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# An improved local search algorithm for 3-SAT

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#### Abstract

We slightly improve the pruning technique presented in Dantsin et. al. (2002) to obtain an  $\mathcal{O}^*(1.473^n)$  algorithm for 3-SAT.

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## 1 Introduction

An instance of 3-SAT is a boolean formula  $\varphi$  in n variables  $x_1, \ldots, x_n$ , defined as the conjunction of a set  $\mathcal{C}$  of disjunctive clauses of length at most 3. Satisfiability of  $\varphi$  can be tested in a straightforward manner in time

 $\mathcal{O}\left(2^n \cdot n^3\right) = \mathcal{O}^*\left(2^n\right).$ 

Here, as usual, we use the  $\mathcal{O}^*$ -notation to indicate that polynomial factors are suppressed.

During the last years so-called *exact algorithms* have been designed solving 3-SAT in time  $\mathcal{O}^*(\alpha^n)$  with  $\alpha < 2$ , see Schoening [3] for an overview. The currently fastest randomized algorithms run in time  $\mathcal{O}^*(1.3302^n)$  (see Hofmeister,

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Schoening, Schuler and Watanabe [2]) and the fastest deterministic algorithm (see Dantsin et. al. [1]) takes  $\mathcal{O}^*(1.481^n)$ . We slightly improve the pruning technique used in Dantsin et. al. [1] to obtain a running time of  $\mathcal{O}^*(1.473^n)$ .

### 2 Local search

Let  $\varphi$  be an instance of 3-SAT given by a set  $\mathcal{C}$  of clauses in variables  $x_1, \ldots, x_n$ . For  $a \in \{0, 1\}^n$  let  $B_r(a) \subseteq \{0, 1\}^n$  denote the set of 0-1 vectors with Hamming distance at most r from a. The currently fastest algorithms for 3-SAT are based on *local search*: First, a *covering code* of suitable *radius*  $r \leq n$  is constructed, i.e. a set  $A \subseteq \{0, 1\}^n$  such that

$$\{0,1\}^n = \bigcup_{a \in A} B_r(a)$$

holds. Next we search for a truth assignment for  $\varphi$  in each  $B_r(a)$ ,  $a \in A$ , separately. To make our paper self-contained, we briefly describe the basic idea for constructing a covering code and (to some extent) the local search within a given  $B_r(a)$  as presented in Dantsin et. al. [1].

#### Covering codes.

As  $B_r := B_r(0)$  contains exactly

$$V\left(n,r\right) = \sum_{i=1}^{r} \binom{n}{i}$$

elements, a covering code  $A \subseteq \{0,1\}^n$  of radius  $r \leq n$  must necessarily satisfy

$$|A| \ge \frac{2^n}{V(n,r)}.$$

Covering codes of approximately this size indeed exist and can be constructed randomly: Choose

$$t = \frac{n2^n}{V\left(n,r\right)}$$

elements from  $\{0,1\}^n$  uniformly at random, resulting in a set  $A \subseteq \{0,1\}^n$  of size  $|A| \leq t$ . The probability that a particular  $a^* \in \{0,1\}^n$  is not covered by any  $B_r(a), a \in A$  is at most

$$P[a^* \text{ not covered}] = \left(1 - \frac{V(n,r)}{2^n}\right)^t \le e^{-n},$$

using  $1 + x \leq e^x$  for  $x \in \mathbb{R}$ . So the probability that A is not a covering code is at most  $2^n e^{-n}$ , which tends to 0 as  $n \to \infty$ .

This procedure can be de-randomized by taking in each step a new code word  $a \in \{0, 1\}^n$  that is best possible in the sense that it covers as many as possible of the yet uncovered elements in  $\{0, 1\}^n$ . Note, however, that this greedy construction takes  $\mathcal{O}^*(2^n)$  per step and thus almost  $\mathcal{O}(2^{2n}) = \mathcal{O}^*(4^n)$ in total (which is far too slow). Dantsin et. al. [1] therefore propose the following. Let  $K \in \mathbb{N}$  be a constant and assume w.l.o.g. that  $n = Kn_0$  and r = Kr. Then construct a covering code  $A_0 \subseteq \{0, 1\}^{n_0}$  in time  $\mathcal{O}(4^{n_0}) =$  $\mathcal{O}^*(\sqrt[\kappa]{4^n})$  and take

$$A = \underbrace{A_0 \times \ldots \times A_0}_{K \text{ times}}$$

as a covering code for  $\{0,1\}^n$ . Proceeding this way, the time needed for constructing the covering code becomes negligible.

#### Local search.

Assume we want to search for a truth assignment for  $\varphi$  in  $B_r(a) \subseteq \{0, 1\}^n$ . We may assume w.l.o.g. that a = 0, i.e., we search in  $B_r = B_r(0)$ . (Interchange  $x_i$  with  $\overline{x}_i$  if necessary.) If a = 0 is not a truth assignment for  $\varphi$ , there must exist a *false clause*, i.e. a clause  $C \in \mathcal{C}$  that is false under a = 0, say  $C = (x_i \lor x_{i'} \lor x_{i''})$ . It then suffices to search for a truth assignment in  $B_{r-1} \subseteq \{0, 1\}^{n-1}$  w.r.t. each of the formulae

$$\varphi_1 = \varphi [x_i = 1], \ \varphi_2 = \varphi [x_{i'} = 1] \text{ and } \varphi_3 = \varphi [x_{i''} = 1],$$

obtained by fixing a variable as indicated in brackets. If necessary, we may even fix in addition some variables to zero, e.g., define  $\varphi_1 := \varphi [x_i = 1], \varphi_2 := \varphi [x_{i'} = 1, x_i = 0]$  and  $\varphi_3 := \varphi [x_{i''} = 1, x_i = 0, x_{i'} = 0]$ .

Continuing this way, our search can be described by a search tree  $T_r$ , constructed by branching on false clauses (one false clause per node), as indicated in figure 1.



Fig. 1. The search tree  $T_r$ 

Needless to say that we never branch to formulas  $\varphi' = \varphi [x_i = 1, ...]$  that are obviously non-satisfiable because they contain an empty (non-satisfiable)

clause. (For example, if  $(\overline{x}_i) \in C$ , we would only branch to  $\varphi_2$  and  $\varphi_3$  in figure 1.) We denote the number of leaves of  $T_r$  by  $|T_r|$  and refer to it as the *size* of  $T_r$ . Clearly,

$$|T_r| \le 3^r \tag{1}$$

holds, an immediate consequence of the recursion  $|T_r| \leq 3|T_{r-1}|$  (see figure 1). In case  $\varphi$  contains a false 2-clause  $C \in \mathcal{C}$ , then branching on C would yield  $|T_r| \leq 2|T_{r-1}|$ .

As pointed out in Dantsin et. al. [1], this simple argument already gives an  $\mathcal{O}^*\left(\sqrt[2]{3}^n\right) \approx \mathcal{O}^*(1.7321^n)$  algorithm: Take  $r = \frac{n}{2}$  and search  $B_r(0)$  and  $B_r(1)$  separately in time  $\mathcal{O}^*(3^r) = \mathcal{O}^*\left(\sqrt[2]{3}^n\right)$  each.

### Smaller search trees.

The trivial bound (1) on the size of the search tree can be improved by a clever branching technique, as shown in Dantsin et. al. [1]: Assume that  $\varphi$  contains three pairwise disjoint false clauses  $C = (x_i \vee x_{i'} \vee x_{i''}), C_1 = (x_j \vee x_{j'} \vee x_{j''})$  and  $C'_1 = (x_k \vee x_{k'} \vee x_{k''})$  and a (true) clause  $(\overline{x}_i \vee \overline{x}_j \vee \overline{x}_k)$ . We may then branch along  $(\overline{x}_i \vee \overline{x}_j \vee \overline{x}_k)$ , i.e. first branch on C at the root node  $\varphi$ , then branch on  $C_1$  at  $\varphi_1 = \varphi[x_i = 1]$  and finally branch on  $C'_1$  at  $\varphi'_1 = \varphi_1[x_j = 1] = \varphi[x_i = 1, x_j = 1]$ . The resulting search tree is indicated in figure 2.



Fig. 2. Branching along  $(\overline{x}_i \vee \overline{x}_j \vee \overline{x}_k)$ 

Note that the node corresponding to  $\varphi'_1$  has only two descendants because  $\varphi[x_i = 1, x_j = 1, x_k = 1]$  is ruled out by the clause  $(\overline{x}_i \vee \overline{x}_j \vee \overline{x}_k)$ .

If a similar branching was possible also at  $\varphi_2$  and  $\varphi_3$ , we would get a search tree satisfying a recursion

$$|T_r| \le 6|T_{r-2}| + 6|T_{r-3}|. \tag{2}$$

Indeed, this is what Dantsin et. al. [1] show. Assuming inductively that  $|T_k| \leq c\alpha^k$  holds for some constant c > 0, (2) implies that

$$|T_r| \le \mathcal{O}\left(\alpha^r\right),\tag{3}$$

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where  $\alpha = \sqrt[3]{4} + \sqrt[3]{2} \approx 2.848$  is the largest root of  $\alpha^3 - 6\alpha - 6 = 0$ .

The main result of our paper slightly improves this bound as follows.

**Theorem 2.1** By branching on false clauses we can ensure that

$$|T_r| \le c\beta^r,$$

where  $\beta = \frac{1+\sqrt{21}}{2} \approx 2.792$  is the largest root of  $\beta^3 - 6\beta - 5 = 0$ .

### Running time.

Let  $\rho < \frac{1}{2}$  and  $r = \rho n$ . By Stirling's formula, the size of a covering code we construct is (up to a polynomial factor) bounded by

$$|A| = \mathcal{O}^*\left(\left[2\varrho^{\varrho}\left(1-\varrho\right)^{1-\varrho}\right]^n\right).$$

According to (3), the number of nodes in  $T_r$  is bounded by  $n|T_r| = \mathcal{O}^*(|T_r|)$ and hence the total running time is thus bounded by

$$\mathcal{O}^*\left(|A||T_r|\right) = \mathcal{O}^*\left(\left[2(\alpha\varrho)^{\varrho}\left(1-\varrho\right)^{1-\varrho}\right]^n\right).$$

This expression is minimal for  $\rho \approx 0.26$ , yielding the bound of  $\mathcal{O}^*(1.481^n)$  in Dantsin et. al. [1].

Similarly, replacing  $\alpha$  by  $\beta$  from Theorem 2.1, we obtain for  $\rho \approx 0.264$  an exact algorithm that runs in  $\mathcal{O}^*(1.473^n)$ .

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