

# Govocitos: a software tool for estimating fish fecundity based on digital analysis of histological images

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## Abstract

To estimate productivity of a fish stock, the precise determination of fish fecundity is essential. The stereological method accurately estimates fecundity from histological images of a fish gonad. Traditionally, the fecundity is estimated using the stereological method, which overlays an hexagonal grid on the histological image and counts the number of grid points associated to each oocyte category (oocytes are reproductive cells) and the number of oocytes in each category. This process is done manually often using off-the-shelf software, but it is very time-consuming, requires specialized technicians, and does not allow to review the calculations. In this paper, we describe and evaluate the software Govocitos, which offers an easy and automatic way to estimate fecundity using the stereological method. Govocitos contains a module to automatically detects the matured oocytes in the slice (nearly 80%

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of oocytes are correctly detected) and a module to automatically classify the oocytes according to the presence/absence of nucleus (with 84% of accuracy) and to three development stages (with 87% of accuracy). It also provides a user friendly GUI that allows the experts to modify the outlines and classifications of oocytes, to calculate diameters, areas and roundness, to build diameter frequency histograms, to count the points and objects inside the grid, to estimate partial and potential fecundity and to export the data to files and into a database. In addition, Govocitos provides the possibility of varying grid characteristics, it can be trained to work with different species and it allows to check and supervise the calculations whenever needed including in a later point in time. Govocitos is a free software that can be downloaded from <http://lia.ei.uvigo.es/daeira/software/govocitos>.

*Keywords:*

Histological image, fish fecundity, computer vision, edge detection, object recognition, texture analysis, classification.

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## **1. Introduction**

Fecundity is one of the most important parameters for estimating productivity of a fish stock, and thus, of interest to fishery scientists as a critical parameter of stock assessment, as well as a basic aspect of population dynamics, studied by Lasker (1985) and Hunter et al. (1992). To assess stock reproductive potential and its impact on recruitment variability (replacement rate of the population), it is necessary to study oocyte development

47 dynamics and estimate both the potential fecundity and the resorption rate  
48 (atresia) of oocytes in order to estimate the egg production that can be used  
49 as an indicator of stock productivity. Beside, Katsukawa (1997) states that  
50 it is a reference point for fisheries management to develop a precautionary  
51 approach to sustainable fisheries.

52 Determining fish fecundity in a precise and unbiased way is essential for  
53 stock assessment. Therefore, in the last decades many efforts have been un-  
54 dertaken to develop simpler, faster and more precise and accurate methods.  
55 The most common and widespread method to estimate fecundity is the gravi-  
56 metric method, proposed by McGregor (1922) and Raitt (1933), that uses  
57 whole mounts samples of gonad tissue. Begenal and Braum (1978) summa-  
58 rizes most of these methods based on counting the number of mature oocytes  
59 in whole mounts preparations, assuming that all the oocytes larger than a  
60 certain diameter threshold are mature and recruited to be released. It is a  
61 basic, simple and inexpensive technique, however, it is not possible to de-  
62 termine the maturity stage of oocytes with the naked eye, especially at the  
63 beginning of the maturation process. This adds uncertainty to the fecundity  
64 estimates. Moreover, the gravimetric method can be a tedious and very time  
65 consuming procedure, especially for species with asynchronous oocyte devel-  
66 opment that simultaneously present a wide range of oocyte diameters within  
67 the ovary.

68 Assuming the basics of the gravimetric method and with the evolution of  
69 computerized image analysis, Witthames and Walker (1987) proposed alter-

70 native methods to estimate fecundity. Emerson et al. (1990), taking advan-  
71 tage of the precise classification of oocytes maturity stage from histological  
72 images under a microscope, developed a stereometric method based on the  
73 stereological approach proposed by Weibel and Gómez (1962) and Weibel  
74 (1979), that allows fecundity estimation guaranteeing at the same time the  
75 selection of mature oocytes by histology for fecundity estimation.

76 Stereology relates three-dimensional parameters (i.e., the volume) that  
77 define a structure with two-dimensional measures (i.e., the area) obtained  
78 from sections of this structure. Estimating the number of oocytes in each  
79 category (e.g., *previtelogenic*, *cortical alveoli*, *vitelogenic*, *atretic* or *hydrated*)  
80 and their relative area from histological sections is routinely done in many  
81 laboratories. Advantages and disadvantages of these methods are enumer-  
82 ated by Murua and Saborido-Rey (2003). Different interesting parameters  
83 can be estimated from a single sample using stereology: the spawning sta-  
84 tus of female, the atresia intensity and prevalence, the potential fecundity,  
85 the oocyte size distribution and maturation dynamics. For applying stere-  
86 ology to fecundity estimates some assumptions must be made — spherical  
87 shape of oocytes and homogeneous distribution of oocytes within the ovary  
88 — and correction factors have to be applied to adjust the oocyte frequency  
89 depending on their size (i.e., probability of being included in the histological  
90 section), because larger oocytes have a higher probability of appearing in the  
91 histological section than smaller ones. To estimate the relative area occu-  
92 pied by each oocyte category, usually a hexagonal grid of points is used. In

93 this grid, each point has the same associated area, so, counting the number  
94 of points that contact oocytes of one category and the number of oocytes  
95 of this category on the slide, the relative area and number of oocytes can  
96 be estimated and extrapolated to the entire ovary. Fine grids with a high  
97 number of points (i.e., small associated area) improves the accuracy of esti-  
98 mates but increases the time of processing the sample, because the counting  
99 is commonly done manually. Thus, there exists a trade-off between accuracy  
100 and time consumption of the method.

101 On the other hand, the oocytes' maturity stage has to be classified pre-  
102 cisely, which requires experienced technicians and specific training for each  
103 species under study. The process is often not reproducible and different  
104 results are obtained by different technicians.

105 Applications of computer vision are recently playing a more and more im-  
106 portant role in fisheries and fish farming industries. Mathiassen et al. (2011)  
107 provides a review of research and industrial solutions that use imaging tech-  
108 nologies for the inspection of fish and fish products related to post-harvest  
109 operations like: automatic sorting and grading, estimate the chemical com-  
110 position (e.g., salt, fat, proteins), weight estimation. Hu et al. (2012) use  
111 computer vision for fish diseases diagnose. Zion (2012) review the state of  
112 art of computer vision technologies in aquaculture, in which the main in-  
113 spection task are: counting fishes, size measurement and mass estimation,  
114 gender identification and quality assessment, species and stock identification  
115 and monitoring welfare. The inspection tasks are employed in all stages of

116 production from hatcheries to harvest. All the above mentioned computer  
117 vision approaches are focused on the analysis of images of the whole fish or  
118 a fish product.

119 However, despite the progress of computing tools based on image anal-  
120 ysis, the image analysis with commercial off-the-shelf software for fecundity  
121 estimation is still time-consuming, requires high technological imaging equip-  
122 ment and specialized technicians, and does not allow to review the calculation  
123 process. With the aim of giving an answer to all the needs and difficulties, we  
124 propose a multi-platform software (called Govocitos) that includes a specifi-  
125 cally designed algorithm for the automatic recognition of oocytes, and that  
126 allows their maturity stage classification from histological images as well as  
127 fecundity estimation according to the stereological principle. This software  
128 fulfills the following requirements:

- 129 1. Provides a friendly graphical user interface (GUI) to interactively work  
130 with histological images.
- 131 2. Uses an algorithm to automatically recognize and classify the mature  
132 oocytes in a histological image.
- 133 3. Estimates automatically the oocyte diameter distribution facilitating  
134 the study of fish reproductive biology (even for less experienced tech-  
135 nicians).
- 136 4. Provides data sharing among researchers from different laboratories  
137 and allows to review the results.

- 138 5. Works faster and more precisely than manual or semi-automatic tradi-  
139 tional methods.
- 140 6. It is accurate and trustworthy.

141 Govocitos is being used by the Instituto de Investigaci3n Mariñas of  
142 CSIC (Spanish Research Center) since 2012. A version of Govocitos run-  
143 ning locally in a personal computer can freely be downloaded from [http:](http://lia.ei.uvigo.es/daeira/software/govocitos)  
144 [//lia.ei.uvigo.es/daeira/software/govocitos](http://lia.ei.uvigo.es/daeira/software/govocitos). This paper is organized as  
145 follows: Section 2 first describes the architecture of the proposed system and  
146 then analyzes every module of the system and the underlying algorithms to  
147 automatically recognize and classify the mature oocytes in the histological  
148 image. Section 3 discusses the statistical evaluation of the automatic detec-  
149 tion and classification algorithms and, finally, Section 4 draws the conclusions  
150 and proposes future work.

## 151 2. Methods

### 152 2.1. System architecture

153 The system is structured in three logical layers: the graphical user in-  
154 terface (GUI) layer, the application logic layer and the data storage and  
155 communication layer. The implementation of the layers uses currently four  
156 modules. Figure 1 shows the architecture of the system. The GUI provides a  
157 user friendly interface to draw, interact and visualize data (see Section 2.5).  
158 The application layer refers to the data processing of inputs (see Sections 2.2,

2.3 and 2.6). The first two layers are enclosed in the Govocitos software that runs on a personal computer. The third layer is implemented on a server machine with Internet connection. Govocitos is a multi-platform software (Windows/Linux) written in the C++ programming language. The division into modules is:

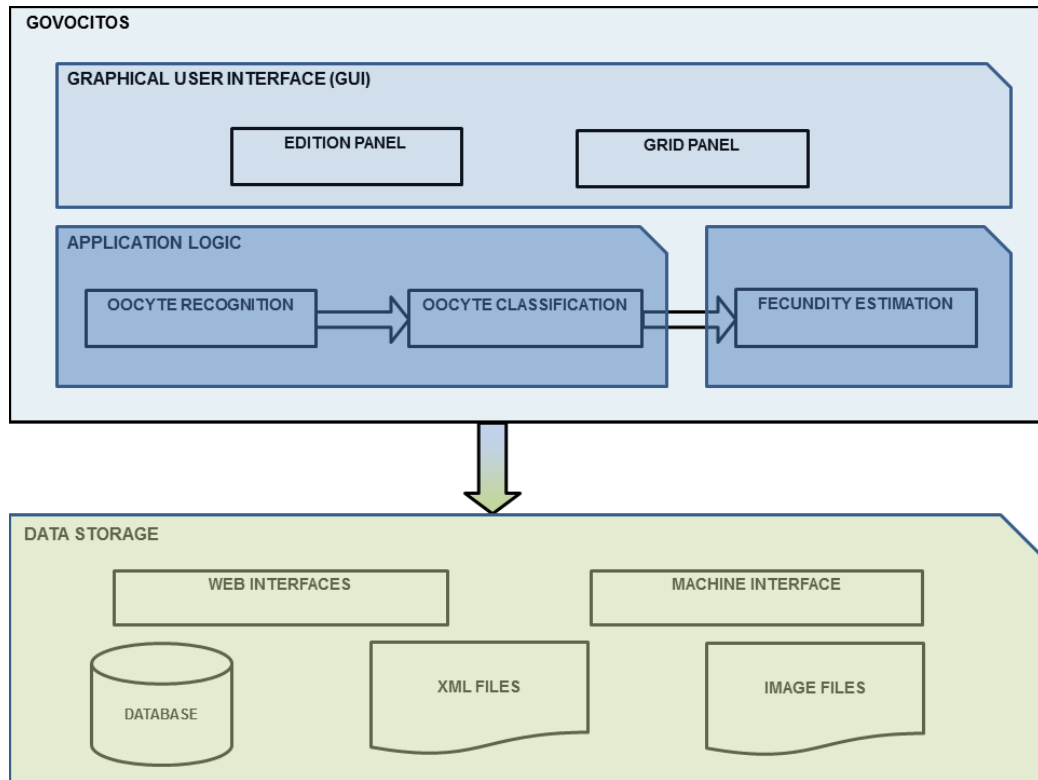


Figure 1: System architecture from the viewpoint of the developers.

**GUI:** an intuitive and friendly graphical user interface to manually draw the outline of matured oocytes and to specify its class (state of development and presence/absence of nucleus).



167 **Unsupervised detection and classification:** these modules process the  
168 histological image and automatically provide the outlines of matured  
169 oocytes and its classification. Afterwards, the experts can modify and  
170 supervise these results using the graphical interface.

171 **Fecundity:** it estimates the fecundity from the matured oocytes being rec-  
172 ognized and classified by one of the two first modules and some in-  
173 formation stored in the database like calibration, ovarian volume, fish  
174 weight, etc.

175 **Data storage:** the information required and calculated by Govocitos is sup-  
176 ported by either local or web-based databases and XML files.

177 Since these modules are independent among them, new modules may be  
178 added or existing ones may be modified easily, facilitating the expansion, the  
179 improvement and the usage of the system for other purposes.

## 180 *2.2. Oocyte recognition*

181 From the point of view of computer vision, the recognition of matured  
182 oocytes in histological images is a segmentation process in which an image is  
183 divided in objects (mature oocytes) and background (rest of image). Many  
184 image segmentation methods have been proposed in the last four decades, be-  
185 ing specially relevant the works of Sonka et al. (1999), Muñoz et al. (2003) and  
186 Papari and Petkov (2011)). These methods may be grouped in four families:  
187 thresholding, region-based, edge-based, and mixture methods. Some tech-  
188 niques enclosed in each group were tested by us in Alén et al. (2006), Anta

189 et al. (2007) and Cernadas et al. (2008)). The main conclusion at which we  
 190 arrived is that histological images are textured and very complex, and that  
 191 conventional methods are not robust and general enough to work satisfac-  
 192 tory with different fish species and illumination conditions. Consequently,  
 193 for the segmentation of histological microscopic fish images we propose a  
 194 multi-scalar Canny (MSC) filter followed by an information fusion step to  
 195 remove edges detected by different runs of the Canny filter. Our method has  
 196 two variants: an unsupervised and a supervised one, sharing their first step.  
 197 There is a consensus in the scientific community about the superior perfor-  
 198 mance of the Canny edge detector proposed by Canny (1986), in relation to  
 199 other common differential operators like Sobel, Prewitt, Roberts, Laplacian,  
 200 Laplacian of Gaussian (LoG) and difference of Gaussians (DoG).

201 The Canny edge detector is based on DoG performing the following steps:  
 202 i) smooth the input image using a Gaussian kernel with a given smoothing  
 203 parameter  $\sigma$ ; ii) differentiate using a first difference operator; iii) perform the  
 204 non-maxima suppression process, which finds local maxima in the direction  
 205 perpendicular to the edge; and iv) perform the thresholding with hysteresis,  
 206 using two thresholds (low and high, denoted by  $T_L$  and  $T_H$  respectively) in  
 207 order to avoid spurious responses. The filter performance depends critically  
 208 on the parameter values (thresholds and smoothing parameter  $\sigma$ ).

209 The pixel neighborhood in the Canny filter is controlled by  $\sigma$  and its  
 210 optimal value depends on the type and size of objects of interest in the image.  
 211 High  $\sigma$  values smooth the inner regions of cells which are often textured.

212 When cells are very close to each other or edges are weak, high  $\sigma$  values blur  
 213 interesting edges as well. In the latter case, finer scales (i.e., low  $\sigma$  values)  
 214 must be used, although the Canny filter will detect more noisy edges. For  
 215 a given  $\sigma$  value, the variation of thresholds  $T_L$  and  $T_H$  controls the strength  
 216 in the gradient image. High thresholds detect the strongest edges (normally  
 217 true edges), but they often miss other true edges. So, low thresholds are also  
 218 necessary to detect weak true contours.

219 Let  $I$  be a histological image,  $S$  be the number of smothing values,  
 220  $C_S = \{\sigma_i \mid i = 1, \dots, S \text{ and } \sigma_i > 0.1\}$  be the set of scales, and let  
 221  $C_T = \{(T_L^j, T_H^j) \mid j = 1, \dots, T, \text{ and } 0 < T_L^j \leq T_H^j < 1\}$  be a set of thresh-  
 222 old pairs. The MSC filter is applied to  $I$  in several steps. For all  $\sigma_i \in C_S$ :  
 223 1) smooth  $I$  with Gaussian filter using  $\sigma_i$  to obtain  $I_{Si}$ ; 2) apply gradient  
 224 operator to  $I_{Si}$ , providing the edge map image  $I_{Si}^M$ ; 3) perform non-maxima  
 225 suppression on  $I_{Si}^M$ ; and 4) perform edge detection with hysteresis using all  
 226 the threshold pairs in  $C_T$ . The threshold values initially in the interval  $(0, 1)$   
 227 are scaled to an absolute threshold pair for the pixel values in the image,  
 228 usually in the interval  $(0, 255)$ , so that their final values depend on the his-  
 229 togram of gradient magnitudes in the image (magnitude of  $I_{Si}^M$ ). The output  
 230 of the MSC filter is a set  $E_I$  with all the detected edges. Since the minimum  
 231 diameter,  $d_{\min}$ , of matured oocytes is an intrinsic attribute of each fish specie,  
 232 which can be specified by technicians, we apply a size filter to  $E_I$  removing  
 233 all edges whose convex hull diameter is lower than  $d_{\min}$ .

234 In the *unsupervised algorithm*, the input is the histological image  $I$  and

235 the output are the detected oocytes. Let  $E_I = \{e_j^I \mid j = 1, \dots, M\}$  be the  
 236  $M$  edges detected by the MSC filter. We know that the oocytes of interest  
 237 should have an elliptical shape for the majority of cells. We select a subset  
 238  $E_I^R \subseteq E_I$  comprising the edges whose convex hull roundness is lower than  
 239  $r_{\max}$ ,  $E_I^R = \{e_j^I \in E_I \mid r(e_j^I) < r_{\max}\}$ . Finally, we apply an *overlap test*  
 240 in  $E_I^R$  to select the edges which are candidates to represent an oocyte: 1)  
 241 if the centroid of an edge  $i$  lies inside the edge  $j$  and vice versa, the two  
 242 edges are considered candidates for the same oocyte; and 2) if the centroid  
 243 of  $i$  lies inside the edge  $j$  but the opposite is not true, edge  $i$  is considered a  
 244 noisy oocyte. Among the candidate edges for the same oocyte, one of them  
 245 is selected randomly.

246 In the *supervised version*, the output are also the detected oocytes, but the  
 247 input also includes one point  $(x_o, y_o)$  inside a true oocyte, which is previously  
 248 marked by the expert in the histological image using the Govocitos GUI. An  
 249 edge  $e_j^I \in E_I$  is a candidate to be the detected oocyte, if  $(x_o, y_o)$  is inside  $e_j^I$ .  
 250 If there is more than one candidate, we randomly choose one of them.

### 251 2.3. Oocyte classification

252 Once the outlines of matured oocytes are recognized in the histological  
 253 image, the software will classify the oocytes into classes according to the  
 254 presence or absence of the nucleus and into states according to the develop-  
 255 mental stage, i.e., *cortical alveoli*, *hydrated*, *vitelline*, and *atretic*. The work of  
 256 González-Rufino et al. (2013) tested the performance of both classifications

257 using the most popular texture features and classifiers in the literature. The  
258 combination of a Support Vector Machine classifier (SVM) with first order  
259 statistics of the color RGB image and the uniform rotation invariant Local  
260 Binary Patterns (LBP) of a grey scale version of the image was included in  
261 Govocitos to provide the best trade-off between computation time and effi-  
262 ciency for both types of classifications. The texture feature vector has only  
263 15 inputs.

264 The classifiers which discriminate between presence and absence of the  
265 nucleus and discriminate among the developmental stages must be trained  
266 before starting the classification process. To train a classifier, the system ran-  
267 domly selects a number of patterns (previously labeled manually by users).  
268 The patterns are stored in the database. Specifically, 1000 patterns (oocytes)  
269 including exemplars of each class (with and without nucleus for the classifica-  
270 tion according to presence/absence of nucleus, and *cortical alveoli*, *hydrated*,  
271 *vitelogenic* and *atretic* according to development stage). The maximum size  
272 of 1000 patterns allows to avoid slow training times. Given this information,  
273 the GUI of Govocitos includes a functionality to train the classifiers for each  
274 species. The classifiers can be trained as many times as needed, because a  
275 larger number of training samples may improve the classification accuracy.

#### 276 2.4. Data storage

277 All data in the system are stored in an RDBMS (Relational Database  
278 Management System) using the SQL (Structured Query Language) for inter-

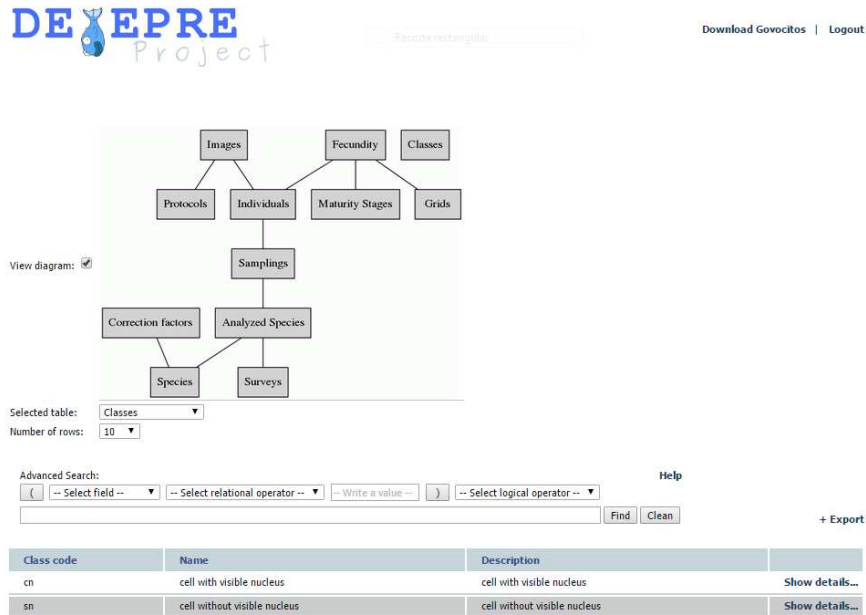


Figure 2: Screenshot showing the web interface to interact with the database.

279 action, XML (eXtensible Markup Language) files containing image attributes  
 280 and the proper image files (usually in TIFF format, but other formats are  
 281 supported as well). Access to the database is provided with a user interface  
 282 and a machine interface. The expected way of access for users is the web  
 283 interface, as it can be seen in the screenshot of Figure 2. The machine in-  
 284 terface works with common network protocols. All ways of access have been  
 285 designed to be both secure and easy-to-use. The image files contain the digi-  
 286 talized histological samples. The XML files store non-structured information  
 287 like outlines and classes for each detected or annotated mature oocyte in the  
 288 histological image. There is just one XML file per image. The RDBMS also  
 289 stores authentication information.

## 290 2.5. Graphical user interface

291 The flowchart describing the functionality of Govocitos is shown in Figure  
292 3. The graphical user interface offers different, so called, *views* depending on  
293 the current process the user carries out. Figure 4 shows the main interface  
294 window of Govocitos.

295 A typical working session for a user might be: first, the user opens all the  
296 processed images of an individual fish, just clicking in the specimen identifi-  
297 cation code to estimate fish fecundity, or a single colored histological image to  
298 recognize and classify its mature oocytes automatically (see Figure 3). Once  
299 a histological image is selected, the user performs the unsupervised detection  
300 or goes to the editing view to draw the outlines of target objects (i.e., mature  
301 oocytes). In this view, the user can delete or modify noisy/erroneous detected  
302 objects. Then, the user marks those oocytes that have not been recognized  
303 by the automatic algorithm. Re-starting with this new clue, the supervised  
304 algorithm (see Section 2.2) will try to provide the outlines of the annotated  
305 oocytes as well. After this, the user could again supervise the results using  
306 the editing tools. Figure 5 shows the editing view of Govocitos. Once the  
307 outlines of all mature oocytes are correct, Govocitos automatically classi-  
308 fies them into their class with or without nucleus and development stage.  
309 Classes and stages can be manually modified or re-assigned in the edition  
310 panel. Govocitos computes and displays the mean diameters and areas for  
311 the selected classes and stages. It also stores the data in files for further  
312 analysis, including the outlines and classifications of the matured oocytes in

313 the histological image.

314 The fecundity view encloses the functionality to estimate the individual  
315 fish fecundity. To perform this action, the XML files containing the outline  
316 and classification of oocytes for all images associated to a single fish had to  
317 be previously created, i.e., at least one image has to be processed and saved  
318 in the database. The fecundity is estimated using the Equation 1 with a  
319 previously overlaid hexagonal grid on the image. Traditionally, a 168-point  
320 grid covering only the central area of the image has been used to estimate  
321 fecundity (see Figure 6). However, Govocitos allows to configure the grid size,  
322 i.e., the number of points and their inbetween distance. Moreover, Govocitos  
323 allows to estimate the fecundity based on the entire image, i.e., considering  
324 all pixels as the Weibel grid area. Govocitos estimates the partial areas of  
325 each oocyte in all maturity stages counting all pixels occupied by each of  
326 them.

327 Independently of the grid size or the number of points, Govocitos esti-  
328 mates fecundity almost instantaneously. Figure 7 shows the fecundity view  
329 of Govocitos, which visualizes histograms of the distribution of diameters by  
330 class and stage, estimates the fecundity and exports all data in files and/or  
331 in the database.

## 332 *2.6. Fecundity estimation*

333 Stereology fundamentals have been applied to estimate the number of  
334 atretic, developing and hydrated oocytes, following the method developed by



Emerson et al. (1990), which is based on the Delesse principle and uses the equation proposed by Weibel and Gómez (1962) and presented by Murua et al. (2003). Specifically, the fecundity  $F$  is calculated by the following equation:

$$F = O_v \frac{k}{\beta} \frac{\sqrt{N_a^3}}{\sqrt{v_i}} \quad (1)$$

where  $\beta$  is the ratio between the longest and shortest axis of oocytes transected through the nucleus,  $O_v$  is the ovary volume,  $N_a$  is the number of oocyte transsections per unit area,  $v_i$  is the partial area of oocyte in the histological section, and  $k$  is a size distribution coefficient.

## 2.7. Sample preparation and image acquisition

Ovaries at different maturity stages from two fish species were selected to develop and test Govocitos: European hake (*Merluccius merluccius*) and pouting (*Trisopterus luscus*). One ovary lobe was fixed in 4% buffered formaldehyde and one slice per ovary of all females was embedded in paraffin. Then, 3  $\mu m$  sections were cut and stained with haematoxylin and eosin for later microscopical analysis. Fecundity estimates were based on 4 microscope fields per ovary section using a Leica DMRE microscope connected to a Leica DFC320 FX digital video camera with 3.3 Mpixel and a spatial resolution of 1.09  $\mu m$ . The exposure time and color balance are set automatically.

Figure 4 shows a typical image in Govocitos where the mature oocytes are already detected and classified. Different colors correspond to different oocyte development stage: *cortical alveoli* (black), *hydrated* (blue), *vitelline*

356 (red), and *atretic* (green); and the type of line corresponds to the oocyte  
357 class: continuous line for cells with nucleus and dashed lines for cells without  
358 nucleus.

### 359 3. Results

360 A network version of Govocitos was installed at the Instituto de Inves-  
361 tigaci3n Mariñas (IIM) of the State Agency Consejo Superior de Investi-  
362 gaciones Científicas (CSIC) in 2012 with the aim to evaluate the software  
363 operating in a real environment. The IIM biologists used Govocitos in their  
364 daily work to calculate the fecundity, for which they need to recognize and  
365 classify all matured oocytes in the histological images. Their operations in  
366 the Govocitos GUI were logged in files for a later statistical evaluation. The  
367 following subsections summarize the results achieved for the automatic detec-  
368 tion and classification algorithms, the issues related to the grid size used to  
369 estimate the fecundity, and the issues related to the time needed by experts  
370 to analyze each sample or entire fish.

#### 371 3.1. Statistical evaluation of the detection and classification algorithms

372 A total of 61 images belonging to 8 fishes of European hake (31 images)  
373 and 8 to pouting (30 images) were analyzed, detecting and classifying 2405  
374 oocytes (1186 for European hake and 1219 for pouting). The number of  
375 mature oocytes per image varied significantly ranging from 18 to 73 oocytes  
376 for European hake (with a mean value of 38 oocytes) and 23 to 70 for pout-  
377 ing (with a mean value of 40). Technicians performed the following tasks to

378 detect and classify the mature oocytes in every histological image using Gov-  
379 ocitos: 1) load an image into Govocitos; 2) run the non-supervised oocytes  
380 detection algorithm; 3) delete the false positive (erroneous) oocytes; 4) run  
381 the supervised oocytes detection algorithm by clicking inside unrecognized  
382 oocytes; then the algorithm provides their outlines; 5) complete or modify  
383 manually the detection of oocytes; 6) run the automatic classification algo-  
384 rithm to discriminate among oocytes with/without visible nucleus and their  
385 development stage; and, finally, 7) modify manually the label of misclassified  
386 oocytes. All these steps were done with the GUI of Govocitos.

Table 1: Accuracy provided by Govocitos for oocytes detection and classification in histo-  
logical images (in percentages).

	All species		European hake		Lane snapper	
	mean(std)	min-max	mean(std)	min-max	mean(std)	min-max
Detection algorithm						
Non-supervised	63.6(14.4)	19.5-88.5	61.6(9.9)	40.9-77.5	65.6(17.8)	19.5-88.5
Supervised	80.0(13.6)	27.0-98.0	79.7(9.3)	56.8-95.9	80.3(17.1)	27.0-98.0
False positive	19.7(14.8)	0.0-60.0	19.8(15.1)	0-51.5	19.7(14.7)	4.8-60.0
Oocyte classification						
With/without nucleus	83.8(11.3)		78.1(12.2)		81.4(18.6)	
Development stage	87.1(14.6)		89.4(6.8)		92.8(4.9)	

std: standard deviation, min: minimum, max: maximum.

387 For the statistical evaluation of the detection algorithms, we consider  
388 that an oocyte is correctly detected if the user does not modify the outline  
389 provided by the detection algorithm. We consider that an oocyte is a false  
390 positive whenever the user deletes the oocyte outline provided by the detec-  
391 tion algorithm. We count the number of oocytes correctly detected after the  
392 non-supervised and the supervised detection algorithm (Steps 2 and 4 above,  
393 respectively) and the number of false positives (Step 3). For the classifica-

tion algorithm (Steps 6 and 7), we count the number of oocytes correctly classified by Govocitos.

Table 1 shows the results for both species. The classifier for each kind of classification was trained for each species using the same images as in González-Rufino et al. (2013). The detection algorithm does not need any training. The calibration parameters required are the minimum diameter of mature oocytes ( $100\ \mu m$  for both species) and the spatial resolution of the image acquisition process ( $1.09\ \mu m$  per pixels for both species). Although both parameters are not critical, including them decreases the number of false positives. The accurate detection rate is the ratio between the number of oocytes correctly detected and the total number of detected oocytes in the image. The false positive rate is the ratio between the number of oocytes detected erroneously and the total number of oocytes detected in the image by the software.

In relation to the detection algorithm, the mean number of oocytes correctly detected by the non-supervised algorithm is 63.6% and by the supervised version it is 80.0%. Hence, the supervised approach increases significantly the accuracy by approximately 16 points. There is a great variability among images for both species (about 9 points for European hake and 17 for pouting). Table 1 shows the minimum and maximum rates per image achieved for both species and steps of evaluation. Although the variability is higher for pouting (minimum correct detection of 27 and maximum of 98 for the supervised algorithm), it is still high for European hake (minimum of 56.8

417 to maximum of 95.9). We could not establish any correlation between the  
418 number of oocytes in the image and the correct detection rates. Visually, we  
419 can observe that the lowest detection accuracies correspond to images con-  
420 taining a high number of misshapen oocytes (e.g., hydrated oocytes) which  
421 makes the outline detection difficult, or atretic oocytes, which have the con-  
422 tour broken.

423 For some images, the automatic detection of the oocytes outline is al-  
424 most perfect (with rates higher than 95%). Nevertheless, for some others  
425 the correct detection rate is rather low (only 27%). Therefore, we suggest  
426 that automatic detection of oocytes should be supervised by an expert be-  
427 fore starting the fecundity calculation. Regarding the oocyte classification,  
428 the accuracy to classify the oocytes classes (with/without nucleus) is 83.8%  
429 on average for both species and 87.1% for development stage classification  
430 (joining the classes *viteline* and *atretic*). The performance is slightly higher  
431 for pouting (81.4% and 92.8% for classes and stages, respectively) than for  
432 European hake (78.1% and 89.4%, respectively).

### 433 3.2. Software validation

434 Validation is essential for any proposed software system. We have to en-  
435 sure the correctness of the software comparing the fecundity results provided  
436 by both the traditional method and Govocitos (using the same parameters,  
437 e.g., a grid of 168 points). Already Dominguez-Petit et al. (2011) did a pre-  
438 liminary study comparing the fecundity estimated using grids of different

439 characteristics concluding that for the spatial resolution and species of this  
440 work, the fecundity estimates vary depending on grid characteristics (size,  
441 number of points and distance between points). The optimal level is reached  
442 for grids with interpoint distance of 30 pixels or lower, but the interpoint  
443 distance for the traditional grid of 168 points is 125 pixels for these images.

444     The estimation of the time needed to analyze each fish is really hard, es-  
445 sentially due to the performance variability of the automatic recognition algo-  
446 rithm among samples. The automatic recognition of oocytes takes less than  
447 one minute on a common personal computer for an image with 1550x2088  
448 pixels. The automatic classification step is almost instantaneous. So, the  
449 time needed to analyze a sample is dominated by the time needed to mod-  
450 ify and/or add the miss-detected and miss classified oocytes in the sample.  
451 Once the oocytes are detected and classified in the image, the diameters, ar-  
452 eas and fecundity estimations are obtained almost instantaneously. As well,  
453 Govocitos integrates other processing tasks into a single program and it al-  
454 lows to review the intermediate results each time, hence, it avoids repetitions  
455 of complete analysis when the results are not adequate. Anyway, for most of  
456 the images the automatic computation of diameter, profile histograms and  
457 fecundity is adequate enough, alleviating the expert's daily work and making  
458 it easy to carry out fish reproductive studies by non-experts technicians.

## 459 4. Conclusions

460 Govocitos offers an easy and automatic way to estimate fish fecundity  
461 based on the traditional stereological method: use of a grid of points defined  
462 by the user, counting of points and objects inside the grid, estimation of stere-  
463 ological parameters, partial areas and volumes and estimation of potential  
464 fecundity and partial fecundity (for each development stage). Govocitos also  
465 classifies oocytes based on presence/absence of nucleus as well as develop-  
466 mental stage, calculates cell diameters, areas and roundness, builds diameter  
467 frequency histograms and exports data for later analyses, integrating all these  
468 tasks in a single application. In addition, Govocitos provides the possibility  
469 of varying the grid characteristics; even more, it allows using all pixels of  
470 the image as grid points increasing the accuracy of the calculation of par-  
471 tial areas of different objects within the image. Further, it allows checking  
472 and reviewing the calculations in every moment, automatic recognition and  
473 classification of oocytes and interactive supervision of the process by experts.

474 Govocitos includes a multi-scalar Canny filter to automatically detect the  
475 oocyte outline, achieving an accuracy of 64% in an unsupervised way, which  
476 increases up to 80% when the expert marks only one point on the unrecog-  
477 nized oocytes using the GUI. The classifier uses Support Vector Machines  
478 (SVM) combined with texture (Local Binary Patterns) and color features  
479 achieving an accuracy of 84% to discriminate between oocytes with or with-  
480 out nucleus and an accuracy of 87% to discriminate among three development  
481 stages (*cortical alveoli*, *hydrated* and *vitelline/atretic*).

482 It works both automatically and manually, or semi-automatically, as well  
483 as in local or network way. In summary, Govocitos is an easy-to-handle soft-  
484 ware (even for less experienced personnel) that facilitates laboratory routines  
485 for studying fish reproductive ecology for different fish species. It is free soft-  
486 ware that can be easily used after a short training period, offering the same  
487 or even better performance than other expensive and complex image analysis  
488 software tools.

489 Although some first tests using Govocitos with histological images of other  
490 laboratories provide good visual results, in future work, we plan to evaluate  
491 Govocitos more systematically in other real environments (i.e. in other lab-  
492 oratories) to test the robustness of the oocyte recognition and classification  
493 algorithms taking into account different sample preparations and acquisi-  
494 tion conditions of the histological images. We also plan to extend Govocitos  
495 to other applications which require quantitative analysis on images. This  
496 analysis may eventually require to extend and adapt the detection and clas-  
497 sification modules.

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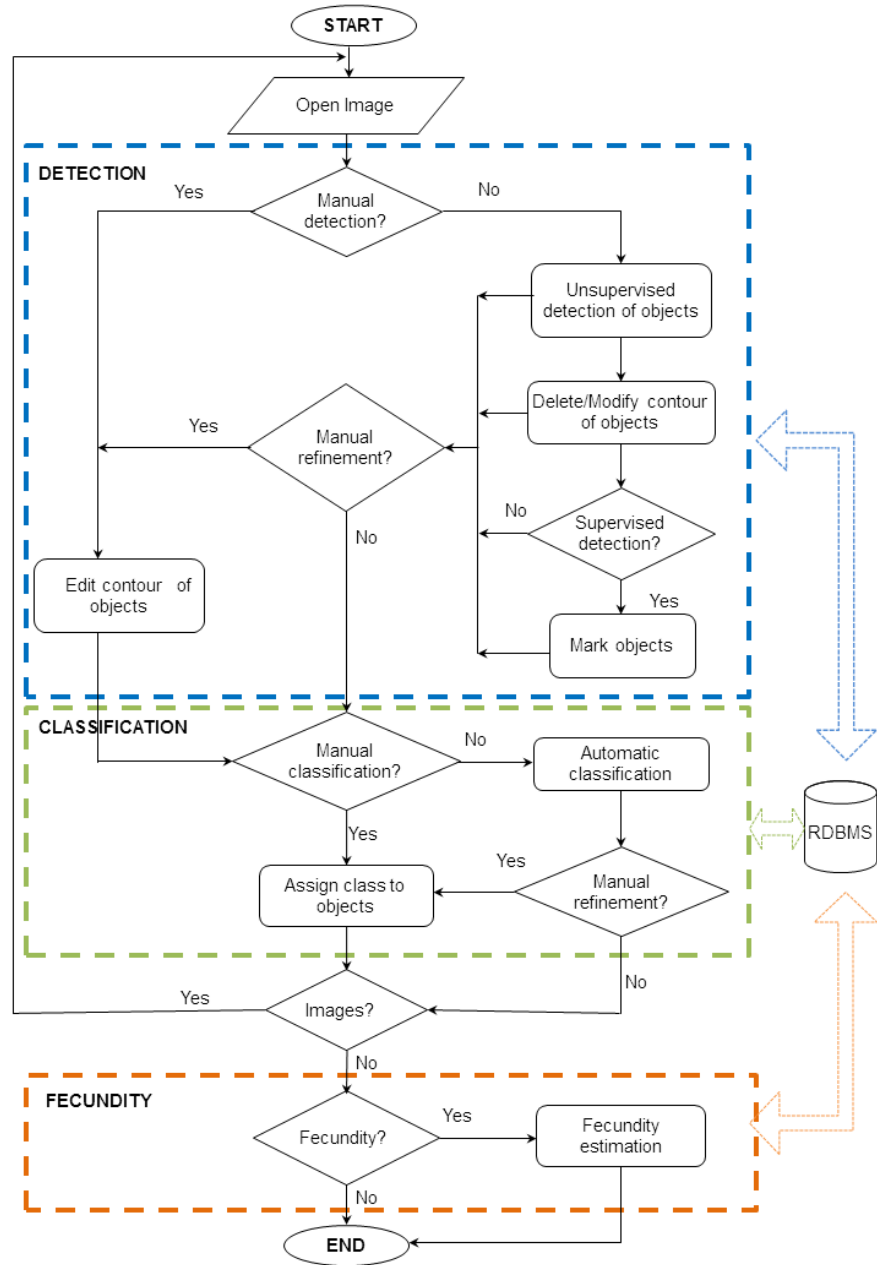


Figure 3: A flowchart containing the main task of Govocitos.

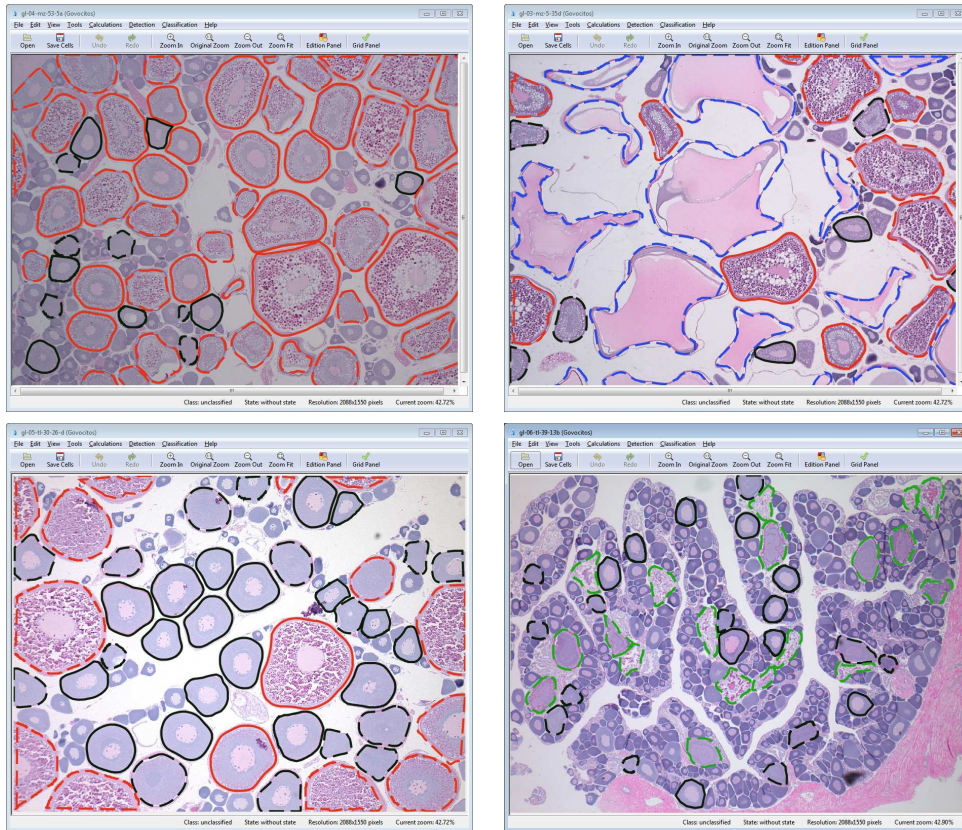


Figure 4: Govocitos software showing some typical histological images of fish ovaries from two species: European hake (upper panels) and pouting (lower panels). The true contours of mature oocytes are overlaid (the color and line type show the stage and class of each of them).

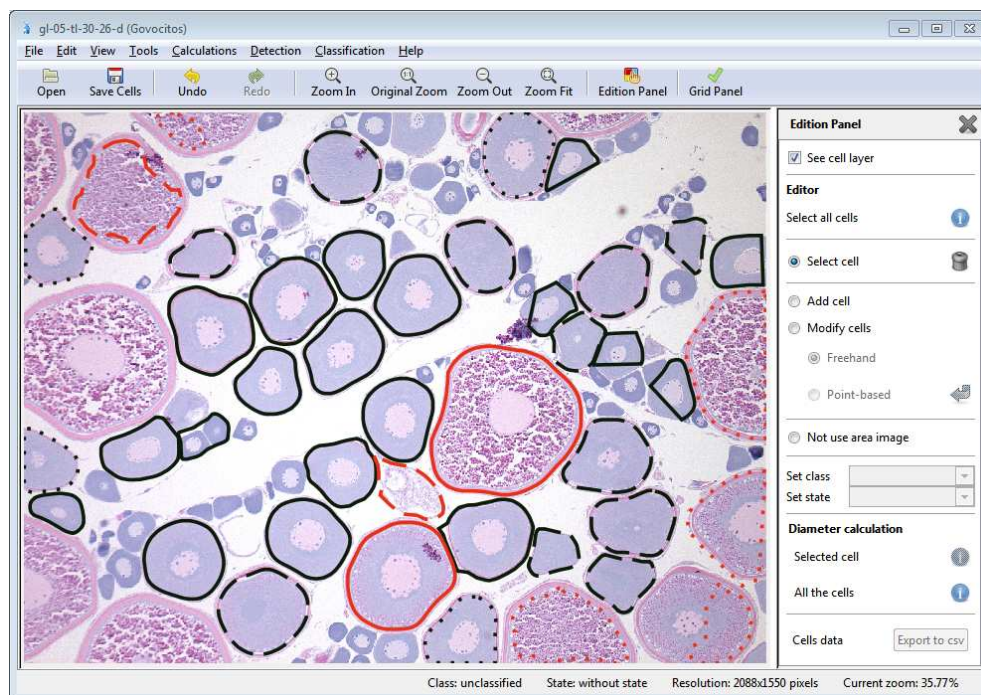


Figure 5: Govocitos software showing the editing view after automatic recognition and classification steps.



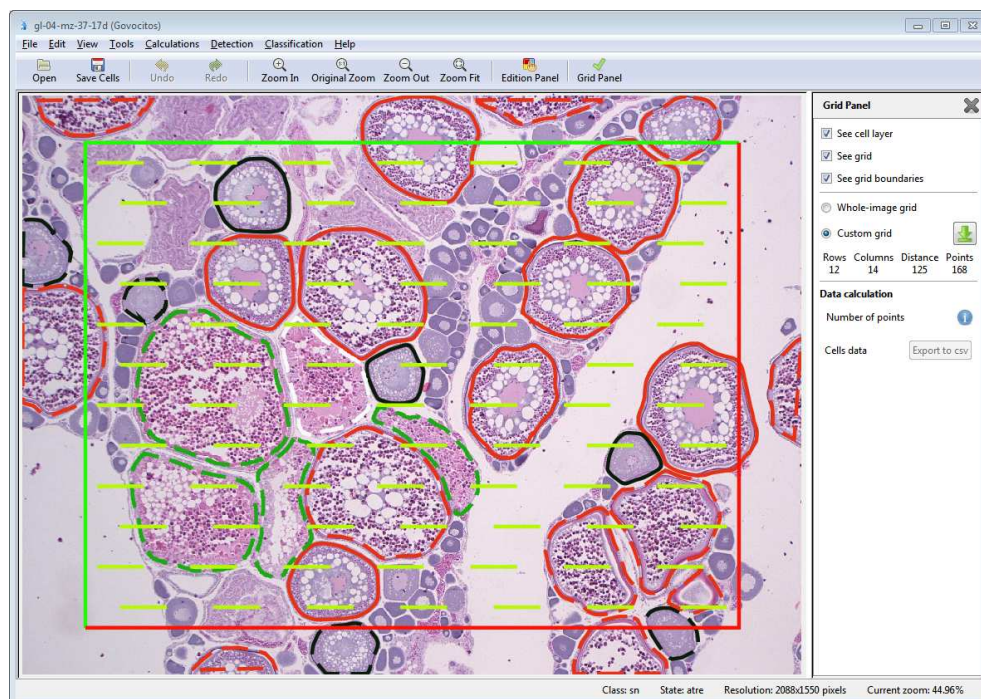


Figure 6: Govocitos software showing the grid view with the traditional grid of 168 points.



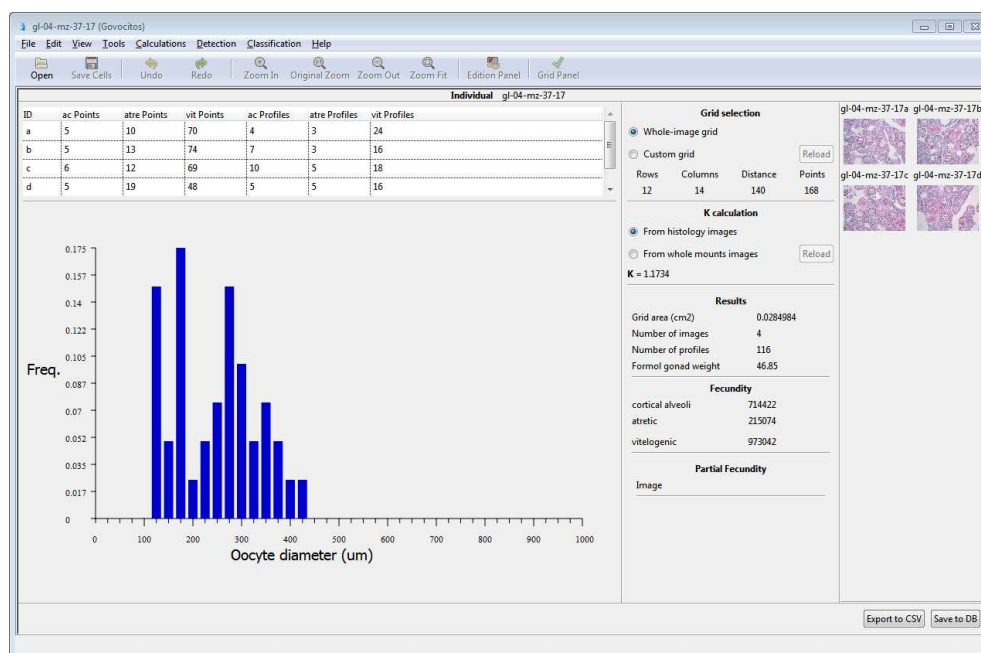


Figure 7: Govocitos software showing the fecundity view.