# Lecture Notes in Artificial Intelligence 12336

#### Subseries of Lecture Notes in Computer Science

Series Editors

Randy Goebel University of Alberta, Edmonton, Canada Yuzuru Tanaka Hokkaido University, Sapporo, Japan Wolfgang Wahlster DFKI and Saarland University, Saarbrücken, Germany

Founding Editor

Jörg Siekmann DFKI and Saarland University, Saarbrücken, Germany More information about this series at http://www.springer.com/series/1244

Andrey Ronzhin · Gerhard Rigoll · Roman Meshcheryakov (Eds.)

# Interactive Collaborative Robotics

5th International Conference, ICR 2020 St Petersburg, Russia, October 7–9, 2020 Proceedings



*Editors* Andrey Ronzhin St. Petersburg Federal Research Center of the Russian Academy of Sciences St. Petersburg, Russia

Roman Meshcheryakov Institute of Control Sciences of the Russian Academy of Sciences Moscow, Russia Gerhard Rigoll Technical University of Munich Munich, Germany

ISSN 0302-9743 ISSN 1611-3349 (electronic) Lecture Notes in Artificial Intelligence ISBN 978-3-030-60336-6 ISBN 978-3-030-60337-3 (eBook) https://doi.org/10.1007/978-3-030-60337-3

LNCS Sublibrary: SL7 - Artificial Intelligence

#### © Springer Nature Switzerland AG 2020

This work is subject to copyright. All rights are reserved by the Publisher, whether the whole or part of the material is concerned, specifically the rights of translation, reprinting, reuse of illustrations, recitation, broadcasting, reproduction on microfilms or in any other physical way, and transmission or information storage and retrieval, electronic adaptation, computer software, or by similar or dissimilar methodology now known or hereafter developed.

The use of general descriptive names, registered names, trademarks, service marks, etc. in this publication does not imply, even in the absence of a specific statement, that such names are exempt from the relevant protective laws and regulations and therefore free for general use.

The publisher, the authors and the editors are safe to assume that the advice and information in this book are believed to be true and accurate at the date of publication. Neither the publisher nor the authors or the editors give a warranty, expressed or implied, with respect to the material contained herein or for any errors or omissions that may have been made. The publisher remains neutral with regard to jurisdictional claims in published maps and institutional affiliations.

This Springer imprint is published by the registered company Springer Nature Switzerland AG The registered company address is: Gewerbestrasse 11, 6330 Cham, Switzerland

#### ICR 2020 Preface

The 5th International Conference on Interactive Collaborative Robotics (ICR 2020) was organized as a satellite event of the 22nd International Conference on Speech and Computer (SPECOM 2020) by the St. Petersburg Institute for Informatics and Automation of the Russian Academy of Sciences (SPIIRAS, St. Petersburg, Russia) and the Technical University of Munich (TUM, Munich, Germany). In July 2020, SPIIRAS incorporated five other research institutions, but has now been transformed into the St. Petersburg Federal Research Center of the Russian Academy of Sciences (SPC RAS).

ICR 2020 was organized as a virtual conference in the online format during October 7–9, 2020. Challenges of human-robot interaction, robot control and behavior in social robotics and collaborative robotics, as well as applied robotic and cyber-physical systems were mainly discussed at the conference.

During the conference an invited talk "A Concept for a Human-Robot Collaboration Workspace using Proximity Sensors" was given by Prof. Ilshat Mamaev (Karlsruhe Institute of Technology, Germany).

Due to the COVID-19 global pandemic, for the first time, ICR 2020 was organized as a fully virtual conference. The virtual conference, in the online format by Zoom had a number of advantages including: an increased number of participants because listeners could take part without any fees, essentially reduced registration fees for authors of the presented papers, no costs for travel and accommodation, a paperless green conference with only electronic proceedings, free access to video presentations after the conference, comfortable home conditions, etc.

This volume contains a collection of 31 papers presented at the conference, which were thoroughly reviewed by members of the Program Committee consisting of more than 20 top specialists in the conference topic areas. Theoretical and more general contributions were presented in common (plenary) sessions. Problem-oriented sessions as well as panel discussions then brought together specialists in limited problem areas with the aim of exchanging knowledge and skills resulting from research projects of all kinds.

Last but not least, we would like to express our gratitude to the authors for providing their papers on time, to the members of the conference reviewing team and Program Committee for their careful reviews and paper selection, and to the editors for their hard work preparing this volume. Special thanks are due to the members of the Local Organizing Committee for their tireless effort and enthusiasm during the conference organization. We hope that you benefitted from the event and that you also enjoyed the social program prepared by the members of the Organizing Committee.

October 2020

Andrey Ronzhin Gerhard Rigoll Roman Meshcheryakov

#### Organization

The ICR 2020 conference was organized by the St. Petersburg Institute for Informatics and Automation of the Russian Academy of Sciences (SPIIRAS, St. Petersburg, Russia) in cooperation with the Technical University of Munich (TUM, Munich, Germany). The conference website is located at: http://www.specom.nw.ru/icr2020/.

#### **Program Committee**

Roman Meshcheryakov (Co-chair), Russia Gerhard Rigoll (Co-chair), Germany Andrey Ronzhin (Co-chair), Russia Andres Annuk, Estonia Christos Antonopoulos, Greece Branislav Borovac, Serbia Oleg Darintsev, Russia Ivan Ermolov, Russia Rinat Galin, Russia Oliver Jokisch, Germany Igor Kalyaev, Russia Alexey Kashevnik, Russia Dongheui Lee, Germany Evgeni Magid, Russia Vladimir Pavlovskiy, Russia Viacheslav Pshikhopov, Russia Mirko Rakovic, Serbia José Rosado, Portugal Hooman Samani, Taiwan Jesus Savage, Mexico Anton Saveliev, Russia Evgeny Shandarov, Russia Lev Stankevich, Russia Tilo Strutz, Germany Sergey Yatsun, Russia Zeynep Yucel, Japan Milos Zelezny, Czech Republic Lyudmila Zinchenko, Russia

### **Organizing Committee**

Andrey Ronzhin (Chair) Anton Saveliev Dmitry Ryumin Natalia Kashina Ekaterina Miroshnikova Margarita Avstriyskaya Natalia Dormidontova Dmitriy Levonevskiy

## Contents

A Concept for a HRC Workspace Using Proximity Sensors Ilshat Mamaev, Hosam Alagi, Gergely Sóti, and Björn Hein	1
Approach to Obstacle Localization for Robot Navigation in Agricultural Territories Egor Aksamentov, Marina Astapova, and Elizaveta Usina	13
Person-Following Algorithm Based on Laser Range Finder and Monocular Camera Data Fusion for a Wheeled Autonomous Mobile Robot Elvira Chebotareva, Ramil Safin, Kuo-Hsien Hsia, Alexander Carballo, and Evgeni Magid	21
On the Problems of SLAM Simulation for Mobile Robots in the Arctic Conditions. Elvira Chebotareva, Tatyana Tsoy, Bulat Abbyasov, Jamila Mustafina, Edgar A. Martinez-Garcia, Yang Bai, and Mikhail Svinin	34
Data Exchange Method for Wireless UAV-Aided Communication in Sensor Systems and Robotic Devices	45
A Combination of Theta*, ORCA and Push and Rotate for Multi-agent Navigation	55
Evaluation of Image Synthesis for Automotive Purposes Václav Diviš and Marek Hrúz	67
Collision Detection in the Work of Collaborative Robots Using an Intelligent System	78
Method of Formation of Reference Movement Speed of Working Tool of Multilink Manipulator	89
Distributing Tasks in Multi-agent Robotic System for Human-Robot Interaction Applications	99
A*-Based Path Planning Algorithm for Swarm Robotics	107

Modeling of Human-Machine Interaction in an Industrial Exoskeleton	
Control System Sergey Jatsun, Andrei Malchikov, Oksana Loktionova, and Andrey Yatsun	116
Gesture-Based Intelligent User Interface for Control of an Assistive Mobile	
Information Robot	126
Distributed Methods for Autonomous Robot Groups	
Fault-Tolerant Management	135
Planning to Score a Goal in Robotic Football with Heuristic Search Ivan Khokhlov, Vladimir Litvinenko, Ilya Ryakin, and Konstantin Yakovlev	148
Q-Learning of Spatial Actions for Hierarchical Planner	
of Cognitive Agents	160
Modeling of Increased Rigidity of Industrial Manipulator Eugene Larkin, Aleksey Bogomolov, and Maxim Antonov	170
Accurate Autonomous UAV Landing Using Vision-Based Detection	
of ArUco-Marker	179
Spatial Resolution-Independent CNN-Based Person Detection in	
Agricultural Image Data	189
Fast Face Features Extraction Based on Deep Neural Networks for Mobile	
Robotic Platforms	200
An Estimation of Distributed Algorithms of the Fault-Tolerant Management	
in the Robot Groups	212
Comparison of ROS-Based Monocular Visual SLAM Methods: DSO,	
LDSO, ORB-SLAM2 and DynaSLAM	222
Cooperative Guidance for Waypoint Following of Distributed	
Multi-UAV System  Tagir Muslimov and Rustem Munasypov	234

Contents	xi
Contents	Л

Indoor vs. Outdoor Scene Classification for Mobile Robots Petr Neduchal, Ivan Gruber, and Miloš Železný	243
Mathematical Modelling of Control and Simultaneous Stabilization of 3-DOF Aerial Manipulation System	253
Comparative Analysis of Approaches to Depth Map Generation for Robot Navigation Julia Rubtsova and Roman Iakovlev	265
Approach to the State Analysis of Industry 4.0 Nodes Based on Behavioral Patterns Viktor Semenov, Mikhail Sukhoparov, and Ilya Lebedev	273
Humanoid Robot Soccer Player for RoboCup Junior League Competitions Evgeny Shandarov, Ilya Shabalin, Irina Prokazina, Vladimir Zhelonkin, Egor Polyntsev, and Alina Sogomonyants	283
A Modular Deep Learning Architecture for Anomaly Detection in HRI Gergely Sóti, Ilshat Mamaev, and Björn Hein	295
Algorithms of Posteriori Multi-objective Optimization for Robotic Gripper Design	308
Energy-Efficient Path Planning Algorithm on Three-Dimensional Large-Scale Terrain Maps for Mobile Robots	319
Author Index	331