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Reasoning with Uncertainty in Robotics

International Workshop, RUR '95
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Preface

This volume contains the (revised) papers presented at the international workshop Reasoning with Uncertainty in Robotics, held on December 4-6, 1995, at the University of Amsterdam, The Netherlands. The programme of the workshop consisted of 2 tutorials, 6 invited talks, 13 presentations of accepted papers, and a forum discussion.

All presented papers are included in this volume, with the exception of 'Reasoning about noisy sensors (and effectors) in the situation calculus', by F. Bacchus, J. Y. Halpern, and H. J. Levesque, since this paper has already been published in the proceedings of IJCAI95. The paper 'An evidential approach to probabilistic map building', by D. Pagac, E. Nebot, and H. Durrant-Whyte does not correspond to the invited talk of Durrant-Whyte, but is included because of the interest it generated during the workshop. Each paper is followed by a transcript (based on recordings) of the discussion ensuing from the author's presentation. A summary of the forum discussion is given in the introduction by the editors.

The programme committee for the workshop was chaired by Frans Groen (University of Amsterdam, The Netherlands) and further consisted of James L. Crowley (IMAG-LIFIA, Grenoble, France), Leo Dorst (University of Amsterdam, The Netherlands), Hugh Durrant-Whyte (University of Sydney, Australia), Alberto Elfes (Automation and Software Systems Institute, Campinas, Brazil), Robert Hummel (Courant Institute of Mathematical Sciences, New York, USA), Leslie Pack Kaelbling (Brown University, Providence, USA), Michiel van Lambalgen (University of Amsterdam, The Netherlands), and Frans Voorbraak (University of Amsterdam, The Netherlands).

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- PIONIER project Reasoning with Uncertainty, of the Netherlands Organization for Scientific Research (NWO)
- Advanced School for Computing and Imaging (ASCI)
- Royal Netherlands Academy of Sciences (KNAW)
- Institute for Logic, Language, and Computation (ILLC)

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