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New Constructions of Non-Adaptive and Error-Tolerance Pooling
Designs

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Abstract

We propose two new classes of non-adaptive pooling designs. The first one is guaranteed to be d -error-detecting and thus $\lfloor \frac{d}{2} \rfloor$ -error-correcting given any positive integer d . Also, this construction induces a construction of a binary code with minimum Hamming distance at least $2d + 2$. The second design is the q -analogue of a known construction on d -disjunct matrices.

1 Introduction

The basic problem of group testing is to identify the set of defectives in a large population of items. We assume some testing mechanism exists which if applied to an arbitrary subset of the population gives a *negative outcome* if the subset contains no defective and *positive outcome* otherwise. Objectives of group testing vary from minimizing the number of tests, limiting number of pools, limiting pool sizes to tolerating a few errors. It is conceivable that these objectives are often contradicting, thus testing strategies are application dependent.

Group testing algorithms can roughly be divided into two categories : *Combinatorial Group Testing* (CGT) and *Probabilistic Group Testing* (PGT). In CGT, it is often assumed that the number of defectives among n items is equal to or at most d for some fixed positive integer d . In PGT, we fix some probability p of having a defective. Group testing strategies can also be either *adaptive* or *non-adaptive*. A group testing algorithm is non-adaptive if all tests must be specified without knowing the outcomes of other tests. A group testing algorithm is *error tolerant* if it can detect or correct some e errors in test outcomes. Test errors could be either $0 \rightarrow 1$, i.e. a negative pool is identified as positive, or $1 \rightarrow 0$ in the contrast.

In this paper, we propose two new classes of non-adaptive and error-tolerance CGT algorithms. Non-adaptive algorithms found its applications in a wide range of practical areas such as DNA library screening [2, 5] and multi-access communications [13], etc.

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For a general reference on CGT, the reader is referred to a monograph by Du and Hwang [6]. Ngo and Du [11] gave a survey on non-adaptive pooling designs.

The rest of the paper is organized as follows. Section 2 presents basic definitions, notations and related works. Section 3 provides our results and section 4 concludes the paper.

2 Preliminaries

Throughout this paper, for any positive integer v we shall use $[v]$ to denote $\{1, 2, \dots, v\}$. Also, given any set X and $k \in \mathbb{N}$ $\binom{X}{k}$ denotes the collection of all k -subsets of X .

2.1 The Matrix Representation

Consider a $v \times n$ 01-matrix M . Let R_i and C_j denote row i and column j respectively. Abusing notation, we also let R_i (resp. C_j) denote the set of column (resp. row) indices corresponding to the 1-entries. The *weight* of a row or a column is the number of 1's it has.

Definition 1 M is said to be d -disjunct if the union of any d columns does not contain another column.

A d -disjunct $v \times n$ matrix M can be used to design a non-adaptive group testing algorithm on n items by associating the columns with the items and the rows with the pools to be tested. If $M_{ij} = 1$ then item j is contained in pool i (and thus test i). If there are no more than d defectives and the test outcomes are error-free, then it is easy to see that the test outcomes uniquely identify the set of defectives. We simply identify the items contained in negative pools as *negatives* (good items) and the rest as *positives* (defected items). Notice that d -disjunct property implies that each set of $\leq d$ defectives corresponds uniquely to a test outcome vector, thus decoding test outcomes involves only a table lookup. The design of a d -disjunct matrix is thus also naturally called a *non-adaptive pooling design*. We shall use this term interchangeably with the long “non-adaptive combinatorial group testing algorithm”.

Let $S(\bar{d}, n)$ denotes the set of all subsets of n items (or columns) with size at most d , called the set of *samples*. For $s \in S(\bar{d}, n)$, let $P(s)$ denote the union of all columns corresponding to s , i.e. $P(s) = \bigcup_{i \in s} C_i$. A pooling design is e -error detecting (correcting) if it can detect (correct) up to e errors in test outcomes. In other words, if a design is e -error detecting then the test outcome vectors form a v -dimensional binary code with minimum Hamming distance at least $e + 1$. Similarly, if a design is e -error correcting then the test outcome vectors form a t -dimensional binary code with minimum Hamming distance at least $2e + 1$. The following remarks are simple to see, however useful later on.

Remark 1 Suppose M has the property that for any $s, s' \in S(\bar{d}, n)$, $s \neq s'$, $P(s)$ and $P(s')$ viewed as vectors have Hamming distance $\geq k$. In other words, $|P(s) \oplus P(s')| \geq k$

where \oplus denotes the symmetric difference. Then, M is $(k - 1)$ -error detecting and $\lfloor \frac{k-1}{2} \rfloor$ -error correcting.

Remark 2 M being d -disjunct is equivalent to the fact that for any set of $d + 1$ distinct columns C_{j_0}, \dots, C_{j_d} with one column (say C_{j_0}) designated, C_{j_0} has a 1 in some row where all C_{j_k} 's, $1 \leq k \leq d$ contain 0's.

2.2 Related Works

Previous works on error-tolerance designs are those of Aigner [1], Muthukrishnan [10], Balding and Torney [3] and Macula [9]. Aigner [1] and Muthukrishnan [10], discussed optimal strategies when $d = 1$ and the number of errors is small, although in a slightly more general setting where each test outcome could be q -ary instead of binary. Balding and Torney [3] studied several instances of the problem when $d \leq 2$. In some specific case, they showed that an optimal strategy is possible if and only if certain Steiner system exists. Macula [9] showed that his construction is error-tolerant with high probability.

On construction of disjunct matrices, the most well-known method is to construct the matrix from *set packing designs*. This method was introduced by Kautz and Singleton [7] in the context of superimposed codes. A t -(v, k, λ) packing is a collection \mathcal{F} of k -subsets of $[v]$ such that any t -subset of $[v]$ is contained in at most λ members of \mathcal{F} . By limiting $\lambda = 1$, we can construct a d -disjunct matrix from a t -($v, k, 1$) packing if $k > d(t - 1)$. Little is known about optimal set packing designs except for the case $t < 4$ (see, for example, [4, 11] for more details). Besides taking results directly from Design Theory, the only other work known on directly constructing d -disjunct matrices is that of Macula [8].

3 Main Results

We first describe our d -disjunct matrices. Given integers $m \geq k > d \geq 1$. A matching of size l (i.e. it has l edges) is called an l -matching.

Definition 2 Let $M(m, k, d)$ be the 01-matrix whose rows are indexed by the set of all d -matchings on K_{2m} , and whose columns are indexed by the set of all k -matchings on K_{2m} . All matchings are to be ordered lexicographically. $M(m, k, d)$ has a 1 in row i and column j if and only if the i^{th} d -matching is contained in the j^{th} k -matching.

For q being a prime power, let F_q denotes $GF(q)$. Let $\binom{F_q^m}{l}$ denotes the set of all l -dimensional subspaces (l -subspaces for short) of the m -dimensional vector space on F_q .

Definition 3 Let $M_q(m, k, d)$ be the 01-matrix whose rows (resp. columns) are indexed by elements of $\binom{F_q^m}{d}$ (resp. $\binom{F_q^m}{k}$). We also order elements of these set lexicographically. $M_q(m, k, d)$ has a 1 in row i and column j if and only if the i^{th} d -subspace is a subspace of the j^{th} k -subspace of F_q^m .

We now show that $M(m, k, d)$ and $M_q(m, k, d)$ are d -disjunct.

Theorem 1 *Let $g(m, l) = \binom{2m}{2l} \frac{(2d)!}{2^d d!}$, $v = g(m, d)$, and $n = g(m, k)$. For $m > k > d \geq 1$, $M(m, k, d)$ is a $v \times n$ d -disjunct matrix with row weight $g(m - d, k - d)$ and column weight $g(k, d)$.*

Proof. It is easy to see that $g(m, l)$ is the number of l -matchings of K_{2m} . Thus, $M(m, k, d)$ is a $v \times n$ matrix with row weight $g(m - d, k - d)$ and column weight $g(k, d)$.

To show $M(m, k, d)$ is d -disjunct, we recall Remark 2. Consider $d + 1$ distinct columns $C_{j_0}, C_{j_1}, \dots, C_{j_d}$ of $M(m, k, d)$. Since all these columns are distinct k -matchings, for each i , $1 \leq i \leq d$ there exists an edge $e_i \in C_{j_0} \setminus C_{j_i}$. Clearly, there exists a d -matching $R \subset C_{j_0}$ which contains all e_i 's. We simply add more edges in C_{j_0} to $\{e_i : 1 \leq i \leq d\}$ if necessary. Since $R \notin C_{j_i}$, $\forall i \in [d]$, C_{j_0} has a 1 in row R where all other C_{j_i} contains 0.

□

Theorem 2 *Let $\begin{bmatrix} m \\ l \end{bmatrix}_q := \frac{(q^m - 1)(q^{m-1} - 1) \dots (q^{m-l+1} - 1)}{(q^l - 1)(q^{l-1} - 1) \dots (q - 1)}$, $v = \begin{bmatrix} m \\ d \end{bmatrix}_q$, and $n = \begin{bmatrix} m \\ k \end{bmatrix}_q$. For $m > k > d \geq 1$, $M_q(m, k, d)$ is a $v \times n$ d -disjunct matrix with row weight $\begin{bmatrix} m-d \\ k-d \end{bmatrix}_q$ and column weight $\begin{bmatrix} k \\ d \end{bmatrix}_q$.*

Proof. It is standard that the Gaussian coefficient $\begin{bmatrix} m \\ l \end{bmatrix}_q$ counts the number of l -subspaces of \mathbb{F}_q^m (see, for example, Chapter 24 of [12]). The weight of any column C of $M_q(m, k, d)$ is the number of d -subspaces of C , hence it is $\begin{bmatrix} k \\ d \end{bmatrix}_q$. The weight w of any row R is the number of k -subspaces of \mathbb{F}_q^m which contains the d -subspace R . To show $w = \begin{bmatrix} m-d \\ k-d \end{bmatrix}_q$, we employ a standard trick (double counting). Let $I(m, k, d)$ be the number of ordered tuples (v_1, \dots, v_{k-d}) of $k - d$ vectors in $\mathbb{F}_q^m \setminus R$ such that each v_i is not in the span of R and other v_j 's, $j \neq i$. Notice that $|\mathbb{F}_q^m| = q^m$ and $|R| = q^d$. Counting $I(m, k, d)$ directly, there are $q^m - q^d$ ways to choose v_1 , then $q^m - q^{d+1}$ ways to choose v_2 and so on. Thus,

$$I(m, k, d) = (q^m - q^d)(q^m - q^{d+1}) \dots (q^m - q^{k-1}) \quad (1)$$

Now, (v_1, \dots, v_{k-d}) can be obtained by first picking a k -subspace C of \mathbb{F}_q^m which contains R in w ways, then (v_1, \dots, v_{k-d}) is chosen from $C \setminus R$ in $I(k, k, d)$ ways. This yields

$$I(m, k, d) = wI(k, k, d) \quad (2)$$

Combining (1) and (2) gives $w = \begin{bmatrix} m-d \\ k-d \end{bmatrix}_q$ as desired. The fact that $M_q(m, k, d)$ is d -disjunct can be shown in a similar fashion to the previous theorem.

□

The following lemma tells us how to choose k so that the test to item ratio $(\frac{v}{n})$ is minimized. The proof is easy to see and we omit it here.

Lemma 1 For $l \in [m]$, we have

- (i) The sequence $g(m, l)$ is unimodal and gets its peak at $l = \lfloor m - \sqrt{\frac{m+1}{2}} \rfloor$.
- (ii) The sequence $\begin{bmatrix} m \\ l \end{bmatrix}_q$ is unimodal and gets its peak at $l = \lfloor \frac{m}{2} \rfloor$.

The following results further explore properties of $M(m, k, d)$. We first need two more definitions.

Definition 4 Let C_0, C_1, \dots, C_d be any $d + 1$ distinct columns of $M(m, k, d)$. A d -matching R is said to be private for C_0 with respect to (wrt for short) C_1, \dots, C_d if $R \in C_0 \setminus \bigcup_{j \geq 1} C_j$. Let $p(C_0; C_1, \dots, C_d)$ denote the number of private d -matchings of C_0 wrt C_1, \dots, C_d .

Theorem 3 Given $m > d \geq 1$, and any set of $d + 1$ distinct columns C_0, C_1, \dots, C_d of $M(m, m, d)$, then $p(C_0; C_1, \dots, C_d) \geq d + 1$.

Proof. Observe that for $1 \leq j \leq d$, $C_0 \cup C_j$ is a loopless multigraph which is 2-regular. $C_0 \cup C_j$ consists of cycles with even lengths. Moreover, $C_0 \neq C_j$ implies that $C_0 \cup C_j$ must have a cycle of length at least $d + 1$; consequently, $|C_0 \setminus C_j| \geq 2, \forall j \in [d]$.

Let $E_i = C_0 \setminus C_i, i \in [d]$. We can assume $|E_i| = 2, \forall i$. We just remove edges from E_i to reduce its size to be exactly 2 for the ease of analysis. Let G be the graph with $V(G) = C_0, E(G) = \{E_1, \dots, E_d\}$. Then, G is a simple graph having m vertices and $\leq d$ edges. $|E(G)| \leq d$ because the E_i 's are not necessarily distinct. Any d -subset R of C_0 such that $R \cap E_i \neq \emptyset, \forall i$ is a private d -matching of C_0 . Note that R is nothing but a vertex cover of size d (d -cover for short) of G . To show $p(C_0; C_1, \dots, C_d) \geq d + 1$, we shall show that the number of d -covers of G is at least 4. Since adding more edges into G can only decrease the number of d -covers, we also assume that G has exactly d edges.

Decompose G into its connected components. Suppose G_1, \dots, G_x are connected components which are not trees, and G'_1, \dots, G'_y are the rest of the components. Isolated points are also considered to be trees. For $i = 1, \dots, x$, let $v_i = |V(G_i)|$ and $e_i = |E(G_i)|$. For $i = 1, \dots, y$, let $v'_i = |V(G'_i)|$ and $e'_i = |E(G'_i)|$. The following equations are straight from the definitions :

$$\sum_{i=1}^x v_i + \sum_{i=1}^y v'_i = m \quad (3)$$

$$\sum_{i=1}^x e_i + \sum_{i=1}^y e'_i = d \quad (4)$$

hence,

$$0 \leq \sum_{i=1}^x e_i - \sum_{i=1}^x v_i = y - (m - d) \quad (5)$$

Note that for any connected simple graph H , picking any $|V(H)| - 1$ vertices out of $V(H)$ gives us a vertex cover. Hence, the number of $(|V(H)| - 1)$ -covers of H is at least $\binom{|V(H)|}{|V(H)|-1} = |V(H)|$. Now, a d -cover of G could be formed by two methods as follows.

- (a) *Method 1.* For each $i \in [x]$, pick in v_i ways a $(v_i - 1)$ -cover for G_i , then cover all other G_j , $j \neq i$ with all their vertices. We have used up $(\sum_{i=1}^x v_i) - 1$ vertices, and need $d - (\sum_{i=1}^x v_i) + 1$ more to cover all G'_i 's. Firstly, there should be enough vertices. Indeed,

$$\sum_{i=1}^y v'_i = m - \sum_{i=1}^x v_i \geq d + 1 - \sum_{i=1}^x v_i$$

Secondly, to cover all G'_i 's, we need at most $\sum_{i=1}^y (v'_i - 1)$ vertices. (3) and (5) assure that

$$\sum_{i=1}^y (v'_i - 1) = m - \sum_{i=1}^x v_i - y < d + 1 - \sum_{i=1}^x v_i$$

In conclusion, this method gives us at least $(\sum_{i=1}^x v_i)$ d -covers for G .

- (b) *Method 2.* This time, we are greedier by first taking all vertices in G_i 's, $i \in [x]$ to cover them. $a = d - \sum_{i=1}^x v_i$ vertices are needed to cover the rest. These a vertices can be chosen as follows. For each $(m - d)$ -subset Y of $[y]$, cover each G'_i , $i \in Y$ with $v'_i - 1$ vertices. Cover each G'_i , $i \notin Y$ using all of its vertices. Indeed, the total number of vertices used is

$$\sum_{i \in Y} (v'_i - 1) + \sum_{i \notin Y} v'_i = \sum_{i \in [y]} v'_i - |Y| = (m - \sum_{i=1}^x v_i) - (m - d) = a$$

Moreover, obviously there are at least $\prod_{i \in Y} v'_i$ ways to pick d -covers for each particular Y . In total, noticing that $y \geq m - d \geq 1$, method 2 gives us at least

$$\begin{aligned}
\sum_{Y \in \binom{[y]}{m-d}} \prod_{i \in Y} v'_i &= \sum_{Y \in \binom{[y]}{m-d}} \prod_{i \in Y} (e'_i + 1) \\
&\geq \sum_{i=1}^y e'_i + \binom{y}{m-d} \\
&\geq \left(\sum_{i=1}^y v'_i - y \right) + (y - m + d + 1) \\
&= d + 1 - \sum_{i=1}^x v_i
\end{aligned}$$

Hence, Methods 1 and 2 combined yields at least $(d + 1)$ private d -matchings of C_0 . □

Corollary 1 *Given $m > d \geq 1$, the following holds :*

- (i) $M(m, m, d)$ is d -error detecting and $\lfloor \frac{d}{2} \rfloor$ -error correcting.
- (ii) Moreover, if the number of defectives is known to be exactly d , then $M(m, m, d)$ is $2d + 1$ -error-detecting and d -error-correcting.

Proof. For any $s, s' \in S(\bar{d}, n)$, $s \neq s'$, without loss of generality we can assume there exists $C_0 \in s \setminus s'$. Theorem 3 implies $|P(s) \oplus P(s')| \geq d + 1$, hence Remark 1 shows (i). If the number of defectives is exactly d , we need to only consider $|s| = |s'| = d$; hence there exists $C_0 \in s \setminus s'$ and $C'_0 \in s' \setminus s$. Again, Theorem 3 and Remark 1 yields (ii). □

Corollary 2 *Given $m > d \geq 1$, then there exists a binary d -error-correcting code of dimension $g(m, d)$ and size $\binom{g(m, m)}{d}$.*

Proof. The code can be constructed by taking all the unions of d columns in $M(m, m, d)$. □

Borrowing an idea from Macula [9], we get the following algorithm which uses $M(m, k, 2)$ for the at most d defective problem, and show that with very high probability, our algorithm gives the correct answer. Notice that each row of $M(m, k, 2)$ is a 2-matching consisting of some two parallel edges (e_1, e_2) of K_{2m} .

Algorithm 1 *Use $M(m, k, 2)$ to design the pools as usual. For each edge $e \in E(K_{2m})$ such that the total number of positive outcomes involving e is $k - 1$, i.e. $|\{(e, x) : \text{the test } (e, x) \text{ is positive}\}| = k - 1$, identify the item $C = \{e\} \cup \{x : (e, x) \text{ is positive}\}$ as a defective.*

Theorem 4 *Algorithm 1 gives correct answer with probability $p(m, k, d)$ where*

$$p(m, k, d) \geq \left[\frac{\sum_{j=1}^k (-1)^{j+1} \binom{k}{j} \left(\sum_{i=0}^j (-1)^i \binom{j}{i} g(m-i, k-i) \right)}{\binom{g(m, k)-1}{d-1}} \right]^d$$

For example, $p(8, 6, 9) \geq 98.5\%$, which means that we could use $M(8, 6, 2)$ to solve the at most 9 defectives problem with 98.5% of success.

Proof. Given a set of d distinct columns C_1, C_2, \dots, C_d . $e \in E(K_{2m})$ is called a mark of C_i if $e \in C_i$ but $e \notin C_j, j \neq i$, in which case C_i is called marked. If C_i is marked by e then exactly $k-1$ tests involving e and another edge in C_i is positive. Thus, algorithm 1 gives correct answer if the set of d defectives is a marked set, i.e. every element is marked.

The probability that algorithm 1 gives correct answer is thus the probability that a random d set of columns of $M(m, k, 2)$ is marked. For a fixed C_1 , there are $\binom{g(m, k)-1}{d-1}$ ways to pick the other $d-1$ columns. Let E_i be the event that C_i is marked relative to the other $d-1$ columns, then

$$p(m, k, d) = P(E_1)P(E_2|E_1)P(E_3|E_1, E_2) \dots \geq (P(E_1))^d$$

To calculate $P(E_1)$, we count number of ways to pick $d-1$ columns other than C_1 such that C_1 is marked by some $e \in C_1$. Let A_i be the collection of all $d-1$ -set of columns other than C_1 such that $e_i \in C_1$ marks C_1 with respect to A_i . The answer is then $|\bigcup\{A_i, 1 \leq i \leq k\}|$. This number can be obtained by applying inclusion-exclusion principle twice. Dividing it by $\binom{g(m, k)-1}{d-1}$ gives us $P(E_1)$ and proves the theorem. \square

4 Discussions

We have given the constructions of two different classes of pooling designs. $M(m, k, d)$ has good performance when the number of defectives is rare comparing to the number of items. Deterministically, a larger ratio of defectives to items is sometime preferred. Probabilistically, however, $M(m, k, 2)$ could be used to solve the $S(\bar{d}, n)$ problem with very high probability of success. The main strength of this construction is that $M(m, m, d)$ is d -error-detecting. It also yields the construction of a d -error-correcting code. $M_q(m, k, d)$ is the q -analogue of the construction given by Macula [8]. An interesting question is: “what is the q -analogue of a matching?”

One could think of several different variations of the matching idea. For example, a possible generalization is to index the rows (resp. columns) of a matrix $M(m, k, d, l)$ with all graphs having d (resp. k) edges whose vertex degrees are $\leq l$. $M(m, k, d)$ is nothing but $M(m, k, d, 1)$. Further investigations in this direction might lead to better designs.

Lastly, in reality given a specific problem with certain parameters, m and k has to be chosen appropriately to suit one's need. More careful analysis need to be done to help pick the *best* m and k given n , d and/or any other constraints from practice. We need some reasonably good asymptotic formulas to estimate them.

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