

# On the complexity of the primal self-concordant barrier method

Jan Brinkhuis

Econometrisch Instituut  
Erasmus Universiteit Rotterdam  
Postbus 1738  
3000 DR Rotterdam  
The Netherlands  
E-mail: brinkhuis@few.eur.nl

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## 1 Introduction

In his Introductory Lectures on Convex Programming Nesterov has given an algorithm to find the analytic centre  $x_F^*$  for a given  $\nu$ -self-concordant barrier  $F$  with bounded domain and a given interior point of this domain. The intended use of this algorithm is as an auxiliary phase in a primal short-step path-following method for solving convex programming problems. For the number of iterations in this auxiliary phase an upperbound is given in [N] which for  $\nu$  much bigger than 1 is essentially

$$7.2\sqrt{\nu} \left( \ln \nu + \frac{1}{2} \ln F'(y_0)^T F''(x_F^*)^{-1} F'(y_0) \right)$$

where  $T$  denotes transpose.

In this note it is shown that the term  $\ln \nu$  can be omitted. Moreover we make the easy observation that the constant 7.2 can be replaced by 3.2. The  $\ln \nu$ -improvement is achieved in the following way. Using certain inequalities from [N] we obtain a lower bound for the total decrease of the penalty parameter in the last two steps of the algorithm *which does not depend on  $\nu$* .

Concerning the constant 7.2 it is clear from [N] how it could be improved: by optimizing the choice of the centering parameter  $\beta$ . A routine optimization shows that  $\beta \approx 0.088$  gives the constant 3.2.

## 2 Statement of the result

In this paper we will use notations, definitions and results from chapter 4 of [N]. We begin by recalling from [N] a scheme to approximate an analytic centre; we use a slightly different stopping criterion. Let  $F$  be a  $\nu$ -self concordant barrier with bounded domain and let a point  $y_0$  in this domain be given. Choose a centering parameter  $\beta < \frac{3}{2} - \frac{1}{2}\sqrt{5} \approx 0.4$  and write  $\gamma = \frac{\sqrt{\beta}}{1+\sqrt{\beta}} - \beta$ . Then  $\gamma > 0$ . We consider the following scheme.

0. Set  $t_0 = 1$

1.  $k$ -th iteration ( $k \geq 0$ ). Set

$$t_{k+1} = \max\left(0, t_k - \frac{\gamma}{\|F'(y_0)\|_{y_k}^*}\right)$$

$$y_{k+1} = y_k - F''(y_k)^{-1}(-t_{k+1}F'(y_0) + F'(y_k))$$

2. Stop the process if  $t_k = 0$ . Set  $\bar{x} = x_k$  and  $N = k$ .

**Theorem 2.1.** *The scheme above terminates and*

$$N \leq 2 + \max\left[0, \frac{1}{\gamma}(\beta + \sqrt{\nu}) \ln\left(\frac{(1 + \sqrt{\beta})\|F'(y_0)\|_{x_F^*}^*}{\gamma(1 - \sqrt{\beta})}\right)\right]$$

*The vector  $\bar{x}$  which is the result of this scheme satisfies*

$$\|F'(\bar{x})\|_{\bar{x}}^* \leq \beta.$$

**Remark 2.2.** If  $\nu$ , the parameter of the barrier, is much bigger than 1, then it is 'optimal' to choose  $\beta$  such that  $\gamma = \gamma(\beta)$  is maximal. A routine calculation shows that this choice is  $\beta \approx 0.088$ , the unique real root of the equation  $4x^3 - 8x^2 + 12x - 1 = 0$ . Then  $\gamma = 0.317$  and so the upperbound in the theorem is essentially

$$3.2 \sqrt{\nu} \ln \|F'(y_0)\|_{x_F^*}^*.$$

### 3 Proof of the result

We write

$$\lambda(t, y) = [(-tF'(y_0) + F'(y))^T F''(y)^{-1} (-tF'(y_0) + F'(y))]^{\frac{1}{2}}$$

for all  $t \in \mathbb{R}$  and all  $y \in \text{dom } F$ . This is well-defined:  $\text{dom } F$  is bounded, so it contains no straight lines and so, by theorem 4.1.3. of [N] the hessian  $F''(y)$  is non- degenerate for all  $y \in \text{dom } F$ .

**Step 1**  $\lambda(t_k, y_k) \leq \beta$  for all  $k$  and  $\lambda(t_{k+1}, y_k) \leq \frac{\sqrt{\beta}}{1+\sqrt{\beta}}$  for all  $k$  with  $t_k > 0$ .

Start induction:  $\lambda(t_0, y_0)$  is seen to be 0.

Induction step: assume  $\lambda(t_k, y_k) \leq \beta$  for some  $k$  with  $t_k > 0$ . Then  $\lambda(t_{k+1}, y_k)$  is by the triangle inequality

$$\leq (t_k - t_{k+1}) \|F'(y_0)\|_{y_k}^* + \lambda(t_k, y_k).$$

This is  $\leq \frac{\sqrt{\beta}}{1+\sqrt{\beta}}$  as  $\lambda(t_k, y_k) \leq \beta$  and  $t_k - t_{k+1} \leq \frac{\gamma}{\|F'(y_0)\|_{y_k}^*}$ .

Applying theorem 4.1.12 of [N] we get

$$\lambda(t_{k+1}, y_{k+1}) \leq \left( \frac{\lambda(t_{k+1}, y_k)}{1 - \lambda(t_{k+1}, y_k)} \right)^2.$$

This is seen to be  $\leq \beta$  as

$$\lambda(t_{k+1}, y_k) \leq \frac{\sqrt{\beta}}{1 + \sqrt{\beta}}.$$

**Step 2**  $\|F'(y_0)\|_{y_k}^* \leq \frac{\beta + \sqrt{\nu}}{t_k}$  for all  $k$  with  $t_k > 0$ .

One has  $t_k \|F'(y_0)\|_{y_k}^* = \|-t_k F'(y_0) + F'(y_k) - F'(y_k)\|_{y_k}^*$ . By the triangle inequality this is  $\leq \lambda(t_k, y_k) + \|F'(y_k)\|_{y_k}^*$ . By  $\lambda(t_k, y_k) \leq \beta$  and the definition of self-concordant barriers this is  $\leq \beta + \sqrt{\nu}$ .

**Step 3.**  $t_k \leq \left(1 - \frac{\gamma}{\beta + \sqrt{\nu}}\right)^k$  for all  $k$  with  $t_{k+1} > 0$ .

Start induction:  $t_0 = 1$ .

Induction step: for all  $k$  with  $t_{k+1} > 0$ , we have  $t_k - \frac{\gamma}{\|F'(y_0)\|_{y_k}^*} > 0$ .

It follows that

$$t_{k+1} \leq \left(1 - \frac{\gamma}{\beta + \sqrt{\nu}}\right) t_k.$$

The rest is clear.

**Step 4.** The algorithm terminates and the resulting vector  $\bar{x}$  satisfies  $\|F'(\bar{x})\|_{\bar{x}}^* \leq \beta$ .

By Corollary 4.2.1 of [N] one has

$$\|F'(y_0)\|_{y_k}^* \leq (\nu + 2\sqrt{\nu})\|F'(y_0)\|_{x_F^*}^*.$$

Therefore for each  $k$  with  $t_{k+1} > 0$  one gets

$$t_k > \frac{\gamma}{(\nu + 2\sqrt{\nu})\|F'(y_0)\|_{x_F^*}^*}.$$

Combining this with step 3 it follows that the algorithm terminates, say after  $N$  iterations.

We write  $\bar{x} = y_N$ . Then  $t_N = 0$ , and  $\|F'(\bar{x})\|_{\bar{x}}^* = \lambda(t_N, y_N) \leq \beta$ .

**Step 5.**  $\|F'(y_0)\|_{y_{N-2}}^* \leq (1 + \sqrt{\beta})\|F'(y_0)\|_{y_{N-1}}^*$ .

By definition

$$y_{N-1} - y_{N-2} = -F''(y_{N-2})^{-1}(-t_{N-1}F'(y_0) + F'(y_{N-2})).$$

Taking the  $\|\cdot\|_{y_{N-2}}$  norm we get  $\|y_{N-1} - y_{N-2}\|_{y_{N-2}} = \|-t_{N-1}F'(y_0) + F'(y_{N-2})\|_{y_{N-2}}^*$ .

This is by definition  $\lambda(t_{N-1}, y_{N-2})$ ; this is  $\leq \frac{\sqrt{\beta}}{1+\sqrt{\beta}}$  by step 1.

This proves  $\|y_{N-1} - y_{N-2}\|_{y_{N-2}} \leq \frac{\sqrt{\beta}}{1+\sqrt{\beta}}$ .

Applying theorem 4.1.6. of [N] we get

$$F''(y_{N-1}) \preceq (1 - \|y_{N-1} - y_{N-2}\|_{y_{N-2}})^{-1}F''(y_{N-2}).$$

It follows, on taking inverses, that

$$F''(y_{N-2})^{-1} \preceq (1 + \sqrt{\beta})^2 F''(y_{N-1})^{-1}.$$

Therefore

$$\|F'(y_0)\|_{y_{N-2}}^* \leq (1 + \sqrt{\beta})\|F'(y_0)\|_{y_{N-1}}^*.$$

**Step 6.**  $\|F'(y_0)\|_{y_{N-1}}^* \leq (1 - \sqrt{\beta})^{-1}\|F'(y_0)\|_{x_F^*}^*$ .

By step 1  $\lambda(t_N, y_{N-1}) \leq \frac{\sqrt{\beta}}{1+\sqrt{\beta}}$ , so as  $t_N = 0$ , we get by theorem 4.1.11 of [N] that

$$\|y_{N-1} - x_F^*\|_{y_{N-1}} \leq \frac{\lambda(0, y_{N-1})}{1 - \lambda(0, y_{N-1})};$$

this is  $\leq \sqrt{\beta}$ . Therefore by theorem 4.1.6 of [N]

$$F''(x_F^*) \preceq (1 - \|y_{N-1} - x_F^*\|_{y_{N-1}})^{-2} F''(y_{N-1}).$$

It follows on taking inverses that

$$F''(y_{N-1})^{-1} \preceq (1 - \sqrt{\beta})^{-2} F''(x_F^*).$$

Therefore

$$\|F'(y_0)\|_{y_{N-1}}^* \leq (1 - \sqrt{\beta})^{-1} \|F'(y_0)\|_{x_F^*}^*.$$

**Step 7.**  $N \leq 2 + \max \left[ 0, \frac{1}{\gamma} (\beta + \sqrt{\nu}) \ln \left[ \frac{(1 + \sqrt{\beta}) \|F'(y_0)\|_{x_F^*}^*}{\gamma(1 - \sqrt{\beta})} \right] \right]$ .

On the one hand, by step 3

$$t_{N-2} \leq \left(1 - \frac{\gamma}{\beta + \sqrt{\nu}}\right)^{N-2}.$$

On the other hand, by  $t_{N-1} > 0$ , we have

$$t_{N-2} > \frac{\gamma}{\|F'(y_0)\|_{y_{N-2}}^*}.$$

Therefore by step 5 and 6 we get

$$t_{N-2} > \frac{(1 - \sqrt{\beta})\gamma}{(1 + \sqrt{\beta})\|F'(y_0)\|_{x_F^*}^*}.$$

Combining this upperbound and lowerbound for  $t_{N-2}$  gives an inequality; on taking the logarithm and on using the inequality  $\ln(1 + \tau) \leq \tau$  we get the required upperbound for  $N$ .

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## References

- [N] Nesterov, *Introductory Lectures on Convex Programming*, Volume I: Basic course, July 2, 1998 (to be published by Kluwer in 2001).