RETRACTION NOTE

Retraction Note to: Estimation of contact forces of underactuated robotic finger using soft computing methods

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Retraction Note to:
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The Editor-in-Chief has retracted this article (Joviæ et al. 2019) because validity of the content of this article cannot be verified. This article showed the evidence of substantial text overlap [most notably with the articles cited (Petkovic et al. 2016; Mladenovic et al. 2016)] and authorship manipulation. All authors disagree about this retraction.

References

Joviæ, S., Arsiæ, N., Mariæ, L. M., et al. (2019). Estimation of contact forces of underactuated robotic finger using soft computing methods. *Journal of Intelligent Manufacturing, 30,* 891. https://doi.org/10.1007/s10845-016-1292-0.

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