



Correction to: EKLT: Asynchronous Photometric Feature Tracking Using Events and Frames

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The original version of this article was unfortunately omitted to publish the footnote “The best result per row is

highlighted in bold” in Table 7. This has been corrected by publishing this erratum. The correct version of Table 7 with the caption has been given below:

Table 7 Performance of the proposed feature tracker using two different types of frames: the DAVIS frames (Brandli et al. 2014), and frames reconstructed using (Scheerlinck et al. 2018)

Scene	Sequences	Track-norm. error (px)		Rel. feature age	
		DAVIS (Brandli et al. 2014)	HF (Scheerlinck et al. 2018)	DAVIS (Brandli et al. 2014)	HF (Scheerlinck et al. 2018)
Black and White	shapes_6dof	0.80	1.51	0.54	0.51
	checkerboard	1.21	1.10	0.35	0.21
High texture	poster_6dof	0.64	0.67	0.45	0.23
	boxes_6dof	0.72	0.74	0.54	0.41
	bicycles	0.76	0.57	0.20	0.16
Natural	pipe_2	0.78	0.55	0.34	0.14
	outdoor_day_1	0.71	0.77	0.23	0.18
	outdoor_forward_5	0.80	1.14	0.25	0.17

The average pixel error and average feature age are reported for all eight test sequences
The best result per row is highlighted in bold

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