



Retraction Note to: Input Displacement Neuro-fuzzy Control and Object Recognition by Compliant Multi-fingered Passively Adaptive Robotic Gripper

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Retraction Note to: J Intell Robot Syst (2016) 82:177–187 <https://doi.org/10.1007/s10846-015-0182-6>

The Editor-in-Chief has retracted this article [1] because validity of the content of this article cannot be verified. This article showed evidence of substantial text overlap (most notably with the article cited [2]) and authorship manipulation. None of the co-authors agree to this retraction.

References

1. Petković, D., Shamshirband, S., Anuar, N.B. et al. J. Intell. Robot. Syst. (2016) 82: 177. <https://doi.org/10.1007/s10846-015-0182-6>
2. Petković, D., Issa, M., Pavlovic, N.D. et al. Expert Syst. Appl. (2012) 39: 13295–13304. <https://doi.org/10.1016/j.eswa.2012.05.072>

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