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# A block hybrid integrator for numerically solving fourth-order **Initial Value Problems**

ABSTRACT

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# 1. Introduction

In this work, fourth-order problems of the type:

$$y^{(iv)} = f(x, y, y', y'', y'''), \quad a \le x \le b,$$

with appropriate initial conditions

$$y(a) = \alpha_0, y'(a) = \alpha_1, y''(a) = \alpha_2, y'''(a) = \alpha_3,$$
(2)

A Linear Multistep Hybrid Block method with four intra-step grid points is presented for

approximating directly the solution of fourth order Initial Value Problems (IVPs). Multiple

Finite Difference formulas are derived and combined in a block formulation to form a nu-

merical integrator that provides direct solution to fourth order IVPs over sub-intervals. The

properties and convergence of the proposed method are discussed. The superiority of this method over existing methods is established numerically on different test problems.

are solved numerically, where a, b,  $\alpha_i$ , i = 0, 1, 2, 3 are real numbers. We will see later that the developed method may also be used for solving system of differential equations.

Problems arising from engineering and other sciences, just to mention a few, have been modeled using high order linear and nonlinear IVPs. One of the applications of fourth order problems arises in the static deflection of a uniform beam or a cantilever beam (with left end embedded and right end free gives rise to fourth order IVPs (see [4,12]).

Several numerical methods exist in the literature, but just a few are specially designed to solve fourth order ordinary differential equations. For instance, Yap and Ismail [2] developed a Block Hybrid Collocation Method (BHCM) and applied it to solve fourth order IVPs. They considered three off-grid points by means of collocation. Abdelrahim and Omar [3] developed a four-step implicit block method with three generalized off-step points and applied it to solve fourth order IVPs directly. In the work by Awovemi [13], a multiderivative collocation method was developed to obtain the approximation of fourth order IVPs. In [10], Hussain et al. presented a Runge–Kutta type method for directly solving this kind of problems.

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In this work, we consider linear multistep hybrid formulas with four mid intra-step grid points and fifth derivatives at the two endpoints. These formulas are constructed using a collocation approach, and put together to form a Block Hybrid Method (see [1,5,6,8,9]).

# 2. Derivation of the method

This section describes the derivation of a continuous implicit four intra-step hybrid block method for the solution of the IVP (1). Consider the grid points on the interval of integration [*a*, *b*],  $\pi_N \equiv \{a = x_0 < x_1 < \cdots < x_{N-1} < x_N = b\}$ , with *h* the constant step size,  $h = x_j - x_{j-1}$ ,  $j = 1, 2, \dots, N$ . The method relies on the approximation of the exact solution y(x) of (1) at the grid points of four adjacent subintervals and the corresponding intermediate points, by the polynomial p(x) given by

$$y(x) \simeq p(x) = \sum_{i=0}^{14} \rho_i x^i.$$
 (3)

This yields

$$y^{(i\nu)}(x) \simeq p^{(4)}(x) = \sum_{i=4}^{14} \rho_i i(i-1)(i-2)(i-3)x^{i-4},$$
(4)

$$y^{(\nu)}(x) \simeq p^{(5)}(x) = \sum_{i=5}^{14} \rho_i i(i-1)(i-2)(i-3)(i-4)x^{i-5}.$$
(5)

Here,  $\rho_i$  are real unknown coefficients to be determined. In order to simplify the derivation of the method we will consider the first block,  $[x_0, x_4]$ , as the formulas obtained may be easily shifted to successive blocks. Thus, we consider the points  $x_{j} = \frac{j}{2}h$ , j = 0, 1, ..., 8 in the four-step scheme for approximating the solution on  $[x_0, x_4]$ . After considering the approximations in (3) up to the third derivative applied to the point  $x_0$ , the fourth derivative in (4) applied to the points  $x_{j}$ , j = 0, 1, ..., 8 and the fifth derivative in (5) applied to the points  $x_j$ , j = 0, 4, we obtain a system of 15 equations with 15 unknowns (the  $\rho_i$ , i = 0, 1, ..., 14). This system may be written in matrix form as

(	1	$x_0$	$x_{0}^{2}$	$x_{0}^{3}$	$x_0^4$	$x_{0}^{5}$	$x_{0}^{6}$		$x_0^{13}$	$x_0^{14}$	)
	0	1	$2x_0$	$3x_0^2$	$4x_0^3$	$5x_0^4$	$6x_0^5$		$13x_0^{12}$	$14x_0^{13}$	
	0	0	2	$6x_0$	$12x_{0}^{2}$	$20x_0^3$	$30x_0^4$		$156x_0^{11}$	$182x_0^{12}$	$(v_0)$
	0	0	0	6	$24x_0$	$60x_0^2$	$120x_0^3$		$1716x_0^{10}$	$2184x_0^{11}$	$\left(\begin{array}{c} \rho_0\\ \rho_1\end{array}\right) \left(\begin{array}{c} y_0'\\ y_0'\end{array}\right)$
	0	0	0	0	24	$120x_0$	$360x_0^2$		$17160x_0^9$	$24024x_0^{10}$	$\rho_2 \qquad y_0'' \qquad y_0'''$
	0	0	0	0	24	$120x_{\frac{1}{2}}$	$360x_{\frac{1}{2}}^2$		$17160x_{\frac{1}{2}}^{9}$	$24024x_{\frac{1}{2}}^{10}$	$\begin{array}{c c} \rho_3 \\ \rho_4 \end{array}  \begin{array}{c} f_0 \\ f_0 \\ f_0 \end{array}$
	0	0	0	0	24	120 <i>x</i> <sub>1</sub>	$360x_1^2$		$17160x_1^{9}$	$24024x_1^{10}$	$\rho_5$ $\int_{\frac{1}{2}}$
	0	0	0	0	24	$120x_{\frac{3}{2}}$	$360x_{\frac{3}{2}}^2$		$17160x_{\frac{3}{2}}^{9}$	$24024x_{\frac{3}{2}}^{10}$	$\rho_{7} = f_{\frac{3}{2}}$
	0	0	0	0	24	120 <i>x</i> <sub>2</sub>	$360x_2^2$		$17160x_2^9$	$24024x_2^{10}$	$\rho_8 \qquad f_2 \qquad f_5 $
	0	0	0	0	24	$120x_{\frac{5}{2}}$	$360x_{\frac{5}{2}}^2$		$17160x_{\frac{5}{5}}^{9}$	$24024x_{\frac{5}{2}}^{10}$	$\rho_{10} = f_3$
	0	0	0	0	24	120 <i>x</i> <sub>3</sub>	$360x_3^2$		$17160x_3^{9}$	$24024x_3^{10}$	$\begin{array}{c c} \rho_{11} & f_{\frac{7}{2}} \\ \rho_{12} & f_{4} \end{array}$
	0	0	0	0	24	$120x_{\frac{7}{2}}$	$360x_{\frac{7}{2}}^2$		$17160x_{\frac{7}{2}}^{9}$	$24024x_{\frac{7}{2}}^{10}$	$\left(\begin{array}{c} \rho_{13} \\ \rho_{13} \end{array}\right) \qquad \qquad$
	0	0	0	0	24	120 <i>x</i> <sub>4</sub>	$360x_4^2$		$17160x_4^{9}$	$24024x_4^{10}$	$\langle \rho_{14} \rangle \langle g_4 \rangle$
	0	0	0	0	0	120	$720x_0$		$154440x_0^8$	$240240x_0^9$	
ĺ	0	0	0	0	0	120	$720x_4$		$154440x_4^8$	$240240x_4^9$	)
	41	_						<b>1</b>	(i)(i	)(u)	

where the approximate values are given by 
$$y_i^{(j)} \simeq y^{(j)}(x_i)$$
,  $f_i = f(x_i, y_i, y'_i, y''_i, y''_i)$ , and  $g_i \simeq \frac{df(x, y_i, y', y''_i, y''_i)}{dx}\Big|_{\{x=x_i, y=y_i, y^{(j)}=y^{(j)}\}, j=1, 2, 3\}}$ .

Solving the system above using a CAS like Mathematica we can obtain the values of the coefficients  $\rho_i$ , i = 0, 1, ..., 14, which are not included here. After simplification, the approximating polynomial in (3) adopts the form

$$p(x) = \sum_{i=0}^{3} \alpha_i(x) y_0^{(i)} h^i + h^4 \sum_{i=0}^{8} \beta_i(x) f_{i/2} + h^5 (\gamma_0(x) g_0 + \gamma_4(x) g_4)$$
(6)

where the  $\alpha$ 's,  $\beta$ 's and  $\gamma$ 's are continuous coefficients (which are cumbersome expression that are not included here, but can be easily obtained with the help of a CAS).

Now, we evaluate p(x) in (6) at the points  $x = x_{\frac{i}{2}}$ , i = 1, 2, ..., 8, and after some simplifications, we obtain the following main methods:

$$y_{\frac{1}{2}} = y_0 + \frac{h^2}{2} + \frac{h^2}{4} + \frac{h^2}{48} + \frac{h^4}{48} + h^4 \left( \frac{33702349021}{1562234878530400} + \frac{222281071}{46852025500} - \frac{371970271}{642715552000} + \frac{9271411/2}{17791488000} \right)$$

$$-\frac{59520777}{106274488520} + \frac{72757/2}{5} + \frac{12525307}{1562234878520400} + \frac{20789017/2}{208972055} - \frac{374517}{237117489152000} + h^5 \left( \frac{2223140}{205705856} + \frac{572224724800}{5} \right) \right)$$

$$y_1 = y_0 + hy'_0 + \frac{h^2}{2} + \frac{h^3}{6} + h^4 \left( \frac{1495257787/6}{38677698000} + \frac{6383912}{209792055} - \frac{374517}{3474800} + \frac{9346/3}{868725} \right)$$

$$-\frac{14192837}{15869520} + \frac{185188/3}{15898457} - \frac{43496/5}{1389870} + \frac{387322/7}{299792055} - \frac{62251197}{3244792060} + h^5 \left( \frac{9123240}{80552060} + \frac{2203026}{4540550} \right) \right)$$

$$y_{\frac{2}} = y_0 + \frac{3}{2} \frac{hy'_0}{4} + \frac{9h^2}{7} + \frac{9h^3}{6} + h^4 \left( \frac{3152248868776}{3214475264000} + \frac{4682520971}{386355206} - \frac{24065280}{820019200} + \frac{21137157}{121252000} \right) + h^5 \left( \frac{9123240}{91322050} + \frac{22337618}{4540550} \right) \right)$$

$$y_{\frac{2}} = y_0 + \frac{3}{4} \frac{hy'_0}{4} + \frac{9h^3}{7} + \frac{h^4}{7} + h^4 \left( \frac{149252481687/6}{52024810676} - \frac{470304629}{3214475264000} \right) + h^5 \left( \frac{91232200}{9132205} + \frac{22337618}{3040375} \right) - \frac{25357}{12252000} - \frac{23009200}{80019200} - \frac{82000920}{80019200} + \frac{27030322}{82005200} - \frac{233527}{20270225} + \frac{343859274}{3460375} \right) - \frac{25357}{20270254} - \frac{343859274}{3460375} - \frac{2337618}{391842150400} \right)$$

$$y_2 = y_0 + 2 hy'_0 + 2h^2y''_0 + \frac{4h^3y''_0}{48} + h^4 \left( \frac{14486443712576}{62439913216} - \frac{408402156257}{9323225} - \frac{7089406257}{128378350} + \frac{7089406257}{930724484} + \frac{260693757}{126225} + \frac{370816852524}{93072424} + \frac{370304527}{19705685274} + \frac{20804627}{190768} + \frac{17581}{297705865072} \right) + h^5 \left( \frac{31290202526}{930724484} + \frac{37081682556}{93074484} - \frac{3708406257}{1262225} + \frac{10076}{1804000} + \frac{17272}{1262225} + \frac{10076}{9408993200} + \frac{1768408257}{126225} + \frac{100846}{1930825224} + \frac{2769763}{29770585672} \right) + h^5 \left( \frac{312902765}{93072424} + \frac{308046257}{930756855726} \right)$$

$$y_3 = y_0 + 3 hy'_0 + \frac{h^3}{2} + \frac{h^4}{48} + h^4 \left( \frac{25260779}{126225}$$

Then, evaluating p'(x) in (6), at the points  $x = x_{\frac{i}{2}}$ , i = 1, 2, ..., 8, we obtain the following formulas for approximating the first derivatives:

$$\begin{array}{l} y_{\frac{1}{2}}' = y_{0}' + \frac{hy_{1}''}{2} + \frac{h^{3}y_{0}''}{8} + h^{3} \left( \frac{13029925219/6}{8136640512000} + \frac{509169931/4}{67805337600} - \frac{11322931/6}{207575000} + \frac{22339813/4}{4151347200} - \frac{1154233/6}{2553034496} \\ + \frac{7033927/5}{230630400} - \frac{13011319/6}{830294400} + \frac{44188141/2}{67805337600} - \frac{1098899799/6}{830294400} + h^{4} \left( \frac{1278138097g_{0}}{256275000} + \frac{3839317g_{0}}{122386003040} \right) \\ y_{1}' = y_{0}' + hy_{0}'' + \frac{h^{3}y_{0}''}{h^{3}y_{0}''} + h^{3} \left( \frac{22061331283/6}{25252700000} + \frac{1924384}{19864845} - \frac{2391523/6}{64864800} + \frac{56344/3}{1447875} - \frac{1726001/5}{5189140} \\ + \frac{226084/3}{1035125} - \frac{23637/6}{205920} + \frac{474256/2}{99324225} - \frac{11440233/6}{8475672000} \right) + h^{4} \left( \frac{23264091g_{0}}{650544800} + \frac{66899g_{0}}{302702400} \right) \\ y_{\frac{1}{2}}' = y_{0}' + \frac{3hy_{1}''}{2} + \frac{9h^{3}y_{0}''}{8} + h^{3} \left( \frac{85673001969/6}{401809408000} + \frac{817974369/4}{2511308800} - \frac{2196099/6}{1025602400} + \frac{225895771/4}{256256000} - \frac{24933339/6}{238007680} \\ + \frac{132143671\frac{1}{2}}{256256000} - \frac{1956337}{7321600} + \frac{2200397436}{2511308800} - \frac{239555543/6}{13036075} + \frac{204376/6}{124027025} + \frac{12322053g_{0}}{12403675} - \frac{18848/6}{1328007580} \right) \\ y_{2}' = y_{0}' + 2hy_{0}'' + 2h^{2}y_{0}''' + h^{3} \left( \frac{786030943/6}{13036075} - \frac{22976384/1}{33108075} + \frac{204376/1}{12027025} + \frac{320896/\frac{3}{2}}{13654350} - \frac{15848/5}{135135} \\ + \frac{45952/2}{482625} - \frac{99928f_{5}}{9207025} + \frac{682112/2}{131086248192} + \frac{7795625f_{1}}{13186248192} + \frac{7795625f_{1}}{144797360608} + \frac{231840625f_{5}}{3513724416} \\ + \frac{24889075f_{\frac{3}{2}}}{166053888} - \frac{6534375f_{1}}{107072525} + \frac{253929375f_{2}}}{8136640512} - \frac{7867903272}{8679032325} \right) \\ y_{3}' = y_{0}' + 3hy_{0}'' + \frac{9y_{0}''}{2} + h^{3} \left( \frac{213173476}{291373476} - \frac{226926f_{1}}{1225225} + \frac{75951}{114400} + \frac{23052}{25025} - \frac{867f_{2}}{128128} \\ + \frac{966f_{\frac{3}{2}}}{10653888} - \frac{8539376}{107072525} + \frac{84368600}{1225275} + \frac{75951}{128128} \\ + \frac{966f_{\frac{3}{2}}}{198648000} + \frac{9970}{12252252} - \frac{82706796}{12252252} - \frac{42322250}{1}f_{1} + \frac{130$$

Similarly, evaluating p''(x) in (6), at the points  $x = x_{\frac{i}{2}}$ , i = 1, 2, ..., 8, we obtain the formulas for approximating the second derivatives:

(8)

$$\begin{split} y_{\frac{1}{2}}^{\prime\prime} &= y_{0}^{\prime\prime} + \frac{hy_{0}^{\prime\prime}}{2} + h^{2} \left( \frac{298916734516}{337565453800} + \frac{2119f_{\frac{1}{2}}}{34600} - \frac{5043739f_{1}}{127733760} + \frac{15287341f_{\frac{1}{2}}}{399168000} - \frac{3661313f_{2}}{113541120} + \frac{8574319f_{\frac{1}{2}}}{399168000} \right. \\ &- \frac{2344229f_{1}}{212889600} + \frac{170223f_{\frac{7}{2}}}{37255660} - \frac{9422989f_{0}}{1091475} - \frac{21f_{1}}{340023600} + \frac{11711g_{0}}{34002720} \right) \\ &+ h^{2} \left( \frac{139420877f_{0}}{39916800} + \frac{344101f_{\frac{1}{2}}}{1091475} - \frac{21f_{1}}{2100} + \frac{22689f_{1}}{253875} - \frac{286259f_{2}}{39916800} + \frac{4237f_{\frac{1}{2}}}{86625} \right. \\ &- \frac{63353f_{1}}{155925} + \frac{1657f_{\frac{7}{2}}}{155925} - \frac{467641f_{6}}{155232000} \right) \\ &+ h^{3} \left( \frac{24251g_{0}}{1990800} + \frac{2248g_{0}}{4435200} \right) \\ &+ h^{3} \left( \frac{24251g_{0}}{1990800} + \frac{2248g_{0}}{512} - \frac{1377081f_{2}}{12615680} + \frac{72117f_{\frac{5}{2}}}{385600} \right. \\ &- \frac{298311f_{5}}{12615680} + \frac{109107f_{2}}{883997600} - \frac{791613f_{6}}{519752} \right) \\ &+ h^{3} \left( \frac{506421g_{0}}{52231360} + \frac{3307g_{1}}{5122} - \frac{1377081f_{2}}{12615680} + \frac{72117f_{\frac{5}{2}}}{385600} \right. \\ &- \frac{298311f_{5}}{199225} + \frac{109107f_{2}}{791612f_{6}} - \frac{791613f_{6}}{51975} + \frac{10928f_{1}}{51925} + \frac{2560f_{3}}{2} - \frac{16f_{5}}{155} + \frac{14848f_{3}}{135544} \right. \\ &- \frac{2608f_{5}}{19975} + \frac{512f_{2}}{24255} - \frac{17f_{5}}{15975} \right) \\ &+ h^{3} \left( \frac{271869526}{20290} + \frac{4739475f_{1}}{6100} + \frac{749475f_{1}}{62237} - \frac{16f_{5}}{155} + \frac{14848f_{3}}{5} \right. \\ &- \frac{2608f_{5}}{15975} + \frac{512f_{2}}{24255} - \frac{17f_{5}}{2435} \right) \\ &+ h^{3} \left( \frac{678125g_{0}}{2253408} + \frac{4794875f_{1}}{48515544} + \frac{748975f_{3}}{1064488} + \frac{14076875f_{5}}{1064488} + \frac{75f_{\frac{3}{2}}}{10047f_{2}} \right) \\ &- \frac{1076372f_{5}}{193344} - \frac{86375f_{2}}{73734568} \right) \\ &+ h^{3} \left( \frac{678125g_{0}}{492250} + \frac{4729f_{2}}{4925} + \frac{14013f_{5}}{492280} + \frac{3807f_{3}}{3} \right) \\ &+ \frac{1037760}{4200} + \frac{2119f_{1}}{272} - \frac{728675f_{1}}{1273400} + \frac{7212725f_{2}}{3} + \frac{14013f_{5}}{492280} + \frac{3807f_{3}}{3} \right) \\ &+ \frac{1037760}{2} + h^{2} \left( \frac{510521651f_{5}}{1072400} h + \frac{72175f_{1}}{422400} + \frac{90371239f_{1}}{9625} + \frac{14013$$

(9)

Finally, evaluating p'''(x) in (6), at the points  $x = x_{\frac{i}{2}}$ , i = 1, 2, ..., 8, we obtain the formulas for approximating the third derivatives given by:

$$\begin{aligned} y_{\frac{1}{2}}^{\prime\prime\prime} &= y_{0}^{\prime\prime\prime} + h \left( \frac{10679850817_{0}}{44700816000} + \frac{10430681_{1}^{4}}{5583320} - \frac{13615822_{1}^{4}}{79833300} + \frac{10734411_{2}^{4}}{6252000} - \frac{1073407_{15}}{7983300} + \frac{1975213f_{3}}{22176000} \right) \\ &- \frac{736493_{1}^{4}}{52657621} + \frac{275918070}{7981300} - \frac{47058100}{4705800} \right) + h^{2} \left( \frac{5520800}{212889800} + \frac{190073_{2}}{22188900} \right) \\ y_{1}^{\prime\prime\prime} &= y_{0}^{\prime\prime\prime} + h \left( \frac{21021839_{0}^{4}}{997922000} + \frac{652069f_{1}}{109175} + \frac{12371_{1}}{623700} + \frac{1921f_{2}^{4}}{2528875} - \frac{6677_{1}}{249480} + \frac{255875}{258875} - \frac{4843}{425300} + \frac{914f_{1}}{95225} - \frac{1220073_{1}}{6858400} \right) + h^{2} \left( \frac{6773}{2200} + \frac{997_{2}}{3326400} \right) \\ y_{\frac{\prime\prime}}^{\prime\prime} &= y_{0}^{\prime\prime\prime} + h \left( \frac{2480509f_{0}}{1038775} + \frac{272301f_{1}}{429200} + \frac{445953f_{1}}{492500} + \frac{170879f_{1}}{332540} - \frac{12221f_{2}}{498500} + \frac{36129f_{2}}{492200} - \frac{35257f_{1}}{4925000} + \frac{7087375}{432500} + \frac{15078f_{2}}{38560} + \frac{5552f_{2}}{492500} + \frac{36129f_{2}}{492200} - \frac{35257f_{1}}{4325000} + \frac{5067f_{2}}{432500} + \frac{5552f_{2}}{138554} + \frac{10074f_{2}}{5} + \frac{2027f_{1}}{485500} + \frac{1024f_{2}^{2}}{4365000} \right) \\ y_{2}^{\prime\prime} &= y_{0}^{\prime\prime\prime} + h \left( \frac{8030805f_{0}}{35765428} + \frac{61322f_{1}}{135325} + \frac{163952f_{1}}{25525} + \frac{5552f_{2}}{52525} + \frac{1024f_{2}^{2}}{532224} + \frac{1024f_{2}^{2}}{532224} + \frac{1024f_{2}^{2}}{532224} + \frac{1024f_{2}^{2}}{15995f_{2}^{2}} + \frac{1026f_{2}}{532224} + \frac{1024f_{2}^{2}}{152925} + \frac{1026f_{2}}{532224} + \frac{1$$

All the formulas in (7)–(10) considered together form the block method, that should be applied sequentially on block of intervals of the form  $[x_n, x_{n+4}]$ , n = 0, 4, N - 4, where *N*, the number of subintervals, must be a multiple of 4 in order to reach after an integer number of blocks the final point  $x_N = b$ .

# 3. Analysis of the method

#### 3.1. Local truncation error and order

Let us consider the linear difference operators associated with the formulas in (7), which could be written as

$$\mathcal{L}_{i/2}[z(x); h] \equiv z\left(x + \frac{i}{2}h\right) - \left[\sum_{k=0}^{3} \alpha_k(x) z^{(k)}(x) h^k + h^4 \sum_{k=0}^{8} \beta_k(x) z^{(4)}\left(x + \frac{k}{2}h\right) + h^5\left(\gamma_0(x) z^{(5)}(x) + \gamma_4(x) z^{(5)}(x + 4h)\right)\right]$$
(11)

for i = 1(1)8. The local truncation error of each of the formulas in (7) is the amount by which the exact solution of the ODE fails to satisfy the corresponding difference operator. Thus, if we consider the exact solution y(x) in (11), after expanding in Taylor series around x we get that each of the local truncation errors is of the form

$$\mathcal{L}[y(x); h] = C_0 y(x) + C_1 h y'(x) + C_2 h^2 y''(x) + \dots + C_q h^q y^{(q)}(x) + O(h^{(q+1)}).$$
<sup>(12)</sup>

where the  $C_i$  are constants. If we have that the first p + 4 constants vanish, that is,

$$C_0 = C_1 = C_2 = \dots = C_{p+3} = 0$$
, and  $C_{p+4} \neq 0$ 

then, it is

$$\mathcal{L}[y(x); h] = C_{p+4}h^{p+4}y^{(p+4)}(x) + O(h^{p+5})$$
(13)

and *p* is called the order of the formula and  $C_{p+4}$  is known as the principal error constant. In this the case for all the formulas, the method is said to be consistent of order *p* (see [7]). Taking  $x = x_n$ , the local truncation errors and principal error constants of the main formulas in (7) are given by

$$\mathcal{L}_{\frac{1}{2}}[y(x_{n}); h] = -\frac{111253613y^{(15)}(x_{n})h^{15}}{565618332716236800} + O(h^{16}); \qquad \mathcal{L}_{1}[y(x_{n}); h] = -\frac{2557283y^{(15)}(x_{n})h^{15}}{690452066304000} + O(h^{16}); \\ \mathcal{L}_{\frac{3}{2}}[y(x_{n}); h] = -\frac{19360377y^{(15)}(x_{n})h^{15}}{1293137477632000} + O(h^{16}); \qquad \mathcal{L}_{2}[y(x_{n}); h] = -\frac{1597y^{(15)}(x_{n})h^{15}}{42141849750} + O(h^{16}); \\ \mathcal{L}_{\frac{5}{2}}[y(x_{n}); h] = -\frac{1731780625y^{(15)}(x_{n})h^{15}}{22624733308649472} + O(h^{16}); \qquad \mathcal{L}_{3}[y(x_{n}); h] = -\frac{8523y^{(15)}(x_{n})h^{15}}{63141478400} + O(h^{16}); \\ \mathcal{L}_{\frac{7}{2}}[y(x_{n}); h] = \frac{12530643727y^{(15)}(x_{n})h^{15}}{57716156399616000} + O(h^{16}); \qquad \mathcal{L}_{4}[y(x_{n}); h] = -\frac{6898y^{(15)}(x_{n})h^{15}}{21070924875} + O(h^{16}).$$

For the formulas in (8)–(10) the local truncation errors may be obtained similarly. From the above results, the order of the block method is p = 11.

#### 3.2. Zero-stability and convergence

A numerical method is zero-stable if the solutions remain bounded as  $h \rightarrow 0$ , which means that the method does not provide solutions that grow unbounded as the number of steps increases. To show the zero-stability of the above block method (7)-(10) after taking  $h \rightarrow 0$  the method may be rewritten in matrix form as

$$A_0 Y_\mu = A_1 Y_{\mu-1} \tag{15}$$

 $)^{T}$ 

where

$$\begin{split} Y_{\mu} &= \left(Y_{\mu}^{0}, Y_{\mu}^{1}, Y_{\mu}^{2}, Y_{\mu}^{3}\right)^{T}, \quad Y_{\mu-1} = \left(Y_{\mu-1}^{0}, Y_{\mu-1}^{1}, Y_{\mu-1}^{2}, Y_{\mu-1}^{3}, Y_{\mu-1}^{3}\right)^{T}, \\ Y_{\mu}^{0} &= \left(y_{\frac{1}{2}}, y_{1}, y_{\frac{3}{2}}, y_{2}, y_{\frac{5}{2}}, y_{3}, y_{\frac{7}{2}}, y_{4}\right) \\ &\vdots \\ Y_{\mu}^{3} &= \left(y_{\frac{1}{2}}^{'''}, y_{1}^{'''}, y_{\frac{3}{2}}^{'''}, y_{\frac{5}{2}}^{'''}, y_{3}^{'''}, y_{\frac{7}{2}}^{'''}, y_{4}^{'''}\right) \\ Y_{\mu-1}^{0} &= \left(y_{\frac{1}{2}-1}, y_{0}, y_{\frac{3}{2}-1}, y_{1}, y_{\frac{5}{2}-1}, y_{2}, y_{\frac{7}{2}-1}, y_{3}\right) \end{split}$$

$$\overset{:}{\underset{\mu^{-1}}{}} = (y_{\frac{1}{2}-1}^{\prime\prime\prime}, y_{0}^{\prime\prime\prime\prime}, y_{\frac{3}{2}-1}^{\prime\prime\prime}, y_{1}^{\prime\prime\prime\prime}, y_{\frac{5}{2}-1}^{\prime\prime\prime}, y_{2}^{\prime\prime\prime\prime}, y_{\frac{7}{2}-1}^{\prime\prime\prime}, y_{3}^{\prime\prime\prime\prime})$$

 $A_0$  is the identity matrix of order 32,  $A_0 = I_{32}$ , and  $A_1$  is a 32 × 32 matrix given by

with the  $A_{ii}$  identical  $8 \times 8$  matrices given by

	( 0 0 0	1 1 1	0 0 0	0 0 0	0 0 0	0 0 0	0 0 0	0 0 0	
$A_{ii} =$	0 0	1 1	0 0	0 0	0 0	0 0	0 0	0 0	
	0 0	1 1	0 0	0 0	0 0	0 0	0 0	0 0	
	0 /	1	0	0	0	0	0	0	Ϊ

The characteristic polynomial of the matrix  $A_{11}$  is given as  $|A_{11} - \lambda I_8| = 0$ , that is,  $\lambda^7 (\lambda - 1) = 0$ . The roots of the characteristic polynomial are  $\lambda_q = 0$ , for q = 1, ..., 7 and  $\lambda_8 = 1$ . For matrices  $A_{22}$ ,  $A_{33}$  and  $A_{44}$  corresponding to the approximate

values for the derivatives up to the third order the results are similar. Consequently, the method is zero-stable, since the roots of the characteristic polynomial are all zero except one, whose modulus is one (see [7,16]). For convergence, we state the following theorem.

**Theorem 3.1.** Henrici [15]. A linear multistep method is said to be convergent if it is consistent (with order  $p \ge 1$ ) and it is zero-stable.

By the above analysis, the method has order p = 11, and is zero-stable. Thus, by the above theorem, the method is convergent.

# 4. Computational procedure

The proposed method is implemented in a block mode without the need of predictors. On each block interval of the form  $[x_n, x_{n+4}]$ , n = 0, 4, N - 4, being N a multiple of 4 in order to have an integer number of blocks, we solve the system given by all the formulas (7)-(10). To do that we use the Newton's method taking as starting values (denoted with a bar over them) the approximations provided by the Taylor formulas up to the order of the differential equation, that is,

$$\begin{split} \overline{y}_{n+\frac{i}{2}} &= y_n + i\frac{h}{2}y'_n + \frac{1}{2}\left(i\frac{h}{2}\right)^2 y''_n + \frac{1}{6}\left(i\frac{h}{2}\right)^3 y'''_n + \frac{1}{24}\left(i\frac{h}{2}\right)^4 f_n \\ \overline{y}_{n+\frac{i}{2}}' &= y'_n + i\frac{h}{2}y''_n + \frac{1}{2}\left(i\frac{h}{2}\right)^2 y''_n + \frac{1}{6}\left(i\frac{h}{2}\right)^3 f_n \\ \overline{y}_{n+\frac{i}{2}}' &= y''_n + i\frac{h}{2}y'''_n + \frac{1}{2}\left(i\frac{h}{2}\right)^2 f_n \\ \overline{y}_{n+\frac{i}{2}}' &= y'''_n + i\frac{h}{2}f_n \,, \end{split}$$

for i = 1, ..., 8. The presence of  $g_n$ , n = 0(4)N, in the formulas of the block method, which approximates the fifth derivative at  $x_n$ , that is,  $g_n \simeq y^{(\nu)}(x_n)$ , requires the calculation of

$$y^{(v)}(x) = \frac{df(x, y(x), y'(x), y''(x), y'''(x))}{dx}$$
$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y'(x) + \frac{\partial f}{\partial y'} y''(x) + \frac{\partial f}{\partial y''} y'''(x) + \frac{\partial f}{\partial y'''} f(x, y(x), y'(x), y'''(x)),$$

which can be obtained by hand in simple cases, or with the use of a computer algebra system in the more complicated ones.

The block method has been implemented using the system *Mathematica*, enhanced by the feature **NSolve**[] for linear problems while nonlinear problems were solved by Newton's method enhanced by the feature **FindRoot**[], as summarized in the code below.

## Algorithm: .

**Data:** *a*, *b* (integration interval), *N* (number of steps),  $y_{00}$ ,  $y_{10}$ ,  $y_{20}$ ,  $y_{30}$  (initial values), *f*,  $\frac{df}{dx}$  **Result:** *sol*, discrete approximate solution of the IVP (1) and (2) 1 Let n = 0,  $h = \frac{b-a}{N}$ ; 2 Let  $x_n = a$ ,  $y_n = y_{00}$ ,  $y'_n = y_{10}$ ,  $y''_n = y_{20}$ ,  $y'''_n = y_{30}$ . Let  $sol = \{(x_n, y_n)\}$ . 3 Solve (7)-(10) to get  $y_{n+i}$ ,  $y''_{n+i}$ ,  $y'''_{n+i}$ , i = 1(1)44 Let  $sol = sol \cup \{(x_{n+i}, y_{n+i})\}_{i=1(1)4}$ . 5 Let  $x_n = x_n + 4h$ ,  $y_n = y_{n+4}$ ,  $y'_n = y'_{n+4}$ ,  $y''_n = y''_{n+4}$ . 6 Let n = n + 47 **if** n = N **then** 8 | go to 12 9 **else** 10 | go to 3; 11 **end** 12 End **Remark 4.1.** Note that the proposed method may also be used for solving systems of fourth-order differential equations, by considering a component-wise implementation. For a system of *m* equations, given in vector form as

$$\mathbf{y}^{(i\nu)} = \mathbf{f}(x, \mathbf{y}^T, \mathbf{y}^{\prime T}, \mathbf{y}^{\prime \prime T}, \mathbf{y}^{\prime \prime \prime T}), \qquad a = x_0 \le x \le b = x_N$$

with initial values

$$\mathbf{y}(a) = \mathbf{y}_0, \quad \mathbf{y}'(a) = \mathbf{\dot{y}}_0, \quad \mathbf{y}''(a) = \mathbf{\ddot{y}}_0, \quad \mathbf{y}'''(a) = \mathbf{\ddot{y}}_0,$$

where  $\mathbf{y} = (y_1, \dots, y_m)^T$ ,  $\mathbf{y}^{(i)} = (y_1^{(i)}, \dots, y_m^{(i)})^T$ , i = 1, 2, 3,

$$\mathbf{f}(x,\mathbf{y}^T,\mathbf{y}'^T,\mathbf{y}''^T,\mathbf{y}'''^T) = (f_1(x,\mathbf{y}^T,\mathbf{y}'^T,\mathbf{y}''^T,\mathbf{y}'''^T),\ldots,f_m(x,\mathbf{y}^T,\mathbf{y}''^T,\mathbf{y}'''^T))^T,$$

and  $\mathbf{y}_0 = (y_{1,0}, \dots, y_{m,0})^T$ ,  $\mathbf{y}'_0 = (\dot{y}_{1,0}, \dots, \dot{y}_{m,0})^T$ ,  $\mathbf{y}''_0 = (\ddot{y}_{1,0}, \dots, \ddot{y}_{m,0})^T$ ,  $\mathbf{y}''_0 = (\ddot{y}_{1,0}, \dots, \ddot{y}_{m,0})^T$ , we apply the method to each of the scalar equations in the differential system. In the general case this would result in an algebraic system of  $32 \times m$  equations, that may be solved using again the Newton's method, as in the scalar case. To get the approximate values of the fifth derivative of each component at  $x_n$ , n = 0(4)N, denoted by  $g_{i,n} \simeq y_i^{(5)}(x_n)$ ,  $i = 1, \dots, m$ , we use the formula

$$y_i^{(5)}(x) = \frac{df_i(x, y_1, \dots, y_m, y'_1, \dots, y'_m, y''_1, \dots, y''_m, y'''_1, \dots, y'''_m)}{dx}$$

$$= \frac{\partial f_i}{\partial x} + \sum_{j=1}^m \frac{\partial f_i}{\partial y_j} y'_j + \sum_{j=1}^m \frac{\partial f_i}{\partial y'_j} y''_j + \sum_{j=1}^m \frac{\partial f_i}{\partial y''_j} y'''_j + \sum_{j=1}^m \frac{\partial f_i}{\partial y''_j} f_j.$$

## 5. Numerical examples

Here, some numerical examples are presented to show the accuracy of the developed Block Hybrid Integrator (BHI). In the examples considered the absolute errors were obtained as  $Err = ||y_i - y(x_i)||_{\infty}$ , where  $y_i$  is the approximate solution obtained using BHI or any other numerical approach used for comparisons, and  $y(x_i)$  is the exact solution of the problem considered at the grid points  $\{x_i\}_{i=1}^N$ . The approximate solutions with the BHI are compared with the approximate solutions obtained with different methods in the literature. We have considered the block hybrid method of eighth order in [2], named as BHCM4, and the block hybrid method of eighth order in [3] named as BH8, which have been developed for directly solving fourth-order problems. We have also included here, the block 10-step Generalized Adams-Moulton Method which we named AM. This method is also a self-starting block method of order 11 and is used for solving first-order problems. We have implemented this method by reducing all the scalar fourth-order problems into systems of four first-order problems. The overall maximum error was thus compared with maximum errors obtained using the BHI and other methods mentioned earlier. Furthermore, we have plotted the efficiency curves which show the maximum absolute errors (in logarithmic scale) versus CPU times and number of function evaluations (FEVAL) for the BHI and the AM. The resulting plots of efficiency curves give in all cases a line for the BHI data below the line for the AM results, indicating that the performance of BHI is better than that of the AM. We have not found any other higher order methods in the literature for directly solving the fourth-order problems, in order to make other comparisons. Anyway, the results in the tables and the efficiency plots give an idea of the good performance of the proposed method. The obtained results clearly display the efficiency of the BHI for the following examples.

Problem 1. Consider the linear IVP;

$$y^{(i\nu)} - y^{\prime\prime\prime} - y^{\prime\prime} - y^{\prime} - 2y = 0; \quad 0 \le x \le 2,$$

$$y(0) = -1$$
,  $y'(0) = 0$ ,  $y''(0) = 1$ ,  $y'''(0) = 30$ ,

whose exact solution is  $y(x) = 2e^{2x} - 5e^{-x} + 2\cos x - 9\sin x$ . This problem has been also used in [2,3] to check the behavior of the methods developed there. In Table 1 we can see that the best performance corresponds to the BHI method. Table 2 shows the absolute errors (AE) at different points of the integration interval when h = 0.1. in Fig. 1 we can see the efficiency curves of the BHI and AM methods.

Problem 2. Consider the nonlinear IVP, (see [2]).

$$y^{(iv)} - (y')^2 + yy''' = -4x^2 + e^x(1+x^2-4x), \quad 0 \le x \le 1,$$

$$y(0) = y'(0) = 1$$
,  $y''(0) = 3$ ,  $y'''(0) = 1$ ,

whose exact solution is  $y(x) = x^2 + e^x$ . Table 3 shows the errors for different methods, where the best performance corresponds to the BHI. The efficiency curves for the BHI and AM methods are shown in Fig. 2.

Problem 3: Application to ship dynamics. Consider the linear IVP;

$$y^{(i\nu)} + 3y'' + (2 + \epsilon \cos{(\Omega t)})y = 0; \quad 0 \le t \le 15,$$

h	Method	Err
0.1	BHI	2.06E-14
	AM	8.33E-8
	BH8	8.07E-10
	BHCM4	1.74E-8
0.05	BHI	4.88E-18
	AM	1.92E-11
	BH8	3.22E-12
	BHCM4	8.45E-11
0.025	BHI	1.18E-21
	AM	2.27E-13
	BH8	7.30E-16
	BHCM4	3.69E-13
0.02	BHI	8.11E-23
	AM	5.68E-14
	BHCM4	7.11E-14

Table 1Comparison of the maximum absolute errors obtained forProblem 1.

Table	2

Absolute errors at different poi	nts, obtained for Problem 1, with $h = 0.1$ .
----------------------------------	---

x	AE with BHI	AE with BH8	AE with BHCM4
0.2	3.84639E-18	3.512997 E-13	2.318519 E-13
0.4	3.52637E-17	4.183300 E-12	2.260324 E-12
0.6	1.33530E-16	1.430233 E-11	1.965140 E-11
0.8	3.72718E-16	3.592435 E-11	9.914494 E-11
1.0	8.66967E-16	7.276201 E-11	3.311345 E-10
1.2	1.82155E-15	1.336016 E-10	9.000018 E-10
1.4	3.55154E-15	2.234540 E-10	2.117600 E-9
1.6	6.60586E-15	3.579606 E-10	4.550582 E-9
1.8	1.18243E-14	5.433495 E-10	9.117964 E-9
2.0	2.06365E-14	8.079574 E-10	1.740907 E-8



Fig. 1. Efficiency curves showing errors versus CPU times and number of function evaluations (FEVAL) for Problem 1.

$$y(0) = 1, y'(0) = y''(0) = y'''(0) = 0$$

taken from [2], which corresponds to a physical problem from ship dynamics. When a sinusoidal wave of frequency  $\Omega$  passes along a ship or offshore structure, the resultant fluid actions vary with time *t*, see [14]. For  $\epsilon = 0$  the theoretical solution is known,  $y(t) = 2\cos(t) - \cos(t\sqrt{2})$ , so we will take this value for the numerical experiments. Table 4 shows the errors obtained with different block hybrid methods, where the best performance corresponds to the BHI. The efficiency curves are shown in Fig. 3.

**Problem 4:** Application to beam problem. Consider the linear IVP which illustrates an ill-posed problem of a Beam on Elastic Foundation, which has appeared in [10].

$$y^{(iv)} + y = 1, \quad 0 \le x \le 1,$$

$$y(0) = 0, y'(0) = 0, y''(0) = 0, y'''(0) = 0$$

# Table 3

Table 4

Comparison of the maximum absolute errors obtained for Problem 2:

h	Method	Err
0.2	BHI	1.21E-17
	AM	5.59E-10
	BHCM4	2.38E-12
0.1	BHI	5.20E-21
	AM	2.84E-14
	BHCM4	1.95E-14



Fig. 2. Efficiency curves showing errors versus CPU times and number of function evaluations (FEVAL) for Problem 2.

		h	Method	l	Err	-			
		0.25	BHI	1	1.55E-12				
			AM BH8	2	4.72E-7 3.15E-8				
			BHCM4	1	5.2E-7				
		0.1	BHI	-	1.93E-15				
			AM		1.34E-11				
			BHCM4	-	2.8E-10				
						-			
Error	$\begin{array}{c} 0.01\\ 0.001\\ 10^{-4}\\ 10^{-5}\\ 10^{-6} \end{array}$		• BHI	$\begin{array}{c} 0.01\\ 0.001\\ 10^{-4}\\ 10^{-5}\\ 10^{-6}\end{array}$					• BHI • AM
	0.15 0.20	0.25	0.30		0	50	100	150	200
	CPU	time					FEVAL		

Comparison of the maximum absolute errors obtained for Problem 3.

Fig. 3. Efficiency curves showing errors versus CPU times and number of function evaluations (FEVAL) for Problem 3.

Here, y is the normalized vertical displacement (deviation), and 1 is the normalized distributed load, with the above initial conditions, see [11].

The exact solution is

$$y(x) = 1 - \frac{1}{2}e^{-\frac{x}{\sqrt{2}}}(1 + e^{\sqrt{2}x})\cos\left(\frac{x}{\sqrt{2}}\right).$$



Fig. 4. Efficiency curves showing errors versus CPU times and number of function evaluations (FEVAL) for Problem 4.



Fig. 5. Efficiency curves showing errors versus CPU times and number of function evaluations (FEVAL) for Problem 5.

We solved this problem with the BHI method taking N = 20, 40, 80, 160. The efficiency curves in Fig. 4 show the maximum absolute errors versus the CPU times and the number of function evaluations. The results with the method BHI are compared with the block form of the generalized Adams–Moulton method denoted as AM. The graphs clearly indicate that the BHI method presents the best performance.

**Problem 5.** Consider the nonlinear IVP, which has appeared in [10], given by

$$y^{(iv)} - y^2 = \cos^2(x) + \sin(x) - 1, \quad 0 \le x \le 10,$$

$$y(0) = 0$$
,  $y'(0) = 1$ ,  $y''(0) = 0$ ,  $y'''(0) = -1$ ,

whose exact solution is  $y(x) = \sin(x)$ . We have solved this problem with the BHI method taking  $h = 1/2^i$ , i = 1, 2, 3, 4. The efficiency plot in Fig. 5 shows the proposed method performs better than the generalized Adams–Moulton method AM. **Problem 6.** Consider the nonlinear IVP (see [10])

$$y^{(i\nu)} = \frac{3\sin(y)(3+2\sin^2(y))}{\cos^7(y)}, \quad 0 \le x \le \pi/4,$$

$$y(0) = 0, y'(0) = 1, y''(0) = 0, y'''(0) = 1$$

whose exact solution is  $y(x) = \arcsin(x)$ . We have solved this problem with the BHI method taking N = 20, 40, 80, 160, and the results have been compared with the block form of the generalized Adams–Moulton method (AM). The efficiency curves in Fig. 6 show the good performance of the BHI method.



Fig. 6. Efficiency curves showing errors versus CPU times and number of function evaluations (FEVAL) for Problem 6.



Fig. 7. Efficiency curves for Problem 7.

Problem 7. Consider the nonlinear system as follows, (see [10])

$$y^{(iv)} = y + \frac{1}{\sqrt{y^2 + z^2}} - \frac{1}{\sqrt{w^2 + u^2}}$$
  

$$y(0) = 1, \quad y'(0) = 0, \quad y''(0) = -1, \quad y'''(0) = 0$$
  

$$z^{(iv)} = z + \frac{1}{\sqrt{y^2 + z^2}} - \frac{1}{\sqrt{w^2 + u^2}}$$
  

$$z(0) = 0, \quad z'(0) = 1, \quad z''(0) = 0, \quad z'''(0) = -1$$
  

$$w^{(iv)} = 16w + \frac{1}{\sqrt{y^2 + z^2}} - \frac{1}{\sqrt{w^2 + u^2}}$$
  

$$w(0) = 1, \quad w'(0) = 0, \quad w''(0) = -4, \quad w'''(0) = 0$$
  

$$u^{(iv)} = 16u + \frac{1}{\sqrt{y^2 + z^2}} - \frac{1}{\sqrt{w^2 + u^2}}$$
  

$$u(0) = 0, \quad u'(0) = 2, \quad u''(0) = 0, \quad u'''(0) = -8$$
  
(16)

where the exact solution is given by

$$\begin{array}{c} y = \cos(x) \\ z = \sin(x) \\ w = \cos(2x) \\ u = \sin(2x) \end{array}$$

$$(17)$$

The considered integration interval is [0, 2]. We have solved this problem with the BHI method for N = 20, 40, 80, 160. Fig. 7 shows the good performance of the proposed method compared with the RKFD5 method in [10].



Fig. 8. Efficiency curves for Problem 8.



$$y^{(uv)} = \frac{1}{w}$$

$$y(0) = 1, \quad y'(0) = 1, \quad y''(0) = 1, \quad y'''(0) = 1$$

$$z^{(iv)} = 16\frac{w^2}{u}$$

$$z(0) = 1, \quad z'(0) = 2, \quad z''(0) = 4, \quad z'''(0) = 8$$

$$w^{(iv)} = 81\frac{u^2}{y^5}$$

$$w(0) = 1, \quad w'(0) = 3, \quad w''(0) = 9, \quad w'''(0) = 27$$

$$u^{(iv)} = 256y^4$$

$$u(0) = 1, \quad u'(0) = 4, \quad u''(0) = 16, \quad u'''(0) = 64$$

$$(18)$$

where the exact solution is

-2

(in)

$$\begin{cases} y = e^{x} \\ z = e^{2x} \\ w = e^{3x} \\ u = e^{4x} \end{cases}$$

$$(19)$$

The problem has been integrated in the interval [0, 2] with the BHI method taking again N = 20, 40, 80, 160. The efficiency curves in Fig. 8 show the outperformance of the BHI method.

### 6. Conclusion

1

A block hybrid integrator (BHI) obtained combining different linear multistep formulas is proposed and applied to solve directly fourth-order IVPs in ordinary differential equations. It was shown that the method is very flexible, easy to derive and may be applied to solve diverse kinds of fourth-order IVPs as can be seen in the numerical examples. The method shows a very high accuracy when compared the numerical results to the exact solution and a very good performance compared with existing methods in the literature.

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