# **Lecture Notes in Computer Science**

10050

Commenced Publication in 1973
Founding and Former Series Editors:
Gerhard Goos, Juris Hartmanis, and Jan van Leeuwen

#### **Editorial Board**

David Hutchison

Lancaster University, Lancaster, UK

Takeo Kanade

Carnegie Mellon University, Pittsburgh, PA, USA

Josef Kittler

University of Surrey, Guildford, UK

Jon M. Kleinberg

Cornell University, Ithaca, NY, USA

Friedemann Mattern

ETH Zurich, Zurich, Switzerland

John C. Mitchell

Stanford University, Stanford, CA, USA

Moni Naor

Weizmann Institute of Science, Rehovot, Israel

C. Pandu Rangan

Indian Institute of Technology, Madras, India

Bernhard Steffen

TU Dortmund University, Dortmund, Germany

Demetri Terzopoulos

University of California, Los Angeles, CA, USA

Doug Tygar

University of California, Berkeley, CA, USA

Gerhard Weikum

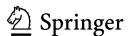
Max Planck Institute for Informatics, Saarbrücken, Germany

More information about this series at http://www.springer.com/series/7411

Marek Chrobak · Antonio Fernández Anta Leszek Gasieniec · Ralf Klasing (Eds.)

# Algorithms for Sensor Systems

12th International Symposium on Algorithms and Experiments for Wireless Sensor Networks, ALGOSENSORS 2016 Aarhus, Denmark, August 25–26, 2016 Revised Selected Papers



Editors
Marek Chrobak
University of California Riverside
Riverside, CA

Antonio Fernández Anta Institute IMDEA Networks Leganés Spain Leszek Gąsieniec University of Liverpool Liverpool UK

Ralf Klasing Université de Bordeaux Talence Cedex France

ISSN 0302-9743 ISSN 1611-3349 (electronic) Lecture Notes in Computer Science ISBN 978-3-319-53057-4 ISBN 978-3-319-53058-1 (eBook) DOI 10.1007/978-3-319-53058-1

Library of Congress Control Number: 2016963667

LNCS Sublibrary: SL5 - Computer Communication Networks and Telecommunications

#### © Springer International Publishing AG 2017

This work is subject to copyright. All rights are reserved by the Publisher, whether the whole or part of the material is concerned, specifically the rights of translation, reprinting, reuse of illustrations, recitation, broadcasting, reproduction on microfilms or in any other physical way, and transmission or information storage and retrieval, electronic adaptation, computer software, or by similar or dissimilar methodology now known or hereafter developed.

The use of general descriptive names, registered names, trademarks, service marks, etc. in this publication does not imply, even in the absence of a specific statement, that such names are exempt from the relevant protective laws and regulations and therefore free for general use.

The publisher, the authors and the editors are safe to assume that the advice and information in this book are believed to be true and accurate at the date of publication. Neither the publisher nor the authors or the editors give a warranty, express or implied, with respect to the material contained herein or for any errors or omissions that may have been made. The publisher remains neutral with regard to jurisdictional claims in published maps and institutional affiliations.

Printed on acid-free paper

This Springer imprint is published by Springer Nature
The registered company is Springer International Publishing AG
The registered company address is: Gewerbestrasse 11, 6330 Cham, Switzerland

#### **Preface**

ALGOSENSORS, the International Symposium on Algorithms and Experiments for Wireless Sensor Networks, is an international forum dedicated to the algorithmic aspects of wireless networks, static or mobile. The 12th edition of ALGOSENSORS was held on August 25, 2016, in Aarhus, Denmark, as a part of the ALGO 2016 event.

Originally focused solely on sensor networks, ALGOSENSORS now covers more broadly algorithmic issues arising in all wireless networks of computational entities, including sensor networks, sensor-actuator networks, and systems of autonomous mobile robots. In particular, it focuses on the design and analysis of discrete and distributed algorithms, on models of computation and complexity, on experimental analysis, in the context of wireless networks, sensor networks, and robotic networks and on all foundational and algorithmic aspects of the research in these areas. This year papers were solicited for three tracks: Distributed and Mobile, Experiments and Applications, and Wireless and Geometry.

In response to the call for papers, 20 submissions were received, out of which nine papers were accepted after a rigorous reviewing process by the (joint) Program Committee, which involved at least three reviewers for each accepted paper. This volume contains the technical papers as well as an invited paper of the keynote talk by Fabian Kuhn (University of Freiburg).

We would like to thank all Program Committee members, as well as the external reviewers, for their fundamental contribution in selecting the best papers resulting in a strong program. We would also like to warmly thank the ALGO 2016 organizers for kindly accepting to co-locate ALGOSENSORS with some of the leading events on algorithms in Europe. Furthermore, we would like to thank the local ALGO 2016 Organizing Committee for their help regarding various administrative tasks, especially the local organizers Gerth Stølting Brodal (chair) and Trine Ji Holmgaard Jensen, as well as the Steering Committee chair, Sotiris Nikoletseas, for their help in ensuring a successful ALGOSENSORS 2016.

December 2016

Marek Chrobak Antonio Fernández Anta Leszek Gąsieniec Ralf Klasing

## **Organization**

### **Program Committee**

Fernando Boavida

Costas Busch

Bogdan Chlebus

Marek Chrobak

Jurek Czyzowicz

University of Coimbra, Portugal

Louisiana State University, USA

University of Colorado Denver, USA

University of California Riverside, USA

Université du Quebec en Outaouais, Canada

Robert Elsässer University of Salzburg, Austria Antonio Fernadez Anta Institute IMDEA Networks, Spain

Pierre Fraigniaud CNRS and Université Paris Diderot, France

Leszek Gąsieniec University of Liverpool, UK Magnús M. Halldórsson Reykjavik University, Iceland

Ralf Klasing

Adrian Kosowski

Evangelos Kranakis

Danny Krizanc

Vincenzo Mancuso

LaBRI - Université Bordeaux, France

IRIF (LIAFA)/Inria Paris, France

Carleton University, Canada

Wesleyan University, USA

Institute IMDEA Networks Spain

Vincenzo Mancuso Institute IMDEA Networks, Spain

Miguel A. Mosteiro
Tomasz Radzik
Gianluca Rizzo
Christian Scheideler
Christopher Thraves
Kean University, USA
King's College London, UK
HES SO Valais, Switzerland
University of Paderborn, Germany
Universidad de Concepción, Chile

## **Steering Committee**

Sotiris Nikoletseas University of Patras and CTI, Greece (Chair)

Josep Diaz

U.P. Catalunya, Spain

Magnús M. Halldórsson

Reykjavik University, Iceland

Magnús M. Halldórsson Reykjavik University, Iceland University of Southern California, USA

P.R. Kumar Texas A&M University, USA

#### **Additional Reviewers**

Bampas, Evangelos Clements, Wyatt Di Stefano, Gabriele Feldmann, Michael Flocchini, Paola Kolb, Christina Krishnan, Hari Lefevre, Jonas Mallmann-Trenn, Frederik Navarra, Alfredo Pajak, Dominik Scalosub, Gabriel Setzer, Alexander Shalom, Mordechai Tamir, Tami Tonoyan, Tigran Wang, Haitao Yu, Dongxiao

# Invited Talk: Developing Robust Wireless Network Algorithms

#### Fabian Kuhn

Department of Computer Science, University of Freiburg, Freiburg, Germany kuhn@cs.uni-freiburg.de

Over the last 30 years, we have seen a tremendous effort in the development of distributed algorithms and abstract models to deal with the characteristic properties of wireless communication networks. The models range from simple graph-based characterizations of interference to more accurate physical models such as the so-called signal-to-noise-and-interference (SINR) model. As different as the typically considered models are, most of them have one thing in common. Whether a node can successfully receive (and decode) a message is determined using some fixed, deterministic rule that depends only on the topology and structure of the actual network and on some additional model parameters.

While in classical wired networks, assuming reliable communication might be a reasonable abstraction, this seems much more problematic in a wireless network setting. The propagation of a wireless signal depends on many diverse environmental factors and it does not seem to be realistic to explicitly model all of these factors or to exactly measure the properties of the wireless communication channels. In addition, the environmental factors might change over time and there can also be additional independent sources of signal interference that cannot be predicted or controlled by the network. Further, wireless devices might also be mobile so that we not only have unreliable communication channels, but potentially even almost arbitrary dynamically changing network topologies. Because the classic abstract wireless communication models do not capture such unpredictable behavior, many existing radio network algorithms might only work in the idealized formal setting for which they were developed.

In the talk, we describe ways to develop more robust wireless network algorithms. In particular, we show that complex, unstable, unreliable, and also dynamic behavior of wireless communication networks can be modeled by adding a non-deterministic component to existing radio network models. As a result, any behavior which is too complex or impossible to predict or model explicitly is determined by an adversary. Clearly, such models might lead to less efficient algorithms. However, they also lead to more robust algorithms which tend to work under a much wider set of underlying assumptions. Very often, such models also lead to much simpler algorithms.

## **Contents**

Multi-message Broadcast in Dynamic Radio Networks	1
Global Synchronization and Consensus Using Beeps in a Fault-Prone MAC <i>Kokouvi Hounkanli, Avery Miller, and Andrzej Pelc</i>	16
Vertex Coloring with Communication and Local Memory Constraints in Synchronous Broadcast Networks	29
A New Kind of Selectors and Their Applications to Conflict Resolution in Wireless Multichannels Networks	45
The Impact of the Gabriel Subgraph of the Visibility Graph on the Gathering of Mobile Autonomous Robots	62
Search-and-Fetch with One Robot on a Disk (Track: Wireless and Geometry)	80
A 2-Approximation Algorithm for Barrier Coverage by Weighted  Non-uniform Sensors on a Line	95
Flexible Cell Selection in Cellular Networks	112
The Euclidean k-Supplier Problem in IR <sup>2</sup>	129
Author Index	141