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European Journal of Operational Research 147 (2003) 146–155

EUROPEAN
JOURNAL
OF OPERATIONAL
RESEARCH

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O.R. Applications

On the distribution of calls in a wireless network driven by fluid traffic

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Received 7 June 2000; accepted 11 December 2001

Abstract

This note develops a modelling approach for wireless networks driven by fluid traffic models. Introducing traffic sets that follow movement of subscribers, the wireless network with time-varying rates is transformed into a stationary network at these traffic sets, which yields that the distribution of calls over the cells of the network depends on the call length distribution only through its mean. The result is extended to a network of infinite server queues with time-varying arrival rates.

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Keywords: Telecommunications; Traffic; Stochastic processes

1. Introduction

Wireless communications has been a rapidly growing service in the field of telecommunications. In contrast with this rapid growth, the capacity of wireless networks is severely restricted causing service degradation due to e.g. blocking or interruption of calls. Due to the cellular nature of wireless networks, these networks have been

modelled using queueing networks; a cell is represented as an Erlang loss queue, where the limited capacity of the wireless network is represented by the limited number of servers. Calls moving among the cells (handovers) are modelled as customers routing among the queues, see Massey and Whitt (1994).

The representation of a wireless network using the queueing network formulation is only partly valid, since

- (i) the exact location of a call on e.g. a road is required for interference,
- (ii) in a cellular network the call length is related to the call, whereas the service time of a customer in a queueing network is related to the queue.

When a call moves from one cell to another, the residual call length must be taken into account.

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¹ The research of Boucherie is partly supported by the Technology Foundation STW, Applied Science Division of NWO and the technology programme of the Ministry of Economic Affairs, The Netherlands.

Only under the assumption of exponentially distributed call lengths and holding times in the cells a standard queueing network formulation is justified as in this case the call length can be re-sampled upon a handover due to the memoryless property of the exponential distribution, see Everitt (1994). For general call lengths this is no longer correct as we have to explicitly deal with the residual call length of calls entering a cell, and for general holding times in the cells we have to explicitly take the location of the calls into account. This note investigates the effect of the call length distribution on the transient distribution of calls over the cells of the network, and presents *sufficient conditions for the call length to affect the distribution of calls over the cells only through its mean*.

A queueing model of a wireless network with calls extending over multiple cells was presented in Boucherie and Van Dijk (2000), where the network was characterized by the call length distribution and the call holding times in the cells. For stationary networks, the influence of the call length distribution on the distribution of the calls over the network was investigated. Typical wireless networks, however, have time-varying arrival rates, due to e.g. hot spots (with increased subscriber density) travelling along a road. As a result, arrival rates are non-stationary, and insensitivity results as obtained in Boucherie and Van Dijk (2000) do not apply. In addition, as observed in Massey and Whitt (1993), for networks of infinite server queues, where call holding times are related to the cell only (and the location of subscribers in the cell is not taken into account), it is shown that – already for a single infinite server queue modelling a single cell – the distribution of the number of calls in a cell depends on all moments of the holding time in the cell. By carefully modelling the precise subscriber location in the cell, mobility of subscribers, and the general call length distribution, this note demonstrates that the distribution of subscribers over the cells in networks with non-stationary arrival rates to the cells generated by a non-stationary Poisson process with rate determined by the density of subscribers in that cell is insensitive to the call length distribution.

First, to determine the exact location of subscribers, a fluid traffic model for subscriber mobility is investigated in detail. Rather than considering the location of subscribers on the *location space* Ω , e.g. a road or a set of roads, we consider the volume, Φ_t , under the density curve over this location space at time t . Subscribers are assumed to be randomly placed at locations inside this volume. Obviously, the projection of these user locations on Ω results in the distribution of subscribers over Ω at time t . We characterize (mobility of) subscribers via (movement of) subsets $\phi \subset \Phi_t$, referred to as *traffic sets*. Due to our modelling assumptions, that are shown to include standard traffic models, subscribers follow the path of the traffic sets.

Second, under the realistic assumption that calls follow the mobility of subscribers, the influence of the call length distribution is investigated. Here the traffic sets play an important role: due to our transformation, the process counting the number of active calls in a traffic set is stochastically equivalent to a stationary infinite server queue, which yields insensitivity with respect to the call length distribution. This insensitivity result is shown to carry over to the distribution of calls over the cells of the network that obviously do have time-varying arrival rates.

The resulting model is closely related to the Poisson arrival location model (PALM) introduced in Massey and Whitt (1993). The general PALM is not directly amenable for performance analysis, and further specification is required to obtain tractable models. In Massey and Whitt (1994) the PALM is applied to wireless networks, and in Leung et al. (1994) a fully Markovian setting is analyzed. In these references, in accordance with the queueing network approach, the distribution of the holding times in the cells is taken as the main distribution governing the behavior of the network. In contrast, this note provides an alternative specification of the PALM investigating the influence of the call length distribution on the distribution of calls over the cells of the network. Via a transformation of the process on the location space Ω into the traffic sets, a straightforward analysis of the influence of the call length distribution can be provided. This demonstrates

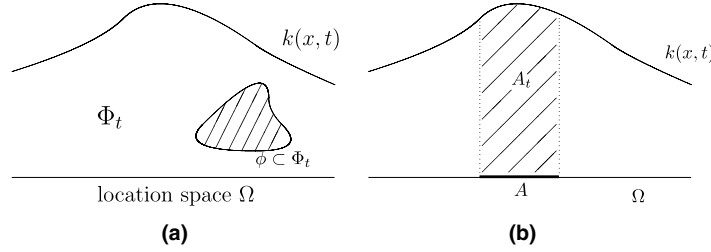


Fig. 1. (a) Traffic Φ_t at time t ; (b) traffic in cell A at time t .

that our modelling approach is suitable for performance analysis of wireless networks.

Here is the organization of this note. Section 2 presents our modelling approach for a network with deterministic subscriber mobility. Section 3 illustrates that this approach includes standard road traffic models. Based on the principle of mass conservation underlying the results of Section 2, Section 4 provides a closely related insensitivity result for networks of infinite server queues with time-varying arrival rates proportional to the number of subscribers in the queue. Under the assumption of exponential holding times in the queues and call lengths extending over multiple queues, it is shown that the distribution of calls over the cells depends on the general call length distribution only through its mean.

2. Model and main result

Consider a *location space* $\Omega \subset \mathbb{R}^m$. The distribution of subscribers over Ω is determined by the summable density $k : \Omega \times \mathbb{R} \rightarrow [0, \infty)$, i.e. $k(x, t)$ gives the mass of subscribers per unit space on location $x \in \Omega$ at time t . The density of subscribers changes in time according to a fluid traffic model. To this end, let

$$\Phi_t := \{(x, h); x \in \Omega, 0 \leq h \leq k(x, t)\} \subset \Omega \times \mathbb{R}$$

be the *traffic* at time t , i.e. Φ_t denotes the set under the graph of the density curve $k(x, t)$ at time t (see Fig. 1(a)). Movement of subscribers is modelled by movement of *traffic sets* $\phi \subset \Phi_t$. Of particular interest for wireless networks is the behavior of the traffic volume in a *cell* $A \subset \Omega$. Therefore, for any $A \subset \Omega$ we introduce the *traffic in cell A at time t*,

$$A_t := \{(x, h); x \in A, 0 \leq h \leq k(x, t)\} \subset \Phi_t,$$

and the *traffic mass in cell A at time t* (see Fig. 1(b))

$$V(A_t) = \int_A k(x, t) dx.$$

Similarly, for each $\phi \subset \Phi_t$ we introduce the mass $V(\phi)$ as the Euclidean volume of ϕ :

$$V(\phi) = \int_{\phi} 1[x \in \phi] dx,$$

where $1[E]$ denotes the indicator function of event E . Movement of subscribers is determined by the *traffic flow function*

$$L : \{(t, \phi, u); t \in \mathbb{R}, \phi \subset \Phi_t, u \in \mathbb{R}\} \rightarrow \Omega \times \mathbb{R},$$

where $L(t, \phi, u) \subset \Phi_u$ gives the position at time u of the traffic set $\phi \subset \Phi_t$ (see Fig. 2). Assume that the traffic flow function has the following properties, for $t, s, u \in \mathbb{R}$:

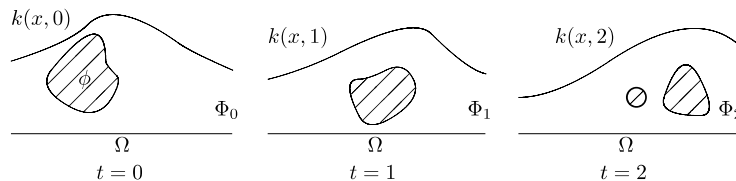


Fig. 2. $L(0, \phi, t)$ describes the evolution of the traffic set $\phi \subset \Phi_0$.

- L1 $L(t, \cdot, u) : \Phi_t \rightarrow \Phi_u$ is a bijection,
 L2 $L(s, L(t, \phi, s), u) = L(t, \phi, u)$ and $L(t, \phi, t) = \phi$ for all $\phi \subset \Phi_t$,
 L3 $V(\phi) = V(L(t, \phi, u))$ for all $\phi \subset \Phi_t$, i.e. the traffic flow function is volume preserving.

The assumptions on the traffic flow function imply that the system is closed, i.e. external arrivals and departures of subscribers to the system are excluded. In particular, applying L1, L2, and L3, for each $t, u \in \mathbb{R}$,

$$\int_{\Omega} k(x, t) dx = \int_{\Omega} k(x, u) dx.$$

External arrivals and departures can be included in the model by labelling a subset of Ω as ‘outside’ and then consider subscribers moving to and from ‘outside’ as departures and arrivals to the system, respectively.

In this paper we are interested in the distribution of calls over the cells of the network. Subscribers are assumed to generate *fresh calls* at random times, independent of their location and movement, and independent of other calls. More subscribers generate more calls and here it is assumed that this relation is linear. Fresh calls are generated uniformly over traffic. For any $A \subset \Omega$, arrival times of fresh calls to cell A form a Poisson process with non-stationary arrival rate

$$\lambda_A(t) := \alpha \int_A k(x, t) dx = \alpha V(A_t), \quad (1)$$

which is proportional to the density of subscribers in cell A at time t , where α is the arrival rate of fresh calls per unit mass of subscribers. For notational convenience the results below are restricted to a constant unit mass arrival rate α . As is indicated in Remark 4 the results can readily be extended to a non-stationary arrival rate $\alpha(t)$. The Poisson process of call arrivals to cell A corresponds to a Poisson arrival process to traffic sets $\{A_t; t \in \mathbb{R}\}$ in which calls arriving to cell A at time t are uniformly distributed over A_t . The fresh call arrival processes for disjoint cells $A, B \subset \Omega$ are independent.

A call remains active during a generally distributed period of time (the *call length*) S with distribution G and finite first moment $\tau := \mathbb{E}[S]$, independent of other calls, its location and gener-

ation time. A call generated in $\phi \subset \Phi_t$ at time t will move along Ω according to the traffic flow function L , independent of its call length and other active calls: if a call was generated by a certain subscriber, it will follow the path of this subscriber for the whole period it is active.

For a call generated at time t in $x \in \Phi_t$ we call the point $L(t, x, 0)$ its *owner*, i.e. it is the position of x at time 0. Due to L1 and L2, the path of each call through the system is uniquely determined by its arrival time, its owner and its call length. If a call is generated at time t with owner x and call length Δt , its path is a function $\ell : [t, t + \Delta t] \rightarrow \Omega \times [0, \infty)$, $\ell(u) = L(0, x, u)$, $t \leq u \leq t + \Delta t$. For each traffic set $\phi \subset \Phi_t$, let

$$L^\phi := \{(L(t, \phi, s), s); s \in \mathbb{R}\}$$

be its *trace* through the system. A traffic set $\hat{\phi}$ such that $(\hat{\phi}, u) \in L^\phi$ will be called *trace L^ϕ at time u* . Two important properties of traces are embodied in the following lemma.

Lemma 1. For $\phi \subset \Phi_t$ and $\hat{\phi}$ such that $(\hat{\phi}, u) \in L^\phi$ for some u , $L^\phi = L^{\hat{\phi}}$. For disjoint sets $\phi, \psi \subset \Phi_t$, for each u the sets $\hat{\phi}$ and $\hat{\psi}$ such that $(\hat{\phi}, u) \in L^\phi$ and $(\hat{\psi}, u) \in L^\psi$ are disjoint.

Proof. For $\phi \subset \Phi_t$ there is a unique set $\hat{\phi} = L(t, \phi, u)$ such that $(\hat{\phi}, u) \in L^\phi$. The first statement follows from the transitivity property L2. The second property follows from L1. \square

Lemma 1 states that each traffic set defines a unique trace and each trace determines at each time a unique traffic set. Furthermore disjoint traffic sets define traces that do not intersect at any time.

Lemma 1 offers a ground to define the following process based on a process of calls in the traffic. For a traffic set ϕ , consider the process $C_\phi = \{C_\phi(s); s \in \mathbb{R}\}$ counting the number of calls in trace L^ϕ : $C_\phi(s)$ gives the number of active calls present in trace L^ϕ at time s . A call generated by a subscriber in traffic set $\phi \subset \Phi_t$ follows its path, i.e. at time $s > t$ it will be in $L(t, \phi, s)$ assuming its call length exceeds $s - t$. Thus, calls generated in trace L^ϕ stay in L^ϕ for the whole activity period. Furthermore, for disjoint sets $\phi, \psi \subset \Phi_t$, calls generated in L^ϕ

never occur in L^ψ . However, as is pointed out in Section 3.2, our formulation also allows merging traffic flows.

Due to L3, the volume of traffic in trace L^ϕ is preserved throughout time. Therefore calls arrive to L^ϕ with Poisson rate

$$\hat{\lambda}_\phi = \alpha V(\phi),$$

while the period of time a call stays in L^ϕ is drawn from the call length distribution G . These observations lead to the following results for the transient behavior of the process \mathbf{C}_ϕ .

Theorem 2. Assume that time t_0 exists such that no active calls are present in Φ_{t_0} . For $\phi \subset \Phi_t$ and all $s \geq t_0$, $C_\phi(s)$ is Poisson distributed with finite mean

$$\mathbb{E}[C_\phi(s)] = \alpha V(\phi) \cdot (\mathbb{E}[S \mid S \leq s - t_0]G(s - t_0) + (s - t_0)(1 - G(s - t_0))). \quad (2)$$

Furthermore, for disjoint sets $\phi, \psi \subset \Phi_t$, the processes \mathbf{C}_ϕ and \mathbf{C}_ψ are independent.

Proof. The process \mathbf{C}_ϕ is stochastically equivalent to a process counting the number of busy servers in an $M/G/\infty$ queue with arrival rate $\hat{\lambda}_\phi = \alpha V(\phi)$ and i.i.d. service time distribution G which implies the Poisson distribution of $C_\phi(s)$, and

$$\begin{aligned} \mathbb{E}[C_\phi(s)] &= \mathbb{E}\left[\int_{\max\{s-S, t_0\}}^s \hat{\lambda}_\phi du\right] \\ &= \hat{\lambda}_\phi \mathbb{E}[s - \max\{s - S, t_0\}] \end{aligned}$$

(see e.g. Massey and Whitt, 1993; Keilson and Servi, 1994), hence (2). Lemma 1 argues that for any times s and u , $C_\phi(s)$ and $C_\psi(u)$ are independent for disjoint $\phi, \psi \subset \Phi_t$, which implies that the processes \mathbf{C}_ϕ and \mathbf{C}_ψ are independent. \square

Remark 3 (Initial conditions). The restrictions on the initial condition in Theorem 2 can be relaxed, see e.g. Keilson and Servi (1994). For example, if at time t_0 a Poisson random number of calls are generated uniformly over traffic Φ_{t_0} then Theorem 2 still holds true with an additional term in (2) depending on the intensity of initial distribution.

Remark 4 (Time-dependent fresh call arrivals). Call generation characteristics can readily be extended to a non-stationary setting as is the case when observing daily behavior of subscribers. For example, subscribers might generate less calls during early morning hours than during office hours, where business activities generate additional calls. To include this behavior into our setting, consider a time-dependent arrival rate of fresh calls per unit mass of subscribers $\alpha(t)$. For any traffic set ϕ , calls arrive to L^ϕ with Poisson rate

$$\hat{\lambda}_\phi(t) = \alpha(t)V(\phi).$$

The process \mathbf{C}_ϕ is stochastically equivalent to a process counting the number of busy servers in an $M_t/G/\infty$ queue with arrival rate $\hat{\lambda}_\phi(t)$ and i.i.d. service time distribution G which again implies a Poisson distribution for $C_\phi(s)$ with

$$\mathbb{E}[C_\phi(s)] = \mathbb{E}\left[\int_{\max\{s-S, t_0\}}^s \hat{\lambda}_\phi(u) du\right],$$

assuming no calls are present in traffic at time t_0 .

An important special case is $t_0 \rightarrow -\infty$, indicating that the system has been in operation long enough for the call characteristics to have reached equilibrium. We assume this is the case from this point on. Hence, for $\phi \subset \Phi_t$ and all s , $C_\phi(s)$ is Poisson distributed with finite mean

$$\mathbb{E}[C_\phi(s)] = \alpha V(\phi)\mathbb{E}[S].$$

While the call behavior in traces under the assumptions above is stationary, the mobility characteristics of the subscribers make the behavior of the load offered to the *cells* time-dependent. This behavior is studied below.

Consider cell $A \subset \Omega$. Let $\mathbf{D}_A = \{D_A(s); s \in \mathbb{R}\}$ be the process counting the number of active calls in cell A . The arrival rate of calls to cell A consists of fresh call arrivals with time-varying arrival rate $\lambda_A(t)$ of (1) and of handovers migrating into cell A from neighboring cells due to the mobility of subscribers following the flow function L . The distribution of $D_A(t)$ can now be obtained from the number of calls in the trace of A_t and the corresponding process \mathbf{C}_{A_t} as is apparent from relation

$$D_A(t) = C_{A_t}(t).$$

Corollary 5. For any positive integer k and any disjoint cells A^1, \dots, A^k , the random variables $D_{A^1}(t), \dots, D_{A^k}(t)$ are independent and Poisson distributed with finite means

$$\mathbb{E}[D_{A^i}(t)] = \lambda_{A^i}(t)\mathbb{E}[S], \quad i = 1, \dots, k, \quad t \in \mathbb{R}.$$

Proof. For disjoint cells A^1, \dots, A^k the corresponding traffic sets A_t^1, \dots, A_t^k at time t are disjoint as well. Theorem 2 implies that the distributions of $D_{A^i}(t)$, $i = 1, \dots, k$, are independent Poisson with means $\lambda_{A^i}(t)\mathbb{E}[S]$. \square

Observe that while for disjoint cells $A, B \subset \Omega$, the numbers of calls $D_A(t)$ and $D_B(t)$ are independent for a fixed t , the processes \mathbf{D}_A and \mathbf{D}_B are generally not independent.

The model studied in this section is a special case of the PALM introduced in Massey and Whitt (1993): a Poisson random measure on $\mathbb{R} \times \Phi_0 \times \mathbb{R}$ is determined by the arrival rate λ , homogeneity of calls over the traffic and the call length distribution. While Massey and Whitt (1993) studied the distribution of the number of calls in a cell of the wireless network with call holding time distribution related only to the cells (the classical queueing network approach), the special setting of our model enables us to study the influence of the call length distribution. In particular, as an immediate consequence of our modelling approach, we can conclude that when calls are homogeneously generated in traffic and subsequently follow the flow of traffic then the numbers of calls in disjoint traffic sets (or cells) are independent (at fixed time) and Poisson distributed with rate proportional to the mass of traffic in the sets, depending on the call length distribution only through its mean.

Remark 6 (Blocking of calls). The model analyzed above does not include blocking of calls such as naturally occurring in wireless networks due to their capacity restrictions. Our model is a step towards obtaining blocking probabilities for such networks that take into account time-varying rates due to customer mobility, and general call lengths. For example, the number of calls in the cells of our network with unlimited capacity clearly exceeds

that number in cells with finite capacity, where blocked calls are cleared from the network, see e.g. Stoyan (1983). Therefore, the probability that the number of subscribers exceeds K in the infinite server queue may be used to approximate the blocking probability in an Erlang loss queue with capacity K . Alternatively, approximations such as the modified offered load approximation, and the pointwise stationary approximation might be generalized to take into account the general call length distribution. These approximations use the relation in equilibrium between the infinite server queue and the Erlang loss queue as the basis for the approximation of the network of Erlang loss queues with time-varying rates via a truncation of the state distribution of the network with unlimited capacity. For details see Massey and Whitt (1993).

3. Examples and extensions

Section 3.1 demonstrates that the traffic flow model incorporates most of the standard traffic models and Section 3.2 considers superposition of flows.

3.1. Standard highway model

Consider a single lane road with cars that cannot overtake, see e.g. Lighthill and Whitham (1955) and Newell (1993) for a complete description. Following Newell (1993), let $A(x, t)$ be the cumulative number of vehicles to pass some location x by the time t , starting with the time of passage of some reference vehicle, that is a vehicle travelling along the road which passage is used as starting point for the observation of the road, e.g. the first vehicle that passes location 0 after time 0. Then, smoothing the curve of $A(x, t)$ such that it is twice differentiable, $A(x, t)$ determines the flow of traffic $q(x, t)$ through location x at time t , and the density of traffic $k(x, t)$ on location x at time t :

$$q(x, t) = \frac{\partial A(x, t)}{\partial t}, \quad k(x, t) = -\frac{\partial A(x, t)}{\partial x}.$$

The velocity $v(x, t)$ on location x at time t is obtained from

$$q(x, t) = k(x, t)v(x, t), \quad (3)$$

while differentiation of A yields the traffic mass conservation principle when there are no external departing or arriving flows:

$$\frac{\partial k(x, t)}{\partial t} + \frac{\partial q(x, t)}{\partial x} = 0. \quad (4)$$

For a subscriber on location x at time t , its trajectory $\chi(t, x, \cdot)$ is determined by a solution of the differential equation

$$\frac{dy}{du} = v(y, u), \quad y(t) = x.$$

Assuming v is continuous and differentiable, there is a unique solution for any pair $(x, t) \in \Omega \times \mathbb{R}$. Hence for any times t and u , $\chi(t, \cdot, u)$ is bijective and transitive. The mass preservation property

$$\int_U k(x, t) dx = \int_{\chi(t, U, u)} k(y, u) dy$$

for any cell $U \subset \mathbb{R}$ and any times t, u can be shown by applying conservation principle (4). The flow function L_χ corresponding to this setting is

$$L_\chi(t, (x, h), u) := \left(\chi(t, x, u), h \cdot \frac{k(\chi(t, x, u), u)}{k(x, t)} \right)$$

for any times $u, t \in \mathbb{R}$, and any position $(x, h) \in \Phi_t$, i.e. any location $x \in \Omega$ and any h with $0 \leq h \leq k(x, t)$. It can readily be shown that this flow function satisfies L1, L2 and L3.

3.1.1. Location independent velocity field

Consider the special case with all subscribers travelling at equal velocity, $v(x, t) \equiv v(t)$, $t \in \mathbb{R}$. Then

$$\chi(t, x, u) := x + \int_t^u v(s) ds.$$

The density now satisfies the relation

$$k(x, u) = k\left(x - \int_t^u v(s) ds, t\right).$$

The corresponding flow function is of a similar simple form:

$$L_\chi(t, (x, h), u) := \left(x + \int_t^u v(s) ds, h \right)$$

for any $u, t \in \mathbb{R}$, and any position $(x, h) \in \Phi_t$.

3.2. Superposition of flows

Consider two independent traffic streams on the same location space Ω with densities $k^1(x, t)$ and $k^2(x, t)$ and flow functions L^1 and L^2 . The total traffic is then obtained as the superposition of these flows. The joint traffic flow is determined by the joint traffic density $k(x, t) = k^1(x, t) + k^2(x, t)$, and the joint flow function L can be defined as

$$L(t, (x, h), u) := \begin{cases} L^1(t, (x, h), u), & h \leq k^1(x, t), \\ L^2(t, (x, h - k^1(x, t)), u) \\ \quad + (0, k^1(x, u)), & h > k^1(x, t), \end{cases}$$

for any times $u, t \in \mathbb{R}$, and any position $(x, h) \in \Phi_t$.

Flows on multi-lane roads, two-way highways and road junctions can be straightforwardly modelled by a superposition of flows. A single car can be described by a single flow with density having a limited support that keeps its shape throughout time. A superposition of a number of such traffic flows would describe traffic in detail. Further examples of a superposition of flows extend the model to general traffic networks. Another extension incorporating non-deterministic holding times is the queueing network in Section 4.

4. Networks of infinite server queues

This section provides an insensitivity result for networks of infinite server queues with time-varying arrival rates proportional to the number of subscribers in the queue. Although the result of this section does not build upon Section 2, it is based on the principle of mass conservation that is underlying the result of Section 2, which demonstrates the implications of arrival rates being proportional to the number of subscribers, and of calls following subscriber mobility. To mimic the setting of Section 2, for a network of infinite server queues we introduce a virtual traffic flow of subscribers to determine both customer arrival rates and customer mobility. Under the assumption of exponential holding times in the queues and call lengths extending over multiple queues, it is shown that the distribution of calls over the cells depends

on the general call length distribution only through its mean.

Consider a tandem network of infinite server queues, labelled $j = \dots, -1, 0, 1, \dots$. Customers arrive to queue j according to a non-homogeneous Poisson arrival process with arrival rate $\lambda_j(t)$. Assume that the arrival rate $\lambda_j(t)$ of customers is determined by a virtual traffic flow of subscribers moving among the queues. If this virtual flow travels with rate μ_j through queue j , then the arrival rate of customers in queue j changes according to

$$\frac{d\lambda_j(t)}{dt} = \mu_{j-1}\lambda_{j-1}(t) - \mu_j\lambda_j(t). \quad (5)$$

We say that the queueing network admits *service mass preservation* (SMP) when (5) holds for each queue j and each time t .

The holding times H_j of customers in queue j are i.i.d. exponentially distributed with mean μ_j^{-1} (naturally corresponding to the movement of the virtual traffic flow), independent of holding times in other queues and of the arrival process. The service requests S of customers extend over multiple queues and are i.i.d. with general distribution G , independent of the arrival process and of holding times in the queues: a customer stays in the network until his service is over, but might traverse a number of queues during his stay. As a consequence, with a customer two clocks are associated, one clock for his service request S (that is set upon arrival in the network, and which the customer takes with him when he moves around in the network), and one clock for his holding time in the queue in which he currently resides (this clock is set upon entry in the queue). Thus, a customer in queue j leaves this queue when either

1. his remaining service time is shorter than his holding time (the clock for his service time S expires before the clock for the holding time H_j expires, in which case the customer also immediately leaves the network), or
2. his holding time is shorter than his remaining service time (he routes to queue $j+1$, there drawing a new exponentially distributed holding time with mean μ_{j+1}^{-1} and his clock for the service time S continues).

Theorem 7 shows that the queue length process in the queueing network under SMP with random holding times in the queues satisfies a relation similar to that obtained in Corollary 5 for the cellular network. To this end, let $K_j(t)$ denote the number of customers in queue j at time t . Assume that $\mu_j^{-1} \geq \epsilon > 0$ for all j , and that $\lambda_j(t) \leq M$ for all j and all t . For simplicity we assume the network started empty at $t = -\infty$.

Theorem 7. *Consider the queueing network above satisfying service mass preservation (5). The distribution of number of customers in queue j at time t is Poisson with mean*

$$\mathbb{E}[K_j(t)] = \lambda_j(t)\mathbb{E}[S].$$

Proof. As the arrival process is Poisson with rates in (5) and customers move independently the analysis of Massey and Whitt (1993) applies and it remains to compute the mean $\mathbb{E}[K_j(t)]$. An explicit expression will be obtained similar to the proof of Corollary 5 by backward tracing of customers.

Let H_j^n denote the total random holding time of a customer from queue $j-n$ up to queue $j-1$,

$$H_j^n := \sum_{i=j-n}^{j-1} H_i,$$

with distribution $F_j^n(y)$ and $H_j^0 = 0$. Let $P_j^n(y)$ denote the probability that a customer originating in queue $j-n$ at some time u will be in queue j at time $u+y$ providing it has not yet terminated, that is

$$\begin{aligned} P_j^n(y) &:= \mathbb{P}[H_j^n + H_j \geq y, H_j^n \leq y] \\ &= F_j^n(y) - F_{j+1}^{n+1}(y), \end{aligned} \quad (6)$$

where $P_j^0(y) = 1 - F_j(y)$, and $P_j^{-1}(y) = 0$. Notice that $P_j^n(0) = 0$, $n \geq 1$, and $P_j^0(0) = 1$. $F_j^n(y)$ and $P_j^n(y)$ are continuous and continuously differentiable on $[0, \infty)$.

We will first show that for each j and $n \geq 0$,

$$\mu_{j-n}P_j^n(y) - \mu_{j-n}P_j^{n-1}(y) + \frac{d}{dy}P_j^n(y) = 0. \quad (7)$$

This is clear for $n = 0$. For $n \geq 1$, let $\phi_j^n(s) = \mathbb{E}[e^{-sH_j^n}]$, which exists for $\text{Re}(s) \geq 0$. As H_j^n is a sum

of independent exponentially distributed random variables,

$$\varphi_j^n(s) = \prod_{i=j-n}^{j-1} \frac{\mu_i}{s + \mu_i}, \quad \operatorname{Re}(s) \geq 0. \quad (8)$$

Taking the Laplace–Stieltjes transform in (7), using (6), we arrive at

$$\begin{aligned} \mu_{j-n} \left(\varphi_j^n(s) - \varphi_{j+1}^{n+1}(s) \right) - \mu_{j-n} \left(\varphi_j^{n-1}(s) - \varphi_{j+1}^n(s) \right) \\ + s \left(\varphi_j^n(s) - \varphi_{j+1}^{n+1}(s) \right) = 0 \end{aligned}$$

for all s , $\operatorname{Re}(s) \geq 0$. Inserting (8) into this expression allows us to conclude (7).

Now consider the arrival rate of customers from other queues into queue j ,

$$v_j(t, u) := \sum_{n=0}^{\infty} \lambda_{j-n}(t-u) P_j^n(u)$$

for some j and t , which is clearly finite since $\lambda_j(t-u) \leq M$ for every j for each u . The rate $v_j(t, u)$ is constant in u . To this end, observe that, using (5)

$$\begin{aligned} \frac{d}{du} v_j(t, u) &= \sum_{n=0}^{\infty} \left[-\mu_{j-n-1} \lambda_{j-n-1}(t-u) \right. \\ &\quad \left. + \mu_{j-n} \lambda_{j-n}(t-u) \right] P_j^n(u) \\ &\quad + \sum_{n=0}^{\infty} \lambda_{j-n}(t-u) \frac{d}{du} P_j^n(u) \\ &= \sum_{n=0}^{\infty} \lambda_{j-n}(t-u) \left[\mu_{j-n} P_j^n(u) \right. \\ &\quad \left. - \mu_{j-n} P_j^{n-1}(u) + \frac{d}{du} P_j^n(u) \right] \\ &= 0, \end{aligned}$$

where the last equality follows from (7) and we have used that all the sums are uniformly convergent, since $\mu_j \leq \epsilon$ for each i . Thus, for all j and any u, t ,

$$\sum_{n=0}^{\infty} \lambda_{j-n}(t-u) P_j^n(u) = v_j(t, 0) = \lambda_j(t). \quad (9)$$

We are now ready to calculate $\mathbb{E}[K_j(t)]$. With a random service time extending over multiple queues, $\mathbb{P}[H_j^n + H_j \geq u, H_j^n \leq u, S \geq u]$ gives the probability that a customer arriving to the system in queue $j-n$ is present in queue j after the time

period of u . Therefore, the expected number of customers arriving to the system in queue $j-n$ and present in cell j at time t is

$$\begin{aligned} \int_0^{\infty} \lambda_{j-n}(t-u) \mathbb{P}[H_j^n + H_j \geq u, H_j^n \leq u, S \geq u] du \\ = \int_0^{\infty} \lambda_{j-n}(t-u) P_j^n(u) \mathbb{P}[S \geq u] du. \end{aligned}$$

Summing this expression over all $n \geq 0$ yields the expected number of customers in queue j at time t . Thus, using (9)

$$\begin{aligned} \mathbb{E}[K_j(t)] &= \sum_{n=0}^{\infty} \int_0^{\infty} \lambda_{j-n}(t-u) P_j^n(u) \mathbb{P}[S \geq u] du \\ &= \lambda_j(t) \int_0^{\infty} \mathbb{P}[S \geq u] du = \lambda_j(t) \mathbb{E}[S]. \quad \square \end{aligned}$$

The result of Theorem 7 can readily be extended to a network of N infinite server queues labelled $j = 1, 2, \dots, N$, with exponential holding times H_j with mean μ_j^{-1} in queue j and general service time S extending over multiple queues where arrival process, holding times and service times are independent. A customer leaving queue j with positive remaining service time routes to queue i with probability p_{ji} in accordance with the mean virtual traffic flow, where $\sum_{i=1}^N p_{ji} = 1$. A customer leaving queue j due to completion of his service leaves the network.

Service mass preservation is expressed as

$$\frac{d\lambda_j(t)}{dt} = \sum_{i=1}^N \mu_i \lambda_i(t) p_{ij} - \mu_j \lambda_j(t), \quad j = 1, \dots, N. \quad (10)$$

Theorem 7 applies for any deterministic path through this network. Superposition of different paths can be extended to this setting which allows us to conclude the following result.

Theorem 8. *Consider the queueing network satisfying service mass preservation (10). The distribution of number of customers in queue j at time t is Poisson with mean*

$$\mathbb{E}[K_j(t)] = \lambda_j(t) \mathbb{E}[S].$$

Remark 9. Insensitivity results for infinite server queues in equilibrium are well-established. In contrast, the queue length distribution of infinite server queues with time-varying arrival rates depends in general on the service time distribution through all its moments, see e.g. Massey and Whitt (1993). Theorems 7 and 8 provide insensitivity results for a network with time-varying arrival rates. These results are due to the service mass preservation properties (5) and (10) describing the movement of subscribers among the queues. Service mass preservation mimics the properties of the traffic flow function, that allow for a transformation of the network with time-varying rates into a stationary setting, which shows that our network with time-varying arrival rates operates on the edge between transient networks and networks in equilibrium.

5. Conclusion

This paper has developed a modelling approach for wireless networks with subscriber movement driven by a fluid traffic that includes standard road traffic models. Through a transformation of the network characteristics to properties of the traffic sets, the distribution of calls over the cells of the network is shown to be a multi-dimensional Poisson distribution with time-varying mean that depends on the call length distribution (that extends over multiple cells) only through its mean. This result ignores capacity constraints and blocking of

calls, and is a step towards developing offered load approximations for wireless networks with time-varying arrival rates (such as e.g. due to a traffic jam moving along a road), and general call length distribution, which is our aim for further research.

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