

NIH Public Access

Author Manuscript

Neuroimage. Author manuscript; available in PMC 2010 August 15.

Published in final edited form as:

Neuroimage. 2009 August 15; 47(2): 618-627. doi:10.1016/j.neuroimage.2009.04.057.

Multi-contrast large deformation diffeomorphic metric mapping for diffusion tensor imaging

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Abstract

Diffusion tensor imaging (DTI) can reveal detailed white matter anatomy and has the potential to detect abnormalities in specific white matter structures. Such detection and quantification are, however, not straightforward. The voxel-based analysis after image normalization is one of the most widely used methods for quantitative image analyses. To apply this approach to DTI, it is important to examine if structures in the white matter are well registered among subjects, which would be highly dependent on employed algorithms for normalization. In this paper, we evaluate the accuracy of normalization of DTI data using a highly elastic transformation algorithm, called large deformation diffeomorphic metric mapping. After simulation-based validation of the algorithm, DTI data from normal subjects were used to measure the registration accuracy. To examine the impact of morphological abnormalities on the accuracy, the algorithm was also tested using data from Alzheimer's disease (AD) patients with severe brain atrophy. The accuracy level was measured by using manual landmark-based white matter matching and surface-based brain and ventricle matching as gold standard. To improve the accuracy level, cascading and multi-contrast approaches were developed. The accuracy level for the white matter was 1.88 ± 0.55 and 2.19 ± 0.84 mm for the measured locations in the controls and patients, respectively.

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Keywords

Human; White matter; Magnetic resonance imaging; Diffusion tensor; Normalization; LDDMM

Introduction

Diffusion tensor imaging (DTI) can reveal the detailed anatomy of white matter tracts, based on diffusion anisotropy and fiber orientation information (Basser et al., 1994; Pierpaoli et al., 1996; Makris et al., 1997; Pajevic and Pierpaoli, 1999; Catani et al., 2002; Wakana et al., 2004; Mori et al., 2005). Theoretically, this enables us to study the effects of diseases on specific white matter tracts. However, quantification of the delineated white matter anatomy is not always straightforward, especially not for group studies when using population-based maps.

The image analysis based on image normalization is one of the most widely used methods for automated quantification of anatomical features revealed in MR images. The normalization method has been applied to morphological analyses of T1-weighted images (for review, see, e.g., Ashburner and Friston, 2000) and, more recently, to DTI studies (Alexander et al., 2001; Jones et al., 2002; Park et al., 2003; Xu et al., 2003; Zhang et al., 2006; Muller et al., 2007; Yushkevich et al., 2008). In this approach, acquired images are transformed (normalized) to a template, which makes it possible to perform subsequent voxel-by-voxel analyses. In this process, the normalization accuracy significantly influences the result (Bookstein, 2001). In our previous paper, we estimated the accuracy level for normalization-based analyses of DTI data using a simple linear transformation (Mori et al., 2008). By using a population-averaged template (ICBM-DTI-81), most of the core white matter regions could be registered within 3 mm for the normal adult population. However, this registration quality cannot be guaranteed for patient populations in which there are substantial anatomical abnormalities. Registration errors complicate the interpretation of population analyses. For example, any detected FA abnormality could be due to real FA differences caused by microstructural changes such as axonal loss or myelin abnormalities or due to regional morphological differences (e.g., enlarged ventricles) causing registration errors. To separate out the effects of contrast (such as FA) from those of morphological changes, the use of nonlinear transformation is the next logical step.

In this paper, we tested the a highly non-linear transformation method, called large deformation diffeomorphic metric mapping (LDDMM) (Miller et al., 1993a,b; Miller et al., 1997) to normalize DTI data. The LDDMM algorithm calculates diffeomorphic transformations between images of anatomical configurations by computing the geodesic flow in the space of diffeomorphisms between these images. This allows the study of anatomical structures as a metric space. The diffeomorphic transformations, the disjoint shapes remain disjoint and there is no fusion of points because of the one-to-one property of diffeomorphisms. Connected shapes also remain connected because of the continuity property, and the smoothness of the object boundaries are preserved because of the smoothness property of the diffeomorphisms.

There are several unique steps required to apply a non-linear transformation method to DTI data. First, DTI can produce various types of image contrasts, so the first step is to choose which contrasts will be used to drive the registration. Second, to apply the resultant transformation to the tensor field, tensor reorientation must be performed. In this study, we first tested our tensor transformation algorithm using a simulated DTI phantom. The method was then tested on a normal elderly population and Alzheimer's disease (AD) patients with

severe brain atrophy. To ensure excellent registration accuracy for the entire brain, multicontrast LDDMM was developed.

Methods and Materials

Subjects

Institutional Review Board approval was obtained for the study and written, informed consent, including HIPAA compliance, was obtained from all subjects. DTI data from 13 AD patients (75.4 ± 7.0 years old) and age-matched 18 normal adult control subjects (73.8 ± 7.6 years old) were used in this study.

MRI scans

The 3.0 T MR scanners (Gyroscan NT, Philips Medical Systems) were used. DTI data were acquired with a single-shot, echo-planar imaging (EPI) sequence with sensitivity encoding (SENSE), using a parallel-imaging factor of 2.5 (Pruessmann et al., 1999). The imaging matrix was 96×96 and zero-filled to 256×256 pixels. The field-of-view was 211×211 mm. Transverse sections of 2.2 mm thickness were acquired parallel to the anterior commissure–posterior commissure line. A total of 55–60 sections covered the entire hemisphere and the brainstem without gaps. Diffusion weighting was encoded along 32 independent orientations, and the *b*-value was 700 mm²/s. Five additional images with minimal diffusion weighting ($b \approx 33 \text{ mm}^2/\text{s}$) were also acquired (called b_0 images hereafter). The scanning time per dataset was approximately 4 min, which was repeated twice to improve the SNR.

DTI data processing

The DTI datasets were transferred to a personal computer running a Windows platform and were processed using DtiStudio (www.MriStudio.org) (Jiang et al., 2006). Images were first realigned for co-registration and eddy current distortion correction, using the affine transformation of the Automatic Image Registration (AIR) package (Woods et al., 1998), in which the first minimally diffusion-weighted image was used as a template. The six elements of the diffusion tensor were calculated for each pixel using multivariate linear fitting. After diagonalization, three eigenvalues and eigenvectors were obtained. For the anisotropy map, fractional anisotropy (FA) was used (Pierpaoli and Basser, 1996). The eigenvector associated with the largest eigenvalue was used as an indicator of fiber orientation.

Normalization process

All normalization procedures, including linear and LDDMM transformation, were performed using an in-house program called Landmarker (www.MriStudio.org, Kennedy Krieger Institute and Johns Hopkins University, X. Li, H. Jiang, and S. Mori). As a target for brain normalization, we used a single-subject white matter atlas called JHU-DTI-MNI atlas (also known as the "Eve atlas"), which is built in into the Landmarker and contains T1, T2, and DTI-derived contrasts. The atlas is in the ICBM-152 coordinate system and has a matrix size of $181 \times 217 \times 181$ (1 mm isotropic resolution).

For the initial atlas-subject registration, affine transformation was used using the least diffusion-weighted images (b_0 images). The transformation matrix was then applied to the calculated diffusion tensor field, based on the method described by Alexander et al. (2001) and Xu et al. (2003). This process took less than 1 min with 2–3 GHz Xeon processors.

After the linear normalization, the images were submitted for LDDMM. In this study, we tested several registration approaches in terms of choices of images that drive the

registration. These were: b_0 image only; FA map only; and b_0 + FA dual-contrast registration. Because of the substantial computer resources required by the multi-contrast LDDMM, the data were resampled to $96 \times 128 \times 96$ ($2 \times 2 \times 2$ mm) before the calculation and the computational time was approximately 5 h using one of the 32 CPUs in a cluster computer. Because of this extensive computational requirement, the Landmarker adopts a centralized "remote" strategy. Namely, the software creates a data packet that is automatically transferred to a designated centralized computational resource with enough computational power. Once the computation is completed, the users can activate the data retrieval function of Landmarker, through which the results can be automatically retrieved. This remote approach can be implemented on local Linuxor Unix servers with proper configurations. The computation time is typically 6 h with a 3 MHz Zeon processor.

Details of LDDMM-based image registration

Single-contrast—The deformable template model of Granander (Granander and Miller, 1996) models the observed anatomical images, I, as an orbit under the group of transformations, G, acting on a template image, I_0 .

$$\boldsymbol{I} = \boldsymbol{G} \boldsymbol{I}_0 = \left\{ \boldsymbol{I}_{0^{\circ}} \boldsymbol{\phi}^{-1}, \boldsymbol{\phi} \in \boldsymbol{G} \right\}.$$
⁽¹⁾

Utilizing this model, for any given two images, I_0 , I_1 : $\Omega \subset \mathbb{R}^3 \to \mathbb{R}$, the LDDMM algorithm (Beg, 2003; Beg et al., 2005) calculates the diffeomorphic transformation, $\varphi: \Omega \to \Omega$, registering the images such that $I_1 = I_0 \circ \varphi^{-1}$. $\Omega \mathbb{R}^3$ is the 3D cube on which the data is defined. The optimal transformation, φ , is generated as the end point, $\phi = \varphi_1^{\nu}$, of the flow of smooth time-dependent vector field, $v_t \in V$, $t \in [0,1]$, with the ordinary differential equation,

$$\frac{d\varphi_t^{\nu}}{dt} = \nu_t(\varphi_t^{\nu}), t \in [0, 1],$$
(2)

where ϕ_0 is the identity transformation such that $\phi_0(x) = x, x \in \Omega$. Then, the optimal transformation, $\hat{\phi}$, is calculated by integrating the vector field that is found by minimizing the following equation.

$$\widehat{\nu} = \arg\min_{\nu: d\varphi_{t}^{\nu}/dt = \nu_{t}(\varphi_{t}^{\nu})} \left(\int_{0}^{1} \|\nu_{t}\|_{V}^{2} dt + \frac{1}{\sigma^{2}} \left\| I_{0^{\circ}} \phi^{-1} - I_{1} \right\|_{L^{2}}^{2} \right).$$
(3)

The solution of Eq. (3) is ensured to be in the space of diffeomorphisms, by enforcing smoothness on the vector fields, $v \in V$. The required smoothness is enforced by defining the norm on *V* as $|f|_V = |Lf|_{L^2}$. *L* is a differential operator defined as $L = -\alpha \nabla^2 + \gamma I_{3 \times 3}$, where $I_{3 \times 3}$ is the identity operator and ∇^2 is the Laplacian operator. $|\cdot|_{L^2}$ is the L^2 norm for the square integrable functions defined on Ω . The gradient of the cost in Eq. (3) is:

$$\nabla_{\nu} E_t = 2\nu_t - K \left(\frac{2}{\sigma^2} \left| \mathbf{D} \varphi_{t,1}^{\nu} \right| \nabla J_t^0 \left(J_t^0 - J_t^1 \right) \right), \tag{4}$$

where the notation $\varphi_{s,t} = \varphi_s^{\circ} \varphi_t^{-1}$ is used. In Eq. (4), $J_t^0 = I_0^{\circ} \varphi_{t,0}$ and $J_t^1 = I_1^{\circ} \varphi_{t,1}$. |Df| is the determinant of the Jacobian matrix. $K:L_2(\Omega, R^3) \rightarrow V$ is a compact self-adjoint operator,

defined by $\langle a, b \rangle_{L}^{2} = \langle Ka, b \rangle_{v}$, which satisfies $K(L^{\dagger}L)g=g$ for any smooth vector field $g \in V$. The parameter σ provides weighting between data matching and smoothness regularization terms. In the LDDMM algorithm, Eq. (3) is solved with a gradient descent algorithm using Eq. (4). In Eq. (4), the effect of the operator, $K=(L^{\dagger}L)^{-1}$, is low-pass filtering. The parameters α and γ define the magnitude and frequency response of this filter. Fig. 1 demonstrates the effects of these parameters on the LDDMM-based image transformation. In this simulation, a simple circle object with a radius of 30 pixels (r=30) is transformed to a larger circle (r=40). The low α/γ ratio leads to less elastic transformation, similar to the linear normalization. As the ratio decreases, the transformation is more localized to the edge of the circle where the contrast difference between the two circles is concentrated. Fig. 1B shows the deformed rectangular grid for different α/γ ratios. Fig. 1C shows the norm of the displacement vector as a function of distance from the center of the circle for deformations with difference more nonlinear and localized at the peripheral where the contrast difference resides.

Multi-contrast—For any given two vector valued images, $I_0 = [I_{01}, I_{02}, ..., I_{0C}]$ and $I_1 = [I_{11}, I_{12}, ..., I_{1C}]$ with I_{0c}, I_{1c} : $\Omega \subset R^3 \rightarrow R, c=1,...,C$, the diffeomorphic transformation, φ , registering these two images, such that $I_1 = I_0 \circ \varphi^{-1}$ or $[I_{11}, I_{12}, ..., I_{1C}] = [I_{01} \circ \varphi^{-1}, I_{02} \circ \varphi^{-1}, ..., I_{0C} \circ \varphi^{-1}]$, is assumed to be generated as the end point of the flow of the smooth time-dependent vector field, $v_t \in V$, with the ordinary differential equation, $\partial \varphi_t^{\nu} / \partial t = v_t(\varphi_t^{\nu}), t \in [0, 1]$. The optimal transformation, $\hat{\varphi}$ is calculated by integrating the vector field, which is found by minimizing the following equation.

$$\widehat{\boldsymbol{\nu}} = \underset{\nu: d\varphi_{l}^{\nu}/dt = \nu_{t}(\varphi_{l}^{\nu})}{\arg\min} \left\{ \int_{0}^{1} \|\boldsymbol{\nu}_{t}\|_{\boldsymbol{V}}^{2} dt + \sum_{c=1}^{c} \left\{ \frac{1}{\sigma_{c}^{2}} \left\| \boldsymbol{I}_{0c^{\circ}} \phi^{-1} - \boldsymbol{I}_{1c} \right\|_{L^{2}}^{2} \right\} \right\}.$$
(5)

Here the index *c* denotes the contrast images. Again, the solution for this equation is ensured to be in the space of diffeomorphisms, by enforcing smoothness on the vector fields $v \in V$. The gradient descent algorithm can be used to solve this equation. The gradient of the cost in Eq. (5) is

$$\nabla_{\nu} E_{t} = 2\nu_{t} - \sum_{i=1}^{N} \left(K \left(\frac{2}{\sigma_{c}^{2}} \left| \mathbf{D} \varphi_{t,1}^{\nu} \right| \nabla J_{t}^{0c} \left(J_{t}^{0c} - J_{t}^{1c} \right) \right) \right), c = 1, \dots, C.$$
(6)

In this equation, the parameters, σ_c , control the weighting of contrast-matching terms and smoothness regularization terms. In this study, we used equal weighting for FA and b_0 images.

Tensor transformation—The LDDMM algorithm is a powerful technique to calculate diffeomorphic transformations between scalar-valued images. However, in its original form, the LDDMM cannot be directly used to register DTI images. With the extension of the LDDMM as a multi-contrast image-matching algorithm, we can seed various scalar-valued isotropy or anisotropy images obtained from DTI data as contrasts to the multi-contrast LDDMM algorithm, and we can calculate diffeomorphisms between tensor images. Deformation of DTI images using the calculated transformations also requires the reorientation of the tensor at each voxel. Let $M: \Omega \subset R^3 \to R^{3 \times 3}$ be a tensor image and let φ be a diffeomorphism registering the tensor image, M, to another tensor image calculated using multi-contrast LDDMM. To transform the tensor image, M, with the diffeomorphism,

 φ , we use the method in Alexander et al. (2001), which is based on the Gram-Schmidt orthonormalization. At each point $x \in \Omega$ of the tensor image, the tensor, M(x), can be

decomposed as, $M(x) = \lambda_1 v_1 v_1^T + \lambda_2 v_2 v_2^T + \lambda_3 v_3 v_3^T$, where $\lambda_1, \lambda_2, \lambda_3$ with $\lambda_1 \ge \lambda_2 \ge \lambda_3$ are eigenvalues and v_1, v_2 , and v_3 are the corresponding unit eigenvectors. The transformation on M(x) with φ can be defined as:

$$\begin{split} \phi \cdot M(x) &= \left(\lambda_1 \widehat{v}_1 \widehat{v}_1^T + \lambda_2 \widehat{v}_2 \widehat{v}_2^T + \lambda_3 \widehat{v}_3 \widehat{v}_3^T\right) \circ \phi^{-1}(x) \\ &= \widetilde{M} \circ \phi^{-1}(x) \\ &= \left[\begin{array}{cc} \widetilde{M}_{11} \circ \phi^{-1}(x) & \widetilde{M}_{12} \circ \phi^{-1}(x) & \widetilde{M}_{13} \circ \phi^{-1}(x) \\ \widetilde{M}_{12} \circ \phi^{-1}(x) & \widetilde{M}_{22} \circ \phi^{-1}(x) & \widetilde{M}_{23} \circ \phi^{-1}(x) \\ \widetilde{M}_{13} \circ \phi^{-1}(x) & \widetilde{M}_{23} \circ \phi^{-1}(x) & \widetilde{M}_{33} \circ \phi^{-1}(x) \end{array}\right], \text{ where } \end{split}$$

$$\begin{aligned} \widehat{\boldsymbol{\nu}}_{1} &= \frac{\mathbf{D}\phi\boldsymbol{\nu}_{1}}{|\mathbf{D}\phi\boldsymbol{\nu}_{1}|}, \\ \widehat{\boldsymbol{\nu}}_{2} &= \frac{\mathbf{D}\phi\boldsymbol{\nu}_{2} - \langle\widehat{\boldsymbol{\nu}}_{1},\mathbf{D}\phi\widehat{\boldsymbol{\nu}}_{2}\rangle\widehat{\boldsymbol{\nu}}_{1}}{\left(||\mathbf{D}\phi\boldsymbol{\nu}_{2}||^{2} - \langle\widehat{\boldsymbol{\nu}}_{1},\mathbf{D}\phi\boldsymbol{\nu}_{2}\rangle^{2}\right)^{1/2}}, \\ \widehat{\boldsymbol{\nu}}_{3} &= \widehat{\boldsymbol{\nu}}_{1} \times \widehat{\boldsymbol{\nu}}_{2}. \end{aligned}$$

In these equations, $\mathbf{D}\varphi$ is the Jacobian matrix of φ . This tensor transformation strategy depends on the assumption that the tissue microstructure does not change during the transformation, which means that the tensor shape (3D ellipsoid shape) in each voxel does not change during deformation, i.e., the eigenvalues do not change, but the principal eigenvector changes according to the Jacobian matrix, $\mathbf{D}\varphi$. The plane generated by the eigenvectors, \mathbf{v}_1 , \mathbf{v}_2 , changes to the plane generated by $\mathbf{D}\varphi\mathbf{v}_1$, $\mathbf{D}\varphi\mathbf{v}_2$.

Application of the multi-contrast LDDMM to human brains

For all 13 AD subjects and 18 control subjects, we mapped each subject to the template using one of the following approaches:

- 1. Only b_0 images were used with the single-contrast LDDMM and the transformations, ϕ_i^{b0} , i = 1, ..., 31, were calculated (b_0 -LDDMM).
- 2. Only FA images were used with the single-contrast LDDMM and the transformations, ϕ_i^{FA} , i = 1,...,31, were calculated (FA-LDDMM).
- **3.** Both b_0 and FA images were used with the multi-contrast LDDMM and the transformations, ϕ_i^{b0-FA} , i = 1,...,31, were calculated (b_0 + FA-LDDMM).

In these transformations, the subscripts indicate the subject number (13 AD and 18 control subjects) and the superscripts denote the type of contrast images used in mappings.

Measurement of registration quality

Landmark-based measurements—We used manual landmarks as the gold standard for the degree of matching of various white matter structures between the atlas and subject data after normalization. For the landmarks, we used a so-called "standard landmark set," which consists of 237 landmarks at easy-to-identify white matter structures in the JHU-DTI-MNI atlas, as previously described (Mori et al., 2008). These landmarks were transferred to the normalized patient images and manually moved to corresponding structures. The average distance between the positions of the 237 landmarks in the template and the normalized images represents the normalization quality of the white matter.

To compare the registration results with different approaches (affine, b_0 -LDDMM, FA-LDDMM, and b_0 + FA-LDDMM), we performed a one-sided Kolmogorov–Smirnov (KS) test on cumulative distributions of the pair-wise landmark distances, in which the number of landmarks (*Y* axis) within a given distance (*X* axis) is plotted. For the calculation of the cumulative distributions, the averaged distance function $d:\{1,2,...,M\}\rightarrow[0,G]\subset R$ is defined on the set of *M* landmark points of the template image and this function has the maximum value *G*. The ECDF (empirical cumulative distribution function) of *d* is

$$ECDF(i) = \frac{n(i)}{M}, i=1,\ldots,M,$$

where n(i) is the number of elements or the cardinality of the set $S = \{x: d(x) \le d(i)\}$.

We hypothesized that there was no significant difference between two distributions against the alternative that the two distributions were significantly different. The empirical distribution estimate of KS statistics was obtained using the permutation-based resampling. The entire 237 landmarks were resampled as a whole without replacement for each distribution. Then the KS statistic was computed for each resampled dataset. By repeating this process ten thousand times, an empirical null distribution of the KS statistic was constructed, and the *P*-value was calculated as a percentage of the KS statistics greater than the KS value of the original dataset at 5% significance level.

Surface-based measurement—Landmark-based matching is effective for measuring the registration quality of the white matter. However, it is difficult to apply to cortical and ventricular matching because of the paucity of easy-to-identify landmarks, especially in the cortex. We defined the outer brain surfaces and the ventricle surface of the b_0 images in the template and in each subject and created triangulated meshes. For the surface generation, the image voxels were regarded as values defined as points in a rectangular lattice and eight neighboring voxels formed the eight vertices of a cube. Each cube was decomposed into five tetrahedra. Then the intensity values in the image were used to find whether a given tetrahedron intersected the isosurface. These intersections formed a triangular mesh that presents the surface. Each surface can be represented as a set of vertex coordinates of these triangulated meshes (Fig. 2). The Euclidian distances of the closest vertices between the template and the normalized subject images were calculated. Then, the empirical cumulative distribution curves were calculated similar to the landmark-based measurement. To compare the results with different registration approaches, we again performed a one-sided Kolmogorov–Smirnov (KS) test on the distance cumulative distributions. Note that this surface-to-surface matching measurement does not necessarily measure cortex-to-cortex registration quality, which is beyond the scope of this paper.

Results

Analysis of the impact of the α/γ ratio

The impact of the α/γ ratio on the transformation is demonstrated in Fig. 1. In Fig. 3, we tested the effect of the ratio using circular objects with a varying degree of sinusoidal waves (amplitude=5 pixels) as a template. The total number of the sinusoidal waves around the perimeter (*r*=40 pixels) is changed to 10, 20, 30, and 40, in which the wavelength is 25.13, 12.57, 8.38, and 6.28 pixels, respectively. A circle object with the same diameter was transformed to these targets with different α/γ ratios and the mismatch was measured by counting the number of pixels that were not aligned to the template before and after the transformation. This simulation provides an idea about the relationship between the elasticity of the transformation controlled by the α/γ ratio and the complexity of the target

structures. The results indicate that the transformation provided by a ratio larger than 0.01 is not elastic enough and no improvement (=1) was observed for this type of highly non-linear shape difference. The matching quality improves rapidly as the ratio decreases. For the low-frequency modulation (f=10), no improvement is observed below 0.001, but as the frequency increases (f>10), higher elasticity ($\alpha/\gamma < 0.001$) is required.

Fig. 4 demonstrates the impact of the α/γ ratio on the transformation of human brains; a control subject and an AD patient with severe anatomical deformation are depicted. The color images are Jacobian maps of the transformation from template to subject showing how much change in local tissue volume was introduced by the transformation. For the control subject, the gross mis-registration is appreciable after affine transformation, which is mostly removed by LDDMM with $\alpha/\gamma = 0.01$. The Jacobian map at $\alpha/\gamma = 0.01$ clearly shows the degree of local (non-linear) expansion (Jacobian>1) or shrinkage (Jacobian<1) to match the brain shape of the atlas to that of the subject. As the α/γ ratio decreases, the more local and larger transformation is exerted, especially in cortical areas, as evidenced by the Jacobian maps, even though matching improvement is not immediately obvious visually. The difference between an α/γ of 0.0025 and 0.001 is minimum and is confined to the cortex. For the AD patient, the improvement is visually appreciable up to $\alpha/\gamma = 0.005$ (please notice how the ventricle shrinks and the corpus callosum enlarges, approaching those of the template).

In Fig. 4, the α/γ ratio is gradually decreased (called a "cascading" ratio, hereafter). This ensures that there is only a small amount of required transformation at each step up to 0.001. If such a highly elastic transformation is applied directly to linearly normalized images without proper initialization, the registration may converge to an apparently wrong solution, as demonstrated in Fig. 5, especially when the patient anatomy is dramatically different from the template. The cascading approach is more computationally expensive, but ensures more robust results. Based on these results, we adopted a three-step LDDMM with a decreasing α/γ of 0.01–0.005–0.0025 for all further experiments.

Qualitative examination of the improvement by multi-contrast LDDMM

In Fig. 6, an example of LDDMM normalization is shown for an AD patient with severe brain atrophy. In this figure, results from the four different transformation approaches are compared: affine (before LDDMM); b_0 -LDDMM; FA-LDDMM; and b_0 + FA-LDDMM. From visual inspection, the following points can be immediately appreciated. First, the affine transformation (Fig. 6E) is capable of matching the overall outer brain shape, but fails to register inner structures. Second, when the b_0 image is used for LDDMM (Fig. 6C), not only the brain surface, but also the ventricle surface, is well registered. However, the white matter structures revealed by the FA map are not well-matched. The opposite results are obtained when an FA map is used (Fig. 6D), which carries rich anatomical information about the white matter, but the gray matter–CSF boundary is not well depicted. As a result, while the white matter matching looks excellent, there is a gross mismatch at the brain and ventricle surfaces. The entire brain has noticeably better registration accuracy when the FA and b_0 images are used simultaneously to drive the registration (Fig. 6B).

Quantitative measurements of transformation accuracy

To measure the registration accuracy, we performed two types of the measurements using control and AD populations. First, we measured the registration accuracy of the white matter by placing 237 landmarks on major white matter structures in both the template and the patient image. Second, the brain and ventricle surfaces were defined using the b_0 images and surface matching was measured.

The results of the landmark-based white matter measurements are shown in Fig. 7. After affine transformation, registration accuracy measured by average landmark distance was 3.51 ± 1.16 and 4.40 ± 1.67 mm for the normal and AD populations, respectively. When FA maps were used to drive the LDDMM, the registration was improved to 1.65 ± 0.47 and 1.84 ± 0.65 mm for the normal and AD populations, respectively. The test–retest reliability of the landmark placement was 1.58 ± 0.60 , indicating that the matching quality approached the accuracy of this measurement. The b_0 + FA-LDDMM achieved registration accuracy similar to the FA-LDDMM (1.88 ± 0.55 and 2.19 ± 0.84 mm for the control and AD groups, respectively), but b_0 -LDDMM showed hardly any improvement over the affine registration (3.12 ± 0.54 and 3.99 ± 0.84 mm). A statistically significant improvement in the registration accuracy was observed by using FA (*P*-value=0.01) or b_0 + FA (*P*-value = 0.001) mappings for 5% significance level.

In Figs. 8A and B, results of the brain surface matching are shown. The FA-driven LDDMM leads to poor normalization quality. The b_0 image with high contrast for the brain boundary leads to significant improvement in normalization compared to the affine transformation. The same trend is observed for the ventricle shape matching (Figs. 8C and D). Although significant improvement is found by the FA-LDDMM, the b_0 contrast is necessary for better registration accuracy.

Discussion

Choice of template

Several studies have measured registration accuracy for white matter structures (Grachev et al., 1999; Ardekani et al., 2005) using T_1 -weighted images for brain normalization. These approaches, in which there is only limited contrast within white matter, have shown that most white matter structures can be accurately registered within 3 mm by using linear and non-linear registration tools that are widely available, such as AIR and SPM. In our previous report using DTI data, the young adult population was normalized to a population-averaged DTI template (ICBM-DTI-81) (Mori et al., 2008), and we also found that 90% of the landmarks were within 3 mm. In the present study, we measured approximately 5 mm/90% as the normalization quality by affine transformation (Fig. 7A). This discrepancy is most likely due to the choice of the template. The choice of a population-averaged atlas, such as ICBM-DTI-81 as a template, ensures maximum matching between the template and linearly normalized subject data. Therefore, if linear transformation is used, the population-averaged atlas is a preferable choice as a template.

In this study, we employed a single-subject "Eve" atlas (JHU-DTI-MNI). There are several important points we would like to make regarding the choice of this template. First, highly non-linear transformation methods may not work properly with a population-averaged template, such as ICBM-DTI-81, in which the anatomical definition is blurred due to averaging. This is not a substantial issue for linear normalization, which is mostly driven by a large contrast change at the outside boundary of the brain, but the blurred internal structures could easily confuse highly non-linear transformation. Our initial testing of LDDMM led to overly inflated white matter when a population-averaged map is used as a template. Second, if a single subject is used as a template, the choice of the template could be an important issue. If the normalization algorithm is perfect, the template simply serves as the origin of coordinates to measure anatomical variability and the location of the origin may not be important as long as we are interested in differences among groups. However, in reality, it is preferable that the template image is similar to subject images so that the algorithm is not trapped by improper local minima during the transformation process. This issue is also related to the question of whether we should use an age-matched template. Our present study cannot address this issue completely. However, it is encouraging that the white

matter of both the normal adult and AD patients were registered to the single-subject JHU-DTI-MNI atlas with excellent accuracy.

Choice of non-linear transformation parameters

Unlike linear transformation, non-linear transformation results are strongly dependent on transformation parameters. For LDDMM, the α/γ ratio determines the elasticity. The higher the elasticity, the more complicated shape differences could be matched (Fig. 4). However, the elasticity also has a higher probability of being trapped to a biologically wrong solution (Fig. 5).

In LDDMM, the α/γ ratio determines the amount of elasticity. It is not straightforward to determine which ratio is correct. The simulations in Figs. 1, 3, 4 and 5 should provide some ideas about the impact of this ratio on the image transformation and the ability of LDDMM to match the fine detail of the anatomy. Our empirical observation is as follows: 1) a ratio larger than 0.01 leads to conservative transformation; 2) for normal brain anatomy, for which affine transformation can match most deep white matter structures within 5 mm, single LDDMM transformation with a ratio=0.005 should provide the registration accuracy reported in this paper; and 3) for severely abnormal anatomy, it is important to employ cascading LDDMM transformation with a decreasing α/γ ratio, as reported in this paper. The downside of the cascading approach is the longer computation time.

Normalization accuracy by LDDMM

As expected, the affine transformation led to poor registration for both white matter and the ventricle of AD patients. To improve the normalization quality, non-linear transformation is needed. The results of LDDMM normalization are strongly dependent on image contrasts (Fig. 6). When b_0 images are used to drive LDDMM, it has little impact on white matter registration because of the lack of contrasts within the white matter. b_0 images, on the other hand, can match the brain and ventricle surfaces much more precisely. The opposite is true when FA maps are used for LDDMM. Namely, white matter structures are better registered while the brain surfaces are poorly matched. By combining these two contrasts using the two-contrast approach, the registration quality improves within the measurement errors both for the young adult and AD patient groups. Because these two images have strong contrasts in mutually complementary locations, the equal weighting factor, σ_c , for FA and b_0 maps, seem a reasonable choice. In the future, if more contrasts are added, non-equal weighting may need to be examined.

Even if the normalization is accurately performed, it is always advised to exercise careful interpretation of image analysis results after normalization, especially when the data contain severe atrophy and a large amount of deformation is necessary (and therefore more pixel interpolation and partial volume effects). For example, excessive pixel interpolation may lead to loss of FA which reflects tissue atrophy, but not axonal or myelin damage.

In this paper, we did not perform a comparison with other widely used normalization methods such as SPM. In a recent publication by Klein et al. (2009), highly elastic registration tools were compared with the default setting of SPM and as expected, the former tools in general delivered improved registration accuracy. In this paper, we demonstrated the impact of the parameters that control the transformation elasticity. Also demonstrated is the potential pitfall of employing too elastic parameters and importance of gradual increase of elasticity during the transformation (Fig. 5). These points exemplify difficulties of comparing different registration tools because the results may vary depending on employed parameters and how the tools are used. It is therefore important to know how each registration tool works and carefully evaluate the impact of parameters. The multi-contrast

approach and the cascading elasticity control could be combined with other registration tools to improve their accuracy.

Scalar- and tensor-based normalization

There are two unique issues for DTI normalization. First, when we choose contrasts to drive LDDMM, it is possible to use tensor orientation information. The second issue is the transformation of the tensor field, which requires the reorientation of the first eigenvector. The former issue has not been discussed in this study, where we used scalar images (b_0 and FA images) to drive LDDMM. By inspecting DTI-derived images, it becomes immediately apparent that off-diagonal tensor element and eigenvector maps carry far stronger contrasts for intra-white matter structures, and thus, they could be more effective to drive normalization. It would be interesting in future work to see further improvement of normalization quality by adding these contrasts to the multi-contrast LDDMM. In the past, several methods have been postulated to use these contrasts for the normalization of DTI (Park et al., 2003; Cao et al., 2005; Zhang et al., 2006). However, these contrasts are rotationally variant, and therefore, require constant re-calculation during deformation. As a result, the method by Cao et al. (2005), while it may further improve the registration accuracy, requires far longer computational time. It is, therefore, important to carefully evaluate the added benefit with respect to increased computational loads.

In conclusion, we evaluated an LDDMM-based normalization method by testing single- and two-contrast approaches using b_0 and FA contrasts, and these were applied to young adults and AD patients. Based on manual landmark-based measurements as gold standard, we found that the two-contrast (FA+ b_0) approaches can register the entire brain with higher spatial accuracy. The impact of a parameter that controls the elasticity of the transformation (α/γ) was also demonstrated. Using our brain atlas with 1 mm spatial resolution, the α/γ ratio of 0.01 provides conservative non-linear transformation. For brains with normal anatomy, an $\alpha/\gamma = 0.005$ should achieve a high degree of matching for the white matter structures. For brains with severe anatomical changes, the cascading approach, in a range of 0.01–0.001, is recommended.

Acknowledgments

The authors thank Mr. Joseph S. Gillen, Ms. Terri Brawner, Ms. Kathleen Kahl, and Ms. Ivana Kusevic for experimental assistance. This publication was made possible by grant numbers P41RR015241, U24RR021382, R01EB004130, MH071616, HL085343, and R01AG20012, and by the Johns Hopkins Alzheimer's Disease Research Center (P50AG005146). The National Center for Research Resources (NCRR) is a component of the National Institutes of Health (NIH). Its contents are solely the responsibility of the authors and do not necessarily represent the official view of NCRR or NIH. This research was supported by NIH grants. The images acquired on Alzheimer's patients were supported by a methods development grant from Glaxo-Smith-Kline. Equipment used in the study is manufactured by Philips. Dr. van Zijl is a paid lecturer for Philips Medical Systems. Dr. van Zijl is the inventor of technology that is licensed to Philips. This arrangement has been approved by Johns Hopkins University in accordance with its conflict of interest policies.

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Fig. 1.

Simple simulations to demonstrate the effect of the α/γ ratio, in which a circle of the 30pixel radius is transformed to the 40-pixel radius, (A) with varying α/γ ratios (B and C). In (B), transformations of a grid are shown to demonstrate the transformation effect. Note that with the low ratio, a large transformation is localized at the boundary of the circle where the contrast difference locates. In (C), the amount of pixel shift (as much as the radius difference=10 pixels) at each location across the diameter.



Fig. 2.

A flowchart for the surface-based measurement of registration accuracy. The brain and ventricle surfaces were defined by triangular meshes for the template and the normalized subject brains. Then distances between the closest triangle vertices of the two meshes were measured.



Fig. 3.

Simulation of transformation accuracy of LDDMM with a varying α/γ ratio. Circular objects with different degrees of sinusoidal perimeter modulation (frequency=10, 20, 30, and 40) are created from a circle. All objects have a radius of 40 pixels and the amplitude of the sinusoid is 5 pixels. After the LDDMM, the number of the mismatched pixels are counted and normalized by the mismatch before the LDDMM, which is shown in the graph.

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Fig. 4.

Transformation of a normal adult and a severely abnormal case (AD patient) with gradually decreasing α/γ ratios. For a visual clue, the outline of the white matter of the template is superimposed on the data. The color maps are Jacobian maps of the calculated LDDMM transformation from template to the subject. Voxel value in Jacobian map less than 1 (blue) indicates shrinkage and a value larger than 1 (red) indicates expansion. For example, the ventricle of the AD patient is red while the white matter is blue, indicating the enlarged ventricles and white matter atrophy.



Fig. 5.

Examples of transformation with small α/γ ratios (highly elastic transformation) with and without the cascading approach. Performing the highly elastic transformation directly on linearly registered images may lead to an inaccurate solution for severely abnormal brains, such as the AD case used in this demonstration.



Fig. 6.

Demonstration of LDDMM using an FA image only, a b_0 image only, and an FA + b_0 dual contrast. The upper and bottom rows show b_0 and FA images from the atlas (first column) and an AD patient (2nd–4th columns). The b_0 images carry a strong contrast for the tissue–CSF boundaries and the FA image shows strong contrast for the intra-white matter structures. These boundaries defined in the atlas (blue lines) are superimposed on the transformed AD patient images for visual clues.



Fig. 7.

Results of landmark-based accuracy measurements of LDDMM transformation of the white matter. The 237 landmarks were manually placed on the template and the subjects in the corresponding locations after three different types of LDDMM registration (FA only, b_0 only, and FA + b_0) and their distances were measured. Results from 13 normal subjects (A) and 18 AD patients (B) are shown. The results are presented as the cumulative population of landmarks as a function of distance. The red line represents the registration results after the affine normalization and before the LDMMM.



Fig. 8.

Measurements of surface-matching accuracy for the brain (A and B) and the ventricle (C and D). Images (A) and (C) show 3D maps of the residual difference after affine, b_0 -LDDMM, FA-LDDMM, and b_0 +FA-LDDMM transformation of the brain (A) and the ventricle (C) of AD patients (n = 13). The cumulative error histograms are also shown in (B) and (D) for the brain and the ventricle surfaces of the normal (n = 18) and the AD patients (n = 13).