There is No EPTAS for Two-dimensional Knapsack

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Abstract

In the d-dimensional (vector) knapsack problem given is a set of items, each having a d-dimensional size vector and a profit, and a d-dimensional bin. The goal is to select a subset of the items of maximum total profit such that the sum of all vectors is bounded by the bin capacity in each dimension. It is well known that, unless P = NP, there is no fully polynomial time approximation scheme for d-dimensional knapsack, already for d = 2. The best known result is a polynomial time approximation scheme (PTAS) due to Frieze and Clarke (European J. of Operational Research, 100–109, 1984) for the case where $d \geq 2$ is some fixed constant. A fundamental open question is whether the problem admits an efficient PTAS (EPTAS).

In this paper we resolve this question by showing that there is no EPTAS for d-dimensional knapsack, already for d=2, unless W[1]=FPT. Furthermore, we show that unless all problems in SNP are solvable in sub-exponential time, there is no approximation scheme for two-dimensional knapsack whose running time is $f(1/\varepsilon)|\mathcal{I}|^{o(\sqrt{1/\varepsilon})}$, for any function f. Together, the two results suggest that a significant improvement over the running time of the scheme of Frieze and Clarke is unlikely to exist.

Keywords: two-dimensional knapsack, efficient polynomial time approximation schemes, parameterized complexity, theory of computation

1 Introduction

In the well known d-dimensional knapsack problem, given is a set of n items $\{1, \ldots, n\}$, where each item i has a d-dimensional size vector $\bar{s}_i \geq 0$, and a profit $p_i > 0$. Also, given is a d-dimensional bin whose capacity is $\bar{B} = (B_1, \ldots, B_d)$. A feasible solution is a subset of the items $A' \subseteq A$ such that the total size of the items in A' in each dimension r is bounded by B_r , $1 \leq r \leq d$. The objective is to find a feasible solution of maximum total profit. The special case where d = 1 is the classic 0-1 knapsack problem.

This paper studies the efficiency of finding $(1-\varepsilon)$ -approximations for d-dimensional knapsack. A maximization problem Π admits a polynomial-time approximation scheme (PTAS) if there is an algorithm $\mathcal{A}(\mathcal{I},\varepsilon)$ such that, for any $\varepsilon>0$ and any instance \mathcal{I} of Π , $\mathcal{A}(\mathcal{I},\varepsilon)$ outputs a $(1-\varepsilon)$ -approximate solution in time $|\mathcal{I}|^{f(1/\varepsilon)}$ for some function f. As ε gets smaller, the exponent of the polynomial $|\mathcal{I}|^{f(1/\varepsilon)}$ may become very large. Two important restricted classes of approximation schemes were defined to eliminate this dependence. An efficient polynomial-time approximation scheme (EPTAS) is a PTAS whose running time is $f(1/\varepsilon)|\mathcal{I}|^{O(1)}$, whereas a fully polynomial time approximation scheme (FPTAS) runs in time $(1/\varepsilon)^{O(1)}|\mathcal{I}|^{O(1)}$.

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While the classic 0-1 knapsack problem admits an FPTAS, i.e., for any $\varepsilon > 0$, a $(1 - \varepsilon)$ -approximation for the optimal solution can be found in $O(n/\varepsilon^2 \cdot \log(1/\varepsilon))$ steps [10, 11], packing in higher dimensions (also known as *d-dimensional vector packing*) is substantially harder to solve, exactly or approximately. It is well known that, unless P = NP, there is no FPTAS for *d*-dimensional knapsack, already for d = 2 [12, 14] (see also [13],[7]). Frieze and Clarke developed in [6] the first PTAS for the *d*-dimensional knapsack. Subsequently, a scheme with improved running time of $O(n^{\lceil d/\varepsilon \rceil - d})$ was given by Caprara et al. [1].

As d-dimensional knapsack does not admit an FPTAS, a fundamental open question is whether there exists an EPTAS. In this paper we resolve this question by showing that there is no EPTAS for two-dimensional knapsack, unless W[1] = FPT.² Furthermore, we use the results of [2] to show that unless all problems in SNP are solvable in sub-exponential time,³ there is no approximation scheme for two-dimensional knapsack whose running time is $f(1/\varepsilon)|\mathcal{I}|^{o(\sqrt{1/\varepsilon})}$, for any function f. Together, the two results suggest that a significant improvement over the running time of the scheme of [1] is unlikely to exist. We note that, for the case where d=1 an EPTAS exists also for the $multiple\ knapsack$ problem (see the recent work of Jansen [9]).

2 Hardness Results

Denote by $OPT(\mathcal{I})$ the value of an optimal solution for an instance \mathcal{I} of the d-dimensional knapsack problem. We use in the proof of hardness the following parameterized version of the subset sum problem, known as sized subset sum. Given a set of positive integers $L = \{x_1, \ldots, x_n\}$, and the positive integer S, k, decide if there is a subset $L' \subseteq L$ of size k, such that the sum of elements in L' is exactly S (in this case we say that the input is satisfied). The sized subset sum problem is known to be W[1]-hard [4].

We give a reduction from an instance (L, S, k) of sized subset sum to an instance of twodimensional knapsack, denoted by R(L, S, k).

Given an instance (L, S, k), we first modify the values of the elements in L. Define

$$\tilde{x}_i = \frac{x_i + \frac{k-1}{k} \cdot S}{k},$$

and let $\tilde{L} = \{\tilde{x}_1, \dots, \tilde{x}_n\}$. Note that, for any $1 \leq i \leq n$, $0 \leq \tilde{x}_i \leq \frac{2 \cdot S}{k}$ (w.l.o.g. $x_i \leq S$). An important property of the above transformation is that it does not affect the satisfiability of the original instance.

Lemma 1 The instance (L, S, k) is satisfied if and only if (\tilde{L}, S, k) is satisfied.

Proof: If (L, S, k) is satisfied then there is a subset $\{x_{i_1}, \ldots, x_{i_k}\} = L' \subseteq L$ such that $\sum_{i=1}^k x_{i_i} = S$. Consider the subset $\{\tilde{x}_{i_1}, \ldots, \tilde{x}_{i_k}\} = \tilde{L}' \subseteq \tilde{L}$, then

$$\sum_{j=1}^{k} \tilde{x}_{i_j} = \sum_{j=1}^{k} \frac{x_{i_j} + \frac{k-1}{k} \cdot S}{k} = \frac{1}{k} \sum_{j=1}^{k} x_{i_j} + \frac{1}{k} \sum_{j=1}^{k} \frac{k-1}{k} \cdot S = S,$$

¹See also the comprehensive survey of known results in [12].

²For the recent theory of fixed-parameter algorithms and parameterized complexity, see, e.g., [5, 3].

 $^{^{3}}$ The complexity class of SNP was introduced in [15]. The class includes such NP-hard problems as *vertex* cover, independent set and 3SAT, among others. Based on known results in complexity theory, it is unlikely that all of the problems in this class can be solved in sub-exponential time (see [2] and the references therein).

and we have that (\tilde{L}, S, k) is also satisfied.

If (\tilde{L}, S, k) is satisfied, then there is a subset $\{\tilde{x}_{i_1}, \dots, \tilde{x}_{i_k}\} = \tilde{L}' \subseteq \tilde{L}$ such that $\sum_{j=1}^k \tilde{x}_{i_j} = S$. By the definition of \tilde{L} , we have that

$$S = \sum_{j=1}^{k} \tilde{x}_{i_j} = \sum_{j=1}^{k} \frac{x_{i_j} + \frac{k-1}{k} \cdot S}{k} = \frac{1}{k} \sum_{j=1}^{k} x_{i_j} + \frac{1}{k} \sum_{j=1}^{k} \frac{k-1}{k} \cdot S = \frac{1}{k} \sum_{j=1}^{k} x_{i_j} + \frac{k-1}{k} \cdot S,$$

and $\sum_{i=1}^{k} x_{i_i} = S$. Thus, (L, S, k) is satisfied as well.

Now, we define the instance R(L, S, k) of two-dimensional knapsack. The items are $\{1, \ldots, n\}$, where each item i has size $\bar{s}_i = (\tilde{x}_i, \frac{2 \cdot S}{k} - \tilde{x}_i)$ and unit profit. Let $s_{i,1}$ and $s_{i,2}$ denote the first and second entries to the vector \bar{s}_i , respectively. The capacity of the bin is $\bar{B} = (S, S)$. Note that R(L, S, k) can be computed in polynomial time in the size of the instance (L, S, k), and its size is also polynomial.

Lemma 2 $OPT(R(L, S, k)) \leq k$.

Proof: Assume that there is a feasible subset of items $A \subseteq \{1, ..., n\}$ whose value is greater than k for R(L, S, k), then $|A| \ge k+1$. Since A is feasible, we have that $\sum_{i \in A} s_{i,1} = \sum_{i \in A} \tilde{x}_i \le S$, and thus

$$S \ge \sum_{i \in A} s_{i,2} = \sum_{i \in A} \left(\frac{2 \cdot S}{k} - \tilde{x}_i \right) = |A| \cdot \frac{2 \cdot S}{k} - \sum_{i \in A} \tilde{x}_i > S,$$

a contradiction. \Box

Lemma 3 The instance (\tilde{L}, S, k) is satisfied if and only if $OPT(R(L, S, k)) \geq k$.

Proof: If the instance (\tilde{L}, S, k) is satisfied then there is a subset $\{\tilde{x}_{i_1}, \dots, \tilde{x}_{i_k}\} = \tilde{L}' \subseteq \tilde{L}$ such that $\sum_{j=1}^k \tilde{x}_{i_j} = S$. Thus, the solution $A = \{i_1, \dots, i_k\}$ for R(L, S, k) is feasible in both dimensions, i.e., $\sum_{j=1}^k s_{i_j,1} = \sum_{j=1}^k \tilde{x}_{i_j} = S$, and also $\sum_{j=1}^k s_{i_j,2} = \sum_{j=1}^k \left(\frac{2\cdot S}{k} - \tilde{x}_{i_j}\right) = S$. The value of this solution is k, therefore $OPT(R(L, S, k)) \geq k$.

If $OPT(R(L, S, k)) \ge k$ then, by Lemma 2, we have that OPT(R(L, S, k)) = k. Let $A = \{i_1, \dots, i_k\}$ be an optimal solution, then

$$S \ge \sum_{j=1}^{k} s_{i_j,2} = \sum_{j=1}^{k} \left(\frac{2 \cdot S}{k} - \tilde{x}_{i_j} \right) = 2S - \sum_{j=1}^{k} \tilde{x}_{i_j},$$

and we have that $\sum_{j=1}^k \tilde{x}_{i_j} \geq S$. On the other hand, $S \geq \sum_{j=1}^k s_{i_j,1} = \sum_{j=1}^k \tilde{x}_{i_j}$, and thus $\sum_{j=1}^k \tilde{x}_{i_j} = S$. It follows that (\tilde{L}, S, k) is satisfied.

By the above discussion, we have the next lemma.

Lemma 4 For any instance (L, S, k) of sized subset sum, (L, S, k) is satisfied if and only if $OPT(R(L, S, k)) \ge k$.

Proof: The statement of the lemma follows immediately from Lemmas 1 and 3. \Box

Suppose that we have an approximation scheme $\mathcal{A}(\mathcal{I}, \varepsilon)$ for two-dimensional knapsack. We now show how \mathcal{A} can be used to decide if an input for sized subset sum is satisfied.

Lemma 5 Let $\mathcal{A}(\mathcal{I}, \varepsilon)$ be an approximation scheme for two-dimensional knapsack with running time $f(1/\varepsilon) \cdot |\mathcal{I}|^{g(1/\varepsilon)}$, then there is an algorithm for sized subset sum with running time $f(2k) \cdot |\mathcal{I}|^{g(1/\varepsilon)}$.

Proof: Consider the following algorithm for sized subset sum. Given an instance (L, S, k), define the input for two-dimensional knapsack $\mathcal{I} = R(L, S, k)$, and run $\mathcal{A}(\mathcal{I}, \frac{1}{2k})$. If the optimal solution output by the algorithm is of value at least k return that (L, S, k) is satisfied, otherwise return that it cannot be satisfied.

Note that if $OPT(\mathcal{I}) \geq k$, the value output by \mathcal{A} is at least $\left(1 - \frac{1}{2k}\right) k = k - \frac{1}{2} > k - 1$. On the other hand, if $OPT(\mathcal{I}) < k$, the output value is at most k - 1. Also, by Lemma 4, (L, S, k) is satisfied if and only if $OPT(\mathcal{I}) \geq k$. Hence, the algorithm decides correctly if (L, S, k) is satisfied.

The construction of \mathcal{I} takes polynomial time in |(L, S, k)|, and running \mathcal{A} on the instance \mathcal{I} requires $f(2k) \cdot |R(L, S, k)|^{O(g(2k))}$ steps. Thus, the running time of the algorithm is $f(2k) \cdot |(L, S, k)|^{O(g(2k))}$.

We summarize in our main result.

Theorem 6 There is no EPTAS for two-dimensional knapsack unless W[1] = FPT.

Proof: Assume there is an EPTAS for two-dimensional knapsack. That is, there exists an algorithm $\mathcal{A}(\mathcal{I},\varepsilon)$ that, given an instance \mathcal{I} for the problem, returns a $(1-\varepsilon)$ -approximation for the optimal solution in $f(1/\varepsilon) \cdot |\mathcal{I}|^c$ steps. Then, by Lemma 5, there is an algorithm for sized subset sum whose running time is $f(2k) \cdot |(L,S,k)|^{c'}$. It follows that sized subset sum is fixed parameter tractable, which cannot hold unless W[1] = FPT.

The standard parametrization of two-dimensional knapsack is as follows. Given an instance of the problem in which all values are integral, and an integer $k \ge 1$, decide if there is a feasible solution of value k or greater. In fact, we have shown the following.

Theorem 7 The standard parametrization of two-dimensional knapsack is W[1]-hard.

We can use the same reduction to derive an explicit lower bound on the running time of approximation schemes for two-dimensional knapsack, under a different complexity measure. To do so, we first derive a lower bound on the complexity of sized subset sum.

Chen at el. show in [2] that unless all problems in SNP are solvable in sub-exponential time, there is no algorithm for independent set whose running time is $f(k)m^{o(k)}$, where m is the input length. Downey and Fellows [4] give a reduction from independent set to perfect code in which, given a graph G and a parameter k, a new graph H is constructed, such that G has an independent set of size k iff H has a perfect code of size $k' = \frac{k(k+1)}{2} + k + 1$. Under the same assumption, this implies that there is no algorithm for perfect code with running time $f(k)m^{o(\sqrt{k})}$, where m is the input size. Furthermore, a reduction given in [4], from perfect code with a parameter k to sized subset sum with the same parameter k, implies that there is no algorithm for sized subset sum with running time $f(k) \cdot |\mathcal{I}|^{o(\sqrt{k})}$. This is summarized in the next result.

Lemma 8 Unless all problems in SNP are solvable in sub-exponential time, there is no algorithm for sized subset sum whose running time is $f(k) \cdot |\mathcal{I}|^{o(\sqrt{k})}$, for any function f, where $|\mathcal{I}|$ is the input size.

From the above discussion, we have

Theorem 9 Unless all problems in SNP are solvable in sub-exponential time, there is no approximation scheme for two-dimensional knapsack with running time $f(1/\varepsilon)|\mathcal{I}|^{o(\sqrt{1/\varepsilon})}$, for any function f, where $|\mathcal{I}|$ is the size of the input for the problem.

Proof: Assume that there is an approximation scheme $\mathcal{A}(\mathcal{I}, \varepsilon)$ for two-dimensional knapsack with running time $f(1/\varepsilon)|\mathcal{I}|^{o(\sqrt{1/\varepsilon})}$, for some function f. Thus, by Lemma 5, there is an algorithm for sized subset sum whose running time is $f(2k)|\mathcal{I}|^{o(\sqrt{k})}$. By Lemma 8, this cannot hold unless all problems in SNP are solvable in sub-exponential time.

In conclusion, we comment that our reductions yield a restricted class of highly structured inputs for d-dimensional knapsack, which may not reflect the set of inputs arising in real-life applications. For many inputs, it seems reasonable to assume that a small modification in the bin capacity would result in a small change in the profit of an optimal solution for the given instance. For such inputs, augmenting algorithms, i.e., algorithms that output a solution with profit at least as high as the optimal, while violating the bin capacity (in any dimension) at most by factor $(1 + \varepsilon)$, seem to fit well. For fixed values of d, an augmenting algorithm, with running time polynomial in $1/\varepsilon$ and in the input size, can be used to obtain a feasible solution whose profit is at least $1 - \varepsilon$ of the optimal. ⁴

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⁴Such an algorithm can be obtained by discretizing the item sizes in each dimension, r, to be integral multiples of $\frac{\varepsilon}{n} \cdot B_r$, and using dynamic programming over the maximal profit attainable for each of the possible size vectors. Detailed expositions of these standard techniques are given, e.g., in [8, 16].

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