## **CORRECTION**



## Correction to: Scarce data driven deep learning of drones via generalized data distribution space

Chen Li<sup>1</sup> · Schyler C. Sun<sup>1</sup> · Zhuangkun Wei<sup>1</sup> · Antonios Tsourdos<sup>1</sup> · Weisi Guo<sup>1,2</sup>

Received: 5 October 2023 / Accepted: 6 October 2023 / Published online: 15 November 2023 © The Author(s) 2023

## Correction to: Neural Computing and Applications https://doi.org/10.1007/s00521-023-08522-z

The article Scarce data driven deep learning of drones via generalized data distribution space written by [Chen Li, Schyler C. Sun, Zhuangkun Wei, Antonios Tsourdos, Weisi Guo], was originally published Online First without Open Access. After publication in volume 35, issue 20, page [15095-15108] the author decided to opt for Open Choice and to make the article an Open Access publication. Therefore, the copyright of the article has been changed to © "The Author(s)] [2023] and the article is forthwith distributed under the terms of the Creative Commons Attribution 4.0 International License, which permits use, sharing, adaptation, distribution and reproduction in any medium or format, as long as you give appropriate credit to the original author(s) and the source, provide a link to the Creative Commons licence, and indicate if changes were made. The images or other third party material in this article are included in the article's Creative Commons

The original article can be found online at https://doi.org/10.1007/s00521-023-08522-z.

□ Chen Li

c.li.21@cranfield.ac.uk

Schyler C. Sun

Schyler.Sun@cranfield.ac.uk

Zhuangkun Wei

Zhuangkun.Wei@cranfield.ac.uk

Antonios Tsourdos

a.tsourdos@cranfield.ac.uk

Weisi Guo

Weisi.Guo@cranfield.ac.uk

- Digital Aviation Research Technology Centre (DARTeC), Cranfield University, College Road, Cranfield MK43 0AL, Bedfordshire, UK
- Alan Turing Institute, 96 Euston Road, London NW1 2DB, England, UK

licence, unless indicated otherwise in a credit line to the material. If material is not included in the article's Creative Commons licence and your intended use is not permitted by statutory regulation or exceeds the permitted use, you will need to obtain permission directly from the copyright holder.

This work is supported by the Department of Transport under the S-TRIG program 2020–21; and the EPSRC/ UKRI Trustworthy Autonomous Systems Node in Security [grant number EP/ V026763/1].

**Open Access** This article is licensed under a Creative Commons Attribution 4.0 International License, which permits use, sharing, adaptation, distribution and reproduction in any medium or format, as long as you give appropriate credit to the original author(s) and the source, provide a link to the Creative Commons licence, and indicate if changes were made. The images or other third party material in this article are included in the article's Creative Commons licence, unless indicated otherwise in a credit line to the material. If material is not included in the article's Creative Commons licence and your intended use is not permitted by statutory regulation or exceeds the permitted use, you will need to obtain permission directly from the copyright holder. To view a copy of this licence, visit http://creativecommons.org/licenses/by/4.0/.

**Publisher's Note** Springer Nature remains neutral with regard to jurisdictional claims in published maps and institutional affiliations.

