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# On Gaussian Group Convex Models^ 

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#### Abstract

The Gaussian group model is a statistical model consisting of central normal distributions whose precision matrices are of the form $g g^{\top}$, where $g$ is an element of a matrix group $G$. When the set of $g g^{\top}$ is convex in the vector space of real symmetric matrices, the set forms an affine homogeneous convex domain studied by Vinberg. In this case, we give the smallest number of samples such that the maximum likelihood estimator (MLE) of the parameter exists with probability one. Moreover, if the MLE exists, it is explicitly expressed as a rational function of the sample data.


Keywords: Gaussian group model • affine homogeneous convex domain - maximum likelihood estimator • Riesz distribution

## 1 Introduction

Let $G$ be a subgroup of $G L(N, \mathbb{R})$, and $\mathcal{M}_{G}$ the set $\left\{g g^{\top} ; g \in G\right\} \subset \operatorname{Sym}(N, \mathbb{R})$. The Gaussian group model associated to $G$ is a statistical model consisting of central multivariate normal laws whose precision (concentration) matrices belong to $\mathcal{M}_{G}$ ([1]). It is an example of a transformation family, that is, an exponential family whose parameter space forms a group (see [2]). A fundamental problem is to estimate an unknown precision matrix $\theta=g g^{\top} \in \mathcal{M}_{G}$ from samples $X_{1}, X_{2}, \ldots, X_{n} \in \mathbb{R}^{N}$. In [1], the existence and uniqueness of the maximum likelihood estimator (MLE) $\hat{\theta}$ of $\theta$ are discussed in connection with Geometric Invariant Theory. In the present paper, under the assumption that $\mathcal{M}_{G} \neq\left\{I_{N}\right\}$ is a convex set, we compute the number $n_{0}$ for which MLE exists uniquely with probability one if and only if $n \geq n_{0}$ (Theorem 4). In this case, an expression of the MLE as a rational function of the samples $X_{1}, \ldots, X_{n}$ is given (Theorem 3).

Since $\mathcal{M}_{G}$ is convex, it is regarded as a convex domain in an affine space $I_{N}+$ $V$, where $V$ is a linear subspace of the vector space $\operatorname{Sym}(N, \mathbb{R})$ of real symmetric matrices of size $N$. Moreover $\mathcal{M}_{G}$ is contained in the cone $\operatorname{Sym}^{+}(N, \mathbb{R})$ of positive definite symmetric matrices, so that $\mathcal{M}_{G}$ does not contain any straight line (actually, we shall see that $\mathcal{M}_{G}$ is exactly the intersection $\left(I_{N}+V\right) \cap \operatorname{Sym}^{+}(N, \mathbb{R})$, see Proposition 2 and Theorem 2). Thus $\mathcal{M}_{G}$ is an affine homogeneous convex

[^0]domain on which $G$ acts transitively as affine transforms. Then we can apply Vinberg's theory [9] to $\mathcal{M}_{G}$. In particular, using the left-symmetric algebra structure on $V$ explored in [6], we give a specific description of $\mathcal{M}_{G}$ as in Theorem 2, where the so-called real Siegel domain appears naturally. On the other hand, every homogeneous cone is obtained as $\mathcal{M}_{G}$ by [6]. In particular, all the symmetric cones discussed in [3] as well as the homogeneous graphical models in [8, Section 3.3] appear in our setting.

The rational expression of MLE is obtained by using the algebraic structure on $V$, whereas the existence condition is deduced from the previous works [4] and [5] about the Wishart and Riesz distributions on homogeneous cones. It seems feasible to generalize the results of this paper to a wider class of Gaussian models containing decomposable graphical models based on [7] in future.

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## 2 Structure of the convex parameter set

In what follows, we assume that $\mathcal{M}_{G}$ is a convex set in the vector space $\operatorname{Sym}(N, \mathbb{R})$ and that $\mathcal{M}_{G} \neq\left\{I_{N}\right\}$. The affine subspace spanned by elements of $\mathcal{M}_{G}$ is of the form $I_{N}+V$, where $V$ is a linear subspace of $\operatorname{Sym}(N, \mathbb{R})$, and $\mathcal{M}_{G}$ is an open connected set in $I_{N}+V$. Let $\bar{G}$ be the closure of $G$ in $G L(N, \mathbb{R})$. Then we have $\mathcal{M}_{\bar{G}}=\mathcal{M}_{G}$. Indeed, for $\tilde{g} \in \bar{G}$, the set $\tilde{g} \mathcal{M}_{G} \tilde{g}^{\top}=\left\{\tilde{g} \theta \tilde{g}^{\top} ; \theta \in \mathcal{M}_{G}\right\}$ is contained in the closure $\overline{\mathcal{M}_{G}}$ of $\mathcal{M}_{G}$. On the other hand, since $\tilde{g}$ is invertible, the set $\tilde{g} \mathcal{M}_{G} \tilde{g}^{\top}$ is open in the affine space $I_{N}+V$. Thus the point $\tilde{g} \tilde{g}^{\top} \in \tilde{g} \mathcal{M}_{G} \tilde{g}^{\top} \subset \overline{\mathcal{M}_{G}}$ is an relatively interior point of the convex set $\overline{\mathcal{M}_{G}}$, so that $\tilde{g} \tilde{g}^{\top} \in \mathcal{M}_{G}$, which means that $\mathcal{M}_{\bar{G}} \subset \mathcal{M}_{G}$. Therefore we can assume that $G$ is a closed linear Lie group without loss of generality. Furthermore, we can assume that $G$ is connected. Following Vinberg's argument [9, Chapter 1, Section 6], we shall show that $\mathcal{M}_{G_{\text {alg }}^{0}}=\mathcal{M}_{G}$, where $G_{\text {alg }}^{0}$ is the identity component (in the classical topology) of the real algebraic hull of $G$ in $G L(N, \mathbb{R})$. Let $\mathfrak{g}$ be the Lie algebra of $G$. For $h \in G_{\text {alg }}^{0}$, we have $h h^{\top} \in I_{N}+V$ and $h \mathfrak{g} h^{-1}=\mathfrak{g}$ because these are algebraic conditions that are satisfied by all the elements of $G$. The second condition together with the connectedness of $G$ tells us that $h G h^{-1}=G$. Let $\mathcal{U}$ be a neighborhood of $I_{N}$ in $G_{\text {alg }}^{0}$ such that $h h^{\top} \in \mathcal{M}_{G}$ for all $h \in \mathcal{U}$. Then for any $\theta=g g^{\top} \in \mathcal{M}_{G}(g \in G)$, we have $h \theta h^{\top}=\left(h g h^{-1}\right) h h^{\top}\left(h g h^{-1}\right)^{\top} \in g_{0} \mathcal{M}_{G} g_{0}^{\top}=\mathcal{M}_{G}$, where $g_{0}:=h g h^{-1} \in G$. Thus, if $h$ is the product $h_{1} h_{2} \cdots h_{m} \in G_{\text {alg }}^{0}$ with $h_{1}, \ldots, h_{m} \in \mathcal{U}$, we see that $h h^{\top} \in \mathcal{M}_{G}$ inductively. Therefore we conclude that $\mathcal{M}_{G_{\text {alg }}^{0}}=\mathcal{M}_{G}$.

By Vinberg [9], we have the generalized Iwasawa decomposition

$$
G_{\mathrm{alg}}^{0}=\mathcal{T} \cdot\left(G_{\mathrm{alg}}^{0} \cap O(N)\right),
$$

where $\mathcal{T}$ is a maximal connected split solvable Lie subgroup of $G_{\mathrm{alg}}^{0}$. Moreover, $\mathcal{T}$ is triangularized simultaneously by an orthogonal matrix $U \in O(N)$, which means that a group $\mathcal{T}^{U}=\left\{U^{-1} h U ; h \in \mathcal{T}\right\}$ is contained in the group $\mathcal{T}_{N}$ of lower triangular matrices of size $N$ with positive diagonal entries. Let $\mathcal{M}_{G}^{U}$ be the set $\left\{U^{\top} \theta U ; \theta \in \mathcal{M}_{G}\right\}$, which is equal to $\mathcal{M}_{\mathcal{T}^{U}}$. By the uniqueness of the Cholesky decomposition, we have a bijection $\mathcal{T}^{U} \ni h \mapsto h h^{\top} \in \mathcal{M}_{G}^{U}$. The tangent space of $\mathcal{M}_{G}^{U}$ at $I_{N}$ is naturally identified with $V^{U}:=\left\{U^{\top} y U ; y \in V\right\}$.

In general, for $x \in \operatorname{Sym}(N, \mathbb{R})$, we denote by $\underset{\vee}{x}$ the lower triangular matrix
for which $x=\underset{\vee}{x}+(\underset{\checkmark}{x})^{\top}$. Actually, we have $(\underset{\vee}{x})_{i j}=\left\{\begin{array}{ll}x_{i j} & (i>j) \\ x_{i i} / 2 & (i=j) \\ 0 & (i<j) .\end{array}\right.$ Then we define a bilinear product $\triangle$ on $\operatorname{Sym}(N, \mathbb{R})$ by

$$
x \triangle y:=x_{V} y+y(\underset{V}{x})^{\top} \quad(x, y \in \operatorname{Sym}(N, \mathbb{R}))
$$

The algebra $(\operatorname{Sym}(N, \mathbb{R}), \triangle)$ forms a compact normal left-symmetric algebra (CLAN), see [9, Chapter 2] and [6].

Lemma 1. The space $V^{U}$ is a subalgebral of $(\operatorname{Sym}(N, \mathbb{R}), \triangle)$. Namely, for any $x, y \in V^{U}$, one has $x \triangle y \in V^{U}$.

Proof. Let $\mathfrak{t}^{U}$ be the Lie algebra of $\mathcal{T}^{U}$. In view of the Cholesky decomposition mentioned above, we have a linear isomorphism $\mathfrak{t}^{U} \ni T \mapsto T+T^{\top} \in V^{U}$. Thus we obtain

$$
\begin{equation*}
\mathfrak{t}^{U}=\left\{\underset{V}{x} ; x \in V^{U}\right\} \tag{1}
\end{equation*}
$$

Let us consider the action of $h \in \mathcal{T}^{U}$ on the set $\mathcal{M}_{G}^{U}$ given by $\mathcal{M}_{G}^{U} \ni \theta \mapsto$ $h \theta h^{\top} \in \mathcal{M}_{G}^{U}$. This action is naturally extended to the affine space $I_{N}+V^{U}$ as affine transformations. The infinitesimal action of $T=\underset{\vee}{x} \in \mathfrak{t}^{U}$ on $I_{N}+y \in$ $I_{N}+V^{U}\left(y \in V^{U}\right)$ is equal to $T\left(I_{N}+y\right)+\left(I_{N}+y\right) T^{\top}=x+x \Delta y$ which must be an element of $V^{U}$. Therefore $x \triangle y \in V^{U}$.

Proposition 1 ([6, Theorem 2 and Proposition 2] ). If $V^{U}$ contains the identity matrix $I_{N}$, after an appropriate permutation of the rows and columns, $V^{U}$ becomes the set of symmetric matrices of the form

$$
y=\left(\begin{array}{cccc}
Y_{11} & Y_{21}^{\top} & \ldots & Y_{r 1}^{\top} \\
Y_{21} & Y_{22} & & Y_{r 2}^{\top} \\
\vdots & & \ddots & \vdots \\
Y_{r 1} & Y_{r 2} & \ldots & Y_{r r}
\end{array}\right) \quad\left(\begin{array}{l}
Y_{k k}=y_{k k} I_{\nu_{k}}, y_{k k} \in \mathbb{R}, \quad(k=1, \ldots, r) \\
Y_{l k} \in V_{l k}
\end{array} \quad(1 \leq k<l \leq r) .\right.
$$

where $N=\nu_{1}+\cdots+\nu_{r}$, and $V_{l k}$ are subspaces of $\operatorname{Mat}\left(\nu_{l}, \nu_{k} ; \mathbb{R}\right)$ satisfying (V1) $A \in V_{l k} \Rightarrow A A^{\top} \in \mathbb{R} I_{\nu_{l}}$ for $1 \leq k<l \leq r$,
(V2) $A \in V_{l j}, B \in V_{k j} \Rightarrow A B^{\top} \in V_{l k}$ for $1 \leq j<k<l \leq r$,
(V3) $A \in V_{l k}, B \in V_{k j} \Rightarrow A B \in V_{l j}$ for $1 \leq j<k<l \leq r$.
Clearly $I_{N} \in V^{U}$ if and only if $I_{N} \in V$. In this case, Proposition 1 together with [6, Theorem 3] tells us that $\mathcal{T}^{U}=\mathfrak{t}^{U} \cap \mathcal{T}_{N}$ and $\mathcal{M}_{G}^{U}=\mathcal{M}_{\mathcal{T} U}=V^{U} \cap$ $\mathrm{Sym}^{+}(N, \mathbb{R})$. It follows that we obtain:

Proposition 2. If $I_{N} \in V$, one has $\mathcal{M}_{G}=V \cap \operatorname{Sym}^{+}(N, \mathbb{R})$.
Here we remark that every homogeneous cone is realized as $\mathcal{M}_{G}$ this way by [6]. For example, if $U=I_{N}, \nu_{1}=\cdots=\nu_{r}=2$ and $V_{l k}=\left\{\left(\begin{array}{cc}a & -b \\ b & a\end{array}\right) ; a, b \in \mathbb{R}\right\}$ $(1 \leq k<l \leq r)$, then $\mathcal{M}_{G}=V \cap \operatorname{Sym}^{+}(N, \mathbb{R})$ is linearly isomorphic to the cone $\operatorname{Herm}^{+}(r, \mathbb{C})$ of positive definite $r \times r$ Hermitian matrices, which is a realization of the symmetric space $G L(r, \mathbb{C}) / U(r)$. See [4] and [6] for other examples.

If $V^{U}$ does not contain $I_{N}$, we consider the direct sum $\tilde{V}^{U}:=\mathbb{R} I_{N} \oplus V^{U}$, which is also a subalgebra of $(\operatorname{Sym}(N, \mathbb{R}), \triangle)$. Then we apply Proposition 1 to $\tilde{V}^{U}$. Since $V^{U}$ is a two-sided ideal of $\tilde{V}^{U}$ of codimension one, after some renumbering of indices $k$ and $l$, we see that $V^{U}$ equals the subspace of $\tilde{V}^{U}$ costing of elements $y$ with $y_{11}=0$. Namely, we have the following.

Theorem 1. If $V^{U}$ does not contain the identity matrix $I_{N}$, after an appropriate permutation of the rows and columns, $V^{U}$ becomes the set of symmetric matrices of the form

$$
y=\left(\begin{array}{cccc}
0 & Y_{21}^{\top} & \ldots & Y_{r 1}^{\top} \\
Y_{21} & Y_{22} & & Y_{r 2}^{\top} \\
\vdots & & \ddots & \vdots \\
Y_{r 1} & Y_{r 2} & \ldots & Y_{r r}
\end{array}\right) \quad\left(\begin{array}{l}
Y_{k k}=y_{k k} I_{\nu_{k}}, y_{k k} \in \mathbb{R}, \quad k=2, \ldots, r \\
Y_{l k} \in V_{l k}, \\
1 \leq k<l \leq r
\end{array}\right)
$$

where $V_{l k}$ are the same as in Proposition 1.
In what follows, we shall consider the case where $I_{N} \notin \mathcal{M}_{G}^{U}$ because our results below for the case $I_{N} \in \mathcal{M}_{G}^{U}$ will be obtained formally by putting $\nu_{1}=0$ and $V_{k 1}=\{0\}$, as is understood by comparing Proposition 1 and Theorem 1. Put $N^{\prime}:=\nu_{2}+\cdots+\nu_{r}=N-\nu_{1}$. Let $W$ and $V^{\prime}$ be the vector spaces of matrices $w$ and $y^{\prime}$ respectively of the forms

$$
w=\left(\begin{array}{c}
Y_{21} \\
\vdots \\
Y_{r 1}
\end{array}\right) \in \operatorname{Mat}\left(N^{\prime}, \nu_{1} ; \mathbb{R}\right), \quad y^{\prime}=\left(\begin{array}{ccc}
Y_{22} & & Y_{r 2}^{\top} \\
\vdots & \ddots & \\
Y_{r 2} & \ldots & Y_{r r}
\end{array}\right) \in \operatorname{Sym}\left(N^{\prime}, \mathbb{R}\right)
$$

Let $\mathcal{P}^{\prime}$ be the set $V^{\prime} \cap \operatorname{Sym}^{+}\left(N^{\prime}, \mathbb{R}\right)$. Then $\mathcal{P}^{\prime}$ forms a pointed open convex cone in the vector space $V^{\prime}$.

Theorem 2. Under the assumptions above, one has

$$
\mathcal{M}_{G}=\left\{U\left(\begin{array}{cc}
I_{\nu_{1}} & w^{\top} \\
w & y^{\prime}
\end{array}\right) U^{\top} ; w \in W, y^{\prime} \in V^{\prime}, y^{\prime}-w w^{\top} \in \mathcal{P}^{\prime}\right\}
$$

Moreover $\mathcal{M}_{G}$ equals the intersection of $\operatorname{Sym}^{+}(N, \mathbb{R})$ and the affine space $I_{N}+V$.

Proof. Let $\mathfrak{t}^{\prime}$ be the set of the lower triangular matrices $\underset{V}{y^{\prime}}$ with $y^{\prime} \in V^{\prime}$. Then we see from [6] that $\mathfrak{t}^{\prime}$ is a Lie algebra, and that the corresponding Lie group $\mathcal{T}^{\prime}:=\exp \mathfrak{t}^{\prime} \subset G L\left(N^{\prime}, \mathbb{R}\right)$ equals $\mathfrak{t}^{\prime} \cap \mathcal{T}_{N^{\prime}}$. Namely, $\mathcal{T}^{\prime}$ is the set of $h^{\prime}$ of the form

$$
h^{\prime}=\left(\begin{array}{ccc}
T_{22} & \\
\vdots & \ddots & \\
T_{r 2} \ldots & T_{r r}
\end{array}\right) \in \mathcal{T}_{N^{\prime}} \quad\binom{T_{k k}=t_{k k} I_{\nu_{k}}, t_{k k}>0, \quad k=2, \ldots, r}{T_{l k} \in V_{l k}, \quad 2 \leq k<l \leq r}
$$

Since we have $\mathfrak{t}^{U}=\left\{\binom{0}{L T^{\prime}} ; L \in W, T^{\prime} \in \mathfrak{t}^{\prime}\right\}$ by (1), the corresponding Lie group $\mathcal{T}^{U}$ is the set of $\left(\begin{array}{cc}I_{\nu_{1}} & 0 \\ L & h^{\prime}\end{array}\right)$ with $L \in W$ and $h^{\prime} \in \mathcal{T}^{\prime}$. Therefore, $\mathcal{M}_{G}^{U}=$ $\mathcal{M}_{\mathcal{T}^{U}}$ is the set of matrices $\left(\begin{array}{cc}I_{\nu_{1}} & 0 \\ L & h^{\prime}\end{array}\right)\left(\begin{array}{cc}I_{\nu_{1}} & L^{\top} \\ 0 & \left(h^{\prime}\right)^{\top}\end{array}\right)=\left(\begin{array}{cc}I_{\nu_{1}} & L^{\top} \\ L & L L^{\top}+a^{\prime}\end{array}\right)$ with $a^{\prime}=$ $h^{\prime}\left(h^{\prime}\right)^{\top} \in \mathcal{P}^{\prime}$. On the other hand, as is discussed in [6, Theorem 3], the map $T^{\prime} \ni h^{\prime} \mapsto h^{\prime}\left(h^{\prime}\right)^{\top} \in \mathcal{P}^{\prime}$ is bijective, which completes the proof.

## 3 Existence condition and an explicit expression of MLE

Let $X_{1}, \ldots, X_{n}$ be independent random vectors obeying the central multivariate normal law $N(0, \Sigma)$ with $\theta:=\Sigma^{-1} \in \mathcal{M}_{G}$. The density function $f$ of $\left(X_{1}, \ldots, X_{n}\right)$ is given by
$f\left(x_{1}, \ldots, x_{n} ; \theta\right):=(2 \pi)^{-n N / 2}(\operatorname{det} \theta)^{n / 2} \prod_{j=1}^{N} e^{-x_{j}^{\top} \theta x_{j} / 2} \quad\left(x_{j} \in \mathbb{R}^{N}, j=1, \ldots, n\right)$.
Let $\pi: \operatorname{Sym}(N, \mathbb{R}) \rightarrow V$ be the orthogonal projection with respect to the trace inner product. Putting $y:=\pi\left(\sum_{j=1}^{N} x_{j} x_{j}^{\top} / 2\right) \in V$, we have $f\left(x_{1}, \ldots, x_{n} ; \theta\right)=$ $c(x)(\operatorname{det} \theta)^{n / 2} e^{-\operatorname{tr} \theta y}$, where $c(x):=(2 \pi)^{-n N / 2} \exp \left(\operatorname{tr}\left\{\left(I_{N}-\pi\left(I_{N}\right)\right) \sum_{j=1}^{N} x_{j} x_{j}^{\top} / 2\right\}\right)$, which is independent of $\theta$. Thus, given $Y:=\pi\left(\sum_{k=1}^{n} X_{j} X_{j}^{\top} / 2\right) \in V$, the maximum likelihood estimator $\hat{\theta}$ is an element of $\mathcal{M}_{G}$ at which the log likelihood function $F(\theta ; Y):=(n / 2) \log \operatorname{det} \theta-\operatorname{tr}(Y \theta)$ attains the maximum value.

In what follows, we shall assume that $U=I_{N}$. Indeed, a general case is easily reduced to this case. For $k=2, \ldots, r$, let $V_{[k]}$ and $W_{k-1}$ be the vector spaces of matrices $y_{[k]}$ and $Z_{k-1}$ respectively of the forms

$$
y_{[k]}=\left(\begin{array}{ccc}
Y_{k k} & & Y_{r k}^{\top} \\
\vdots & \ddots & \\
Y_{r k} & \ldots & Y_{r r}
\end{array}\right) \in \operatorname{Sym}\left(N_{k}, \mathbb{R}\right), \quad Z_{k-1}=\left(\begin{array}{c}
Y_{k, k-1} \\
\vdots \\
Y_{r, k-1}
\end{array}\right) \in \operatorname{Mat}\left(N_{k}, \nu_{k-1} ; \mathbb{R}\right)
$$

where $N_{k}:=\nu_{k}+\cdots+\nu_{r}$. Note that $V^{\prime}=V_{[2]}$ and $W=W_{1}$ in the previous notation. We have an inductive expression of $y \in V$ as

$$
y=\left(\begin{array}{cc}
0 & Z_{1}^{\top}  \tag{2}\\
Z_{1} & y_{[2]}
\end{array}\right), \quad y_{[k]}=\left(\begin{array}{cc}
y_{k k} I_{\nu_{k}} & Z_{k}^{\top} \\
Z_{k} & y_{[k+1]}
\end{array}\right) \quad(k=2, \ldots r-1), \quad y_{[r]}=y_{r r} I_{\nu_{r}} .
$$

Let $\mathcal{T}_{[k]} \subset \mathcal{T}_{N_{k}}$ be the group of lower triangular matrices $y_{[k]}\left(y_{[k]} \in V_{[k]}\right)$ with positive diagonal entries. Then $\mathcal{T}^{\prime}=\mathcal{T}_{[2]}$. Any element $h \in \stackrel{\vee}{\mathcal{T}}$ is expressed as

$$
h=\left(\begin{array}{cc}
I_{\nu_{1}} & 0 \\
L_{1} & h_{[2]}
\end{array}\right), \quad h_{[k]}=\left(\begin{array}{cc}
t_{k k} I_{\nu_{k}} & 0 \\
L_{k} & h_{[k+1]}
\end{array}\right) \in \mathcal{T}_{[k]} \quad(k=2, \ldots, r-1)
$$

with $L_{k} \in W_{k}$ and $h_{[r]}=t_{r r} I_{\nu_{r}} \in \mathcal{T}_{[r]}$. We observe that

$$
h_{[k]} h_{[k]}^{\top}=\left(\begin{array}{cc}
t_{k k}^{2} I_{\nu_{k}} & t_{k k} L_{k}^{\top} \\
t_{k k} L_{k} & L_{k} L_{k}^{\top}+h_{[k+1]} h_{[k+1]}^{\top}
\end{array}\right) \in V_{[k]} .
$$

We shall regard $V_{[k]}$ as a subspace of $V^{\prime}=V_{[2]}$ by zero-extension. Define a map $q_{k}: \mathbb{R}_{>0} \times W_{k} \rightarrow V^{\prime}$ for $k=2, \ldots, r-1$ by $q_{k}\left(t_{k k}, L_{k}\right):=\left(\begin{array}{cc}t_{k k}^{2} & t_{k k} L_{k}^{\top} \\ t_{k k} L_{k} & L_{k} L_{k}^{\top}\end{array}\right) \in$ $V_{[k]} \subset V^{\prime}$, and define also $q_{r}\left(t_{r r}\right):=t_{r r}^{2} I_{n_{r}} \in V_{[r]} \subset V^{\prime}$. If $\theta=h h^{\top}$, we have

$$
\theta=\left(\begin{array}{cc}
I_{\nu_{1}} & L_{1}  \tag{3}\\
L_{1} & L_{1} L_{1}^{\top}+\theta^{\prime}
\end{array}\right), \quad \theta^{\prime}=\sum_{k=2}^{r-1} q_{k}\left(t_{k k}, L_{k}\right)+q_{r}\left(t_{r r}\right) .
$$

For $y^{\prime} \in V^{\prime}=V_{[2]}$ and $k=2, \ldots, r-1$, we have

$$
\begin{equation*}
\operatorname{tr}\left(y^{\prime} q_{k}\left(t_{k k}, L_{k}\right)\right)=\nu_{k} y_{k k} t_{k k}^{2}+2 t_{k k} \operatorname{tr}\left(Z_{k}^{\top} L_{k}\right)+\operatorname{tr}\left(y_{[k+1]} L_{k} L_{k}^{\top}\right) \tag{4}
\end{equation*}
$$

Let $m_{k}(k=1, \ldots, r-1)$ be the dimension of the vector space $W_{k}$, and take an orthonormal basis $\left\{e_{k \alpha}\right\}_{\alpha=1}^{m_{k}}$ of $W_{k}$ with respect to the trace inner product. For $L_{k} \in W_{k}$, let $\lambda_{k}:=\left(\lambda_{k 1}, \ldots, \lambda_{k m_{k}}\right)^{\top} \in \mathbb{R}^{m_{k}}$ be the column vector for which $L_{k}=\sum_{\alpha=1}^{m_{k}} \lambda_{k \alpha} e_{k \alpha}$. Defining $\zeta_{k} \in \mathbb{R}^{m_{k}}$ for $Z_{k} \in W_{k}$ similarly, we have $\zeta_{k}^{\top} \lambda_{k}=\operatorname{tr}\left(Z_{k}^{\top} L_{K}\right)$. Let $\psi_{k}: V^{\prime} \rightarrow \operatorname{Sym}\left(m_{k}, \mathbb{R}\right)$ be a linear map defined in such a way that $\operatorname{tr}\left(y^{\prime} L_{k} L_{\underline{k}}^{\top}\right)=\lambda_{k}^{\top} \psi_{k}\left(y^{\prime}\right) \lambda_{k}$, and define $\phi_{k}: V^{\prime} \rightarrow \operatorname{Sym}\left(1+m_{k}, \mathbb{R}\right)$ by $\phi_{k}\left(y^{\prime}\right):=\left(\begin{array}{cc}\nu_{k} y_{k k} & \zeta_{k}^{\top} \\ \zeta_{k} & \psi_{k}(y)\end{array}\right)$. In view of (4), we have

$$
\operatorname{tr}\left(y^{\prime} q_{k}\left(t_{k k}, L_{k}\right)\right)=\operatorname{tr}\left(\phi_{k}\left(y^{\prime}\right)\left(\begin{array}{cc}
t_{k k}^{2} & t_{k k} \lambda_{k}^{\top}  \tag{5}\\
t_{k k} \lambda_{k} & \lambda_{k} \lambda_{k}^{\top}
\end{array}\right)\right) .
$$

Let $\phi_{k}^{*}: \operatorname{Sym}\left(1+m_{k}, \mathbb{R}\right) \rightarrow V^{\prime}$ be the adjoint map of $\phi_{k}$, which means that $\operatorname{tr} \phi_{k}^{*}(S) y^{\prime}=\operatorname{tr} S \phi\left(y^{\prime}\right)$ for $S \in \operatorname{Sym}\left(1+m_{k}, \mathbb{R}\right)$. Define also $\phi_{r}\left(y^{\prime}\right):=\nu_{r} y_{r r} \in$ $\mathbb{R} \equiv \operatorname{Sym}(1, \mathbb{R})$ and $\phi_{r}^{*}(c)=c I_{\nu_{r}} \in V_{[r]} \subset V^{\prime}$ for $c \in \mathbb{R}$.

Let $\mathcal{Q}^{\prime} \subset V^{\prime}$ be the dual cone of $\mathcal{P}^{\prime} \subset V^{\prime}$, that is, the set of $y^{\prime} \in V^{\prime}$ such that $\operatorname{tr}\left(y^{\prime} a\right)>0$ for all $a \in \overline{\mathrm{P}^{\prime}} \backslash\{0\}$. If $y^{\prime} \in \mathcal{Q}^{\prime}$, then $\phi_{k}\left(y^{\prime}\right)$ and $\psi_{k-1}\left(y^{\prime}\right)$ are positive definite for $k=2, \ldots, r$. Moreover, it is known (see [4, Proposition 3.4 (iii)]) that

$$
\begin{equation*}
\mathcal{Q}^{\prime}=\left\{y^{\prime} \in V^{\prime} ; \operatorname{det} \phi_{k}\left(y^{\prime}\right)>0 \text { for all } k=2, \ldots, r\right\} \tag{6}
\end{equation*}
$$

If $Y:=\pi\left(\sum_{j=1}^{n} X_{j} X_{j}^{\top} / 2\right)$ is expressed as in (2), then we can show that $Y^{\prime}:=$ $Y_{[2]}$ belongs to the closure of $\mathcal{Q}^{\prime}$, so that $\phi_{k}\left(Y^{\prime}\right)$ and $\psi_{k-1}\left(Y^{\prime}\right)$ are positive semidefinite for $k=2, \ldots r$.

Theorem 3. (i) If $Y^{\prime} \in \mathcal{Q}^{\prime}$, then $\hat{\theta}=\arg \max _{\theta \in \mathcal{M}_{G}} F(\theta ; Y)$ exists uniquely, and it is expressed as $\hat{\theta}=\left(\begin{array}{cc}I_{\nu_{1}} & \hat{L}_{1}^{\top} \\ \hat{L}_{1} & \hat{L}_{1} \hat{L}_{1}^{\top}+\hat{\theta}^{\prime}\end{array}\right)$ with $\hat{\lambda}_{1}=-\psi_{1}\left(Y^{\prime}\right)^{-1} \zeta_{1} \in \mathbb{R}^{m_{1}}$, which is the column vector corresponding to $\hat{L}_{1}$, and

$$
\hat{\theta}^{\prime}=\frac{n \nu_{r}}{2} \phi_{r}^{*}\left(\phi_{r}\left(Y^{\prime}\right)^{-1}\right)+\sum_{k=2}^{r-1} \frac{n \nu_{k}}{2} \phi_{k}^{*}\left(\phi_{k}\left(Y^{\prime}\right)^{-1}-\left(\begin{array}{lc}
0 & 0  \tag{7}\\
0 & \psi_{k}\left(Y^{\prime}\right)^{-1}
\end{array}\right)\right)
$$

(ii) If $Y^{\prime} \notin \mathcal{Q}^{\prime}$, then $F(\theta ; Y)$ is unbounded, so that $\hat{\theta}$ does not exist.

Proof. (i) Keeping (2), (3) and $(\operatorname{det} \theta)^{n / 2}=\prod_{k=2}^{r}\left(t_{k k}\right)^{n \nu_{k}}$ in mind, we define

$$
\begin{aligned}
F_{1}\left(L_{1} ; Y\right) & :=-2 \operatorname{tr}\left(Z_{1}^{\top} L_{1}\right)-\operatorname{tr}\left(Y^{\prime} L_{1} L_{1}^{\top}\right), \\
F_{k}\left(t_{k k}, L_{k} ; Y\right) & :=n \nu_{k} \log t_{k k}-\operatorname{tr}\left(q_{k}\left(t_{k k}, L_{k}\right) Y^{\prime}\right) \quad(k=2, \ldots, r-1), \\
F_{r}\left(t_{r r} ; Y\right) & :=n \nu_{r} \log t_{r r}-\nu_{r} y_{r r} t_{r r}^{2}
\end{aligned}
$$

so that $F(\theta ; Y)=F_{1}\left(L_{1} ; Y\right)+F_{r}\left(t_{r r} ; Y\right)+\sum_{k=2}^{r-1} F_{k}\left(t_{k k}, L_{k} ; Y\right)$. It is easy to see that $F_{r}\left(t_{r r} ; Y\right)$ takes a maximum value at $\hat{t}_{r r}=\sqrt{\frac{n}{2 y_{r r}}}$. Then $q_{r}\left(\hat{t}_{r r}\right)=\frac{n}{2 y_{r r}} I_{\nu_{r}}=$ $\frac{n \nu_{r}}{2} \phi_{r}^{*}\left(\phi_{r}\left(Y^{\prime}\right)^{-1}\right)$. On the other hand, $F_{1}\left(L_{1} ; Y\right)=-2 \zeta_{1}^{\top} \lambda_{1}-\lambda_{1}^{\top} \psi_{1}\left(Y^{\prime}\right) \lambda_{1}$ equals

$$
\zeta_{1}^{\top} \psi_{1}\left(Y^{\prime}\right)^{-1} \zeta_{1}-\left(\lambda_{1}+\psi_{1}\left(Y^{\prime}\right)^{-1} \zeta_{1}\right)^{\top} \psi_{1}\left(Y^{\prime}\right)\left(\lambda_{1}+\psi_{1}\left(Y^{\prime}\right)^{-1} \zeta_{1}\right)
$$

which attains a maximum value when $\lambda_{1}=-\psi_{1}\left(Y^{\prime}\right)^{-1} \zeta_{1}$ because $\psi_{1}\left(Y^{\prime}\right)$ is positive definite. Similarly, we see from (5) that

$$
\begin{align*}
& F_{k}\left(t_{k k}, L_{k}\right)=n \nu_{k} \log t_{k k}-\left(\nu_{k} y_{k k}-\zeta_{k}^{\top} \psi_{k}\left(Y^{\prime}\right)^{-1} \zeta_{k}\right) t_{k k}^{2}  \tag{8}\\
&-\left(\lambda_{k}+t_{k k} \psi_{k}\left(Y^{\prime}\right)^{-1} \zeta_{k}\right)^{\top} \psi_{k}\left(Y^{\prime}\right)\left(\lambda_{k}+t_{k k} \psi_{k}\left(Y^{\prime}\right)^{-1} \zeta_{k}\right)
\end{align*}
$$

Since $\nu_{k} y_{k k}-\zeta_{k}^{\top} \psi_{k}\left(Y^{\prime}\right)^{-1} \zeta_{k}=\operatorname{det} \phi_{k}\left(Y^{\prime}\right) / \operatorname{det} \psi_{k}\left(Y^{\prime}\right)>0$, we see that $F_{k}\left(t_{k k}, L_{k} ; Y^{\prime}\right)$ attains at $\left(\hat{t}_{k k}, \hat{L}_{k}\right)$ with $\hat{t}_{k k}=\sqrt{\frac{n \nu_{k}}{2\left(\nu_{k} y_{k k}-\zeta_{k}^{\top} \psi_{k}\left(Y^{\prime}\right)^{-1} \zeta_{k}\right)}}$ and $\hat{\lambda}_{k}=-\hat{t}_{k k} \psi_{k}\left(Y^{\prime}\right)^{-1} \zeta_{k} \in$ $\mathbb{R}^{m_{k}}$, which is the column vector corresponding to $\hat{L}_{k}$. By a straightforward calculation, we have

$$
\left(\begin{array}{cc}
\hat{t}_{k k}^{2} & \hat{t}_{k k} \hat{\lambda}_{k}^{\top} \\
\hat{t}_{k k} \hat{\lambda}_{k} & \hat{\lambda}_{k} \hat{\lambda}_{k}^{\top}
\end{array}\right)=\frac{n \nu_{k}}{2}\left(\phi_{k}\left(Y^{\prime}\right)^{-1}-\left(\begin{array}{lc}
0 & 0 \\
0 & \psi_{k}\left(Y^{\prime}\right)^{-1}
\end{array}\right)\right) \in \operatorname{Sym}\left(1+m_{k}, \mathbb{R}\right)
$$

which maps to $q_{k}\left(\hat{t}_{k k}, \hat{L}_{k}\right)$ by $\phi_{k}^{*}: \operatorname{Sym}\left(1+m_{k}, \mathbb{R}\right) \rightarrow V^{\prime}$ thanks to (5). Therefore the assertion (i) is verified.
(ii) By (6), there exists $k$ for which $\operatorname{det} \phi_{k}\left(Y^{\prime}\right)=0$. If $\operatorname{det} \phi_{r}\left(Y^{\prime}\right)=y_{r r}^{\nu_{r}}=0$, then $F_{r}\left(t_{r r} ; Y^{\prime}\right)=n \nu_{r} \log t_{r r} \rightarrow+\infty$ in $t_{r r} \rightarrow+\infty$. Let us consider the case where $\operatorname{det} \phi_{l}\left(Y^{\prime}\right)>0$ for $l=k+1, \ldots, r$ and $\operatorname{det} \phi_{k}\left(Y^{\prime}\right)=0$. Then one can show that $\psi_{k}\left(Y^{\prime}\right)$ is positive definite because in this case $Y_{[k+1]} \in V_{[k+1]}$ belongs to the
dual cone of $\mathcal{P}_{[k+1]}:=V_{[k+1]} \cap \operatorname{Sym}^{+}\left(N_{k}, \mathbb{R}\right)$ by the same reason as (6). Since $\nu_{k} y_{k k}-\zeta_{k}^{\top} \psi_{k}\left(Y^{\prime}\right)^{-1} \zeta_{k}=\operatorname{det} \phi_{k}\left(Y^{\prime}\right) / \operatorname{det} \psi_{k}\left(Y^{\prime}\right)=0$, we see from (8) that

$$
\max _{L_{k} \in W_{k}} F_{k}\left(t_{k k}, L_{k} ; Y^{\prime}\right)=n \nu_{k} \log t_{k k} \rightarrow+\infty \quad\left(t_{k k} \rightarrow+\infty\right)
$$

which completes the proof.
We remark that a generalization of the formula (7) is found in [5, Theorem 5.1]. By Theorem 3, the existence of the MLE $\hat{\theta}$ is equivalent to that the random matrix $Y^{\prime}$ belongs to the cone $\mathcal{Q}^{\prime}$ with probability one. On the other hand, the distribution of $Y^{\prime}$ is nothing else but the Wishart distribution on $\mathcal{Q}^{\prime}$ studied in [4] and [5]. The Wishart distribution is obtained as a natural exponential family generated by the Riesz distribution $\mu_{n}$ on $V^{\prime}$ characterized by its Laplace transform: $\int_{V^{\prime}} e^{-\operatorname{tr}\left(y^{\prime} a\right)} \mu_{n}\left(d y^{\prime}\right)=(\operatorname{det} a)^{-n / 2}$ for all $a \in \mathcal{P}^{\prime}$. Note that, if $a \in \mathcal{P}^{\prime}$ is a diagonal matrix, we have $(\operatorname{det} a)^{-n / 2}=\prod_{k=2}^{r} a_{k k}^{-n \nu_{k} / 2}$. As is seen in [5, Theorem 4.1 (ii)], the support of the Riesz distribution $\mu_{n}$ is determined from the parameter $\left(n \nu_{2} / 2, \ldots, n \nu_{r} / 2\right) \in \mathbb{R}^{r-1}$. In fact, $\operatorname{supp} \mu_{n}=\overline{\mathcal{Q}^{\prime}}$ if and only if $n \nu_{k} / 2>m_{k} / 2$ for $k=2, \ldots, r$, and $Y^{\prime} \in \mathcal{Q}^{\prime}$ almost surely in this case. Otherwise, $\operatorname{supp} \mu_{n}$ is contained in the boundary of $\mathcal{Q}^{\prime}$, so that $Y^{\prime}$ never belongs to $\mathcal{Q}^{\prime}$. Therefore, if $n_{0}$ is the smallest integer that is greater than $\max \left\{\frac{m_{k}}{\nu_{k}} ; k=2, \ldots, r\right\}$, we have the following final result.

Theorem 4. The maximum likelihood estimator $\hat{\theta}=\arg \max _{\theta \in \mathcal{M}_{G}} F(\theta ; Y)$ exists with probability one if and only if $n \geq n_{0}$. If $n<n_{0}$, then the log likelihood function $F(\theta ; Y)$ of $\theta \in \mathcal{M}_{G}$ is unbounded.

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