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Nonparametric Stein-type Shrinkage Covariance Matrix Estimators in **High-Dimensional Settings**

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Abstract

Estimating a covariance matrix is an important task in applications where the number of variables is larger than the number of observations. In the literature, shrinkage approaches for estimating a high-dimensional covariance matrix are employed to circumvent the limitations of the sample covariance matrix. A new family of nonparametric Stein-type shrinkage covariance estimators is proposed whose members are written as a convex linear combination of the sample covariance matrix and of a predefined invertible target matrix. Under the Frobenius norm criterion, the optimal shrinkage intensity that defines the best convex linear combination depends on the unobserved covariance matrix and it must be estimated from the data. A simple but effective estimation process that produces nonparametric and consistent estimators of the optimal shrinkage intensity for three popular target matrices is introduced. In simulations, the proposed Stein-type shrinkage covariance matrix estimator based on a scaled identity matrix appeared to be up to 80% more efficient than existing ones in extreme high-dimensional settings. A colon cancer dataset was analyzed to demonstrate the utility of the proposed estimators. A rule of thumb for adhoc selection among the three commonly used target matrices is recommended.

Keywords— Covariance matrix, High-dimensional settings, Nonparametric estimation, Shrinkage estimation

1 Introduction

The problem of estimating large covariance matrices arises frequently in modern applications, such as in genomics, cancer research, clinical trials, signal processing, financial mathematics, pattern recognition and computational convex geometry. Formally, the goal is to estimate the covariance matrix Σ based on a sample of N independent and identically distributed (i.i.d) p-variate random vectors $\mathbf{X}_1, \ldots, \mathbf{X}_N$ with mean vector $\boldsymbol{\mu}$ in the "small N, large p" paradigm, that is when N is a lot smaller compared to p. It is a well-known fact that the sample covariance matrix

$$\mathbf{S} = \frac{1}{N-1} \sum_{i=1}^{N} (\mathbf{X}_i - \bar{\mathbf{X}}) (\mathbf{X}_i - \bar{\mathbf{X}})^T,$$

where $\bar{\mathbf{X}} = \sum_{i=1}^{N} \mathbf{X}_i / N$ is the sample mean vector, is not performing satisfactory in high-dimensional settings. For example, **S** is singular even when Σ is a strictly positive definite matrix. Recent research in estimating high-dimensional covariance matrices includes banding, tapering, penalization and shrinkage methods. We focus on the Steinian shrinkage method (Stein, 1956) as adopted by Ledoit and Wolf (2004) because it leads to covariance matrix estimators that are: (i) non-singular (ii) well-conditioned, (iii) invariant to permutations of the order of the p variables, (iv) consistent to departures from a multivariate normal model, (v) not necessarily sparse, (vi) expressed in closed form and (vii) computationally cheap regardless of p.

Ledoit and Wolf (2004) proposed a Stein-type covariance matrix estimator for Σ based on

$$\mathbf{S}^{\star} = (1 - \lambda)\mathbf{S} + \lambda \nu \mathbf{I}_{p},\tag{1}$$

where \mathbf{I}_p is the $p \times p$ identity matrix, and where λ and ν minimize the risk function $\mathbf{E}\left[||\mathbf{S}^* - \boldsymbol{\Sigma}||_F^2\right]$, that is

and

$$\lambda = \frac{\mathrm{E}\left[||\mathbf{S} - \boldsymbol{\Sigma}||_F^2\right]}{\mathrm{E}\left[||\mathbf{S} - \nu \mathbf{I}_p||_F^2\right]}$$
$$\nu = \frac{\mathrm{tr}(\boldsymbol{\Sigma})}{p}.$$

The optimal shrinkage intensity parameter λ in (1) suggests how much we must shrink the eigenvalues of the sample covariance matrix **S** towards the eigenvalues of the target matrix $\nu \mathbf{I}_p$. For example, $\lambda = 0$ implies no contribution of $\nu \mathbf{I}_p$ to \mathbf{S}^* , while $\lambda = 1$ implies no contribution of **S** to \mathbf{S}^* . Intermediate values for λ reveal the simultaneous contribution of **S** and $\nu \mathbf{I}_p$ to \mathbf{S}^* . Despite the attractive interpretation, \mathbf{S}^* is not a covariance matrix estimator because ν and λ depend on the unobservable covariance matrix Σ . For this reason, Ledoit and Wolf (2004) proposed to plug-in nonparametric *N*-consistent estimators for ν and λ in (1) and use the resulting matrix as a shrinkage covariance matrix estimator for Σ . Although ν seems to be adequately estimated by $\hat{\nu} = \text{tr}(\mathbf{S})/p$, we noticed via simulations that the estimator of λ proposed by Ledoit and Wolf (2004) was biased in extreme high-dimensional settings and when $\Sigma = \mathbf{I}_p$. This is counter-intuitive because $\lambda = 1$ and the plug-in estimator of \mathbf{S}^* is expected to be as close as possible to the target matrix $\nu \mathbf{I}_p$. In addition, this observation underlines the importance of choosing a target matrix that approximates well the true underlying dependence structure. To this direction, Fisher and Sun (2011) proposed Stein-type shrinkage covariance matrix estimators for alternative target matrices. However, they are no longer nonparametric as their construction was based on a multivariate normal model assumption.

Motivated by the above, we improve estimation of the optimal shrinkage intensity by providing a consistent estimator of λ in high-dimensional settings. To construct the estimator of λ we follow three simple steps: (i) expand the expectations in the numerator and denominator of λ assuming a multivariate normal model, (ii) prove that this ratio, say λ^* , is asymptotically equivalent to λ , and (iii) replace each unknown parameter in λ^* with unbiased and consistent estimators constructed using U-statistics. The last step is essential in our proposal so as to ensure consistent and nonparametric estimation of λ . Further, we relax the normality assumption in Fisher and Sun (2011) for target matrices other than $\nu \mathbf{I}_p$ in (1) and we illustrate how to estimate consistently the corresponding optimal shrinkage intensities in high-dimensional settings. In other words, we propose a new nonparametric family of Stein-type shrinkage estimators suitable for high-dimensional settings that preserve the attractive properties mentioned in the first paragraph and can accommodate arbitrary target matrices.

The rest of this paper is organized as follows. In Section 2, we present the working framework that allows us to manage the high-dimensional setting. Section 3 contains the main results where we derive consistent and nonparametric estimators for the optimal shrinkage intensity of three different target matrices. We evaluate the performance of the proposed covariance matrix estimators via simulations in Section 4. In Section 5, we illustrate the use of the proposed estimators in a colon cancer study and we recommend a rule of thumb for selecting the target matrix. In Section 6, we summarize our findings and discuss future research. The technical details can be found in the appendix. Throughout the paper, we use $||\mathbf{A}||_F^2 = \operatorname{tr}(\mathbf{A}^T \mathbf{A})/p$ to denote the scaled Frobenius norm of \mathbf{A} , $\operatorname{tr}(\mathbf{A})$ to denote the trace of the matrix \mathbf{A} , $\mathbf{D}_{\mathbf{A}}$ to denote the diagonal matrix with elements the diagonal elements of \mathbf{A} , and $\mathbf{A} \circ \mathbf{B}$ to denote the Hadamard product of the matrices \mathbf{A} and \mathbf{B} . In the above, it is implicit that \mathbf{A} and \mathbf{B} are $p \times p$ matrices.

2 Framework for High-Dimensional Settings

Let $\mathbf{X}_1, \ldots, \mathbf{X}_N$ be a sample of i.i.d. *p*-variate random vectors from the nonparametric model

$$\mathbf{X}_i = \mathbf{\Sigma}^{1/2} \mathbf{Z}_i + \boldsymbol{\mu},\tag{2}$$

where $\boldsymbol{\mu} = \mathrm{E}[\mathbf{X}_i]$ is the *p*-variate mean vector, $\boldsymbol{\Sigma} = \mathrm{cov}[\mathbf{X}_i] = \boldsymbol{\Sigma}^{1/2} \boldsymbol{\Sigma}^{1/2}$ is the $p \times p$ covariance matrix, and $\mathbf{Z}_1, \ldots, \mathbf{Z}_N$ is a collection of i.i.d. *p*-variate random vectors. Instead of distributional assumptions,

moments restrictions are imposed on the random variables in \mathbf{Z}_i . In particular, let Z_{ia} be the *a*-th random variable in \mathbf{Z}_i and suppose that $\mathbf{E}[Z_{ia}] = 0$, $\mathbf{E}[Z_{ia}^2] = 1$, $\mathbf{E}[Z_{ia}^4] = 3 + B$ with $-2 \leq B < \infty$ and for any nonnegative integers l_1, \ldots, l_4 such that $\sum_{\nu=1}^4 l_{\nu} \leq 4$

$$\mathbf{E}[Z_{ia_1}^{l_1} Z_{ia_2}^{l_2} Z_{ia_3}^{l_3} Z_{ia_4}^{l_4}] = \mathbf{E}[Z_{ia_1}^{l_1}] \mathbf{E}[Z_{ia_2}^{l_2}] \mathbf{E}[Z_{ia_3}^{l_2}] \mathbf{E}[Z_{ia_4}^{l_4}],$$
(3)

where the indexes a_1, \ldots, a_4 are distinct. The nonparametric model (2) includes the *p*-variate normal distribution $N_p(\boldsymbol{\mu}, \boldsymbol{\Sigma})$ as a special case obtained if Z_{ia} are i.i.d. N(0, 1) random variables. Since B = 0 under a multivariate normal model, B can be interpreted as a measure of departure of the fourth moment of Z_{ia} to that of a N(0, 1) random variable. The assumption of common fourth moments is made for notational ease and the results of this paper remain valid even if $E[Z_{ia}^4] = 3 + B_a$ for finite B_a ($a = 1, \ldots, p$). Model (2) assumes that \mathbf{X}_i is a linear combination of \mathbf{Z}_i , a random vector that contains standardized white noise variables. Unlike the usual definition of white noise, model (2) makes no distributional assumptions for \mathbf{Z}_i and it allows dependence patterns given that the pseudo-independence condition (3) holds. Therefore, the working framework can cover situations in which the white noise mechanism does not produce independent and/or identically distributed random variables.

To handle the high-dimensional setting, we restrict the dimension of Σ by assuming that

as
$$N \to \infty, p = p(N) \to \infty, \frac{\operatorname{tr}(\boldsymbol{\Sigma}^4)}{\operatorname{tr}^2(\boldsymbol{\Sigma}^2)} \to t_1 \text{ and } \frac{\operatorname{tr}(\boldsymbol{\Sigma}^2)}{\operatorname{tr}^2(\boldsymbol{\Sigma})} \to t_2,$$
 (4)

with $0 \leq t_2 \leq t_1 \leq 1$. This flexible assumption does not specify the limiting behavior of p with respect to N, thus including the case where p/N is bounded (Ledoit and Wolf, 2004). At the same time, it does not seriously restrict the class of covariance matrices for Σ that satisfy assumption (4). For example, members of this class are covariance matrices whose eigenvalues are bounded away from 0 and ∞ (Chen et al., 2010), banded first-order auto-regressive covariance matrices such that $\Sigma = \{\sigma_a \sigma_b \rho^{|a-b|} I(|a-b| \leq k)\}_{1 \leq a,b \leq p}$ with $-1 \leq \rho \leq 1$, σ_a and σ_b bounded positive constants and $1 \leq k \leq p$ (Chen et al., 2010), covariance matrices that have a few divergent eigenvalues as long as they diverge slowly (Chen and Qin, 2010), and covariance matrices with a compound symmetry correlation pattern, that is $\Sigma = \{\sigma_a \sigma_b \rho\}_{1 \leq a,b \leq p}$. Model (2) and assumption (4) constitute an attractive working framework to handle the 'small N, large p' paradigm. A similar but stricter working framework was considered by Chen et al. (2010) in the context of hypothesis testing for Σ . By contrast, we avoid making assumptions about moments of fifth or higher order and we allow more options for Σ .

3 Main Results

Under the nonparametric model (2), the expectations in the numerator and denominator of the optimal shrinkage intensity λ in (1) can be explicitly calculated to obtain that

$$\lambda = \frac{\mathrm{E}\left[||\mathbf{S} - \boldsymbol{\Sigma}||_{F}^{2}\right]}{\mathrm{E}\left[||\mathbf{S} - \boldsymbol{\nu}\mathbf{I}||_{F}^{2}\right]} = \frac{\mathrm{tr}(\boldsymbol{\Sigma}^{2}) + \mathrm{tr}^{2}(\boldsymbol{\Sigma}) + B\mathrm{tr}(\mathbf{D}_{\boldsymbol{\Sigma}}^{2})}{N\mathrm{tr}(\boldsymbol{\Sigma}^{2}) + \frac{p - N + 1}{p}\mathrm{tr}^{2}(\boldsymbol{\Sigma}) + B\mathrm{tr}(\mathbf{D}_{\boldsymbol{\Sigma}}^{2})}$$

Since $\operatorname{tr}(\mathbf{D}_{\mathbf{A}}^2) = \operatorname{tr}(\mathbf{A} \circ \mathbf{A}) \leq \operatorname{tr}(\mathbf{A}^2) \leq \operatorname{tr}^2(\mathbf{A})$ for any positive definite matrix \mathbf{A} , the contribution of $B\operatorname{tr}(\mathbf{D}_{\mathbf{\Sigma}}^2)$ to λ under assumption (4) is negligible when compared to that of $\operatorname{tr}(\mathbf{\Sigma}^2)$ or $\operatorname{tr}^2(\mathbf{\Sigma})$. Ignore $B\operatorname{tr}(\mathbf{D}_{\mathbf{\Sigma}}^2)$ in λ and define

$$\lambda^{\star} = \frac{\operatorname{tr}(\boldsymbol{\Sigma}^2) + \operatorname{tr}^2(\boldsymbol{\Sigma})}{N\operatorname{tr}(\boldsymbol{\Sigma}^2) + \frac{p - N + 1}{p}\operatorname{tr}^2(\boldsymbol{\Sigma})}$$

This is the optimal shrinkage intensity of the multivariate normal model or, more generally, $\lambda = \lambda^*$ when B = 0 in the nonparametric model (2). Under assumption (4), it follows that

$$\begin{aligned} |\lambda - \lambda^{\star}| &= \frac{(N-1)\left(\operatorname{tr}(\boldsymbol{\Sigma}^2) - \frac{1}{p}\operatorname{tr}^2(\boldsymbol{\Sigma})\right)}{N\left(\operatorname{tr}(\boldsymbol{\Sigma}^2) - \frac{1}{p}\operatorname{tr}^2(\boldsymbol{\Sigma})\right) + \frac{p+1}{p}\operatorname{tr}^2(\boldsymbol{\Sigma})} \\ &\times \frac{|B|\operatorname{tr}(\mathbf{D}_{\boldsymbol{\Sigma}}^2)}{N\left(\operatorname{tr}(\boldsymbol{\Sigma}^2) - \frac{1}{p}\operatorname{tr}^2(\boldsymbol{\Sigma})\right) + \frac{p+1}{p}\operatorname{tr}^2(\boldsymbol{\Sigma}) + B\operatorname{tr}(\mathbf{D}_{\boldsymbol{\Sigma}}^2)} \\ &\leq \frac{|B|\frac{\operatorname{tr}(\mathbf{D}_{\boldsymbol{\Sigma}}^2)}{\operatorname{tr}^2(\boldsymbol{\Sigma})}}{N\left(\frac{\operatorname{tr}(\boldsymbol{\Sigma}^2) - \frac{1}{p}\right) + \frac{p+1}{p} + B\frac{\operatorname{tr}(\mathbf{D}_{\boldsymbol{\Sigma}}^2)}{\operatorname{tr}^2(\boldsymbol{\Sigma})}} \to 0, \end{aligned}$$

where |k| denotes the absolute value of the real number k. Therefore, the optimal shrinkage intensity obtained under normality is asymptotically equivalent to the optimal shrinkage intensity with respect to model (2) as long as the trace ratios restrictions in (4) hold. This means that it suffices to construct a nonparametric and consistent estimator of λ^* to estimate λ . To accomplish this, replace the unknown parameters $\operatorname{tr}(\Sigma)$ and $\operatorname{tr}(\Sigma^2)$ in λ^* with the unbiased estimators

$$Y_{1N} = U_{1N} - U_{4N} = \frac{1}{N} \sum_{i=1}^{N} \mathbf{X}_{i}^{T} \mathbf{X}_{i} - \frac{1}{P_{2}^{N}} \sum_{i \neq j}^{*} \mathbf{X}_{j}^{T} \mathbf{X}_{i}$$

and

$$Y_{2N} = U_{2N} - 2U_{5N} + U_{6N}$$

= $\frac{1}{P_2^N} \sum_{i \neq j}^* (\mathbf{X}_i^T \mathbf{X}_j)^2 - 2 \frac{1}{P_3^N} \sum_{i \neq j \neq k}^* \mathbf{X}_i^T \mathbf{X}_j \mathbf{X}_i^T \mathbf{X}_k + \frac{1}{P_4^N} \sum_{i \neq j \neq k \neq l}^* \mathbf{X}_i \mathbf{X}_j^T \mathbf{X}_k \mathbf{X}_l^T$

respectively, where $P_t^s = s!/(s-t)!$ and \sum^* denotes summation over mutually distinct indices. Note that U_{1N} and U_{2N} are the unbiased estimators of $\operatorname{tr}(\Sigma)$ and $\operatorname{tr}(\Sigma^2)$ respectively, when the data are centered around the mean vector (i.e., $\boldsymbol{\mu} = \mathbf{0}$), while the remaining terms (U_4, U_5 and U_6) are Ustatistics of second, third and fourth order that ensure the unbiasedness of Y_{1N} and Y_{2N} when $\boldsymbol{\mu} \neq \mathbf{0}$. In B, we argue that Y_{1N} and Y_{2N} are ratio-consistent estimators to $\operatorname{tr}(\Sigma)$ and $\operatorname{tr}(\Sigma^2)$ respectively. Here, it should be noted a statistic $\hat{\theta}$ is called a ratio-consistent estimator to θ if $\hat{\theta}/\theta$ converges in probability to one. Therefore, it follows from the continuous mapping theorem that

$$\hat{\lambda} = \frac{Y_{2N} + Y_{1N}^2}{NY_{2N} + \frac{p - N + 1}{p}Y_{1N}^2}$$

is a consistent estimator of λ . The proposed Stein-type shrinkage estimator for Σ ,

$$\hat{\mathbf{S}}^{\star} = (1 - \hat{\lambda})\mathbf{S} + \hat{\lambda}\hat{\nu}\mathbf{I}_p,$$

is obtained by plugging-in $\hat{\nu} = Y_{1N}/p$ and $\hat{\lambda}$ in (1).

3.1 Alternative target matrices

Next, we consider target matrices other than $\nu \mathbf{I}_p$ in (1). This extension is motivated by situations where $\lambda \to 1$ and $\nu \mathbf{I}_p$ is not a good approximation of Σ . In this case, $\hat{\mathbf{S}}^{\star}$ remains a well-defined and non-singular covariance matrix estimator but it fails to reflect the underlying dependence structure.

Let \mathbf{T} be a well-conditioned and non-singular target matrix, and define the matrix

$$\mathbf{S}_T^{\star} = (1 - \lambda_T)\mathbf{S} + \lambda_T \mathbf{T}.$$
 (5)

Simple algebraic manipulation shows that the optimal shrinkage intensity

$$\lambda_T = \frac{\mathrm{E}\left[||\mathbf{S} - \boldsymbol{\Sigma}||_F^2\right] + \mathrm{E}\left[\mathrm{tr}\{(\mathbf{S} - \boldsymbol{\Sigma})(\boldsymbol{\Sigma} - \mathbf{T})\}\right]/p}{\mathrm{E}\left[||\mathbf{S} - \mathbf{T}||_F^2\right]}$$
(6)

minimizes the expected risk function $E[||\mathbf{S}_T^* - \boldsymbol{\Sigma}||_F^2]$. A closed form solution for λ_T can be derived by calculating the expectations in (6) with respect to model (2). The key idea of our proposal is to simplify the estimation process for λ_T by identifying terms in the numerator and denominator of λ_T that can be safely ignored under assumption (4). One approach is to examine whether the optimal shrinkage intensity under the multivariate normal model assumption is asymptotically equivalent to λ_T . Whenever this is the case, we can set B = 0 in λ_T and replace the remaining parameters with unbiased and ratio-consistent estimators to obtain $\hat{\lambda}_T$. The proposed Stein-type shrinkage covariance matrix estimator is

$$\hat{\mathbf{S}}_T^{\star} = (1 - \hat{\lambda}_T)\mathbf{S} + \hat{\lambda}_T \mathbf{T}.$$

Note that if we set $\mathbf{T} = \nu \mathbf{I}_p$ then $\lambda_T = \lambda$ and thus $\mathbf{S}_T^* = \mathbf{S}^*$. We provide the estimator of λ_T for two target matrices: i) the identity matrix $\mathbf{T} = \mathbf{I}_p$, and ii) the diagonal matrix $\mathbf{T} = \mathbf{D}_{\mathbf{S}}$ whose diagonal elements are the sample variances. To guarantee the consistency of λ_T , we suppose that $t_1 = t_2 = 0$ in (4). This assumption does not heavily affects the class of Σ under consideration. In fact, all the dependence patterns mentioned in Section 2 satisfy this stronger version of assumption (4) except the compound symmetry correlation matrix. We believe that this is a small price to pay if we are willing to increase the range of the target matrices in (1).

First, when $\mathbf{T} = \mathbf{I}_p$ in (5) the optimal shrinkage intensity in (6) becomes

$$\lambda_I = \frac{\operatorname{tr}(\boldsymbol{\Sigma}^2) + \operatorname{tr}^2(\boldsymbol{\Sigma}) + B\operatorname{tr}(\mathbf{D}_{\boldsymbol{\Sigma}}^2)}{\operatorname{tr}(\boldsymbol{\Sigma}^2) + \operatorname{tr}^2(\boldsymbol{\Sigma}) + (N-1)\operatorname{tr}\left[(\boldsymbol{\Sigma} - \mathbf{I}_p)^2\right] + B\operatorname{tr}(\mathbf{D}_{\boldsymbol{\Sigma}}^2)}$$

As before, we can ignore the terms $Btr(\mathbf{D}_{\Sigma}^2)$ in λ_I and prove that

$$\hat{\lambda}_I = \frac{Y_{2N} + Y_{1N}^2}{NY_{2N} + Y_{1N}^2 - (N-1)(2Y_{1N} - p)}$$

is a consistent estimator of λ_I .

When $\mathbf{T} = \mathbf{D}_{\mathbf{S}}$, we can use the results in A and prove that the optimal shrinkage intensity in (6) is

$$\begin{split} \lambda_D &= \frac{\mathrm{E}\left[||\mathbf{S} - \boldsymbol{\Sigma}||_F^2\right] + \mathrm{E}\left[\mathrm{tr}\{(\mathbf{S} - \boldsymbol{\Sigma})(\boldsymbol{\Sigma} - \mathbf{D}_{\mathbf{S}})\}\right]/p}{\mathrm{E}\left[||\mathbf{S} - \mathbf{D}_{\mathbf{S}}||_F^2\right]} \\ &= \frac{\left(\mathrm{E}[\mathrm{tr}(\mathbf{S}^2)] - \mathrm{tr}(\boldsymbol{\Sigma}^2)\right) + \left(\mathrm{E}[\mathrm{tr}(\boldsymbol{\Sigma}\mathbf{D}_{\mathbf{S}})] - \mathrm{E}[\mathrm{tr}(\mathbf{S}\mathbf{D}_{\mathbf{S}})]\right)}{\mathrm{E}[\mathrm{tr}(\mathbf{S}^2)] - \mathrm{E}[\mathrm{tr}(\mathbf{D}_{\mathbf{S}}^2)]} \\ &= \frac{\mathrm{tr}(\boldsymbol{\Sigma}^2) + \mathrm{tr}^2(\boldsymbol{\Sigma}) - 2\mathrm{tr}(\mathbf{D}_{\mathbf{\Sigma}}^2) + B\left[\mathrm{tr}(\mathbf{D}_{\mathbf{\Sigma}}^2) - \sum_{a=1}^p \sum_{b=1}^p \left(\boldsymbol{\Sigma}_{ab}^{1/2}\right)^4\right]}{N\mathrm{tr}(\boldsymbol{\Sigma}^2) + \mathrm{tr}^2(\boldsymbol{\Sigma}) - (N+1)\mathrm{tr}(\mathbf{D}_{\mathbf{\Sigma}}^2) + B\left[\mathrm{tr}(\mathbf{D}_{\mathbf{\Sigma}}^2) - \sum_{a=1}^p \sum_{b=1}^p \left(\boldsymbol{\Sigma}_{ab}^{1/2}\right)^4\right]}, \end{split}$$

where $\Sigma_{ab}^{1/2}$ denotes the (a, b)-th element of $\Sigma^{1/2}$. It can be shown that $B\left[\operatorname{tr}(\mathbf{D}_{\Sigma}^2) - \sum_{a=1}^p \sum_{b=1}^p \left(\Sigma_{ab}^{1/2}\right)^4\right]$ has negligible contribution to λ_D and that

$$Y_{3N} = U_{3N} - 2U_{7N} + U_{8N}$$
$$= \frac{1}{P_2^N} \sum_{i \neq j}^* \operatorname{tr}(\mathbf{X}_i \mathbf{X}_i^T \circ \mathbf{X}_j \mathbf{X}_j^T) - 2\frac{1}{P_3^N} \sum_{i \neq j \neq k}^* \operatorname{tr}(\mathbf{X}_i \mathbf{X}_i^T \circ \mathbf{X}_j \mathbf{X}_k^T) + \frac{1}{P_4^N} \sum_{i \neq j \neq k \neq l}^* \operatorname{tr}(\mathbf{X}_i \mathbf{X}_j^T \circ \mathbf{X}_k \mathbf{X}_l^T)$$

is an unbiased and ratio-consistent estimator to $tr(\mathbf{D}_{\Sigma}^2)$. The construction of Y_{3N} is closely related to that of Y_{1N} and Y_{2N} . To see this, note that Y_{3N} is a linear combination of three U-statistics, U_{3N} ,

the unbiased estimator of $tr(\mathbf{D}_{\Sigma}^2)$ when $\boldsymbol{\mu} = \mathbf{0}$, and U_{7N} and U_{8N} , which make the bias of Y_{3N} zero when $\boldsymbol{\mu} \neq \mathbf{0}$. Hence, a consistent estimator of λ_D is

$$\hat{\lambda}_D = \frac{Y_{2N} + Y_{1N}^2 - 2Y_{3N}}{NY_{2N} + Y_{1N}^2 - (N+1)Y_{3N}},$$

3.2 Remarks

There is no need to account for the mean vector when the random vectors are centered. In this case, the proposed shrinkage covariance matrix estimators can be obtained by replacing N-1 with N in the formula for $\hat{\lambda}$, $\hat{\lambda}_I$ or $\hat{\lambda}_D$, the sample covariance matrix **S** with $\sum_{i=1}^{p} \mathbf{X}_i \mathbf{X}_i^T / N$ and the statistics Y_{1N} , Y_{2N} and Y_{3N} with U_{1N} , U_{2N} and U_{3N} respectively. The last modification is due to the fact that U_{1N} , U_{2N} and U_{3N} are unbiased and ratio-consistent estimators to the targeted parameters when $\boldsymbol{\mu} = \mathbf{0}$.

Fisher and Sun (2011) derived Stein-type shrinkage covariance matrix estimators for the three target matrices considered herein under a multivariate normal model. We emphasize that our estimators differ in three important aspects. First, the consistency of the proposed estimators for the optimal shrinkage intensities λ , λ_I or λ_D is not sensitive to departures of the normality assumption. Second, $\operatorname{tr}(\Sigma^2)$ and $\operatorname{tr}(\mathbf{D}_{\Sigma})$ are estimated using *U*-statistics and are not based on the sample covariance matrix \mathbf{S} as in Fisher and Sun (2011). Consequently, we avoid terms such as $(\mathbf{X}_i^T \mathbf{X}_i)^2$ or \mathbf{X}_{ia}^4 , which allows us to control their asymptotic variance. Third, the class of covariance matrices under consideration in Fisher and Sun (2011) is different. They require the first four arithmetic means of the eigenvalues of Σ to converge while we place trace ratios restrictions on Σ .

3.3 Software implementation

The R (R Core Team, 2014) language package *Shrinkcovmat* implements the proposed Stein-type shrinkage covariance estimators and it is available at http://cran.r-project.org/web/packages/ShrinkCovMat. The core functions *shinkcovmat.equal*, *shinkcovmat.identity* and *shinkcovmat.unequal* provide the proposed shrinkage covariance matrix estimators when $\mathbf{T} = \nu \mathbf{I}_p$, $\mathbf{T} = \mathbf{I}_p$ and $\mathbf{T} = \mathbf{D}_s$ respectively. The statistics Y_{1N} , Y_{2N} and Y_{3N} are calculated using the computationally efficient formulas given in C. To modify the shrinkage estimators when $\boldsymbol{\mu} = \mathbf{0}$, one should set the argument *centered*=TRUE in the core functions.

4 Simulations

We carried out a simulation study to investigate the performance of the proposed Stein-type covariance matrix estimators. The *p*-variate random vectors $\mathbf{X}_1, \ldots, \mathbf{X}_N$ were generated according to model (2), where we employed the following three distributional scenarios regarding $\mathbf{Z}_1, \ldots, \mathbf{Z}_N$:

- 1. A normality scenario, in which $Z_{ia} \stackrel{i.i.d}{\sim} N(0,1)$.
- 2. A gamma scenario, in which $Z_{ia} = (Z_{ia}^* 8)/4$, $Z_{ia}^* \stackrel{i.i.d}{\sim} \text{Gamma}(4, 0.5)$ and thus B = 12.
- 3. A mixture of Scenarios 1 and 2, in which the first p/2 elements of \mathbf{Z}_i are distributed according to Scenario 1 and the remaining elements according to Scenario 2.

Scenarios 2 and 3 were used to empirically verify the nonparametric nature of the proposed methodology. To mimic high-dimensional settings, we let N range from 10 to 100 with increments of 10 and we let p = 100, 500, 1000, 1500 and 2500. The proposed family of covariance estimators was evaluated using $\hat{\mathbf{S}}^*$, the proposed shrinkage covariance matrix estimator when $\mathbf{T} = \nu \mathbf{I}_p$, which was then compared to $\hat{\mathbf{S}}_{LW}^*$ and $\hat{\mathbf{S}}_{FS}^*$, the corresponding shrinkage covariance matrix estimator proposed by Ledoit and Wolf (2004) and Fisher and Sun (2011) respectively. As in Ledoit and Wolf (2004), we assumed that $\boldsymbol{\mu} = \mathbf{0}$ and we made the necessary adjustments to $\hat{\mathbf{S}}^*$ and $\hat{\mathbf{S}}_{FS}^*$. Since $\hat{\mathbf{S}}_{FS}^*$ was constructed under a multivariate normal model assumption, its performance was evaluated only in sampling schemes that involved Scenario 1. We excluded the shrinkage estimator of Schäfer and Strimmer (2005) in

		$\hat{\lambda}$		$\hat{\lambda}_{L}$	LW	$\hat{\lambda}_{FS}$	
N	p	Mean	S.E.	Mean	S.E.	Mean	S.E.
10	100	0.9914	0.0133	0.8997	0.0196	0.9925	0.0119
	1000	0.9992	0.0013	0.9000	0.0019	0.9992	0.0012
	2500	0.9997	0.0005	0.9000	0.0008	0.9997	0.0005
50	100	0.9924	0.0113	0.9789	0.0167	0.9925	0.0112
	1000	0.9992	0.0012	0.9800	0.0020	0.9992	0.0012
	2500	0.9997	0.0005	0.9800	0.0008	0.9997	0.0005
100	100	0.9923	0.0114	0.9864	0.0145	0.9924	0.0113
	1000	0.9992	0.0012	0.9900	0.0020	0.9992	0.0011
	2500	0.9997	0.0005	0.9900	0.0008	0.9997	0.0004

Table 1: Estimation of the optimal shrinkage intensity $\lambda = 1$ under Scenario 1 when $\Sigma = \mathbf{I}_p$.

our simulation studies because they do not guarantee consistent estimation of λ in high-dimensional settings. Given Σ , N, p and the distributional scenario, we draw 1000 replicates based on which we calculated the simulated percentage relative improvement in average loss (SPRIAL) of $\hat{\mathbf{S}}^{\star}$ and of $\hat{\mathbf{S}}_{FS}^{\star}$ for estimating Σ . Formally, the SPRIAL criterion of $\hat{\Sigma}$ was defined as

$$SPRIAL(\hat{\boldsymbol{\Sigma}}) = \frac{\sum_{b=1}^{1000} ||\hat{\mathbf{S}}_{LW,b}^{\star} - \boldsymbol{\Sigma}||_{F}^{2} - \sum_{b=1}^{1000} ||\hat{\boldsymbol{\Sigma}}_{b} - \boldsymbol{\Sigma}||_{F}^{2}}{\sum_{b=1}^{1000} ||\hat{\mathbf{S}}_{LW,b}^{\star} - \boldsymbol{\Sigma}||_{F}^{2}} \times 100\%,$$

where $\hat{\mathbf{S}}_{LW,b}^{\star}$ denotes the estimator of Ledoit and Wolf (2004) at replicate b (b = 1, ..., 1000) and $\hat{\boldsymbol{\Sigma}}_{b}$ denotes the corresponding estimator of the competing estimation process that generates the covariance matrix estimator $\hat{\boldsymbol{\Sigma}}$. By definition, $\text{SPRIAL}(\boldsymbol{\Sigma}) = 100\%$ and $\text{SPRIAL}(\hat{\mathbf{S}}_{LW}^{\star}) = 0\%$. Therefore, positive (negative) values of $\text{SPRIAL}(\hat{\boldsymbol{\Sigma}})$ imply that $\hat{\boldsymbol{\Sigma}}$ is a more (less) efficient covariance matrix estimator than $\hat{\mathbf{S}}_{LW}^{\star}$ while values around zero imply that the two estimators were equally efficient. Note that we treated $\hat{\mathbf{S}}_{LW}^{\star}$ as the baseline estimator because Ledoit and Wolf (2004) have already established its efficiency over the sample covariance matrix \mathbf{S} .

To explore the situation in which the target matrix equals the true covariance matrix, we set $\mathbf{\Sigma} = \mathbf{I}_p$. In this case, accurate estimation of λ is crucial due to the fact that $\lambda = 1$ regardless of N and p. Table 1 contains the simulation results under Scenario 1 for the mean of the estimated optimal shrinkage intensities based on the proposed method $(\hat{\lambda})$, the approach of Ledoit and Wolf (2004) $(\hat{\lambda}_{LW})$ and the approach of Fisher and Sun (2011) $(\hat{\lambda}_{FS})$ when N = 10, 50, 100 and p = 100, 1000, 2500. As required, $\hat{\lambda}$, $\hat{\lambda}_{LW}$ and $\hat{\lambda}_{FS}$ were all restricted to lie on the unit interval. Compared to $\hat{\lambda}_{LW}$, $\hat{\lambda}$ appeared to be more accurate in estimating λ as it was substantially less biased and with slightly smaller standard error for all N and p. Although the bias of $\hat{\lambda}_{LW}$ decreased as N increased, $\hat{\lambda}_{LW}$ seemed to be biased downwards even when N = 100. These trends also occurred for Scenarios 2 and 3, and for this reason the results are omitted. As expected, no significant difference was noticed between $\hat{\lambda}$ and $\hat{\lambda}_{FS}$ under Scenario 1. Figure 1 displays SPRIAL($\hat{\mathbf{S}}^*$) under Scenario 2 - similar patterns were observed for the other two distributional scenarios. Clearly, $\hat{\mathbf{S}}^*$ was more effective than $\hat{\mathbf{S}}_{LW}^*$ for $p \leq 500$ (59.54% – 97.81%) and for p = 100 and $N \leq 50$ (15.24% – 61.16%). We should mention that $\hat{\mathbf{S}}^*$ and $\hat{\mathbf{S}}_{FS}^*$ were equally efficient, meaning that SPRIAL($\hat{\mathbf{S}}^*$) and SPRIAL($\hat{\mathbf{S}}_{FS}^*$) took similar values.

To investigate the performance of $\hat{\mathbf{S}}^*$ when Σ deviates slightly from the target matrix, we employed a tridiagonal correlation matrix for Σ in which the non-zero off-diagonal elements were all equal to 0.1. Figure 2 suggests that $\hat{\mathbf{S}}^*$ outperformed $\hat{\mathbf{S}}_{LW}^*$ in extreme high-dimensional settings ($N \leq 50$) under Scenario 3. The efficiency gains in using $\hat{\mathbf{S}}^*$ instead of $\hat{\mathbf{S}}_{LW}^*$ decreased at a much faster rate than before as N increased. Note that similar trends were observed under Scenarios 1 and 2 (results not shown).

Next, we considered dependence structures such that $\nu \mathbf{I}_p$ is a rather poor approximation of Σ . First, we defined Σ as a first order autoregressive correlation matrix with (a, b)-th element $\Sigma_{ab} = 0.5^{|a-b|}$. Although the results in Table 2 imply that $\hat{\lambda}$ is a more accurate estimator of λ than $\hat{\lambda}_{LW}$,

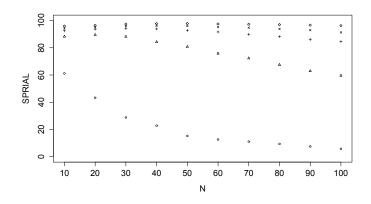


Figure 1: SPRIAL($\hat{\mathbf{S}}^*$) under Scenario 2 when $\boldsymbol{\Sigma} = \mathbf{I}_p$ and p = 100 (\circ symbols), 500 (+ symbols), 1000 (\triangle symbols), 1500 (x symbols) or 2500 (\diamond symbols).

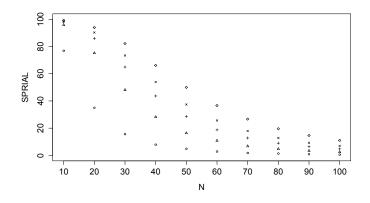


Figure 2: SPRIAL(\mathbf{S}^{\star}) under Scenario 3 when $\boldsymbol{\Sigma}$ is a tridiagonal correlation matrix with (a, b)-th element $\Sigma_{ab} = 0.1I(|a - b|)$ and p = 100 (\circ symbols), 500 (+ symbols), 1000 (\bigtriangleup symbols), 1500 (x symbols) or 2500 (\diamond symbols).

Figure 3 suggests that $\hat{\mathbf{S}}^{\star}$ and $\hat{\mathbf{S}}_{LW}^{\star}$ were almost equally efficient as soon as N = 30 and regardless of the dimensionality. We reached the same conclusions when we let Σ to be either a positive definite matrix whose p eigenvalues were drawn from the uniform distribution U(0.5, 10) or a block diagonal covariance matrix such that the dimension of each block matrix is $p/4 \times p/4$ and the eigenvalues of these 4 block matrices were drawn from U(0.5, 5), U(5, 10), U(10, 20) and U(0.5, 100) respectively. In particular, $\hat{\lambda}$ seemed to outperformed $\hat{\lambda}_{LW}$ for all configurations of (N, p, Σ) while SPRIAL($\hat{\mathbf{S}}^{\star}$) was close to zero unless $N \leq 30$. Hence, if the target matrix $\nu \mathbf{I}_p$ fails to describe adequately the dependence structure, we expect $\hat{\mathbf{S}}^{\star}$ to be more efficient than $\hat{\mathbf{S}}_{LW}^{\star}$ only for small sample sizes.

Further, we adopted a compound symmetry correlation form for Σ with correlation parameter $\rho = 0.5$. This is the only configuration of Σ where $t_1 \neq 0$ and $t_2 \neq 0$ in assumption (4). The estimator $\hat{\lambda}_{LW}$ appeared to be less biased but with larger standard error than $\hat{\lambda}$, while the SPRIAL($\hat{\mathbf{S}}^{\star}$) was always close to zero. The performance of $\hat{\mathbf{S}}^{\star}$ and $\hat{\mathbf{S}}_{LW}^{\star}$ was comparable across the related sampling schemes.

We also evaluated the performance of the inverse of the competing Stein-type shrinkage covariance matrix estimators using a modified version of the SPRIAL criterion, that is we replaced Σ , $\hat{\Sigma}$ and $\hat{\mathbf{S}}_{LW}^{\star}$ with their corresponding inverses in SPRIAL($\hat{\Sigma}$). The inverse of $\hat{\mathbf{S}}^{\star}$ was more efficient that of $\hat{\mathbf{S}}_{LW}^{\star}$ when Σ was equal to the identity matrix or to the tridiagonal correlation matrix, and quite surprisingly when Σ satisfied the compound symmetry correlation pattern and $N \leq 50$, as shown in Figure 4. In all other sampling schemes, the inverses of $\hat{\mathbf{S}}^{\star}$ and $\hat{\mathbf{S}}_{LW}^{\star}$ were comparable.

			$\hat{\lambda}$		$\hat{\lambda}_{LW}$		$\hat{\lambda}_{FS}$	
N	p	λ	Mean	S.E.	Mean	S.E.	Mean	S.E.
10	100	0.9392	0.9418	0.0300	0.8474	0.0277	0.9422	0.0277
	1000	0.9934	0.9933	0.0035	0.8940	0.0032	0.9933	0.0031
	2500	0.9973	0.9973	0.0014	0.8976	0.0013	0.9973	0.0013
50	100	0.7556	0.7571	0.0240	0.7418	0.0237	0.7571	0.0237
	1000	0.9678	0.9676	0.0033	0.9482	0.0032	0.9675	0.0032
	2500	0.9869	0.9868	0.0014	0.9671	0.0013	0.9868	0.0013
100	100	0.6071	0.6080	0.0175	0.6018	0.0175	0.6080	0.0174
	1000	0.9377	0.9375	0.0032	0.9281	0.0032	0.9375	0.0032
	2500	0.9741	0.9741	0.0013	0.9643	0.0013	0.9741	0.0013

Table 2: Estimation of λ under Scenario 1 when Σ satisfies a first-order auto-regressive correlation form with correlation parameter $\rho = 0.5$.

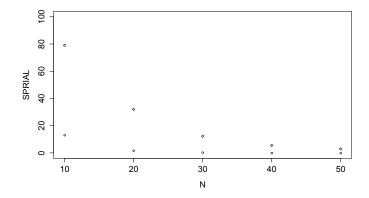


Figure 3: SPRIAL($\hat{\mathbf{S}}^*$) under Scenario 2 when $\boldsymbol{\Sigma}$ satisfies a first-order autoregressive form with correlation parameter $\rho = 0.5$ and p = 100 (\circ symbols) or 2500 (\diamond symbols).

Based on our simulations, SPRIAL($\hat{\mathbf{S}}^{\star}$) was an increasing function of p and a decreasing function of N while keeping the remaining parameters fixed. This indicates that, compared to $\hat{\mathbf{S}}_{LW}^{\star}$, $\hat{\mathbf{S}}^{\star}$ is an improved estimator of Σ in extreme high-dimensional settings. The nonparametric nature of $\hat{\mathbf{S}}^{\star}$ was empirically verified because both the SPRIAL criterion and the bias of $\hat{\lambda}$ seemed to remain constant across the three distributional scenarios. In addition, we find reassuring that the simulation results for $\hat{\lambda}$ and $\hat{\lambda}_{FS}$ and for $\hat{\mathbf{S}}^{\star}$ and $\hat{\mathbf{S}}_{FS}^{\star}$ were almost identical under a multivariate normal distribution. To this end, we also believe that the above trends together with the fact that we have not encountered a situation in which $\hat{\mathbf{S}}^{\star}$ was performing significantly worse than $\hat{\mathbf{S}}_{LW}^{\star}$ are favoring the consistency of the proposed covariance matrix estimators.

5 Empirical Study: Colon Cancer Study

Alon et al. (1999) described a colon cancer study where expression levels for 2000 genes were measured on 40 normal and on 22 colon tumor tissues. The dataset is available at http://genomicspubs.princeton.edu/oncology/affydata. As in Fisher and Sun (2011), we apply a logarithmic (base 10) transformation to the expression levels and sort the genes based on the between-group to within-group sum of squares (BW) selection criterion (Dudoit et al., 2002). In the literature, it has been suggested to estimate the covariance matrix of the genes using a subset of the p top genes (see, e.g., Fisher and Sun, 2011). With this in mind, we plan to estimate the covariance matrix of the normal and of the colon cancer group for subsets of the top p genes, where p = 250, 500, 750, 1000, 1250, 1500, 1750 and 2000. The Quantile-Quantile plots in Figure 5 raise concerns regarding the assumption that the 4 top

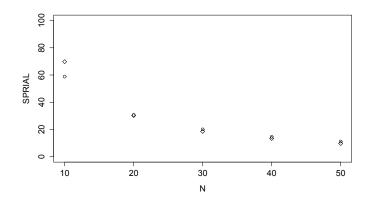


Figure 4: SPRIAL criterion for the inverse of $\hat{\mathbf{S}}^*$ under Scenario 3 when $\boldsymbol{\Sigma}$ satisfies a compound symmetry correlation matrix and p = 100 (\circ symbols) or 2500 (\diamond symbols).

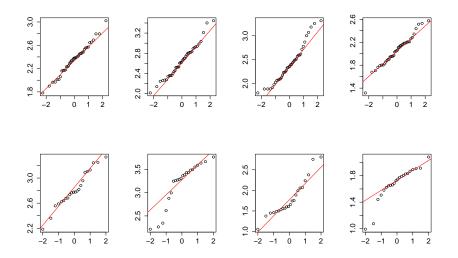


Figure 5: Quantile-Quantile plots for the expression levels of the 4 top genes according to the BW selection criterion. The top panel corresponds to the normal group and the bottom panel to the colon cancer group.

genes are marginally normally distributed. Since similar patterns occur for the remaining genes, we conclude that a multivariate normal model is not likely to hold and nonparametric covariance matrix estimation is required. For this purpose, we calculate $\hat{\mathbf{S}}^{\star}$, $\hat{\mathbf{S}}_{I}^{\star}$ and $\hat{\mathbf{S}}_{D}^{\star}$ for both groups and for all values of p.

The optimal shrinkage intensity λ_T in (5) is informative for the suitability of the selected target matrix **T** because it reveals its contribution to \mathbf{S}_T^* . If $\hat{\lambda}$, $\hat{\lambda}_I$ and $\hat{\lambda}_D$ differ significantly, then it is meaningful to choose the target matrix with the largest estimated optimal shrinkage intensity. Otherwise, the selection of the target matrix can be based on $\hat{\nu}$ and r, the range of the p sample variances. In particular, we suggest to employ \mathbf{I}_p when $\hat{\nu}$ is close to 1.00, $\mathbf{D}_{\mathbf{S}}$ when r is large (say more than one unit so as to account for the sampling variability), and $\nu \mathbf{I}_p$ when neither of these seems plausible. Table 3 displays the estimated optimal shrinkage intensities for the proposed family of shrinkage covariance estimators, $\hat{\nu}$ and r in both groups. The estimates of λ and λ_D are very similar in both groups for all subsets of genes and larger than those of λ_I . This suggests that $\mathbf{D}_{\mathbf{S}}$ and $\nu \mathbf{I}_p$ are better options than \mathbf{I}_p as a target matrix. Since r appears to be relatively small and constant across the top p genes in both groups, it seems sensible to set $\mathbf{T} = \nu \mathbf{I}_p$ for all p. Therefore, we recommend using $\hat{\mathbf{S}}^*$ to estimate the covariance matrix of the genes in the normal and in the colon cancer group and regardless of p.

		p							
Group	Statistic	250	500	750	1000	1250	1500	1750	2000
Normal	$\hat{\lambda}$	0.1407	0.1467	0.1465	0.1454	0.1435	0.1423	0.1414	0.1401
	$\hat{ u}$	0.0999	0.0963	0.0938	0.0916	0.0902	0.0894	0.0889	0.0882
	$\hat{\lambda}_D$	0.1402	0.1464	0.1463	0.1452	0.1434	0.1422	0.1413	0.1400
	r	0.4604	0.4638	0.4700	0.4714	0.4714	0.4714	0.4714	0.4714
	$\hat{\lambda}_I$	0.0564	0.0791	0.0913	0.0987	0.1036	0.1075	0.1105	0.1125
Colon	$\hat{\lambda}$	0.2035	0.2048	0.1970	0.1959	0.1952	0.1967	0.1969	0.1956
	$\hat{ u}$	0.1113	0.1060	0.1033	0.0996	0.0984	0.0975	0.0965	0.0958
	$\hat{\lambda}_D$	0.2027	0.2044	0.1967	0.1957	0.1950	0.1966	0.1968	0.1955
	r	0.4107	0.4107	0.4201	0.4201	0.4226	0.4226	0.4226	0.4226
	$\hat{\lambda}_I$	0.1081	0.1367	0.1476	0.1542	0.1599	0.1654	0.1688	0.1705

Table 3: The estimates of λ , λ_I , λ_D , ν and the range of the *p* sample variances (*r*) in the colon cancer dataset.

6 Discussion

We proposed a new family of nonparametric Stein-type shrinkage estimators for a high-dimensional covariance matrix. This family is based on improving the nonparametric estimation of the optimal shrinkage intensity for three commonly used target matrices at the expense of imposing mild restrictions for the covariance matrix Σ . In our simulations, the proposed shrinkage covariance matrix estimator $\hat{\mathbf{S}}^*$ was more precise than that of Ledoit and Wolf (2004) for estimating Σ , especially when the number of variables p is extremely large compared to the sample size N and/or $\nu \mathbf{I}_p$ is a good approximation of Σ . Unsurprisingly, the behavior of our estimators and that of Fisher and Sun (2011) were similar as long as an underlying multivariate normal model holds. However, we emphasize that our estimators are more flexible since they are robust to departures from normality. In addition, we recommended a simple data-driven strategy for selecting the target matrix in (5). The main idea is to compare $\hat{\lambda}, \hat{\lambda}_I$ and $\hat{\lambda}_D$ and choose the target matrix with the largest estimated optimal shrinkage intensity. If these estimates are similar and $\hat{\nu}$ is close to one, then it is sensible to use \mathbf{I}_p as target matrix. Otherwise, $\nu \mathbf{I}_p$ should be selected when the p sample variances are very close and \mathbf{D}_S when these vary. The R package *ShrinkCovMat* implements the proposed estimators.

Since \mathbf{S}^* , \mathbf{S}_I^* and \mathbf{S}_D^* are all biased estimators of $\boldsymbol{\Sigma}$, their risk functions might be unbounded especially when none of the corresponding target matrices describes adequately the underlying dependence structure. In these situations, a more suitable target matrix T in (5) must be considered. The corresponding λ_T should be estimated by following our guidelines in Section 3.1. If such a target matrix cannot be identified, one should choose among the alternative covariance matrix estimation methods mentioned in the Introduction.

In future research, we aim to investigate formal procedures for selecting the target matrix in (5) and to extend the proposed Steinian shrinkage approach for estimating correlation matrices.

A Useful Results

We list six results with respect to model (2) that allows us to derive the formulas for the λ , λ_I and λ_D :

1. $E[tr(\mathbf{S})] = tr(\mathbf{\Sigma}).$

2.
$$\operatorname{E}[\operatorname{tr}(\mathbf{S}^2)] = \frac{N}{N-1}\operatorname{tr}(\mathbf{\Sigma}^2) + \frac{1}{N-1}\operatorname{tr}^2(\mathbf{\Sigma}) + \frac{B}{N-1}\operatorname{tr}(\mathbf{D}_{\mathbf{\Sigma}}^2).$$

3.
$$\operatorname{E}[\operatorname{tr}^2(\mathbf{S})] = \operatorname{tr}^2(\mathbf{\Sigma}) + \frac{2}{N-1}\operatorname{tr}(\mathbf{\Sigma}^2) + \frac{B}{N-1}\operatorname{tr}(\mathbf{D}_{\mathbf{\Sigma}}^2)$$

4. $\operatorname{E}[\operatorname{tr}(\mathbf{D}_{\mathbf{S}})] = \operatorname{tr}(\mathbf{D}_{\mathbf{\Sigma}}).$

- 5. $\operatorname{E}[\operatorname{tr}(\mathbf{D}_{\mathbf{S}}^2)] = \operatorname{E}[\operatorname{tr}(\mathbf{SD}_{\mathbf{S}})] = \frac{N+1}{N-1}\operatorname{tr}(\mathbf{D}_{\mathbf{\Sigma}}^2) + \frac{B}{N-1}\sum_{a=1}^p \sum_{b=1}^p \left(\sum_{ab}^{1/2}\right)^4$, where $\sum_{ab}^{1/2}$ denotes the (a, b)-th element of $\mathbf{\Sigma}^{1/2}$.
- 6. $\operatorname{E}[\operatorname{tr}(\boldsymbol{\Sigma}\mathbf{D}_{\mathbf{S}})] = \operatorname{tr}(\mathbf{D}_{\mathbf{\Sigma}}^2).$

B Consistency of Y_{1N} , Y_{2N} and Y_{3N}

Note that $E[Y_{1N}] = E[tr(\mathbf{S})] = tr(\mathbf{\Sigma})$. Under assumption (4), derivations in Chen et al. (2010) imply that

$$\frac{\operatorname{Var}[Y_{1N}]}{\operatorname{tr}^2(\boldsymbol{\Sigma})} \le \left[\frac{2 + \max\{0, B\}}{N} + \frac{2}{N(N-1)}\right] \frac{\operatorname{tr}(\boldsymbol{\Sigma}^2)}{\operatorname{tr}^2(\boldsymbol{\Sigma})} \le \frac{3 + \max\{0, B\}}{N} \to 0.$$

Thus Y_{1N} is a ratio-consistent estimator to $\operatorname{tr}(\Sigma)$. Similarly, it can be shown that Y_{2N} and Y_{3N} are unbiased estimators to $\operatorname{tr}(\Sigma^2)$ and $\operatorname{tr}(\mathbf{D}_{\Sigma}^2)$ respectively, and that $\operatorname{Var}[Y_{2N}]/\operatorname{tr}^2(\Sigma^2) \to 0$ and $\operatorname{Var}[Y_{3N}]/\operatorname{tr}^2(\mathbf{D}_{\Sigma}^2) \to 0$ as $N \to \infty$. Hence, Y_{2N} and Y_{3N} are ratio-consistent estimators of $\operatorname{tr}(\Sigma^2)$ and $\operatorname{tr}(\mathbf{D}_{\Sigma}^2)$.

C Alternative Formulas for Y_{1N} , Y_{2N} and Y_{3N}

Note that

$$Y_{1N} = U_{1N} - U_{4N} = \frac{1}{N} \sum_{i=1}^{N} \mathbf{X}_i^T \mathbf{X}_i - \frac{1}{P_2^N} \sum_{i \neq j}^* \mathbf{X}_j^T \mathbf{X}_i = \operatorname{tr}(\mathbf{S}).$$

Himeno and Yamada (2014) showed that

$$Y_{2N} = U_{2N} - 2U_{5N} + U_{6N}$$

= $\frac{1}{P_2^N} \sum_{i \neq j}^* (\mathbf{X}_i^T \mathbf{X}_j)^2 - 2 \frac{1}{P_3^N} \sum_{i \neq j \neq k}^* \mathbf{X}_i^T \mathbf{X}_j \mathbf{X}_i^T \mathbf{X}_k$
+ $\frac{1}{P_4^N} \sum_{i \neq j \neq k \neq l}^* \mathbf{X}_i \mathbf{X}_j^T \mathbf{X}_k \mathbf{X}_l^T$
= $\frac{N-1}{N(N-2)(N-3)} [(N-1)(N-2)\operatorname{tr}(\mathbf{S}^2) + \operatorname{tr}^2(\mathbf{S}) - NQ]$

where

$$Q = \frac{1}{N-1} \sum_{i=1}^{N} \left[(\mathbf{X}_i - \bar{\mathbf{X}})^T (\mathbf{X}_i - \bar{\mathbf{X}}) \right]^2.$$

Also it can be shown that

$$\begin{split} Y_{3N} &= U_{3N} - 2U_{7N} + U_{8N} \\ &= \frac{1}{P_2^N} \sum_{i \neq j}^* \operatorname{tr}(\mathbf{X}_i \mathbf{X}_i^T \circ \mathbf{X}_j \mathbf{X}_j^T) - 2 \frac{1}{P_3^N} \sum_{i \neq j \neq k}^* \operatorname{tr}(\mathbf{X}_i \mathbf{X}_i^T \circ \mathbf{X}_j \mathbf{X}_k^T) \\ &+ \frac{1}{P_4^N} \sum_{i \neq j \neq k \neq l}^* \operatorname{tr}(\mathbf{X}_i \mathbf{X}_j^T \circ \mathbf{X}_k \mathbf{X}_l^T) \\ &= \frac{1}{P_2^N} \sum_{a=1}^p \sum_{i \neq j}^* X_{ia}^2 X_{ja}^2 \\ &- 4 \frac{1}{P_3^N} \left\{ \sum_{a=1}^p \left(\sum_{i=1}^N X_{ia}^2 \right) \left(\sum_{i=1}^{N-1} \sum_{j=i+1}^N X_{ia} X_{ja} \right) - \sum_{a=1}^p \sum_{i \neq j}^* X_{ia}^3 X_{ja} \right\} \\ &+ \frac{2}{P_4^N} \left\{ 2 \sum_{a=1}^p \left(\sum_{i=1}^{N-1} \sum_{j=i+1}^N X_{ia} X_{ja} \right)^2 - \sum_{a=1}^p \sum_{i \neq j}^* X_{ia}^2 X_{ja}^2 \right\}. \end{split}$$

Together these results reduce the computational cost for Y_{1N} , Y_{2N} and Y_{3N} from $O(N^4)$ to $O(N^2)$.

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