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Photogrammetric Image Analysis

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Preface

Automated extraction of objects from remotely sensed data is an important topic of research in photogrammetry, computer vision, remote sensing, and geoinformation science. PIA11 addressed researchers and practitioners from universities, research institutes, industry, government organizations, and private companies. The range of topics covered by the conference is reflected by the terms of reference of the cooperating working groups (WGs) of the International Society for Photogrammetry and Remote Sensing (ISRPS):

- □ Lidar, SAR and Optical Sensors (WG I/2)
- □ Pose Estimation and Surface Reconstruction (WG III/1)
- □ Complex Scene Analysis and 3D Reconstruction (WG III/4)
- □ Image Sequence Analysis (WG III/5)

After the successful series of ISPRS conferences on Photogrammetric Image Analysis in Munich in 1999, 2003, and 2007, in 2011 the PIA11 event again discussed recent developments, the potential of various data sources, and future trends in automated object extraction with respect to both sensors and processing techniques, focusing on methodological research. It was held at the Technische Universitaet Muenchen (TUM) in Munich, Germany, during October 5-7, 2011.

Prospective authors were invited to submit full papers of a maximum length of six A4 pages. We received 54 full papers coming from 18 countries for review. The submitted papers were subject to a rigorous double-blind peer-review process. Forty-two papers were reviewed by three members of the Program Committee, whereas the rest (12 papers) were reviewed by two members of the committee. In total we received 150 reviews from 29 reviewers. Altogether 30 papers were accepted based on the reviews, which corresponds to a rejection rate of 44%. Finally, 25 of the 54 papers (46%) were published in this book.

Additionally, authors who intended to present application-oriented work particularly suitable for interactive presentation were invited to submit extended abstracts. Altogether, PIA11 featured seven oral sessions, two poster sessions, and two invited talks, namely, "Convex Optimization Methods for Computer Vision" (Daniel Cremers) and "Exploiting Redundancy for Reliable Aerial Computer Vision" (Horst Bischof).

Finally, the editors wish to thank all contributing authors and the members of the Program Committee. In addition, we would like to express our thanks to the Local Organizing Committee, without whom this event could not have taken place. Ludwig Hoegner did a great job managing the conference tool. The final editing of all incoming manuscripts and the preparation of the proceedings by Michael Schmitt are gratefully acknowledged. Konrad Eder and Dorota Iwaszczuk did a great job organizing the social events and accommodation, Florian

VI Preface

Burkert in caring for the technical equipment, and Sebastian Tuttas in supervising the Local Organizing Committee assistants. We would also like to thank Christine Elmauer, Carsten Goetz, and Gabriele Aumann for their support in making PIA11 a successful event.

Last but not least we would like to thank our sponsors MVTec Software GmbH and INPHO GmbH - A TRIMBLE COMPANY, and our supporting institutions ISPRS, ASPRS, DGPF, EuroSDR, EARSeL, and IAG for their assistance, as well as the Springer Verlag for giving us the opportunity to publish selected papers of PIA11 in the LNCS series.

October 2011

Uwe Stilla Franz Rottensteiner Helmut Mayer Boris Jutzi Matthias Butenuth

Organization

PIA11 was organized by the Department of Photogrammetry and Remote Sensing, Technische Universitaet Muenchen (TUM), and sponsored by the International Society for Photogrammetry and Remote Sensing (ISPRS).



Cooperating ISPRS Working Groups:

- □ Lidar, SAR and Optical Sensors (WG I/2)
- □ Pose Estimation and Surface Reconstruction (WG III/1)
- $\hfill\Box$ Complex Scene Analysis and 3D Reconstruction (WG III/4)
- □ Image Sequence Analysis (WG III/5)

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DGPF – German Society for Photogrammetry, Remote Sensing and Geoinformation



EuroSDR - Spatial Data Research



 ${\bf EARSeL-European\ Association\ of\ Remote\ Sensing\ Laboratories}$



IAG - International Association of Geodesy

Table of Contents

Orientation

Efficient Video Mosaicking by Multiple Loop Closing	1
Estimating the Mutual Orientation in a Multi-camera System with a Non Overlapping Field of View	13
Absolute Orientation of Stereoscopic Cameras by Aligning Contours in Pairs of Images and Reference Images	25
Matching between Different Image Domains	37
Matching	
Reliable Image Matching with Recursive Tiling	49
In-Strip Matching and Reconstruction of Line Segments from UHR Aerial Image Triplets	61
Refined Non-rigid Registration of a Panoramic Image Sequence to a LiDAR Point Cloud	73
Image Sequence Processing in Stereovision Mobile Mapping – Steps towards Robust and Accurate Monoscopic 3D Measurements and Image-Based Georeferencing	85
Object Detection	
Gable Roof Detection in Terrestrial Images	97

Multi-spectral False Color Shadow Detection	109
Extraction of Non-forest Trees for Biomass Assessment Based on Airborne and Terrestrial LiDAR Data	121
Detection of Windows in IR Building Textures Using Masked Correlation	133
3D-Reconstruction and DEM	
Fast Marching for Robust Surface Segmentation	147
A Performance Study on Different Stereo Matching Costs Using Airborne Image Sequences and Satellite images	159
Fusion of Digital Elevation Models Using Sparse Representations Haris Papasaika, Effrosyni Kokiopoulou, Emmanuel Baltsavias, Konrad Schindler, and Daniel Kressner	171
Change Detection in Urban Areas by Direct Comparison of Multi-view and Multi-temporal ALS Data	185
Towards Airborne Single Pass Decimeter Resolution SAR Interferometry over Urban Areas	197
Classification	
Regionwise Classification of Building Facade Images	209
Supervised Classification of Multiple View Images in Object Space for Seismic Damage Assessment	221
Conditional Random Fields for Urban Scene Classification with Full Waveform LiDAR Data	233

People and Tracking	
Statistical Unbiased Background Modeling for Moving Platforms Michael Kirchhof and Uwe Stilla	245
A Scheme for the Detection and Tracking of People Tuned for Aerial Image Sequences	257
Event Detection Based on a Pedestrian Interaction Graph Using Hidden Markov Models Florian Burkert and Matthias Butenuth	271
Trajectory Extraction and Density Analysis of Intersecting Pedestrian Flows from Video Recordings	285
Image Processing	
Measurement Accuracy of Center Location of a Circle by Centroid Method	297

Author Index.....

Table of Contents

XIII

309