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Formal Methods and Tools for Industrial Critical Systems

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Abstract Formal methods and tools have become well-established and widely applied to ensure the correctness of fundamental components of industrial critical systems in domains like railways, avionics and automotive. In this Introduction to the special issue, we outline a number of recent achievements concerning the use of formal methods and tools for the specification and verification of critical systems from a variety of industrial domains. These achievements are represented by four properly revised and extended versions of papers that were selected from the 26th *International Conference on Formal Methods for Industrial Critical Systems* (FMICS 2021).

Keywords Formal Methods · Tools · Critical Systems

1 Introduction

In industrial domains such as railways, avionics and automotive, critical (software) systems must comply with stringent dependability and safety requirements and standards. Therefore, formal methods and tools are commonly used for decades now when engineering such critical systems (cf., e.g., Craigen et al (1995); Clarke et al (1996); Hinchey and Bowen (1999); Woodcock et al (2009); Sztipanovits et al (2012); Gnesi and Margaria (2013); Sifakis (2013, 2014); Güdemann and Núñez (2017); Basile et al (2018); ter Beek et al (2018); Garavel et al (2020); Gleirscher and Marmsoler (2020);

Margaria and Kiniry (2020); Ferrari and ter Beek (2022)), in particular in specific application domains (cf., e.g., Brat et al (2004); Campos et al (2014); ter Beek et al (2016); Voas and Schaffer (2016); Ozay and Tabuada (2017); Weyers et al (2017); ter Beek and Loreti (2018); Bonfanti et al (2018); Marko et al (2020); Michael et al (2021); Wing (2021); Kulik et al (2022); ter Beek and Ferrari (2022)).

Formal methods are rigorous and mathematics-based specification languages to describe (model) system behaviour (cf., e.g., Wing (1990); Hinchey et al (2010); Almeida et al (2011); Bowen and Hinchey (2014); Nielson and Nielson (2019)) that come with a precise semantics and with tools for automated formal verification (analysis) of these system models, based on techniques like theorem proving (cf. Robinson and Voronkov (2001)) and model checking (cf. Clarke et al (2009, 2018)), including probabilistic (cf. Baier and Katoen (2008)) and statistical (cf. Agha and Palmskog (2018)) approaches.

As in other engineering disciplines, the envisioned advantage of using formal methods and tools is the expectation that appropriate mathematical modelling and analysis contributes to the correctness of the developed systems by eliminating errors in the initial designs, i.e. well before implementation, and by guaranteeing robust and fault-tolerant systems that behave as specified even in uncertain environments.

This special issue dedicated to “Formal Methods and Tools for Industrial Critical Systems” contains a total of four papers that concern properly revised and extended versions of papers from the 26th *International Conference on Formal Methods for Industrial Critical Systems* (FMICS 2021).

Based on the original reviews and the subsequent discussions among the PC members and PC chairs of

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FMICS 2021 invited the authors of four papers to submit a revised and substantially extended version of their original conference paper to this special issue. The authors of all four papers decided to accept this invitation and based on a thorough reviewing process, by which each paper was reviewed by three reviewers of which at least two had not previously reviewed the conference version, the editors of this special issue decided accept all four papers for inclusion in this special issue.

2 FMICS

The aim of the FMICS conference series is to provide a forum for researchers who are interested in the development and application of formal methods in industry. In particular, FMICS brings together scientists and engineers who are active in the area of formal methods and interested in exchanging their experiences in the industrial usage of these methods. FMICS also strives to promote research and development for the improvement of formal methods and tools for industrial applications. FMICS is the annual conference of the ERCIM Working Group on Formal Methods for Industrial Critical Systems¹, and it is the key conference in the intersection of industrial applications and Formal Methods.

FMICS 2021 was held online during August 24–26, 2021 (the conference was originally scheduled to be held in Paris, France).

FMICS 2021 called for contributions on the following, non-exhaustive, topics of interest:

- Case studies and experience reports on industrial applications of formal methods, focusing on lessons learned or identification of new research directions.
- Methods, techniques and tools to support automated analysis, certification, debugging, descriptions, learning, optimisation and transformation of complex, distributed, real-time, embedded, mobile and autonomous systems.
- Verification and validation methods (model checking, theorem proving, SAT/SMT constraint solving, abstract interpretation, etc.) that address shortcomings of existing methods with respect to their industrial applicability (e.g., scalability and usability issues).
- Impact of the adoption of formal methods on the development process and associated costs. Application of formal methods in standardisation and industrial forums.

The proceedings of FMICS 2021 have been published in Springer’s Lecture Notes in Computer Science series (cf. Lluch-Lafuente and Mavridou (2021)).

¹ <https://fmics.inria.fr/>

3 Selected Papers

In the remainder of this Introduction to the special issue, we briefly present the contributions of the papers that make up this special issue.

The paper *Automated Formal Analysis of Temporal Properties of Ladder Programs*, by Belo Lourenço et al (2022), the recipient of the FMICS 2021 Best Paper Award, describes a new approach for verifying the code running on Programmable Logic Controllers (PLCs). PLCs are industrial digital computers used as automation controllers in manufacturing processes. The software running on PLCs can be developed using Ladder Logic language, i.e., a graphical language that uses circuit diagrams of relay logic hardware to represent programs. Because of the widespread use of PLCs in industry, verifying that a given Ladder Logic program conforms to its expected behavior is of critical importance. The presented approach translates the Ladder Logic program into a Why3 program for deductive verification using automated theorem provers. The verification process, which is fully automated, either obtains a complete proof that verifies the Ladder program or a counterexample. The authors provide a prototype implementation of their approach, as well as experiments that demonstrate its effectiveness.

The paper *Verification and Synthesis of Co-Simulation Algorithms Subject to Algebraic Loops and Adaptive Steps*, by Hansen et al (2022) presents an approach to synthesize and verify orchestration algorithms for co-simulation scenarios of complex systems with algebraic loops, step rejections, adaptive couplings, and reactivity constraints. Such an approach is particularly useful for Cyber-Physical systems (CPSs), which are becoming increasingly complex. The authors argue that traditional simulation techniques are no longer sufficient to cope with the integrated development processes of CPS, which consist of heterogeneous subsystems typically developed using different tools and formalisms. The presented co-simulation approach was implemented in a tool called Scenario-Verifier, which is integrated with the orchestration engine Maestro 2. The integration enables users to seamlessly simulate their co-simulation scenarios. The authors demonstrate the effectiveness of their approach using two real-world case studies, which were simulated in Maestro 2 using a verified and synthesized orchestration algorithm from Scenario-Verifier.

The paper *Randomized Reachability Analysis in Uppaal: Fast Error Detection in Timed Systems*, by Kiviriga et al (2022) presents the implementation of randomized reachability analysis in the tool Uppaal. Randomized reachability analysis is a non-exhaustive technique for the detection of safety violations through repeated ex-

ploration of a model by means of random walks. It uses under-approximation for the quick falsification of models. The presented method analyses Timed Automata and Stopwatch Automata models. The authors demonstrate the scalability and effectiveness of their approach, by providing an evaluation of the strengths and weaknesses of random reachability analysis. The authors show that their implementation outperforms in several cases existing model checking techniques by several orders of magnitude. The benefits are particularly notable when checking industrial sized systems, where traditional model checking techniques often become intractable due to the state space explosion problem.

The final paper *SMT Solving for the Validation of B and Event-B Models* by Schmidt and Leuschel (2022) presents a new translation from B and Event-B operators to SMT-LIB. The authors also extend the interface of the PROB constraint solver to Z3 to run different solver configurations in parallel. Empirical results show that the new translation and workflow improves performance and coverage when compared to the prior PROB implementation by utilizing Z3's lambda functions. The integration of Z3 is also able to decide a lot of constraints with bounded and unbounded integer domains where PROB's solver times out. On the other hand, Z3 was not as effective for constraints that involve set cardinality or many quantifiers. To tackle such challenging constraints, the authors also developed a direct implementation of SMT solving in PROB using its constraint solver as a theory solver. The empirical evaluation performed by the authors showed that a diverse portfolio of constraint solving backends is beneficial for the B language, since no constraint solver is best for all types of constraints.

4 Discussion

We have briefly presented the four selected papers that constitute this special issue. The topics addressed in these papers cover a broad range of formal methods and tools, ranging from theorem proving and SMT solving to randomized reachability analysis and synthesis of co-simulation algorithms. Moreover, they contain applications to critical systems from industrial domains such as automation controllers and Cyber Physical systems. For future and more effective application in industry, the approaches described in the papers constituting this special issue require further development and implementation.

In the future, Belo Lourenço et al (2022) would like to improve the counterexample generation of their tool and augment the trust in translation from Ladder Logic to WhyML by developing a systematic and automatic

validation process. Hansen et al (2022) plan to formalize the FMI 3.0 standard, integrate the Scenario-Verifier with other orchestration engines, and examine whether it is possible to synthesize an optimal orchestration algorithm for a given co-simulation scenario. Kiviriga et al (2022) intend to further investigate methods to improve efficiency (tokenized, coverage-based, and guided methods) and to enhance user experience (through automatic sanity checks). Finally, Schmidt and Leuschel (2022) plan to provide alternative translations for B sequences using lambda functions, compile other configurations in Z3 to run in parallel, and experiment with different SMT solvers to solve SMT-LIB models.

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