

# Convergence analysis of a family of 14-node brick elements \*

Zhaoliang Meng<sup>†a</sup>, Zhongxuan Luo<sup>a,b</sup>, Dongwoo Sheen<sup>c,d</sup>, and Sihwan Kim<sup>c</sup>

<sup>a</sup>*School of Mathematical Sciences, Dalian University of Technology, Dalian, 116024, China*

<sup>b</sup>*School of Software, Dalian University of Technology, Dalian, 116620, China*

<sup>c</sup>*Department of Mathematics, Seoul National University, Seoul 151-747, Korea.*

<sup>d</sup>*Interdisciplinary Program in Computational Sciences & Technology, Seoul National University, Seoul 151-747, Korea.*

November 10, 2021

## Abstract

In this paper, we will give a convergence analysis for a family of 14-node elements which was proposed by I. M. Smith and D. J. Kidger [Int. J. Numer. Meth. Engng., 35:1263–1275, 1992]. The 14 DOFs are taken as the values at the eight vertices and the six face-centroids. For second-order elliptic problems, we will show that among all the Smith-Kidger 14-node elements, Type 1, Type 2 and Type 5 elements provide optimal-order convergent solutions while Type 6 element gives one-order lower convergent solutions. Motivated by our proof, we also find that the order of convergence of the Type 6 14-node nonconforming element improves to be optimal if we change the DOFs into the values at the eight vertices and the integration values on the six faces. We also show that Type 1, Type 2 and Type 5 keep the optimal-order convergence if the integral DOFs on the six faces are adopted.

**Keywords:** Nonconforming element; Brick element; 14-node element; Second-order elliptic problem; Smith-Kidger element

## 1 Introduction

Among many three-dimensional brick elements, there have been well-known simplest conforming elements such as the trilinear element, the 27-node element and seredipity

---

\*This project is supported by NNSFC (Nos. 11301053, 61033012, 19201004, 11271060, 61272371), “the Fundamental Research Funds for the Central Universities”. Also partially supported by NRF of Korea (Nos. 2011-0000344, F01-2009-000-10122-0).

<sup>†</sup>Corresponding author: mzhl@dlut.edu.cn

elements. For the nonconforming case, Rannacher-Turek [7] presented the rotated trilinear elements with the two types of 6 DOFs: the face-centroid values type and the face integrals type. Douglas-Santos-Sheen-Ye [2] then modified the element of Rannacher-Turek such that the face-centroid values type and the face integrals type are identical, that is, the element fulfills the mean value property “the face-centroid value = the face average integral”. Later Park-Sheen presented a  $P_1$ -nonconforming finite element on cubic meshes which has only 4 DOFs [6]. Wilson also defined a linear-order nonconforming brick element [1, 15] with 11 DOFs whose polynomial space consists of trilinear polynomials plus  $\{1 - x_1^2, 1 - x_2^2, 1 - x_3^2\}$  on  $\widehat{\mathbf{K}} = [-1, 1]^3$  (see [1, Page 217, Remark 4.2.3]). All these three dimensional elements are of  $O(h)$  convergence rate in energy norm.

In the direction of obtaining higher-order convergent nonconforming elements, Smith and Kidger [12] successfully developed three-dimensional brick elements of 14 DOFs by adding additional polynomials to  $P_2$ . They investigated six most possible 14 DOFs elements systematically considering the Pascal pyramid, and concluded that their Type 1 (as well as Type 2) and Type 6 elements are successful ones. The additional polynomial space for Type 1 element is the span of the four nonsymmetric cubic polynomials  $\{x_1x_2x_3, x_1^2x_2, x_2^2x_3, x_3^2x_1\}$  while that for Type 6 element is the span of  $\{x_1x_2x_3, x_1x_2^2x_3^2, x_1^2x_2x_3^2, x_1^2x_2^2x_3\}$ . Only recently a new nonconforming brick element of 14 DOFs with quadratic and cubic convergence in the energy and  $L_2$  norms, respectively, is introduced by Meng, Sheen, Luo, and Kim [5], which has the same type of DOFs but has only cubic polynomials added to  $P_2$ . And then, the authors compared these 14-node elements numerically, see [4]. Numerical tests show that at least for second-order elliptic problems Meng-Sheen-Luo-Kim and some of Smith-Kidger elements are convergent with optimal order or with lower order.

A convergence analysis for Meng-Sheen-Luo-Kim element was reported in [5] and is fairly easy because it satisfies the patch test of Irons [3], which implies that a successful  $P_k$ -nonconforming element needs to satisfy that on each interface the jump of adjacent polynomials be orthogonal to  $P_{k-1}$  polynomials on the interface. Unfortunately, it was found in mathematics that the patch test is neither necessary nor sufficient, see [9] and the references therein. As shown in this paper, the Smith-Kidger elements can only pass a lower order patch test or can not pass it, but give optimal order convergence from our numerical results or lower convergence order. Thus, the convergence analysis for Smith-Kidger element seems to be quite different and complex. For the convergence of the nonconforming element which fail to pass the patch test, see the works of Stummel, Shi, *etc.* [14, 8, 10, 11].

In this paper, we will provide a convergence analysis for Smith-Kidger elements for second-order elliptic problems. We show that although the patch test fails, Type 1, 2 and 5 Smith-Kidger elements are of optimal convergence order, while Type 6 element loses one order of accuracy. Furthermore, we also present a new brick element with the same DOFs, which is also convergent in optimal orders. Finally, if the value at the eight vertices and the integration values over six faces are taken as the DOFs, then we can show that Type 1, 2, 5, and 6 elements and the proposed new element can get optimal convergence order, which implies that Type 6 element improves one order of accuracy.

The paper is organized as follows. In Section 2, we will introduce Smith-Kidger

elements and give the basis functions firstly. In Section 3, we define an interpolation operator and present our convergence analysis for Type 1 Smith-Kidger element. In Section 4, we will analyze the other elements and present the corresponding error estimates very briefly. In Section 5, a new 14-node brick element is proposed. Finally, in Section 6, we conclude our results.

## 2 The quadratic nonconforming brick elements

Let  $\widehat{\mathbf{K}} = [-1, 1]^3$  and denote the vertices and face-centroids by  $V_j, 1 \leq j \leq 8$ , and  $M_k, 1 \leq k \leq 6$ , respectively. (see Fig. 1)

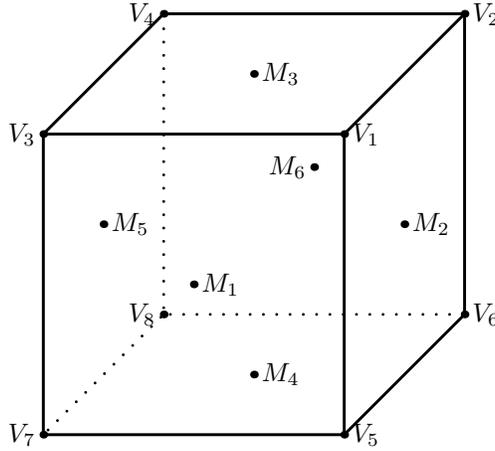


Figure 1:  $V_j$  denotes the vertices,  $j = 1, 2, \dots, 8$ , and  $M_k$  denotes the face-centroids,  $k = 1, 2, \dots, 6$ .

Smith and Kidger [12] defined the following six 14-node elements:

$$\widehat{\mathbb{P}}_{SK}^{(1)} = P_2(\widehat{\mathbf{K}}) \oplus \text{Span}\{\widehat{x}_1\widehat{x}_2\widehat{x}_3, \widehat{x}_1^2\widehat{x}_2, \widehat{x}_2^2\widehat{x}_3, \widehat{x}_3^2\widehat{x}_1\}, \quad (1a)$$

$$\widehat{\mathbb{P}}_{SK}^{(2)} = P_2(\widehat{\mathbf{K}}) \oplus \text{Span}\{\widehat{x}_1\widehat{x}_2\widehat{x}_3, \widehat{x}_1\widehat{x}_2^2, \widehat{x}_2\widehat{x}_3^2, \widehat{x}_3\widehat{x}_1^2\}, \quad (1b)$$

$$\widehat{\mathbb{P}}_{SK}^{(3)} = P_2(\widehat{\mathbf{K}}) \oplus \text{Span}\{\widehat{x}_1\widehat{x}_2\widehat{x}_3, \widehat{x}_1^3, \widehat{x}_2^3, \widehat{x}_3^3\}, \quad (1c)$$

$$\widehat{\mathbb{P}}_{SK}^{(4)} = P_2(\widehat{\mathbf{K}}) \oplus \text{Span}\{\widehat{x}_1\widehat{x}_2\widehat{x}_3, \widehat{x}_1^2\widehat{x}_2\widehat{x}_3, \widehat{x}_1\widehat{x}_2^2\widehat{x}_3, \widehat{x}_1\widehat{x}_2\widehat{x}_3^2\}, \quad (1d)$$

$$\widehat{\mathbb{P}}_{SK}^{(5)} = P_2(\widehat{\mathbf{K}}) \oplus \text{Span}\{\widehat{x}_1\widehat{x}_2\widehat{x}_3, \widehat{x}_1^2\widehat{x}_2 + \widehat{x}_1\widehat{x}_2^2, \widehat{x}_2^2\widehat{x}_3 + \widehat{x}_2\widehat{x}_3^2, \widehat{x}_3^2\widehat{x}_1 + \widehat{x}_3\widehat{x}_1^2\}, \quad (1e)$$

$$\widehat{\mathbb{P}}_{SK}^{(6)} = P_2(\widehat{\mathbf{K}}) \oplus \text{Span}\{\widehat{x}_1\widehat{x}_2\widehat{x}_3, \widehat{x}_1\widehat{x}_2^2\widehat{x}_3, \widehat{x}_1^2\widehat{x}_2\widehat{x}_3, \widehat{x}_1\widehat{x}_2^2\widehat{x}_3\}, \quad (1f)$$

whose DOFs are the function values at the eight vertices and the six face-centroids. They reported that Type 3 element fails and is inadmissible. We also remark that Type 4 element is also inadmissible since  $(\widehat{x}_1^2 - 1)\widehat{x}_2\widehat{x}_3 \in \widehat{\mathbb{P}}_{SK}^{(4)}$  vanishes at all these points. In [4], we observe that Type 1 (and 2) and Type 5 elements give optimal convergence results both in  $L^2$ - and  $H^1$ -norms at least for second-order elliptic problems, while Type 6 element loses one order of accuracy in each norm.

In what follows, we will give an error estimate for Type 1 Smith-Kidger element in detail; error estimates for the other types can be obtained completely analogously and thus are stated very briefly.

To begin with, denote by  $V_m, m = 1, \dots, 8$ , the eight vertices  $(j, k, l), |j| = |k| = |l| = 1, j, k, l \in \mathbb{Z}$ , and and by  $V_m, m = 1, \dots, 6$ , the six face-centroids  $(j, k, l), |j| + |k| + |l| = 1, j, k, l \in \mathbb{Z}$ . The basis functions corresponding to the eight vertices  $V_j, j = 1, \dots, 8$ , are denoted by  $\widehat{\phi}_{V_j}^V$ , and those corresponding to the six face-centroids by  $\widehat{\phi}_{M_j}^F, j = 1, \dots, 6$ .

To describe the brick elements in a uniform fashion, set

$$\begin{aligned} r_0(\widehat{x}_1, \widehat{x}_2, \widehat{x}_3) &= \widehat{x}_1 \widehat{x}_2 \widehat{x}_3, \quad r_1(\widehat{x}_1, \widehat{x}_2, \widehat{x}_3) = \widehat{x}_1 \widehat{x}_3^2, \\ r_2(\widehat{x}_1, \widehat{x}_2, \widehat{x}_3) &= \widehat{x}_2 \widehat{x}_1^2, \quad r_3(\widehat{x}_1, \widehat{x}_2, \widehat{x}_3) = \widehat{x}_3 \widehat{x}_2^2, \end{aligned} \quad (2)$$

so that

$$\widehat{\mathbb{P}}_{SK}^{(1)} = P_2(\widehat{\mathbf{K}}) \oplus \text{Span}\{r_0(\widehat{x}_1, \widehat{x}_2, \widehat{x}_3), r_1(\widehat{x}_1, \widehat{x}_2, \widehat{x}_3), r_2(\widehat{x}_1, \widehat{x}_2, \widehat{x}_3), r_3(\widehat{x}_1, \widehat{x}_2, \widehat{x}_3)\}.$$

Then the basis functions for Type 1 Smith-Kidger elements are given as follows: for  $(j, k, l) = V_m, m = 1, \dots, 8$ ,

$$\begin{aligned} \widehat{\phi}_{(j,k,l)}^V(\widehat{x}_1, \widehat{x}_2, \widehat{x}_3) &= \frac{1}{16} [-1 + \widehat{x}_1^2 + \widehat{x}_2^2 + \widehat{x}_3^2] + \frac{1}{8} [jk\widehat{x}_1\widehat{x}_2 + jl\widehat{x}_1\widehat{x}_3 + kl\widehat{x}_2\widehat{x}_3 \\ &\quad + jklr_0(\widehat{x}_1, \widehat{x}_2, \widehat{x}_3) + r(\widehat{x}_1, \widehat{x}_2, \widehat{x}_3)], \end{aligned} \quad (3)$$

and, for  $(j, k, l) = M_m, m = 1, \dots, 6$ ,

$$\widehat{\phi}_{(j,k,l)}^F(\widehat{x}_1, \widehat{x}_2, \widehat{x}_3) = \frac{1}{4} + \frac{1}{2}\ell(\widehat{x}_1, \widehat{x}_2, \widehat{x}_3) + \frac{1}{4}q(\widehat{x}_1, \widehat{x}_2, \widehat{x}_3) - \frac{1}{2}r(\widehat{x}_1, \widehat{x}_2, \widehat{x}_3), \quad (4)$$

where the linear, quadratic, and the remaining higher-order terms are defined by

$$\ell(\widehat{x}_1, \widehat{x}_2, \widehat{x}_3) = j\widehat{x}_1 + k\widehat{x}_2 + l\widehat{x}_3, \quad (5a)$$

$$q(\widehat{x}_1, \widehat{x}_2, \widehat{x}_3) = -(\widehat{x}_1^2 + \widehat{x}_2^2 + \widehat{x}_3^2) + 2(j\widehat{x}_1^2 + k\widehat{x}_2^2 + l\widehat{x}_3^2), \quad (5b)$$

$$r(\widehat{x}_1, \widehat{x}_2, \widehat{x}_3) = jr_1(\widehat{x}_1, \widehat{x}_2, \widehat{x}_3) + kr_2(\widehat{x}_1, \widehat{x}_2, \widehat{x}_3) + lr_3(\widehat{x}_1, \widehat{x}_2, \widehat{x}_3). \quad (5c)$$

Assume that  $\Omega \in \mathbb{R}^3$  is a parallelepiped domain with boundary  $\Gamma$ . Let  $(\mathcal{T}_h)_{h>0}$  be a regular family of triangulations of  $\Omega$  into parallelepipeds  $\mathbf{K}_j, j = 1, 2, \dots, N_{\mathbf{K}}$ , where  $h = \max_{\mathbf{K} \in \mathcal{T}_h} h_{\mathbf{K}}$  with  $h_{\mathbf{K}} = \text{diam}(\mathbf{K})$ . For each  $\mathbf{K} \in \mathcal{T}_h$ , let  $T_{\mathbf{K}} : \widehat{\mathbf{K}} \rightarrow \mathbb{R}^3$  be an invertible affine mapping such that

$$\mathbf{K} = T_{\mathbf{K}}(\widehat{\mathbf{K}}),$$

and set  $\phi_{\mathbf{K}} = \widehat{\phi} \circ T_{\mathbf{K}}^{-1} : \mathbf{K} \rightarrow \mathbb{R}$  for all  $\widehat{\phi} \in \widehat{\mathbb{P}}_{SK}^{(1)}$ , whose collection will be designated by

$$\mathbb{P}_{\mathbf{K}} = \text{Span}\{\phi_{\mathbf{K}} \mid \widehat{\phi} \in \widehat{\mathbb{P}}_{SK}^{(1)}\}.$$

Let  $N_V$  and  $N_F$  denote the numbers of vertices and faces, respectively. Then set

$$\mathcal{V}_h = \{V_1, V_2, \dots, V_{N_V} : \text{the set of all vertices of } \mathbf{K} \in \mathcal{T}_h\},$$

$$\begin{aligned}
\mathcal{F}_h &= \{F_1, F_2, \dots, F_{N_F} : \text{ the set of all faces of } \mathbf{K} \in \mathcal{T}_h\}, \\
\mathcal{F}_h^i &= \{F_1, F_2, \dots, F_{N_F^i} : \text{ the set of all interior faces of } \mathbf{K} \in \mathcal{T}_h\}, \\
\mathcal{M}_h &= \{M_1, M_2, \dots, M_{N_F} : \text{ the set of all face-centroids on } \mathcal{F}_h\}, \\
\mathcal{F}_h^{(1)} &= \{F \in \mathcal{F}_h : \text{ the set of all faces with outward normal } (\pm 1, 0, 0)\}, \\
\mathcal{F}_h^{(2)} &= \{F \in \mathcal{F}_h : \text{ the set of all faces with outward normal } (0, \pm 1, 0)\}, \\
\mathcal{F}_h^{(3)} &= \{F \in \mathcal{F}_h : \text{ the set of all faces with outward normal } (0, 0, \pm 1)\}.
\end{aligned}$$

Obviously we have  $\mathcal{F}_h = \mathcal{F}_h^{(1)} \cup \mathcal{F}_h^{(2)} \cup \mathcal{F}_h^{(3)}$ .

We consider the following nonconforming finite element spaces:

$$\begin{aligned}
\mathcal{N}\mathcal{C}^h &= \{\phi : \Omega \rightarrow \mathbb{R} \mid \phi|_{\mathbf{K}} \in \mathbb{P}_{\mathbf{K}} \forall \mathbf{K} \in \mathcal{T}_h, \phi \text{ is continuous at all } V_j \in \mathcal{V}_h, M_k \in \mathcal{M}_h\}, \\
\mathcal{N}\mathcal{C}_0^h &= \{\phi \in \mathcal{N}\mathcal{C}^h \mid \phi(V) = 0 \forall V_j \in \mathcal{V}_h \cap \Gamma \text{ and } \phi(M) = 0 \forall M_k \in \mathcal{M}_h \cap \Gamma\}.
\end{aligned}$$

### 3 The interpolation operator and convergence analysis

In this section we will define an interpolation operator and analyze convergence in the case of Dirichlet boundary value problems. The case of Neumann boundary value problem is quite similar and the results will be omitted.

#### 3.1 The second order elliptic problem

Denote by  $(\cdot, \cdot)$  the  $L^2(\Omega)$  inner product and by  $\langle \cdot, \cdot \rangle$  the duality pairing between  $H^{-1}(\Omega)$  and  $H_0^1(\Omega)$ , which is an extension of the duality pairing between  $L^2(\Omega)$  and itself. By  $\|\cdot\|_k$  and  $|\cdot|_k$  we adopt the standard notations for the norm and seminorm for the Sobolev spaces  $H^k(\Omega)$ . Consider then the following Dirichlet boundary value problem:

$$-\Delta u = f, \quad \Omega, \tag{6a}$$

$$u = 0, \quad \Gamma, \tag{6b}$$

with  $f \in H^1(\Omega)$ . We will further assume that the coefficients are sufficiently smooth and that the elliptic problem (6) has an  $H^3(\Omega)$ -regular solution such that  $\|u\|_3 \leq C\|f\|_1$ . The weak problem is then given as usual: find  $u \in H_0^1(\Omega)$  such that

$$a(u, v) = \langle f, v \rangle, \quad v \in H_0^1(\Omega), \tag{7}$$

where  $a : H_0^1(\Omega) \times H_0^1(\Omega) \rightarrow \mathbb{R}$  is the bilinear form defined by  $a(u, v) = (\nabla u, \nabla v)$  for all  $u, v \in H_0^1(\Omega)$ . The nonconforming Galerkin method for Problem (6) states as follows: find  $u_h \in \mathcal{N}\mathcal{C}_0^h$  such that

$$a_h(u_h, v_h) = \langle f, v_h \rangle, \quad v_h \in \mathcal{N}\mathcal{C}_0^h, \tag{8}$$

where

$$a_h(u, v) = \sum_{\mathbf{K} \in \mathcal{T}_h} a_{\mathbf{K}}(u, v),$$

with  $a_{\mathbf{K}}$  being the restriction of  $a$  to  $\mathbf{K}$ .

Notice that in order to have point values defined properly we need to recall the following Sobolev embedding theorem

$$W^{m,p}(\Omega) \longrightarrow C^0(\bar{\Omega}), \text{ if } \frac{1}{p} - \frac{m}{d} < 0.$$

Thus we should have  $p > \frac{3}{m}$ . For a given cube  $\mathbf{K} \in \mathcal{T}_h$ , define the local interpolation operator  $\Pi_{\mathbf{K}} : W^{1,p}(\mathbf{K}) \cap H_0^1(\Omega) \longrightarrow \widehat{\mathbb{P}}_{SK}^{(1)}$ ,  $p > 3$ , by

$$\Pi_{\mathbf{K}}\phi(V_i) = \phi(V_i), \quad \Pi_{\mathbf{K}}\phi(M_j) = \phi(M_j)$$

for all vertices  $V_i$  and face-centroids  $M_j$  of  $\mathbf{K}$ . The global interpolation operator  $\Pi_h : W^{1,p}(\Omega) \cap H_0^1(\Omega) \rightarrow \mathcal{N}\mathcal{C}_0^h$  is then defined through the local interpolation operator  $\Pi_{\mathbf{K}}$  by  $\Pi_h|_{\mathbf{K}} = \Pi_{\mathbf{K}}$  for all  $\mathbf{K} \in \mathcal{T}_h$ . Since  $\Pi_h$  preserves  $P_2$  for all  $\mathbf{K} \in \mathcal{T}_h$ , it follows from the Bramble-Hilbert Lemma that

$$\begin{aligned} \sum_{\mathbf{K} \in \mathcal{T}_h} \|\phi - \Pi_h\phi\|_{0,\mathbf{K}} + h \sum_{\mathbf{K} \in \mathcal{T}_h} \|\phi - \Pi_h\phi\|_{1,\mathbf{K}} &\leq Ch^k \|\phi\|_k, \\ \phi \in W^{k,p}(\Omega) \cap H_0^1(\Omega), 1 \leq k \leq 3. \end{aligned} \quad (9)$$

We now consider the energy-norm error estimate and first consider the following Strang lemma [13].

**Lemma 1.** *Let  $u \in H^1(\Omega)$  and  $u_h \in \mathcal{N}\mathcal{C}_0^h$  be the solutions of Eq. (7) and Eq. (8), respectively. Then*

$$\|u - u_h\|_h \leq C \left\{ \inf_{v_h \in \mathcal{N}\mathcal{C}_0^h} \|u - v_h\|_h + \sup_{w_h \in \mathcal{N}\mathcal{C}_0^h} \frac{|a_h(u, w_h) - \langle f, w_h \rangle|}{\|w_h\|_h} \right\}. \quad (10)$$

Here, and in what follows,  $\|\cdot\|_h$  denotes the usual broken energy norm such that  $\|v\|_h = \sqrt{a_h(v, v)}$ .

Due to (9), the first term in the right side of (10) is bounded by

$$\inf_{v_h \in \mathcal{N}\mathcal{C}_0^h} \|u - v_h\|_h \leq \|u - \Pi_h u\|_h \leq Ch^s |u|_{s+1}, \quad 1 < s \leq 2. \quad (11)$$

Denote by  $f_{jk}$  the trace of  $f|_{\mathbf{K}_j}$  on  $F_{jk} = \partial\mathbf{K}_j \cup \partial\mathbf{K}_k$  if it is nonempty. Similarly, the face  $F_{jk}$  will designate the boundary of  $K_j$  common with that of  $K_k$ .

Now let us bound the second term of the right side of (10) which denotes the consistency error. For a given cube  $\mathbf{K} \in \mathcal{T}_h$ , denote by  $F_K^{x_1^+}$  and  $F_K^{x_1^-}$  the face of  $\mathbf{K}$  with outward normal  $(1, 0, 0)$  and  $(-1, 0, 0)$ , respectively. Similarly, we denote the other faces

by  $F_K^{x_2^+}, F_K^{x_2^-}, F_K^{x_3^+}$ , and  $F_K^{x_3^-}$  so that  $\partial\mathbf{K} = \{F_K^{x_1^+}, F_K^{x_1^-}, F_K^{x_2^+}, F_K^{x_2^-}, F_K^{x_3^+}, F_K^{x_3^-}\}$ . Thus, integrating by parts elementwise, we have

$$\begin{aligned} a_h(u, w_h) - \langle f, w_h \rangle &= \sum_{\mathbf{K} \in \mathcal{T}_h} \left\langle \frac{\partial u}{\partial \boldsymbol{\nu}}, w_h \right\rangle_{\partial\mathbf{K}} \\ &= \sum_{\mathbf{K} \in \mathcal{T}_h} \int_{F_K^{x_1^+} \cup F_K^{x_1^-}} \frac{\partial u}{\partial \boldsymbol{\nu}} w_h \, ds + \sum_{\mathbf{K} \in \mathcal{T}_h} \int_{F_K^{x_2^+} \cup F_K^{x_2^-}} \frac{\partial u}{\partial \boldsymbol{\nu}} w_h \, ds \\ &\quad + \sum_{\mathbf{K} \in \mathcal{T}_h} \int_{F_K^{x_3^+} \cup F_K^{x_3^-}} \frac{\partial u}{\partial \boldsymbol{\nu}} w_h \, ds =: E_1 + E_2 + E_3, \end{aligned} \quad (12)$$

where  $\boldsymbol{\nu}$  is the unit outward normal to  $\mathbf{K}$ .

Before proceeding, we need the following lemma.

**Lemma 2.** *By  $F_k$  denote the face containing the centroid  $M_k$  and by  $V_j^{F_k}, j = 1, 2, 3, 4$ , denote the vertices on the face  $F_k$ . If  $p \in \widehat{\mathbb{P}}_{SK}^{(1)}, p(V_j^{F_k}) = 0, j = 1, 2, 3, 4$ , and  $p(M_k) = 0$ , then*

$$\int_{F_k} p(x_1, x_2, x_3) ds = 0, \quad k = 1, 2, \dots, 6. \quad (13)$$

*Proof.* Without loss of generality, we assume that  $M_1 = (1, 0, 0)$ . In this case, we have  $p \in \widehat{\mathbb{P}}_{SK}^{(1)}$  and  $p(1, \pm 1, \pm 1) = p(1, 0, 0) = 0$ . We need to prove that

$$\int_{F_1} p(1, x_2, x_3) dx_2 dx_3 = 0. \quad (14)$$

It follows from  $p(1, \pm 1, \pm 1) = 0$  that

$$p(1, x_2, x_3) = l_1(x_2, x_3)(x_2^2 - 1) + l_2(x_2, x_3)(x_3^2 - 1), \quad l_j \in P_1(\mathbb{R}^2), \quad j = 1, 2. \quad (15)$$

Set

$$l_j(x_2, x_3) = a_j x_2 + b_j x_3 + c_j, \quad j = 1, 2.$$

Then  $p(1, 0, 0) = 0$  implies that  $c_1 + c_2 = 0$ , which reduces (15) to

$$p(1, x_2, x_3) = (a_1 x_2 + b_1 x_3)(x_2^2 - 1) + (a_2 x_2 + b_2 x_3)(x_3^2 - 1) + c_1(x_2^2 - x_3^2).$$

Since

$$\widehat{\mathbb{P}}_{SK}^{(1)}|_{x_1=1} = \text{Span}\{1, x_2, x_3, x_2^2, x_2 x_3, x_3^2, x_2^2 x_3\}, \quad (16)$$

invoking  $p \in \widehat{\mathbb{P}}_{SK}^{(1)}$ , we have

$$a_1 = a_2 = b_2 = 0,$$

which leads to

$$p(1, x_2, x_3) = b_1 x_3(x_2^2 - 1) + c_1(x_2^2 - x_3^2). \quad (17)$$

It follows from (17) that (13) holds. This completes the proof.  $\square$

This lemma implies that Type 1 element can pass lower order patch test (test functions are in  $P_0$  not  $P_1$ ), which will lead to a convergence solution for the second order elliptic problems, but the convergence order is not optimal. To bound  $E_1, E_2, E_3$ , we also need some interpolation operators.

### 3.2 Some interpolation and projection operators

For the reference element  $\widehat{\mathbf{K}} = [-1, 1] \times [-1, 1] \times [-1, 1]$ , consider the interpolation problem on the face of  $F_{\widehat{\mathbf{K}}}^{x_1^+}$ : the interpolation points are  $(1, 1, 1)$ ,  $(1, 1, -1)$ ,  $(1, -1, 1)$ ,  $(1, -1, -1)$ , and  $(1, 0, 0)$ , which are the four vertices and the centroid of  $F_{\widehat{\mathbf{K}}}^{x_1^+}$ , with the interpolation space  $\widehat{Q}_1^*(F_{\widehat{\mathbf{K}}}^{x_1^+})$ , where

$$\widehat{Q}_1^*(F_{\widehat{\mathbf{K}}}^{x_1^+}) := \text{Span}\{1, \widehat{x}_2, \widehat{x}_3, \widehat{x}_2\widehat{x}_3, \widehat{x}_3^2\} \subset \widehat{\mathbb{P}}_{SK}^{(1)}|_{\widehat{x}_1=1}$$

is an enriched bilinear polynomial space on the face  $F_{\widehat{\mathbf{K}}}^{x_1^+}$  (see (16)).

The above interpolation problem has a solution by using the bubble function

$$b(\widehat{x}_2, \widehat{x}_3) = 1 - \widehat{x}_3^2,$$

and the standard bilinear interpolation basis functions

$$\begin{aligned} q_1(\widehat{x}_2, \widehat{x}_3) &= \frac{1}{4}(1 + \widehat{x}_2)(1 + \widehat{x}_3), & q_2(\widehat{x}_2, \widehat{x}_3) &= \frac{1}{4}(1 - \widehat{x}_2)(1 + \widehat{x}_3), \\ q_3(\widehat{x}_2, \widehat{x}_3) &= \frac{1}{4}(1 - \widehat{x}_2)(1 - \widehat{x}_3), & q_4(\widehat{x}_2, \widehat{x}_3) &= \frac{1}{4}(1 + \widehat{x}_2)(1 - \widehat{x}_3), \end{aligned}$$

as follows:

$$\widehat{\varphi}_j = q_j - \frac{1}{4}b, \quad j = 1, \dots, 4; \quad \widehat{\varphi}_5 = b.$$

Thus for a continuous function  $f$  defined on the face  $F_{\widehat{\mathbf{K}}}^{x_1^+}$ , the interpolation polynomial is given by

$$\widehat{\mathcal{I}}_F^{x_1^+} f = f(1, 1, 1)\widehat{\varphi}_1 + f(1, -1, 1)\widehat{\varphi}_2 + f(1, -1, -1)\widehat{\varphi}_3 + f(1, 1, -1)\widehat{\varphi}_4 + f(1, 0, 0)\widehat{\varphi}_5. \quad (18)$$

And then we can also define the interpolation operator on the opposite face with the same space and denote it by  $\widehat{\mathcal{I}}_F^{x_1^-}$ . Similarly, define the interpolation operators on the other faces of  $\widehat{\mathbf{K}}$  with the corresponding spaces:

$$\begin{aligned} \widehat{Q}_1^*(F_{\widehat{\mathbf{K}}}^{x_2}) &:= \text{Span}\{1, \widehat{x}_3, \widehat{x}_1, \widehat{x}_3\widehat{x}_1, \widehat{x}_1^2\} \subset \widehat{\mathbb{P}}_{SK}^{(1)}|_{\widehat{x}_2=\pm 1}, \\ \widehat{Q}_1^*(F_{\widehat{\mathbf{K}}}^{x_3}) &:= \text{Span}\{1, \widehat{x}_1, \widehat{x}_2, \widehat{x}_1\widehat{x}_2, \widehat{x}_2^2\} \subset \widehat{\mathbb{P}}_{SK}^{(1)}|_{\widehat{x}_3=\pm 1} \end{aligned}$$

and denote them by  $\widehat{\mathcal{I}}_F^{x_2^+}$ ,  $\widehat{\mathcal{I}}_F^{x_2^-}$ ,  $\widehat{\mathcal{I}}_F^{x_3^+}$ ,  $\widehat{\mathcal{I}}_F^{x_3^-}$ , respectively.

For a given  $\mathbf{K} \in \mathcal{T}_h$ , we can define the interpolation operator  $\mathcal{I}_F^{x_i^\pm}$  by  $\mathcal{I}_F^{x_i^\pm} = \widehat{\mathcal{I}}_F^{x_i^\pm} \circ T_{\mathbf{K}}^{-1}$ . Notice that  $[\mathcal{I}_F^{x_i^\pm} w_h]_F = 0$  for all interior faces  $F$  for every  $w_h \in \mathcal{N}\mathcal{C}_0^h$ . Moreover, the above interpolation operators preserve linear polynomials on each surface as stated in the following lemma.

**Lemma 3.**  $\mathcal{I}_F^{x_i^\pm}$  map  $w_h \in \mathcal{N}\mathcal{C}_0^h$  such that their images across interior faces are continuous for all interior faces  $F$ . Moreover, they preserve bilinear polynomials on faces.

Moreover, the above interpolation has the following interesting property:

**Lemma 4.** For all  $w_h \in \mathcal{N}\mathcal{C}_0^h$  and  $\mathbf{K} \in \mathcal{T}_h$ ,

$$w_h|_{F_{\mathbf{K}}^{x_i^+}} - \mathcal{I}_F^{x_i^+}(w_h|_{\mathbf{K}}) = w_h|_{F_{\mathbf{K}}^{x_i^-}} - \mathcal{I}_F^{x_i^-}(w_h|_{\mathbf{K}}), \quad i = 1, 2, 3. \quad (19)$$

*Proof.* We only prove the case of  $i = 1$  in Eq. (19) which suffices to prove the statement on the reference element  $\widehat{\mathbf{K}}$ :

$$\widehat{w}_h|_{\widehat{F}_{\widehat{\mathbf{K}}}^{x_1^+}} - \widehat{\mathcal{I}}_{\widehat{F}}^{x_1^+}(\widehat{w}_h) = \widehat{w}_h|_{\widehat{F}_{\widehat{\mathbf{K}}}^{x_1^-}} - \widehat{\mathcal{I}}_{\widehat{F}}^{x_1^-}(\widehat{w}_h) \quad \forall \widehat{w}_h \in \widehat{\mathbb{P}}_{SK}^{(1)}. \quad (20)$$

Due to the interpolation property,  $\widehat{w}_h|_{\widehat{F}_{\widehat{\mathbf{K}}}^{x_1^+}} - \widehat{\mathcal{I}}_{\widehat{F}}^{x_1^+}(\widehat{w}_h) = 0$  for all  $\widehat{w}_h \in \widehat{Q}_1^*(F_{\widehat{\mathbf{K}}}^{x_1^+})$ , and the same is true if  $x_1^+$  is replaced by  $x_1^-$ . Thus, it suffices to show that (19) holds for all  $\widehat{w}_h \in \widehat{\mathbb{P}}_{SK}^{(1)}|_{\widehat{x}_1=1} \setminus \widehat{Q}_1^*(F_{\widehat{\mathbf{K}}}^{x_1^+})$ , which is nothing but  $\text{Span}\{\widehat{x}_2^2, \widehat{x}_2^2\widehat{x}_3\}$ . Since both  $\widehat{x}_2^2$  and  $\widehat{x}_2^2\widehat{x}_3$  are independent of  $\widehat{x}_1$ , it is obvious that (20) holds for each of them. This proves the lemma.  $\square$

Define  $RQ = \text{Span}\{1, \widehat{x}_1, \widehat{x}_2, \widehat{x}_3, \widehat{x}_1^2 - \widehat{x}_2^2, \widehat{x}_1^2 - \widehat{x}_3^2\}$ . For the reference element  $\widehat{\mathbf{K}}$ , let  $R_{\widehat{\mathbf{K}}} : H^2(\widehat{\mathbf{K}}) \rightarrow RQ$  be an interpolation operator defined by

$$R_{\widehat{\mathbf{K}}}\widehat{\phi}(\widehat{M}_j) = \widehat{\phi}(\widehat{M}_j), j = 1, \dots, 6$$

for all  $\widehat{\phi} \in H^2(\widehat{\mathbf{K}})$ . It is exactly the so-called rotation element. Obviously,

$$R_{\widehat{\mathbf{K}}}\widehat{\phi} = \sum_{i=1}^6 \widehat{\phi}(\widehat{M}_i)\widehat{\psi}_i(\widehat{x}, x_2, x_3)$$

where

$$\begin{cases} \widehat{\psi}_i = \frac{1}{6} \left( 1 + 3\widehat{x}_i + \sum_{1 \leq j \leq 3, j \neq i} (\widehat{x}_i^2 - \widehat{x}_j^2) \right), \\ \widehat{\psi}_{7-i} = \frac{1}{6} \left( 1 - 3\widehat{x}_i + \sum_{1 \leq j \leq 3, j \neq i} (\widehat{x}_i^2 - \widehat{x}_j^2) \right), \end{cases} \quad i = 1, 2, 3.$$

It is easy to notice that for  $i = 1, 2, \dots, 6$

$$\widehat{\psi}_i|_{\widehat{x}_j=1} = \widehat{\psi}_i|_{\widehat{x}_j=-1}, \quad \text{if } j \neq i \text{ and } j \neq 7-i$$

and for  $i = 1, 2, 3$

$$\begin{aligned} \widehat{\psi}_i|_{\widehat{x}_i=1} &= \widehat{\psi}_{7-i}|_{\widehat{x}_i=-1} = 1 - \frac{1}{6} \sum_{1 \leq j \leq 3, j \neq i} \widehat{x}_j^2, \\ \widehat{\psi}_i|_{\widehat{x}_i=-1} &= \widehat{\psi}_{7-i}|_{\widehat{x}_i=1} = -\frac{1}{6} \sum_{1 \leq j \leq 3, j \neq i} \widehat{x}_j^2. \end{aligned}$$

Thus we have

$$R_{\widehat{\mathbf{K}}}\widehat{\phi}|_{\widehat{x}_j=1} = \sum_{i=1}^6 \widehat{\phi}(\widehat{M}_i)\widehat{\psi}_i|_{x_j=1}$$

$$\begin{aligned}
&= \sum_{1 \leq i \leq 6, i \neq j, i \neq 7-j} \widehat{\phi}(\widehat{M}_i) \widehat{\psi}_i|_{x_j=1} + \widehat{\phi}(\widehat{M}_j) \left( 1 - \frac{1}{6} \sum_{1 \leq i \leq 3, i \neq j} \widehat{x}_i^2 \right) \\
&\quad - \widehat{\phi}(\widehat{M}_{7-j}) \left( \frac{1}{6} \sum_{1 \leq i \leq 3, i \neq j} \widehat{x}_i^2 \right) \\
&:= \Theta(\widehat{\mathbf{K}}, \widehat{\phi}, \{\widehat{x}_1, \widehat{x}_2, \widehat{x}_3\} \setminus \widehat{x}_j) + \widehat{\phi}(\widehat{M}_j),
\end{aligned}$$

and

$$\begin{aligned}
R_{\widehat{\mathbf{K}}} \widehat{\phi}|_{\widehat{x}_j=-1} &= \sum_{i=1}^6 \widehat{\phi}(\widehat{M}_i) \widehat{\psi}_i|_{x_j=-1} \\
&= \sum_{1 \leq i \leq 6, i \neq j, i \neq 7-j} \widehat{\phi}(\widehat{M}_i) \widehat{\psi}_i|_{x_j=1} - \widehat{\phi}(\widehat{M}_j) \left( \frac{1}{6} \sum_{1 \leq i \leq 3, i \neq j} \widehat{x}_i^2 \right) \\
&\quad - \widehat{\phi}(\widehat{M}_{7-j}) \left( 1 - \frac{1}{6} \sum_{1 \leq i \leq 3, i \neq j} \widehat{x}_i^2 \right) \\
&= \Theta(\widehat{\mathbf{K}}, \widehat{\phi}, \{\widehat{x}_1, \widehat{x}_2, \widehat{x}_3\} \setminus \widehat{x}_j) + \widehat{\phi}(\widehat{M}_{7-j}),
\end{aligned}$$

For any given  $\mathbf{K} \in \mathcal{T}_h$ , we can define the interpolation operator  $R_{\mathbf{K}} := R_{\widehat{\mathbf{K}}} \cdot T_{\mathbf{K}}^{-1}$ . Denote by  $M_{\mathbf{K}}^{x_j^+}$  and  $M_{\mathbf{K}}^{x_j^-}$  the centroids of the faces  $F_{\mathbf{K}}^{x_j^+}$  and  $F_{\mathbf{K}}^{x_j^-}$ , respectively. Then for any  $\phi \in H^2(\mathbf{K})$ , we have

$$\begin{aligned}
R_{\mathbf{K}} \phi|_{F_{\mathbf{K}}^{x_j^+}} &= \Theta(\mathbf{K}, \phi, \{x_1, x_2, x_3\} \setminus x_j) + \phi(M_{\mathbf{K}}^{x_j^+}), \\
R_{\mathbf{K}} \phi|_{F_{\mathbf{K}}^{x_j^-}} &= \Theta(\mathbf{K}, \phi, \{x_1, x_2, x_3\} \setminus x_j) + \phi(M_{\mathbf{K}}^{x_j^-}).
\end{aligned}$$

### 3.3 The error estimates

Turn to bound  $|E_1| + |E_2| + |E_3|$  in (12). Below, we will give an estimate of  $|E_1|$  in detail while similar estimates of  $|E_2|$  and  $|E_3|$  will be omitted.

It is easy to notice that for any  $F \in \partial \mathbf{K}' \cap \partial \mathbf{K}'' \cap \mathcal{F}_h^{(1)} \neq \emptyset$  and  $w \in \mathcal{N} \mathcal{C}_0^h$ , we have

$$\begin{aligned}
&\int_F \nabla u (w|_{\mathbf{K}'} - w|_{\mathbf{K}''}) ds \\
&= \int_F \nabla u ((w|_{\mathbf{K}'} - \mathcal{I}_F^{x_1}(w)) - (w|_{\mathbf{K}''} - \mathcal{I}_F^{x_1}(w))) ds \\
&= \int_F (\nabla u - M_F(\nabla u)) ((w|_{\mathbf{K}'} - \mathcal{I}_F^{x_1}(w)) - (w|_{\mathbf{K}''} - \mathcal{I}_F^{x_1}(w))) ds
\end{aligned}$$

where  $M_F(\nabla u)$  denotes the value of  $\nabla u$  at the centroid of  $F$ . The second equality holds due to the orthogonality (13). Hence we have

$$E_1 = \sum_{\mathbf{K} \in \mathcal{T}_h} \sum_{i=1}^3 \int_{F_{\mathbf{K}}^{x_1^+} \cup F_{\mathbf{K}}^{x_1^-}} \frac{\partial u}{\partial x_i} w \nu_i ds$$

$$\begin{aligned}
&= \sum_{\mathbf{K} \in \mathcal{T}_h} \sum_{i=1}^3 \left( \int_{F_K^{x_1^+}} \frac{\partial u}{\partial x_i} (w - \mathcal{J}_F^{x_1^+}(w)) \nu_i ds + \int_{F_K^{x_1^-}} \frac{\partial u}{\partial x_i} (w - \mathcal{J}_F^{x_1^-}(w)) \nu_i ds \right) \\
&= \sum_{\mathbf{K} \in \mathcal{T}_h} \sum_{i=1}^3 \left( \int_{F_K^{x_1^+}} \left( \frac{\partial u}{\partial x_i} - M_{F_K^{x_1^+}} \left( \frac{\partial u}{\partial x_i} \right) \right) (w - \mathcal{J}_F^{x_1^+}(w)) \nu_i ds \right. \\
&\quad \left. + \int_{F_K^{x_1^-}} \left( \frac{\partial u}{\partial x_i} - M_{F_K^{x_1^-}} \left( \frac{\partial u}{\partial x_i} \right) \right) (w - \mathcal{J}_F^{x_1^-}(w)) \nu_i ds \right),
\end{aligned}$$

where  $\boldsymbol{\nu} = (\nu_1, \nu_2, \nu_3)^T$  is the outward normal derivative of  $F$ . Thus due to (19), we arrive at

$$\begin{aligned}
E_1 &= \sum_{\mathbf{K} \in \mathcal{T}_h} \sum_{i=1}^3 \left( \int_{F_K^{x_1^+}} \left( \frac{\partial u}{\partial x_i} - \Theta(\mathbf{K}, \frac{\partial u}{\partial x_i}, x_2, x_3) - M_{F_K^{x_1^+}} \left( \frac{\partial u}{\partial x_i} \right) \right) (w - \mathcal{J}_F^{x_1^+}(w)) \nu_i ds \right. \\
&\quad \left. + \int_{F_K^{x_1^-}} \left( \frac{\partial u}{\partial x_i} - \Theta(\mathbf{K}, \frac{\partial u}{\partial x_i}, x_2, x_3) - M_{F_K^{x_1^-}} \left( \frac{\partial u}{\partial x_i} \right) \right) (w - \mathcal{J}_F^{x_1^-}(w)) \nu_i ds \right) \\
&= \sum_{\mathbf{K} \in \mathcal{T}_h} \sum_{i=1}^3 \left( \int_{F_K^{x_1^+}} \left( \frac{\partial u}{\partial x_i} - R_{\mathbf{K}} \frac{\partial u}{\partial x_i} \right) (w - \mathcal{J}_F^{x_1^+}(w)) \nu_i ds \right. \\
&\quad \left. + \int_{F_K^{x_1^-}} \left( \frac{\partial u}{\partial x_i} - R_{\mathbf{K}} \frac{\partial u}{\partial x_i} \right) (w - \mathcal{J}_F^{x_1^-}(w)) \nu_i ds \right).
\end{aligned}$$

Since  $R_{\mathbf{K}}$  and  $\mathcal{J}_F^x$  preserves  $P_1(\mathbf{K})$  and  $P_1(F_K^{x_1})$ , respectively, it follows from trace theorem and Cauchy-Schwartz inequality, we get

$$|E_1| \leq Ch^2 \|w\|_h \|u\|_{H^3(\Omega)}.$$

Similarly, we also have

$$|E_2| \leq Ch^2 \|w\|_h \|u\|_{H^3(\Omega)}, \quad |E_3| \leq Ch^2 \|w\|_h \|u\|_{H^3(\Omega)}.$$

Hence

$$\sup_{w \in \mathcal{N}\mathcal{C}_0^h} \frac{|a_h(u, w) - \langle f, w \rangle|}{\|w\|_h} = \sup_{w \in \mathcal{N}\mathcal{C}_0^h} \frac{|E_1 + E_2 + E_3|}{\|w\|_h} \leq Ch^2 \|u\|_{H^3(\Omega)}.$$

By collecting the above results, we get the following energy-norm error estimate.

**Theorem 1.** *Let  $u \in H^3(\Omega) \cap H_0^1(\Omega)$  and  $u_h \in \mathcal{N}\mathcal{C}_0^h$  satisfy (7) and (8), respectively. Then we have the energy norm error estimate:*

$$\|u - u_h\|_h \leq Ch^2 \|u\|_3.$$

By a standard Aubin-Nitsche duality argument, an  $L_2(\Omega)$ -error estimate can be easily obtained.

**Theorem 2.** Let  $u \in H^3(\Omega) \cap H_0^1(\Omega)$  and  $u_h \in \mathcal{N}\mathcal{C}_0^h$  be the solution of (7) and (8), respectively. Then we have

$$\|u - u_h\|_0 \leq Ch^3 \|u\|_3.$$

*Proof.* Let  $\eta_h = \Pi_h u - u_h \in \mathcal{N}\mathcal{C}_0^h$  and consider the dual problem:

$$-\Delta\psi = \eta_h, \quad \Omega, \quad (21a)$$

$$\psi = 0, \quad \partial\Omega. \quad (21b)$$

Since  $\eta_h \in L^2(\Omega)$ , the elliptic regularity implies that  $\|\psi\|_2 \leq C\|\eta_h\|$ . An application of (9) to the triangle inequality makes us to prove only  $\|\eta_h\|_h \leq Ch^2 \|u\|_3$ .

First, we have from Theorem 1 and (9) that

$$\|\eta_h\|_h \leq \|u - u_h\|_h + \|u - \Pi_h u\|_h \leq Ch^2 \|u\|_3. \quad (22)$$

Following the arguments in the derivation of the energy estimate, we have

$$\begin{aligned} \|\eta_h\|^2 &= - \sum_{\mathbf{K} \in \mathcal{T}_h} (\eta_h, \Delta\psi)_{\mathbf{K}} \\ &= \sum_{\mathbf{K} \in \mathcal{T}_h} (\nabla\eta_h, \nabla\psi)_{\mathbf{K}} - \sum_{\mathbf{K} \in \mathcal{T}_h} \langle \eta_h, \boldsymbol{\nu} \cdot \nabla\psi \rangle_{\partial\mathbf{K}} \\ &= a_h(\eta_h, \psi) - \sum_{\mathbf{K} \in \mathcal{T}_h} \langle \eta_h - \mathcal{I}_F \eta_h, \boldsymbol{\nu} \cdot \nabla\psi \rangle_{\partial\mathbf{K}}, \\ &= a_h(\eta_h, \psi) - \sum_{\mathbf{K} \in \mathcal{T}_h} \langle \eta_h - \mathcal{I}_F \eta_h, \boldsymbol{\nu} \cdot (\nabla\psi - M_F(\nabla\psi)) \rangle_{\partial\mathbf{K}}, \end{aligned}$$

where  $M_F(\nabla\psi)$  denotes the value of  $\nabla\psi$  at the centroid of  $F$ . Hence, invoking the elliptic regularity and (22)

$$\begin{aligned} \|\eta_h\|^2 &\leq |a_h(\eta_h, \psi)| + \left[ \sum_{\mathbf{K} \in \mathcal{T}_h} |\eta_h - \mathcal{I}_F \eta_h|_{0, \partial\mathbf{K}}^2 \right]^{\frac{1}{2}} \left[ \sum_{\mathbf{K} \in \mathcal{T}_h} |\boldsymbol{\nu} \cdot (\nabla\psi - M_F(\nabla\psi))|_{0, \partial\mathbf{K}}^2 \right]^{\frac{1}{2}} \\ &\leq |a_h(\eta_h, \psi)| + Ch^{\frac{1}{2}} \|\eta_h\|_h h^{\frac{1}{2}} \|\psi\|_2 \\ &\leq |a_h(\eta_h, \psi)| + Ch^3 \|u\|_h \|\eta_h\|. \end{aligned} \quad (23)$$

Thus it remains to bound  $|a_h(\eta_h, \psi)|$ . For this, write

$$a_h(\eta_h, \psi) = a_h(\eta_h, \psi - \Pi_h \psi) + a_h(\Pi_h u - u, \Pi_h \psi) + a_h(u - u_h, \Pi_h \psi). \quad (24)$$

The first term in (24) is bounded as follows:

$$\begin{aligned} |a_h(\eta_h, \psi - \Pi_h \psi)| &\leq C \|\eta_h\|_h \|\psi - \Pi_h \psi\|_h \\ &\leq Ch^2 \|u\|_3 h \|\psi\|_2 \leq Ch^3 \|u\|_3 h \|\eta_h\|. \end{aligned} \quad (25)$$

Since the second term in (24) can be decomposed by

$$a_h(\Pi_h u - u, \Pi_h \psi) = \sum_{\mathbf{K} \in \mathcal{T}_h} (\Pi_h u - u, -\Delta(\Pi_h \psi))_{\mathbf{K}}$$

$$\begin{aligned}
& + \sum_{\mathbf{K} \in \mathcal{T}_h} \langle \Pi_h u - u, \boldsymbol{\nu} \cdot \nabla \Pi_h \psi \rangle_{\partial \mathbf{K}} \\
= & \sum_{\mathbf{K} \in \mathcal{T}_h} (\Pi_h u - u, -\Delta \Pi_h \psi)_{\mathbf{K}} \\
& + \sum_{\mathbf{K} \in \mathcal{T}_h} \langle \Pi_h u - u, \boldsymbol{\nu} \cdot (\nabla \Pi_h \psi - M_F(\nabla \Pi_h \psi)) \rangle_{\partial \mathbf{K}},
\end{aligned}$$

it can be estimated as follows:

$$|a_h(\Pi_h u - u, \Pi_h \psi)| \leq Ch^3 \|u\|_3 \|\psi\|_2 + Ch^{\frac{3}{2}} \|u\|_3 h^{\frac{1}{2}} \|\psi\|_2 \leq Ch^3 \|u\|_3 \|\eta_h\|. \quad (26)$$

The third term in (24) is bounded in the same fashion as

$$|a_h(u - \Pi_h u, \Pi_h \psi)| \leq Ch^3 \|u\|_3 \|\eta_h\|. \quad (27)$$

Collecting (25)–(27) and plugging into (24) combined with (23), one sees that the theorem follows by deviding both sides by  $\|\eta_h\|$ .  $\square$

## 4 Error estimates of other Smith-Kidger elements

In this section we claim that the approximation of the solutions of the second-order elliptic problem with Type 2 and 5 Smith-Kidger elements is also convergent in optimal order. In these case, it is easy to check that the orthogonality in Lemma 2 holds. The difference during the proof lies in the construction of the interpolation operator. For the second type element, the interpolation of  $\mathcal{J}_F^{x_1}$ ,  $\mathcal{J}_F^{x_2}$ ,  $\mathcal{J}_F^{x_3}$  should be  $\text{Span}\{1, x_2, x_3, x_2 x_3, x_2^2\}$ ,  $\text{Span}\{1, x_1, x_3, x_1 x_3, x_3^2\}$  and  $\text{Span}\{1, x_1, x_2, x_1 x_2, x_1^2\}$ , respectively. And for the fifth type element, the corresponding interpolation spaces should be taken as  $\text{Span}\{1, x_2, x_3, x_2 x_3, x_3^2 + x_2^2\}$ ,  $\text{Span}\{1, x_1, x_3, x_1 x_3, x_1^2 + x_3^2\}$  and  $\text{Span}\{1, x_1, x_2, x_1 x_2, x_1^2 + x_2^2\}$ , respectively.

For Type 6 element, the orthogonality in Lemma 2 does not hold, but the Eq. (19) holds. Thus, we have

$$\begin{aligned}
|E_1| &= \left| \sum_{\mathbf{K} \in \mathcal{T}_h} \left( \int_{F_{\mathbf{K}}^{x_1^+}} \frac{\partial u}{\partial \boldsymbol{\nu}} (w - \mathcal{J}_F^{x_1^+}(w)) \, ds + \int_{F_{\mathbf{K}}^{x_1^-}} \frac{\partial u}{\partial \boldsymbol{\nu}} (w - \mathcal{J}_F^{x_1^-}(w)) \, ds \right) \right| \\
&= \left| \sum_{\mathbf{K} \in \mathcal{T}_h} \left( \int_{F_{\mathbf{K}}^{x_1^+}} \left( \frac{\partial u}{\partial \boldsymbol{\nu}} - P_{\mathbf{K}}^0 \left( \frac{\partial u}{\partial \boldsymbol{\nu}} \right) \right) (w - \mathcal{J}_F^{x_1^+}(w)) \, ds \right. \right. \\
&\quad \left. \left. + \int_{F_{\mathbf{K}}^{x_1^-}} \left( \frac{\partial u}{\partial \boldsymbol{\nu}} - P_{\mathbf{K}}^0 \left( \frac{\partial u}{\partial \boldsymbol{\nu}} \right) \right) (w - \mathcal{J}_F^{x_1^-}(w)) \, ds \right) \right| \\
&\leq Ch \|u\|_2 \|w\|_h,
\end{aligned}$$

where

$$P_{\mathbf{K}}^0 \left( \frac{\partial u}{\partial \boldsymbol{\nu}} \right) = \frac{1}{|\mathbf{K}|} \int_{\mathbf{K}} \frac{\partial u}{\partial \boldsymbol{\nu}} \, ds,$$

and  $|\mathbf{K}| = \int_{\mathbf{K}} ds$ . By a similar derivation, we will get

**Theorem 3.** *Let  $u \in H^2(\Omega) \cap H_0^1(\Omega)$  satisfy (7) and  $u_h$  be the solution of (8) with the sixth type element. Then we have the energy norm error estimate:*

$$\begin{aligned} \|u - u_h\|_h &\leq Ch \|u\|_2, \\ \|u - u_h\|_0 &\leq Ch^2 \|u\|_2. \end{aligned}$$

## 5 A new 14-node brick element

In this section, we present a new element with 14-node. The degrees of freedom are the same with those in Smith-Kidger element and Meng-Sheen-Luo-Kim element. But the shape function space is taken as  $P_2 \oplus \text{Span}\{x_1x_2x_3, x_1(x_2^2 + x_3^2), x_2(x_1^2 + x_3^2), x_3(x_1^2 + x_2^2)\}$ . Denote the corresponding higher-degree polynomials to those in (2) as follows:

$$\begin{aligned} r_0(\hat{x}_1, \hat{x}_2, \hat{x}_3) &= \hat{x}_1\hat{x}_2\hat{x}_3, \quad r_1(\hat{x}_1, \hat{x}_2, \hat{x}_3) = \frac{1}{2}\hat{x}_1(\hat{x}_2^2 + \hat{x}_3^2), \\ r_2(\hat{x}_1, \hat{x}_2, \hat{x}_3) &= \frac{1}{2}\hat{x}_2(\hat{x}_1^2 + \hat{x}_3^2), \quad r_3(\hat{x}_1, \hat{x}_2, \hat{x}_3) = \frac{1}{2}\hat{x}_3(\hat{x}_1^2 + \hat{x}_2^2). \end{aligned} \tag{28}$$

Then, again equipped with the 8 vertex values plus 6 face integrals DOFs, the basis functions corresponding to the vertices and face-integrals are given exactly same as the formulae (3), (4), and (5).

In order to analyze convergence, we need to verify the orthogonality in Lemma 2 and Eq. (20). The orthogonality can be checked directly as in the proof in Lemma 2. In order to check Eq. (20), it is enough to define the corresponding interpolation spaces as  $\text{Span}\{1, x_2, x_3, x_2x_3, x_3^2 + x_2^2\}$ ,  $\text{Span}\{1, x_1, x_3, x_1x_3, x_1^2 + x_3^2\}$  and  $\text{Span}\{1, x_1, x_2, x_1x_2, x_1^2 + x_2^2\}$ , respectively. Thus, by following the same argument as in the previous sections, we also get optimal convergence for the second-order elliptic problems. That is, in this case, Theorems 1 and 2 hold.

## 6 Further remarks and conclusions

In this paper, we have proved that for second-order elliptic problems, the Smith-Kidger element of type 1, 2 and 5 can obtain optimal convergence order both in energy norm and  $L_2(\Omega)$  norm, while the sixth type element loses one order of accuracy in each norm. In the proof, the key points lie in that they have weak orthogonality (Lemma 2) and satisfy Eq. (20). In [5]. We also proposed another kind of DOFs, that is, the values at the eight vertices and the integration values over six faces. Indeed, it is easy to check that Type 1, 2, 5 and the new element presented in this paper give optimal convergence orders for second-order elliptic problems. Besides, we can show that if the face-centroid values DOFs are replaced by the face integrals DOFs, Type 6 element also are of optimal-order convergence owing to a weak orthogonality, thus improving one order accuracy.

## References

- [1] P. G. Ciarlet. *The Finite Element Method for Elliptic Equations*. North–Holland, Amsterdam, 1978.
- [2] J. Douglas, Jr., J. E. Santos, D. Sheen, and X. Ye. Nonconforming Galerkin methods based on quadrilateral elements for second order elliptic problems. *ESAIM–Math. Model. Numer. Anal.*, 33(4):747–770, 1999
- [3] B.H. Irons and A. Razzaque. Experience with the patch test for convergence of finite elements. In A.K.Aziz, editor, *The mathematical foundations of the finite element method with applications to partial differential equations*, pages 557–587, New York, 1977. Academic Press.
- [4] S. Kim, Z. Luo, Z. Meng, and D. Sheen. Numerical study on three-dimensional quadratic nonconforming brick elements. *East-west Journal of Mathematics*, 2013. To appear.
- [5] Z. Meng, D. Sheen, Z. Luo, and S. Kim. Three-dimensional quadratic nonconforming brick element. *Numerical Methods for Partial Differential Equations*, 2013. To appear.
- [6] C. Park and D. Sheen.  $P_1$ -nonconforming quadrilateral finite element methods for second-order elliptic problems. *SIAM J. Numer. Anal.*, 41(2):624–640, 2003
- [7] R. Rannacher and S. Turek. Simple nonconforming quadrilateral Stokes element. *Numer. Methods Partial Differential Equations*, 8:97–111, 1992.
- [8] Z. Shi. The F-E-M-test for convergence of nonconforming finite elements. *Math. Comp.*, 49:391–405, 1987.
- [9] Z.-C. Shi. Nonconforming finite element methods. *J. Comput. Appl. Math.*, 149(1):221 – 225, 2002.
- [10] Z.C. Shi. An explicit analysis of Stummel’s patch test examples. *Int. J. Numer. Meth. Engng.*, 20(7):1233–1246, 1984.
- [11] Z. Shi and J. Wang. Convergence analysis of a class of nonconforming finite elements. *Mathematica Numerica Sinica*, 22(1):97–102, 2000. In Chinese.
- [12] I. M. Smith and D. J. Kidger. Elastoplastic analysis using the 14–node brick element family. *Int. J. Numer. Meth. Engng.*, 35:1263–1275, 1992.
- [13] G. Strang and G. J. Fix. *An Analysis of the Finite Element Method*. Prentice–Hall, Englewood Cliffs, 1973.
- [14] F. Stummel. The generalized patch test. *SIAM J. Numer. Anal.*, 16(3):449–471, 1979.
- [15] E L. Wilson, R. L. Taylor, W. P. Doherty, and J. Ghaboussi. Incompatible displacement models. 1971.