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Cristina Bazgan · Henning Fernau (Eds.)

# Combinatorial Algorithms

33rd International Workshop, IWOCA 2022  
Trier, Germany, June 7–9, 2022  
Proceedings

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# Preface

The 33rd International Workshop on Combinatorial Algorithms (IWOCA 2022) was planned as a hybrid event, with the on-site activities taking place at the University of Trier, Germany. Due to the COVID-19 pandemic and also in order to lower the carbon footprint of the conference, it was decided that the conference could be also attended online. The conference was scheduled during June 7–9, 2022, followed by the Graphmaster and Stringmaster Workshops.

IWOCA is an annual conference series that started in 1989 as AWOCA (Australasian Workshop on Combinatorial Algorithms), and became an international conference in 2007, having been held in Australia, Canada, the Czech Republic, Finland, France, Indonesia, India, Italy, Japan, Singapore, South Korea, the UK, and the USA. Now, Germany can be added to this list of IWOCA countries. The conference brings together researchers on diverse topics related to combinatorial algorithms, such as algorithms and data structures; algorithmic and combinatorial aspects of cryptography and information security; algorithmic game theory and complexity of games; approximation algorithms; complexity theory; combinatorics and graph theory; combinatorial generation, enumeration, and counting; combinatorial optimization; combinatorics of words; computational biology; computational geometry; decompositions and combinatorial designs; distributed and network algorithms; experimental combinatorics; fine-grained complexity; graph algorithms and modeling with graphs; graph drawing and graph labeling; network theory and temporal graphs; quantum computing and algorithms for quantum computers; online algorithms; parameterized and exact algorithms; probabilistic and randomized algorithms; and streaming algorithms.

The Program Committee (PC) of IWOCA 2022 received 96 abstract submissions; finally, 86 full papers were submitted. Each submission was reviewed by at least three PC members and some trusted external referees, and evaluated on its quality, originality, and relevance to the conference. The PC selected 35 papers for presentation at the conference and inclusion in the proceedings. Three invited talks were scheduled for IWOCA 2022, given by Akanksha Agrawal (Indian Institute of Technology Madras, India) Erik Demaine (MIT, USA), and Bhaskar Ray Chaudhury (University of Illinois Urbana-Champaign, USA), as also testified by these proceedings.

The Program Committee also selected two papers to receive the Best Paper Award and the Best Student Paper Award, respectively. These awards were sponsored by Springer. The awardees are

- Best Paper Award: Hideo Bannai, Tomohiro I, Tomasz Kociumaka, Dominik Köppl, Simon Puglisi. Computing Longest (Common) Lyndon Subsequence.
- Best Student Paper Award: Kanae Yoshiwatari, Hironori Kiya, Tesshu Hanaka, Hirotaka Ono. Winner Determination Algorithms for Graph Games with Matching Structures.

We would like to thank all invited speakers for accepting to give a talk at the conference, the Program Committee members who graciously gave their time and energy, and the 122 external reviewers for their expertise.

The organization of IWOCA 2022 started in the middle of the pandemic crisis. To cope with the related uncertainties, we decided to run IWOCA as a hybrid event. We still hope that, in particular, a number of younger participants were able to enjoy IWOCA as an on-site event, possibly as their first-ever conference.

We also thank Springer for publishing the proceedings of IWOCA 2022 in their ARCoSS/LNCS series and for their financial support towards the best paper awards. Also, we were one of the last conferences collecting experiences with OCS, a Springer system we used for managing the collection and editing of the papers.

Finally, we thank the Steering Committee for giving us the opportunity to serve as program chairs of IWOCA 2022 and for their continuous support.

April 2022

Cristina Bazgan  
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# Graphs as Algorithms: Characterizing Motion-Planning Gadgets through Simulation and Complexity (Abstract of Invited Talk)

Erik D. Demaine

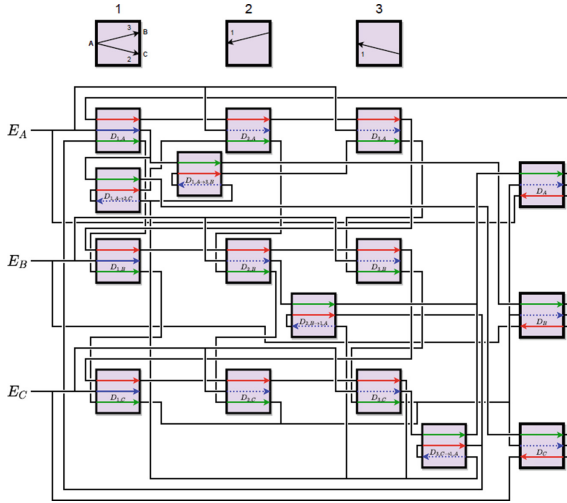
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**Abstract.** Most motion planning problems—designing the route for one or more agents (robots, humans, cars, drones, etc.) through a changeable environment—are computationally difficult: NP-hard, PSPACE-hard, or worse. Such hardness proofs usually consist of several *gadgets*—local pieces of environment with limited agent interactions/traversals, some of which change local state, which in turn change available interactions/traversals—that can be pasted together into the overall reduction. Such gadgets essentially act like finite automata, where the transitions are controlled by one or more agents traversing the environment.

In this talk, I'll describe our quest to characterize exactly which such gadgets suffice to prove different kinds of hardness, in our *motion-planning-through-gadgets framework* that has developed over the past few years [1–9]. This framework enables many hardness proofs, old and new, to be distilled down to a single diagram of a single gadget.

Even stronger, we aim to characterize which motion-planning gadgets can *simulate* which others. Gadget simulations are given by a graph describing how to connect together the simulating gadgets (along with their initial states) in a way that acts like the simulated gadget, essentially representing a reduction algorithm as a graph. See Fig. 1.

**Keywords:** Gadgets • Motion planning • Computational complexity



**Fig. 1.** Illustrative example of a proof that a “door” gadget is *universal*, meaning that it can simulate all other gadgets, from [2]. This graph of connections between door gadgets (drawn as shaded squares) describes an algorithmic reduction from motion planning on doors to motion planning on the desired gadget (with state diagram at top).

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# Contents

## Invited Papers

Distance from Triviality 2.0: Hybrid Parameterizations . . . . .	3
<i>Akanksha Agrawal and M. S. Ramanujan</i>	
On the Existence of EFX Allocations . . . . .	21
<i>Bhaskar Ray Chaudhury</i>	

## Contributed Papers

Lower Bounds for Restricted Schemes in the Two-Adaptive Bitprobe Model. . . . .	31
<i>Sreshth Aggarwal, Deepanjan Kesh, and Divyam Singal</i>	
Perfect Matchings with Crossings . . . . .	46
<i>Oswin Aichholzer, Ruy Fabila-Monroy, Philipp Kindermann, Irene Parada, Rosna Paul, Daniel Perz, Patrick Schnider, and Birgit Vogtenhuber</i>	
Graph Parameters, Implicit Representations and Factorial Properties . . . . .	60
<i>Bogdan Alecu, Vladimir E. Alekseev, Aistis Atminas, Vadim Lozin, and Viktor Zamaraev</i>	
Approximating Subset Sum Ratio via Subset Sum Computations . . . . .	73
<i>Giannis Alonistiotis, Antonis Antonopoulos, Nikolaos Melissinos, Aris Pagourtzis, Stavros Petsalakis, and Manolis Vasilakis</i>	
Faster Algorithm for Finding Maximum 1-Restricted Simple 2-Matchings . . .	86
<i>Stepan Artamonov and Maxim A. Babenko</i>	
Lower Bounds on the Performance of Online Algorithms for Relaxed Packing Problems . . . . .	101
<i>János Balogh, György Dósa, Leah Epstein, and Łukasz Jeż</i>	
An Adjacency Labeling Scheme Based on a Decomposition of Trees into Caterpillars . . . . .	114
<i>Avah Banerjee</i>	
Computing Longest (Common) Lyndon Subsequences. . . . .	128
<i>Hideo Bannai, Tomohiro I, Tomasz Kociumaka, Dominik Köppl, and Simon J. Puglisi</i>	

Structure-Aware Combinatorial Group Testing: A New Method for Pandemic Screening . . . . .	143
<i>Thaís Bardini Idalino and Lucia Moura</i>	
Convex Grid Drawings of Planar Graphs with Constant Edge-Vertex Resolution . . . . .	157
<i>Michael A. Bekos, Martin Gronemann, Fabrizio Montecchiani, and Antonios Symvonis</i>	
1-Extendability of Independent Sets. . . . .	172
<i>Pierre Bergé, Anthony Busson, Carl Feghali, and Rémi Watrigant</i>	
Tukey Depth Histograms . . . . .	186
<i>Daniel Bertschinger, Jonas Passweg, and Patrick Schnider</i>	
An Efficient Algorithm for the Proximity Connected Two Center Problem. . .	199
<i>Binay Bhattacharya, Amirhossein Mozafari, and Thomas C. Shermer</i>	
A New Temporal Interpretation of Cluster Editing. . . . .	214
<i>Cristiano Bocci, Chiara Capresi, Kitty Meeks, and John Sylvester</i>	
List Covering of Regular Multigraphs . . . . .	228
<i>Jan Bok, Jiří Fiala, Nikola Jedličková, Jan Kratochvíl, and Paweł Rzażewski</i>	
The Slotted Online One-Sided Crossing Minimization Problem on 2-Regular Graphs . . . . .	243
<i>Elisabet Burjons, Janosch Fuchs, and Henri Lotze</i>	
Perfect Matching Cuts Partitioning a Graph into Complementary Subgraphs. . . . .	257
<i>Diane Castonguay, Erika M. M. Coelho, Hebert Coelho, Julliano R. Nascimento, and Uéverton S. Souza</i>	
On the Intractability Landscape of Digraph Intersection Representations. . . .	270
<i>Andrea Caucchiolo and Ferdinando Cicalese</i>	
The RED-BLUE SEPARATION Problem on Graphs . . . . .	285
<i>Subhadeep Ranjan Dev, Sanjana Dey, Florent Foucaud, Ralf Klasing, and Tuomo Lehtilä</i>	
Harmless Sets in Sparse Classes . . . . .	299
<i>Pål Grønås Drange, Irene Muzi, and Felix Reidl</i>	
The Parameterized Complexity of $s$ -Club with Triangle and Seed Constraints . . . . .	313
<i>Jaroslav Garvardt, Christian Komusiewicz, and Frank Sommer</i>	

Space-Efficient B Trees via Load-Balancing . . . . .	327
<i>Tomohiro I and Dominik Köppl</i>	
An Additive Approximation Scheme for the Nash Social Welfare Maximization with Identical Additive Valuations . . . . .	341
<i>Asei Inoue and Yusuke Kobayashi</i>	
Controlling Weighted Voting Games by Deleting or Adding Players with or Without Changing the Quota . . . . .	355
<i>Joanna Kaczmarek and Jörg Rothe</i>	
Practical Space-Efficient Index for Structural Pattern Matching . . . . .	369
<i>Sung-Hwan Kim and Hwan-Gue Cho</i>	
A Shift Gray Code for Fixed-Content Łukasiewicz Words . . . . .	383
<i>Paul W. Lapey and Aaron Williams</i>	
Learning from Positive and Negative Examples: Dichotomies and Parameterized Algorithms . . . . .	398
<i>Jonas Lingg, Mateus de Oliveira Oliveira, and Petra Wolf</i>	
Using Edge Contractions and Vertex Deletions to Reduce the Independence Number and the Clique Number . . . . .	412
<i>Felicia Lucke and Felix Mann</i>	
Shortest Unique Palindromic Substring Queries in Semi-dynamic Settings . . .	425
<i>Takuya Mieno and Mitsuru Funakoshi</i>	
On Relative Clique Number of Triangle-Free Planar Colored Mixed Graphs . . . . .	439
<i>Soumen Nandi, Sagnik Sen, and S. Taruni</i>	
Exact Polynomial Time Algorithm for the Response Time Analysis of Harmonic Tasks . . . . .	451
<i>Thi Huyen Chau Nguyen, Werner Grass, and Klaus Jansen</i>	
Computing a Minimum Subset Feedback Vertex Set on Chordal Graphs Parameterized by Leafage . . . . .	466
<i>Charis Papadopoulos and Spyridon Tzimas</i>	
Linear Time Construction of Indexable Elastic Founder Graphs . . . . .	480
<i>Nicola Rizzo and Veli Mäkinen</i>	
On Critical Node Problems with Vulnerable Vertices . . . . .	494
<i>Jannik Schestag, Niels Grüttemeier, Christian Komusiewicz, and Frank Sommer</i>	

**Winner Determination Algorithms for Graph Games**  
**with Matching Structures . . . . . 509**  
    *Kanae Yoshiwatari, Hironori Kiya, Tesshu Hanaka, and Hirotaka Ono*

**Author Index . . . . . 523**