



ERRATUM

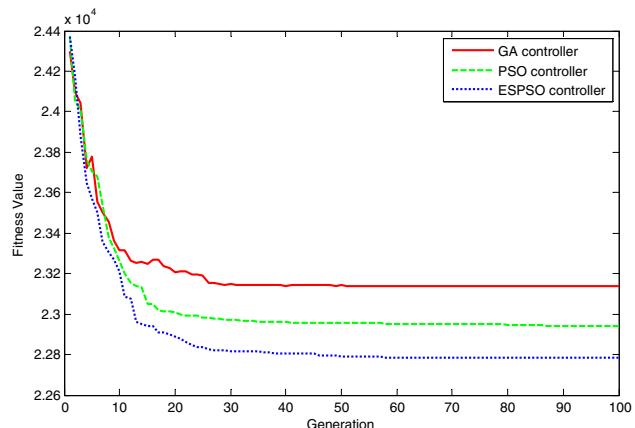
## Erratum to: Optimal Fuzzy Controller Design Using an Evolutionary Strategy-Based Particle Swarm Optimization for Redundant Wheeled Robots

Hsu-Chih Huang<sup>1</sup> · Sendren Sheng-Dong Xu<sup>2</sup> · Chih-Hao Chiang<sup>1</sup>

Published online: 14 May 2016  
© Taiwan Fuzzy Systems Association and Springer-Verlag Berlin Heidelberg 2016

### Erratum to: Int.J.Fuzzy Syst. (2015) 17(3):390–398 DOI 10.1007/s40815-015-0055-y

In the original publication of this article Fig. 4 is incorrectly published. This error in no way affects the conclusions of the study. The correct figure is provided in this erratum.



**Fig. 4** The evolutions of the FC-ESPSO and conventional controllers to achieve elliptic trajectory tracking

The online version of the original article can be found under doi:[10.1007/s40815-015-0055-y](https://doi.org/10.1007/s40815-015-0055-y).

✉ Hsu-Chih Huang  
hchuang@niu.edu.tw  
Sendren Sheng-Dong Xu  
sdxu@mail.ntust.edu.tw

<sup>1</sup> Department of Electrical Engineering, National Ilan University, Yilan, Taiwan

<sup>2</sup> Graduate Institute of Automation and Control, National Taiwan University of Science and Technology, Taipei, Taiwan