



Editorial Expression of Concern: Trajectory tracking system of wheeled robot based on immune algorithm and sliding mode variable structure

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Expression of concern to:
Intelligent Service Robotics
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The Editor-in-Chief would like to alert the readers that the peer review process of this article may have been compromised. Post-publication peer review did not identify any major flaws in the article, but suggested minor revisions. The authors did not provide any comments or corrections. Therefore, the readers are advised to interpret the results with caution.

Authors Yanting Lan and Xiaodong Chen have not responded to any correspondence from the editor or publisher about this Editorial Expression of Concern.

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