

The four-in-a-tree problem in triangle-free graphs

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Abstract

The three-in-a-tree algorithm of Chudnovsky and Seymour decides in time $O(n^4)$ whether three given vertices of a graph belong to an induced tree. Here, we study four-in-a-tree for triangle-free graphs. We give a structural answer to the following question: what does a triangle-free graph look like if no induced tree covers four given vertices? Our main result says that any such graph must have the “same structure”, in a sense to be defined precisely, as a square or a cube.

We provide an $O(nm)$ -time algorithm that given a triangle-free graph G together with four vertices outputs either an induced tree that contains them or a partition of $V(G)$ certifying that no such tree exists. We prove that the problem of deciding whether there exists a tree T covering the four vertices such that at most one vertex of T has degree at least 3 is NP-complete.

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Key words: tree, algorithm, three-in-a-tree, four-in-a-tree, triangle-free graphs, induced subgraph.

1 Introduction

Many interesting classes of graphs are defined by forbidding induced subgraphs, see [2] for a survey. This is why the detection of several kinds of induced subgraphs is interesting, see [6] for a survey. In particular, the problem of deciding whether a graph G contains as an induced subgraph some graph obtained after possibly subdividing prescribed edges of a prescribed graph H has been studied. It turned out that this problem can be polynomial or NP-complete according to H and to the set of edges that can be subdivided. Details, examples and open problems are given in [6]. The most general tool for solving this kind of problems (when they are polynomial) seems to be the *three-in-a-tree* algorithm of Chudnovsky and Seymour:

Theorem 1.1 (see [3]) *Let G be a connected graph and x_1, x_2, x_3 be three distinct vertices of G . Then deciding if there exists an induced tree of G that contains x_1, x_2, x_3 can be done in time $O(n^4)$.*

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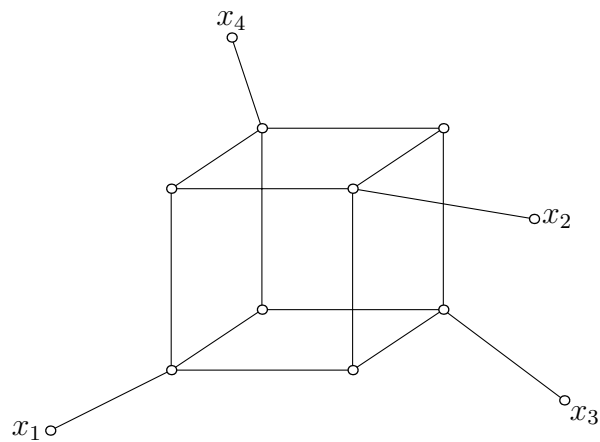


Figure 1: no tree covers x_1, x_2, x_3, x_4 , first example

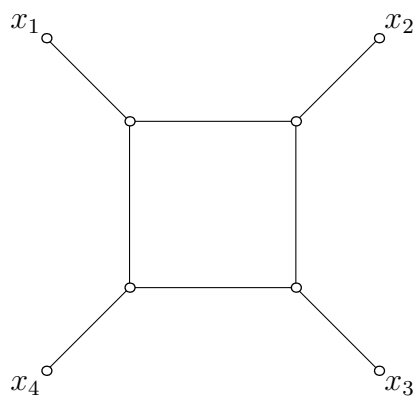


Figure 2: no tree covers x_1, x_2, x_3, x_4 , second example

How to use three-in-a-tree is discussed in [3] and further evidences of its generality are given in [6]. Because of the power and deepness of three-in-a-tree, it would be interesting to generalise it. Here we study *four-in-a-tree*: the problem whose instance is a graph G together with four of its vertices, and whose question is “Does G contain an induced tree covering the four vertices?”. Since this problem seems complicated to us, we restrict ourselves to triangle-free graphs. Our approach is similar to that of Chudnovsky and Seymour for three-in-a-tree. We give a structural answer to the following question: what does a triangle-free graph look like if no induced tree covers four given vertices x_1, x_2, x_3, x_4 ? On Fig. 1 and 2, two examples of such graphs are represented. Our main result, Theorem 2.3, says that any triangle-free graph that does not contain a tree covering four vertices x_1, x_2, x_3, x_4 must have the “same structure”, in a sense to be defined later, as one of the two examples. The details of the statement are given in Section 2.

Our result is algorithmic: we provide an $O(nm)$ -time algorithm that given a graph G together with four vertices x_1, x_2, x_3, x_4 outputs either an induced tree that contains x_1, x_2, x_3, x_4 or a partition of $V(G)$ certifying that no such tree exists. Note that apart from very basic subroutines such as Breadth First Search, our algorithm is self-contained. In particular it does not rely on three-in-a-tree. Our proofs will use the following result of Derhy and Picouleau:

Theorem 1.2 (see [4]) *Let G be a triangle-free connected graph and x_1, x_2, x_3 be three distinct vertices of G . Then there is an induced tree of G that contains x_1, x_2, x_3 . Moreover such a tree of minimum size can be done in time $O(m)$.*

Another generalisation of three-in-a-tree would be interesting. Let us call *centered tree* any tree that contains at most one vertex of degree greater than two. Note that any minimal tree covering three vertices of a graph is centered. Hence, three-in-a-tree and three-in-a-centered-tree are in fact the same problem. So four-in-a-centered-tree is also an interesting generalisation of three-in-a-tree. But we will prove in Section 5 that it is NP-complete, even when restricted to several classes of graphs, including triangle-free graphs.

We leave open the following problems: four-in-a-tree for general graphs, k -in-a-tree for triangle-free graphs.

Notation

All our graphs are simple and finite. We say that a graph G *contains* a graph H if G contains an induced subgraph isomorphic to H . We say that G is H -free if it does not contain H . If $Z \subseteq V(G)$ then $G[Z]$ denotes the subgraph of G induced by Z . When we describe the complexity of an algorithm whose input is a graph, n stands for the number of its vertices and m stands for the number of its edges.

We call *path* any connected graph with at least one vertex of degree 1 and no vertex of degree greater than 2. A path has at most two vertices of degree 1, which are the *ends* of the path. If a, b are the ends of a path P we say that P is *from a to b* . The other vertices are the *interior* vertices of the path. We denote by $v_1 - \dots - v_n$ the path whose edge set is $\{v_1v_2, \dots, v_{n-1}v_n\}$. When P is a path, we say that P is *a path of G* if P is an induced subgraph of G . If P is a path and if a, b are two vertices of P then we denote by $a - P - b$ the only induced subgraph of P that is path from a to b .

Note that by *path of a graph*, we mean induced path. Also, by *tree of a graph*, we mean an induced subgraph that is a tree.

The *union* of two graphs $G = (V, E)$ and $G' = (V', E')$ is the graph $G \cup G' = (V \cup V', E \cup E')$. A set $X \subseteq V(G)$ is *complete* to a set $Y \subseteq V(G)$ if there are all possible edges between X and Y . A set $X \subseteq V(G)$ is *anticomplete* to a set $Y \subseteq V(G)$ if there are no edges between X and Y .

When G is a graph and v a vertex, $N(v)$ denotes the set of all the neighbors of v . If $A \subseteq V(G)$ then $N(A)$ denotes the set of these vertices of G that are not in A but that have neighbors in A . If $Z \subseteq V(G)$, then $N_Z(A)$ denotes $N(A) \cap Z$. If H is an induced subgraph of G , then we write $N_H(A)$ instead of $N_{V(H)}(A)$.

When we define k sets A_1, \dots, A_k , we usually denote their union by A . We use this with no explicit mention : if we define sets S_1, \dots, S_8 then S will denote their union, and so on.

2 Main results

A *terminal* of a graph is a vertex of degree one. Given a graph G and vertices y_1, \dots, y_k , let us consider the graph G' obtained from G by adding for each y_i a new terminal x_i adjacent to y_i . It is easily seen that there exists an induced tree of G covering y_1, \dots, y_k if and only if there exists an induced tree of G' covering x_1, \dots, x_k . So, four-terminals-in-a-tree and four-in-a-tree are essentially the same problems, from an algorithmic point of view and from a structural point of view. Hence, for convenience, we may restrict ourselves to the problem four-in-a-tree where the four vertices to be covered are terminals.

As mentioned in the introduction, our main result states that a graph that does not contain a tree covering four given terminals x_1, x_2, x_3, x_4 must have the “same structure” as one of the graphs represented on Fig. 1 or 2. Let us now define this precisely.

A graph that has the same structure as the graph represented on Fig 1 is what we call a *cubic structure*: a graph G is said to be a *cubic structure* with respect to a 4-tuple of distinct terminals (x_1, x_2, x_3, x_4) if there exist sets A_1, \dots, A_4 , B_1, \dots, B_4 , S_1, \dots, S_8 and R such that:

1. $A \cup B \cup S \cup R = V(G)$;
2. $A_1, \dots, A_4, B_1, \dots, B_4, S_1, \dots, S_8, R$ are pairwise disjoint;
3. $x_i \in A_i$, $i = 1, \dots, 4$;
4. S_i is a stable set, $i = 1, \dots, 8$;
5. S_i is non-empty, $i = 1, \dots, 4$;
6. at most one of S_5, S_6, S_7, S_8 is empty;
7. S_i is complete to $(S_5 \cup S_6 \cup S_7 \cup S_8) \setminus S_{i+4}$, $i = 1, 2, 3, 4$;
8. S_i is anticomplete to S_{i+4} , $i = 1, 2, 3, 4$;
9. S_i is anticomplete to S_j , $1 \leq i < j \leq 4$;
10. S_i is anticomplete to S_j , $5 \leq i < j \leq 8$;

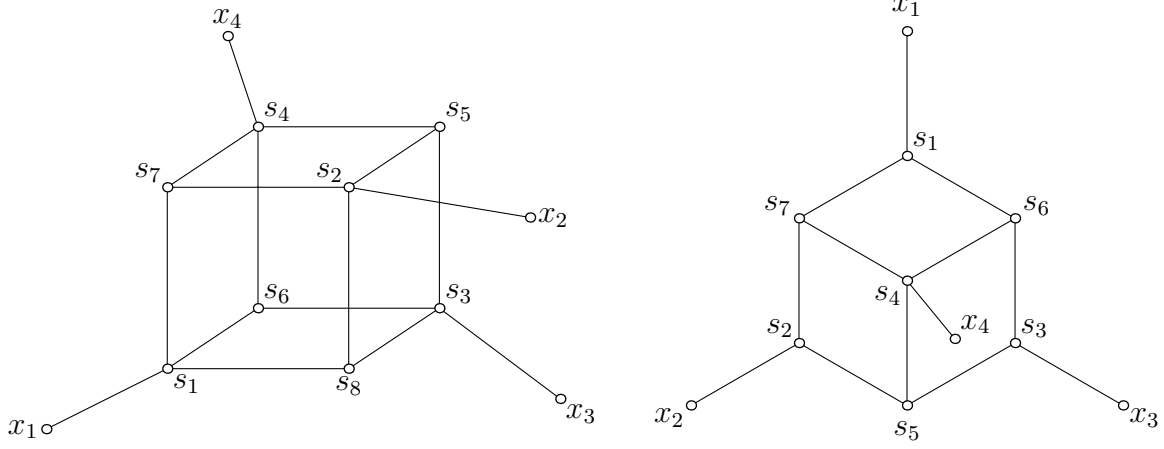


Figure 3: Two examples of cubic structure

11. $N(A_i) = S_i$, $i = 1, 2, 3, 4$;
12. $N(B_i) \subseteq S_i \cup N_S(S_i)$, $i = 1, 2, 3, 4$;
13. $N(R) \subseteq S_5 \cup S_6 \cup S_7 \cup S_8$;
14. $G[A_i]$ is connected, $i = 1, 2, 3, 4$.

A 17-tuple $(A_1, \dots, A_4, B_1, \dots, B_4, S_1, \dots, S_8, R)$ of sets like in the definition above is a *split* of the cubic structure. On Fig. 3, two cubic structures are represented. A *cubic structure of a graph G* is a subset Z of $V(G)$ such that $G[Z]$ is a cubic structure. The following lemma, to be proved in Section 4, shows that if a cubic structure is discovered in a triangle-free graph, then one can repeatedly add vertices to it, unless at some step a tree covering x_1, x_2, x_3, x_4 is found:

Lemma 2.1 *There is an algorithm with the following specification:*

INPUT: a triangle-free graph G , four terminals x_1, x_2, x_3, x_4 , a split of a cubic structure Z of G , and a vertex $v \notin Z$.

OUTPUT: a tree of $G[Z \cup \{v\}]$ that covers x_1, x_2, x_3, x_4 or a split of the cubic structure $G[Z \cup \{v\}]$.

COMPLEXITY: $O(m)$.

Let us now turn our attention to our second kind of structure. A graph that has the same structure as the graph represented on Fig 2 is what we call a square structure: a graph G is said to be a *square structure* with respect to a 4-tuple (x_1, x_2, x_3, x_4) of distinct terminals if there are sets $A_1, A_2, A_3, A_4, S_1, S_2, S_3, S_4, R$ such that:

1. $A \cup S \cup R = V(G)$;

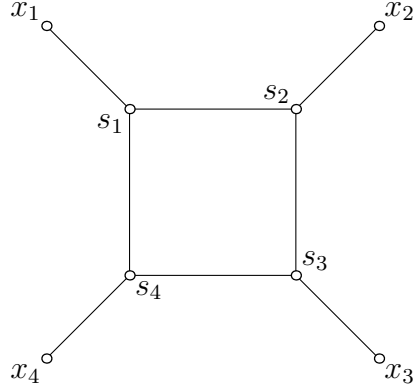


Figure 4: The smallest square structure

2. $A_1, A_2, A_3, A_4, S_1, S_2, S_3, S_4, R$ are pairwise disjoint;
3. $x_i \in A_i, i = 1, \dots, 4$;
4. S_i is a stable set, $i = 1, \dots, 4$;
5. $S_1, S_2, S_3, S_4 \neq \emptyset$;
6. S_i is complete to S_{i+1} , where the addition of subscripts is taken modulo 4, $i = 1, 2, 3, 4$;
7. S_i is anticomplete to S_{i+2} , $i = 1, 2$;
8. $N(A_i) = S_i$, $i = 1, 2, 3, 4$;
9. $N(R) \subseteq S_1 \cup S_2 \cup S_3 \cup S_4$;
10. $G[A_i]$ is connected, $i = 1, \dots, 4$.

A 9-tuple $(A_1, \dots, A_4, S_1, \dots, S_4, R)$ of sets like in the definition above is a *split* of the square structure. On Fig. 4, the smallest square structure is represented. A *square structure* of a graph G is a subset Z of $V(G)$ such that $G[Z]$ is a square structure. The following lemma, to be proved in Section 3, shows that if a square structure is discovered in a triangle-free graph, then one can repeatedly add vertices to it, unless at some step a cubic structure or a tree covering x_1, x_2, x_3, x_4 is found:

Lemma 2.2 *There is an algorithm with the following specification:*

INPUT: a triangle-free graph G , four terminals x_1, x_2, x_3, x_4 , a split of a square structure Z of G , and a vertex $v \notin Z$.

OUTPUT: a tree of $G[Z \cup \{v\}]$ that covers x_1, x_2, x_3, x_4 or a split of some cubic structure of G or a split of the square structure $G[Z \cup \{v\}]$.

COMPLEXITY: $O(m)$.

From the two lemmas above the main theorem follows:

Theorem 2.3 *Let G be a connected graph and x_1, x_2, x_3, x_4 be four distinct terminals of G . Then either:*

- (1) G is a cubic or a square structure with respect to (x_1, x_2, x_3, x_4) ;
- (2) G contains a tree that covers x_1, x_2, x_3, x_4 .

Moreover, exactly one of these two statements (1) and (2) holds. This result is algorithmic in the sense that there exists an $O(nm)$ -time algorithm whose input is a graph and four terminals x_1, x_2, x_3, x_4 and whose output is either a partition of $V(G)$ showing that G is a cubic or a square structure with respect to (x_1, x_2, x_3, x_4) , or a tree that covers x_1, x_2, x_3, x_4 .

PROOF — Let us first check that at most one of (1), (2) holds. This means that a square or cubic structure with respect to a 4-tuple (x_1, x_2, x_3, x_4) of terminals cannot contain a tree covering x_1, x_2, x_3, x_4 . For suppose that such a tree T exists in a square structure G with a split $(A_1, \dots, A_4, S_1, \dots, S_4, R)$. By the definition of square structures T must contain a vertex in every S_i , $i = 1, 2, 3, 4$. So, T contains a square, a contradiction.

Suppose now that such a tree T exists in a cubic structure G with a split $(A_1, \dots, A_4, B_1, \dots, B_4, S_1, \dots, S_8, R)$. By the definition of cubic structures T must contain a vertex in every S_i , $i = 1, 2, 3, 4$. Since T contains no cycle, T has vertices in at most one of S_5, S_6, S_7, S_8 , say in S_5 up to symmetry. So, T contains no vertex of $S_6 \cup S_7 \cup S_8$. So x_1, x_2 lie in two different components of T , a contradiction.

The fact that at least one of (1), (2) holds follows directly from the algorithm announced in the theorem. A description of this algorithm will complete the proof. So let us suppose that G and four terminals x_1, x_2, x_3, x_4 are given. The algorithm goes through three steps:

First step: by Theorem 1.2 we find in time $O(m)$ a minimal tree T that covers x_1, x_2, x_3 . Note that since x_1, x_2, x_3 are of degree one, T contains a vertex c of degree 3 and is the union of three paths $P_1 = c - \dots - x_1$, $P_2 = c - \dots - x_2$, $P_3 = c - \dots - x_3$.

Then we use BFS (short name for Breadth First Search, see [5]) to find a path $Q = x_4 - \dots - w$ such that w has neighbors in T , and minimal with respect to this property. If w has a neighbor in P_i then we let u_i be the neighbor of w closest to x_i along P_i .

If w has neighbors in P_1, P_2, P_3 then note that when $1 \leq i < j \leq 3$, $u_i u_j \notin E(G)$ because else, G contains a triangle. So $V(Q \cup (u_1 - P_1 - x_1) \cup (u_2 - P_2 - x_2) \cup (u_3 - P_3 - x_3))$ induces a tree that covers x_1, x_2, x_3, x_4 , so we stop the algorithm and output this tree. Note that from here on, $w \notin E(G)$.

If w has neighbors in exactly one of P_1, P_2, P_3 , say in P_1 up to symmetry, then we compute by Theorem 1.2 a tree T' of $G[P_1 \cup \{w\}]$ that minimally covers w, c, x_1 . We see that $V(Q \cup T' \cup P_2 \cup P_3)$ induces a tree that covers x_1, x_2, x_3, x_4 , so we stop the algorithm and output this tree.

So, we are left with the case where w has neighbors in two paths among P_1, P_2, P_3 , say in P_1, P_3 up to symmetry. Then there are two cases. First case: one of $u_1 c, u_3 c$ is not in $E(G)$. Up to symmetry we suppose $u_1 c \notin E(G)$. We compute by Theorem 1.2 a tree T'' of $G[P_3 \cup \{w\}]$ that minimally covers w, c, x_3 . We see that $V(Q \cup (x_1 - P_1 - u_1) \cup T'' \cup P_2)$ induces a tree that covers x_1, x_2, x_3, x_4 , so we stop the algorithm and output this tree. Second case:

u_1c, u_3c are both in $E(G)$. Then we observe that $V(P_1 \cup P_2 \cup P_3 \cup Q)$ is a square structure of G . A split can be done by putting $A_1 = V(x_1 - P_1 - u_1) \setminus \{u_1\}$, $A_2 = V(P_2) \setminus \{c\}$, $A_3 = V(x_3 - P_3 - u_3) \setminus \{u_3\}$; $A_4 = V(Q) \setminus \{w\}$, $S_1 = \{u_1\}$, $S_2 = \{c\}$, $S_3 = \{u_3\}$, $S_4 = \{w\}$ and $R = \emptyset$. We keep this square structure Z and go the next step.

Second step: while there exists a vertex v not in Z , we use the algorithm of Lemma 2.2 to add v to Z , keeping a square structure. If we manage to put every vertex of G in Z then we have found that G is a square structure that we output. Else, Lemma 2.2 says that at some step we have found either a tree covering x_1, x_2, x_3, x_4 that we output, or a cubic structure Z' , together with a split for it. In this last case, we go to the next step.

Third step: while there exists a vertex v not in Z' , we use the algorithm of Lemma 2.1 to add v to Z' , keeping a cubic structure. If we manage to put every vertex of G in Z' then we have found that G is a cubic structure that we output. Else, Lemma 2.1 says that at some step we have found a tree covering x_1, x_2, x_3, x_4 that we output.

Complexity analysis: we run at most $O(n)$ times $O(m)$ algorithms. So the overall complexity is $O(nm)$. \square

3 Proof of Lemma 2.2

Let $Z \subseteq V(G)$ be a square structure of G with respect to x_1, x_2, x_3, x_4 together with a split like in the definition and let v be in $V(G) \setminus Z$. Note that Z , the split of Z and v are given by assumption.

Here below, we give a proof of the existence of the objects that the algorithm of our Lemma must output, namely a tree, a cubic structure or an augmented square structure. But this proof is in fact the description of an $O(m)$ -time algorithm. To see this, it suffices to notice that all the proof relies on a several run of BFS or of the algorithm of Theorem 1.2, and on checks of neighborhoods of several vertices. At the end, we give more information on how to transform our proof into an algorithm.

When $s_i \in S_i \cup A_i$, we define the path P_{s_i} to be a path from s_i to x_i , whose interior is in A_i , $i = 1, 2, 3, 4$. Note that P_{s_i} exists since by Item 10 of the definition of square structures, $G[A_i]$ is connected and by Item 8 every vertex of S_i has a neighbor in A_i , $i = 1, 2, 3, 4$.

If v has no neighbor in A then v can be put in R and we obtain a split of the square structure $Z \cup \{v\}$. So we may assume that v has a neighbor in A , say $a_1 \in A_1$. We choose a_1 subject to the minimality of P_{a_1} .

Claim 3.1 *Suppose that there exists a path $Q = v - \dots - w$ where $Q \setminus v \subseteq R$ and such that w has neighbors in $(A \setminus A_1) \cup (S \setminus S_1)$. Suppose Q minimal with respect to these properties. Then either:*

1. *there exists a tree of $G[Z \cup \{v\}]$ that covers x_1, x_2, x_3, x_4 ;*
2. *$N_S(w) = S_2 \cup S_4$ and $N_A(w) \subseteq A_1$;*
3. *$G[Z \cup \{v\}]$ contains a cubic structure.*

PROOF — Note that possibly $Q = v = w$. Note also that by the definition of R , w have neighbors in A only when $w = v$.

(1) If w has a neighbor in $A_2 \cup A_4$ there exists a tree that covers x_1, x_2, x_3, x_4 .

Up to symmetry w has a neighbor $a_2 \in A_2$. We choose a_2 subject to the minimality of P_{a_2} . Note that here $Q = v = w$.

If v has also a neighbor $a_3 \in S_3 \cup A_3$ and a neighbor $a_4 \in S_4 \cup A_4$ (note that G being triangle-free $a_3 \in S_3$ and $a_4 \in S_4$ cannot happen) then we choose a_3, a_4 subject to the minimality of respectively P_{a_3}, P_{a_4} . So, $V(P_{a_1} \cup Q \cup P_{a_2} \cup P_{a_3} \cup P_{a_4})$ induces a tree that covers x_1, x_2, x_3, x_4 . Hence we may assume that v has no neighbor in $S_4 \cup A_4$.

If v has a neighbor $a_3 \in S_3 \cup A_3$ then we pick $s_3 \in S_3$ (if $a_3 \in S_3$, we choose $s_3 = a_3$). We let T_3 be a tree of $G[A_3 \cup \{v, s_3\}]$ that covers v, s_3, x_3 . Note that T_3 exists by Theorem 1.2 because $G[A_3 \cup \{v, s_3\}]$ is connected. So, $V(P_{a_1} \cup Q \cup P_{a_2} \cup T_3 \cup P_{s_4})$ where $s_4 \in S_4$ induces a tree that covers x_1, x_2, x_3, x_4 . Hence we may assume that v has no neighbor in $S_3 \cup A_3$.

Now, we pick $s_1 \in S_1$ and we let T_1 be a tree of $G[A_1 \cup \{v, s_1\}]$ that covers v, s_1, x_1 . Note that T_1 exists by Theorem 1.2 because $G[A_1 \cup \{v, s_1\}]$ is connected. So, $V(T_1 \cup P_{a_2} \cup P_{s_3} \cup P_{s_4})$ where $s_3 \in S_3, s_4 \in S_4$ induces a tree that covers x_1, x_2, x_3, x_4 . This proves (1).

So, we may assume that w has no neighbor in $A_2 \cup A_4$.

(2) If w has a neighbor in S_3 there exists a tree that covers x_1, x_2, x_3, x_4 .

Let s_3 be a neighbor of w in S_3 . Note that G being triangle-free, w has no neighbor in $S_2 \cup S_4$. We let T_3 be a tree of $G[A_3 \cup \{w, s_3\}]$ that covers w, s_3, x_3 . Note that in fact T_3 is a path either from s_3 to x_3 or from w to x_3 . So, $V(P_{a_1} \cup Q \cup P_{s_2} \cup T_3 \cup P_{s_4})$ where $s_2 \in S_2, s_4 \in S_4$ induces a tree that covers x_1, x_2, x_3, x_4 . This proves (2).

So, we may assume that w has no neighbor in S_3 .

(3) If w has no neighbor in $S_2 \cup S_4$ there exists a tree that covers x_1, x_2, x_3, x_4 .

If w has no neighbor in $S_2 \cup S_4$, by the definition of Q , w must have a neighbor $a_3 \in A_3$.

We pick $s_3 \in S_3$. We let T_3 be a tree of $G[A_3 \cup \{w, s_3\}]$ that covers w, s_3, x_3 . So, $V(P_{a_1} \cup Q \cup P_{s_2} \cup T_3 \cup P_{s_4})$ where $s_2 \in S_2, s_4 \in S_4$ induces a tree that covers x_1, x_2, x_3, x_4 . This proves (3).

So, we may assume that w has a neighbor in $S_2 \cup S_4$ (say $s_2 \in S_2$ up to symmetry).

(4) If w has no neighbor in A_3 then either there exists a tree that covers x_1, x_2, x_3, x_4 or $N_S(w) = S_2 \cup S_4$ and $N_A(w) \subseteq A_1$.

If $s_4 \in S_4$ is a non-neighbor of w , then $V(P_{a_1} \cup Q \cup P_{s_2} \cup P_{s_3} \cup P_{s_4})$, where $s_3 \in S_3$ is a tree that covers x_1, x_2, x_3, x_4 . So, we may assume that w is complete to S_4 . By the same way we may also assume that w is complete to S_2 . Hence $N_S(w) = S_2 \cup S_4$ and $N_A(w) \subseteq A_1$. This proves (4).

Note that if $N_S(w) = S_2 \cup S_4$ and $N_A(w) \subseteq A_1$ then the second output of our Claim 3.1 holds. So, from the definition of Q we may assume that w has a neighbor a_3 in A_3 . This implies $v = w$. We choose a_3 subject to the minimality of P_{a_3} .

(5) If v has a neighbor in S_4 there exists a tree that covers x_1, x_2, x_3, x_4

Let $s_4 \in S_4$ be such that $vs_4 \in E(G)$. Then $V(P_{a_1} \cup v \cup P_{s_2} \cup P_{a_3} \cup P_{s_4})$ is a tree that covers x_1, x_2, x_3, x_4 . This proves (5).

So, we may assume that v has a non-neighbor $s_4 \in S_4$.

Let us finish the proof of our claim. We pick $s_1 \in S_1$ and $s_3 \in S_3$. Note that $vs_1 \notin E(G)$ since G is triangle-free. If $a_1s_1 \notin E(G)$ then $V(P_{a_1} \cup P_{s_2} \cup P_{a_3} \cup P_{s_4}) \cup \{s_1, v\}$ induces a tree that covers x_1, x_2, x_3, x_4 . So we may assume $s_1a_1 \in E(G)$. Symmetrically, we may assume $s_3a_3 \in E(G)$.

We observe that $V(P_{a_1} \cup P_{s_2} \cup P_{a_3} \cup P_{s_4}) \cup \{s_1, s_3, v\}$ is a cubic structure. A split is given by : $A_1 = V(P_{a_1} \setminus a_1)$, $A_2 = V(P_{s_2} \setminus s_2)$, $A_3 = V(P_{a_3} \setminus a_3)$, $A_4 = V(P_{s_4} \setminus s_4)$, $S_1 = \{a_1\}$, $S_2 = \{s_2\}$, $S_3 = \{a_3\}$, $S_4 = \{s_4\}$, $S_5 = \{s_3\}$, $S_6 = \emptyset$, $S_7 = \{s_1\}$, $S_8 = \{v\}$, $B = \emptyset$, $R = \emptyset$. \square

Now, let C be the set of the $(S_2 \cup S_4)$ -complete vertices of $R \cup \{v\}$. Let Y be the set of those vertices w of $R \cup \{v\}$ such that there exists a path from v to w whose interior is in R . Let Y_1 be the set of those vertices w of $Y \setminus C$ such that there exists a path from v to w whose interior is in $R \setminus C$. Let Y_2 be the set of those vertices w of $Y \cap C$ such that there exists a path from v to w whose interior is in $R \setminus C$. Let Y_3 be $Y \setminus (Y_1 \cup Y_2)$. Note that $Y = Y_1 \cup Y_2 \cup Y_3$.

Note that we may assume that the only possible output of Claim 3.1 is $N_S(w) = S_2 \cup S_4$ and $N_A(w) \subseteq A_1$. Also no vertex of Y has a neighbor in $A_2 \cup A_3 \cup A_4$ (for v this follows from Claim 3.1, for the rest of Y this follows from the definition of R). Note that $v \notin Y_3$. But $v \in Y_2$ is possible since v can be complete to $S_2 \cup S_4$. So $N_{Z \cup \{v\}}(Y_3) \subseteq Y_2 \cup S$ from the definition of R . Also $N_{Z \cup \{v\}}(Y_2) \subseteq Y_1 \cup Y_3 \cup A_1 \cup S_2 \cup S_4$. And from Claim 3.1, $N_{Z \cup \{v\}}(Y_1) \subseteq Y_2 \cup A_1 \cup S_1$.

Hence, we can put all the vertices of Y_1 in A_1 , all the vertices of Y_2 in S_1 and leave all the vertices of Y_3 in R . More formally we let:

- $A'_1 = A_1 \cup Y_1$;
- $A'_i = A_i$, $i = 2, 3, 4$;
- $S'_1 = S_1 \cup Y_2$;
- $S'_i = S_i$, $i = 2, 3, 4$;
- $R' = R \setminus (Y_1 \cup Y_2)$.

We see that $(A'_1, \dots, A'_4, S'_1, \dots, S'_4, R')$ is a square structure of $Z \cup \{v\}$.

Here is how to transform the proof above into an algorithm. We first compute C . After, we use BFS to compute Y . The output of BFS is a rooted tree whose root is v . Similarly, we compute Y_1, Y_2, Y_3 . We check whether $N_{Z \cup \{v\}}(Y_1) \subseteq Y_2 \cup A_1 \cup S_1$. If this is true, the paragraph above shows how to output an augmented square structure. Else there is a vertex $w \in Y_1$ such that w has neighbors in $(A \setminus A_1) \cup (S \setminus S_1)$. Hence by backtracking the BFS tree from w , we find a path $Q = v \dots w$ where $Q \setminus v \subseteq R$ and such that w has neighbors in $(A \setminus A_1) \cup (S \setminus S_1)$. Moreover, the condition $N_S(w) = S_2 \cup S_4$ and $N_A(w) \subseteq A_1$ fails since $w \notin C$. So the proof of Claim 3.1 is a description of how, by just checking several neighborhoods, we can find either:

- a tree of $G[Z \cup \{v\}]$ that covers x_1, x_2, x_3, x_4 or

- a split of the a cubic structure of $G[Z \cup \{v\}]$,

This completes the proof of Lemma 2.2.

4 Proof of Lemma 2.1

Let $Z \subseteq V(G)$ be a cubic structure of G with respect to x_1, x_2, x_3, x_4 together with a split like in the definition and let v be in $V(G) \setminus Z$. Note that Z , the split of Z and v are given by assumption.

Here below, we give a proof of the existence of the objects that the algorithm of our Lemma must output, namely a tree or an augmented cubic structure. But like in the proof of Lemma 2.2, this proof is in fact the description of an $O(m)$ -time algorithm. We omit the details of how to tranform the proof into an algorithm, since they are similar to those of the proof of Lemma 2.2.

When $s_i \in S_i \cup A_i$, we define the path P_{s_i} to be a path from s_i to x_i , whose interior is in A_i , $i = 1, 2, 3, 4$. Note that P_{s_i} exists since by Item 14 of the definition of cubic structures, $G[A_i]$ is connected and by Item 11 every vertex of S_i has a neighbor in A_i , $i = 1, 2, 3, 4$.

Claim 4.1 *The lemma holds when v has neighbors in A .*

PROOF — For suppose that v has a neighbor in A , say $a_1 \in A_1$ (the cases with a neighbor in A_2, A_3, A_4 are symmetric). We choose a_1 subject to the minimality of P_{a_1} .

(1) *If there exists a path $Q = v - \dots - w$ where $Q \setminus v \subseteq B \cup R$ and such that w has neighbors in $A_2 \cup A_3 \cup A_4 \cup S_2 \cup S_3 \cup S_4 \cup S_5$ then there exists a tree of $G[Z \cup \{v\}]$ that covers x_1, x_2, x_3, x_4 .*

Let Q be such a path, minimal with respect to its properties. Note that possibly $v = w$.

If w is adjacent to $a_2 \in S_2 \cup A_2$, $a_3 \in S_3 \cup A_3$ and $a_4 \in S_4 \cup A_4$ then we choose a_2, a_3, a_4 subject to the minimality of $P_{a_2}, P_{a_3}, P_{a_4}$. So, $V(P_{a_1} \cup Q \cup P_{a_2} \cup P_{a_3} \cup P_{a_4})$ induces a tree of G that covers x_1, x_2, x_3, x_4 . Hence, by symmetry, we may assume that w has no neighbor in $S_4 \cup A_4$.

If w is adjacent to $a_2 \in S_2 \cup A_2$, $a_3 \in S_3 \cup A_3$ then $v = w$ because no vertex in $B \cup R$ can have neighbors in both $S_2 \cup A_2$, $S_3 \cup A_3$ by Items 12, 13. We suppose that a_2, a_3 are chosen subject to the minimality of P_{a_2}, P_{a_3} . Let T_2 be a tree of $G[A_2 \cup \{v, s_2\}]$ that covers x_2, v, s_2 where s_2 is some vertex of S_2 (if $a_2 \in S_2$ we choose $s_2 = a_2$). Note that T_2 exists by Theorem 1.2 because $G[A_2 \cup \{v, s_2\}]$ is connected. One of S_6, S_7 is non-empty by Item 6 of the definition, and we may assume $S_7 \neq \emptyset$ because of the symmetry between S_2, S_7 and S_3, S_6 . So, $V(P_{a_1} \cup T_2 \cup P_{a_3} \cup P_{s_4}) \cup \{s_7\}$ where $s_4 \in S_4$, $s_7 \in S_7$ is a tree that covers x_1, x_2, x_3, x_4 , except when $vs_7 \in E(G)$. But then, $V(P_{a_1} \cup Q \cup P_{a_2} \cup P_{a_3} \cup P_{s_4}) \cup \{s_7\}$ is tree that covers x_1, x_2, x_3, x_4 , because $a_2 \in S_2$ would entail the triangle a_2s_7w . Hence, by symmetry, we may assume that w has no neighbor in $S_3 \cup A_3$.

If w is adjacent to $a_2 \in S_2 \cup A_2$ then chose a_2 subject to the minimality of P_{a_2} . Suppose first that some vertex of Q has a neighbor $s_6 \in S_6$. Then $G[A_1 \cup Q \cup S_2 \cup A_2 \cup \{s_6\}]$ is connected, so it contains a tree T_6 that covers x_1, x_2, s_6 . We observe that $V(T_6 \cup P_{s_3} \cup P_{s_4})$ where $s_3 \in S_3$, $s_4 \in S_4$ is a tree that covers x_1, x_2, x_3, x_4 . Hence we assume from here on that no vertex of Q has a neighbor in S_6 . Let T_2 be a tree of $G[A_2 \cup \{s_2, w\}]$ that covers

x_2, w, s_2 where s_2 is some vertex of S_2 (if $a_2 \in S_2$ we choose $s_2 = a_2$). Suppose now that $S_5 \neq \emptyset$. We observe that $V(P_{a_1} \cup Q \cup T_2 \cup P_{s_3} \cup P_{s_4}) \cup \{s_5\}$ where $s_3 \in S_3, s_4 \in S_4, s_5 \in S_5$, is a tree of G that covers x_1, x_2, x_3, x_4 except when $ws_5 \in E(G)$. But in this case we observe that $V(P_{a_1} \cup Q \cup P_{a_2} \cup P_{s_3} \cup P_{s_4}) \cup \{s_5\}$ is a tree of G that covers x_1, x_2, x_3, x_4 . Hence, we may assume that $S_5 = \emptyset$ and by Item 6 of the definition we have $S_6, S_7, S_8 \neq \emptyset$. If no vertex of Q has a neighbor in $S_7 \cup S_8$ then $V(P_{a_1} \cup Q \cup T_2 \cup P_{s_3} \cup P_{s_4}) \cup \{s_7, s_8\}$ where $s_7 \in S_7, s_8 \in S_8$, is a tree of G that covers x_1, x_2, x_3, x_4 . So we may assume that some vertex of Q has a neighbor in $S_7 \cup S_8$ and we let u be the vertex of Q closest to v that has one neighbor in $S_7 \cup S_8$, say $s_7 \in S_7$ (the case with one neighbor in S_8 is similar because of the symmetry between S_7, S_4 and S_8, S_3). Let $s_2 \in S_2$. So $V(P_{a_1} \cup (v-Q-u) \cup P_{s_2} \cup P_{s_3} \cup P_{s_4}) \cup \{s_6, s_7\}$ is a tree of G that covers x_1, x_2, x_3, x_4 except when some vertex of $v-Q-u$ has a neighbor in P_{s_2} . But then, by the minimality of Q , we must have $u = w$. Now since G is triangle-free, $a_2 \notin S_2$. So, $V(P_{a_1} \cup Q \cup P_{a_2} \cup P_{s_3} \cup P_{s_4}) \cup \{s_6, s_7\}$ is a tree of G that covers x_1, x_2, x_3, x_4 . Hence we may assume that w has no neighbor in $S_2 \cup A_2$.

Now w has no neighbors in $S_2 \cup S_3 \cup S_4 \cup A_2 \cup A_3 \cup A_4$. So w must have a neighbor $s_5 \in S_5$. Hence, $V(P_{a_1} \cup Q \cup P_{s_2} \cup P_{s_3} \cup P_{s_4}) \cup \{s_5\}$ where $s_2 \in S_2, s_3 \in S_3, s_4 \in S_4$ is a tree that covers x_1, x_2, x_3, x_4 . This proves (1).

(2) If there exists a path $Q = v - \dots - w$ whose interior is in $B \cup R$ and such that w has neighbors in $S_6 \cup S_7 \cup S_8$ then either Q contains a vertex that is complete to $S_6 \cup S_7 \cup S_8$ or there exists a tree of $G[Z \cup \{v\}]$ that covers x_1, x_2, x_3, x_4 .

Let Q be such a minimal path. It suffices to prove that w is complete to $S_6 \cup S_7 \cup S_8$ or that a tree covering x_1, x_2, x_3, x_4 exists. By (1), we may assume that no vertex of Q has a neighbor in $A_2 \cup A_3 \cup A_4 \cup S_2 \cup S_3 \cup S_4 \cup S_5$. So up to the symmetry between S_6, S_7, S_8 , we may assume that w has a non-neighbor $s_6 \in S_6$ and a neighbor $s_7 \in S_7$ for otherwise our claim is proved. Hence $V(P_{a_1} \cup Q \cup P_{s_2} \cup P_{s_3} \cup P_{s_4}) \cup \{s_6, s_7\}$ is a tree that covers x_1, x_2, x_3, x_4 . This proves (2).

Now, let C be the set of the $(S_6 \cup S_7 \cup S_8)$ -complete vertices of $Z \cup \{v\}$. Let Y be the set of these vertex w of $B \cup R \cup \{v\}$ such that there exists a path from v to w whose interior is in $B \cup R$. Let Y_1 be the set of these vertices w of $Y \setminus C$ such that there exists a path from v to w whose interior is in $(B \cup R) \setminus C$. Let Y_2 be the set of these vertices w of $Y \cap C$ such that there exists a path from v to w whose interior is in $(B \cup R) \setminus C$. Let Y_3 be $Y \setminus (Y_1 \cup Y_2)$. Note that $Y = Y_1 \cup Y_2 \cup Y_3$.

By (1), we may assume that no vertex of Y has a neighbor in $A_2 \cup A_3 \cup A_4 \cup S_2 \cup S_3 \cup S_4 \cup S_5$. Note that $v \notin Y_3$. But $v \in Y_2$ is possible since v can be complete to $(S_6 \cup S_7 \cup S_8)$. So by (2), $N_{Z \cup \{v\}}(Y_3) \subseteq Y_2 \cup S_1$. Also by (2), $N_{Z \cup \{v\}}(Y_2) \subseteq Y_1 \cup Y_3 \cup A_1 \cup S_6 \cup S_7 \cup S_8$. And $N_{Z \cup \{v\}}(Y_1) \subseteq Y_2 \cup A_1 \cup S_1$.

Hence, we can put all the vertices of Y_1 in A_1 , all the vertices of Y_2 in S_1 and all the vertices of Y_3 in B_1 . We obtain a split of the cubic structure $Z \cup \{v\}$. \square

Claim 4.2 *The lemma holds if v is complete to $(S_1 \cup S_2 \cup S_3 \cup S_4) \setminus S_i, i = 1, 2, 3, 4$.*

PROOF — We prove the claim when $i = 4$, the other cases are symmetric. So v is complete

to $S_1 \cup S_2 \cup S_3$.

(1) If there exists a path $Q = v - \dots - w$ such that $V(Q \setminus v) \subseteq B \cup R$ and w has a neighbor s_4 in S_4 then $G[Z \cup \{v\}]$ contains a tree that covers x_1, x_2, x_3, x_4 .

Let us consider such a path Q minimal with respect its properties. Every vertex of $Q \setminus v$ is in B_4 . Indeed, B_4 is the only set among B_1, \dots, B_4, R that allows neighbors in S_4 , and there are no edges between the sets B_1, \dots, B_4, R . Hence by the properties of B_4 , no vertex of $Q \setminus v$ can have neighbors in $S_1 \cup S_2 \cup S_3$. So, $V(P_{s_4} \cup Q \cup P_{s_1} \cup P_{s_2} \cup P_{s_3})$ where $s_1 \in S_1, s_2 \in S_2, s_3 \in S_3$, induces a tree that covers x_1, x_2, x_3, x_4 . This proves (1).

Let Y be the set of these vertices w of $B \cup R$ such that there exists a path $Q = v - \dots - w$ whose interior is in $B \cup R$. If v has some neighbors in B_4 then by (1) we may assume that every component of $G[Y \cap B_4]$ contains no neighbors of vertices of S_4 . So, every such component can be taken out of B_4 and put in R instead. Then we may put v in S_8 and we obtain a split of the cubic structure $Z \cup \{v\}$. \square

Claim 4.3 *The lemma holds.*

PROOF — By Claim 4.1 we may assume that v has no neighbor in A .

(1) For the pairs (i, j) such that $1 \leq i < j \leq 4$ and the pairs (i, j) among $(1, 5), (2, 6), (3, 7), (4, 8)$ the statement below is true:

If there exists a path $Q = u - \dots - w$ of $G[B \cup R \cup \{v\}]$ such that u has a neighbor in S_i and w has a neighbor in S_j then the lemma holds.

Let us choose such a pair (i, j) and such a path Q , subject to the minimality of Q . Note that by the definition of a cubic structure, $V(Q) \subseteq B \cup R$ is impossible. So, Q contains v .

If u is adjacent to $s_1 \in S_1, s_2 \in S_2, s_3 \in S_3, s_4 \in S_4$ then $Q = u = v$ by the minimality of Q . So, $V(P_{s_1} \cup P_{s_2} \cup P_{s_3} \cup P_{s_4} \cup Q)$ induces a tree that covers x_1, x_2, x_3, x_4 . Hence, we may assume that u (and symmetrically w) has no neighbor in S_4 .

If u is adjacent to $s_1 \in S_1, s_2 \in S_2, s_3 \in S_3$ then $Q = u = v$ by the minimality of Q . By Claim 4.2 we may assume that v is not complete to $S_1 \cup S_2 \cup S_3$, so v has a non-neighbor in $S_1 \cup S_2 \cup S_3$, say $s_1 \in S_1$. Let $s_2 \in S_2, s_3 \in S_3$ be neighbors of v . By Item 6 of the definition, we have $S_6 \cup S_7 \neq \emptyset$, so up to the symmetry between S_2, S_7 and S_3, S_6 we may assume that there exists $s_6 \in S_6$. Note that $vs_6 \notin E(G)$ because G is triangle-free. So $V(P_{s_1} \cup P_{s_2} \cup P_{s_3} \cup P_{s_4} \cup Q) \cup \{s_6\}$ induces a tree that covers x_1, x_2, x_3, x_4 . So, we may assume that u (and symmetrically w) has no neighbor in S_3 .

If (i, j) is such that $1 \leq i < j \leq 4$ then up to symmetry, u has a neighbor in $s_1 \in S_1$ and w has a neighbor $s_2 \in S_2$. No vertex of Q has neighbors in $S_5 \cup S_6$ because such a vertex would form a triangle or would contradict the minimality of Q . Also no vertex of Q has neighbors in $S_3 \cup S_4$. Indeed for u, w this follows from the preceeding paragraphs, and for the interior vertices of Q , it follows from the minimality of Q . So, $V(P_{s_1} \cup P_{s_2} \cup P_{s_3} \cup P_{s_4} \cup Q) \cup \{s\}$ where $s \in S_5 \cup S_6$ is a tree that covers x_1, x_2, x_3, x_4 .

If u has a neighbor $s_1 \in S_1$ and w has a neighbor $s_5 \in S_5$, then no vertex of Q has neighbors in $S_2 \cup S_3 \cup S_4$. Indeed, such a vertex would form a triangle or would contradict the minimality of Q . So, $V(P_{s_1} \cup P_{s_2} \cup P_{s_3} \cup P_{s_4} \cup Q) \cup \{s_5\}$ induces a tree that covers

x_1, x_2, x_3, x_4 . Similarly, we can prove that our claim holds when (i, j) is one of $(2, 6)$, $(3, 7)$, $(4, 8)$. This proves (1).

Let Y be the set of these vertex u of $B \cup R \cup \{v\}$ such that there exists a path from v to u whose interior is in $B \cup R$. From (1) it follows that $N_Z(Y)$ is included in either $S_1 \cup N_S(S_1)$, $S_2 \cup N_S(S_2)$, $S_3 \cup N_S(S_3)$, $S_4 \cup N_S(S_4)$ or $S_5 \cup S_6 \cup S_7 \cup S_8$. So, respectively to these cases, Y can be put in either B_1 , B_2 , B_3 , B_4 or R , and we obtain a split of the cubic structure $Z \cup \{v\}$. \square

This completes the proof of Lemma 2.1.

5 NP-completeness of four-in-a-centered-tree

The NP-completeness of four-in-a-centered-tree follows directly from the fact (proved by Bienstock [1]) that the problem of detecting an induced cycle passing through two prescribed vertices of a graph is NP-complete. In fact, the NP-completeness result of Bienstock remains true for several classes of graphs where some induced subgraphs are forbidden. In [6], L  v  que, Lin, Maffray and Trotignon study the kinds of graph that can be forbidden. We use one of their result. When $k \geq 3$, we denote by C_k the cycle on k vertices.

Theorem 5.1 (see [6]) *Let $k \geq 3$ be an integer. Then the following problem is NP-complete:*

INSTANCE: *two vertices x, y of degree 2 of a graph G that does not contain C_3, \dots, C_k .*

QUESTION: *does G contain an induced cycle covering x, y ?*

We deduce easily:

Theorem 5.2 *Let $k \geq 3$ be an integer. Then the following problem is NP-complete:*

INSTANCE: *four terminals x_1, x_2, x_3, x_4 of a graph G that does not contain C_3, \dots, C_k .*

QUESTION: *Does G contain a centered tree covering x_1, x_2, x_3, x_4 ?*

PROOF — Let us consider an instance G, x, y of the NP-complete problem of Theorem 5.1. Let x', x'' be the neighbors of x and y', y'' be the neighbors of y . We prepare an instance G', x_1, x_2, x_3, x_4 of our problem as follows. We delete x, y . We add five vertices c, x_1, x_2, x_3, x_4 and the following edges: $cx_1, cx_2, cx', cx'', x_3y', x_4y''$. Now, G', x_1, x_2, x_3, x_4 is an instance of our problem.

Since $x_1 - c - x_2$ is a P_3 of G' and since x_1, x_2 are of degree 1, every induced centered tree of G' covering x_1, x_2, x_3, x_4 must be made of four edge-disjoint paths $c - x_1$, $c - x_2$, $c - \dots - x_3$, $c - \dots - x_4$. So, such a tree exists if and only if there exists an induced cycle of G covering x, y . This proves that our problem is NP-complete. \square

By the same way, four-in-a-centered-tree can be proved NP-complete for several classes of graphs defined by a given list \mathcal{L} of forbidden subgraphs. Each time, the proof relies on a direct application of an NP-completeness result for \mathcal{L} -free graphs from [6]. Going into the

details of every possible list that we can get would not be too illuminating since the lists are described in [6]. Let us just mention one result: four-in-a-centered-tree is NP-complete for triangle-free graphs with every vertex except one of degree at most three.

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