Reconfiguration of Connected Graph Partitions via Recombination^{*}

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Abstract

Motivated by applications in gerrymandering detection, we study a reconfiguration problem on connected partitions of a connected graph G. A partition of V(G) is **connected** if every part induces a connected subgraph. In many applications, it is desirable to obtain parts of roughly the same size, possibly with some slack s. A **Balanced Connected** k-**Partition with slack** s, denoted (k, s)-**BCP**, is a partition of V(G) into k nonempty subsets, of sizes n_1, \ldots, n_k with $|n_i - n/k| \leq s$, each of which induces a connected subgraph (when s = 0, the k parts are perfectly balanced, and we call it k-**BCP** for short).

A recombination is an operation that takes a (k, s)-BCP of a graph G and produces another by merging two adjacent subgraphs and repartitioning them. Given two k-BCPs, A and B, of Gand a slack $s \ge 0$, we wish to determine whether there exists a sequence of recombinations that transform A into B via (k, s)-BCPs. We obtain four results related to this problem: (1) When s is unbounded, the transformation is always possible using at most 6(k - 1) recombinations. (2) If G is Hamiltonian, the transformation is possible using O(kn) recombinations for any $s \ge n/k$, and (3) we provide negative instances for $s \le n/(3k)$. (4) We show that the problem is PSPACE-complete when $k \in O(n^{\varepsilon})$ and $s \in O(n^{1-\varepsilon})$, for any constant $0 < \varepsilon \le 1$, even for restricted settings such as when G is an edge-maximal planar graph or when k = 3 and G is planar.

1 Introduction

Partitioning the vertex set of a graph G = (V, E) into k nonempty subsets $V = \bigcup_{i=1}^{k} V_i$ that each induces a connected graph $G[V_i]$ is a classical problem, known as the **Connected Graph Partition** problem [9, 16]. Motivated by fault-tolerant network design and facility location problems, it is part of a broader family of problems where each induced graph $G[V_i]$ must have a certain graph property (e.g., ℓ -connected or H-minor-free). In some instances, it is desirable that the parts V_1, \ldots, V_k have the approximately the same size (depending on some pre-established threshold). A **Balanced Connected** k-Partition (for short, k-BCP) is a connected partition requiring that $|V_i| = n/k$, for $i \in \{1, \ldots, k\}$ where n = |V(G)| is the total number of vertices. Dyer and Frieze [7] proved that finding a k-BCP is NP-hard for all $2 \le k \le n/3$. For k = 2, 3 the problem can be solved efficiently

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when G is bi- or triconnected, respectively [19, 22], and is equivalent to the perfect matching problem for k = n/2. Later Chlebíková [4] and Chataigner et al. [3] obtained approximation and inapproximability results for maximizing the "balance" ratio $\max_i |V_i| / \min_j |V_j|$ over all connected *k*-partitions. See also [12, 14, 18, 23] for variants under various other optimization criteria.

In this paper, our basic element is a connected k-partition of a graph G = (V, E) that is balanced up to some additive threshold that we call a **slack** $s \ge 0$, denoted (k, s)-**BCP**. We explore the space of all (k, s)-**BCP**s of the graph G = (V, E). Note that the total number of (k, s)-**BCP**s for all $s \ge 0$, is bounded above by the number k-partitions of V, which is the Stirling number of the second kind S(n, k), and asymptotically equals $(1 + o(1))k^n/k!$ for constant k. This bound is the best possible for the complete graph $G = K_n$.

In a recent application [1, 6, 17], G = (V, E) represents the adjacency graph of precincts in an electoral map, which should be partitioned into k districts V_1, \ldots, V_k where each district will elect one representative. Motivated by the design and evaluation of electoral maps under optimization criteria designed to promote electoral fairness, practitioners developed empirical methods to sample the configuration space of potential district maps by a random walk on the graph where each step corresponds to some elementary reconfiguration move [8]. From a theoretical perspective, the stochastic process converges to uniform sampling [13, 15]. However, the move should be local to allow efficient computation of each move, and it should support rapid mixing (i.e., the random walk should converge, in total variation distance, to its steady state distribution in time polynomial in n). Crucially, the space of (approximately balanced) k-partitions of G must be connected under the proposed move. Previous research considered the **single switch** move, in which a single vertex $v \in V$ switches from one set V_i to another set V_j (assuming that both $G[V_i]$ and $G[V_j]$ remain connected). Akitaya et al. [2] proved that the configuration space is connected under single switch moves if G is biconnected, but in general it is NP-hard both to decide whether the space is connected and to find a shortest path between two valid k-partitions. While the single switch is local, both worst-case constructions and empirical evidence [5, 17] indicate that it does not support rapid mixing.

In this paper we consider a different move. Specifically, we consider the configuration space of k-partitions under the **recombination** move, proposed by DeFord et al. [5], in which the vertices in $V_i \cup V_j$, for some $i, j \in \{1, \ldots, k\}$, are re-partitioned into $V'_i \cup V'_j$ such that both $G[V'_i]$ and $G[V'_j]$ are connected. We also study variants restricted to balanced or near-balanced partitions, that is, when $|V_i| = n/k$ for all $i \in \{1, \ldots, k\}$, or when $|V_i| - n/k| \leq s$ for a given slack $s \geq 0$. In application domains mentioned above, the underlying graph G is often planar or near-planar, and in some cases it is a triangulation (i.e., an edge-maximal planar graph). Results pertaining to these special cases are of particular interest.

Definitions. Let G = (V, E) be a graph with n = |V(G)|. For a positive integer k, a **connected** k-partition Π of G is a partition of V(G) into disjoint nonempty subsets $\{V_1, \ldots, V_k\}$ such that the induced subgraph $G[V_i]$ is connected for all $i \in \{1, \ldots, k\}$. Each subgraph induced by V_i is called a **district**. We write $\Pi(v)$ for the subset in Π that contains vertex v.

Denote by Part(G, k) the set of connected k-partitions on G. We also consider subsets of Part(G, k) in which all districts have the same or almost the same number of vertices. A connected k-partition of G is **balanced** (k-BCP) if every district has precisely n/k vertices (which implies that n is a multiple of k); and it is **balanced with slack** $s \ge 0$ ((k, s)-BCP), if $||U| - n/k| \le s$ for every district $U \subset V$. Let $Bal_s(G, k)$ denote the set of connected k-partitions on G that are

balanced with slack s, i.e., the set of all (k, s)-BCPs. The set of balanced k-partitions is denoted $Bal(G, k) = Bal_0(G, k)$; and $Part(G, k) = Bal_{\infty}(G, k)$.

We now formally define a **recombination move** as a binary relation on $\mathsf{Bal}_s(G, k)$. Two nonidentical (k, s)-BCPs, $\Pi_1 = \{V_1, \ldots, V_k\}$ and $\Pi_2 = \{W_1, \ldots, W_k\}$, are related by a recombination move if there exist $i, j \in \{1, \ldots, k\}$, and a permutation π on $\{1, \ldots, k\}$ such that $V_i \cup V_j = W_{\pi(i)} \cup W_{\pi(j)}$ and $V_\ell = W_{\pi(\ell)}$ for all $\ell \in \{1, \ldots, k\} \setminus \{i, j\}$. We say that Π_1 and Π_2 are a recombination of each other. This binary relation is symmetric and defines a graph on $\mathsf{Bal}_s(G, k)$ for all $s \geq 0$. This graph is the **configuration space** of $\mathsf{Bal}_s(G, k)$ under recombination, denoted by $\mathcal{R}_s(G, k)$.

Balanced Recombination Problem BR(G, k, s): Given a graph G = (V, E) with |V| = n vertices and two (k, s)-BCPs A and B, decide whether there exists a path between A and B in $\mathcal{R}_s(G, k)$, i.e. whether there is a sequence of recombination moves that carries A to B such that every intermediate partition is a (k, s)-BCP.

Our Results. We prove, in Section 2, that the configuration space $\mathcal{R}_{\infty}(G, k)$ is connected whenever the underlying graph G is connected and the size of the districts is unrestricted. It is easy, however, to construct a graph G where $\mathcal{R}_0(G, k)$ is disconnected. We study what is the minimum slack s, as a function of n and k, that guarantees that $\mathcal{R}_s(G, k)$ is connected for all connected (or possibly biconnected) graphs G with n vertices. We prove that $\mathcal{R}_s(G, k)$ is connected and its diameter is O(nk) for s = n/k when G is a Hamiltonian graph (Section 3). As a counterpart, we construct a family of Hamiltonian planar graphs G such that $\mathcal{R}_s(G, k)$ is disconnected for s < n/(3k) (Section 4).

We prove in Section 5 that BR(G, k, s) is PSPACE-complete even for the special case when G is a triangulation (i.e., an edge-maximal planar graph), k is $O(n^{\varepsilon})$ and s is $O(n^{1-\varepsilon})$ for constant $0 < \varepsilon \leq 1$. As a consequence we show that finding a (k, s)-BCP of G is NP-hard in the same setting. Note that the previously known hardness proofs for finding k-BCPs either require that G is weighted and nonplanar [3] or G contain cut vertices [7]. In contrast, if G is planar and 4-connected, then G admits a Hamilton cycle [20] and, therefore, a (k, s)-BCP is easily obtained by partitioning a Hamilton cycle into the desired pieces. Finally, we modify our construction to also show that BR(G, k, s) is PSPACE-complete even for the special case when G is planar, k = 3, and s is bounded above by $O(n^{1-\varepsilon})$ for constant $0 < \varepsilon \leq 1$.

2 Recombination with Unbounded Slack

In this section, we show that the configuration space $\mathcal{R}_{\infty}(G, k)$ is connected under recombination moves if G is connected (cf. Theorem 3). The proof proceeds by induction on k, where the induction step depends on Lemma 2 below.

We briefly review some standard graph terminology. A **block** of a graph G is a maximal biconnected component of G. A vertex $v \in V(G)$ is a **cut vertex** if it lies in two or more blocks of G, otherwise it is a **block vertex**. In particular, if v is a block vertex, then G - v is connected. If G is a connected graph with two or more vertices, then every block has at least two vertices. A block is a **leaf-block** if it contains precisely one cut vertex of G. Every connected graph either is biconnected or has at least two leaf blocks. The **arboricity** of a graph G is the minimum number of forests that cover all edges in E = (G). The **degeneracy** of G is the largest minimum vertex degree over all induced subgraphs of G. It is well known that if the arboricity of a graph is a, then its degeneracy is between a and 2a - 1.

Lemma 1. If the arboricity of a graph is a, then it contains a block vertex of degree at most 2a - 1.

Proof. It is enough to prove the claim for a connected component of G, so we may assume that G is connected. First assume that G is biconnected. Then every vertex is a block vertex. Since the degeneracy of G is at most 2a - 1, there exists a vertex of degree at most 2a - 1, as required. Next assume that G is not biconnected. Let G[U] be a leaf-block of G, and let $u \in U$ be the unique cut-vertex of G in U. Since the degeneracy of G is at most 2a - 1, there exists a vertex in U whose degree in G[U] is at most 2a - 1. If a block vertex $v \in U \setminus \{u\}$ has degree at most 2a - 1, our proof is complete. Suppose, to the contrary, that the degree of every block vertex in U is at least 2a (and the degree of the unique cut vertex in G[U] is at least 1). By the handshake lemma, the number of edges in G[U] is at least $\frac{1}{2}(2a(|U| - 1) + 1) > a(|U| - 1)$. However, the arboricity of G[U] is at most a, and a forests on the vertex set U jointly contain at most a(|U| - 1) edges, which provides a contradiction.

The heart of the induction step of our main result hinges on the following lemma.

Lemma 2. Let G be a connected graph, $k \ge 2$ an integer, and $\Pi_1, \Pi_2 \in Part(G, k)$ be two kpartitions of G. Then there exists a block vertex $v \in V(G)$ such that up to three recombination moves can transform Π_1 and Π_2 each to two new k-partitions in which $\{v\}$ is a singleton distinct. Proof. Let $\Pi_1 = \{V_1, \ldots, V_k\}$ and $\Pi_2 = \{W_1, \ldots, W_k\}$. We construct two spanning trees, T_1 and T_2 , for G that each contain k-1 edges between the districts of Π_1 and Π_2 , respectively. Specifically, for $i \in \{1, \ldots, k\}$, let $T(V_i)$ be a spanning tree of $G[V_i]$, $T(W_i)$ a spanning tree of $G[W_i]$. As G is connected, we can augment the forest $\bigcup_{i=1}^k T(V_i)$ to a spanning tree T_1 of G, using k-1 new edges, which connect vertices in distinct districts. Similarly, we can augment $\bigcup_{i=1}^k T(W_i)$ to a spanning tree T_2 of G. Now, let $G' = T_1 \cup T_2$. By definition, the arboricity of G' is at most 2. By Lemma 1, G' contains a block vertex v with $\deg_{G'}(v) \le 3$.

We show that we can modify Π_1 (resp., Π_2) to create a singleton district $\{v\}$ in at most three moves. Assume without loss of generality that $v \in V_1$ and $v \in W_1$. Since $\deg_{G'}(v) \leq 3$, we have $\deg_{T(V_1)}(v) \leq 3$ and $\deg_{T(W_1)}(v) \leq 3$. Consequently, $T(v_1) - v$ (resp., $T(W_1) - v$) has at most three components, each of which is adjacent to some other district, since G' - v is connected. Up to three successive recombinations can decrease the district V_1 with the components of $T(V_1) - v$, and reduce V_1 to $\{v\}$. Similarly, at most three successive recombinations can reduce W_1 to $\{v\}$.

Theorem 3. Let G be a connected graph and $k \ge 1$ a positive integer. For all $\Pi_1, \Pi_2 \in Part(G, k)$, there exists a sequence of at most 6(k-1) recombination moves that transforms Π_1 to Π_2 .

Proof. We proceed by induction on k. In the base case, k = 1, and $\Pi_1 = \Pi_2$. Assume that k > 1 and claim holds for k - 1. By Lemma 2, we can find a block vertex $v \in V(G)$ and up to six recombination moves transform Π_1 and Π_2 into Π'_1 and Π'_2 such that both contain $\{v\}$ as a singleton district. Since v is a block vertex, G - v is connected; and since $\{v\}$ is a singleton district in both Π'_1 and Π'_2 , we have $\Pi_1 - \{v\}, \Pi_2 - \{v\} \in Part(G - v, k - 1)$. By induction, a sequence of up to 6(k - 2) recombination moves in G - v can transform $\Pi_1 - \{v\}, \Pi_2 - \{v\}$. These moves remain valid recombination moves in G if we add singleton district $\{v\}$. Overall, the combination of these sequences yields a sequence of up to 6 + 6(k - 2) = 6(k - 1) recombination moves that transforms Π_1 to Π_2 . This completes the induction step. \Box

3 Recombination with Slack

In this section, we prove that the configuration space $\mathcal{R}_s(G, k)$ is connected if the slack is greater or equal to the average district size, that is, $s \ge n/k$, and the underlying graph G is Hamiltonian (Theorem 9).

Let G be a graph with n vertices that contains a Hamilton cycle C. Assume that n is a multiple of k. A k-partition in $Bal_s(G, k)$ is **canonical** if each district consists of consecutive vertices along C. Using a slack of $s \ge n/k$, we can transform any canonical k-partition to any other using $O(k^2)$ reconfigurations.

Lemma 4. Let G be a graph with n vertices and a Hamilton cycle C, $k \ge 1$ is a divisor of n, and $s \ge n/k$. Then the subgraph of $\mathcal{R}_s(G, k)$ induced by canonical k-partitions is connected and its diameter is at most $k^2 + 1$.

Proof. Let $\Pi = \{V_1, \ldots, V_k\}$ be a canonical k-partition with slack s, where districts $V_i, i \in \{1, \ldots, k\}$ are labeled in cyclic order along C. We call a district V_i large if $|V_i| > n/k$. We first show that at most $\binom{k}{2}$ moves are enough to bring any canonical k-partition into a balanced canonical partition, i.e., none of its districts is large. Then we show that any pair of balanced canonical k-partitions is within k + 1 moves apart. Overall the diameter of $\mathcal{R}_s(G, k)$ is at most $2\binom{k}{2} + k + 1 = k^2 + 1$.

Our first proof is by induction on k - m, where the first m blocks are balanced (i.e, $|V_i| = n/k$ for all $i \leq m$). In the base case, k - m = 0, and all districts are balanced. In the induction step, assume that $0 \leq m < k$. Since average size of the districts V_{m+1}, \ldots, V_k is n/k, but $|V_{m+1}| \neq n/k$, then there exist districts both below and above the average. Let j > m be the first index such that $V_j \leq n/k$ and $V_{j+1} \geq n/k$ or vice versa. We recombine V_j and V_{j+1} into V'_j and V'_{j+1} such that $|V'_j| = n/k$. By assumption, $2n/k - s \leq |V_j| + |V_{j+1}| \leq 2n/k + s$, thus $n/k - s \leq |V'_{j+1}| \leq n/k + s$, hence the new k-partition is a (k, s)-BCP. We then successively recombine V_i and V_{i-1} for $i = j, j - 1, \ldots, m + 1$. In each of these recombinations, we set $|V'_{i-1}| = n/k$ and $|V'_i| = |V_{i-1} \cup V_i| - n/k$, thus $n/k - s \leq |V'_i| \leq n/k + s$. After $j - m - 1 \leq k - m - 1$ moves, we obtain a (k, s)-BCP Π'' with $|V''_{m+1}| = n/k$, and we can increment m. The number of recombination moves is bounded by $\sum_{m=0}^{k-2} (k - m - 1) = \sum_{i=1}^{k-1} i = \binom{k}{2}$.

It remains to show that any two balanced canonical partitions in $\mathcal{R}_s(G, k)$ are within k moves apart. Note that if $\Pi_1 = \{V_1, \ldots, V_k\}$ and $\Pi_2 = \{W_1, \ldots, W_k\}$ are two balanced canonical partitions, then Π_2 is a cyclic shift of Π_1 along C. Without loss of generality, assume that $V_1 \cap W_1 \neq \emptyset$ and $W_1 \subset V_1 \cup V_2$. We describe k + 1 moves that brings Π_1 to Π_2 . This process is similar to the induction step of the previous argument. First, recombine V_1 and V_2 making $V'_1 = V_1 - W_2$ and $V'_2 = V_2 \cup W_2$. Then, recombine V'_i and V_{i+1} making making $V''_i = W_i$ and $V'_{i+1} = V_{i+1} \cup W_{i+1}$ for $i = 2, \ldots, k$. Finally, we recombine V'_1 and V'_k into W_1 and W_k . Through this procedure, there are only two unbalanced districts at any given time; the only large district is V'_1 and $|V'_1| < 2n/k$. \square

In the remainder of this section, we show that every k-partition in $Bal_s(G, k)$ can be brought into canonical form by a sequence of O(nk) recombinations.

Preliminaries. We introduce some terminology. Let $\Pi = \{V_1, \ldots, V_k\} \in \mathsf{Bal}_s(G, k)$ with a slack of $s \ge n/k$. For every $i \in \{1, \ldots, k\}$, a **fragment** of $G[V_i]$ is a maximum set $F \subset V_i$ of vertices that are contiguous along C. Every set V_i is the disjoint union of one or more fragments. The *k*-partition Π is canonical if and only if every district has precisely one fragment. Our strategy is to "defragment" Π if it is not canonical, that is, we reduce the number of fragments using recombination moves.

We distinguish between two types of districts in Π : A district V_i is **small** if $|V_i| \leq n/k$, otherwise it is **large**. Every edge in E(G) is either an edge or a **chord** of the cycle C. For every $i \in \{1, \ldots, k\}$, let f_i be the number of fragments of V_i . Let T_i be a spanning tree of $G[V_i]$ that contains the minimum number of chords. The edges of $G[V_i]$ along C form a forest of f_i paths; we can construct T_i by augmenting this forest to a spanning tree of $G[V_i]$ using $f_i - 1$ chords.

The **center** of a tree T is a vertex $v \in V(T)$ such that each component of T - v has up to |V(T)|/2 vertices. It is well known that every tree has a center. For $i \in \{1, \ldots, k\}$, let c_i be a center of the spanning tree T_i of $G[V_i]$. Let the fragment of V_i be **heavy** if it contains c_i ; and **light** otherwise. We also define a parent-child relation between the fragments of V_i . Fragments A and B are in a parent-child relation if they are adjacent in T_i and if c_i is closer to A than to B in T_i . Note that a light fragment and its descendants jointly contain less than $|V_i|/2 \leq (n/k + s)/2$ vertices; see Fig. 1.



Figure 1: Left: A distinct V_i with 26 vertices (hollow dots) in six fragments (bold arcs) along C. The spanning tree T_i of $G[V_i]$ contains five edges, with a center at c_i . Right: Parent-child relationship between fragments is defined by the tree rooted at the fragment containing c_i .

The following four lemmas show that we can decrease the number of fragments under some conditions. In all four lemmas, we assume that G is a graph with a Hamiltonian cycle C, and Π is a noncanonical (k, s)-BCP with $s \ge n/k$.

Lemma 5. If a light fragment of a large district is adjacent to a small district along C, then a recombination move can decrease the number of fragments.

Proof. Assume without loss of generality that v_1v_2 is an edge of C, where $v_1 \in F_1 \subset V_1$, $v_2 \in F_2 \subseteq V_2$, F_1 is a light fragment of a large district V_1 , and F_2 is some fragment of a small district V_2 . Let \overline{F}_1 be the union of fragment F_1 and all its descendants. By the definition of the center c_1 , we have $|\overline{F}_1| < |V_1|/2$. Apply a recombination replacing V_1 and V_2 with $W_1 = V_1 \setminus \overline{F}_1$ and $W_2 = V_2 \cup \overline{F}_1$.

We show that the resulting partition is a (k, s)-BCP. Note also that both $G[\overline{F}_1]$ and $G[V_1 \setminus \overline{F}_1] = G[W_1]$ are connected. Since $v_1v_2 \in E(G)$, then $G[V_2 \cup \overline{F}_1] = G[W_2]$ is also connected. As W_1 contains the center of V_1 , we have $|W_1| \ge 1$ and $|W_1| < |V_1| \le n/k + s$. As V_2 is small, have $|W_2| = |V_2| + |\overline{F}_1| < n/k + n/k \le 2n/k \le n/k + s$. Finally, note that $F_1 \cup F_2$ is a single fragment in the resulting k-partition, hence the number of fragments decreased by at least 1.

Lemma 6. If a light fragment of a large district is adjacent to some small district along C, then there exists two adjacent districts along C whose combined size is at most 2n/k.

Proof. Suppose, to the contrary, that every small district is adjacent only to heavy fragments along C, and the combined size of every pair of adjacent districts along C is greater than $\frac{2n}{k}$, meaning that at least one district is large. We assign every small district to an adjacent large district as follows. For every small district V_i , let F_i be one of its arbitrary fragments. We assign V_i to the large district whose heavy fragment is adjacent to F_i in the clockwise direction along C. Since every large district has a unique heavy fragment, and at most one district precedes it in clockwise order along C, the assignment is a matching of the small districts to large districts. Denote this matching by M. Every district that is not part of a pair in M must be large. By assumption, every pair in M has combined size greater than $\frac{2n}{k}$, so the average district size over the districts in M is greater than $\frac{n}{k}$. The districts not in M are large so their average size also exceeds $\frac{n}{k}$. Overall the average district size exceeds $\frac{n}{k}$. But Π is a k-partition of n vertices, hence the average district size is exactly $\frac{n}{k}$, a contradiction.

Lemma 7. If districts V_1 and V_2 are adjacent along C and $|V_1 \cup V_2| \le n/k + s$, then there is a recombination move that either decreases the number of fragments, or maintains the same number of fragments and creates a singleton district.

Proof. Assume, w.l.o.g., that $v_1 \in F_1 \subseteq V_1$, $v_2 \in F_2 \subseteq V_2$, where v_1v_2 is an edge of C, and F_1 and F_2 are fragments of V_1 and V_2 , respectively. The induced graph $G[V_1 \cup V_2]$ is connected, and $T_1 \cup T_2 \cup v_1v_2$ is one of its spanning trees. If T_1 or T_2 contains a chord, say e, then $(T_1 \cup T_2 \cup v_1v_2) - e$ has two components, T_3 and T_4 , each of size at most n/k + s - 1. A recombination move can replace V_1 and V_2 with $V(T_3)$ and $V(T_4)$. Since fragments F_1 and F_2 merge into one fragment, the number of fragments decreases by at least one. Otherwise, neither T_1 nor T_2 contains a chord. Then V_1 and V_2 each has a single fragment, so $V_1 \cup V_2$ is a chain of vertices along C. Let v be the first vertex in this chain. A recombination move can replace V_1 and V_2 with $W_1 = \{v\}$ and $W_2 = (V_1 \cup V_2) \setminus \{v\}$. By construction both $G[W_1]$ and $G[W_2]$ are connected, $|W_1| = 1$, $|W_2| = |V_1 \cup V_2| - 1 \le n/k + s - 1$, and the number of fragments does not change.

Lemma 8. If there exists a singleton district, then there exists a sequence of at most k-1 recombination moves that decreases the number of fragments.

Proof. Let $C = (v_1, \ldots, v_n)$. Assume without loss of generality that $V_1 = \{v_1\}$ is a singleton district, and $v_2 \in F_2 \subseteq V_2$, where F_2 is a fragment of district V_2 . Since not all districts are singletons, we may further assume that $|V_2| \ge 2$. We distinguish between two cases.

Case 1: $F_2 \neq V_2$ (i.e., V_2 has two or more fragments). Let e be an arbitrary chord in T_2 , and denote the two subtrees of $T_2 - e$ by T_2^- and T_2^+ such that v_2 is T_2^- . Since $|V_2| \leq n/k + s$, the subtrees T_2^- and T_2^+ each have at most n/k + s - 1 vertices. We can recombine V_1 and V_2 into $W_1 = V_1 \cup V(T_2^-)$ and $W_2 = V(T_2^+)$. Then $|W_1| \leq 1 + (n/k + s - 1) = n/k + s$ and $|W_2| \leq n/k + s - 1$; they both induce a connected subgraph of G. As the singleton fragment V_1 and F_2 merge into one fragment of W_1 , the number of fragments decreases by at least one.

Case 2: $F_2 = V_2$ (i.e., district V_2 has only one fragment). Let t > 2 be the smallest index such that v_t is in a district that has two or more fragments (such district exists since Π is not canonical). Then the chain (v_1, \ldots, v_{t-1}) is covered by single-fragment districts that we denote by V_1, \ldots, V_ℓ along C. By recombining V_i and V_{i+1} for $i = 1, \ldots, \ell - 1$, we create new single-fragment districts

 W_1, \ldots, W_ℓ such that $|W_i| = |V_{i+1}|$ for $i = 1, \ldots, \ell + 1$ and $|W_\ell| = |V_1| = 1$. Now we can apply Case 1 for the singleton district W_ℓ .

We are now ready to prove the main result of this section.

Theorem 9. If G is a Hamiltonian graph on n vertices and $s \ge n/k$, then $\mathcal{R}_s(G,k)$ is connected and its diameter is O(nk).

Proof. Based on Lemmas 5–8, the following algorithm successively reduces the number of fragments to k, thereby transforming any balanced k-partition to a canonical partition. While the number of fragments is more than k, do:

- 1. If a fragment of a small district is adjacent to a light fragment of a large district along C, then apply the recombination move in Lemma 5, which decreases the number of fragments.
- 2. Else, by Lemma 6, there are two adjacent districts along C whose combined size is at most 2n/k. Apply a recombination move in Lemma 7. If this move does not decrease the number of fragments, it creates a singleton district, and then up to k 1 recombination moves in Lemma 8 decrease the number of fragments by at least one.

There can be at most n different fragments in a k-partition of a set of n vertices. We can reduce the number of fragments using up to k recombination moves. Overall, O(nk) recombination moves can bring any two (k, s)-BCPs to canonical form, which are within $k^2 + 1$ moves apart by Lemma 4. \Box

4 Disconnected Configuration Space

In this section we show that the configuration space is not always connected, even in Hamiltonian graphs. Specifically, we show the following result:

Theorem 10. For any $k \ge 4$ and s > 0 there exists a Hamiltonian planar graph G of n = k(3s+2) vertices such that $\mathcal{R}_s(G, k)$ is disconnected.

Proof. For simplicity, we first argue about the construction for k = s = 4 and thus n = 56 (an extension to larger values of k is given afterwards). Our instance consists of a cycle (shown as an octagon in Fig. 2) and four additional edges e_1, \ldots, e_4 called **chords**. Note that G is planar despite the non-planar drawing in Fig. 2 (we may draw e_1 and e_3 in the outer face). All four districts initially have n/4 = 14 vertices.

Note that, if we were to remove any of the chords, the corresponding district would be split into two connected components. The removal of the chords e_1, \ldots, e_4 would split two of the districts (marked with circles in Fig. 2) into two components of sizes 1 + s and 1 + 2s, resp., and it would split the other two districts into two components of the same size within a vertex difference.

When a chord e is critical for the connectivity of the induced graph $G[V_i]$ of a district V_i , we say that V_i is **split** (by e). As noted above, all four districts are split in the initial partition. We claim that no sequence of recombinations can change this fact. Assume, for the sake of contradiction, that after a sequence of recombinations, one of the districts D is not split. Consider the last recombination before this happens.

This recombination involves two districts V_i and V_j that are split via edges e_i and e_j , respectively. The union of the two districts would have three components (after removing e_i and e_j). Thus, at



Figure 2: Problem instance showing that $\mathcal{R}_s(G,k)$ is not always connected (for k = 4, n = 56 and $s = 4 = \frac{n}{3k} - O(1)$).

least one of the two districts must remain split after the recombination (that is, we cannot "unsplit" both districts in one recombination).

Next, we show that not even one district can become unsplit. We distinguish between four cases depending on the edge that initially split a district, but it no longer does so after the recombination:

- We first argue that this edge can be neither e_1 nor e_2 . We first argue for e_1 . By the assumption that D is the first unsplit district, the other chords $(e_2, e_3, \text{ and } e_4)$ each split other districts. In particular, D is contained in a contiguous arcs of C that does not include an endpoint of any other chord. Since e_1 was involved in the recombination, we may assume that D is contained in the lower right or lower left portion of Fig 2, between the edges of e_3 and e_4 or e_2 and e_4 . In either case, D can contain at most 2s + 1 vertices. Since n/k = 3s + 2, this is not possible unless the slack was at least s + 1. Edge e_2 can be ruled out with an symmetric argument.
- Edge e_3 is ruled out using a similar argument. Assume again that D is the first unsplit district, and the other three chords each split other districts. Then D is contained in a contiguous arc of C between endpoints of e_1 , e_2 , or e_4 , and this arc contains an endpoint of e_3 . Assume first that D is in an arc containing the left endpoint of e_3 . Then the right endpoint of e_3 is in a district D' that contains both endpoints of e_2 . However, D' contains an arc of C between the endpoints of e_2 , and e_2 does not split any district, a contradiction. Next assume that D is in the arc containing the right endpoint of e_3 . Then D is contained in an arc between two endpoints of e_2 , and so D is adjacent to the district split by e_2 . The union of these two districts lies in a continuous arc of 4s+3 vertices. However, the minimum size of two districts is 2(n/k - s) = 2(2s + 2); a contradiction. By symmetry, we also rule out e_4 , and thus we obtain that all districts must be split at all times.

Finally, it remains to show how to extend the proof for larger values of k. Observe that in the proof we never looked at the upper left side of the octagon (where we have a cluster of 2s vertices of one district followed by 2s vertices of another district). For each additional district we need, we can simply place 2 + 3s consecutive vertices. Those districts can do local recombinations, but they will not prevent the initial four districts from being split.

5 Hardness Results

This section presents our hardness results. Our reductions are from Nondeterministic Constrained Logic (NCL) reconfiguration which is PSPACE-complete [10, 11]. An instance of NCL is given by a planar cubic undirected graph G_{NCL} where each edge is colored either red or blue. Each vertex is either incident to three blue edges or incident to two red and one blue edges. We respectively call such vertices **OR** and **AND** vertices. An orientation of G_{NCL} must satisfy the constraint that at every vertex $v \in V(G_{NCL})$, at least one blue edge or at least two red edges are oriented towards v. A move is an operation that transforms a satisfying orientation to another by reversing the orientation of a single edge. The problem gives two satisfying orientations A and B of G_{NCL} and asks for a sequence of moves to transform A into B. As in [2], we subdivide each edge in G_{NCL} obtaining a bipartite graph G'_{NCL} with one part formed by original vertices in $V(G_{NCL})$ and another part formed by degree-2 vertices. We require that an orientation must additionally satisfy the constraint that each degree-2 vertex v must have an edge oriented towards v. The question of whether there exists a sequence of moves transforming orientation A' into B' of G'_{NCL} remains PSPACE-complete. We follow the framework in [2] with a few crucial differences. The main technical challenge is dealing with the slack constraints while maintaining the desired behavior for the gadgets. We first describe the reduction to instances of our problem with slack equals zero. We then generalize the proofs.

5.1 Zero Slack

In the following reduction, we are given a bipartite instance of NCL given by (G'_{NCL}, A', B') , and we produce an instance of BR(G, k, s) of the balanced recombination problem consisting of two (k, s)-BCP of a planar graph G, Π_A and Π_B , with $k = O(|V(G_{NCL})|)$ districts, and slack s = 0.

Construction. We first describe a building block used in our gadgets, called **heavy vertices**, represented by green dots in Figure 3. Each heavy vertex q is associated with a positive integer **weight** w(q) and represents a vertex that we also call q, slightly abusing notation, attached to w(q) - 1 degree-1 vertices. The property that we exploit is that whichever district that contains vertex q must also contain all (w(q)-1) degree-1 vertices attached to it or else the district containing one of such vertices would be disconnected. Then, in practice we can consider the w(q) vertices represented by the heavy vertex q as a single vertex q with weight w(q) towards the size of the district containing it. The ordinary vertices (i.e., vertices of weight 1) are called **light**. We now define the AND and OR gadgets corresponding to the vertices of G_{NCL} and the degree-2 gadget corresponding to the degree-2 vertices of G'_{NCL} . Let α be a positive integer to be determined. The **AND gadget** is shown in Figure 3 (a) made of 6 light vertices and 3 heavy vertices. We set $w(v_a) = w(v_b) = \alpha$ and $w(v_c) = 8\alpha - 3$. The **OR gadget** is shown in Figure 3 (b) made of 6 light vertices and 7 heavy vertices. We set $w(v_a) = w(v_b) = w(v'_a) = w(v'_b) = w(v'_c) = \alpha$, $w(v_c) = 6\alpha - 3$, and $w(v') = 9\alpha$. The **degree-2 gadget** is shown in Figure 3 (c) made of 4 light vertices and 2 heavy vertices. We set $w(v_a) = w(v_b) = 5\alpha - 1$. Each edge *e* of G'_{NCL} is represented by two vertices, e^- and e^+ , that are shared by the two gadgets corresponding to the vertices incident to *e*, as shown in Figure 3 (d). For each vertex of G'_{NCL} , create a corresponding gadget identifying the vertex pairs e^- and e^+ as shown in the figure. This concludes the construction of *G*. We set $\alpha = 5$ so that the maximum weight of heavy vertices in AND/OR gadgets is greater than $5\alpha - 1$.



Figure 3: Gadgets for the reduction from NCL to BR(G, k, 0).

We now define Π_A and Π_B based on A' and B' respectively. We describe the construction of a set \mathcal{M}_X of (k, 0)-BCPs of G for an arbitrary satisfying orientation X of G'_{NCL} . Every district will have 10α vertices. Refer to Figure 4. For every vertex $v \in G'_{NCL}$ create a district D_v containing v_e for every edge e incident to v. Add e^+ (e^-) to D_v if e is directed towards (away from) v in X. That concludes the description for AND and degree-2 gadgets. If v is an OR vertex, let a_{i} b and c be the edges incident to v. Since X satisfies the NCL constraints, at least one edge is directed towards v. Without loss of generality, let a be directed towards v in X. Let v_1 be an arbitrary vertex in $\{v'_a, v'_b\}$. Then, add the vertices in $\{v'_a, v'_b, v'_c\} \setminus \{v_1\}$ to D_v and create a district $D_{v'} = \{v', v_1\}$. Note that if there are multiple edges directed towards v in X, then there are multiple options of edges to be labeled "a", and that v_1 is chosen arbitrarily. Let \mathcal{M}_X be the set of all k-partitions that can be constructed from X with the procedure above. Lemma 11 will show that the members of \mathcal{M}_X are indeed (k, 0)-BCPs. We choose $\Pi_A \in \mathcal{M}_{A'}$ and $\Pi_B \in \mathcal{M}_{B'}$ arbitrarily. By construction, $k = |V(G'_{NCL})| + n_{OR}$, where n_{OR} is the number of OR vertices. This concludes the construction. Note that given a k-partition $\Pi \in \mathcal{M}_X$, the above description implies a method to obtain a corresponding orientation X of G'_{NCL} . Namely, for every degree-2 (AND or OR) gadget, if there is a district D_v in Π containing both $\{v_a, v_b\}$ (all vertices in $\{v_a, v_b, v_c\}$) orient e towards v if and only if $e^+ \in D_v$, $e \in \{a, b\}$ $(e \in \{a, b, c\})$.

Correctness. We show that there exist a correspondence between a move in an orientation of G'_{NCL} and a recombination in a (k, 0)-BCP of G.



Figure 4: Equivalence between a satisfying orientation of G'_{NCL} and a k-BCP of G.

Lemma 11. A k-partition $\Pi \in \mathcal{M}_X$ is a (k, 0)-BCP if and only if X satisfies the NCL constraints.

Proof. Consider an AND vertex v incident to edges a, b, and c as in Figure 3 (a). By definition D_v contains v_e and exactly one of $\{e^+, e^-\}$ for $e \in \{a, b, c\}$. If $G[D_v]$ is connected, then D_v must contain either c^+ , or a^+ and b^- . Then, either c is directed towards v or both a and b are directed towards v in X. Thus the NCL constraint for v is satisfied. The other direction is analogous.

Similarly, we can show the equivalence for degree-2 vertices. Consider an OR vertex v incident to edges a, b, and c as in Figure 3 (b). Recall that $D_{v'}$ contains v' and exactly one heavy vertex in $\{v'_a, v'_b, v'_c\}$. Then, $G[D_v]$ contains a single path between two vertices in $\{v_a, v_b, v_c\}$ using vertices in $\{v'_a, v'_b, v'_c\}$, i.e., D_v induces two components in $\{v_a, v_b, v_c, v'_a, v'_b, v'_c\}$. Since $\{v_a, v_b, v_c\} \subset D_v$ by definition, D_v must contain at least one vertex in $\{a^+, b^+, c^+\}$. Thus the NCL constraint for v is satisfied. The other direction is analogous. \Box

The following lemma shows that the subgraph of the configuration space $\mathcal{R}_0(G, k)$ induced by \mathcal{M}_X is connected if X satisfies the NCL constraints.

Lemma 12. Given a satisfying orientation X of G'_{NCL} and two k-partitions $\Pi_1, \Pi_2 \in \mathcal{M}_X$, then there is a sequence of at most n_{OR} recombinations that takes Π_1 to Π_2 .

Proof. By construction, Π_1 and Π_2 are identical except at gadgets of OR vertices. Let v be an OR vertex where $\Pi_1(v') \neq \Pi_2(v')$. Then recombine $\Pi_1(v')$ and $\Pi_1(v_a)$ into $\Pi_2(v')$ and $\Pi_2(v_a)$. The resulting k-partition is in \mathcal{M}_X and by Lemma 11 its districts induce connected subgraphs. By repeating this procedure at all OR gadgets whose districts differ from the ones in Π_2 we eventually get Π_2 . There can be at most n_{OR} recombinations since this is the number of OR gadgets.

The following lemma establishes the equivalence between a recombination move in G and an edge reversal move in G'_{NCL} .

Lemma 13. For every (k, 0)-BCP $\Pi_1 \in \mathcal{M}_{X_1}$ obtained from a satisfying orientation X_1 on G'_{NCL} , every recombination on Π_1 yields a (k, 0)-BCP Π_2 such that $\Pi_2 \in \mathcal{M}_{X_2}$ where X_2 is an orientation on G'_{NCL} that differs from X_1 by the orientation of at most a single edge. Similarly, for an orientation X_2 on G'_{NCL} obtained from X_1 by reversing the orientation of a single edge, there is a sequence of one or two recombinations that takes any $\Pi_1 \in \mathcal{M}_{X_1}$ to some $\Pi_2 \in \mathcal{M}_{X_2}$. Proof. We begin with proving the first claim. Let D_p and D_q be two districts in Π_1 that are recombined into districts V and W of Π_2 . First assume that p = v is an OR vertex of G'_{NCL} , D_v is the district containing $\{v_a, v_b, v_c\}$, and q = v'. Let W be the district containing v'. Since $w(v') = 9\alpha$ and $n/k = 10\alpha$, then W must contain exactly v' and one heavy vertex in $\{v'_a, v'_b, v'_c\}$. Then D_p and V induces the same graph on $\{v_a, v_b, v_c, a^+, b^+, c^+\}$. Thus, we can read a graph orientation $X_2 = X_1$ from Π_2 , i.e., both Π_1 and Π_2 are in \mathcal{M}_{X_1} . Now, assume that p is an AND/OR vertex of G'_{NCL} adjacent to edges $a, b, and c, D_p$ is the district containing $\{p_a, p_b, p_c\}$, and q is a degree-2 vertex of G'_{NCL} adjacent to edges c and d with D_q being the district containing $\{p_c, p_d\}$. Let V be the district containing the heavier vertex in $\{p_a, p_b, p_c\}$. By construction, the weight of such vertex is greater than $5\alpha - 1$. Then V cannot contain $\{p_c, p_d\}$ and $\{p_c, p_d\} \subset W$. Due to size constraints, W cannot contain any other heavy vertex and $\{p_a, p_b, p_c\} \subset V$. Note that D_p and V (D_q and W) differ only by a vertex in $\{c^-, c^+\}$. We can then read an orientation X_2 off of Π_2 that differs from X_1 only by the orientation of c.

We proceed to prove the second claim. Let $c = pq \in E(G'_{NCL})$ be the edge whose orientation differs between X_1 and X_2 . Let p be an AND/OR vertex incident to $a, b, c \in E(G'_{NCL})$, and qbe a degree-2 vertex incident to $c, d \in E(G'_{NCL})$. Let Π_1 be an arbitrary (k, 0)-BCP in \mathcal{M}_{X_1} . First, assume that p is an AND vertex. Recombine $D_p, D_q \in \Pi_{X_1}$ into $D'_p = D_p \setminus \{c^-\} \cup \{c^+\}$ and $D'_q = D_q \setminus \{c^+\} \cup \{c^-\}$ obtaining Π_2 . By Lemma 11, the districts in Π_2 are connected and by construction $\Pi_2 \in \mathcal{M}_{X_2}$. Now assume that p is an OR vertex. If c is directed towards q in X_1 , the same proof as above holds. Else, c is directed towards p in X_1 and since X_2 satisfies the NCL constraints there is an edge $e \in \{a, b\}$ directed towards p. If $D_{p'} \in \Pi_{X_1}$ does not contain v'_e , we can perform one recombination so that it does as in Lemma 12. The remainder of the proof is the same as for the case when p is an AND vertex. \square

The combination of Lemmas 11, 12, and 13 yield the following lemma.

Lemma 14. BR(G, k, 0) is PSPACE-complete even for a planar graph G with constant maximum degree.

5.2 Generalizations

This section presents three generalizations of Lemma 14. The second generalization subsumes the first as well as Lemma 14. However we present all three in this order for ease of exposition.

Larger slack. By simply adjusting the value of $\alpha = 5 + s$, we can generalize Lemma 14 to larger slacks $s = O(n^{1-\varepsilon})$ for any constant $0 < \varepsilon \leq 1$. Indeed, any value $\alpha > 4 + s$ would work. There is a trade-off between the size of the slack and the maximum degree of G as the maximum degree is $\Theta(\alpha)$. Note the orientation of an edge e is encoded by the membership of the corresponding vertex e^+ in the (k, s)-BCP of G. In Section 5.1, e^- was used to balance the size of the districts; and e^- and e^+ were necessarily in a different districts. When the slack s is positive, this will no longer be the case, but as long as the districts in each gadget contain the same heavy vertices as in Section 5.1, we can use membership of e^+ to encode the orientation of e. The key properties that we have to maintain for all (k, s)-BCPs Π are the following:

- (i) for all $v \in V(G'_{NCL})$ of degree-2 incident to edges a and b, $\Pi(v_a) = \Pi(v_b)$;
- (ii) for $v \in V(G'_{NCL})$ of all degree-3 incident to edges a, b, and c, $\Pi(v_a) = \Pi(v_b) = \Pi(v_c)$; and
- (iii) for all OR vertices $v \in V(G'_{NCL})$, $\Pi(v')$ contains exactly one heavy vertex other than v'.

Property (iii) is clearly satisfied because n/k remains 10α and $\Pi(v')$ cannot contain only v'or else it would contain less than $n/k - s = 9\alpha + 5$ vertices, and it also cannot contain 3 heavy vertices or it would contain more than $n/k + s = 11\alpha - 5$ vertices. Consider Property (ii). Recall that $w(v_c) \ge 6\alpha - 3$. Then, $\Pi(v_c)$ cannot contain any heavy vertices of adjacent gadgets (of weight $5\alpha - 1$) or it would be larger than the maximum allowed size. Then $\Pi(v_c)$ must contain only heavy vertices in the gadget. Indeed, all other available heavy vertices have weight α . Then, $\Pi(v_c)$ must contain all other available heavy vertices in the gadget (excluding v' and one other in case v is an OR vertex because of (iii)) or it would contain less then the minimum allowed number of vertices. Then, Property (i) becomes trivial given (ii) and (iii). Note that this approach does not allow the slack to be linear in n. By construction, the size of the instance becomes $n = |V(G)| = \Theta(s|V(G_{NCL})|)$. We allow s to be any polynomial in $|V(G_{NCL})|$ as long as the size of the output instance of the reduction is polynomial. Note that k is fixed for a given G_{NCL} . Then k is bounded by O(n/s).

Corollary 15. BR(G, k, s) is PSPACE-complete even if G is planar, $k \in O(n^{\varepsilon})$, and $s \in O(n^{1-\varepsilon})$ for any constant $0 < \varepsilon \le 1$.

Bounded-degree triangulation G. We now generalize Corollary 15 restricting G to be a planar triangulation of constant maximum degree. As a consequence, our reduction proves that BCP is also NP-hard for this class of graphs generalizing the results in [3]. The main technical ingredient of this section is the gadget shown in Figure 5 (b) called **filler gadget**. It consists of 5 vertices labeled "red" inducing a maximal planar subgraph. Each internal face f of this induced subgraph is called a **heavy face**, and is assigned a positive integer weight w(f). We assume that w(f) is a multiple of 3. Each heavy face represents a subgraph G_f with w(f) + 3 vertices whose outer face is f. Figure 5 (a) shows the recursive construction of G_f . Then G_f is the 4-connected maximal planar graph with 6 vertices (including the 3 vertices of f) containing a heavy face f'. The face f' is chosen so that it is vertex-disjoint from f and w(f') = w(f) - 3. The base case, a heavy face with zero weight, is simply an ordinary face.



Figure 5: Construction of the filler gadget.

We now describe how to modify G produced in the reduction in Section 5.1. We will add filler gadgets to the faces of G and triangulate the resulting plane graph as follows. We set the weight of every heavy face in the filler gadgets to $10\alpha - s - 1$. We proceed with the details; refer to Figure 5 (c). First, assign each heavy vertex to a face of G. For each face f assigned with one or more heavy vertices, add one copy of the filler gadget to the interior of f for each heavy vertex. Triangulate f so that there is no new edge between vertices of f, i.e., all new edges have at least one endpoint at a filler gadget. We also require that for each heavy vertex v there is a face f_v containing v and one edge of the outer face of its corresponding filler gadget F_v . We transfer the weight from v to f_v by making v a light vertex and f_v a heavy face, and setting $w(f_v) = 5s + w(v) - 1$. For remaining faces f of G, if f is not a triangle and has not been assigned any heavy vertex, add a copy of the filler gadget in f triangulating it as before, i.e., no new edge should be between vertices of f. Choose a neighboring face f' (sharing an edge with the gadget) to make if heavy with w(f') = 5s. The resulting graph G' is an edge-maximal planar graph. Finally, set $\alpha = 11s + 5$ and increase k by 5 for each copy of the filler gadget used.

It remains to define the initial and target (k, s)-BCPs Π_A and Π_B defining an instance of BR(G, k, s). We construct such (k, s)-BCPs with 0 slack. For that, we show that we can find a balanced connected partition of the filler gadget and 5s vertices in the neighbor heavy face into 5 connected districts. We construct a Hamiltonian path of the gadget and its neighboring heavy face as follows. The main structure of the Hamiltonian path is shown in Figure 6 (a). For each heavy face we need to find a path that visits all internal vertices and starts and ends with a vertex on its outer face. We accomplish this with the recursive construction shown in Figure 6 (b). Considering that the path starts in the filler gadget, we ignore the first edge to obtain the desired Hamiltonian path. It is now easy to partition the 10α -long prefix of the path into 5 connected components. The remainder of the construction follows Section 5.1.



Figure 6: Inductive construction of the Hamiltonian path used to partition the filler gadget.

Lemma 16. In every (k, s)-BCP Π of G', for every filler gadget F, exactly five districts of Π intersect F and the number of vertices in the union of these five districts outside of F is at most 10s.

Proof. First note that n/k remains 10α . The number of vertices in F is $5(10\alpha - s)$, thus it must intersect at least 5 districts of Π . Each district that intersects F must contain a red vertex since each heavy face has less than the minimum capacity of a district. Since F has only 5 red vertices, there must be exactly 5 districts intersecting F, each containing exactly one red vertex. The maximum number of vertices of these districts outside of F is $5(10\alpha + s) - 5(10\alpha - s) = 10s$.

Lemma 16 allows us to mostly ignore filler gadgets. We refer to the districts that intersect a filler gadget as a **filler district**. Recall that every heavy vertex v in G is now adjacent to a heavy face f_v in G'. Since $10s < w(f_v) < 10\alpha - s$, if a filler district contains v then it would disconnect vertices of f_v that cannot be in any district. Then, the district that contains v is not filler and it must also contain the $w(v) \pm 5s - 1$ vertices in f_v that are not in filler districts. That mimics the weights of heavy vertices in G such as v in a 3-connected graph G' within a $\pm 5s$ accuracy. One can check that the new choice of α accommodates this variations guaranteeing properties (i)–(iii). We omit the details since the argument is fairly similar as before. The situation in which filler districts contain normal vertices of G would then be equivalent to the reduction in Section 5.1 where some of the non-heavy vertices are deleted. Intuitively, deleting vertices only makes it more difficult to satisfy the connectivity constraints. We need to extend the equivalence to the NCL orientation to allow for when vertices e^+ corresponding to an edge e are taken by filler districts. That would correspond to a partial orientation where e is not directed, i.e., it does not count for

satisfying the constraints of neither its endpoints. It is clear that such a variant of NCL remains PSPACE-complete since we still require that the constraints are satisfied at each vertex ignoring undirected edges and a sequence of operations in this setting can be converted by a sequence in the normal NCL setting and vice versa by assigning an arbitrary direction for an undirected edge. For more details see an asynchronous vertion of NCL [21]. Then, Lemmas 11–13 hold for this variant. The construction distributes the weights of heavy vertices of G into heavy faces of G'. By the recursive construction, the degree of each vertex increases by at most 2. Then, the filler gadget has constant degree. Note that k remains O(n/s).

Theorem 17. BR(G, k, s) is PSPACE-complete even if G is maximal planar of constant maximum degree, $k \in O(n^{\varepsilon})$, and $s \in O(n^{1-\varepsilon})$ for $0 < \varepsilon \leq 1$.

Finding Balanced Connected Partitions. The NCL orientation problem is defined by an input undirected graph G_{NCL} edge colored as before, and asks whether there exist an orientation of G_{NCL} that satisfies the NCL constraints. This problem in NP-complete [11]. We remark that our construction implies the following theorem.

Theorem 18. It is NP-complete to decide whether there exist a (k, s)-BCP of a graph G, even if G is maximal planar of constant maximum degree, $k \in O(n^{\varepsilon})$, and $s \in O(n^{1-\varepsilon})$ for $0 < \varepsilon \leq 1$.

Constant number of districts. Note that, in the previous hardness proofs, k cannot be a constant. We now build on Lemma 14 to prove PSPACE-hardness for instances of BR(G,3,s). Note that with k = 2 the configuration space is the complete graph by definition. Also note that this result does not subsume Theorem 17 since the graph produced has cut-vertices as we will see in the remainder of this section. We now show how to modify the graph G produced in the reduction of Section 5.1. We modify the gadgets as follows. The AND gadget remains unchanged while the OR gadget adjacent to edges a, b and c as in Figure 7 (a) is changed by adding the edges $a^+v'_a$, $a^+v'_b, b^+v'_b, b^+v'_c, c^+v'_a, \text{ and } c^+v'_c$. The vertices v'_a, v'_b and v'_c are no longer heavy vertices. The main difference is in the degree-2 gadgets which are shown in Figure 7 (b). They now have six heavy vertices each, v_a , v'_a , v_{ab} , v'_{ab} , v_b , v'_b . Refer to Figure 7 (c)–(d). For each face f of G_{NCL} we create a new heavy vertex v_f in G which concludes the description of V(G). We now describe how to complete E(G). For that we have to describe two spanning trees of a new graph G^*_{NCL} described as follows. We build G_{NCL}^* from G_{NCL} by adding v_f to the face f, triangulating the result by adding edges incident to v_f , and deleting every original edge of G_{NCL} . Refer to Figure 7 (c). Note that G_{NCL}^* is bipartite, there is a one-to-one correspondence between degree-2 vertices of G_{NCL}' and faces of G^*_{NCL} , and that such faces are quadrilaterals. Let T_1 be a spanning tree of G^*_{NCL} and T_2 be an interdigitating spanning tree of the dual of G^*_{NCL} , i.e., spanning all degree-2 vertices of G'_{NCL} so that T_1 and T_2 do not both use the the primal or dual of the same edge. For every edge uv_f in T_1 , add an edge $u_a v_f$, where a is an edge incident to u in G'_{NCL} and a appears before u in a clockwise traversal of f. For every edge uv in T_2 , add the edge $u'_{ab}v_{cd}$ or $u_{ab}v'_{cd}$ where a and b (resp., c and d) are the edges incident to u (resp., v) and the addition of the edge does not introduce a crossing in G. Then, for every pair of vertices of the form v_a or v'_a where a is an edge incident to a degree-2 vertex v in G'_{NCL} that are currently in the same face of G, add an edge between them excluding edges of the form $v_a v'_a$, i.e., an edge inside a face of a degree-2 vertex. Note that the new edges could be of the form $v_a v_b$, i.e., connecting two vertices in the same degree-2 vertex but

corresponding to a different edge of G'_{NCL} as shown in Figure 7 (d) by curved edges. Finally, delete one of the edges added in the last step.

We now give some informal intuition about the construction. We will set up the weights so that heavy vertices can only be part of the same districts which we label V_1 , V_2 and V_3 in any (k, s)-BCP of G. The following is the key property that we exploit.

(*) District V_1 must contain every vertex v_f created from a face f of G_{NCL} as well as every v_a , v_b and v_c of a gadget corresponding to a degree-3 vertex v of G'_{NCL} . District V_2 must contain all vertices of degree-2 gadgets of the form v_{ab} or v'_{ab} . District V_3 must contain all remaining heavy vertices, i.e., heavy vertices of degree-2 gadgets of the form v_a and heavy vertices v' of gadgets corresponding to OR vertices v.

The connectivity of V_1 (V_2) will mimic, in broad terms, the spanning tree T_1 (T_2). District V_3 will separate V_1 and V_2 also containing the heavy vertex v' of OR gadgets. We now encode the direction of an edge e in G'_{NCL} by whether V_1 or V_3 contain e^+ respectively meaning that e points to its degree-3 or degree-2 end.

We now adjust the weights of the heavy vertices of G in order to obtain property (*). Let n_2 , n_{OR} and n_{AND} be the number of degree-2, OR and AND vertices in G'_{NCL} respectively. Set the weights of V_1 's heavy vertices to $w_1 = \alpha$, which we will set later. Choose one of the heavy vertices assigned to V_2 and set its weight to $n/3 + s - w_1$, and set the weights of its remaining heavy vertices to $w_2 = (w_1 - s - n_2)/(2n_2 - 1)$. Choose one of the heavy vertices assigned to V_3 and set its weight to $n/3 + s - w_2$, and set the weights of its remaining heavy vertices to $w_3 = (w_2 - s - 3n_2 - n_{OR})/(4n_2 + n_{OR} - 1)$. We set α so that $w_3 = s + n_\ell$ where n_ℓ is the number of light vertices in G. Then $\alpha \in O(n_2^2 s)$ and $|V(G)| \in O(\alpha |V(G_{NCL})|)$.

Theorem 19. BR(G,3,s) is PSPACE-complete even if G is planar with constant maximum degree, and $s \in O(n^{1-\varepsilon})$ for $0 < \varepsilon \le 1$.

Proof. As before, each individual weight of a heavy vertex is smaller than the minimum threshold for a district and thus a district must contain all vertices in the heavy vertex. We can implement the weights of a heavy vertex v with a path of length w(v) with an endpoint at v in order to keep the maximum degree of G upper bounded by a constant. We can assume that G_{NCL} has constant face degree, or else one can use techniques by Hearn and Demaine [11] to split large faces using their "red-blue conversion" gadget. Thus, we keep the maximum degree of G upper bounded by a constant. We first show that property (\star) holds in any (k, s)-BCP II on G. By construction, we have that $w_1 > w_2 > w_3$. We first show the claim for V_3 . Assume that V_3 is the district containing the heavy vertex of wight n/3 + s - w2. For contradiction assume that it also contain a heavy vertex whose weight is not w_3 . Then such vertex must have a weight larger than w_2 which makes the size of V_3 greater than n/3 + s, a contradiction. Now assume for contradiction that V_3 does not contain all of the heavy vertices with weight w_3 . Then the maximum size of V_3 is $n/3 - w_3 + n_{\ell} = n/3 - s$ even if V_3 contains all light vertices, a contradiction since V_1 and V_2 need to contain light vertices to be connected. We conclude that V_3 must satisfy (\star). The arguments for V_2 are similar once (\star) is established for V_3 , and thus V_1 also satisfies (\star).

We now show that Lemma 11 holds in this context. By (\star) , V_1 must connect all v_a , v_b and v_c in every AND and OR gadget. Moreover, apart from such vertices, V_1 can only contain light vertices and heavy vertices of the form v_f that came from a face f of G_{NCL} . Thus the only paths that connect v_a , v_b and v_c in a given gadget are contained in the gadget itself. Therefore, the NCL



Figure 7: Construction of the reduction with k = 3. The three districts v_1 , v_2 , and V_3 are colored magenta, cyan, and orange respectively. (a) New OR gadget. (b) New degree-2 gadget. (c) G^*_{NCL} overlapped with G'_{NCL} . The edges of G^*_{NCL} are shown in gray and its vertices are shown as squares. (d) The correspondent part of G.

constraints at degree-3 gadgets must be satisfied as before. Note that the new edges in the OR gadget do not change its behavior. It remains to show the same for degree-2 gadgets. By (\star) , V_2 must connect all v_{ab} and v'_{ab} in every degree-2 gadget. By construction and Property (\star) , all paths that connect such vertices must be contained in the same gadget. Similarly, V_3 must connect v_a and v'_a (v_b and v'_b) by a path contained in the degree-2 gadget. Then, at least one vertex in $\{a^+, b^+\}$ must be in V_3 to allow space for V_2 to connect v_{ab} and v'_{ab} .

To conclude the proof it is enough to show that Lemma 13 holds in this context. By the way we encode the orientation of edges, only a recombination between V_1 and V_3 can change the orientation of an edge. The potential worry is that, now that V_1 and V_3 are adjacent at every gadget, one recombination could alter the orientation so that we can't transform it into a sequence of single orientation reversals in G_{NCL} . However, the presence of V_2 in every degree-2 vertex prevents that the orientation of two edges incident to the same degree-2 vertex flip simultaneously. Then the set of edges that flip in one recombination induces paths of at most two edges having a degree-3 vertex as a middle vertex. Then we can represent the simultaneous flips with a sequence of flips having first all flips that point an edge towards a degree-3 vertex followed by all flips that point an edge towards a degree-2 vertex. Each flip in the two subsequences is independent of other flips in the same subsequence. As proved by Viglietta [21], even though one operation can flip many independent edges simultaneously, the problem is still equivalent to regular NCL. In the other direction, we can show that an edge flip can always be obtained by at most 2 recombinations. The first recombination is between V_2 and V_3 so that V_2 contains only the appropriate path between each v_{ab} and v'_{ab} . The second recombination is between V_1 and V_3 , exchanging the membership of a^+ and a^- representing the reversal of an edge a.

6 Conclusion and Open Problems

We have shown that the configuration space $\mathcal{R}_s(G,k)$ of (k,s)-BCPs is connected when G is connected and $s = \infty$, or when G is Hamiltonian and $s \ge |V(G)|/k$. We hope that our results inform future research on the properties of G, k, and s that are sufficient to obtain an efficient sampling of $\mathsf{Bal}_s(G,k)$. We also leave it as an open problem whether our results in Section 3 generalize to other classes of graphs. We conjecture that the configuration space $\mathcal{R}_s(n,k)$ is connected for every **biconnected** graph G on n vertices when $s \ge n/k$. However, our techniques do not directly generalize; it is unclear how to extend the notion of canonical k-partitions in the absence of a Hamilton cycle.

We have shown that BR(G, k, s) is PSPACE-complete even in specific settings that are of interest in applications such as sampling electoral maps. Our results imply that the configuration space $\mathcal{R}_s(G, k)$ has diameter exponential in n, establishing as well an exponential lower bound on the mixing time of a Markov chain on $\mathcal{R}_s(G, k)$ for these settings. We note that Theorems 17 and 19 do not include other settings of interest such as when G is maximal planar (or even 3-connected) and k is a constant. We leave these as open problems.

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