# An improved local search algorithm for 3-SAT 

Tobias Brueggemann ${ }^{1}$, Walter Kern ${ }^{2}$<br>Department of Applied Mathematics, University of Twente, P.O. Box 217, 7500 AE Enschede, The Netherlands


#### Abstract

We slightly improve the pruning technique presented in Dantsin et. al. (2002) to obtain an $\mathcal{O}^{*}\left(1.473^{n}\right)$ algorithm for 3-SAT.


Keywords: exact algorithm, local search, 3-SAT MSC2000: 68Q25

## 1 Introduction

An instance of 3 -SAT is a boolean formula $\varphi$ in $n$ variables $x_{1}, \ldots, x_{n}$, defined as the conjunction of a set $\mathcal{C}$ of disjunctive clauses of length at most 3 . Satisfiability of $\varphi$ can be tested in a straightforward manner in time

$$
\mathcal{O}\left(2^{n} \cdot n^{3}\right)=\mathcal{O}^{*}\left(2^{n}\right)
$$

Here, as usual, we use the $\mathcal{O}^{*}$-notation to indicate that polynomial factors are suppressed.

During the last years so-called exact algorithms have been designed solving 3 -SAT in time $\mathcal{O}^{*}\left(\alpha^{n}\right)$ with $\alpha<2$, see Schoening [3] for an overview. The currently fastest randomized algorithms run in time $\mathcal{O}^{*}\left(1.3302^{n}\right)$ (see Hofmeister,

[^0]Schoening, Schuler and Watanabe [2]) and the fastest deterministic algorithm (see Dantsin et. al. [1]) takes $\mathcal{O}^{*}\left(1.481^{n}\right)$. We slightly improve the pruning technique used in Dantsin et. al. [1] to obtain a running time of $\mathcal{O}^{*}\left(1.473^{n}\right)$.

## 2 Local search

Let $\varphi$ be an instance of 3 -SAT given by a set $\mathcal{C}$ of clauses in variables $x_{1}, \ldots, x_{n}$. For $a \in\{0,1\}^{n}$ let $B_{r}(a) \subseteq\{0,1\}^{n}$ denote the set of $0-1$ vectors with Hamming distance at most $r$ from $a$. The currently fastest algorithms for 3-SAT are based on local search: First, a covering code of suitable radius $r \leq n$ is constructed, i.e. a set $A \subseteq\{0,1\}^{n}$ such that

$$
\{0,1\}^{n}=\bigcup_{a \in A} B_{r}(a)
$$

holds. Next we search for a truth assignment for $\varphi$ in each $B_{r}(a), a \in A$, separately. To make our paper self-contained, we briefly describe the basic idea for constructing a covering code and (to some extent) the local search within a given $B_{r}(a)$ as presented in Dantsin et. al. [1].

## Covering codes.

As $B_{r}:=B_{r}(0)$ contains exactly

$$
V(n, r)=\sum_{i=1}^{r}\binom{n}{i}
$$

elements, a covering code $A \subseteq\{0,1\}^{n}$ of radius $r \leq n$ must necessarily satisfy

$$
|A| \geq \frac{2^{n}}{V(n, r)}
$$

Covering codes of approximately this size indeed exist and can be constructed randomly: Choose

$$
t=\frac{n 2^{n}}{V(n, r)}
$$

elements from $\{0,1\}^{n}$ uniformly at random, resulting in a set $A \subseteq\{0,1\}^{n}$ of size $|A| \leq t$. The probability that a particular $a^{*} \in\{0,1\}^{n}$ is not covered by any $B_{r}(a), a \in A$ is at most

$$
P\left[a^{*} \text { not covered }\right]=\left(1-\frac{V(n, r)}{2^{n}}\right)^{t} \leq \mathrm{e}^{-n}
$$

using $1+x \leq \mathrm{e}^{x}$ for $x \in \mathbb{R}$. So the probability that $A$ is not a covering code is at most $2^{n} \mathrm{e}^{-n}$, which tends to 0 as $n \rightarrow \infty$.

This procedure can be de-randomized by taking in each step a new code word $a \in\{0,1\}^{n}$ that is best possible in the sense that it covers as many as possible of the yet uncovered elements in $\{0,1\}^{n}$. Note, however, that this greedy construction takes $\mathcal{O}^{*}\left(2^{n}\right)$ per step and thus almost $\mathcal{O}\left(2^{2 n}\right)=\mathcal{O}^{*}\left(4^{n}\right)$ in total (which is far too slow). Dantsin et. al. [1] therefore propose the following. Let $K \in \mathbb{N}$ be a constant and assume w.l.o.g. that $n=K n_{0}$ and $r=K r$. Then construct a covering code $A_{0} \subseteq\{0,1\}^{n_{0}}$ in time $\mathcal{O}\left(4^{n_{0}}\right)=$ $\mathcal{O}^{*}\left(\sqrt[K]{4}^{n}\right)$ and take

$$
A=\underbrace{A_{0} \times \ldots \times A_{0}}_{K \text { times }}
$$

as a covering code for $\{0,1\}^{n}$. Proceeding this way, the time needed for constructing the covering code becomes negligible.

## Local search.

Assume we want to search for a truth assignment for $\varphi$ in $B_{r}(a) \subseteq\{0,1\}^{n}$. We may assume w.l.o.g. that $a=0$, i.e., we search in $B_{r}=B_{r}(0)$. (Interchange $x_{i}$ with $\bar{x}_{i}$ if necessary.) If $a=0$ is not a truth assignment for $\varphi$, there must exist a false clause, i.e. a clause $C \in \mathcal{C}$ that is false under $a=0$, say $C=\left(x_{i} \vee x_{i^{\prime}} \vee x_{i^{\prime \prime}}\right)$. It then suffices to search for a truth assignment in $B_{r-1} \subseteq\{0,1\}^{n-1}$ w.r.t. each of the formulae

$$
\varphi_{1}=\varphi\left[x_{i}=1\right], \varphi_{2}=\varphi\left[x_{i^{\prime}}=1\right] \text { and } \varphi_{3}=\varphi\left[x_{i^{\prime \prime}}=1\right]
$$

obtained by fixing a variable as indicated in brackets. If necessary, we may even fix in addition some variables to zero, e.g., define $\varphi_{1}:=\varphi\left[x_{i}=1\right], \varphi_{2}:=$ $\varphi\left[x_{i^{\prime}}=1, x_{i}=0\right]$ and $\varphi_{3}:=\varphi\left[x_{i^{\prime \prime}}=1, x_{i}=0, x_{i^{\prime}}=0\right]$.

Continuing this way, our search can be described by a search tree $T_{r}$, constructed by branching on false clauses (one false clause per node), as indicated in figure 1.


Fig. 1. The search tree $T_{r}$
Needless to say that we never branch to formulas $\varphi^{\prime}=\varphi\left[x_{i}=1, \ldots\right]$ that are obviously non-satisfiable because they contain an empty (non-satisfiable)
clause. (For example, if $\left(\bar{x}_{i}\right) \in \mathcal{C}$, we would only branch to $\varphi_{2}$ and $\varphi_{3}$ in figure
1.) We denote the number of leaves of $T_{r}$ by $\left|T_{r}\right|$ and refer to it as the size of $T_{r}$. Clearly,

$$
\begin{equation*}
\left|T_{r}\right| \leq 3^{r} \tag{1}
\end{equation*}
$$

holds, an immediate consequence of the recursion $\left|T_{r}\right| \leq 3\left|T_{r-1}\right|$ (see figure 1). In case $\varphi$ contains a false 2 -clause $C \in \mathcal{C}$, then branching on $C$ would yield $\left|T_{r}\right| \leq 2\left|T_{r-1}\right|$.

As pointed out in Dantsin et. al. [1], this simple argument already gives an $\mathcal{O}^{*}\left(\sqrt[2]{3}^{n}\right) \approx \mathcal{O}^{*}\left(1.7321^{n}\right)$ algorithm: Take $r=\frac{n}{2}$ and search $B_{r}(0)$ and $B_{r}(1)$ separately in time $\mathcal{O}^{*}\left(3^{r}\right)=\mathcal{O}^{*}\left(\sqrt[2]{3}{ }^{n}\right)$ each.

## Smaller search trees.

The trivial bound (1) on the size of the search tree can be improved by a clever branching technique, as shown in Dantsin et. al. [1]: Assume that $\varphi$ contains three pairwise disjoint false clauses $C=\left(x_{i} \vee x_{i^{\prime}} \vee x_{i^{\prime \prime}}\right), C_{1}=$ $\left(x_{j} \vee x_{j^{\prime}} \vee x_{j^{\prime \prime}}\right)$ and $C_{1}^{\prime}=\left(x_{k} \vee x_{k^{\prime}} \vee x_{k^{\prime \prime}}\right)$ and a (true) clause $\left(\bar{x}_{i} \vee \bar{x}_{j} \vee \bar{x}_{k}\right)$. We may then branch along $\left(\bar{x}_{i} \vee \bar{x}_{j} \vee \bar{x}_{k}\right)$, i.e. first branch on $C$ at the root node $\varphi$, then branch on $C_{1}$ at $\varphi_{1}=\varphi\left[x_{i}=1\right]$ and finally branch on $C_{1}^{\prime}$ at $\varphi_{1}^{\prime}=\varphi_{1}\left[x_{j}=1\right]=\varphi\left[x_{i}=1, x_{j}=1\right]$. The resulting search tree is indicated in figure 2 .


Fig. 2. Branching along $\left(\bar{x}_{i} \vee \bar{x}_{j} \vee \bar{x}_{k}\right)$
Note that the node corresponding to $\varphi_{1}^{\prime}$ has only two descendants because $\varphi\left[x_{i}=1, x_{j}=1, x_{k}=1\right]$ is ruled out by the clause $\left(\bar{x}_{i} \vee \bar{x}_{j} \vee \bar{x}_{k}\right)$.

If a similar branching was possible also at $\varphi_{2}$ and $\varphi_{3}$, we would get a search tree satisfying a recursion

$$
\begin{equation*}
\left|T_{r}\right| \leq 6\left|T_{r-2}\right|+6\left|T_{r-3}\right| \tag{2}
\end{equation*}
$$

Indeed, this is what Dantsin et. al. [1] show. Assuming inductively that $\left|T_{k}\right| \leq c \alpha^{k}$ holds for some constant $c>0$, (2) implies that

$$
\begin{equation*}
\left|T_{r}\right| \leq \mathcal{O}\left(\alpha^{r}\right) \tag{3}
\end{equation*}
$$

where $\alpha=\sqrt[3]{4}+\sqrt[3]{2} \approx 2.848$ is the largest root of $\alpha^{3}-6 \alpha-6=0$.
The main result of our paper slightly improves this bound as follows.
Theorem 2.1 By branching on false clauses we can ensure that

$$
\left|T_{r}\right| \leq c \beta^{r}
$$

where $\beta=\frac{1+\sqrt{21}}{2} \approx 2.792$ is the largest root of $\beta^{3}-6 \beta-5=0$.

## Running time.

Let $\varrho<\frac{1}{2}$ and $r=\varrho n$. By Stirling's formula, the size of a covering code we construct is (up to a polynomial factor) bounded by

$$
|A|=\mathcal{O}^{*}\left(\left[2 \varrho^{\varrho}(1-\varrho)^{1-\varrho}\right]^{n}\right) .
$$

According to (3), the number of nodes in $T_{r}$ is bounded by $n\left|T_{r}\right|=\mathcal{O}^{*}\left(\left|T_{r}\right|\right)$ and hence the total running time is thus bounded by

$$
\mathcal{O}^{*}\left(|A|\left|T_{r}\right|\right)=\mathcal{O}^{*}\left(\left[2(\alpha \varrho)^{\varrho}(1-\varrho)^{1-\varrho}\right]^{n}\right)
$$

This expression is minimal for $\varrho \approx 0.26$, yielding the bound of $\mathcal{O}^{*}\left(1.481^{n}\right)$ in Dantsin et. al. [1].

Similarly, replacing $\alpha$ by $\beta$ from Theorem 2.1, we obtain for $\varrho \approx 0.264$ an exact algorithm that runs in $\mathcal{O}^{*}\left(1.473^{n}\right)$.

## References

[1] E. Dantsin, A. Goerdt, E.A. Hirsch, R. Kannan, J. Kleinberg, C. Papadimitriou, O. Raghavan, U. Schoening [2002]: A deterministic $(2-2 /(k+1))^{n}$ algorithm for $k$-SAT based on local search. In: Theoretical Computer Science 289 (2002), 69-83. Elsevier Science B.V.
[2] T. Hofmeister, U. Schoening, R. Schuler, O. Watanabe [2002]: A Probabilistic 3-SAT Algorithm Further Improved. In: H. Alt, A. Ferreira (Eds.): STACS 2002, LNCS 2285, 192-202. SpringerVerlag Berlin Heidelberg.
[3] U. Schoening [2002]: A Probabilistic Algorithm for $k$-SAT Based on Limited Local Search and Restart. In: Algorithmica 32 (2002), 615-623. Springer-Verlag New York Inc.


[^0]:    ${ }^{1}$ Email: t.brueggemann@math.utwente.nl. Supported by the Netherlands Organization for Scientific Research (NWO) grant 613.000.225 (Local Search with Exponential Neighborhoods)
    ${ }^{2}$ Email: kern@math.utwente.nl. Corresponding author.

