OGGN: A Novel Generalized Oracle Guided Generative Architecture for Modelling Inverse Function of Artificial Neural Networks

Mohammad Aaftab V¹ and Mansi Sharma²

Abstract—This paper presents a novel Generative Neural Network Architecture for modelling the inverse function of an Artificial Neural Network (ANN) either completely or partially. Modelling the complete inverse function of an ANN involves generating the values of all features that corresponds to a desired output. On the other hand, partially modelling the inverse function means generating the values of a subset of features and fixing the remaining feature values. The feature set generation is a critical step for artificial neural networks, useful in several practical applications in engineering and science. The proposed Oracle Guided Generative Neural Network, dubbed as OGGN, is flexible to handle a variety of feature generation problems. In general, an ANN is able to predict the target values based on given feature vectors. The OGGN architecture enables to generate feature vectors given the predetermined target values of an ANN. When generated feature vectors are fed to the forward ANN, the target value predicted by ANN will be close to the predetermined target values. Therefore, the OGGN architecture is able to map, inverse function of the function represented by forward ANN. Besides, there is another important contribution of this work. This paper also introduces a new class of functions, defined as constraint functions. The constraint functions enable a neural network to investigate a given local space for a longer period of time. Thus, enabling to find a local optimum of the loss function apart from just being able to find the global optimum. OGGN can also be adapted to solve a system of polynomial equations in many variables. The experiments on synthetic datasets validate the effectiveness of OGGN on various use cases.

I. INTRODUCTION

Neural networks are known to be great function approximators for a given data, i.e., for a given dataset with features and targets, neural networks are very useful in modelling the function which maps features to targets [1], [2]. The inverse function of a dataset, i.e., the function that maps the targets to corresponding features is also very important. Neural networks have been used to solve the inverse problem, especially in design and manufacturing applications [3]–[10], where the ability to predict features corresponding to a given target value is vital. The modelling of the inverse function can be accomplished by modelling the inverse function of a neural network that maps features to targets. The problem of finding the inverse of a neural network is also crucial in various engineering problems, especially the optimisation ones [11]-[15]. Inverse problems in imaging and computer vision are being solved with the help of deep convolution neural networks [16]–[19]. Generative Adversarial Networks

[20] have also been used extensively in solving inverse problems [21]–[25].

Our paper introduces a novel neural network architecture called Oracle Guided Generative Neural Networks (OGGN). The proposed OGGN model the inverse function (i.e., the function from targets to features) using the forward function (i.e., the function from features to targets). We define oracle as the function mapping features to targets. Theoretically, an oracle can either be a mathematical function or a neural network. The generative neural network is responsible for predicting features that correspond to a desired target, i.e., when the predicted features are modelled using oracle, the output must be close to desired target value. The generator's loss function is dependent on the oracle. Generator tries to minimize loss using gradient descent. Thus, the proposed architecture is called Oracle Guided Generative Neural Network.

The primary contribution of the proposed architecture is solving the problem of modelling the inverse of a given function or neural network. OGGN architecture can generate feature vector based on a given oracle and a given target vector value, such that, when the generated feature vector is fed into the oracle, it outputs the target vector close to the predetermined target value. The proposed OGGN architecture can also find feature vectors subject to constraints like fixed range for a few or all of the feature values. In addition, OGGN can also generate feature vectors corresponding to a required target with one or more feature values fixed as constants. It can also be modified to tackle the problem of solving a system of polynomial equations in many variables. All use cases of OGGN are analyzed on synthetic datasets in various experiments.

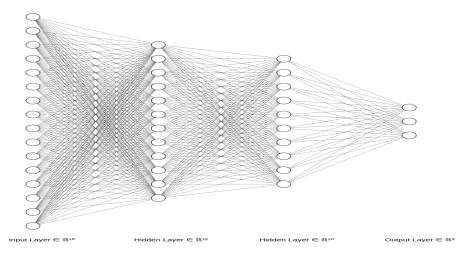
II. RELATED WORK

The problem of developing generative neural networks for finding features has been explored well, especially in the recent years. In this section, we explore some latest methods.

Chen et al. [26] describes a general-purpose inverse design approach using generative inverse design networks along with active learning. They introduce a framework named Generative Inverse Design Networks (GIDNs). Their framework has two DNNs namely, the predictor and the generator. The weights and biases of the predictor are learned using gradient decent and backpropagation, while training on a given dataset. In the designer, the weights and biases are adapted from the predictor and set as constants. Initial Gaussian distribution features are fed into the designer as inputs and the optimized design features are generated as

¹Mohammad Aaftab V is a final Year B.Tech. Mechanical Engineering Student at IIT Madras, India. aaftaabv@gmail.com

²Mansi Sharma is with the Department of Electrical Engineering, IIT Madras, India. mansisharmaiitd@gmail.com



Oracle Neural Network modelling the forward function, i.e. features to targets.

Predictions of features

Predictions of features

| Predictions of features | Predictions of features | Predictions | Prediction

Fig. 1. Oracle neural network: maps features to targets

Fig. 2. Generative network training methodology

outputs. The designer inverse model optimizes the initial inputs or designs based on an objective function via gradient descent with weights and biases of all layers kept as constants and only the input layer values are learned. Active learning takes place in the feedback loop, where the optimized designs or features are verified and added to the dataset. We differ from their approach, in using an additional generator neural network to generate features from random data whose size is tunable according to the complexity of the inverse neural network.

Yang et al. [27] describe neural network inversion in adversarial settings. They present an approach to generate the training data that were used in training a forward neural network using only black box access to it. Our approach also uses a black box access to the forward neural network, but the use cases, training procedure, and architecture are different. While their approach mainly focuses on generating the exact

training data (features and targets) that were used at the time of training the forward neural network, our approach shows how to generate features corresponding to any desired target.

Tahersima et al. [28] present a method to design integrated photonic power splitters using deep neural networks to model the inverse relation. Their approach deals along the same lines as ours. They also use neural networks to find feature vector that corresponds to a given target value. However, their network is different from our approach as it is built for a very specific application of designing integrated photonic power splitters. We proposed an architecture that can be generalized and used for any data.

Zang et al. [29] describes a multi-valued neural network for inverse modeling and application to microwave filters. They also attempt to find the feature vector corresponding to a required target value. They focus mainly on the existence of non-unique feature vectors corresponding to a given target value. Their approach overcomes the above mentioned nonuniqueness problem by generating multiple sets of feature vectors at a time for a given target vector.

Our proposed methodology uses a separate generator neural network to convert random data into features using oracle neural network. Hence, our approach is different from the previous works.

III. PROPOSED ORACLE GUIDED GENERATIVE NEURAL NETWORK

We introduce a novel neural network architecture known as OGGN, for modelling the inverse of a given neural network. Modelling the inverse of a neural network involves finding the values of features that correspond to a desired target value. The most straight forward way to accomplish this task is to train a new neural network with targets as inputs and features as outputs. The data required for training the new inverse neural network can be obtained by swapping the input and output data used to train the forward network. The straight forward method of modelling the inverse function can often suffer from the multi-valued relationship between inputs and outputs. The multi-valued relationship refers to the fact that different feature vectors can correspond to a same target vector. It means that same input values to the inverse network (targets) can have different outputs (features). This causes significant problems while training the inverse neural network directly from the swapped data. Humayun et al. [30] discusses this problem in detail.

The proposed OGGN architecture provides a better alternative method for mapping the inverse of a neural network. Oracle network is the name of the forward neural network whose inverse function we are trying to model (figure 1). The workflow of our architecture is depicted in (figure 2). A generator neural network takes random data as input (the dimensionality of the random data is a hyper-parameter and can be increased or decreased to fit the complexity of the inverse function) and outputs the predicted feature vector value. The training procedure of OGGN is summarized in Algorithm 1.

Algorithm 1: OGGN Methodology

Result: features corresponding to a desired target value

random data (size tunable according to the complexity of system of equations);

Oracle Neural Network (maps the features to targets); e is the acceptable error between predicted targets and desired targets.;

while loss > e do

features = generator(random data); predicted target = oracle(features); loss = (predicted target—desired target)^{2.0}; optimizer adjusts weights and biases of generator neural network based on loss;

end

Once predicted features from generator are obtained, they are modelled into target vectors using the oracle neural network. The loss value of the generator neural network is the mean squared error between the predicted target vectors and desired target vectors. The training of generator neural network is done via gradient descent to minimize the obtained loss value. Minimizing this loss means that the predicted features are close to the features corresponding to the desired target vector. Thus, as the generator trains, it predicts features closer and closer to the required features (i.e., those that correspond the desired target vector). By training the generator, the values of input features corresponding to a desired value of target vector have been derived. It is possible to generate multiple such input feature vectors at a time by passing many rows into the generator neural network and optimising all of them at the same time. Thus, multiple input feature vectors that all correspond to a same or similar value of a output vector can be found.

OGGN can solve the following problems:

- It is possible to model the inverse function to a given neural network by trying to produce the values of feature vectors that correspond to a required output in the forward neural network.
- OGGN can also model only a part of the inverse function of a forward neural network, *i.e.*, it is possible to fix one or more input feature values and train the generator to produce only the remaining feature values such that the whole feature vector corresponds to a desired target value.
- OGGN can constraint the values of one or more generated feature values. This is accomplished by using a family of functions introduced in our paper called constraint functions.
- OGGN can be adapted to solve a system of polynomial equations.

All these use cases are validated using synthetic datasets.

A. Constraint Functions

Activation functions [31] in neural networks such as ReLu, Tanh serve various purposes ranging from introducing non-linearity to the modelling process or avoiding gradient vanishing.

We propose one such family of functions named, *constraint functions*, which serve the purpose of constraining the search/exploration space in a neural network. Constraint functions, like activation functions are applied to each output from a neuron. Constraint functions are conditional and they help the neural network minimize the loss while still exploring in a prescribed space. Constraint functions help in maintaining the outputs in a certain range. One such example function is described in the experiments section below.

IV. EXPERIMENTS AND RESULTS

A. Dataset Preparation

To test the performance of the proposed model, we generated a synthetic dataset. We consider an arbitrary polynomial

exponential function in four variables x_1, x_2, x_3, x_4 . The function is defined as:

$$y = 9x_1^{0.87} + 8.97x_2^{0.02} + 0.876x_3^{0.12} + 2.9876x_4^{0.987}$$
 (1)

The training data has been prepared by randomly choosing values of x_i , i=1,...,4 variables in (1). The target variable y is calculated from polynomial function by substituting the randomly selected x values. We consider 10,000 random sample points of this function (1) for training our model. For testing, we generated a new set of 1000 random samples of the function (1).

B. Experimental Settings

The generated training data is used to train the proposed oracle neural network, which maps the forward function between features and target outputs, i.e., the function mapping from x values to y value. To validate the proposed idea, same oracle network has been used for carrying out all the experiments. Each experiment is designed to validate a use case of the proposed OGGN architecture. The use cases include:

- Generating values of all features corresponding to a desired target value.
- Generating values of some features corresponding to a desired target value, while other feature values are set as constants.
- Generating feature values corresponding to a desired target value, such that, the feature values are restricted within a customizable range.
- Solving a system of polynomial equations.

Each use case requires a different generator neural network architecture.

C. Use Cases of the Proposed OGGN architecture

Here, different use cases of proposed OGGN architecture are described and experiments have been performed to validate the proposed model.

1) Modelling the inverse function: The main purpose of this experiment is to generate values of the features corresponding to a desired output. For example, given a target value y, our objective is to generate the values of x_i , i =1, ..., 4, such that, when they are substituted in the reference function (1), we get the output very near to the previously given target value y. In this experiment, we aim to find feature vectors x_i , i = 1, ..., 4 corresponding to a required output y = 1900. So, the generated $x_i, i = 1, ..., 4$ values from this experiment when modelled using the polynomial function (1), the output is very close to 1900. Generalized steps of this use case is summarized in Algorithm 1. Pseudo code of this experiment is given in Algorithm 2. It is not guaranteed to get the exact desired value always, while modelling the generated features using the forward neural network. It may be either because of the error in modelling the polynomial function by the Oracle network, or due to the polynomial function itself never reach the desired value y for any value of x_i , i = 1, ..., 4. Hence, the generator network

Algorithm 2: Model inverse function using OGGN

Result: features corresponding to a desired target value

random data (size tunable according to the complexity of system of equations); Oracle Neural Network (maps the features to targets); while loss > e do

 x_1, x_2, x_3, x_4 = generator(random data); predicted target = oracle(x_1, x_2, x_3, x_4); loss = (predicted target-desired target)^{2.0}; optimizer adjusts weights and biases of generator neural network based on loss;

end

only tries to minimize the error between the desired output and the predicted target.

After training the generator network for 2000 epochs, we get the feature values $x_1 = 224.6277$, $x_2 = 0.000$, $x_3 =$ 283.2135, $x_4 = 328.2939$. The target value corresponding to the predicted features is 1911.4099. It is clear that this predicted target, 1911.4099 is very close to the desired target value of 1900.00. With this experiment, we verify that we can compute feature vectors that correspond to an output of our choice. Thus, this experiment demonstrates the feasibility of the proposed model and its principle. It verifies the proof of concept or theoretical underpinnings that the proposed OGGN has potential to solve a number of inverse problems. The feature vectors can be further optimized so that the target can be achieved closer to 1900. We can explore different approaches like using more data for training of the oracle network or using extended architecture with more layers for oracle and generator neural networks. Training the networks for a larger number of epochs could also improve the accuracy.

2) Finding the other feature values with one feature specified as constant: In this experiment, we aim to find the optimal values of feature vectors x_i , $i \neq j$, such that one or more variables x_i can be specified as a constant. For example, the value of x_4 is set to 10.0 in the polynomial function (1). The objective is to compute the values of x_1, x_2 , x_3 using proposed model such that the target output should be close to the desired value y = 2000.0. The generator predicts the values of x_1, x_2, x_3 . Now, the feature values (i.e., predicted x_1, x_2, x_3 and constant x_4) are modelled using oracle network. The oracle gives a predicted output and this prediction is compared to target output via mean squared error. The generator network tries to minimize this error by adjusting its weights and biases using back propagation and gradient descent. After training the generator network for 1000 epochs, we estimate the feature values $x_1 = 485.6413$, $x_2 = 70.6677$, $x_3 = 90.4546$, $x_4 = 10.00$. The target value corresponding to the predicted features is 1996.1234. It is clear that the predicted target value 1996.1234 is very close to the desire target value of y = 2000.0. Results can be further improved by using better optimizer or training the networks for longer times with larger datasets. The pseudo code for training OGGN for this experiment is summarized in Algorithm 3.

Algorithm 3: Model subset of inverse function using OGGN

This experiment has been designed to demonstrate that the proposed OGGN architecture can explore different projections of the inverse function as well.

3) Finding the feature vector with some features in a desired range and some features specified to be constant: The objective of this experiment is to find the optimal values of feature vectors $x_i, i \neq j$, such that they are in a desired range and one or more variables x_j can be specified as a constant. For instance, the value of x_4 is set to 100.0 in the polynomial function (1). The objective is to compute the values of x_1, x_2, x_3 using proposed model, such that, the target output should be close to the desired value y = 788.0 and the computed values of x_1, x_2, x_3 are within the desired range of 1 to 100. The generator predicts the values of x_1, x_2, x_3 . The training methodology used in this experiment is summarized in Algorithm 4.

We introduce a family of functions dubbed as constraint functions. These constraint functions decide the range of the output of a neural network. Thus, the feature vectors predicted by generator network are within the predetermined range specified by the constraint functions. The constraint functions are defined as,

$$\begin{cases} x/c_1 & UpperBound \le x \\ x * c_2 & x \le LowerBound \end{cases}$$
 (2)

where, c_1 and c_2 are constants. The values of c_1 and c_2 are decided after checking the range of outputs from the generator network, trained without using constraint functions. If the outputs of unconstrained generator network are higher than the required upper bound, it is necessary to divide those outputs with an appropriate number in order to bring outputs into the desired range. This appropriate value is set as constant c_1 . Similarly, If the outputs of unconstrained generator network are lower than the required lower bound, it is necessary to multiply those outputs with an appropriate number in order to bring outputs into the desired range. This suitable value is set as constant c_2 .

Algorithm 4: Model constrained subset of inverse function using OGGN

Result: some features constrained to a given space corresponding to a desired target value while other features are fixed random data (size tunable according to the complexity of system of equations); Oracle neural network (maps the features to targets); x_4 =100.00 (this is constant); constraints on range of features is given; constraints on range of features is given; constraint functions applied to its output layer; while loss > e do $\begin{vmatrix} x_1, x_2, x_3 = constrainedgenerator(random data); \\ predicted target = oracle(x_1, x_2, x_3, x_4); \\ loss = (predicted target-desired target)^{2.0}; \\ optimizer adjusts weights and biases of generator$

neural network based on loss;

end

For example, in this experiment, the generator before using constraint functions produce the outputs in the range of 200-500. To let the feature values lie between 1 and 100, initially c_1 is set to 2. To further increase the exploration time of generator in the range of 1 and 100, experimentally, the value of c_1 is set to 20.0. Similarly, the value of c_2 has been chosen as 10.0. Thus, the constraint function is defined as

$$\begin{cases} x/20 & 100 \le x \\ x*10 & x \le 1 \end{cases} \tag{3}$$

Like an activation function, the constraint function can be applied to neurons in any layer. However in this experiment, constraint function has been applied on neurons in the output layer only. The constrained generator network predicts x_1 , x_2 , x_3 in the required range. The value of x_4 is set as constant, $x_4 = 100$. The oracle network models the generated features x_1 , x_2 , x_3 and x_4 and predicts the corresponding target. Final loss is calculated as a Mean Squared Error between the predicted target and the required target. The generator neural network then tries to minimize the final loss via gradient descent.

The constraint function enables a neural network to search in a prescribed space for a longer period of time. It helps neural network explore the prescribed space thoroughly. If the global minimum of the loss function lies outside the prescribed range, even a constrained neural network will eventually optimize itself to produce outputs that correspond to global minima of loss function. We can arrive at the local optima by stopping training of the constrained neural network once the outputs go beyond the prescribed range.

We obtained output y=777.5806 with the predicted feature vector $x_1=100.0423$, $x_2=0.0000$, $x_3=53.7249$, $x_4=100.00$. Here the values of x_1 , x_2 , x_3 were generated by the generator after training for 200 epochs. The theoretical maximum value achievable for the function (1) is 787.34, if

all the features x_1 , x_2 , x_3 and x_4 are constrained to lie within the range of 1 and 100. It is apparent that the predicted value is pretty close to the theoretical maximum value. This experiment is designed to show that proposed OGGN architecture can explore different projections of the inverse function in a subspace. Thus, proposed OGGN architecture can impose constraints on one or more features and find the local optimum of a function.

4) Solving a simultaneous system of polynomial equations: In this experiment, we describe another use case of proposed OGGN architecture. OGGN can be used to solve a system of polynomial equations. It is highly versatile and adaptable. Solving a system of polynomial equations involve finding the values of the variables that satisfy all equations. We consider an arbitrary system of polynomial equations to demonstrate the usefulness of the proposed OGGN architecture.

$$9x^{2} + 8.97y^{7.8} + 0.876z - 32.0 = 0,$$

$$12x^{3} + 9.97y^{8} + 10.876z^{3} - 43.0 = 0$$
(4)

To solve (4), we consider the following functions

$$f(x,y,z) = 9x^2 + 8.97y^{7.8} + 0.876z - 32.0,$$

$$g(x,y,z) = 12x^3 + 9.97y^8 + 10.876z^3 - 43.0$$
(5)

Solving the simultaneous system of equations involve finding the values of x, y, z such that both f(x, y, z) and g(x, y, z) would come close to zero. To this end, we consider the oracle function for generator neural network, given as.

oracleoutput =
$$(f(x, y, z)^2 + g(x, y, z)^2)^{0.5}$$
 (6)

The main purpose of oracle is to convert the features into targets. In most real life datasets, a mathematical equation is not available to model the features into targets. The only way to model features into targets in real life datasets is to use a neural network. In the previous experiments, a neural network was used as oracle to demonstrate the ability of the OGGN to work with practical datasets. However, in this example, the objective is to solve a system of equations. A mathematical equation converting variables into targets is readily available. Hence, here the oracle is not a neural network, rather it is a function (6).

The value of the oracle function (6) will be close to zero if and only if both functions f(x,y,z) and g(x,y,z) are close to zero. Hence the solutions of the system of equations (4) are the values of x,y,z such that upon modelling them using the oracle function (6), the output is close to zero. To this end, we task the generator neural network to find the values of x,y,z such that the oracle function value (6) will be close to zero. The training process is summarized in Algorithm 5.

The error e, in algorithm 5 is a small number close to zero. The variables x, y, z predicted by the generator are modelled using the oracle (6). The corresponding loss is calculated as a mean square error between predicted oracle function value and zero. Generator neural network now tries to minimize the loss via gradient descent and back propagation.

Algorithm 5: Solving System of Equations (4): the OGGN way **Result:** solutions of system of equations, x, y, z

```
random data (size tunable according to the complexity of system of equations);  
while loss > e do  
x, y, z = generator(random data);  
predicted target = oracle(x, y, z) (6);  
loss = (predicted target-0.00)<sup>2.0</sup>;  
optimizer adjusts weights and biases of generator neural network based on loss;  
end
```

After training generator neural network, it predicts values of x, y, z such that when modelled using oracle (6), we get an output of 0.0589. The values generated are x = 1.2279, y = 1.0952, z = 0.2624. For these variables, f(x, y, z) = 0.03179 and g(x, y, z) = 0.04953.

If the given system of equations has a solution, we can be certain that the generated values $x=1.2279,\ y=1.0952,\ z=0.2624$ are close to the actual solution. If the system does not have an exact solution, we can conclude that the obtained values of variables $x,\ y,\ z$ take both f(x,y,z) and g(x,y,z) as close to zero as possible. Hence, we conclude in this example that OGGN is capable of solving a system of polynomial equations.

V. CONCLUSIONS AND FUTURE WORK

This paper introduces a novel Oracle Guided Generative Neural Networks (OGGN) to solve the problem of finding the inverse of a given function either fully or partially. The problem of predicting the features corresponding to a desired target is very important and useful in several design and manufacturing fields [3]-[10]. It is also very useful in various engineering problems, especially optimization ones [11]-[15]. OGGN can also generate features subject to constraints, i.e., it can generate features that lie within a given range. Our paper also introduces a class of functions known as Constraint Functions. Constraint functions enable a given neural network to explore a given space thoroughly and arrive at a local optima. The proposed concept of OGGN architecture coupled with constraint functions have huge potential in several practical applications in design and manufacturing industries. OGGNs are flexible and can be adapted to solve a large variety of research problems.

This paper has described a way to generate feature vectors that are able to model a particular fixed target value using OGGN. In the future, we can further extend the proposed idea for generating feature vectors corresponding to different target values. This aids in the process of extending a given dataset by creating new synthetic data. The synthetic data can build a better oracle neural network. This improved oracle can guide the generator more effectively and can lead to the creation of better synthetic data. Thus, OGGNs can potentially help in active learning of both forward mapping

and inverse mapping neural networks for a given dataset. Synthetic dataset generation using the described architecture could helpful in classification tasks [32]. Especially, if there is a lot of class imbalance [33]–[35]. OGGNs can create synthetic data corresponding to the lesser represented class and potentially overcome the problem of class data imbalance.

REFERENCES

- [1] K. Hornik, M. Stinchcombe, and H. White, "Multilayer feedforward networks are universal approximators," *Neural networks*, vol. 2, no. 5, pp. 359–366, 1989.
- [2] S. Wu and M. J. Er, "Dynamic fuzzy neural networks-a novel approach to function approximation," *IEEE transactions on systems, man, and cybernetics, part B (cybernetics)*, vol. 30, no. 2, pp. 358–364, 2000.
- [3] D. Liu, Y. Tan, E. Khoram, and Z. Yu, "Training deep neural networks for the inverse design of nanophotonic structures," *Acs Photonics*, vol. 5, no. 4, pp. 1365–1369, 2018.
- [4] S. A. Hassan, "Artificial neural networks for the inverse design of nanoparticles with preferential nano-bio behaviors," *The Journal of Chemical Physics*, vol. 153, no. 5, p. 054102, 2020.
- [5] J. Lenaerts, H. Pinson, and V. Ginis, "Artificial neural networks for inverse design of resonant nanophotonic components with oscillatory loss landscapes," *Nanophotonics*, vol. 10, no. 1, pp. 385–392, 2021.
- [6] X. Xu, C. Sun, Y. Li, J. Zhao, J. Han, and W. Huang, "An improved tandem neural network for the inverse design of nanophotonics devices," *Optics Communications*, vol. 481, p. 126513, 2021.
- [7] Y. Qu, H. Zhu, Y. Shen, J. Zhang, C. Tao, P. Ghosh, and M. Qiu, "Inverse design of an integrated-nanophotonics optical neural network," *Science Bulletin*, vol. 65, no. 14, pp. 1177–1183, 2020.
- [8] V. Sekar, M. Zhang, C. Shu, and B. C. Khoo, "Inverse design of airfoil using a deep convolutional neural network," *Aiaa Journal*, vol. 57, no. 3, pp. 993–1003, 2019.
- [9] S. So, J. Mun, and J. Rho, "Simultaneous inverse design of materials and structures via deep learning: demonstration of dipole resonance engineering using core–shell nanoparticles," ACS applied materials & interfaces, vol. 11, no. 27, pp. 24264–24268, 2019.
- [10] K. Kim, S. Kang, J. Yoo, Y. Kwon, Y. Nam, D. Lee, I. Kim, Y.-S. Choi, Y. Jung, S. Kim et al., "Deep-learning-based inverse design model for intelligent discovery of organic molecules," npj Computational Materials, vol. 4, no. 1, pp. 1–7, 2018.
- [11] O. May, L. J. Ricalde, B. Ali, E. O. López, E. Venegas-Reyes, and O. A. Jaramillo, "Neural network inverse modeling for optimization," in *Artificial Neural Networks-Models and Applications*. InTech, 2016, vol. 1, no. 2, pp. 168–176.
- [12] J. Hernández, D. Colorado, O. Cortés-Aburto, Y. El Hamzaoui, V. Velazquez, and B. Alonso, "Inverse neural network for optimal performance in polygeneration systems," *Applied Thermal Engineering*, vol. 50, no. 2, pp. 1399–1406, 2013.
- [13] R. Rajesh, R. Preethi, P. Mehata, and B. J. Pandian, "Artificial neural network based inverse model control of a nonlinear process," in 2015 International Conference on Computer, Communication and Control (IC4). IEEE, 2015, pp. 1–6.
- [14] N. Hattab and M. Motelica-Heino, "Application of an inverse neural network model for the identification of optimal amendment to reduce copper toxicity in phytoremediated contaminated soils," *Journal of Geochemical Exploration*, vol. 136, pp. 14–23, 2014.
- [15] V. M. Krasnopolsky, "Neural network applications to solve forward and inverse problems in atmospheric and oceanic satellite remote sensing," in *Artificial Intelligence Methods in the Environmental* Sciences. Springer, 2009, pp. 191–205.
- [16] M. T. McCann, K. H. Jin, and M. Unser, "A review of convolutional neural networks for inverse problems in imaging," arXiv preprint arXiv:1710.04011, 2017.
- [17] G. Ongie, A. Jalal, C. A. Metzler, R. G. Baraniuk, A. G. Dimakis, and R. Willett, "Deep learning techniques for inverse problems in imaging," *IEEE Journal on Selected Areas in Information Theory*, vol. 1, no. 1, pp. 39–56, 2020.
- [18] H. Li, J. Schwab, S. Antholzer, and M. Haltmeier, "Nett: Solving inverse problems with deep neural networks," *Inverse Problems*, vol. 36, no. 6, p. 065005, 2020.
- [19] F. Wang, A. Eljarrat, J. Müller, T. R. Henninen, R. Erni, and C. T. Koch, "Multi-resolution convolutional neural networks for inverse problems," *Scientific reports*, vol. 10, no. 1, pp. 1–11, 2020.

- [20] I. J. Goodfellow, J. Pouget-Abadie, M. Mirza, B. Xu, D. Warde-Farley, S. Ozair, A. Courville, and Y. Bengio, "Generative adversarial networks," arXiv preprint arXiv:1406.2661, 2014.
- [21] H. Ren and P. Ben-Tzvi, "Learning inverse kinematics and dynamics of a robotic manipulator using generative adversarial networks," *Robotics and Autonomous Systems*, vol. 124, p. 103386, 2020.
- [22] Y. Dan, Y. Zhao, X. Li, S. Li, M. Hu, and J. Hu, "Generative adversarial networks (gan) based efficient sampling of chemical composition space for inverse design of inorganic materials," npj Computational Materials, vol. 6, no. 1, pp. 1–7, 2020.
- [23] M. Lenninger, "Generative adversarial networks as integrated forward and inverse model for motor control," 2017.
- [24] A. Creswell and A. A. Bharath, "Inverting the generator of a generative adversarial network," *IEEE transactions on neural networks and learning systems*, vol. 30, no. 7, pp. 1967–1974, 2018.
- [25] M. Asim, M. Daniels, O. Leong, A. Ahmed, and P. Hand, "Invertible generative models for inverse problems: mitigating representation error and dataset bias," in *International Conference on Machine Learning*. PMLR, 2020, pp. 399–409.
- [26] C.-T. Chen and G. X. Gu, "Generative deep neural networks for inverse materials design using backpropagation and active learning," *Advanced Science*, vol. 7, no. 5, p. 1902607, 2020.
- [27] Z. Yang, E.-C. Chang, and Z. Liang, "Adversarial neural network inversion via auxiliary knowledge alignment," arXiv preprint arXiv:1902.08552, 2019.
- [28] M. H. Tahersima, K. Kojima, T. Koike-Akino, D. Jha, B. Wang, C. Lin, and K. Parsons, "Deep neural network inverse design of integrated photonic power splitters," *Scientific reports*, vol. 9, no. 1, pp. 1–9, 2019
- [29] C. Zhang, J. Jin, W. Na, Q.-J. Zhang, and M. Yu, "Multivalued neural network inverse modeling and applications to microwave filters," *IEEE Transactions on Microwave Theory and Techniques*, vol. 66, no. 8, pp. 3781–3797, 2018.
- [30] H. Kabir, Y. Wang, M. Yu, and Q.-J. Zhang, "Neural network inverse modeling and applications to microwave filter design," *IEEE Transactions on Microwave Theory and Techniques*, vol. 56, no. 4, pp. 867–879, 2008.
- [31] C. Nwankpa, W. Ijomah, A. Gachagan, and S. Marshall, "Activation functions: Comparison of trends in practice and research for deep learning," arXiv preprint arXiv:1811.03378, 2018.
- [32] H. I. Fawaz, G. Forestier, J. Weber, L. Idoumghar, and P.-A. Muller, "Deep learning for time series classification: a review," *Data Mining and Knowledge Discovery*, vol. 33, no. 4, pp. 917–963, 2019.
- [33] N. Japkowicz and S. Stephen, "The class imbalance problem: A systematic study," *Intelligent data analysis*, vol. 6, no. 5, pp. 429– 449, 2002.
- [34] X.-Y. Liu, J. Wu, and Z.-H. Zhou, "Exploratory undersampling for class-imbalance learning," *IEEE Transactions on Systems, Man, and Cybernetics, Part B (Cybernetics)*, vol. 39, no. 2, pp. 539–550, 2008.
- [35] J. M. Johnson and T. M. Khoshgoftaar, "Survey on deep learning with class imbalance," *Journal of Big Data*, vol. 6, no. 1, pp. 1–54, 2019.