11 One Can Use a Good Estimate of the       258         7.11.1 One Can Use a Good Estimate of the       258         7.11.2 One Can Use Both Labeled (Training) and Unlabeled       259         7.11.3 Method for Obtaining Sparse Solutions of the Ill-       259         7.12 Three Elements of a Scientific Theory       261         7.12 Three Elements of a Scientific Theory       262         7.13 Stochastic Ill-Posed Problems       262         7.13 Stochastic Ill-Posed Problems       263         Chapter 8 The Vicinal Risk Minimization Principle and         the SVMs       267         8.1 The Vicinal Risk Minimization Principle       267         8.1.1 Hard Vicinity Function       270         8.2 VRM Method for the Pattern Recognition Problem       271         8.3 Examples of Vicinal Kernels       275         8.3.1 Hard Vicinity Functions       275	$7.8.2$ Comparison of the Parzen's and the SVM methods $\therefore$	<b>248</b>
7.9.2 SVM Method for Conditional Probability Estimation       253         7.9.3 The SVM Conditional Probability Estimate:       255         7.10 Estimation of Conditional Density and Regression       255         7.11 Remarks       258         7.11 Remarks       258         7.11 One Can Use a Good Estimate of the       258         7.11.1 One Can Use a Good Estimate of the       258         7.11.2 One Can Use Both Labeled (Training) and Unlabeled       259         7.11.3 Method for Obtaining Sparse Solutions of the Ill-       259         7.12 Three Elements of a Scientific Theory       261         7.12.1 Problem of Density Estimation       262         7.13 Stochastic Ill-Posed Problems       262         7.13 Stochastic Ill-Posed Problems       263         Chapter 8 The Vicinal Risk Minimization Principle and         the SVMs       267         8.1 The Vicinal Risk Minimization Principle       267         8.1.1 Hard Vicinity Function       269         8.1.2 Soft Vicinity Function       270         8.2 VRM Method for the Pattern Recognition Problem       271         8.3 Examples of Vicinal Kernels       275         8.3.1 Hard Vicinity Functions       275	7.9 Conditional Probability Estimation	249
7.9.3 The SVM Conditional Probability Estimate:       255         Summary       255         7.10 Estimation of Conditional Density and Regression       256         7.11 Remarks       258         7.11 Remarks       258         7.11 One Can Use a Good Estimate of the       258         0.11.1 One Can Use a Good Estimate of the       258         0.11.2 One Can Use Both Labeled (Training) and Unlabeled       259         7.11.3 Method for Obtaining Sparse Solutions of the Ill-       259         7.12 Three Elements of a Scientific Theory       261         7.12.1 Problem of Density Estimation       262         7.13 Stochastic Ill-Posed Problems       262         7.13 Stochastic Ill-Posed Problems       263         Chapter 8 The Vicinal Risk Minimization Principle and         the SVMs       267         8.1 The Vicinal Risk Minimization Principle       267         8.1.1 Hard Vicinity Function       269         8.1.2 Soft Vicinity Function       270         8.2 VRM Method for the Pattern Recognition Problem       271         8.3 Examples of Vicinal Kernels       275         8.3.1 Hard Vicinity Functions       275		
Summary2557.10Estimation of Conditional Density and Regression2567.11Remarks2587.11.1One Can Use a Good Estimate of the Unknown Density2587.11.2One Can Use Both Labeled (Training) and Unlabeled (Test) Data2597.11.3Method for Obtaining Sparse Solutions of the Ill- Posed Problems2597.12Three Elements of a Scientific Theory2617.12.1Problem of Density Estimation2627.12.2Theory of Ill-Posed Problems2627.13Stochastic Ill-Posed Problems263Chapter 8 The Vicinal Risk Minimization Principle and the SVMs8.1The Vicinal Risk Minimization Principle2678.1.1Hard Vicinity Function2698.1.2Soft Vicinity Function2708.2VRM Method for the Pattern Recognition Problem2718.3Examples of Vicinal Kernels2758.3.1Hard Vicinity Functions276		253
7.10       Estimation of Conditional Density and Regression       256         7.11       Remarks       258         7.11.1       One Can Use a Good Estimate of the Unknown Density       258         7.11.2       One Can Use Both Labeled (Training) and Unlabeled (Test) Data       259         7.11.3       Method for Obtaining Sparse Solutions of the Ill- Posed Problems       259         7.12       Three Elements of a Scientific Theory       261         7.12.1       Problem of Density Estimation       262         7.12.2       Theory of Ill-Posed Problems       262         7.13       Stochastic Ill-Posed Problems       263         Chapter 8 The Vicinal Risk Minimization Principle and the SVMs         8.1       The Vicinal Risk Minimization Principle       267         8.1.1       Hard Vicinity Function       269         8.1.2       Soft Vicinity Function       270         8.2       VRM Method for the Pattern Recognition Problem       271         8.3       Examples of Vicinal Kernels       275         8.3.1       Hard Vicinity Functions       275	7.9.3 The SVM Conditional Probability Estimate:	
7.11 Remarks       258         7.11.1 One Can Use a Good Estimate of the       Unknown Density       258         7.11.2 One Can Use Both Labeled (Training) and Unlabeled       (Test) Data       259         7.11.3 Method for Obtaining Sparse Solutions of the Ill-       259         7.11.3 Method for Obtaining Sparse Solutions of the Ill-       259         7.12 Three Elements of a Scientific Theory       261         7.12.1 Problem of Density Estimation       262         7.13 Stochastic Ill-Posed Problems       262         7.13 Stochastic Ill-Posed Problems       263         Chapter 8 The Vicinal Risk Minimization Principle and the SVMs         8.1 The Vicinal Risk Minimization Principle       267         8.1.1 Hard Vicinity Function       269         8.1.2 Soft Vicinity Function       270         8.2 VRM Method for the Pattern Recognition Problem       271         8.3 Examples of Vicinal Kernels       275         8.3.1 Hard Vicinity Functions       275	5	
7.11.1       One Can Use a Good Estimate of the Unknown Density       258         7.11.2       One Can Use Both Labeled (Training) and Unlabeled (Test) Data       259         7.11.3       Method for Obtaining Sparse Solutions of the Ill- Posed Problems       259         7.11.3       Method for Obtaining Sparse Solutions of the Ill- Posed Problems       261         7.12       Three Elements of a Scientific Theory       261         7.12.1       Problem of Density Estimation       262         7.12.2       Theory of Ill-Posed Problems       262         7.13       Stochastic Ill-Posed Problems       263         Chapter 8 The Vicinal Risk Minimization Principle and the SVMs         8.1       The Vicinal Risk Minimization Principle       267         8.1.1       Hard Vicinity Function       269         8.1.2       Soft Vicinity Function       270         8.2       VRM Method for the Pattern Recognition Problem       271         8.3       Examples of Vicinal Kernels       275         8.3.1       Hard Vicinity Functions       275	7.10 Estimation of Conditional Density and Regression	
Unknown Density2587.11.2 One Can Use Both Labeled (Training) and Unlabeled (Test) Data2597.11.3 Method for Obtaining Sparse Solutions of the Ill- Posed Problems259Informal Reasoning and Comments72617.12 Three Elements of a Scientific Theory2617.12.1 Problem of Density Estimation2627.12.2 Theory of Ill-Posed Problems2627.13 Stochastic Ill-Posed Problems263Chapter 8 The Vicinal Risk Minimization Principle and the SVMs8.1 The Vicinal Risk Minimization Principle2678.1.1 Hard Vicinity Function2708.2 VRM Method for the Pattern Recognition Problem2718.3 Examples of Vicinal Kernels2758.3.1 Hard Vicinity Functions276		258
7.11.2 One Can Use Both Labeled (Training) and Unlabeled (Test) Data       259         7.11.3 Method for Obtaining Sparse Solutions of the Ill-Posed Problems       259         7.11.3 Method for Obtaining Sparse Solutions of the Ill-Posed Problems       259         Informal Reasoning and Comments       7         261       7.12 Three Elements of a Scientific Theory       261         7.12.1 Problem of Density Estimation       262         7.12.2 Theory of Ill-Posed Problems       262         7.13 Stochastic Ill-Posed Problems       263         Chapter 8 The Vicinal Risk Minimization Principle and the SVMs         8.1 The Vicinal Risk Minimization Principle       267         8.1.1 Hard Vicinity Function       270         8.2 VRM Method for the Pattern Recognition Problem       271         8.3 Examples of Vicinal Kernels       275         8.3.1 Hard Vicinity Functions       276		
(Test) Data2597.11.3 Method for Obtaining Sparse Solutions of the Ill- Posed Problems259Informal Reasoning and Comments72617.12 Three Elements of a Scientific Theory2617.12.1 Problem of Density Estimation2627.12.2 Theory of Ill-Posed Problems2627.13 Stochastic Ill-Posed Problems263Chapter 8 The Vicinal Risk Minimization Principle and the SVMs8.1 The Vicinal Risk Minimization Principle2678.1.1 Hard Vicinity Function2698.1.2 Soft Vicinity Function2708.2 VRM Method for the Pattern Recognition Problem2718.3 Examples of Vicinal Kernels2758.3.1 Hard Vicinity Functions276		258
7.11.3       Method for Obtaining Sparse Solutions of the Ill-Posed Problems       259         Informal Reasoning and Comments — 7       261         7.12       Three Elements of a Scientific Theory       261         7.12.1       Problem of Density Estimation       262         7.12.2       Theory of Ill-Posed Problems       262         7.13       Stochastic Ill-Posed Problems       263         Chapter 8 The Vicinal Risk Minimization Principle and the SVMs         8.1       The Vicinal Risk Minimization Principle       267         8.1       The Vicinity Function       267         8.1.2       Soft Vicinity Function       270         8.2       VRM Method for the Pattern Recognition Problem       271         8.3       Examples of Vicinal Kernels       275         8.3.1       Hard Vicinity Functions       276		050
Posed Problems259Informal Reasoning and Comments — 72617.12 Three Elements of a Scientific Theory2617.12.1 Problem of Density Estimation2627.12.2 Theory of Ill-Posed Problems2627.13 Stochastic Ill-Posed Problems263Chapter 8 The Vicinal Risk Minimization Principle and the SVMs8.1 The Vicinal Risk Minimization Principle2678.1.1 Hard Vicinity Function2698.1.2 Soft Vicinity Function2708.2 VRM Method for the Pattern Recognition Problem2718.3 Examples of Vicinal Kernels2758.3.1 Hard Vicinity Functions276		259
Informal Reasoning and Comments — 7       261         7.12 Three Elements of a Scientific Theory       261         7.12.1 Problem of Density Estimation       262         7.12.2 Theory of Ill-Posed Problems       262         7.13 Stochastic Ill-Posed Problems       263         Chapter 8 The Vicinal Risk Minimization Principle and the SVMs         8.1 The Vicinal Risk Minimization Principle       267         8.1.1 Hard Vicinity Function       269         8.1.2 Soft Vicinity Function       270         8.2 VRM Method for the Pattern Recognition Problem       271         8.3 Examples of Vicinal Kernels       275         8.3.1 Hard Vicinity Functions       276		250
7.12 Three Elements of a Scientific Theory       261         7.12.1 Problem of Density Estimation       262         7.12.2 Theory of Ill-Posed Problems       262         7.13 Stochastic Ill-Posed Problems       263         Chapter 8 The Vicinal Risk Minimization Principle and the SVMs         267       8.1 The Vicinal Risk Minimization Principle         8.1 The Vicinal Risk Minimization Principle       267         8.1.1 Hard Vicinity Function       269         8.1.2 Soft Vicinity Function       270         8.2 VRM Method for the Pattern Recognition Problem       271         8.3 Examples of Vicinal Kernels       275         8.3.1 Hard Vicinity Functions       276		209
7.12 Three Elements of a Scientific Theory       261         7.12.1 Problem of Density Estimation       262         7.12.2 Theory of Ill-Posed Problems       262         7.13 Stochastic Ill-Posed Problems       263         Chapter 8 The Vicinal Risk Minimization Principle and the SVMs         267       8.1 The Vicinal Risk Minimization Principle         8.1 The Vicinal Risk Minimization Principle       267         8.1.1 Hard Vicinity Function       269         8.1.2 Soft Vicinity Function       270         8.2 VRM Method for the Pattern Recognition Problem       271         8.3 Examples of Vicinal Kernels       275         8.3.1 Hard Vicinity Functions       276	Informal Reasoning and Comments $-7$	<b>26</b> 1
7.12.1 Problem of Density Estimation       262         7.12.2 Theory of Ill-Posed Problems       262         7.13 Stochastic Ill-Posed Problems       263         Chapter 8 The Vicinal Risk Minimization Principle and the SVMs         267       8.1 The Vicinal Risk Minimization Principle         8.1 The Vicinal Risk Minimization Principle       267         8.1.1 Hard Vicinity Function       269         8.1.2 Soft Vicinity Function       270         8.2 VRM Method for the Pattern Recognition Problem       271         8.3 Examples of Vicinal Kernels       275         8.3.1 Hard Vicinity Functions       276		261
7.12.2 Theory of Ill-Posed Problems       262         7.13 Stochastic Ill-Posed Problems       263         Chapter 8 The Vicinal Risk Minimization Principle and the SVMs         8.1 The Vicinal Risk Minimization Principle       267         8.1 The Vicinal Risk Minimization Principle       267         8.1.1 Hard Vicinity Function       269         8.1.2 Soft Vicinity Function       270         8.2 VRM Method for the Pattern Recognition Problem       271         8.3 Examples of Vicinal Kernels       275         8.3.1 Hard Vicinity Functions       276	-	262
7.13       Stochastic Ill-Posed Problems       263         Chapter 8 The Vicinal Risk Minimization Principle and the SVMs       267         8.1       The Vicinal Risk Minimization Principle       267         8.1       The Vicinal Risk Minimization Principle       267         8.1.1       Hard Vicinity Function       269         8.1.2       Soft Vicinity Function       270         8.2       VRM Method for the Pattern Recognition Problem       271         8.3       Examples of Vicinal Kernels       275         8.3.1       Hard Vicinity Functions       276	· ·	262
the SVMs2678.1 The Vicinal Risk Minimization Principle2678.1.1 Hard Vicinity Function2698.1.2 Soft Vicinity Function2708.2 VRM Method for the Pattern Recognition Problem2718.3 Examples of Vicinal Kernels2758.3.1 Hard Vicinity Functions276		263
the SVMs2678.1 The Vicinal Risk Minimization Principle2678.1.1 Hard Vicinity Function2698.1.2 Soft Vicinity Function2708.2 VRM Method for the Pattern Recognition Problem2718.3 Examples of Vicinal Kernels2758.3.1 Hard Vicinity Functions276		
8.1 The Vicinal Risk Minimization Principle2678.1.1 Hard Vicinity Function2698.1.2 Soft Vicinity Function2708.2 VRM Method for the Pattern Recognition Problem2718.3 Examples of Vicinal Kernels2758.3.1 Hard Vicinity Functions276	Chapter 8 The Vicinal Risk Minimization Principle and	
8.1.1 Hard Vicinity Function2698.1.2 Soft Vicinity Function2708.2 VRM Method for the Pattern Recognition Problem2718.3 Examples of Vicinal Kernels2758.3.1 Hard Vicinity Functions276	${\bf the\ SVMs}$	267
8.1.2 Soft Vicinity Function2708.2 VRM Method for the Pattern Recognition Problem2718.3 Examples of Vicinal Kernels2758.3.1 Hard Vicinity Functions276	8.1 The Vicinal Risk Minimization Principle	267
<ul> <li>8.2 VRM Method for the Pattern Recognition Problem 271</li> <li>8.3 Examples of Vicinal Kernels</li></ul>	8.1.1 Hard Vicinity Function	
8.3 Examples of Vicinal Kernels	8.1.2 Soft Vicinity Function	
8.3.1 Hard Vicinity Functions	8.2 VRM Method for the Pattern Recognition Problem	271
J.J. J.	8.3 Examples of Vicinal Kernels	275
8.3.2 Soft Vicinity Functions	8.3.1 Hard Vicinity Functions	276
	8.3.2 Soft Vicinity Functions	279

8.4 Nonsymmetric Vicinities	279
8.5. Generalization for Estimation Real-Valued Functions	281
8.6 Estimating Density and Conditional Density	
8.6.1 Estimating a Density Function	
8.6.2 Estimating a Conditional Probability Function	
8.6.3 Estimating a Conditional Density Function	286
8.6.4 Estimating a Regression Function	
Informal Reasoning and Comments — 8	289
Chapter 9 Conclusion: What Is Important in	
Learning Theory?	<b>29</b> 1
9.1 What Is Important in the Setting of the Problem?	291
9.2 What Is Important in the Theory of Consistency of Learning	
Processes?	294
9.3 What Is Important in the Theory of Bounds?	295
9.4 What Is Important in the Theory for Controlling the	
Generalization Ability of Learning Machines?	296
9.5 What Is Important in the Theory for Constructing	
Learning Algorithms?	297
9.6 What Is the Most Important?	
References	301
Remarks on References	301
References	302
Index	311