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Thao Dang · Volker Stolz (Eds.)

Runtime Verification

22nd International Conference, RV 2022
Tbilisi, Georgia, September 28–30, 2022
Proceedings

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ISSN 0302-9743 ISSN 1611-3349 (electronic)
Lecture Notes in Computer Science
ISBN 978-3-031-17195-6 ISBN 978-3-031-17196-3 (eBook)
<https://doi.org/10.1007/978-3-031-17196-3>

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Preface

This volume contains the peer-reviewed proceedings of the 22nd International Conference on Runtime Verification (RV 2022), a hybrid event held during September 28–30, 2022. The conference was part of the Computational Logic Autumn Summit (CLAS 2022), running during September 19–30, 2022, on the campus of the Ivane Javakhishvili Tbilisi State University in Tbilisi, Georgia.

The RV series is a sequence of annual meetings that brings together scientists from both academia and industry interested in investigating novel lightweight formal methods to monitor, analyze, and guide the runtime behavior of software and hardware systems. Runtime verification techniques are crucial for system correctness, reliability, and robustness; they provide an additional level of rigor and effectiveness compared to conventional testing, and are generally more practical than exhaustive formal verification. Runtime verification can be used prior to deployment, for testing, verification, and debugging purposes, and after deployment for ensuring reliability, safety, and security, for providing fault containment and recovery, and for online system repair.

RV started in 2001 as an annual workshop and turned into a conference in 2010. The workshops were organized as satellite events of established forums, including the Conference on Computer-Aided Verification and ETAPS. The proceedings of RV from 2001 to 2005 were published in *Electronic Notes in Theoretical Computer Science*. The RV proceedings have been published in Springer’s *Lecture Notes in Computer Science* since 2006. Previous RV conferences took place in Istanbul, Turkey (2012); Rennes, France (2013); Toronto, Canada (2014); Vienna, Austria (2015); Madrid, Spain (2016); Seattle, USA (2017); Limassol, Cyprus (2018); and Porto, Portugal (2019). The conferences in 2020 and 2021 were held virtually due to the ongoing COVID-19 pandemic.

This year we received 40 submissions, 33 as regular contributions and seven as short or tool papers. Each of these submissions went through a rigorous single-blind review process as a result of which all papers except for a desk-reject received at least three review reports. The Program Committee selected 12 regular and five short/tool papers for presentation during the conference and inclusion in these proceedings. At the suggestion of the reviewers, the authors of five regular contributions that were not initially selected for publication were invited to provide short papers summarizing their ideas and providing pointers to their tools, and these have been included in the proceedings after a final short review. The evaluation and selection process involved thorough discussions among the members of the Program Committee and external reviewers through the EasyChair conference manager, before reaching a consensus on the final decisions.

The conference featured two keynote speakers:

- Serdar Tasiran, Amazon Web Services, USA
- Michal Valko, DeepMind and Inria, France

We are grateful for the support provided by the many people who contributed to RV 2022, including the Steering Committee members. We also thank the members of the Program Committee and their sub-reviewers for their timely and high-quality reviews as well as their contributions to the discussions. The conference organization was partially supported through sponsorship from Runtime Verification Inc., Amazon Web Services, and Springer.

Besik Dundua as local organizing chair assured the smooth organization and running of RV and the other affiliated events at CLAS. Finally, we appreciate the support and assistance provided by the team at Springer, as well as Ana Cavalcanti's and Marie-Claude Gaudel's confidence for including these proceedings into the Formal Methods subline. Volker Stolz is supported by the Norwegian Research Council through grant 309527 – COEMS Training Network.

Thao Dang is supported by the French-Japanese ANR-JST CyphAI project and the UGA DAMon project.

August 2022

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Learning by Bootstrapping of Latents

(Abstract)

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Abstract. We will discuss self-supervised representation learning and a new paradigm for it based on bootstrapping of latents. We first present BYOL (“Bootstrap Your Own Latent”) for images, which relies on two neural networks, referred to as *online* and *target*, that interact and learn from each other: From an augmented view of an image, we train the online network to predict the target network representation of the same image under a different augmented view. At the same time, we update the target network with a slow-moving average of the online network. While prior methods had intrinsically relied on negative pairs, BYOL achieved a new state of the art without them. We will also describe follow-ups of BYOL that we have explored within DeepMind, BGRL for graphs, MYOW for new uncharted domains such as neural readings, and BraVe for videos. We finally apply the paradigm to reinforcement learning and discuss curiosity-driven exploration when the rewards are sparse or absent. For this setting, we give a brand new algorithm BYOL-Explore that jointly learns a world representation, the world dynamics, and an exploration policy.

Contents

Full Papers

Randomized First-Order Monitoring with Hashing.	3
<i>Joshua Schneider</i>	
Automated Surgical Procedure Assistance Framework Using Deep Learning and Formal Runtime Monitoring	25
<i>Gaurav Gupta, Saumya Shankar, and Srinivas Pinisetty</i>	
Relaxing Safety for Metric First-Order Temporal Logic via Dynamic Free Variables	45
<i>Jonathan Julián Huerta y Munive</i>	
Rule-Based Runtime Mitigation Against Poison Attacks on Neural Networks	67
<i>Muhammad Usman, Divya Gopinath, Youcheng Sun, and Corina S. Păsăreanu</i>	
Optimizing Prestate Copies in Runtime Verification of Function Postconditions	85
<i>Jean-Christophe Filliâtre and Clément Pascutto</i>	
A Barrier Certificate-Based Simplex Architecture with Application to Microgrids	105
<i>Amol Damare, Shouvik Roy, Scott A. Smolka, and Scott D. Stoller</i>	
Optimal Finite-State Monitoring of Partial Traces	124
<i>Peeyush Kushwaha, Rahul Purandare, and Matthew B. Dwyer</i>	
Tainting in Smart Contracts: Combining Static and Runtime Verification	143
<i>Shaun Azzopardi, Joshua Ellul, Ryan Falzon, and Gordon J. Pace</i>	
Transaction Monitoring of Smart Contracts	162
<i>Margarita Capretto, Martin Ceresa, and César Sánchez</i>	
Anticipatory Recurrent Monitoring with Uncertainty and Assumptions.	181
<i>Hannes Kallwies, Martin Leucker, César Sánchez, and Torben Scheffel</i>	
Abstract Monitors for Quantitative Specifications	200
<i>Thomas A. Henzinger, Nicolas Mazzocchi, and N. Ege Saraç</i>	
Runtime Verification of Kotlin Coroutines	221
<i>Denis Furian, Shaun Azzopardi, Yliès Falcone, and Gerardo Schneider</i>	

Short and Tool Papers

ASPECTSOL: A Solidity Aspect-Oriented Programming Tool with Applications in Runtime Verification	243
<i>Shaun Azzopardi, Joshua Ellul, Ryan Falzon, and Gordon J. Pace</i>	
Towards Specificationless Monitoring of Provenance-Emitting Systems	253
<i>Martin Stoffers and Alexander Weinert</i>	
A Python Library for Trace Analysis	264
<i>Dennis Dams, Klaus Havelund, and Sean Kauffman</i>	
Lock Contention Performance Classification for Java Intrinsic Locks	274
<i>Nahid Hasan Khan, Joseph Robertson, Ramiro Liscano, Akramul Azim, Vijay Sundaresan, and Yee-Kang Chang</i>	
TestSelector: Automatic Test Suite Selection for Student Projects	283
<i>Filipe Marques, António Morgado, José Fragoso Santos, and Mikoláš Janota</i>	
DECENT: A Benchmark for Decentralized Enforcement	293
<i>Florian Gallay and Yliès Falcone</i>	
Runtime Verification for FMI-Based Co-simulation	304
<i>Anastasios Temperekidis, Nikolaos Kekatos, and Panagiotis Katsaros</i>	
TeSSLa – An Ecosystem for Runtime Verification	314
<i>Hannes Kallwies, Martin Leucker, Malte Schmitz, Albert Schulz, Daniel Thoma, and Alexander Weiss</i>	
Real-Time Visualization of Stream-Based Monitoring Data	325
<i>Jan Baumeister, Bernd Finkbeiner, Stefan Gumhold, and Malte Schledjewski</i>	
Automating Numerical Parameters Along the Evolution of a Nonlinear System	336
<i>Luca Geretti, Pieter Collins, Davide Bresolin, and Tiziano Villa</i>	
Correction to: Rule-Based Runtime Mitigation Against Poison Attacks on Neural Networks	C1
<i>Muhammad Usman, Divya Gopinath, Youcheng Sun, and Corina S. Păsăreanu</i>	
Author Index	347