Modeling Temporal Response Characteristics of V1 Neurons with a Dynamic Normalization Model

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Abstract

We present a dynamic normalization model to represent both the transient and the steady state components of V1 simple and complex cell responses. Primary receptive field properties are chiefly determined by the convergence of LGN afferents. These linear responses are rectified, and subjected to shunting inhibition through cortical feedback, which accounts for the non-linear characteristics of the neuronal responses. The duration of the transient response is determined by the time delay and the low-pass filtering of the cortical feedback. In addition to accounting for basic nonlinear behaviors such as response saturation and cross-orientation inhibition, the model is also able to reproduce several short-term contrast and pattern-selective adaptation effects.

Introduction

Normalization models have been used to account for various non-linear aspects of the steady-state responses of V1 simple and complex cells. In the simplest form of such a model, neural responses are computed by rectifying the responses of a set of oriented linear filters, and dividing each of these responses by the sum of the full set of responses [4]. Such a model can account for non-linear phenomena such as response saturation, cross-orientation suppression and contrast-dependent phase advance of simple cell responses. More recently, a pattern-selective normalization model, in which the divisive signal is a weighted sum of nearby neural responses, has been used to account for surround suppression [7]. None of these models, however, account for the dynamic temporal aspects of neural responses, such as transient responses after the onset or offset of stimuli, and short-term contrast and pattern-selective adaptation. If such effects are not within the scope of a functional description, it cannot meaningfully be connected with a more biophysically-detailed one. An earlier attempt at incorporating realistic temporal dynamics, successfully reproduced the typical transient response of an MT cell to a simple stimulus [5]. Here we propose a generalized normalization model that can capture a host of dynamical effects associated with V1 cells.

The model

The membrane potential is modeled through an RC-type circuit,

$$C \, \frac{dV_i(t)}{dt} + g_i(t)V_i(t) = I_i(t) \; , \qquad (1)$$

whose driving current is provided by the firing of LGN afferents [1, 2]. The membrane conductance $g_i(t)$ is modulated by intra-cortical interactions, and is chiefly responsible for gain-control effects associated with normalization. The constant membrane capacitance C, introduced in Ref. [1] to account for the observed contrast-dependent phase advance of simple

cell responses, is retained here. The neuron's instantaneous firing rate, $R_i(t)$, is obtained by half-wave rectification and squaring of the potential. For the case of modeling simple cell responses, the current $I_i(t)$ is represented by a linear sum of local stimulus contrasts filtered through a kernel that is the product of a spatial Gabor function and a causal temporal kernel with realistic parameter values. To obtain model complex cell responses, a quadrature pair of such filters is employed so as to render the input, $I_i(t)$, nearly independent of the overall spatio-temporal phase, à la energy models.

The various dynamical effects described here are attributable to the following functional dependence of the conductance,

$$g_i^2(t) = \{\, \overline{g^2}(t - \Delta t) \sum_j w_{ij} R_j(t - \Delta t) \,\}_{l.p.} + \sigma^2 \ , \tag{2}$$

where $\overline{g^2}$ indicates a uniform averaging of g^2 over the pool of neurons, Δt is the time-delay in cortical feedback, $l.p.$ denotes low-pass filtering, and σ^2 is the semi-saturation constant. The set of weights w_{ij} allow for pattern-selectivity of the normalization. If the model response represents that of a simple or complex cell, the corresponding pool consists entirely of model simple or complex cells, respectively. Since in the case of modeling simple cells, for each neuron its quadrature companion is weighted equally in the pool, the conductance, unlike the response, is independent of spatio-temporal phase. (Note that the phase independence can also be simulated by an averaging over phases or spatio-temporal locations.) For simplicity, the frequency tuning of the neurons in the pool are fixed in our simulations, but the orientation tunings are allowed to cover the entire range, and the weights follow a normal distribution given by,

$$w_{ij} = \exp\!\big(-\frac{2(\theta_i - \theta_j)^2}{\pi^2}\big) \ , \tag{3}$$

where θ denotes the preferred orientation (in radians). If the weights w_{ij} are taken to be uniform, the model reduces to a standard normalization model when in steady state, thus, encompassing the effects previously studied via normalization.

Results

Simulations of the model have so far been consistent with physiological data. Fig. 1 shows the response histogram of a directionally non-selective model complex cell to a stationary grating of optimal frequency and orientation lasting for 1.25 sec. It clearly shows a transient response followed by a sustained one. The duration of the transient is controlled by the time delay in cortical feedback, 0.05 sec in this case, and the time constant of the low-pass filtering, 0.1 sec. The response during the steady state is noticeably reduced compared to the peak of the transient response, because cortical feedback has instituted the normalization and, consequently, gain control. Transient characteristics can be explored further. Because normalization has not yet taken effect, the early stage of the transient response shows no sign of contrast saturation. Even so, the orientation tuning curve based on the average firing rate obtained from the first 0.5 sec of the response of the neuron of Fig. 1 is essentially identical in shape to that obtained from the steady-state portion of the response. This is evident from the normalized tuning curves in Fig. 2, supporting the inference made by Müller that orientation discrimination is as reliable during the transient stage as subsequently.

One can also examine response characteristics when combinations of gratings are presented either simultaneously or sequentially in time. Cross-orientation suppression refers to the suppression of the response to a stimulus moving in the preferred direction of the neuron if that stimulus is paired with one moving in an orthogonal direction. It has been shown previously that normalization provides a quantitative description of that effect during steady state. Correspondingly, in our model, this suppression is not displayed at the early stage of the transient response, when normalization is not yet operational. However, once normalization manifests itself during the transition from a transient response to the steady state, cross-orientation suppression becomes evident.

With the stimuli presented sequentially in time, adaptation and "forward masking" effects

may be explored. For example, Fig. 3 shows responses to a stationary grating with optimal parameters presented for 0.5 sec, followed by two similar probe gratings of 0.15 sec duration presented 0.2 sec and 2 sec after the adapting grating. The diminished response to the first probe shows rapid contrast adaptation, a gain-control effect. That this effect should fade by the time the second probe is presented, is determined by our choice values for the time-delay and low-pass filtering constants. These parameters dictate which part of the neuron's histogram is contributing to the normalization term. The figure is consistent with the data in Ref. [6].

Our model can also reproduce the pattern-specific adaptation reported in Ref. [6]. Fig. 4 shows the orientation-tuning curves of a complex cell in the model, before (continuous curve) and after (dashed curve) adaptation to a stationary grating. The grating, lasting for 0.5 seconds, has its orientation offset from the optimal one for the cell by 14 degrees. Beyond the overall diminishing of the response, there is the relative suppression in the neighborhood of the adapting orientation. The model predicts that this "rapid adaptation" effect will not be evident during the interval (roughly 0.02 sec) immediately following the onset of the probe stimulus. Furthermore, this effect is present even if the weights w_{ij} in Eq. 2 were chosen to be uniform. It arises due to the underlying dynamics of the normalization model. This is in contrast to recent accounts of such stimulus-specific adaptation in which the feedback (normalization) weights are adjusted according to image statistics [8] or short-term synaptic depression [3].

Summary

We have generalized the basic normalization model in a rather simple manner to account for the time course of V1 neuronal responses. Our model extends the range of observed non-linear behaviors encompassed by such a functional description and advances a step toward a more biophysical account of these mechanisms. But we have not yet determined a biophysically-

detailed explanation, and the particular choice in Eq. 2 is somewhat ad-hoc. However, it can be shown mathematically that extending normalization models to incorporate pattern-selectivity is fairly constrained based on the steady-state responses they generate. It appears, then, that incorporating both biophysical and mathematical constraints should narrow the field of candidate models considerably. Our model can be further tested in a variety of ways, such as to what extent the myriad of effects observed in steady state carry over to the transient portion of the response.
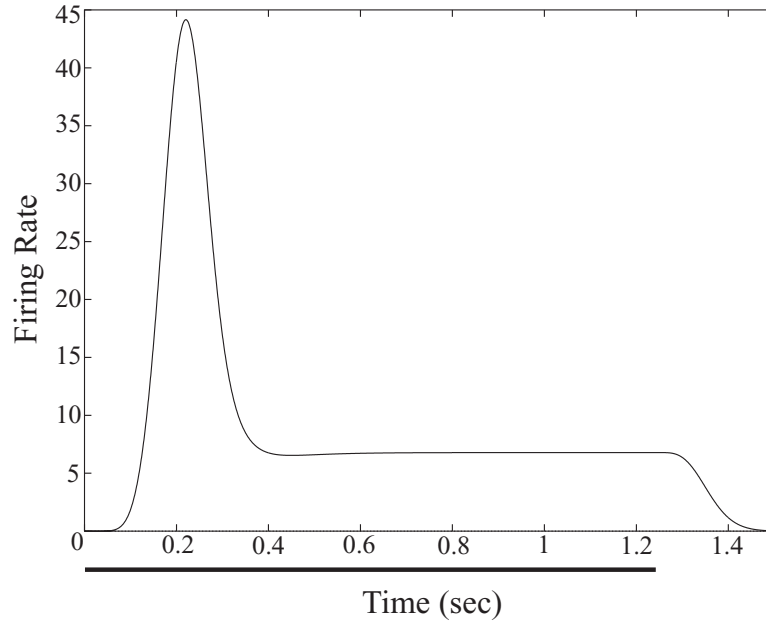
Figure 1: Response histogram of a directionally non-selective model complex cell to a stationary grating of optimal frequency and orientation lasting for 1.25 sec. The time delay for cortical feedback is 0.05 sec and the time constant of low-pass filtering is 0.1 sec. The time course of the stimulus is traced (heavy line) below the graph.
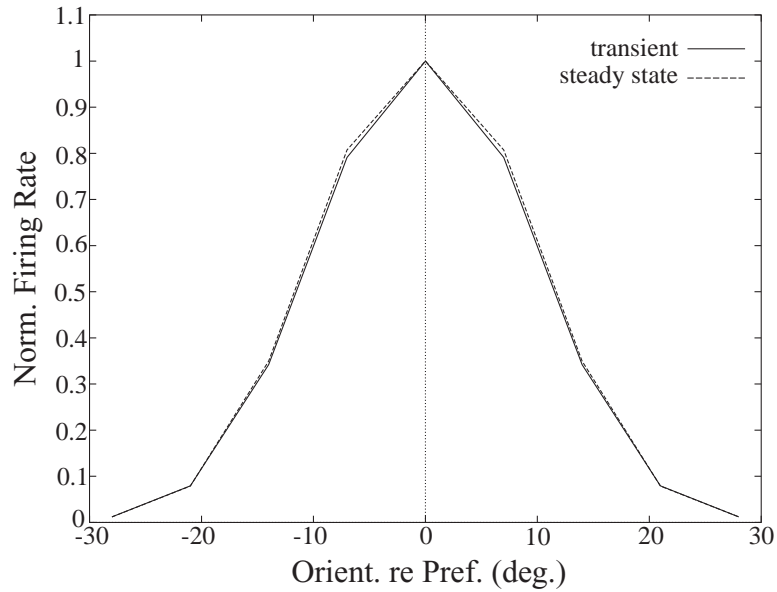

Figure 2: Normalized orientation tuning curves of the neuron of Fig. 1. The continuous and dashed curves correspond to the average response during the first 0.5 sec and the subsequent portion of the histogram, respectively. The curves have been normalized such that their peak values are at one.
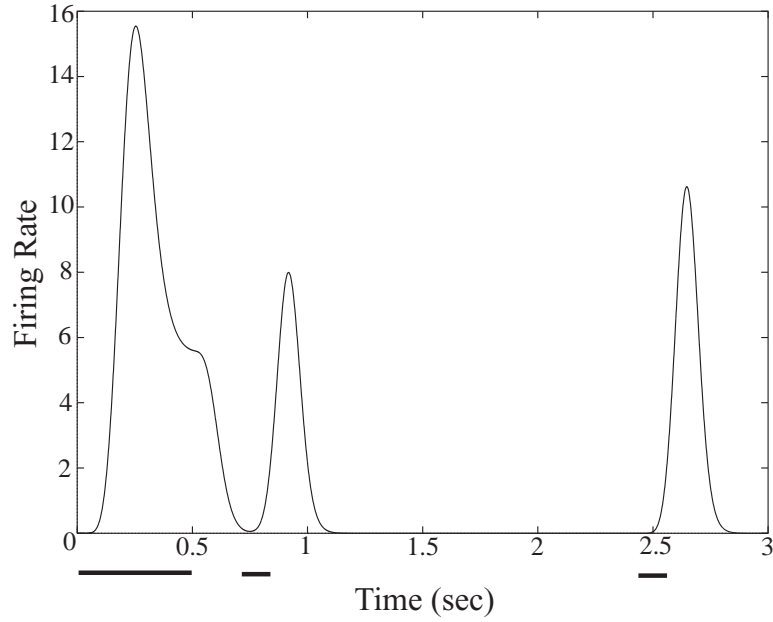
Figure 3: Response histogram of the neuron described in Fig. 1 to a stationary adapting grating presented for 0.5 sec, followed by two probe gratings 0.2 sec and 2.0 sec later, respectively, lasting for 0.15 sec each. All stimuli have optimal frequency and orientation. The time course of the stimulus is traced (heavy line) below the graph.
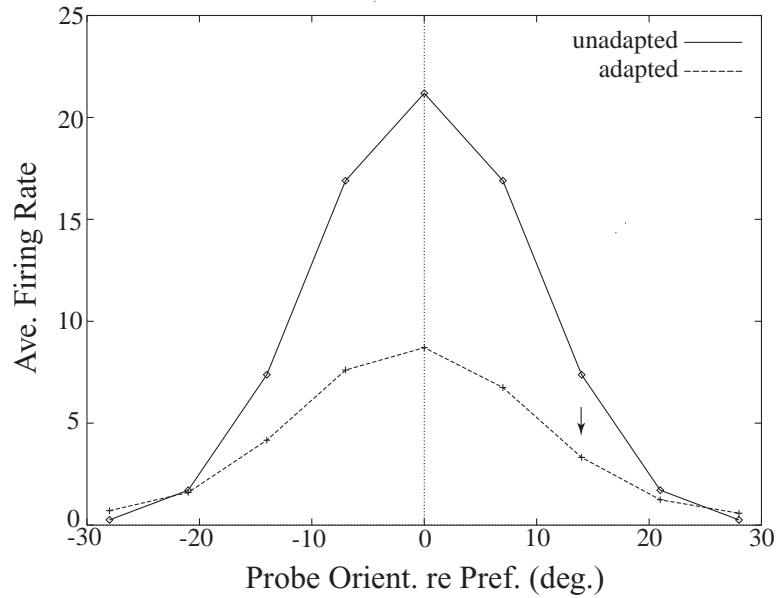

Figure 4: Orientation tuning curves of the neuron described in Fig. 1 before (continuous curve) and 0.2 sec after (dashed curve) rapid adaptation to a stationary grating. The orientation of the adapting stimulus, which lasts for 0.5 sec is indicated by the arrow.

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