# THE KISSING NUMBER IN FOUR DIMENSIONS 

Oleg R. Musin *


#### Abstract

The kissing number problem asks for the maximal number of equal size nonoverlapping spheres that can touch another sphere of the same size in $n$-dimensional space. This problem in dimension three was the subject of a famous discussion between Isaac Newton and David Gregory in 1694. In three dimensions the problem was finally solved only in 1953 by Schütte and van der Waerden. It was proved that the bounds given by Delsarte's method are not good enough to solve the problem in 4-dimensional space. In this paper we present a solution of the problem in dimension four, based on a modification of Delsarte's method.


Keywords: kissing number, contact number, spherical codes, Delsarte's method, Gegenbauer (ultraspherical) polynomials

## 1 Introduction

The kissing number $k(n)$ is the highest number of equal nonoverlapping spheres in $\mathbf{R}^{n}$ that can touch another sphere of the same size. In three dimensions the kissing number problem is asking how many white billiard balls can kiss (touch) a black ball.

The most symmetrical configuration, 12 billiard balls around another, is if the 12 balls are placed at positions corresponding to the vertices of a regular icosahedron concentric with the central ball. However, these 12 outer balls do not kiss each other and may all moved freely. So perhaps if you moved all of them to one side a 13 th ball would possibly fit in?

This problem was the subject of a famous discussion between Isaac Newton and David Gregory in 1694. (May 4, 1694; see [34] for details of this discussion.) It is commonly said that Newton believed the answer was 12 balls, while Gregory thought that 13 might be possible. However, Bill Casselman 9] found some puzzling features in this story.

The Newton-Gregory problem is often called the thirteen spheres problem. R. Hoppe [19] thought he had solved the problem in 1874. But, Thomas Hales

[^0][18] in 1994 published analysis of Hoppe's mistake (see also 33]). It appears that the first complete correct proof of this was published in 1953 by Schütte and van der Waerden 32. A subsequent two-pages sketch of a proof was given by Leech [23] in 1956. (Leech's proof was presented in the first edition of the well known book by Aigner \& Ziegler [1], the authors removed this chapter from the second edition because a complete proof includes too much spherical trigonometry.) The thirteen spheres problem continues to be of interest, new proofs have been published in the last few years by Wu-Yi Hsiang [21], Hiroshi Maehara [25], Károly Böröczky [7], and Kurt Anstreicher [2].

Note that $k(4) \geqslant 24$. Indeed, the unit sphere in $\mathbf{R}^{4}$ centered at $(0,0,0,0)$ has 24 unit spheres around it, centered at the points $( \pm \sqrt{2}, \pm \sqrt{2}, 0,0)$, with any choice of signs and any ordering of the coordinates. The convex hull of these 24 points yields a famous 4-dimensional regular polytope - the " 24 -cell". Its facets are 24 regular octahedra.
H.S.M. Coxeter proposed upper bounds on $k(n)$ in 1963 [11; for $n=4,5,6,7$, and 8 these bounds were $26,48,85,146$, and 244 , respectively. Coxeter's bounds are based on the conjecture that equal size spherical caps on a sphere can be packed no denser than packing where the Delaunay triangulation with vertices at the centers of caps consists of regular simplices. K. Böröczky proved this conjecture in 1978 [6].

The main progress in the kissing number problem in high dimensions was made in the end of 1970's. Vladimir Levenshtein [24, and independently Andrew Odlyzko and N.J.A. Sloane [28 ( $=$ [10, Chap.13]) using Delsarte's method in 1979 proved that $k(8)=240$, and $k(24)=196560$. This proof is surprisingly short, clean, and technically easier than all proofs in three dimensions.

However, $n=8,24$ are the only dimensions in which this method gives a precise result. For other dimensions (for instance, $n=3,4$ ) the upper bounds exceed the lower. In [28] the Delsarte method was applied in dimensions up to 24 (see [10 Table 1.5]). For comparison with the values of Coxeter's bounds on $k(n)$ for $n=4,5,6,7$, and 8 this method gives $25,46,82,140$, and 240 , respectively. (For $n=3$ Coxeter's and Delsarte's methods only gave $k(3) \leqslant 13$ (11) 28.) Kabatiansky and Levenshtein have found an asymptotic upper bound $2^{0.401 n(1+o(1))}$ for $k(n)$ in 1978 [22]. The lower bound $2^{0.2075 n(1+o(1))}$ was found in 35.

Improvements in the upper bounds on kissing numbers (for $n<24$ ) were rather weak during next years (10 Preface to Third Edition] gives a brief review and references). Arestov and Babenko [3] proved that the bound $k(4) \leqslant 25$ cannot be improved using Delsarte's method. Hsiang [20] claims a proof of $k(4)=24$. His work has not received yet a positive peer review.

If $M$ unit spheres kiss the unit sphere in $\mathbf{R}^{n}$, then the set of kissing points is an arrangement on the central sphere such that the (Euclidean) distance between any two points is at least 1. So the kissing number problem can be stated in other way: How many points can be placed on the surface of $\mathbf{S}^{n-1}$ so that the angular separation between any two points is at least $60^{\circ}$ ?

This leads to an important generalization: a finite subset $X$ of $\mathbf{S}^{n-1}$ is called a spherical $z$-code if for every pair $(x, y)$ of $X$ the scalar product $x \cdot y \leq z$. Spheri-
cal codes have many applications. The main application outside mathematics is in the design of signals for data transmission and storage. There are interesting applications to the numerical evaluation of $n$-dimensional integrals 10 Chap.3].

The Delsarte method (also known in coding theory as Delsarte's linear programming method, Delsarte's scheme, polynomial method) is described in [10. 22. ${ }^{1}$ Let $f(t)$ be a real polynomial such that $f(t) \leqslant 0$ for $t \in[-1, z]$, the coefficients $c_{k}$ 's in the expansion of $f(t)$ in terms of Gegenbauer polynomials $G_{k}^{(n)}$ are nonnegative, and $c_{0}=1$. Then the maximal number of points in a spherical $z$-code in $\mathbf{S}^{n-1}$ is bounded by $f(1)$. Suitable coefficients $c_{k}$ 's can be found by the linear programming method [10 Chapters 9,13].

In this paper we present an extension of the Delsarte method that allowed to prove the bound $k(4)<25$, i.e. $k(4)=24$. This extension yields also a proof for $k(3)<13$ [27]. The first version of these proofs used a numerical solution of some nonconvex constrained optimization problems [26] (see also [29]). Now, using geometric approach, we reduced it to relatively simple computations.

## 2 Delsarte's method

Let $X=\left\{x_{1}, x_{2}, \ldots, x_{M}\right\}$ be any finite subset of the unit sphere $\mathbf{S}^{n-1} \subset \mathbf{R}^{n}$, $\mathbf{S}^{n-1}=\left\{x: x \in \mathbf{R}^{n}, x \cdot x=\|x\|^{2}=1\right\}$. From here on we will speak of $x \in \mathbf{S}^{n-1}$ alternatively of points in $\mathbf{S}^{n-1}$ or of vectors in $\mathbf{R}^{n}$.

By $\phi_{i, j}$ we denote the spherical (angular) distance between $x_{i}, x_{j}$. Note that for $X \subset \mathbf{S}^{n-1}, \cos \phi_{i, j}=x_{i} \cdot x_{j}$. It is clear that for any real numbers $u_{1}, u_{2}, \ldots, u_{M}$ the relation

$$
\left\|\sum u_{i} x_{i}\right\|^{2}=\sum_{i, j} \cos \phi_{i, j} u_{i} u_{j} \geqslant 0
$$

holds, or equivalently the Gram matrix $\operatorname{Gram}(X)$ is positive semidefinite, where $\operatorname{Gram}(X)=\left(x_{i} \cdot x_{j}\right)=\left(\cos \phi_{i, j}\right)$.

Schoenberg [30] extended this property to Gegenbauer polynomials $G_{k}^{(n)}$. He proved that if $g_{i, j}=G_{k}^{(n)}\left(\cos \phi_{i, j}\right)$, then the matrix $\left(g_{i, j}\right)$ is positive semidefinite. Schoenberg proved also that the converse holds: if $f(t)$ is a real polynomial and for any finite $X \subset \mathbf{S}^{n-1}$ the matrix $\left(f\left(\cos \phi_{i, j}\right)\right)$ is positive semidefinite, then $f(t)$ is a linear combination of $G_{k}^{(n)}(t)$ with nonnegative coefficients.

Let us recall the definition of Gegenbauer polynomials. Suppose $C_{k}^{(n)}(t)$ be the polynomials defined by the expansion

$$
\left(1-2 r t+r^{2}\right)^{1-n / 2}=\sum_{k=0}^{\infty} r^{k} C_{k}^{(n)}(t)
$$

Then the polynomials $G_{k}^{(n)}(t)=C_{k}^{(n)}(t) / C_{k}^{(n)}(1)$ are called Gegenbauer or ultraspherical polynomials. (So the normalization of $G_{k}^{(n)}$ is determined by the condition $G_{k}^{(n)}(1)=1$.)

[^1]Also the Gegenbauer polynomials $G_{k}^{(n)}$ can be defined by recurrence formula:

$$
G_{0}^{(n)}=1, G_{1}^{(n)}=t, \ldots, G_{k}^{(n)}=\frac{(2 k+n-4) t G_{k-1}^{(n)}-(k-1) G_{k-2}^{(n)}}{k+n-3}
$$

They are orthogonal on the interval $[-1,1]$ with respect to the weight function $\rho(t)=\left(1-t^{2}\right)^{(n-3) / 2}$ (see details in [8, 10, 16, 30]). In the case $n=3, G_{k}^{(n)}$ are Legendre polynomials $P_{k}$, and $G_{k}^{(4)}$ are Chebyshev polynomials of the second kind (but with a different normalization than usual, $U_{k}(1)=1$ ),

$$
G_{k}^{(4)}(t)=U_{k}(t)=\frac{\sin ((k+1) \phi)}{(k+1) \sin \phi}, \quad t=\cos \phi, \quad k=0,1,2, \ldots
$$

For instance, $\quad U_{0}=1, \quad U_{1}=t, \quad U_{2}=\left(4 t^{2}-1\right) / 3, \quad U_{3}=2 t^{3}-t$, $U_{4}=\left(16 t^{4}-12 t^{2}+1\right) / 5, \ldots, U_{9}=\left(256 t^{9}-512 t^{7}+336 t^{5}-80 t^{3}+5 t\right) / 5$.

Let us now prove the bound of Delsarte's method. If a matrix $\left(g_{i, j}\right)$ is positive semidefinite, then the sum of all its entries is nonnegative. Therefore, for $g_{i, j}=G_{k}^{(n)}\left(t_{i, j}\right), t_{i, j}:=\cos \phi_{i, j}$, we have

$$
\begin{equation*}
\sum_{i=1}^{M} \sum_{j=1}^{M} G_{k}^{(n)}\left(t_{i, j}\right) \geqslant 0 \tag{2.1}
\end{equation*}
$$

Suppose

$$
\begin{equation*}
f(t)=c_{0} G_{0}^{(n)}(t)+\ldots+c_{d} G_{d}^{(n)}(t), \text { where } c_{0} \geqslant 0, \ldots, c_{d} \geqslant 0 \tag{2.2}
\end{equation*}
$$

Let

$$
S(X)=\sum_{i=1}^{M} \sum_{j=1}^{M} f\left(t_{i, j}\right)
$$

Using (2.1), we get

$$
\begin{equation*}
S(X)=\sum_{k=0}^{d} \sum_{i=1}^{M} \sum_{j=1}^{M} c_{k} G_{k}^{(n)}\left(t_{i, j}\right) \geqslant \sum_{i=1}^{M} \sum_{j=1}^{M} c_{0} G_{0}^{(n)}\left(t_{i, j}\right)=c_{0} M^{2} \tag{2.3}
\end{equation*}
$$

Let $X=\left\{x_{1}, \ldots, x_{M}\right\} \subset \mathbf{S}^{n-1}$ be a spherical $z$-code, i.e. for all $i \neq j$, $t_{i, j}=\cos \phi_{i, j}=x_{i} \cdot x_{j} \leqslant z$, i.e. $t_{i, j} \in[-1, z]$ (but $t_{i, i}=1$ ). Suppose

$$
f(t) \leqslant 0 \text { for all } t \in[-1, z]
$$

then $f\left(t_{i, j}\right) \leqslant 0$ for all $i \neq j$. That implies

$$
S(X)=M f(1)+2 f\left(t_{1,2}\right)+\ldots+2 f\left(t_{M-1, M}\right) \leqslant M f(1)
$$

If we combine this with (2.3), then for $c_{0}>0$ we get

$$
\begin{equation*}
M \leqslant \frac{f(1)}{c_{0}} \tag{2.4}
\end{equation*}
$$

The inequality (2.4) play a crucial role in the Delsarte method (see details in (3) 4, 5, 10, 14, 15, 22, 24, 28). If $z=1 / 2$ and $c_{0}=1$, then (2.4) implies

$$
k(n) \leqslant f(1)
$$

V.I. Levenshtein 24, and independently A.M. Odlyzko and N.J.A. Sloane 28] have found suitable polynomials $f(t)(f(t) \leqslant 0$ for all $t \in[-1,1 / 2], f$ satisfies (2.2), $c_{0}=1$ ) with

$$
f(1)=240 \text { for } n=8 ; \quad \text { and } \quad f(1)=196560 \text { for } n=24
$$

Then

$$
k(8) \leqslant 240, \quad k(24) \leqslant 196560
$$

For $n=8,24$ sphere packings: $E_{8}$ and Leech lattice give these kissing numbers. Thus $k(8)=240$, and $k(24)=196560$.

When $n=4$, a polynomial $f$ of degree 9 with $f(1) \approx 25.5585$ was found in [28]. This implies $24 \leqslant k(4) \leqslant 25$.

## 3 An extension of Delsarte's method.

Let us now generalize the Delsarte bound $M \leqslant f(1) / c_{0}$.
Definition. Let $f(t)$ be a real function on the interval $[-1,1]$. Consider on $\mathbf{S}^{n-1}$ points $y_{0}, y_{1}, \ldots, y_{m}$ such that

$$
\begin{equation*}
y_{i} \cdot y_{j} \leqslant z \text { for all } i \neq j, \quad f\left(y_{0} \cdot y_{i}\right)>0 \text { for } 1 \leqslant i \leqslant m \tag{3.1}
\end{equation*}
$$

For fixed $y_{0}$ denote by $Q_{m}\left(y_{0}\right)$ the set of all $Y=\left\{y_{1}, \ldots, y_{m}\right\}$ such that $Y$ satisfies (3.1). Let $\mu=\mu(n, z, f)$ be the highest value of $m$ with $Q_{m}\left(y_{0}\right) \neq \emptyset$, i.e. the constraints (3.1) define a non-empty set $Y$.

Suppose $0 \leqslant m \leqslant \mu$,

$$
\begin{gathered}
H\left(y_{0} ; Y\right)=H\left(y_{0} ; y_{1}, \ldots, y_{m}\right):=f(1)+f\left(y_{0} \cdot y_{1}\right)+\ldots+f\left(y_{0} \cdot y_{m}\right), \\
h_{m}=h_{m}(n, z, f):=\max _{Y \in Q_{m}\left(y_{0}\right)}\left\{H\left(y_{0} ; Y\right)\right\} \\
h_{\max }:=\max \left\{h_{0}, h_{1}, \ldots, h_{\mu}\right\} .
\end{gathered}
$$

Theorem 1. Suppose $X \subset \mathbf{S}^{n-1}$ is a spherical $z$-code, $|X|=M$, and $f(t)=c_{0} G_{0}^{(n)}(t)+\ldots+c_{d} G_{d}^{(n)}(t)$ with $c_{0}>0, c_{1} \geqslant 0, \ldots, c_{d} \geqslant 0$. Then

$$
M \leqslant \frac{h_{\max }}{c_{0}}=\frac{1}{c_{0}} \max \left\{h_{0}, h_{1}, \ldots, h_{\mu}\right\} .
$$

Proof. By assumption $f$ satisfies (2.2), then (2.3) yields $S(X) \geqslant c_{0} M^{2}$.
Let $J(i):=\left\{j: f\left(x_{i} \cdot x_{j}\right)>0, j \neq i\right\}$, and $X(i)=\left\{x_{j}: j \in J(i)\right\}$. Then

$$
S_{i}(X):=\sum_{j=1}^{M} f\left(x_{i} \cdot x_{j}\right) \leqslant f(1)+\sum_{j \in J(i)} f\left(x_{i} \cdot x_{j}\right)=H\left(x_{i} ; X(i)\right) \leqslant h_{\max }
$$

so then

$$
S(X)=\sum_{i=1}^{M} S_{i}(X) \leqslant M h_{\max }
$$

We have $c_{0} M^{2} \leqslant S(X) \leqslant M h_{\max }$, i.e. $c_{0} M \leqslant h_{\max }$ as required.
Note that $h_{0}=f(1)$. If $f(t) \leqslant 0$ for all $t \in[-1, z]$, then $\mu(n, z, f)=0$, i.e. $h_{\max }=h_{0}=f(1)$. Therefore, this theorem yields the Delsarte bound $M \leqslant f(1) / c_{0}$.

The problem of evaluating of $h_{\max }$ in general case looks even more complicated than the upper bound problem for spherical $z$-codes. It is not clear how to find $\mu$, what is an optimal arrangement for $Y$ ?

Here we consider this problem only for a very restrictive class of functions

$$
f(t): f(t) \leqslant 0 \text { for } t \in\left[-t_{0}, z\right], \quad 1>t_{0}>z \geqslant 0
$$

For these functions the assumption on $f, f\left(y_{0} \cdot y_{i}\right)>0$, for $Y$ that satisfies (3.1), holds only if

$$
\theta_{i}:=\operatorname{dist}\left(e_{0}, y_{i}\right)<\theta_{0}=\arccos t_{0}
$$

where $e_{0}=-y_{0}$ is the antipodal point to $y_{0}$. In other words, $Y$ lies in the spherical cap $C\left(e_{0}, \theta_{0}\right)$ of center $e_{0}$ and radius $\theta_{0}$. This assumption derives convexity condition for $Y$.

Theorem 2. Suppose $Y=\left\{y_{1}, \ldots, y_{m}\right\} \subset \mathbf{S}^{n-1}$ is a spherical $z$-code, $Y$ belongs to the spherical cap $C\left(e_{0}, \theta_{0}\right)$, and $\theta_{0}<\psi=\arccos z \leqslant 90^{\circ}$. Denote by $\Delta_{m}$ the convex hull of $Y$ in $\mathbf{S}^{n-1}$. Then any $y_{k}$ is a vertex of $\Delta_{m}$, i.e. $\Delta_{m}^{0}=Y$.
(A subset of $\mathbf{S}^{n-1}$ is called (spherical) convex if it contains, with every two nonantipodal points, the small arc of the great circle containing them. The closure of a convex set is convex and is the intersection of closed hemispheres (see details in [13]). If a subset $Y$ of $\mathbf{S}^{n-1}$ lies in a hemisphere, then the convex hull of $Y$ is well defined, and is the intersection of all convex sets containing $Y$.)

Proof. In this paper we need the only one fact from spherical trigonometry, namely the law of cosines:

$$
\cos \phi=\cos \theta_{1} \cos \theta_{2}+\sin \theta_{1} \sin \theta_{2} \cos \varphi
$$

where for spherical triangle $A B C$ the angular lengths of its sides are $\operatorname{dist}(A, B)=\theta_{1}, \operatorname{dist}(A, C)=\theta_{2}, \operatorname{dist}(B, C)=\phi$, and $\angle B A C=\varphi$.

By assumption

$$
\theta_{k}=\operatorname{dist}\left(y_{k}, e_{0}\right) \leqslant \theta_{0}<\psi, 1 \leqslant k \leqslant m ; \quad \phi_{k, j}:=\operatorname{dist}\left(y_{k}, y_{j}\right) \geqslant \psi, k \neq j
$$

Let us prove that there are no $y_{k}$ inside $\Delta_{m}$. Assume the converse. Then consider the great ( $n-2$ )-sphere $\Omega_{k}$ such that $y_{k} \in \Omega_{k}$, and $\Omega_{k}$ is orthogonal to the arc $e_{0} y_{k}$. (Note that $\theta_{k}>0$. Conversely, $y_{k}=e_{0}$ and $\phi_{k, j}=\theta_{j} \leqslant \theta_{0}<\psi$.)

The great sphere $\Omega_{k}$ divides $\mathbf{S}^{n-1}$ into two hemispheres: $H_{1}$ and $H_{2}$. Suppose $e_{0} \in H_{1}$, then at least one $y_{j}$ belongs $H_{2}$. Consider the triangle $e_{0} y_{k} y_{j}$ and denote by $\gamma_{k, j}$ the angle $\angle e_{0} y_{k} y_{j}$ in this triangle. The law of cosines yields

$$
\cos \theta_{j}=\cos \theta_{k} \cos \phi_{k j}+\sin \theta_{k} \sin \phi_{k, j} \cos \gamma_{k, j}
$$

Since $y_{j} \in H_{2}$, we have $\gamma_{k, j}>90^{\circ}$, and $\cos \gamma_{k, j}<0$ (Fig. 1). Therefore,

$$
\cos \theta_{j}<\cos \phi_{k} \cos \phi_{k, j}<\cos \phi_{k, j} \leqslant \cos \psi
$$

then $\theta_{j}>\psi-$ a contradiction.
Now we show how to determine $\mu$ in our case. Denote by $A(n, \psi)$ the maximal size of a spherical $n$-dimensional $z$-code. (Here as above $\cos \psi=z$.) Note that $A\left(n, 60^{\circ}\right)$ is the kissing number $k(n)$.


Fig. 1


Fig. 2

Theorem 3. Suppose $Y=\left\{y_{1}, \ldots, y_{m}\right\} \subset \mathbf{S}^{n-1}$ is a spherical $z$-code, $m \geqslant 2$, and $Y$ lies in the spherical cap of center $e_{0}$ and radius $\theta_{0}$, where $t_{0}=\cos \theta_{0} \geqslant z$. Then

$$
m \leqslant A\left(n-1, \arccos \frac{z-t_{0}^{2}}{1-t_{0}^{2}}\right)
$$

Proof. We have $\phi_{i, j} \geqslant \psi=\arccos z, i \neq j ; \theta_{i} \leqslant \theta_{0}, 1 \leqslant i \leqslant m$; and $\theta_{0} \leqslant \psi$.
Let $\Pi$ be the projection of $Y$ onto equator $\mathbf{S}^{n-2}$ from the pole $e_{0}$. Denote by $\gamma_{i, j}$ the distances between points of $\Pi$ in $\mathbf{S}^{n-2}$ (Fig. 2). Then from the law of cosines and the inequality $\cos \phi_{i, j} \leqslant z$, we get

$$
\begin{aligned}
& \quad \cos \gamma_{i, j}=\frac{\cos \phi_{i, j}-\cos \theta_{i} \cos \theta_{j}}{\sin \theta_{i} \sin \theta_{j}} \leqslant \frac{z-\cos \theta_{i} \cos \theta_{j}}{\sin \theta_{i} \sin \theta_{j}} \\
& \text { Let } \quad Q(\alpha)=\frac{z-\cos \alpha \cos \beta}{\sin \alpha \sin \beta}, \text { then } Q^{\prime}(\alpha)=\frac{\cos \beta-z \cos \alpha}{\sin ^{2} \alpha \sin \beta} .
\end{aligned}
$$

From this follows, if $0<\alpha, \beta \leqslant \theta_{0}$, then $\cos \beta \geqslant z$ (because $\theta_{0} \leqslant \psi$ ); so then $Q^{\prime}(\alpha) \geqslant 0$, and $Q(\alpha) \leqslant Q\left(\theta_{0}\right)$. Therefore,

$$
\cos \gamma_{i, j} \leqslant \frac{z-\cos \theta_{i} \cos \theta_{j}}{\sin \theta_{i} \sin \theta_{j}} \leqslant \frac{z-\cos ^{2} \theta_{0}}{\sin ^{2} \theta_{0}}=\frac{z-t_{0}^{2}}{1-t_{0}^{2}}
$$

This completes the proof.
Corollary 1. Suppose $f(t) \leqslant 0$ for $t \in\left[-t_{0}, z\right], \quad 1>t_{0} \geqslant z \geqslant 0$. If $2 t_{0}^{2} \leqslant z+1$, then

$$
\mu(n, z, f) \leqslant A\left(n-1, \arccos \frac{z-t_{0}^{2}}{1-t_{0}^{2}}\right)
$$

otherwise $\mu(n, z, f)=1$.
Proof. $2 t_{0}^{2}>z+1$ if and only if $\psi>2 \theta_{0}$. Clearly that in this case the size of any $z$-code in the cap $C\left(e_{0}, \theta_{0}\right)$ is at most 1 . In the other case $\mu \geqslant 2$ and it follows from Theorem 3.

Corollary 2. Suppose $f(t) \leqslant 0$ for $t \in\left[-t_{0}, z\right], 1>t_{0} \geqslant z \geqslant 0$. Then

$$
\mu(3, z, f) \leqslant 5
$$

Proof. Note that

$$
T=\frac{z-t_{0}^{2}}{1-t_{0}^{2}} \leqslant \frac{z-z^{2}}{1-z^{2}}=\frac{z}{1+z}<\frac{1}{2} . \quad \text { Then } \delta=\arccos T>60^{\circ}
$$

Thus $\mu(3, z, f) \leqslant A(2, \delta) \leqslant 360^{\circ} / \delta<6$.
Corollary 3. Suppose $f(t) \leqslant 0$ for $t \in\left[-t_{0}, z\right], 1>t_{0}>z \geqslant 0$.
(i) If $t_{0}>\sqrt{z}$, then $\mu(4, z, f) \leqslant 4$.
(ii) If $z=1 / 2, t_{0} \geqslant 0.6058$, then $\mu(4, z, f) \leqslant 6$.

Proof. Denote by $\varphi_{k}(M)$ the largest angular separation that can be attained in a spherical code on $\mathbf{S}^{k-1}$ containing $M$ points. In three dimensions the best codes and the values $\varphi_{3}(M)$ presently known for $M \leqslant 12$ and $M=24$ (see [12] 17 31). Schütte and van der Waerden 31 proved that

$$
\varphi_{3}(5)=\varphi_{3}(6)=90^{\circ}, \quad \cos \varphi_{3}(7)=\cot 40^{\circ} \cot 80^{\circ}, \quad \varphi_{3}(7) \approx 77.86954^{\circ}
$$

(i) Since $z-t_{0}^{2}<0$, Corollary 1 yields: $\mu(4, z, f) \leqslant A(3, \delta)$, where $\delta>90^{\circ}$. We have $\delta>\varphi_{3}(5)$. Thus $\mu<5$.
(ii) Note that for $t_{0} \geqslant 0.6058$,

$$
\arccos \frac{1 / 2-t_{0}^{2}}{1-t_{0}^{2}}>77.87^{\circ}
$$

So Corollary 1 implies $\mu(4,1 / 2, f) \leqslant A\left(3,77.87^{\circ}\right)$. Since $77.87^{\circ}>\varphi_{3}(7)$, we have $A\left(3,77.87^{\circ}\right)<7$, i.e. $\mu \leqslant 6$.

Corollary 1 shows that if $t_{0}$ is close enough to 1 , then $\mu$ is small enough. Then one gets relatively small - dimensional optimization problems for computation of numbers $h_{m}$ for small $n$. If additionally $f(t)$ is a monotone decreasing function on $\left[-1,-t_{0}\right]$, then these problems can be reduced to low-dimensional optimization problems of a type that can be easily treated numerically.

## 4 Optimal and irreducible sets

In this section we consider $f(t)$ that satisfies the monotonicity assumption:
$f(t)$ is a monotone decreasing function on the interval $\left[-1,-t_{0}\right]$,

$$
\begin{equation*}
f(t) \leqslant 0 \text { for } t \in\left[-t_{0}, z\right], \quad 1>t_{0}>z \geqslant 0 \tag{*}
\end{equation*}
$$

Consider a spherical $z$-code $Y=\left\{y_{1}, \ldots, y_{m}\right\} \subset \mathbf{S}^{n-1}$ such that $Y$ lies in a spherical cap $C\left(e_{0}, \theta_{0}\right)$ of center $e_{0}$ and radius $\theta_{0}$ with $\theta_{0}<\psi=\arccos z \leqslant 90^{\circ}$. As above, $\theta_{k}=\operatorname{dist}\left(y_{k}, e_{0}\right), \phi_{i, j}=\operatorname{dist}\left(y_{i}, y_{j}\right), \Delta_{m}$ is the convex hull of $Y$ in $\mathbf{S}^{n-1}, \cos \theta_{0}=t_{0}$, and $y_{0}=-e_{0}$. Then $H\left(y_{0} ; Y\right)$ is represented in the form:

$$
\begin{equation*}
F\left(\theta_{1}, \ldots, \theta_{m}\right):=H\left(y_{0} ; Y\right)=f(1)+f\left(-\cos \theta_{1}\right)+\ldots+f\left(-\cos \theta_{m}\right) \tag{4.1}
\end{equation*}
$$

Since $Y$ is a $z$-code, we have the constraint $\phi_{i, j} \geqslant \psi$ for all $i \neq j$. Denote by $\Gamma_{\psi}(Y)$ the graph with the set of vertices $Y$ and the set of edges $y_{i} y_{j}$ such that $\phi_{i, j}=\psi$.

Definition. We say that a spherical $z$-code $Y,|Y|=m$, in a spherical cap $C\left(e_{0}, \theta_{0}\right) \subset \mathbf{S}^{n-1}, \theta_{0}<\psi \leqslant 90^{\circ}$, is optimal for $f$ if $H\left(y_{0} ; Y\right)=h_{m}$. If optimal $Y$ is not unique up to isometry, then we call $Y$ as optimal if the graph $\Gamma_{\psi}(Y)$ has the maximal number of edges.

Let us call a spherical $z$-code $Y$ in a cap $C\left(e_{0}, \theta_{0}\right) \subset \mathbf{S}^{n-1}$ as irreducible if there are no points $y_{i} \in Y$ can be shifted towards $e_{0}$ (i.e. this shift decreases $\left.\theta_{i}\right)$ such that $Y^{\prime}$, what is obtained after this shifting, is also a $z$-code. As above, in the case when irreducible $Y$ is not defined uniquely up to isometry by $\theta_{i}$, we say that $Y$ is irreducible if the graph $\Gamma_{\psi}(Y)$ has the maximal number of edges.

Proposition 1. Suppose $f(t)$ satisfies the monotonicity assumption (*). If $Y$ is optimal for $f$, then $Y$ is irreducible.

Proof. Since (4.1), we have that the function $F\left(\theta_{1}, \ldots, \theta_{m}\right)$ increases whenever $\theta_{k}$ decreases. From this follows that no $y_{k}$ can be shifted towards $e_{0}$. In the converse case, $H\left(y_{0} ; Y\right)$ increases whenever $y_{k}$ tends to $e_{0}$. It contradicts the optimality of the initial set $Y$.

Lemma 1. If $Y$ is irreducible, then
(i) $e_{0} \in \Delta_{m}=\operatorname{conv} Y$;
(ii) If $m>1$, then $\operatorname{deg} y_{i}>0$ for all $y_{i} \in Y$, where by $\operatorname{deg} y_{i}$ denoted the degree of the vertex $y_{i}$ in the graph $\Gamma_{\psi}(Y)$.

Proof. ( $i$ ) Otherwise whole $Y$ can be shifted to $e_{0}$.
(ii) Indeed, if $\phi_{i, j}>\psi$ for all $j \neq i$, then $y_{i}$ can be shifted towards $e_{0}$.

For $m=1$ from this follows that $e_{0}=y_{1}$. Thus

$$
\begin{equation*}
h_{1}=f(1)+f(-1) . \tag{4.2}
\end{equation*}
$$

For $m=2$, Lemma 1 implies that $\phi_{1,2}=\psi$, i.e. $\Delta_{2}=y_{1} y_{2}$ is an arc of length $\psi$.

Consider $\Delta_{m} \subset \mathbf{S}^{n-1}$ of dimension $k, \operatorname{dim} \Delta_{m}=k$. Since $\Delta_{m}$ is a convex set, there exists the great $k$-dimensional sphere $\mathbf{S}^{k}$ in $\mathbf{S}^{n-1}$ containing $\Delta_{m}$.

Note that if $\operatorname{dim} \Delta_{m}=1$, then $m=2$. Indeed, since $\operatorname{dim} \Delta_{m}=1$, it follows that $Y$ belongs to the great circle $\mathbf{S}^{1}$. It is clear that in this case $m=2$. (For instance, $m>2$ contradicts Theorem 2 for $n=2$.)

To prove our main results in this section for $n=3,4$ we need the following fact. (For $n=3$, when $\Delta$ is an arc, a proof of this claim is trivial.)

Lemma 2. Consider in $\mathbf{S}^{n-1}$ an arc $\omega$ and a regular simplex $\Delta$, both are with edge lengths $\psi, \psi \leqslant 90^{\circ}$. Suppose the intersection of $\omega$ and $\Delta$ is not empty. Then at least one of the distances between vertices of $\omega$ and $\Delta$ is less than $\psi$.

Proof. We have $\omega=u_{1} u_{2}, \Delta=v_{1} v_{2} \ldots v_{k}, \operatorname{dist}\left(u_{1}, u_{2}\right)=\operatorname{dist}\left(v_{i}, v_{j}\right)=\psi$.
Assume the converse. Then $\operatorname{dist}\left(u_{i}, v_{j}\right) \geqslant \psi$ for all $i, j$. By $U$ denote the union of the spherical caps of centers $v_{i}, i=1, \ldots, k$, and radius $\psi$. Let $B$ be the boundary of $U$. Note that $u_{1}$ and $u_{2}$ don't lie inside $U$. If $\left\{u_{1}^{\prime}, u_{2}^{\prime}\right\}=\omega \bigcap B$, then $\psi=\operatorname{dist}\left(u_{1}, u_{2}\right) \geqslant \operatorname{dist}\left(u_{1}^{\prime}, u_{2}^{\prime}\right)$, and $\omega^{\prime} \bigcap \Delta \neq \emptyset$, where $\omega^{\prime}=u_{1}^{\prime} u_{2}^{\prime}$.

We have the following optimization problem: to find an arc $w_{1} w_{2}$ of minimal length subject to the constraints $w_{1}, w_{2} \in B$, and $w_{1} w_{2} \bigcap \Delta \neq \emptyset$ ? It is not hard to prove that $\operatorname{dist}\left(w_{1}, w_{2}\right)$ attains its minimum when $w_{1}$ and $w_{2}$ are at the distance of $\psi$ from all $v_{i}$, i.e. $w_{1} v_{1} \ldots v_{k}$ and $w_{2} v_{1} \ldots v_{k}$ are regular simplices with the common facet $\Delta$. Using this, it can be shown by direct calculation that

$$
\begin{equation*}
\cos \alpha=\frac{2 k z^{2}-(k-1) z-1}{1+(k-1) z}, \quad \alpha=\min \operatorname{dist}\left(w_{1}, w_{2}\right), z=\cos \psi \tag{4.3}
\end{equation*}
$$

We have $\alpha \leqslant \psi$. From (4.3) follows that $\cos \alpha \geqslant z$ if and only if $z \geqslant 1$ or $(k+1) z+1 \leqslant 0$. It contradicts the assumption $0 \leqslant z<1$.

Now we consider irreducible sets in three dimensions. In this case dim $\Delta_{m} \leqslant 2$.
Theorem 4. Suppose $Y$ is irreducible and $\operatorname{dim}\left(\Delta_{m}\right)=2$.
Then $3 \leqslant m \leqslant 5$, and $\Delta_{m}$ is a spherical regular triangle, rhomb, or equilateral pentagon with edge lengths $\psi$.

Proof. From Corollary 2 follows that $m \leqslant 5$. On the other hand, $m>2$. Then $m=3,4,5$. Theorem 2 implies that $\Delta_{m}$ is a convex polygon. From Lemma 1 it follows that $e_{0} \in \Delta_{m}$, and $\operatorname{deg} y_{i} \geqslant 1$.

First let us prove that if $\operatorname{deg} y_{i} \geqslant 2$ for all $i$, then $\Delta_{m}$ is equilateral $m$-gon with edge lengths $\psi$. Indeed, it is clear for $m=3$.

Lemma 2 implies that two diagonals of $\Delta_{m}$ of lengths $\psi$ do not intersect each other. That yields the proof for $m=4$. When $m=5$, it remains to consider the case where $\Delta_{5}$ consists of two regular non overlapping triangles
with a common vertex (Fig. 3). This case contradicts the convexity of $\Delta_{5}$. Indeed, $\angle y_{i} y_{1} y_{j}>60^{\circ}$ (see the proof of Corollary 2), then

$$
180^{\circ} \geqslant \angle y_{2} y_{1} y_{5}=\angle y_{2} y_{1} y_{3}+\angle y_{3} y_{1} y_{4}+\angle y_{4} y_{1} y_{5}>180^{\circ}
$$

- a contradiction.


Fig. 3


Fig. 4

Now we prove that $\operatorname{deg} y_{i} \geqslant 2$. Suppose $\operatorname{deg} y_{1}=1$, i.e. $\phi_{1,2}=\psi, \phi_{1, i}>\psi$ for $i=3, \ldots, m$. If $e_{0} \notin y_{1} y_{2}$, then after sufficiently small turn of $y_{1}$ round $y_{2}$ to $e_{0}$ (Fig. 4) the distance $\theta_{1}$ decreases - a contradiction. (This turn will be considered in Lemma 3 with more details.)

It remains to consider the case: $e_{0} \in y_{1} y_{2}$. If $\phi_{i, j}=\psi$ where $i>2$ or $j>2$, then $e_{0} \notin y_{i} y_{j}$. Indeed, in the converse case, we have two intersecting diagonals of lengths $\psi$. Therefore, $\operatorname{deg} y_{i} \geqslant 2$ for $2<i \leqslant m$. For $m=3,4$ it implies the proof. For $m=5$ there is the case where $Q_{3}=y_{3} y_{4} y_{5}$ is a regular triangle of side length $\psi$. Note that $y_{1} y_{2}$ cannot intersect $Q_{3}$ (otherwise we again have intersecting diagonals of lengths $\psi$ ), then $y_{1} y_{2}$ is a side of $\Delta_{5}$. In this case, as above, after sufficiently small turn of $Q_{3}$ round $y_{2}$ to $e_{0}$ the distance $\theta_{i}, i=3,4,5$, decreases - a contradiction.

Now we extend these results to four dimensions. ${ }^{2}$
Let us consider a rotation $R(\varphi, \Omega)$ on $\mathbf{S}^{n-1}$ about an $(n-3)$ - dimensional great sphere $\Omega$ in $\mathbf{S}^{n-1}$. Without loss of generality, we may assume that

$$
\Omega=\left\{\vec{u}=\left(u_{1}, \ldots, u_{n}\right) \in \mathbf{R}^{n}: u_{1}=u_{2}=0, u_{1}^{2}+\ldots+u_{n}^{2}=1\right\}
$$

[^2]Denote by $R(\varphi, \Omega)$ the rotation in the plane $\left\{u_{i}=0, i=3, \ldots, n\right\}$ through an angle $\varphi$ about the origin $\Omega$ :

$$
u_{1}^{\prime}=u_{1} \cos \varphi-u_{2} \sin \varphi, \quad u_{2}^{\prime}=u_{1} \sin \varphi+u_{2} \cos \varphi, \quad u_{i}^{\prime}=u_{i}, i=3, \ldots, n
$$

Let

$$
\begin{array}{cl}
H_{+}=\left\{\vec{u} \in \mathbf{S}^{n-1}: u_{2} \geqslant 0\right\}, & H_{-}=\left\{\vec{u} \in \mathbf{S}^{n-1}: u_{2} \leqslant 0\right\} \\
Q=\left\{\vec{u} \in \mathbf{S}^{n-1}: u_{2}=0, u_{1}>0\right\}, & \bar{Q}=\left\{\vec{u} \in \mathbf{S}^{n-1}: u_{2}=0, u_{1} \geqslant 0\right\} .
\end{array}
$$

Note that $H_{-}$and $H_{+}$are closed hemispheres of $\mathbf{S}^{n-1}, \bar{Q}=Q \bigcup \Omega$, and $\bar{Q}$ is a hemisphere of the unit sphere $\Omega_{2}=\left\{\vec{u} \in \mathbf{S}^{n-1}: u_{2}=0\right\}$ bounded by $\Omega$.

Lemma 3. Consider two points $y$ and $e_{0}$ in $\mathbf{S}^{n-1}$. Suppose $y \in Q$ and $e_{0} \notin \bar{Q}$. If $e_{0} \in H_{+}$, then any rotation $R(\varphi, \Omega)$ of $y$ with sufficiently small positive $\varphi$ decreases the distance between $y$ and $e_{0}$.
If $e_{0} \in H_{-}$, then any rotation $R(\varphi, \Omega)$ of $y$ with sufficiently small negative $\varphi$ decreases the distance between $y$ and $e_{0}$.

Proof. Let $y$ be rotated into the point $y(\varphi)$. If the coordinate expressions of $y$ and $e_{0}$ are

$$
\begin{aligned}
& y=\left(u_{1}, 0, u_{3}, \ldots, u_{n}\right), \quad u_{1}>0 ; \quad e_{0}=\left(v_{1}, v_{2}, \ldots, v_{n}\right) \text {, then } \\
& r(\varphi):=y(\varphi) \cdot e_{0}=u_{1} v_{1} \cos \varphi+u_{1} v_{2} \sin \varphi+u_{3} v_{3}+\ldots+u_{n} v_{n}
\end{aligned}
$$

Therefore, $r^{\prime}(\varphi)=-u_{1} v_{1} \sin \varphi+u_{1} v_{2} \cos \varphi$, i.e. $r^{\prime}(0)=u_{1} v_{2}$. Then

$$
\begin{aligned}
& r^{\prime}(0)>0
\end{aligned} \quad \text { iff } \quad v_{2}>0, \quad \text { i.e. } \quad e_{0} \in H_{+} ; ~ 子 \quad \text { i.e. } \quad e_{0} \in H_{-} .
$$

That proves the lemma for $v_{2} \neq 0$. In the case $v_{2}=0$, by assumption $\left(e_{0} \notin \bar{Q}\right)$ we have $v_{1}<0$. In this case $r^{\prime}(0)=0$, and $r^{\prime \prime}(0)=-u_{1} v_{1}>0$, i.e. $\varphi=0$ is a minimum point. This completes the proof.

Proposition 2. Let $Y$ be irreducible and $m=|Y| \geqslant n$. Suppose there are no closed great hemispheres $\bar{Q}$ in $\mathbf{S}^{n-1}$ such that $\bar{Q}$ contains $n-1$ points from $Y$ and $e_{0}$. Then any vertex of $\Gamma_{\psi}(Y)$ has degree at least $n-1$.

Proof. Without loss of generality, we may assume that

$$
\phi_{1, i}=\psi, \quad i=2, \ldots, \operatorname{deg} y_{1}+1 ; \quad \phi_{1, i}>\psi, \quad i=\operatorname{deg} y_{1}+2, \ldots, m
$$

Suppose $\operatorname{deg} y_{1}<n-1$. Then $\phi_{1, i}>\psi$ for $i=n, \ldots, m$. Let us consider the great $(n-3)$ - dimensional sphere $\Omega$ in $\mathbf{S}^{n-1}$ that contains the points $y_{2}, \ldots, y_{n-1}$. Then Lemma 3 implies that a rotation $R(\varphi, \Omega)$ of $y_{1}$ with sufficiently small $\varphi$ decreases $\theta_{1}$. It contradicts the irreducibility of $Y$.

Proposition 3. If $Y$ is irreducible, $|Y|=n$, $\operatorname{dim} \Delta_{n}=n-1$, then $\operatorname{deg} y_{i}=n-1$ for all $i=1, \ldots, n$. In other words, $\Delta_{n}$ is a regular simplex of edge lengths $\psi$.

Proof. Clearly, $\Delta_{n}$ is a spherical simplex. Denote by $F_{i}$ its facets,

$$
F_{i}:=\operatorname{conv}\left\{y_{1}, \ldots, y_{i-1}, y_{i+1}, \ldots, y_{n}\right\}
$$

Let for $\sigma \subset I_{m}:=\{1, \ldots, m\}$

$$
F_{\sigma}:=\bigcap_{i \in \sigma} F_{i}
$$

We claim for $i \neq j$ that:

$$
\begin{equation*}
\text { If } e_{0} \notin F_{\{i, j\}}, \text { then } \phi_{i, j}=\psi \tag{4.4}
\end{equation*}
$$

Conversely, from Lemma 3 follows that there exists a rotation $R\left(\varphi, \Omega_{i j}\right)$ of $y_{i}$ (or $y_{j}$ if $e_{0} \in F_{i}$ ) decreases $\theta_{i}$ (respectively, $\theta_{j}$ ), where $\Omega_{i j}$ is the great $(n-3)$ - dimensional sphere contains $F_{\{i, j\}}$. It contradicts the irreducibility assumption for $Y$.

This yields, if there is no pair $\{i, j\}$ such that $e_{0} \in F_{\{i, j\}}$, then $\phi_{i, j}=\psi$ for all $i, j$ from $I_{m}$.

Suppose $e_{0} \in F_{\sigma}$, where $\sigma$ has maximal size and $|\sigma|>1$. Let $\bar{\sigma}=I_{m} \backslash \sigma$. From (4.4) follows that $\phi_{i, j}=\psi$ if $i \in \bar{\sigma}$ or $j \in \bar{\sigma}$. It remains to prove that $\phi_{i, j}=\psi$ for $i, j \in \sigma$.

Let $\Lambda$ be the intersection of the spheres of centers $y_{i}, i \in \bar{\sigma}$, and radius $\psi$. Then $\Lambda$ is a sphere in $\mathbf{S}^{n-1}$ of dimension $|\sigma|-1$. Note that all $y_{i}, i \in \sigma$, lie on $\Lambda$ at the same distance from $e_{0}$. It is clear that $Y$ is irreducible if and only if $y_{i}, i \in \sigma$, on $\Lambda$ are vertices of a regular simplex of edge length $\psi$.

Finally, we have that all edges of $\Delta_{n}$ are of lengths $\psi$ as required.
Corollary 4. If $n>3$, then $\Delta_{4}$ is a regular tetrahedron of edge lengths $\psi$.
Proof. Let us show that $\operatorname{dim} \Delta_{4}=3$. In the converse case, $\operatorname{dim} \Delta_{4}=2$, and from Theorem 4 follows that $\Delta_{4}$ is a rhomb. Suppose $y_{1} y_{3}$ is the minimal length diagonal of $\Delta_{4}$. Then $\phi_{2,4}>\psi$ (see Lemma 2). Let us consider a sufficiently small turn of the facet $y_{1} y_{2} y_{3}$ round $y_{1} y_{3}$. If $e_{0} \notin y_{1} y_{3}$, then this turn decreases either $\theta_{4}$ (if $e_{0} \in y_{1} y_{2} y_{3}$ ) or $\theta_{2}$, a contradiction. In the case $e_{0} \in y_{1} y_{3}$ any turn of $y_{2}$ round $y_{1} y_{3}$ decreases $\phi_{2,4}$ and doesn't change $\theta_{2}$. Obviously, there is a turn such that $\phi_{2,4}$ becomes is equal to $\psi$. That contradicts the irreducibility of $Y$ also.

Lemma 4. If $Y \subset \mathbf{S}^{3}$ is irreducible, $|Y|=5$, then $\operatorname{deg} y_{i} \geqslant 3$ for all $i$.
Proof. (1) Let us show that $\operatorname{dim} \Delta_{5}=3$. In the converse case, $\operatorname{dim} \Delta_{5}=2$, and from Theorem 4 follows that $\Delta_{5}$ is a convex equilateral pentagon. Suppose $y_{1} y_{3}$ is the minimal length diagonal of $\Delta_{5}$. We have $\phi_{2, k}>\psi$ for $k>3$. Suppose $e_{0} \notin y_{1} y_{3}$. If $e_{0} \in y_{1} y_{2} y_{3}$ then any sufficiently small turn of the facet $y_{1} y_{2} y_{3}$ round $y_{1} y_{3}$ decreases $\theta_{4}$ and $\theta_{5}$, otherwise it decreases $\theta_{2}$, a contradiction. In the case $e_{0} \in y_{1} y_{3}$ any turn of $y_{2}$ round $y_{1} y_{3}$ decreases $\phi_{2, k}$ for $k=4,5$, and
doesn't change $\theta_{i}$. It can be shown in the elementary way that there is a turn such that $\phi_{2,4}$ or $\phi_{2,5}$ becomes is equal to $\psi$, a contradiction.

In three dimensions there exist only two combinatorial types of convex polytopes with 5 vertices: (A) and (B) (see Fig. 5). In the case (A) the arc $y_{3} y_{5}$ lies inside $\Delta_{5}$, and for (B): $y_{2} y_{3} y_{4} y_{5}$ is a facet of $\Delta_{5}$.

(2) By $s_{i j}$ we denote the arc $y_{i} y_{j}$, and by $s_{i j k}$ denote the triangle $y_{i} y_{j} y_{k}$. Let $\tilde{s}_{i j k}$ be the intersection of the great $2-$ hemisphere $Q_{i j k}$ and $\Delta_{5}$, where $Q_{i j k}$ contains $y_{i}, y_{j}, y_{k}$ and bounded by the great circle passes through $y_{i}, y_{j}$. Proposition 2 yields: if there are no $i, j, k$ such that $e_{0} \in \tilde{s}_{i j k}$, then $\operatorname{deg} y_{i} \geqslant 3$ for all $i$.

It remains to consider all cases $e_{0} \in \tilde{s}_{i j k}$. Note that for (A) $\tilde{s}_{i j k} \neq s_{i j k}$ only for three cases: $i=1,2,4$; where $j=3, k=5$, or $j=5, k=3\left(\tilde{s}_{i 35}=\tilde{s}_{i 53}\right)$.
(3) Lemma 1 yields that $\operatorname{deg} y_{k}>0$. Now we consider the cases $\operatorname{deg} y_{k}=1,2$.

$$
\text { If } \operatorname{deg} y_{k}=1, \phi_{k, \ell}=\psi, \text { then } e_{0} \in s_{k \ell} .
$$

Indeed, otherwise there exists the great circle $\Omega$ in $\mathbf{S}^{3}$ such that $\Omega$ contains $y_{\ell}$, and the great sphere passes through $\Omega$ and $y_{k}$ doesn't pass through $e_{0}$. Then Lemma 3 implies that a rotation $R(\varphi, \Omega)$ of $y_{k}$ with sufficiently small $\varphi$ decreases $\theta_{k}$ - a contradiction.

Since $\theta_{0}<\psi, e_{0}$ can not be a vertex of $\Delta_{5}$. Therefore, $e_{0}$ lies inside $s_{k \ell}$. From this follows if $s_{i j}$ for any $j$ doesn't intersect $s_{k \ell}$, then $\operatorname{deg} y_{i} \geqslant 2$.

Arguing as above it is easy to prove that

$$
\text { If } \operatorname{deg} y_{k}=2, \phi_{k, i}=\phi_{k, j}=\psi, \text { then } e_{0} \in \tilde{s}_{i j k}
$$

(4) Now we prove that $\operatorname{deg} y_{k} \geqslant 2$ for all $k$. Conversely, $\operatorname{deg} y_{k}=1, e_{0} \in s_{k \ell}$.
a). First we consider the case when $s_{k \ell}$ is an "external" edge of $\Delta_{5}$. For the type (A) that means $s_{k \ell}$ differs from $s_{35}$, and for (B) it is not $s_{35}$ or $s_{24}$. Since $\Delta_{5}$ is convex, there exists the great $2-$ sphere $\Omega_{2}$ passes through $y_{k}, y_{\ell}$ such that 3 other points $y_{i}, y_{j}, y_{q}$ lie inside the hemisphere $H_{+}$bounded by $\Omega_{2}$. Let $\Omega$ be the great circle in $\Omega_{2}$ that contains $y_{\ell}$ and is orthogonal to the arc $s_{k \ell}$. Then (Lemma 3) there exists a small turn of $y_{i}, y_{j}, y_{q}$ round $\Omega$ that simultaneously decreases $\theta_{i}, \theta_{j}, \theta_{q}$ - a contradiction.
b). For the type (A) when $\operatorname{deg} y_{3}=1, \phi_{3,5}=\psi, e_{0} \in s_{35}$; we claim that $s_{124}$ is a regular triangle with side length $\psi$. Indeed, from (3) follows that $\operatorname{deg} y_{i} \geqslant 2$ for $i=1,2,4$. Moreover, if $\operatorname{deg} y_{i}=2$, then $e_{0}=s_{35} \bigcap s_{124}$. Therefore, in any case, $\phi_{1,2}=\phi_{1,4}=\phi_{2,4}=\psi$. We have the arc $s_{35}$ and the regular triangle $s_{124}$, both are with edge lengths $\psi$. Then from Lemma 2 follows that some $\phi_{i, j}<\psi$ - a contradiction.
c). Now for the type (B) consider the case: $\operatorname{deg} y_{3}=1, \phi_{3,5}=\psi, e_{0} \in s_{35}$. Then for $y_{2}$ we have: $\operatorname{deg} y_{2}=1$ only if $\phi_{2,4}=\psi, e_{0}=s_{24} \bigcap s_{35} ; \quad \operatorname{deg} y_{2}=2$ only if $\phi_{2,4}=\phi_{2,5}=\psi$; and $\phi_{2,4}=\phi_{1,2}=\phi_{2,5}=\psi$ if $\operatorname{deg} y_{2}=3$. Thus, in any case, $\phi_{2,4}=\psi$. We have two intersecting diagonals $s_{24}, s_{35}$ of lengths $\psi$. Then Lemma 2 contradicts the assumption that $Y$ is a $z$-code. This contradiction concludes the proof that $\operatorname{deg} y_{k} \geqslant 2$ for all $k$.
(5) Finally let us prove that $\operatorname{deg} y_{k} \geqslant 3$ for all $k$. Assume the converse. Then $\operatorname{deg} y_{k}=2, e_{0} \in \tilde{s}_{i j k}$, where $\phi_{k, i}=\phi_{k, j}=\psi$.

Case facet: Let $s_{i j k}$ be a facet of $\Delta_{5}$, and $e_{0} \notin s_{i j}$. By the same argument as in (4a), where $\Omega_{2}$ be the great sphere contains $s_{i j k}$, and $\Omega$ be the great circle passes through $y_{i}, y_{j}$, we can prove that there exists a shift decreases $\theta_{\ell}, \theta_{q}$ for two other points $y_{\ell}, y_{q}$ from $Y$, a contradiction.

If $e_{0} \in s_{i j}$, then any turn of $s_{\ell q}$ round $\Omega$ doesn't change $\theta_{\ell}$ and $\theta_{q}$. However, if this turn is in a positive direction, then it decreases $\phi_{k, \ell}$ and $\phi_{k, q}$. Clearly, there exists a turn when $\phi_{k, \ell}$ or $\phi_{k, q}$ is equal to $\psi$ - a contradiction.

It remains to consider all cases where $s_{i j k}$ is not a facet. Namely, there are the following cases: $s_{124}, s_{135}\left(\right.$ type (A)), $s_{234}$ (type (B)).

Case $s_{124}$ : We have $\operatorname{deg} y_{1}=2, \phi_{1,2}=\phi_{1,4}=\psi, e_{0} \in s_{124}$. Consider a small turn of $y_{3}$ round $s_{24}$ towards $y_{1}$. If $e_{0} \notin s_{24}$, then this turn decreases $\theta_{3}$. Therefore, the irreducibility yields $\phi_{3,5}=\psi$. In the case $e_{0} \in s_{24}, \theta_{3}^{\prime}=\theta_{3}$, but $\phi_{1,3}$ decreases. It again implies $\phi_{3,5}=\psi$. Since $s_{35}$ cannot intersects a regular triangle $s_{124}$ [see Lemma 2, (4b)], $\phi_{2,4}>\psi$. Then $\operatorname{deg} y_{2}=\operatorname{deg} y_{4}=3$. (Since $e_{0} \in s_{124}, \operatorname{deg} y_{2}=2$ only if $\phi_{2,4}=\psi$.) Thus we have three isosceles triangles $s_{243}, s_{241}, s_{245}$. Using this and $\phi_{3,5}=\psi$, we obviously have $\phi_{1, i}<\psi$ for $i=3,5$, - a contradiction.

Case $s_{135}\left(\right.$ type (A)): This case has two subcases: $\tilde{s}_{135}, \tilde{s}_{315}$.
In the subcase $\tilde{s}_{135}$ we have $\operatorname{deg} y_{1}=2, \phi_{1,3}=\phi_{1,5}=\psi, e_{0} \in \tilde{s}_{135}$.
If $e_{0} \notin s_{135}$, then any turn of $y_{1}$ round $s_{35}$ decreases $\theta_{1}$ (Lemma 3). Then $e_{0} \in s_{135}$. Clearly, any small turn of $y_{2}$ round $s_{35}$ increases $\phi_{2,4}$. On the other hand, this turn decreases $\theta_{2}$ (if $e_{0} \notin s_{35}$ ) and $\phi_{1,2}$. Arguing as above, we get a contradiction. The subcase $\tilde{s}_{315}$, where $\phi_{3,5}=\psi$, can be proven by the same arguments as Case $s_{124}$.

Case $s_{234}\left(\right.$ type (B)): This case has two subcases: $\tilde{s}_{234}, \tilde{s}_{324}$.
In fact, $\tilde{s}_{234}$ is the same as Case facet, and $\tilde{s}_{324}$ can be proven in the same way as subcase $\tilde{s}_{135}$. This concludes the proof.

Lemma 4 yields that the degree of any vertex of $\Gamma_{\psi}(Y)$ is not less than 3. This implies that at least one vertex of $\Gamma_{\psi}(Y)$ has degree 4. Indeed, if all vertices of $\Gamma_{\psi}(Y)$ are of degree 3 , then the sum of the degrees equals 15 , i.e. is
not an even number. There exists only one type of $\Gamma_{\psi}(Y)$ with these conditions (Fig. 6). The lengths of all edges of $\Delta_{5}$ except $y_{2} y_{4}, y_{3} y_{5}$ are equal to $\psi$. For fixed $\phi_{2,4}=\alpha, \Delta_{5}$ is uniquely defined up to isometry. Therefore, we have the 1-parametric family $P_{5}(\alpha)$ on $\mathbf{S}^{3}$. If $\phi_{3,5} \geqslant \phi_{2,4}$, then $z \geqslant \cos \alpha \geqslant 2 z-1$.


Fig. 6: $P_{5}(\alpha)$

These results can be summarized as follows.
Theorem 5. Let $Y \subset \mathbf{S}^{3}$ be an irreducible set, $|Y|=m \leqslant 5$. Then $\Delta_{m}$ for $2 \leqslant m \leqslant 4$ is a regular simplex of edge lengths $\psi$, and $\Delta_{5}$ is isometric to $P_{5}(\alpha)$ for some $\alpha \in[\psi, \arccos (2 z-1)]$.

## 5 On calculations of $h_{m}$

In this technical section we explain how to find an upper bound on $h_{m}$ for $n=4, m \leqslant 6$. Note that Theorem 5 gets for computation of $h_{m}$ a lowdimensional optimization problem (see (5.3)). Our first approach for this problem was to apply numerical methods 26. However, that is a nonconvex constrained optimization problem. In this case, the Nelder-Mead simplex method and other local improvements methods cannot guarantee finding a global optimum. It's possible (using estimations of derivatives) to organize computational process in such way that it gives a global optimum. However, such solutions are very hard to verify and some mathematicians don't accept that kind of proofs. Fortunately, using geometric approach, estimations of $h_{m}$ can be reduced to relatively simple computations.

First consider the case $m=2$. Suppose $f$ satisfies the monotonicity assumption $(*)$, and $Y$ is optimal. Then $\tilde{f}(\theta):=f(-\cos \theta)$ is a monotone decreasing function in $\theta, \Delta_{2}=y_{1} y_{2}$ is an arc of length $\psi, e_{0} \in \Delta_{2}$, and $\theta_{1}+\theta_{2}=\psi$, where $\theta_{i} \leqslant \theta_{0}$. Since (4.1), $F\left(\theta_{1}, \theta_{2}\right)$ is a symmetric function in $\theta_{1}, \theta_{2}$. We can assume that $\theta_{1} \leqslant \theta_{2}$, then $\theta_{1} \in\left[\psi-\theta_{0}, \psi / 2\right]$. Since $\Theta_{2}\left(\theta_{1}\right):=\psi-\theta_{1}$ is a monotone decreasing function, $\tilde{f}\left(\Theta_{2}\left(\theta_{1}\right)\right)$ is a monotone increasing function in $\theta_{1}$. Thus for any $\theta_{1} \in[\zeta, \xi] \subset\left[\psi-\theta_{0}, \psi / 2\right]$ :

$$
F\left(\theta_{1}, \theta_{2}\right) \leqslant \Phi_{2}([\zeta, \xi]):=f(1)+\tilde{f}(\zeta)+\tilde{f}(\psi-\xi)
$$

Let $a_{1}=\psi-\theta_{0}, a_{2}, \ldots, a_{N}, a_{N+1}=\psi / 2$ be points in $\left[\psi-\theta_{0}, \psi / 2\right]$ such that $a_{i+1}=a_{i}+\varepsilon$, where $\varepsilon=\left(\theta_{0}-\psi / 2\right) / N$. If $\theta_{1} \in\left[a_{i}, a_{i+1}\right]$, then $h_{2}=H\left(y_{0} ; Y\right)=F\left(\theta_{1}, \theta_{2}\right) \leqslant \Phi_{2}\left(\left[a_{i}, a_{i+1}\right]\right)$. Thus

$$
h_{2} \leqslant \lambda_{2}\left(N, \psi, \theta_{0}\right):=\max _{1 \leqslant i \leqslant N}\left\{\Phi_{2}\left(c_{i}\right)\right\}, \text { where } c_{i}:=\left[a_{i}, a_{i+1}\right] .
$$

Clearly, $\lambda_{2}\left(N, \psi, \theta_{0}\right)$ tends to $h_{2}$ as $N \rightarrow \infty(\varepsilon \rightarrow 0)$.
That implies a very simple method for calculations of $h_{2}$. Now we extend this approach to higher $m$.

Suppose we know what optimal $Y=\left\{y_{1}, \ldots, y_{m}\right\} \subset \mathbf{S}^{n-1}$ is up to isometry. Let us assume that $\operatorname{dim} \Delta_{m}=n-1$, and $V:=y_{1} \ldots y_{n-1}$ is a facet of $\Delta_{m}$. Then $\operatorname{rank}\left\{y_{1}, \ldots, y_{n-1}\right\}=n-1$, and $Y$ belongs to the hemisphere $H_{+}$, where $H_{+}$contains $Y$ and bounded by the great sphere $\tilde{S}$ passes through $V$.

Let us show that any $y \in H_{+}$is uniquely determined by the set of distances $\theta_{i}=\operatorname{dist}\left(y, y_{i}\right), \quad i=1, \ldots, n-1$. Indeed, there are at most two solutions: $y_{+} \in H_{+}$and $y_{-} \in H_{-}$of the quadratic equation

$$
\begin{equation*}
y \cdot y=1, \quad \text { where } y \cdot y_{i}=\cos \theta_{i}, i=1, \ldots, n-1 \tag{5.1}
\end{equation*}
$$

Note that $y_{+}=y_{-}$if and only if $y \in \tilde{S}$.
This implies that $\theta_{k}, k \geqslant n$, is determined by $\theta_{i}, i=1, \ldots, n-1$;

$$
\theta_{k}=\Theta_{k}\left(\theta_{1}, \ldots, \theta_{n-1}\right)
$$

It is not hard to solve (5.1) and, therefore, to give an explicit expression for $\Theta_{k}$.
Let $\bar{\xi}=\left(\xi_{1}, \ldots, \xi_{n-1}\right)$, where $0<\xi_{i} \leqslant \theta_{0}<\psi$. (Recall that $\phi_{i, j}=$ $\operatorname{dist}\left(y_{i}, y_{j}\right) ; \cos \psi=z ; \cos \theta_{0}=t_{0}$.) Now we consider a domain $D(\bar{\xi})$ in $H_{+}$, where

$$
D(\bar{\xi})=\left\{y \in H_{+}: \operatorname{dist}\left(y, y_{i}\right) \leqslant \xi_{i}, \quad 1 \leqslant i \leqslant n-1\right\}
$$

In other words, $D(\bar{\xi})$ is the intersection of the spherical caps $C\left(y_{i}, \xi_{i}\right)$ in $H_{+}$:

$$
D(\bar{\xi})=\bigcap_{i=1}^{n-1} C\left(y_{i}, \xi_{i}\right) \bigcap H_{+} .
$$

Suppose $\operatorname{dim} D(\bar{\xi})=n-1$. Then $D(\bar{\xi})$ has "vertices", "edges", and " $k$-faces" for $k \leqslant n-1$. Indeed, let

$$
\begin{aligned}
& \sigma \subset I:=\{1, \ldots, n-1\}, \quad 0<|\sigma| \leqslant n-1 \\
& \tilde{F}_{\sigma}:=\left\{y \in D(\bar{\xi}): \operatorname{dist}\left(y, y_{i}\right)=\xi_{i} \forall i \in \sigma\right\}
\end{aligned}
$$

It is easy to prove that $\operatorname{dim} \tilde{F}_{\sigma}=n-1-|\sigma| ; \tilde{F}_{\sigma}$ belongs to the boundary $B$ of $D(\bar{\xi})$; and if $\sigma \subset \sigma^{\prime}$, then $\tilde{F}_{\sigma^{\prime}} \subset \tilde{F}_{\sigma}$. Actually, $D(\bar{\xi})$ is combinatorially equivalent to an $(n-1)$-dimensional simplex.

Now we consider the minimum of $\Theta_{k}\left(\theta_{1}, \ldots, \theta_{n-1}\right)$ on $D(\bar{\xi})$ for $k \geqslant n$. In other words, we are looking for a point $p_{k}(\bar{\xi}) \in D(\bar{\xi})$ such that

$$
\operatorname{dist}\left(y_{k}, p_{k}(\bar{\xi})\right)=\operatorname{dist}\left(y_{k}, D(\bar{\xi})\right)
$$

Since $\phi_{i, k} \geqslant \psi>\theta_{0}$, all $y_{k}$ lie outside $D(\bar{\xi})$. Clearly, $\Theta_{k}$ achieves its minimum at some point in $B$. Therefore, there is $\sigma \subset I$ such that

$$
\begin{equation*}
p_{k}(\bar{\xi}) \in \tilde{F}_{\sigma} \tag{5.2}
\end{equation*}
$$

Suppose $\sigma=I$, then $\tilde{F}_{\sigma}$ is a vertex of $D(\bar{\xi})$. Let us denote this point by $p_{*}(\bar{\xi})$. Note that the function $\Theta_{k}$ at the point $p_{*}(\bar{\xi})$ is equal to $\Theta_{k}(\bar{\xi})$.

Let $\sigma_{k}(\bar{\xi})$ be $\sigma \subset I$ of maximal size such that $\sigma$ satisfies (5.2). Then for $\sigma_{k}(\bar{\xi})=I, p_{k}(\bar{\xi})=p_{*}(\bar{\xi})$, and for $\left|\sigma_{k}(\bar{\xi})\right|<n-1, p_{k}(\bar{\xi})$ belongs to the open part of $\tilde{F}_{\sigma_{k}(\bar{\xi})}$.

Consider $n=3$. There are two cases for $p_{k}(\bar{\xi})$ (see Fig. 7): $p_{3}(\bar{\xi})=p_{*}(\bar{\xi})=$ $\tilde{F}_{\{1,2\}}, p_{4}(\bar{\xi})$ is the intersection in $H_{+}$of the great circle passes through $y_{1}, y_{4}$, and the circle $\tilde{S}\left(y_{1}, \xi_{1}\right)$ of center $y_{1}$ and radius $\xi_{1}\left(\tilde{F}_{\{1\}} \subset \tilde{S}\left(y_{1}, \xi_{1}\right)\right)$. The same holds for all dimensions.


Fig. 7


Fig. 8

Denote by $S_{\sigma}(k)$ the great $|\sigma|$-dimensional sphere passes through $y_{i}, i \in \sigma$, and $y_{k}$. Let $\tilde{S}\left(y_{i}, \xi_{i}\right)$ be the sphere of center $y_{i}$ and radius $\xi_{i}$; and for $\sigma \subset I$

$$
\tilde{S}_{\sigma}:=\bigcap_{i \in \sigma} \tilde{S}\left(y_{i}, \xi_{i}\right)
$$

Denote by $s(\sigma, k)$ the intersection of $S_{\sigma}(k)$ and $\tilde{S}_{\sigma}$ in $H_{+}$,

$$
s(\sigma, k)=S_{\sigma}(k) \bigcap \tilde{S}_{\sigma} \bigcap H_{+}
$$

Lemma 5. Suppose $D(\bar{\xi}) \neq \emptyset, 0<\xi_{i} \leqslant \theta_{0} \quad$ for all $i$, and $k \geqslant n$. Then (i) $p_{k}(\bar{\xi}) \in s\left(\sigma_{k}(\bar{\xi}), k\right)$,
(ii) if $s(\sigma, k) \neq \emptyset,|\sigma|<n-1$, then $s(\sigma, k)$ consists of the one point $p_{k}(\bar{\xi})$.

Proof. (i) Let $\theta_{k}^{*}:=\Theta_{k}\left(p_{k}(\bar{\xi})\right)=\operatorname{dist}\left(y_{k}, p_{k}(\bar{\xi})\right)$. Since $\Theta_{k}$ achieves its minimum at $p_{k}(\bar{\xi})$, the sphere $\tilde{S}\left(y_{k}, \theta_{k}^{*}\right)$ touches the sphere $\tilde{S}_{\sigma(\bar{\xi})}$ at $p_{k}(\bar{\xi})$. If some sphere touches the intersections of spheres, then the touching point belongs to the great sphere passes through the centers of these spheres. Thus $p_{k}(\bar{\xi}) \in S_{\sigma(\bar{\xi})}(k)$.
(ii) Note that $s(\sigma, k)$ belongs to the intersection in $H_{+}$of the spheres $S\left(y_{i}, \xi_{i}\right)$, $i \in \sigma$, and $S_{\sigma}(k)$. Any intersection of spheres is also a sphere. Since

$$
\operatorname{dim} S_{\sigma}(k)+\operatorname{dim} \tilde{S}_{\sigma}=n-1,
$$

this intersection is empty, or is a 0 -dimensional sphere (i.e. 2-points set). In the last case, one point lies in $H_{+}$, and another one in $H_{-}$. Therefore, $s(\sigma, k)=\emptyset$, or $s(\sigma, k)=\{p\}$. Denote by $\sigma^{\prime}$ the maximal size $\sigma^{\prime} \supset \sigma$ such that $s\left(\sigma^{\prime}, k\right)=\{p\}$. It is not hard to see that $\tilde{S}\left(y_{k}, \operatorname{dist}\left(y_{k}, p\right)\right)$ touches $\tilde{S}_{\sigma^{\prime}}$ at $p$. Thus $p=p_{k}(\bar{\xi})$.

Lemma 5 implies a simple method for calculations of the minimum of $\Theta_{k}$ on $D(\bar{\xi})$. For this we can consider $s(\sigma, k), \sigma \subset I$, and if $s(\sigma, k) \neq \emptyset$, then $s(\sigma, k)=\left\{p_{k}(\bar{\xi})\right\}$, so then $\Theta_{k}$ attains its minimum at this point. In the case when $\Delta_{n}$ is a simplex we can find the minimum by very simple method.

Corollary 5. Suppose $|Y|=n, \bar{\xi}$ satisfies the assumtions of Lemma 5, and $D(\bar{\xi})$ lies inside $\Delta_{n}$. Then

$$
\theta_{n} \geqslant \Theta_{n}\left(\xi_{1}, \ldots, \xi_{n-1}\right) \text { for all } y \in D(\bar{\xi})
$$

Proof. Clearly, $\Delta_{n}$ is a simplex. Since $D(\bar{\xi})$ lies inside $\Delta_{n}$, for $|\sigma|<n-1$ the intersection of $\tilde{S}_{\sigma}$ and $S_{\sigma}(k)$ is empty. Thus $p_{n}(\bar{\xi})=p_{*}(\bar{\xi})$.

For fixed $y_{i} \in \mathbf{S}^{n-1}, i=1, \ldots, m$; the function $H$ depends only on a position $y=-y_{0}=e_{0} \in \mathbf{S}^{n-1}$. Let

$$
H_{m}(y):=f(1)+f\left(-y \cdot y_{1}\right)+\ldots+f\left(-y \cdot y_{m}\right)
$$

i.e. $H_{m}(y)=H(-y ; Y)$. Then

$$
h_{m}=\max _{y}\left\{H_{m}(y)\right\}
$$

subjects to the constraint

$$
\begin{equation*}
y \in T\left(Y, \theta_{0}\right):=\left\{y \in \Delta_{m} \subset \mathbf{S}^{n-1}: y \cdot y_{i} \geqslant t_{0}, i=1, \ldots, m\right\} \tag{5.3}
\end{equation*}
$$

where $y_{i} \cdot y_{j} \leqslant z$ for $i \neq j$, and $1>t_{0}>z \geqslant 0$.
Suppose $\operatorname{dim} \Delta_{m}=n-1$, and $y_{1} \ldots y_{n-1}$ is a facet of $\Delta_{m}$. Then (4.1) yields

$$
H_{m}(y)=F\left(\theta_{1}, \ldots, \theta_{n-1}, \Theta_{n}, \ldots, \Theta_{m}\right)=\tilde{F}_{m}\left(\theta_{1}, \ldots, \theta_{n-1}\right)
$$

where

$$
\begin{aligned}
& \tilde{F}_{m}\left(\theta_{1}, \ldots, \theta_{n-1}\right):=f(1)+\tilde{f}\left(\theta_{1}\right)+\ldots+\tilde{f}\left(\theta_{n-1}\right)+\tilde{f}\left(\Theta_{n}\left(\theta_{1}, \ldots, \theta_{n-1}\right)\right)+\ldots \\
& +\tilde{f}\left(\Theta_{m}\left(\theta_{1}, \ldots, \theta_{n-1}\right)\right), \\
& \qquad \tilde{f}(\theta):= \begin{cases}f(-\cos \theta) & 0 \leqslant \theta \leqslant \theta_{0} \\
-\infty & \theta>\theta_{0}\end{cases}
\end{aligned}
$$

Lemma 6. Suppose $f$ satisfies $(*),|Y|=m, \operatorname{dim} \Delta_{m}=n-1, y_{1} \ldots y_{n-1}$ is a facet of $\Delta_{m}$, $\operatorname{dist}\left(y_{i}, y_{j}\right) \geqslant \psi>\theta_{0} \quad$ for $i \neq j, \quad 0 \leqslant \zeta_{i}<\xi_{i} \leqslant \theta_{0} \quad$ for $i=1, \ldots, n-1 ;$ and $\Theta_{k}(\bar{\xi}) \leqslant \theta_{0}$ for all $k \geqslant n$. If $D(\bar{\xi}) \neq \emptyset$, then

$$
H_{m}(y) \leqslant \Phi_{Y}(\bar{\zeta}, \bar{\xi}) \quad \text { for any } \quad y \in E(\bar{\zeta}, \bar{\xi}):=D(\bar{\xi}) \backslash U(\bar{\zeta})
$$

where

$$
\begin{gathered}
\Phi_{Y}(\bar{\zeta}, \bar{\xi}):=f(1)+\tilde{f}\left(\zeta_{1}\right)+\ldots+\tilde{f}\left(\zeta_{n-1}\right)+\tilde{f}\left(\Theta_{n}\left(p_{n}(\bar{\xi})\right)\right)+\ldots+\tilde{f}\left(\Theta_{m}\left(p_{m}(\bar{\xi})\right)\right) \\
U(\bar{\zeta}):=\bigcup_{i=1}^{n-1} C\left(y_{i}, \zeta_{i}\right)
\end{gathered}
$$

Proof. We have for $1 \leqslant i \leqslant n-1$ and $y \in \underset{\sim}{E}(\bar{\zeta}, \bar{\xi}): \theta_{i} \geqslant \zeta_{i}$ (Fig. 8). By the monotonicity assumption $(*)$ this implies $\tilde{f}\left(\theta_{i}\right) \leqslant \tilde{f}\left(\zeta_{i}\right)$. On the other hand, $y \in D(\bar{\xi})$. Then Lemma 5 yields $\left.\tilde{f}\left(\theta_{k}\right) \leqslant \tilde{f}\left(\Theta_{k}\left(p_{k}(\bar{\xi})\right)\right)\right)$ for $k \geqslant n$.

From Corollary 5 and Lemma 6 follow
Corollary 6. Let $|Y|=n$. Suppose $f, \xi, \zeta$, and $Y$ satisfy the assumptions of Lemma 6 and Corollary 5. Then for any $y \in E(\bar{\zeta}, \bar{\xi})$ :

$$
H_{m}(y) \leqslant f(1)+\tilde{f}\left(\zeta_{1}\right)+\ldots+\tilde{f}\left(\zeta_{n-1}\right)+\tilde{f}\left(\Theta_{n}(\bar{\xi})\right)
$$

Let $K\left(n, \theta_{0}\right):=\left[0, \theta_{0}\right]^{n-1}$, i.e $K\left(n, \theta_{0}\right)$ is an $(n-1)$-dimensional cube of side length $\theta_{0}$. Consider for $K\left(n, \theta_{0}\right)$ the cubic grid $L(N)$ of sidelength $\varepsilon$, where $\varepsilon=\theta_{0} / N$ for given positive integer $N$. Then the grid (tessellation) $L(N)$ consists of $N^{n-1}$ cells, any cell $c \in L(N)$ is an $(n-1)$-dimensional cube of sidelength $\varepsilon$, and for any point $\left(\theta_{1}, \ldots, \theta_{n-1}\right)$ in $c$ we have

$$
\zeta_{i}(c) \leqslant \theta_{i} \leqslant \xi_{i}(c), \quad \xi_{i}(c)=\zeta_{i}(c)+\varepsilon, \quad i=1, \ldots, n-1
$$

Let $\tilde{L}(N)$ be the subset of cells $c$ in $L(N)$ such that $D(\bar{\xi}(c)) \neq \emptyset$. There exists $c \in L(N)$ such that $H_{m}$ attains its maximum on $T\left(Y, \theta_{0}\right)$ at some point in $E(\bar{\zeta}(c), \bar{\xi}(c))$. Therefore, Lemma 6 yields

Lemma 7. Suppose $f$ and $Y$ satisfy the assumptions of Lemma 6, $N$ is a positive integer, and $y \in \Delta_{m}$ is such that $\operatorname{dist}\left(y, y_{i}\right) \leqslant \theta_{0}$ for all $i$. Then

$$
H_{m}(y) \leqslant \max _{c \in \tilde{L}(N)}\left\{\Phi_{Y}(\bar{\zeta}(c), \bar{\xi}(c))\right\}
$$

Now we apply these results for computations of $h_{m}$. Suppose $\Delta_{m}$ is a regular simplex of edge length $\psi$. Since (4.1), $F$ is a symmetric function in the variables $\theta_{1}, \ldots, \theta_{m}$. Then we can consider this problem only on the domain

$$
\Lambda:=\left\{y \in \Delta_{n}: \psi-\theta_{0} \leqslant \theta_{1} \leqslant \theta_{2} \leqslant \ldots \leqslant \theta_{m} \leqslant \theta_{0}\right\} .
$$

Let $L_{\Lambda}(N)$ be the subset of cells $c$ in $\tilde{L}(N)$ such that $c \bigcap \Lambda \neq \emptyset$. If $c \in L_{\Lambda}(N)$ lies inside $\Delta_{m},{ }^{3}$ then we have an explicit expression for $\Phi_{m}(c):=\Phi_{Y}(\bar{\zeta}(c), \bar{\xi}(c))$

[^3](see Corollary 6). For $n=4$, Theorem 5 implies that $\Delta_{m}$ is a regular simplex, where $m=2,3,4$. Thus from Lemma 7 follows
$$
h_{m} \leqslant \lambda_{m}\left(N, \psi, \theta_{0}\right):=\max _{c \in L_{\Lambda}(N)}\left\{\Phi_{m}(c)\right\} .
$$

Now we consider the case $n=4, m=5$. Theorem 5 yields: $\Delta_{5}$ is isometric to $P_{5}(\alpha)$ for some $\alpha \in\left[\psi, \psi^{\prime}:=\arccos (2 z-1)\right]$ (see Fig. 6). Let the vertices $y_{1}, y_{2}, y_{3}$ of $P_{5}(\alpha)$ be fixed. Then the vertices $y_{4}(\alpha), y_{5}(\alpha)$ are uniquely determined by $\alpha$.

Note that for any $y \in D\left(\theta_{0}, \theta_{0}, \theta_{0}\right)$ the distance $\theta_{4}(\alpha):=\operatorname{dist}\left(y, y_{4}(\alpha)\right)$ increases, and $\theta_{5}(\alpha)$ decreases whenever $\alpha$ increases. Let $\alpha_{1}=\psi, \alpha_{2}, \ldots, \alpha_{N}, \alpha_{N+1}=$ $\psi^{\prime}$ be points in $\left[\psi, \psi^{\prime}\right]$ such that $\alpha_{i+1}=\alpha_{i}+\epsilon$, where $\epsilon=\left(\psi^{\prime}-\psi\right) / N$. Then

$$
\theta_{4}\left(\alpha_{i}\right)<\theta_{4}\left(\alpha_{i+1}\right), \quad \theta_{5}\left(\alpha_{i}\right)>\theta_{5}\left(\alpha_{i+1}\right),
$$

so then

$$
\tilde{f}\left(\theta_{4}\left(\alpha_{i}\right)\right)>\tilde{f}\left(\theta_{4}\left(\alpha_{i+1}\right)\right), \quad \tilde{f}\left(\theta_{5}\left(\alpha_{i}\right)\right)<\tilde{f}\left(\theta_{5}\left(\alpha_{i+1}\right)\right)
$$

Combining this with Lemma 7, we get

$$
\begin{gathered}
h_{5} \leqslant \lambda_{5}\left(N, \psi, \theta_{0}\right):=f(1)+\max _{c \in \tilde{L}(N)}\left\{R_{1,2,3}(c)+\max _{1 \leqslant i \leqslant N}\left\{R_{4,5}(c, i)\right\}\right\}, \\
R_{1,2,3}(c)=\tilde{f}\left(\zeta_{1}(c)\right)+\tilde{f}\left(\zeta_{2}(c)\right)+\tilde{f}\left(\zeta_{3}(c)\right), \\
R_{4,5}(c, i)=\tilde{f}\left(\Theta_{4}\left(p_{4}\left(\bar{\xi}(c), \alpha_{i}\right)\right)\right)+\tilde{f}\left(\Theta_{5}\left(p_{5}\left(\bar{\xi}(c), \alpha_{i+1}\right)\right)\right),
\end{gathered}
$$

where $p_{k}(\bar{\xi}, \alpha)=p_{k}(\bar{\xi})$ with $y_{k}=y_{k}(\alpha)$.
Clearly, $\lambda_{m}\left(N+1, \psi, \theta_{0}\right) \leqslant \lambda_{m}\left(N, \psi, \theta_{0}\right)$. It's not hard to show that

$$
h_{m}=\lambda_{m}\left(\psi, \theta_{0}\right):=\lim _{N \rightarrow \infty} \lambda_{m}\left(N, \psi, \theta_{0}\right)
$$

Finally let us consider the case: $n=4, m=6$. In this case, we give an upper bound on $h_{6}$ by separate argument.

Lemma 8. Let $n=4$, $f$ satisfies $(*), \sqrt{z}>t_{0}>z, \theta_{0}^{\prime} \in\left[\arccos \sqrt{z}, \theta_{0}\right]$. Then

$$
h_{6} \leqslant \max \left\{\tilde{f}\left(\theta_{0}^{\prime}\right)+\lambda_{5}\left(\psi, \theta_{0}\right), f(-\sqrt{z})+\lambda_{5}\left(\psi, \theta_{0}^{\prime}\right)\right\}
$$

Proof. Let $Y=\left\{y_{1}, \ldots, y_{6}\right\} \subset C\left(e_{0}, \theta_{0}\right) \subset \mathbf{S}^{3}$, where $Y$ is an optimal $z$-code. We may assume that $\theta_{1} \leqslant \theta_{2} \leqslant \ldots \leqslant \theta_{6}$. Then from Corollary $3(i)$ follows that

$$
\theta_{0} \geqslant \theta_{6} \geqslant \theta_{5} \geqslant \arccos \sqrt{z}
$$

Let us consider two cases: (a) $\theta_{0} \geqslant \theta_{6} \geqslant \theta_{0}^{\prime}$, (b) $\theta_{0}^{\prime} \geqslant \theta_{6} \geqslant \arccos \sqrt{z}$.
(a) We have $h_{6}=H\left(y_{0} ; y_{1}, \ldots, y_{6}\right)=H\left(y_{0} ; y_{1}, \ldots, y_{5}\right)+\tilde{f}\left(\theta_{6}\right)$,

$$
H\left(y_{0} ; y_{1}, \ldots, y_{5}\right) \leqslant h_{5}=\lambda_{5}\left(\psi, \theta_{0}\right), \quad \tilde{f}\left(\theta_{6}\right) \leqslant \tilde{f}\left(\theta_{0}^{\prime}\right)
$$

Then $h_{6} \leqslant \tilde{f}\left(\theta_{0}^{\prime}\right)+\lambda_{5}\left(\psi, \theta_{0}\right)$.
(b) In this case all $\theta_{i} \leqslant \theta_{0}^{\prime}$, i.e. $Y \subset C\left(e_{0}, \theta_{0}^{\prime}\right)$. Since

$$
H\left(y_{0} ; y_{1}, \ldots, y_{5}\right) \leqslant \lambda_{5}\left(\psi, \theta_{0}^{\prime}\right), \quad \tilde{f}\left(\theta_{6}\right) \leqslant f(-\sqrt{z})
$$

it follows that $h_{6} \leqslant f(-\sqrt{z})+\lambda_{5}\left(\psi, \theta_{0}^{\prime}\right)$.
We have proved the following theorem.
Theorem 6. Suppose $n=4$, $f$ satisfies $(*), \sqrt{z}>t_{0}>z>0$, and $N$ is a positive integer. Then
(i) $h_{0}=f(1), \quad h_{1}=f(1)+f(-1)$;
(ii) $h_{m}=\lambda_{m}\left(\psi, \theta_{0}\right) \leqslant \lambda_{m}\left(N, \psi, \theta_{0}\right)$ for $2 \leqslant m \leqslant 5$;
(iii) $h_{6} \leqslant \max \left\{\tilde{f}\left(\theta_{0}^{\prime}\right)+\lambda_{5}\left(\psi, \theta_{0}\right), f(-\sqrt{z})+\lambda_{5}\left(\psi, \theta_{0}^{\prime}\right)\right\} \forall \theta_{0}^{\prime} \in\left[\arccos \sqrt{z}, \theta_{0}\right]$.
$6 \quad k(4)=24$
For $n=4, z=\cos 60^{\circ}=1 / 2$ we apply this extension of Delsarte's method with $f(t)=53.76 t^{9}-107.52 t^{7}+70.56 t^{5}+16.384 t^{4}-9.832 t^{3}-4.128 t^{2}-0.434 t-0.016$


Fig. 9. The graph of the function $f(t)$
The expansion of $f$ in terms of $U_{k}=G_{k}^{(4)}$ is

$$
f=U_{0}+2 U_{1}+6.12 U_{2}+3.484 U_{3}+5.12 U_{4}+1.05 U_{9}
$$

The polynomial $f$ has two roots on $[-1,1]: t_{1}=-t_{0}, t_{0} \approx 0.60794, t_{2}=1 / 2$, $f(t) \leqslant 0$ for $t \in\left[-t_{0}, 1 / 2\right]$, and $f$ is a monotone decreasing function on the interval $\left[-1,-t_{0}\right]$. The last property holds because there are no zeros of the derivative $f^{\prime}(t)$ on $\left[-1,-t_{0}\right]$. Therefore, $f$ satisfies $(*)$ for $z=1 / 2$.

Remark. The polynomial $f$ was found by using the algorithm in Appendix. This algorithm for $n=4, z=1 / 2, d=9, N=2000, t_{0}=0.6058$ gives $E \approx 24.7895$. For the polynomial $f$ the coefficients $c_{k}$ were changed to "better looking" ones with $E \approx 24.8644$.

We have $t_{0}>0.6058$. Then Corollary $3(i i)$ gives $\mu \leqslant 6$. Let us apply Theorem 6 with $\psi=\arccos z=60^{\circ}, \theta_{0}=\arccos t_{0} \approx 52.5588^{\circ}$ for calculations of $h_{m}$. We get

$$
\begin{gathered}
h_{0}=f(1)=18.774, \quad h_{1}=f(1)+f(-1)=24.48 \\
h_{2} \approx 24.8644, \quad h_{3} \approx 24.8345, \quad h_{4} \approx 24.818, \quad h_{5} \approx 24.6856
\end{gathered}
$$

Let $\theta_{0}^{\prime}=50^{\circ}$. We have $\tilde{f}\left(50^{\circ}\right) \approx 0.0906, \arccos \sqrt{z}=45^{\circ}, \tilde{f}\left(45^{\circ}\right) \approx 0.4533$,

$$
\begin{gathered}
\lambda_{5}\left(60^{\circ}, \theta_{0}\right)=h_{5} \approx 24.6856, \quad \lambda_{5}\left(60^{\circ}, 50^{\circ}\right) \approx 23.9181 \\
h_{6} \leqslant \max \left\{\tilde{f}\left(50^{\circ}\right)+h_{5}, \tilde{f}\left(45^{\circ}\right)+\lambda_{5}\left(60^{\circ}, 50^{\circ}\right)\right\} \approx 24.7762<h_{2}
\end{gathered}
$$

Thus $h_{\max }=h_{2}<25$.
Theorem 7. $k(4)=24$
Proof. Let $X$ be a spherical $1 / 2$-code in $\mathbf{S}^{3}$ with $M=k(4)$ points. The polynomial $f$ is such that $c_{0}=1, h_{\max }<25$. Theorem 1 yields: $k(4) \leqslant h_{\max }<25$. Recall that $k(4) \geqslant 24$. Consequently, $k(4)=24$.

## 7 Concluding remarks

This extension of Delsarte's method can be applied to other dimensions and spherical $z$-codes.

The most interesting application is a new proof for the Newton-Gregory problem, $k(3)<13$. In dimension three computations of $h_{m}$ are technically easier than for $n=4$. This proof needs from mathematics just basic calculus and simple spherical geometry (see details in [27]).

Let

$$
f(t)=\frac{2431}{80} t^{9}-\frac{1287}{20} t^{7}+\frac{18333}{400} t^{5}+\frac{343}{40} t^{4}-\frac{83}{10} t^{3}-\frac{213}{100} t^{2}+\frac{t}{10}-\frac{1}{200} .
$$

Then $f$ satisfies $(*), t_{0} \approx 0.5907, \mu(3,1 / 2, f)=4$, and $h_{\max }=h_{1}=12.88$. The expansion of $f$ in terms of Legendre polynomials $P_{k}=G_{k}^{(3)}$ is

$$
f=P_{0}+1.6 P_{1}+3.48 P_{2}+1.65 P_{3}+1.96 P_{4}+0.1 P_{5}+0.32 P_{9}
$$

Since $c_{0}=1, c_{i} \geqslant 0, k(3) \leqslant h_{\max }=12.88<13$.

Direct application of the method developed in this paper, presumably could lead to some improvements in the upper bounds on kissing numbers in dimensions $9,10,16,17,18$ given in [10, Table 1.5]. ("Presumably" because the equality $h_{\max }=E$ is not proven yet.)

In 9 and 10 dimensions Table 1.5 gives: $306 \leqslant k(9) \leqslant 380, \quad 500 \leqslant k(10) \leqslant 595$.
The algorithm gives:
$n=9: \operatorname{deg} f=11, E=h_{1}=366.7822, t_{0}=0.54$;
$n=10: \operatorname{deg} f=11, E=h_{1}=570.5240, t_{0}=0.586$.
For these dimensions there is a good chance to prove that $k(9) \leqslant 366, k(10) \leqslant 570$.

From the equality $k(3)=12$ follows $\varphi_{3}(13)<60^{\circ}$. The method gives $\varphi_{3}(13)<59.4^{\circ}(\operatorname{deg} f=11)$. The lower bound on $\varphi_{3}(13)$ is $57.1367^{\circ}$ [17]. Therefore, we have $57.1367^{\circ} \leqslant \varphi_{3}(13)<59.4^{\circ}$.

Using our approach it can be proven that $\varphi_{4}(25)<59.81^{\circ}, \varphi_{4}(24)<60.5^{\circ}$. That improve the bounds:

$$
\begin{gathered}
\left.\varphi_{4}(25)<60.79^{\circ}, \quad \varphi_{4}(24)<61.65^{\circ} \text { [24] (cf. [5] }\right) ; \varphi_{4}(24)<61.47^{\circ} \text { [5]; } \\
\varphi_{4}(25)<60.5^{\circ}, \quad \varphi_{4}(24)<61.41^{\circ} \text { [4]. }
\end{gathered}
$$

Now in these cases we have

$$
57.4988^{\circ}<\varphi_{4}(25)<59.81^{\circ}, \quad 60^{\circ} \leqslant \varphi_{4}(24)<60.5^{\circ}
$$

However, for $n=5,6,7$ direct use of this extension of the Delsarte method doesn't give better upper bounds on $k(n)$ than the Delsarte method. It is an interesting problem to find better methods.

## Appendix. An algorithm for computation suitable polynomials $f(t)$

In this Appendix is presented an algorithm for computation "optimal" 4 polynomials $f$ such that $f(t)$ is a monotone decreasing function on the interval $\left[-1,-t_{0}\right]$, and $f(t) \leqslant 0$ for $t \in\left[-t_{0}, z\right], \quad t_{0}>z \geqslant 0$. This algorithm based on our knowledge about optimal arrangement of points $y_{i}$ for given $m$. Coefficients $c_{k}$ can be found via discretization and linear programming; such method had been employed already by Odlyzko and Sloane [28] for the same purpose.

Let us have a polynomial $f$ represented in the form $f(t)=1+\sum_{k=1}^{d} c_{k} G_{k}^{(n)}(t)$. We have the following constraints for $f$ : ( C 1$) c_{k} \geqslant 0,1 \leqslant k \leqslant d$; (C2) $f(a)>f(b)$ for $-1 \leqslant a<b \leqslant-t_{0}$; (C3) $f(t) \leqslant 0$ for $-t_{0} \leqslant t \leqslant z$.

We do not know $e_{0}$ where $H_{m}$ attains its maximum, so for evaluation of $h_{m}$ let us use $e_{0}=y_{c}$, where $y_{c}$ is the center of $\Delta_{m}$. All vertices $y_{k}$ of $\Delta_{m}$ are at the distance of $\rho_{m}$ from $y_{c}$, where

$$
\cos \rho_{m}=\sqrt{(1+(m-1) z) / m}
$$

[^4]When $m=2 n-2, \Delta_{m}$ presumably is a regular $(n-1)$-dimensional crosspolytope. ${ }^{5}$ In this case $\cos \rho_{m}=\sqrt{z}$.

Let $I_{n}=\{1, \ldots, n\} \bigcup\{2 n-2\}, \quad m \in I_{n}, \quad b_{m}=-\cos \rho_{m}$, then $H_{m}\left(y_{c}\right)=f(1)+m f\left(b_{m}\right)$. If $F_{0}$ is such that $H\left(y_{0} ; Y\right) \leqslant E=F_{0}+f(1)$, then (C4) $f\left(b_{m}\right) \leqslant F_{0} / m, \quad m \in I_{n}$. Note that $E=F_{0}+1+c_{1}+\ldots+c_{d}=F_{0}+f(1)$ is a lower estimate of $h_{\text {max }}$. A polynomial $f$ that satisfies (C1-C4) and gives the minimal $E$ can be found by the following

## Algorithm.

Input: $n, z, t_{0}, d, N$.
Output: $c_{1}, \ldots, c_{d}, F_{0}, E$.
First replace (C2) and (C3) by a finite set of inequalities at the points $a_{j}=-1+\epsilon j, \quad 0 \leqslant j \leqslant N, \quad \epsilon=(1+z) / N:$

Second use linear programming to find $F_{0}, c_{1}, \ldots, c_{d}$ so as to minimize $E-1=F_{0}+\sum_{k=1}^{d} c_{k} \quad$ subject to the constraints
$c_{k} \geqslant 0, \quad 1 \leqslant k \leqslant d ; \quad \sum_{k=1}^{d} c_{k} G_{k}^{(n)}\left(a_{j}\right) \geqslant \sum_{k=1}^{d} c_{k} G_{k}^{(n)}\left(a_{j+1}\right), \quad a_{j} \in\left[-1,-t_{0}\right] ;$
$1+\sum_{k=1}^{d} c_{k} G_{k}^{(n)}\left(a_{j}\right) \leqslant 0, \quad a_{j} \in\left[-t_{0}, z\right] ; \quad 1+\sum_{k=1}^{d} c_{k} G_{k}^{(n)}\left(b_{m}\right) \leqslant F_{0} / m, \quad m \in I_{n}$.
Let us note again that $E \leqslant h_{\max }$, and $E=h_{\max }$ only if $h_{\max }=H_{m_{0}}\left(y_{c}\right)$ for some $m_{0} \in I_{n}$.

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[^0]:    *Institute for Mathematical Study of Complex Systems, Moscow State University, Russia omusin@gmail.com

[^1]:    ${ }^{1}$ See also Pfender \& Ziegler [29] for a beautiful exposition.

[^2]:    ${ }^{2}$ In the first version of this paper for $m \geqslant n$ has been claimed that any vertex of $\Gamma_{\psi}(Y)$ has degree at least $n-1$. However, E. Bannai, M. Tagami, and referees of this paper found some gaps in our exposition. Most of them are related to "degenerated" configurations. In this paper we need only the case $n=4, m<6$. For this case E. Bannai and M. Tagami verified each step of our proof, considered all "degenerated" configurations, and finally gave clean and detailed proof (see E. Bannai and M. Tagami: On optimal sets in Musin's paper "The kissing number in four dimensions" in the Proceedings of the COE Workshop on Sphere Packings, November 1-5, 2004, in Fukuoka Japan). I wish to thank Eiichi Bannai, Makoto Tagami, and anonymous referees for helpful and useful comments. Now this claim in general case can be considered only as conjecture.

[^3]:    ${ }^{3}$ Clearly, it holds for all $c \in L_{\Lambda}(N)$ if $N$ is sufficiently large.

[^4]:    ${ }^{4}$ Open problem: is it true that for given $t_{0}, d$ this algorithm defines $f$ with minimal $h_{\max }$ ?

[^5]:    ${ }^{5}$ It is also an open problem.

