# On path factors of (3, 4)-biregular bigraphs

Armen S. Asratian<sup>\*</sup>, Carl Johan Casselgren<sup>†</sup>

Abstract. A (3, 4)-biregular bigraph G is a bipartite graph where all vertices in one part have degree 3 and all vertices in the other part have degree 4. A path factor of G is a spanning subgraph whose components are nontrivial paths. We prove that a simple (3, 4)-biregular bigraph always has a path factor such that the endpoints of each path have degree three. Moreover we suggest a polynomial algorithm for the construction of such a path factor.

Keywords: path factor, biregular bigraph, interval edge coloring

# 1 Introduction

We use [9] and [7] for terminology and notation not defined here and consider finite loop-free graphs only. V(G) and E(G) denote the sets of vertices and edges of a graph G, respectively. A proper edge coloring of a graph G with colors  $1, 2, 3, \ldots$  is a mapping  $f : E(G) \to \{1, 2, 3, \ldots\}$  such that  $f(e_1) \neq f(e_2)$  for every pair of adjacent edges  $e_1$  and  $e_2$ . A bipartite graph with bipartition (Y, X) is called an (a, b)-biregular bigraph if every vertex in Y has degree a and every vertex in Xhas degree b. A path factor of a graph G is a spanning subgraph whose components are nontrivial paths. Some results on different types of path factors can be found in [1, 2, 17, 18, 20, 23]. In particular, Ando et al [2] showed that a claw-free graph with minimum degree d has a path factor whose components are paths of length at least d. Kaneko [17] showed that every cubic graph has a path factor such that each component is a path of length 2, 3 or 4. It was shown in [18] that a 2-connected cubic graph has a path factor whose components are paths of length 2 or 3.

In this paper we investigate the existence of path factors of (3, 4)-biregular bigraphs such that the endpoints of each path have degree three. Our investigation is motivated by a problem on interval colorings. A proper edge coloring of a graph G with colors  $1, 2, 3, \ldots$  is called an *interval* (or *consecutive*) coloring if the colors received by the edges incident with each vertex of G form an interval of integers. The notion of interval colorings was introduced in 1987 by Asratian and Kamalian [5] (available in English as [6]). Generally, it is an  $\mathcal{NP}$ -complete problem to determine whether a given bipartite graph has an interval coloring [22]. Nevertheless, trees, regular and

<sup>\*</sup>Linköping University, Linköping Sweden, arasr@mai.liu.se.

<sup>&</sup>lt;sup>†</sup>Umeå University, Umeå, Sweden, carl-johan.casselgren@math.umu.se.

complete bigraphs [13, 16], doubly convex bigraphs [16], grids [12] and all outerplanar bigraphs [8, 11] have interval colorings. Hansen [13] proved that every  $(2, \beta)$ -biregular bigraph admits an interval coloring if  $\beta$  is an even integer. A similar result for  $(2, \beta)$ -biregular bigraphs for odd  $\beta$  was given in [14, 19]. Only a little is known about  $(3, \beta)$ -biregular bigraphs. It follows from the result of Hanson and Loten [15] that no such a graph has an interval coloring with fewer than  $3 + b - \gcd(3, b)$  colors, where gcd denotes the greatest common divisor. We showed in [3] that the problem to determine whether a  $(3, \beta)$ -biregular bigraph has an interval coloring is  $\mathcal{NP}$ -complete in the case when 3 divides  $\beta$ .

It is unknown whether all (3, 4)-biregular bigraphs have interval colorings. Pyatkin [21] showed that such a graph G has an interval coloring if G has a 3-regular subgraph covering the vertices of degree four. Another sufficient condition for the existence of an interval coloring of a (3, 4)biregular bigraph G was obtained in [4, 10]: G admits an interval coloring if it has a path factor where every component is a path of length not exceeding 8 and the endpoints of each path have degree three. It was conjectured in [4] that every simple (3, 4)-biregular bigraph has such a path factor. However this seems difficult to prove.

In this note we prove a little weaker result. We show that a simple (3, 4)-biregular bigraph always has a path factor such that the endpoints of each path have degree three. Moreover, we suggest a polynomial algorithm for the construction of such a path factor.

Note that (3, 4)-biregular bigraphs with multiple edges need not have path factors with the required property. For example, consider the graph G formed from three triple-edges by adding a claw; that is, the pairs  $x_iy_i$  have multiplicity three for  $i \in \{1, 2, 3\}$ , and there is an additional vertex  $y_0$  with neighborhood  $\{x_1, x_2, x_3\}$ . Clearly, there is no path factor of G such that the endpoints of each path have degree 3.

### 2 The result

A pseudo path factor of a (3,4)-biregular bigraph G with bipartition (Y, X) is a subgraph F of G, such that every component of F is a path of even length and  $d_F(x) = 2$  for every  $x \in X$ . Let  $V_F = \{y \in Y : d_F(y) > 0\}.$ 

**Theorem 1.** Every simple (3,4)-biregular bigraph has a pseudo path factor.

**Proof.** Let G be a simple (3, 4)-biregular bigraph with bipartition (Y, X). The algorithm below constructs a sequence of subgraphs  $F_0, F_1, F_2, \ldots$  of G, where  $V(F_0) = V(G), \emptyset = E(F_0) \subset E(F_1) \subset E(F_2) \subset \ldots$  and each component of  $F_j$  is a path, for every  $j \ge 0$ . At each step  $i \ge 1$ the algorithm constructs  $F_i$  by adding to  $F_{i-1}$  one or two edges until the condition  $d_{F_j}(x) = 2$ holds for all  $x \in X$ , where  $j \ge 1$ . Then  $F = F_j$  is a pseudo path factor of G. Parallelly the algorithm constructs a sequence of subgraphs  $U_0, U_1, U_2, \ldots$  of G, where  $V(U_0) = V(G)$ ,  $\emptyset = E(U_0) \subset E(U_1) \subset E(U_2) \subset \cdots \subset E(U_j)$ . The edges of each  $U_i$  will not be in the final pseudo path factor F. The algorithm is based on Properties 1-4. During the algorithm the vertices in the set Y are considered to be unscanned or scanned. Initially all vertices in Y are unscanned. At the beginning of each step  $i \ge 1$  we have a current vertex  $x_i$ . The algorithm selects an unscanned vertex  $y_i$ , adjacent to  $x_i$ , and determines which edges incident with  $y_i$  will be in  $F_i$  and which ones in  $U_i$ . If  $d_{F_i}(v) = 2$  for each  $v \in X$ , the algorithm stops. Otherwise the algorithm selects a new current vertex and goes to the next step.

#### Algorithm

Initially  $F_0 = (V(G), \emptyset), U_0 = (V(G), \emptyset)$  and all vertices in Y are unscanned.

**Step** 0. Select a vertex  $y_0 \in Y$ . Let  $x_0, x_1, w$  be the vertices in X adjacent to  $y_0$  in G. Put  $F_1 = F_0 + \{wy_0, y_0x_0\}$  and  $U_1 = U_0 + y_0x_1$ . Consider the vertex  $y_0$  to be scanned. Go to step 1 and consider the vertex  $x_1$  as the current vertex for step 1.

Step i  $(i \ge 1)$ . Suppose that a vertex  $x_i$  with  $d_{F_{i-1}}(x_i) \le 1$  was selected at step (i-1) as the current vertex. By Property 4 (see below),  $d_{U_{i-1}}(x_i) \le 2$ . Therefore there is an edge  $x_i y_i$ with  $y_i \in Y$  which neither belongs to  $F_{i-1}$ , nor to  $U_{i-1}$ . Then, by Property 3, the vertex  $y_i$  is an unscanned vertex and therefore the subgraph  $F_{i-1} + x_i y_i$  does not contain a cycle. Since  $d_G(y_i) = 3$ , the vertex  $y_i$ , besides  $x_i$ , is adjacent to two other vertices,  $w_1^{(i)}$  and  $w_2^{(i)}$ .

**Case 1.**  $d_{F_{i-1}}(w_1^{(i)}) = 2 = d_{F_{i-1}}(w_2^{(i)}).$ 

Put  $F_i = F_{i-1} + x_i y_i$  and  $U_i = U_{i-1} + \{y_i w_1^{(i)}, y_i w_2^{(i)}\}$ . Consider the vertex  $y_i$  to be scanned. If  $d_{F_i}(v) = 2$  for every vertex  $v \in X$  then Stop. Otherwise select an arbitrary vertex  $x_{i+1} \in X$  with  $d_{F_i}(x_{i+1}) \leq 1$ , go to step (i+1) and consider  $x_{i+1}$  as the current vertex for step (i+1).

**Case 2.**  $d_{F_{i-1}}(w_1^{(i)}) = 2$  and  $d_{F_{i-1}}(w_2^{(i)}) \le 1$ .

Put  $F_i = F_{i-1} + x_i y_i$ ,  $U_i = U_{i-1} + \{y_i w_1^{(i)}, y_i w_2^{(i)}\}$  and consider the vertex  $y_i$  to be scanned. Furthermore put  $x_{i+1} = w_2^{(i)}$ , go to step (i+1) and consider the vertex  $x_{i+1}$  as the current vertex for step (i+1).

**Case 3.**  $d_{F_{i-1}}(w_1^{(i)}) \leq 1$  and  $d_{F_{i-1}}(w_2^{(i)}) \leq 1$ . Subcase 3a.  $d_{F_{i-1}}(w_1^{(i)}) = 0$  or  $d_{F_{i-1}}(w_2^{(i)}) = 0$ .

We assume that  $d_{F_{i-1}}(w_1^{(i)}) = 0$ . Put  $F_i = F_{i-1} + \{x_i y_i, y_i w_1^{(i)}\}, U_i = U_{i-1} + y_i w_2^{(i)}$  and consider the vertex  $y_i$  to be scanned. Furthermore put  $x_{i+1} = w_2^{(i)}$ , go to step (i + 1) and consider the vertex  $x_{i+1}$  as the current vertex for step (i + 1).

Subcase 3b.  $d_{F_{i-1}}(w_1^{(i)}) = 1 = d_{F_{i-1}}(w_2^{(i)}).$ 

Since  $y_i$  is an unscanned vertex and  $F_{i-1} + x_i y_i$  does not contain a cycle, the vertex  $y_i$  is an endvertex of only one path in  $F_{i-1} + x_i y_i$ . Then at least one of the graphs  $F_{i-1} + \{x_i y_i, y_i w_1^{(i)}\}$  and  $F_{i-1} + \{x_i y_i, y_i w_2^{(i)}\}$  does not contain a cycle. Assume, for example, that  $F_{i-1} + \{x_i y_i, y_i w_1^{(i)}\}$  does not contain a cycle. Then put  $F_i = F_{i-1} + \{x_i y_i, y_i w_1^{(i)}\}$ ,  $U_i = U_{i-1} + y_i w_2^{(i)}$  and consider the vertex  $y_i$  to be scanned. Furthemore put  $x_{i+1} = w_2^{(i)}$ , go to step (i+1) and consider the vertex  $x_{i+1}$  as

the current vertex for step (i+1).

Now we will prove the correctness of the algorithm. At the beginning of step i we have that  $x_i$  is the current vertex,  $y_i$  is an unscanned vertex adjacent to  $x_i$  and  $w_1^{(i)}$ ,  $w_2^{(i)}$  are the two other vertices adjacent to  $y_i$ . The following two properties are evident.

**Property 1**. The algorithm determines which edges incident with  $y_i$  will be in  $F_i$  and which edges will be in  $U_i$ . The vertex  $y_i$  is then considered to be scanned and the algorithm will never consider  $y_i$  again.

**Property 2.** The current vertex  $x_{i+1}$  for step (i+1) is selected among the vertices  $w_1^{(i)}$  and  $w_2^{(i)}$ , except the case  $d_{F_i}(w_1^{(i)}) = d_{F_i}(w_2^{(i)}) = 2$  when an arbitrary vertex  $x_{i+1} \in X$  with  $d_{F_i}(x_{i+1}) \leq 1$  is selected as the current vertex.

Properties 1 and 2 imply the next property:

**Property 3.** If  $x \in X$ ,  $y \in Y$  and the edge xy neither belongs to  $F_{i-1}$ , nor to  $U_{i-1}$ , then the vertex y is unscanned at the beginning of step i.

**Property 4.** If  $x \in X$  and  $d_{F_{i-1}}(x) \leq 1$  then  $d_{U_{i-1}}(x) \leq 2$ .

**Proof.** The statement is evident if  $d_{U_{i-1}}(x) = 0$ . Suppose that  $d_{U_{i-1}}(x) \ge 1$  and j is the minimum number such that j < i and an edge incident with x was included in  $U_{j-1}$  at step (j-1). Then the statement of Property 4 is evident if j = i - 1.

Now we consider the case j < i - 1. Clearly,  $d_{F_{j-1}}(x) \leq 1$  because  $F_{j-1} \subset F_{i-1}$  and  $d_{F_{j-1}}(x) \leq d_{F_{i-1}}(x) \leq 1$ . Let  $xy_{j-1}$  be the edge included in  $U_{j-1}$  at step (j-1). Since  $d_{U_{j-1}}(x) = 1$  and  $d_{F_{j-1}}(x) \leq 1$ , there is an edge  $xy_j$  with  $y_j \in Y$  which neither belongs to  $F_{j-1}$ , nor to  $U_{j-1}$ . Then, by Property 3, the vertex  $y_j$  is an unscanned vertex and therefore the subgraph  $F_{j-1} + xy_j$  does not contain a cycle. According to the description of the algorithm, the edge  $xy_j$  will be in any case included in  $F_j$  at step j, that is,  $d_{F_j}(x) \geq 1$ . Then  $d_{F_k}(x) = 1$  for every  $k, j \leq k \leq i-1$ , because  $F_j \subset F_k \subset F_{i-1}$  and  $1 \leq d_{F_j}(x) \leq d_{F_k}(x) \leq d_{F_{i-1}}(x) \leq 1$ . Now we will show that  $d_{U_{k-1}}(x) = 1$  for each  $k, j \leq k < i-1$ . Suppose to the contrary that  $d_{U_{k-2}}(x) = 1$  and  $d_{U_{k-1}}(x) = 2$  for some k, j < k < i-1, that is, another edge incident with x was included in  $U_{k-1}$  at step (k-1). Then the conditions  $d_{U_{k-1}}(x) = 2$  and  $d_{F_{k-1}}(x) = 1$  imply that there is an edge  $e \neq y_j x$  incident with x which neither belongs to  $F_{k-1}$ , nor to  $U_{k-1}$ . Using a similar argument as above we obtain that the edge e should be included in  $F_k$  at step k. But then  $d_{F_{i-1}}(x) \geq d_{F_k}(x) = 2$ , which contradicts our assumption  $d_{F_{i-1}}(x) \leq 1$ . Thus  $d_{U_{k-1}}(x) = 1$  for each  $k, j \leq k < i-1$ . It is possible that an edge incident with x will be included in  $U_{k-1}$  at step (i-1). Therefore  $d_{U_{i-1}}(x) \leq 2$ .

The description of the algorithm and Properties 1-4 show that the algorithm will stop at step i only when  $d_{F_i}(x) = 2$  for every  $x \in X$ , that is, when  $F_i$  is a pseudo path factor of G. The proof of Theorem 1 is complete.

Now we will prove that every pseudo path factor of a (3, 4)-biregular bigraph G can be transformed into a path factor of G, such that the endpoints of each path have degree 3.

**Lemma 2.** Let G be a (3, 4)-biregular bigraph with bipartition (Y, X). Then |X| = 3k and |Y| = 4k, for some positive integer k.

This is evident because |E(G)| = 4|X| = 3|Y|.

**Lemma 3.** Let F be a pseudo path factor of a (3, 4)-biregular bigraph G with bipartition (Y, X). Then F has a component which is a path of length at least four.

**Proof.** By Lemma 2 we have that |X| = 3k and |Y| = 4k for some integer k. We also have that  $d_F(x) = 2$  for each vertex  $x \in X$ . If the length of all paths in F is two, then  $|Y| \ge 2|X| = 6k$  which contradicts |Y| = 4k. Therefore F has a component which is a path of length at least four.  $\Box$ 

**Theorem 4.** Let F be a pseudo path factor of a simple (3, 4)-biregular bigraph G with bipartition (Y, X). If  $V_F \neq Y$  and  $y_0$  is a vertex with  $d_F(y_0) = 0$ , then there is a pseudo path factor F' with  $V_{F'} = V_F \cup \{y_0\}$ , such that no path in F' is longer than the longest path in F.

**Proof.** Let  $y_0 \in Y$  and  $d_F(y_0) = 0$ . We will describe an algorithm which will construct a special trail T with origin  $y_0$ .

**Step** 1. Select an edge  $y_0x_1 \notin E(F)$ . Since  $d_F(x_1) = 2$ , there are two edges of F,  $x_1y_1$  and  $x_1u_1$ , which are incident with  $x_1$ .

**Case 1.**  $d_F(y_1) = 2$  or  $d_F(u_1) = 2$ . Suppose, for example, that  $d_F(y_1) = 2$ . Then put  $T = y_0 \rightarrow x_1 \rightarrow y_1$  and Stop. **Case 2.**  $d_F(y_1) = 1 = d_F(u_1)$ .

Put  $T = y_0 \rightarrow x_1 \rightarrow y_1$  and go to Step 2.

**Step** *i*  $(i \ge 1)$ . Suppose that we have already constructed a trail  $T = y_0 \rightarrow x_1 \rightarrow y_1 \rightarrow \cdots \rightarrow x_i \rightarrow y_i$  which satisfies the following conditions:

- (a) All edges in T are distinct and  $y_{j-1}x_j \notin E(F)$ ,  $x_jy_j \in E(F)$  for  $j = 1, \ldots, i$ .
- (b) The vertices  $y_1, \ldots, y_i$  are distinct.
- (c) A component of F containing the vertex  $x_j$  is a path of length 2, for j = 1, ..., i.

Select an edge  $e \in E(G) \setminus E(F)$  which is incident with  $y_i$ . The existence of such an edge follows from the conditions (a), (b) and (c). Moreover, the condition (b) implies that  $e \notin T$ . Let  $e = y_i x_{i+1}$ . Then  $d_F(x_{i+1}) = 2$  because F is a pseudo path factor of G. Since  $e \notin E(T)$ , the conditions (a), (b) and (c) imply that at least one of the edges of F incident with  $x_{i+1}$ , does not belong to T.

**Case 1**.  $x_{i+1}$  lies on a component of F which is a path of length two.

Select a vertex  $y_{i+1}$  such that  $x_{i+1}y_{i+1} \in E(F) \setminus E(T)$ , add the edge  $x_{i+1}y_{i+1}$  and the vertex  $y_{i+1}$  to T and go to step (i+1). Now  $T = y_0 \to x_1 \to y_1 \to \cdots \to x_{i+1} \to y_{i+1}$ .

**Case** 2.  $x_{i+1}$  lies on a component of F which is a path of length at least four. There is a vertex  $y_{i+1}$  such that  $x_{i+1}y_{i+1} \in E(F) \setminus E(T)$  and  $d_F(y_{i+1}) = 2$ . Add the edge  $x_{i+1}y_{i+1}$  and the vertex  $y_{i+1}$  to T and Stop. We have now that  $T = y_0 \to x_1 \to y_1 \to \cdots \to x_{i+1} \to y_{i+1}$ .

By Lemma 3, F has a component which is a path of length at least four. Therefore the algorithm will stop after a finite number of steps. Let the trail  $T = y_0 \rightarrow x_1 \rightarrow y_1 \rightarrow \cdots \rightarrow x_{i+1} \rightarrow y_{i+1}$ , be the result of the algorithm, where  $i \ge 0$ , the vertex  $x_j$  lies on a component of F which is a path of length two for each  $j \le i$ , the vertex  $x_{i+1}$  lies on a component of F which is a path of length at least 4, and  $d_F(y_{i+1}) = 2$ . We define a new pseudo path factor F' by setting V(F') = V(F) and

$$E(F') = (E(F) \setminus \{x_j y_j : j = 1, \dots, i, i+1\}) \cup \{y_{j-1} x_j : j = 1, \dots, i, i+1\}.$$

Clearly,  $V_{F'} = V_F \cup \{y_0\}$  and the proof of Theorem 4 is complete.

Theorems 1 and 4 imply the following theorem:

**Theorem 5.** Every simple (3, 4)-biregular bigraph has a path factor such that the endpoints of each path have degree 3.

## References

- J. Akiyama, M. Kano, Factors and factorizations of graphs- a survey, J. Graph Theory, 9 (1985) 1-42.
- [2] K. Ando, Y. Egawa, A. Kaneko, K. Kawarabayashi, H. Matsuba, Path factors in claw-free graphs, Discrete Mathematics 243 (2002) 195-2000
- [3] A. S. Asratian and C. J. Casselgren, On interval edge colorings of  $(\alpha, \beta)$ -biregular bipartite graphs, Discrete Math. 307 (2006) 1951-1956.
- [4] A. S. Asratian, C. J. Casselgren, J. Vandenbussche and D.B. West, *Proper path-factors and interval edge-colorings of* (3, 4)-*biregular bigraphs*, arXiv:0704.2650v1.
- [5] A. S. Asratian and R. R. Kamalian, Interval coloring of the edges of a multigraph (in Russian), Applied mathematics, 5 (1987), 25-34, Erevan University.
- [6] A. S. Asratian and R. R. Kamalian, Investigation of interval edge-colorings of graphs, Journal of Combinatorial Theory. Series B 62 (1994), no. 1, 34-43.
- [7] A. S. Asratian, T. M. J. Denley, R. Häggkvist, *Bipartite graphs and their applications*, Cambridge University Press, Cambridge, 1998.

- [8] M. A. Axenovich, On interval colorings of planar graphs. Proc. 33rd Southeastern Intl. Conf. Combin., Graph Theory and Computing (Boca Raton, FL, 2002). Congr. Numer. 159 (2002), 77–94.
- [9] J. A. Bondy, U. S. R. Murty, *Graph theory with applications*, American Elsevier Publishing Co., Inc., New York, 1976.
- [10] C. J. Casselgren, Some results on interval edge colorings of bipartite graphs, Master's Thesis, Linköping University, Linköping, Sweden, 2005
- K. Giaro, M. Kubale, Compact scheduling of zero-one time operations in multi-stage systems, Discrete Appl. Math. 145 (2004) 95-103
- [12] K. Giaro, M. Kubale, Consecutive edge-colorings of complete and incomplete Cartesian products of graphs, Congr. Numer. 128(1997) 143-149.
- [13] H. M. Hansen, Scheduling with minimum waiting periods (in Danish), Master Thesis, Odense University, Odense, Denmark, 1992.
- [14] D. Hanson, C. O. M. Loten, B. Toft, On interval colourings of bi-regular bigraphs, Ars Combin. 50 (1998), 23-32.
- [15] D. Hanson, C. O. M. Loten, A lower bound for interval colouring bi-regular bigraphs, Bulletin of the ICA 18 (1996), 69-74.
- [16] R. R. Kamalian, Interval edge-colorings of graphs, Doctoral thesis, Novosibirsk, 1990.
- [17] A. Kaneko, A necessary and sufficient condition for the existence of a path factor every component of which is a path of length at least 2, J. Comb.Theory B 88 (2003)195-218
- [18] K. Kawarabayashi, H. Matsuba, Y. Oda, K. Ota, Path factors in cubic graphs, J. Graph Theory, 39 (2002) 188-193.
- [19] A.V. Kostochka, Unpublished manuscript, 1995
- [20] M.D. Plummer, Graph factors and factorization: 1985-2003: A survey, Discrete Mathematics, 307 (2007) 791-821.
- [21] A. V. Pyatkin, Interval coloring of (3,4)-biregular bigraphs having large cubic subgraphs, Journal of Graph Theory 47 (2004), 122-128.
- [22] S. V. Sevastjanov, Interval colorability of the edges of a bigraph (in Russian), Metody Diskretnogo Analiza, 50 (1990), 61-72.
- [23] H. Wang, Path factors of bipartite graphs J. Graph Theory 18 (1994) 161–167.