Data-driven stabilizations of goodness-of-fit tests

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Abstract

Exact null distributions of goodness-of-fit test statistics are generally challenging to obtain in tractable forms. Practitioners are therefore usually obliged to rely on asymptotic null distributions or Monte Carlo methods, either in the form of a lookup table or carried out on demand, to apply a goodness-of-fit test. There exist simple and useful transformations of several classic goodness-of-fit test statistics that stabilize their exact-n critical values for varying sample sizes n. However, detail on the accuracy of these and subsequent transformations in yielding exact p-values, or even deep understanding on the derivation of several transformations, is still scarce nowadays. The latter stabilization approach is explained and automated to (i) expand its scope of applicability and (ii) yield upper-tail exact p-values, as opposed to exact critical values for fixed significance levels. Improvements on the stabilization accuracy of the exact null distributions of the Kolmogorov–Smirnov, Cramér–von Mises, Anderson–Darling, Kuiper, and Watson test statistics are shown. In addition, a parameter-dependent exact-n stabilization for several novel statistics for testing uniformity on the hypersphere of arbitrary dimension is provided. A data application in astronomy illustrates the benefits of the advocated stabilization for quickly analyzing small-to-moderate sequentially-measured samples.

Keywords: Exact distribution; Goodness-of-fit; p-value; Stabilization; Uniformity.

1 Introduction

The classical one-sample goodness-of-fit problem is concerned with testing the null hypothesis in which the cumulative distribution function (cdf) F of an independent and identically distributed (iid) random sample X_1, \ldots, X_n equals a certain prescribed cdf F_0 . The most popular class of goodness-of-fit statistics for testing $\mathcal{H}_0 : F = F_0$ is arguably that based on F_n , the empirical cumulative distribution function (ecdf) of X_1, \ldots, X_n . Ecdf-based test statistics confront F_n against F_0 , their best-known representatives being the Kolmogorov–Smirnov (D_n) , Cramér–von Mises (W_n^2) , and Anderson–Darling (A_n^2) statistics, all of them generating omnibus tests of \mathcal{H}_0 against $\mathcal{H}_1 : F \neq F_0$. When F_0 is continuous, testing \mathcal{H}_0 reduces to testing whether the iid sample U_1, \ldots, U_n , $U_i := F_0(X_i), i = 1, \ldots, n$, is distributed as Unif(0, 1), the continuous uniform distribution on (0, 1). Hence, tests of uniformity, despite their a priori limited applicability, provide powerful approaches to most of the goodness-of-fit problems concerned with fully-specified null hypotheses. In particular, the above ecdf-based statistics have the attractive property of being distribution-free, i.e., their exact null distributions do not depend on F_0 .

Both ecdf-based tests and uniformity tests have been exported to deal with data naturally arising in supports different from \mathbb{R} or subsets thereof. This is the case of directional data, that is, data supported on the unit hypersphere $\mathbb{S}^{p-1} := \{\mathbf{x} \in \mathbb{R}^p : ||\mathbf{x}|| = 1\}, p \geq 2$, which commonly occurs in the form of circular (p = 2) or spherical (p = 3) data. The analysis of directional data faces specific challenges due to the non-Euclideanity of the support; see Mardia and Jupp (1999) for a book-length treatment of tailored statistical methods and Pewsey and García-Portugués (2021) for a review of recent advances. In particular, tests of uniformity on \mathbb{S}^{p-1} must be invariant under arbitrary rotations of the data coordinates, as these do not alter the uniform/non-uniform nature of the data.

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While a sizable number of tests of uniformity on \mathbb{S}^{p-1} exist (see a review in García-Portugués and Verdebout (2018)), perhaps the two most known omnibus tests are those of Kuiper (1960) and Watson (1961) on \mathbb{S}^1 : their statistics, V_n and U_n^2 , can be regarded as the rotation-invariant versions of the Kolmogorov–Smirnov and Cramér–von Mises tests of uniformity, respectively. Moving beyond \mathbb{S}^1 has proven a challenging task for ecdf-based tests up to relatively recent years, with Cuesta-Albertos et al. (2009) using a Kolmogorov–Smirnov test on random projections data and García-Portugués et al. (2020) proposing a class of projected-ecdf statistics that extends Watson (1961)'s test to \mathbb{S}^{p-1} (see Section 3.1). As in the classical setting, tests of uniformity on \mathbb{S}^{p-1} allow for testing the goodness-of-fit of more general distributions: in \mathbb{S}^1 , this is a straightforward application of the probability integral transform in the angles space $[-\pi, \pi)$; the case \mathbb{S}^{p-1} , $p \geq 3$, is remarkably more complex and has been recently put forward in Jupp and Kume (2020).

Statistic	Exact distribution approximations
D_n	Massey $(1950, 1951)^{*,\dagger}$, Birnbaum $(1952)^{\ddagger}$, Maag and Dicaire $(1971)^{\$}$, Marsaglia et al. $(2003)^{\ddagger}$, Brown and Harvey $(2007)^{\dagger,\dagger\dagger}$, Facchinetti $(2009)^{\dagger\dagger}$
W_n^2	Marshall $(1958)^{\dagger\dagger}$, Pearson and Stephens $(1962)^{\P,\ddagger\ddagger}$, Tiku $(1965)^{\ddagger}$, Stephens and Maag $(1968)^{\ddagger,\P,\ddagger\ddagger}$, Knott $(1974)^{**}$, Csörgö and Faraway $(1996)^{\ddagger}$
V_n	Stephens (1965) [*] , Maag and Dicaire (1971) [§] , Durbin (1973); Arsham (1988) ^{††}
U_n^2	Pearson and Stephens $(1962)^{\P,\ddagger\ddagger}$, Tiku $(1965)^{\ddagger}$, Quesenberry and Miller Jr $(1977)^{\ddagger\ddagger}$
A_n^2	Lewis $(1961)^{\ddagger\ddagger}$, Marsaglia and Marsaglia $(2004)^{\parallel}$

Table 1: Summary of existing specific approaches for approximating exact distributions of several goodnessof-fit test statistics. The approximations rely of the following main techniques: difference equations^{*}, recursive formulae[†], truncated approximations[‡], asymptotic expansions[§], approximation of distribution moments[¶], correction factors^{||}, characteristic function approximation^{**}, direct formulae^{††}, and Monte Carlo simulations^{‡‡}.

Historically, applications of goodness-of-fit tests were somehow hampered due to the absence of exact distribution theory for finite sample sizes. Statisticians focused on giving extensive tables of critical values for each statistic's exact distribution and, alternatively, approximating exact distributions of remarkable statistics. Table 1 lists the approximations available for the exact distributions of D_n , W_n^2 , V_n , U_n^2 , and A_n^2 , as well as the main techniques behind them. Although these specific approximations are highly accurate, the complexity of their expressions, and the lack of straightforward applicability to other statistics beyond the ones they were designed for, have not displaced the customary use of Monte Carlo simulations, asymptotic distributions, or even lookup tables when emitting general test decisions. In order to reduce the size of lookup tables, Stephens (1970) transformed several statistics T_n (among others, D_n , V_n , W_n^2 , and U_n^2) into T_n^* in such a way that the upper tails of T_n^* remain roughly constant on n. Comparing T_n^* (and not T_n) with certain fixed asymptotic critical values for T_n gives a more accurate test calibration for small-to-moderate n's. This approach also allowed finding finite-sample approximations in a wider set of goodness-offit problems: Stephens (1974, 1977, 1979) and D'Agostino and Stephens (1986) derived analogous transformations for D_n , V_n , W_n^2 , U_n^2 , and A_n^2 when testing the goodness-of-fit of normal, exponential, logistic, and extreme value distributions. Other authors, such as Dufour and Maag (1978), found modifications for D_n to use with truncated or censored samples, and Crown (2000) applied this method to an A_n^2 -related statistic for testing normal and exponential distributions. Hegazy and Green (1975) found transformations for new test statistics by fitting a functional relationship between the critical values and the sample size, introducing the first explicit use of a regression view to stabilize test statistics and offering insight into Stephens' original work. Pettitt (1977) also applied this regression approach to A_n^2 for normality tests. Johannes and Rasche (1980) proposed an improved modification for Durbin (1969)'s C statistic, finding a specific transformation for each significance level; these approximations give more accurate results for a wider set of significance levels,

yet at the expense of tabulating a higher number of transformations. More recently, using several regressions for different significance levels too, Marks (1998, 2007) found transformations for D_n to test for Erlang distributions, while Heo et al. (2013) did the same for A_n^2 with several extreme value distributions. As Table 2 shows, Stephens' transformations are present in nowadays' R software for goodness-of-fit testing, which also implements some of the statistic-specific approaches from Table 1.

Methodology	R package	Statistics and references				
Exact	goftest	$\mid W_n^2$ (Csörgö and Faraway, 1996), A_n^2 (Marsaglia and Marsaglia, 2004)				
distributions	stats	D_n (Marsaglia et al., 2003)				
Transformation	circular	V_n, U_n^2 (Stephens, 1970)				
hasod	sphunif	D_n, W_n^2, V_n, U_n^2 (Stephens, 1970)				
Daseu	EnvStats	D_n, W_n^2, A_n^2 (D'Agostino and Stephens, 1986)				

Table 2: R packages implementing different approximation methods to compute exact *p*-values of goodnessof-fit tests: circular (Agostinelli and Lund, 2017), sphunif (García-Portugués and Verdebout, 2021), EnvStats (Millard, 2013), goftest (Faraway et al., 2019), and stats (R Core Team, 2021).

In this paper we build on Stephens' transformations to expand and automate them. First, we present a data-driven procedure to achieve a better stabilization, with respect to the sample size n. of the exact null distribution of a generic test statistic T_n of interest, for a wider range of significance levels α (i.e., upper α -quantiles of T_n). Specifically, new modifications for the (one-sample) Kolmogorov–Smirnov, Cramér–von Mises, Kuiper, and Watson test statistics are derived and shown to extend the scope of applicability of previous approaches. To the best of our knowledge, we also provide the first instance of such a stabilization for the Anderson–Darling test statistic. Second, we provide a method to approximate upper-tail exact p-values for the tests constructed from stabilized statistics. Through an extensive simulation study, we show a significant improvement in the precision of the stabilization of the exact critical values of T_n for several sample sizes, as well as a competitive computational cost when compared with statistic-specific methods for evaluating exact null distributions. We also show large improvements, both in precision and computational efficiency, over the use of Monte Carlo simulation, arguably the most popular test calibration approach nowadays. Third, we develop an extension of our stabilization procedure to deal with several recent test statistics for assessing uniformity on \mathbb{S}^{p-1} , $p \geq 2$, and which hence have dimension-dependent distributions. In particular, we stabilize the exact null distribution of a novel Anderson–Darling test statistic for circular data. Finally, the introduced stabilization methodology allows us to perform tests in batches of small-to-moderate samples in an accurate and fast manner that does not require Monte Carlo simulation. This is illustrated in an astronomical dataset comprised of the longitudes at which sunspots appear, which exhibits a suspected temporal mix of uniform and non-uniform patterns.

The rest of the paper is organized as follows. Section 2 introduces Stephens' approach (Section 2.1) and our proposed extension (Section 2.2), together with simulation studies and a comparison between several modifications (Section 2.3). Section 3 briefly introduces the projected-ecdf statistics for testing uniformity on the hypersphere (Section 3.1), develops the parameter-dependent transformations to achieve their stabilization (Section 3.2), and analyzes the empirical performance of these transformations (Section 3.3). Section 4 gives an application of the modified statistics in astronomy. A final discussion of the obtained results concludes the paper in Section 5. Further analyses and empirical results are included in the Supplementary Material (SM). All the code and data are available at https://github.com/afernandezdemarcos/approxstats.

2 Stabilization of ecdf statistics

2.1 On Stephens' stabilization

Stephens (1970) stabilization aims to transform a statistic T_n into T_n^* through a function of n, so that the upper α -quantiles of T_n^* are well approximated by the upper α -quantiles of T_∞ , the random variable distributed as the asymptotic null distribution of T_n , for small-to-moderate sample sizes. The transformation can be interpreted as a two-step stabilization. First, in the quantile ratios stabilization, T_n is modified to the statistic $T_n^{\alpha_0\text{-s}}$ so that the ratios of $T_n^{\alpha_0\text{-s}}$'s upper α -quantiles with respect to a certain reference upper α_0 -quantile are roughly constant as a function of n. Second, in the asymptotic stabilization, $T_n^{\alpha_0\text{-s}}$ is transformed into T_n^* so that the upper α -quantiles of T_n^* are approximately equal to the asymptotic upper α -quantiles for small-to-asymptotic sample sizes. For the sake of brevity, and since we are concerned only with upper-tail tests, henceforth we will use " α -quantile" as a replacement for "upper α -quantile".

The ratios involved in the first step are $T_{n;\alpha}/T_{n;\alpha_0}$, where $T_{n;\alpha}$ is the α -quantile of the distribution for sample size n, i.e., $\mathbb{P}[T_n \geq T_{n;\alpha}] = \alpha$. Obviously, these ratios do not have to be constant for all n, as Figure 1 shows for W_n^2 . The quantile ratios stabilization step searches for a transformed statistic, $T_n^{\alpha_0-s}$, whose quantile ratios $T_{n;\alpha}^{\alpha_0-s}/T_{n;\alpha_0}^{\alpha_0-s}$ do not depend on n. In other words, the desideratum is that these quantile ratios, for any sample size n, equal the asymptotic quantile ratios $T_{\infty;\alpha}/T_{\infty;\alpha_0}$, where $T_{\infty;\alpha}$ is the asymptotic α -quantile. One way to find such transformation is by setting $T_n^{\alpha_0-s} :=$ $T_n - p(n)$ for a certain function $p : \mathbb{N} \to \mathbb{R}$ such that it verifies $\lim_{n\to\infty} p(n) = 0$ and the second equality below, for all n and α :

$$\frac{T_{n;\alpha}^{\alpha_0 \circ s}}{T_{n;\alpha_0}^{\alpha_0 \circ s}} = \frac{T_{n;\alpha} - p(n)}{T_{n;\alpha_0} - p(n)} = \lim_{n \to \infty} \frac{T_{n;\alpha} - p(n)}{T_{n;\alpha_0} - p(n)} = \frac{T_{\infty;\alpha}}{T_{\infty;\alpha_0}} =: k_{\infty;\alpha}.$$
(1)

Hence, p is such that

$$p(n) = \frac{T_{n;\alpha} - k_{\infty;\alpha} \cdot T_{n;\alpha_0}}{1 - k_{\infty;\alpha}}.$$

which clearly depends on α . Stephens fitted p (see the end of this section) for a specific value of α , at the expense of accuracy for other significance levels. Upon this step, the quantile ratios of $T_n^{\alpha_0-s}$ are roughly constant for all n, as Figure 1 shows for W_n^2 . This first step can be omitted for statistics with quantile ratios that are already roughly stable, as it is remarkably the case of D_n and V_n (Stephens, 1970, Section 5). In this case, $p \approx 0$.

The asymptotic stabilization step aims to transform the already modified statistic, $T_n^{\alpha_0\text{-s}}$, into T_n^* so that the α -quantiles of this latter statistic are well approximated by the asymptotic α -quantiles of the original statistic T_n . For that goal, $g : \mathbb{N} \to \mathbb{R}$ is defined as $g(n) := T_{\infty;\alpha}/T_{n;\alpha}^{\alpha_0\text{-s}}$. Owing to (1), in principle this function does not depend on the significance level α , only on α_0 :

$$\frac{T_{\infty;\alpha}}{T_{n;\alpha}^{\alpha_0-s}} = \frac{T_{\infty;\alpha_0}}{T_{n;\alpha_0}^{\alpha_0-s}},\tag{2}$$

which holds for any value of α . However, when p and g are fitted in practice, (2) will approximately hold for a certain set of α values, as those shown in Figure 1. The function g is estimated from the ratio between $T_{\infty;\alpha}/T_{n;\alpha}^{\alpha_0-s}$ for a particular value α_1 (possibly different from α_0), which could result in a loss of accuracy for other quantiles.

The final modified form of T_n is

$$T_n^* = T_n^{\alpha_0 \cdot \mathbf{s}} \cdot g(n) = (T_n - p(n)) \cdot g(n), \tag{3}$$

where we highlight that in practice the functions p and g have to be estimated beforehand. Once these fits are readily available, the main benefit of (3) is the simplicity of its use, which only requires evaluating a simple *n*-dependent transformation of T_n . The fits of *p* and *g* were originally handcrafted on a case-by-case basis (even "found by trial", Stephens, 1970, Section 5), or were heavily influenced by Stephens' functional forms, which pose significant limitations in terms of automation and flexibility. Moreover, the approximation error to the exact quantiles of T_n that is obtained is, first, dependent on α_1 and, second, significant for α -quantiles different from α_1 . An additional downside of (3) is the initial stabilization step, which increases the complexity and tuning required (selection of α_0), and is a source of uncertainty for the final approximation. In order to overcome these problems, we present in the next section an enhanced stabilization approach that improves the accuracy of exact α -quantiles while retaining the simplicity of the transformation.



Figure 1: Quantile ratios of the Cramér–von Mises statistic W_n^2 (leftmost two figures) and its ratio-stabilized statistic $W_n^{2,0.10-s}$ (rightmost two figures).

2.2 (n, α) -stabilization

Our stabilization consists of a single-step transformation of the original statistic T_n into $T_n^*(\alpha)$ by a function that depends on the sample size n and the significance level α at which the test is to be performed, so that the exact α -quantile of $T_n^*(\alpha)$ is closely approximated by the α -quantile of T_{∞} . Additionally to its improved accuracy and simplicity, an advantage of our modification is that it compresses extensive lookup tables: critical values do not need to be available for different significance levels because α is already included within the transformation.

The ratios $T_{\infty;\alpha}/T_{n;\alpha}$, shown in Figure 1 for W_n^2 , can be directly modeled as a function $g : \mathbb{N} \times (0,1) \to \mathbb{R}$ of (n,α) , hence condensing the two steps from Section 2.1 into one. To that aim, we define g as the function satisfying

$$\alpha = \mathbb{P}\left[T_n \ge T_{n;\alpha}\right] = \mathbb{P}\left[T_n \ge T_{\infty;\alpha}/g(n,\alpha)\right],\tag{4}$$

for all (n, α) , and our transformed statistic (for the α significance level) as

$$T_n^*(\alpha) := T_n \cdot g(n, \alpha)$$

It is very convenient to reexpress g, as defined in (4), as

$$\frac{T_{\infty;\alpha}}{T_{n;\alpha}} = g(n,\alpha) + \varepsilon, \tag{5}$$

where $\varepsilon = 0$ if (4) is perfectly satisfied for all (n, α) . Indeed, Equation (5) casts the stabilization problem as an error-free fixed-design regression problem with predictors (n, α) , response $Y := T_{\infty;\alpha}/T_{n;\alpha}$, and unknown regression function g. Casting Stephens' stabilizations as a regression problem was early introduced in Hegazy and Green (1975), Pettitt (1977), and Johannes and Rasche (1980). Yet these works focus on using the sample size as the unique predictor, for isolated α -quantiles, an approach that has been later applied in Marks (1998, 2007) and Heo et al. (2013). We introduce now a sufficiently flexible parametric specification for g in (5) that allows its effective estimation in practice. We resort to a linear model featuring negative powers of the sample size n and significance level α as predictors, as well as the corresponding interaction effects between them. Precisely, we consider the following saturated model:

$$g(n,\alpha) = 1 + \frac{\beta_1}{\sqrt{n}} + \frac{\beta_2}{n} + \frac{\beta_3}{\sqrt{n\alpha}} + \frac{\beta_4}{\sqrt{n\alpha}} + \frac{\beta_5}{n\sqrt{\alpha}} + \frac{\beta_6}{n\alpha}.$$
 (6)

The fixed intercept and negative powers of n were included to guarantee that $\lim_{n\to\infty} g(n,\alpha) = 1$, thus in accordance with $\lim_{n\to\infty} T_{\infty;\alpha}/T_{n;\alpha} = 1$. Powers of $n^{-1/2}$ resemble the sample size factors in the terms of an Edgeworth series. The powers of $\alpha^{-l/2}$, l = 1, 2, were experimentally found to be an appropriate specification for capturing the interactions with n. The appropriateness of the model specification (6) is exhaustively investigated in A in the SM. Upon available samples of the form $\{(n_j, \alpha_j, Y_j)\}_{j=1}^J, Y_j := T_{\infty;\alpha_j}/T_{n_j;\alpha_j}$, model (6) is estimated through weighted least squares, using the weight $w_j := n_j^{-1/2} \mathbb{1}_{\{0 < \alpha_j \le 0.25\}}$ for the *j*-th observation to give heavier weight to the approximation error on lower sample sizes. The indicator in w_j reflects our interest in only stabilizing the upper tail of the test statistic T_n , hence disregarding those quantiles associated with non-rejections of the test based on T_n . B in the SM provides more detail on the selection of the weight function among several alternatives.

The data required for fitting (6) is to be produced under the (fairly realistic nowadays) assumption that it is feasible to simulate a large number of statistics T_n under the null hypothesis and for varying sample sizes. Specifically, we have carried out the following simulation for the test statistics D_n , W_n^2 , V_n , U_n^2 , and A_n^2 . We produced $M = 10^7$ Monte Carlo random samples for T_n , for each of the sample sizes n in the set $\mathcal{N} := \{5, \ldots, 100, 102, \ldots, 200, 204, \ldots, 300, 308, \ldots, 404,$ $420, \ldots, 500\}$. We then condensed these statistics as the quantiles $\{T_{n_j;\alpha_j} : n_j \in \mathcal{N}, \alpha_j \in \mathcal{A}\}$, for $\mathcal{A} := \{a/A : a = 1, \ldots, A\}$, $A = 10^3$. The asymptotic α -quantiles $\{T_{\alpha;\alpha_j} : \alpha_j \in \mathcal{A}\}$ were computed from the statistics' asymptotic null distributions, as those were readily available in the literature. The generated sample is therefore $\{(n_j, \alpha_j, Y_j)\}_{j=1}^J$, $J = \#\mathcal{N} \times A$. Clearly, this is a computationallyintensive process, although it only needs to be done once per kind of test statistic. The procedure is analogous for other one-sample test statistics that are feasible to simulate under the simple null hypothesis at hand. If the limiting distribution is not available or tractable, a sufficiently large sample size n could be used to approximate $T_{\infty;\alpha}$ by $T_{n;\alpha}$ by Monte Carlo.

Using the sample $\{(n_j, \alpha_j, Y_j)\}_{j=1}^J$, we advocate the use of stepwise regression for performing model selection within (6). Specifically, we performed a forward-backward search for minimizing the Bayesian Information Criterion (BIC) on the space of models contained in (6). The search was initiated with the model featuring only the predictors used in Stephens' modifications, i.e., $n^{-1/2}$ and n^{-1} . To attain simpler models than the BIC-optimal one, a final step was implemented to iteratively drop one-by-one the predictors that contributed the least to the adjusted R^2 of the resulting model. The threshold was established to keep only three final terms (for simplicity), the predictors removed decreasing less than 0.15% the R_{adi}^2 which, averaged across the five statistics, was larger than 0.96.

The resulting modified forms for D_n , W_n^2 , V_n , U_n^2 , and A_n^2 are collected in Table 3. All of the transformations have three correcting terms, one dependent on n and the other two related to n and α , $(n\sqrt{\alpha})^{-1}$ being common to the five statistics. Interestingly, the same correction terms are present within the groups of supremum- and quadratic-norm statistics, as well as in the pairs of linear and circular variants. These forms are valid for $n \ge 5$, which anecdotally gives a minor improvement over Stephens' forms, valid for $n \ge 8$. The steps to use them with the upper-tail test for \mathcal{H}_0 that is based on T_n and that is carried out at the significance level α are as follows:

- (i) Compute the test statistic T_n using its original form.
- (*ii*) Calculate the corresponding modified test statistic, $T_n^*(\alpha)$, in Table 3.
- (*iii*) Retrieve an asymptotic critical value $T_{\infty;\alpha}$ in Table 3. If $T_n^*(\alpha) > T_{\infty;\alpha}$, reject \mathcal{H}_0 at significance level α .

T_n	$T_n^*(lpha)$	$T_{\infty;0.15}$	$T_{\infty;0.1}$	$T_{\infty;0.05}$	$T_{\infty;0.025}$	$T_{\infty;0.01}$
D_n	$D_n \left(1 + \frac{0.1575}{\sqrt{n}} + \frac{0.0192}{n\sqrt{\alpha}} - \frac{0.0051}{\sqrt{n\alpha}} \right)$	1.1380	1.2239	1.3581	1.4803	1.6277
W_n^2	$W_n^2 \left(1 - \frac{0.1651}{n} + \frac{0.0749}{n\sqrt{\alpha}} - \frac{0.0014}{n\alpha} \right)$	0.2841	0.3473	0.4613	0.5806	0.7435
V_n	$V_n \left(1 + \frac{0.2330}{\sqrt{n}} + \frac{0.0276}{n\sqrt{\alpha}} - \frac{0.0068}{\sqrt{n\alpha}} \right)$	1.5370	1.6196	1.7473	1.8625	2.0010
U_n^2	$U_n^2 \left(1 - \frac{0.1505}{n} + \frac{0.0917}{n\sqrt{\alpha}} - \frac{0.0018}{n\alpha} \right)$	0.1313	0.1518	0.1869	0.2220	0.2685
A_n^2	$A_n^2 \left(1 + \frac{0.0360}{n} - \frac{0.0234}{n\sqrt{\alpha}} + \frac{0.0006}{n\alpha} \right)$	1.6212	1.9331	2.4922	3.0775	3.8784

Table 3: Modified statistics for sample size n and significance level α . Modified forms are valid for $n \geq 5$ and $0 < \alpha \leq 0.25$. \mathcal{H}_0 is rejected at significance level α if $T_n^*(\alpha) > T_{\infty;\alpha}$.

The transformed statistics can also be used to obtain approximations to exact *p*-values, provided the asymptotic quantiles $\mathcal{T}_{\infty} := \{T_{\infty;\alpha_j} : \alpha_j \in \mathcal{A}\}$ have been precomputed. This is done in two steps. First, *p*-value bounds $[\alpha_1, \alpha_2]$ are obtained from the grid \mathcal{A} such that $T_n^*(\alpha_1) \leq T_{\infty;\alpha_1}$ and $T_n^*(\alpha_2) > T_{\infty;\alpha_2}$. Once these discrete bounds for *p*-value are available, a linear interpolation is applied to define $t_{\infty}(\alpha) := T_{\infty;\alpha_1} + (T_{\infty;\alpha_2} - T_{\infty;\alpha_1})(\alpha - \alpha_1)/(\alpha_2 - \alpha_1)$ for $\alpha \in [\alpha_1, \alpha_2]$ and then the root $\alpha^* \in [\alpha_1, \alpha_2]$ of

$$T_n^*(\alpha^*) = t_\infty(\alpha^*) \tag{7}$$

is obtained by Newton–Raphson (NR). The approximate *p*-value is then set to α^* . If $\alpha_1 \geq \alpha_{\max}$, $\alpha_{\max} = 0.25$ being the maximum element in \mathcal{A} for which the transformation has been estimated, *p*-value = α_{\max} is returned. Algorithm 1 summarizes this process.

Algorithm 1 *p*-value approximation using the (n, α) -modification

```
function PVALUE_APPROX(T_n, n, \mathcal{T}_{\infty}, \mathcal{A})
  1:
                 for j from 1 to \#\mathcal{A} do
  2:
                         T_{\mathrm{mod},\alpha} \leftarrow T_n^*(T_n, n, \mathcal{A}[j])
  3:
                         if T_{\text{mod},\alpha} > \mathcal{T}_{\infty}[j] then
  4:
                                 if j = 1 then
  5:
                                           \begin{aligned} & (\alpha_1, \alpha_2) \leftarrow (\mathcal{A}[j], \mathcal{A}[j+1]) \\ & (T_{\infty;\alpha_2}, T_{\infty;\alpha_1}) \leftarrow (\mathcal{T}_{\infty}[j], \mathcal{T}_{\infty}[j+1]) \end{aligned} 
  6:
  7:
                                  else
  8:
                                          (\alpha_1, \alpha_2) \leftarrow (\mathcal{A}[j-1], \mathcal{A}[j])
  9:
                                          (T_{\infty;\alpha_2}, T_{\infty;\alpha_1}) \leftarrow (\mathcal{T}_{\infty}[j-1], \mathcal{T}_{\infty}[j])
10:
                                  \alpha^* \leftarrow \operatorname{NR}(T_n^*(T_n, n, \alpha) - t_\infty(\alpha, \mathcal{T}_\infty, \alpha_1, \alpha_2))
11:
12:
                                  return \alpha^*
13:
                 return 0.25
```

When there is no α_1 in \mathcal{A} such that $T_n^*(\alpha_1) \leq T_{\infty;\alpha_1}$, the *p*-value is set as the nonnegative extrapolation of the root in (7), with α_1 and α_2 being the two lowest elements in \mathcal{A} .

2.3 Simulation study

For the test statistics D_n , V_n , W_n^2 , U_n^2 , and A_n^2 , we evaluate next the divergence of the exact-*n* critical values under \mathcal{H}_0 from their corresponding approximations given by: (a) Stephens' modified forms; (b) the particular approximation methods from Table 2; (c) Monte Carlo approximation with 10⁴ trials; and (d) our proposed transformations. Figure 2 displays the relative errors for the rejection proportions generated by approximated critical values based on methods (a)–(d). These relative



Figure 2: Relative error (in %) $|\alpha - \tilde{\alpha}|/\alpha$ between the significance level α and $\tilde{\alpha}$, the empirical rejection rate using an approximated exact-*n* critical value, averaged across different sample sizes *n*. The legend in Figure 2a details the approximation methods considered and applies to the rest of the panels, with different specific methods in Figures 2c and 2e. The gray shaded area corresponds to the 95% confidence interval of the relative error when $\tilde{\alpha}$ is produced by the exact-*n* critical value estimated by $M = 10^7$ Monte Carlo samples.

errors are defined as $|\alpha - \tilde{\alpha}|/\alpha$, where α is the significance level and $\tilde{\alpha}$ is the empirical rejection rate obtained with $M = 10^7$ Monte Carlo samples when using an α -critical value computed by each approximation method. The $M = 10^7$ Monte Carlo samples under \mathcal{H}_0 were drawn for each of the sample sizes n in $\mathcal{N}_{\text{test}} := \{5, \ldots, 10, 20, \ldots, 50, 100, 200, 300\}$. The sample quantiles for the significance levels in $\mathcal{A}_{\text{test}} := \{a/100 : a = 1, \ldots, 25\}$ were computed for each sample size and statistic. For the critical value approximations (a) and (d), critical values were computed by applying the corresponding inverse transformation from Table 8 to the asymptotic α -critical value $T_{\infty;\alpha}$. Obtaining the critical values in (b) is straightforward using the functions $\mathtt{stats} ::: C_pKolmogorov2x$ (R Core Team, 2021) for D_n , and $\mathtt{goftest} :: \mathtt{pCvM}$ and $\mathtt{goftest} :: \mathtt{pAD}$ (Faraway et al., 2019) for W_n^2 and A_n^2 , respectively. For the critical value approximation based on (c), the (random) relative error for each critical value was averaged over 10^3 simulations to give an estimate of the average Monte Carlo relative error. Each panel in Figure 2 shows the relative error along $\mathcal{A}_{\text{test}}$ averaged for three sets of sample sizes: $5 \leq n < 10, 10 \leq n < 100$, and $n \geq 100$.

Along $\mathcal{A}_{\text{test}}$, the average relative errors of our stabilizations are 0.5%, 0.3%, 0.5%, 0.3%, and 0.7% for D_n , W_n^2 , U_n^2 , A_n^2 , and V_n , respectively. The relative errors remain fairly stable for every significance value in $\mathcal{A}_{\text{test}}$ without significant differences between the sets of sample sizes analyzed. Compared to Stephens' stabilizations, our relative error is lower by a factor of $\times 2$, $\times 12$, $\times 2$, $\times 3$, and $\times 4$ on average, respectively. The largest improvements are achieved for $\alpha \neq 0.05$, since Stephens' stabilizations were tuned for $\alpha = 0.05$, and for sample sizes $n \leq 100$. This behavior is more obvious in W_n^2 and U_n^2 , which are the statistics that, in Stephens' approach, use an additional prior step for stabilizing the quantile ratios. When compared to the Monte Carlo approximation with 10⁴ samples, our relative error is lower for every significance level and sample size tested, and improves by $\times 5$, $\times 10$, $\times 5$, $\times 9$, and $\times 4$ on average, respectively. As expected, the approximation methods that are specifically designed for each test statistic achieve the lowest relative errors.

Table 4 presents a comparison of the running times between our p-value approximation (Algorithm 1) and the already implemented p-value approximation methods for D_n , W_n^2 , and A_n^2 described in Table 2. Our method is shown to be $\times 3.8$, $\times 5.4$, and $\times 4.8$ faster than Marsaglia et al. (2003). Csörgö and Faraway (1996), and Marsaglia and Marsaglia (2004), respectively. These methods are already implemented in C++, except for Csörgö and Faraway (1996) which is in R. Hence, C++ and R versions implementing Algorithm 1 were developed for each statistic to allow a fair comparison. In addition, Table 5 compares the running times between the *p*-value approximation based on Algorithm 1 and a Monte Carlo p-value approximation based on 10^4 trials, which shows that our method is $\times 75 \cdot 10^4$, $\times 58 \cdot 10^4$, and $\times 93 \cdot 10^4$ faster. Monte Carlo approximation was implemented in R code with calls to C++-coded statistics (the most time-consuming part), and the C++ version of Algorithm 1 was used. All comparisons were carried out using microbenchmark package (Mersmann, 2019). In order to compute the median running time of each function for a given sample size n and significance level α , 10³ evaluations of the compiled functions were run after 10 warm-up runs using the same machine, a regular desktop computer with a 3.6GHz processor. In all cases, the computation of the original statistic T_n was excluded from the timings. R and C++ integration was done with the Rcpp package (Eddelbuettel and François, 2011).

The empirical results show that our stabilized statistics give more accurate results than those by Stephens, while still retaining the simplicity of the latter. When it comes to the Monte Carlo approximation (with 10^4 trials), relative errors on the empirical rejection rates are lowered by a factor that varies from $\times 4$ to $\times 10$, depending on the statistic. In addition, Table 5 shows how our stabilization algorithm outperforms Monte Carlo execution times. Part of these improvements could be attributed to the R-C++ mix, as opposed to pure C++. Yet, given the massive difference in timing orders, we regard this effect as second-order. Arguably, for D_n , W_n^2 , and A_n^2 , the tailored approximation methods are to be preferred due to their better accuracy. Even in these highlycompetitive settings, our stabilizations still offer comparative advantages, as Figure 2 shows that their average relative error is < 0.7%, sufficing for most practical applications, while Table 4 shows an improvement of $\times 5$ in running times with respect to specific methods.

Q						n				
u	5	6	7	8	9	10	20	30	40	50
		D_n : N	ſarsagl	ia et a	l. (2003	B) vs. A	Algorit	hm 1		
0.01	2.48	2.56	3.04	2.96	3.00	3.23	7.09	10.74	17.08	23.38
0.02	2.28	2.28	2.40	2.75	2.80	2.85	4.80	9.62	12.04	17.39
0.05	1.61	1.97	1.90	1.87	1.90	2.29	3.06	5.94	7.29	10.50
0.10	1.22	1.21	1.44	1.43	1.48	1.49	2.24	3.33	4.17	6.05
0.15	1.02	0.96	0.98	1.13	1.15	1.19	1.42	2.74	3.45	3.67
0.25	0.68	0.71	0.70	0.71	0.70	0.81	1.04	1.48	1.82	2.64
	W	r_n^2 : Csö	rgö an	d Fara	way (1	996) vs	. Algo	rithm [1	
0.01	10.43	10.40	10.17	10.12	10.03	10.00	10.60	10.68	10.66	11.82
0.02	8.69	8.47	8.42	8.47	8.73	8.75	8.92	9.06	8.85	8.99
0.05	5.54	5.53	5.61	5.57	5.56	5.58	5.67	5.68	5.64	5.68
0.10	3.46	3.50	3.48	3.46	3.45	3.48	3.50	3.48	3.48	3.49
0.15	2.50	2.48	2.49	2.54	2.48	2.55	2.57	2.50	2.51	2.52
0.25	1.62	1.62	1.63	1.59	1.59	1.64	1.61	1.61	1.65	1.64
	A_n^2 :	Marsa	iglia an	nd Mar	saglia ((2004)	vs. Alg	gorithn	n 1	
0.01	6.66	6.28	6.23	6.14	6.20	6.42	6.29	6.18	6.29	6.43
0.02	6.00	6.52	5.91	6.18	6.13	6.22	5.91	6.26	6.14	6.60
0.05	5.12	5.24	5.72	5.74	5.36	6.04	5.24	5.23	5.44	5.44
0.10	4.26	4.39	4.35	4.26	4.26	4.81	4.35	4.52	4.36	4.32
0.15	3.70	3.62	3.64	3.78	3.64	3.65	3.78	3.75	3.72	3.74
0.25	2.87	3.19	2.79	2.85	3.10	3.02	2.83	2.85	2.98	2.87

Table 4: Running time ratios between specific *p*-value approximation methods and our *p*-value approximation method (Algorithm 1). Ratios are computed for the median running times of 10^3 evaluations, for each pair (n, α) . The averages of the median running times of Algorithm 1 are $3.65\mu s$, $225\mu s$ (for R version, $4.5\mu s$ for C++ version), and $3\mu s$ for D_n , W_n^2 , and A_n^2 , respectively.

α					η	ı				
u	5	6	7	8	9	10	20	30	40	50
	D_n : Monte Carlo vs. Algorithm 1									
0.05	14	16	19	23	16	28	69	118	182	261
		W	V_n^2 : Mo	nte Ca	rlo vs.	Algori	thm 1			
0.05	10	12	14	13	17	21	51	94	146	203
		A	a_n^2 : Mo	nte Ca	rlo vs.	Algori	thm 1			
0.05	15	19	22	26	32	33	80	150	227	325

Table 5: Running time ratios, in scale $\times 10^4$, between a *p*-value Monte Carlo approximation based on 10^4 trials and our *p*-value approximation method (Algorithm 1). Ratios are computed for the median running times of 10^3 evaluations, for each pair (n, α) . The averages of the median running times for the Monte Carlo approximation are 2.34s, 2.35s, and 2.35s for D_n , W_n^2 , and A_n^2 , respectively.

3 Stabilization of parameter-dependent statistics

This section gives an extension of the (n, α) -transformations introduced in Section 2.2 that is designed to stabilize the exact distributions of statistics that depend on a (known) parameter. Instances of the transformation are given for testing uniformity on \mathbb{S}^{p-1} , $p \ge 2$ being the statistic parameter.

Projected-ecdf test statistics 3.1

García-Portugués et al. (2020) proposed a class of test statistics to evaluate the null hypothesis of uniformity of an iid sample $\mathbf{X}_1, \ldots, \mathbf{X}_n$ on \mathbb{S}^{p-1} . Projected-ecdf statistics compute the weighted quadratic discrepancy between $F_{n,\gamma}$, the edd of $\gamma' \mathbf{X}_1, \ldots, \gamma' \mathbf{X}_n$ for $\gamma \in \mathbb{S}^{p-1}$, and F_p , the dd of the random variable $\gamma' \mathbf{X}$ when $\mathbf{X} \sim \text{Unif}(\mathbb{S}^{p-1})$. The weighted quadratic discrepancies are integrated over all possible directions $\gamma \in \mathbb{S}^{p-1}$, a convenient specification of the projected-ecdf statistics being

$$P_{n,p}^{w} := n \int_{\mathbb{S}^{p-1}} \left[\int_{-1}^{1} \left(F_{n,\gamma}(x) - F_{p}(x) \right)^{2} w(F_{p}(x)) \, \mathrm{d}F_{p}(x) \right] \mathrm{d}\gamma,$$

where $w: [0,1] \to \mathbb{R}$ is a certain weight function and the cdf F_p is that of the random variable T, with $T^2 \sim \text{Beta}(1/2, (p-1)/2)$.

The weights $w \equiv 1$ and w(u) = 1/(u(1-u)) result in the Projected Cramér–von Mises statistic, $P_{n,p}^{\text{CvM}}$, and the Projected Anderson–Darling statistic, $P_{n,p}^{\text{AD}}$, respectively. The test based on $P_{n,p}^{\text{CvM}}$ happens to be an extension of the Watson test to \mathbb{S}^{p-1} , $p \geq 2$, since $P_{n,2}^{CvM} = U_n^2/2$. Moreover, the test based on $P_{n,3}^{\text{CvM}}$ is equivalent to the chordal-based test on \mathbb{S}^2 by Bakshaev (2010), whose statistic for $p \ge 2$ is

$$N_{n,p} := n \mathbb{E}_{\mathcal{H}_0} \left[\| \mathbf{X}_1 - \mathbf{X}_2 \| \right] - \frac{1}{n} \sum_{i,j=1}^n \| \mathbf{X}_i - \mathbf{X}_j \|.$$

The statistic $P_{n,p}^{AD}$ represents the first instance of the Anderson–Darling statistic in the context of directional data. Particularly, $P_{n,2}^{AD}$ can be regarded as the circular variant of A_n^2 , just as U_n^2 is the circular variant of W_n^2 . Asymptotic distributions and computational formulae for $P_{n,p}^{\text{CvM}}$ and $P_{n,p}^{\text{AD}}$ are provided in García-Portugués et al. (2020), while the sphunif R package (García-Portugués and Verdebout, 2021) provides implementations for $P_{n,p}^{\text{CvM}}$, $P_{n,p}^{\text{AD}}$, and $N_{n,p}$, for all $p \geq 2$.

3.2Stabilization of projected-ecdf statistics

Let $T_{n,p}$ be a statistic depending on $p \in \mathbb{N}$. From expression (4), the ratios $T_{\infty,p;\alpha}/T_{n,p;\alpha}$ can be modeled as a function $g: \mathbb{N} \times \mathbb{N} \times (0,1) \to \mathbb{R}$ of (n, p, α) . Hence, the modified version of the statistic $T_{n,p}$ is defined as

$$T_{n,p}^*(\alpha) := T_{n,p} \cdot g(n,p,\alpha).$$

As in expression (5), the stabilization of $T_{n,p}$ can be approached as a regression problem, now with

predictors (n, p, α) , response $Y := T_{\infty,p;\alpha}/T_{n,p;\alpha}$, and unknown regression function g. The connection between $P_{n,2}^{\text{CvM}}$ and U_n^2 implies the stabilized form of $P_{n,2}^{\text{CvM}}$ to have the same set of predictors based on (n, α) as the Watson statistic already presented in Table 3: \mathcal{R} := $\{1/n, 1/(n\sqrt{\alpha}), 1/(n\alpha)\}$. An additional reflection suggests the adequacy of choosing \mathcal{R} for stabilizing $P_{n,p}^{CvM}$, also when $p \geq 3$, due to its appearance in all the transformations for quadratic-ecdf statistics in Table 3 and the quadratic nature of $P_{n,p}^{\text{CvM}}$. For different particular values of $p \geq 2$, it was noted that, if regression models were fitted to the ratios $P_{\infty,p;\alpha}^{\text{CvM}}/P_{n,p;\alpha}^{\text{CvM}}$, the coefficients fitted for each predictor $r \in \mathcal{R}$ could be modeled as a smooth function of p denoted as $q_r : \mathbb{N} \to \mathbb{R}$. Unsurprisingly, given its similarity to $P_{n,p}^{\text{CvM}}$, the same considerations also hold for $P_{n,p}^{\text{AD}}$. Moreover, the statistic $N_{n,p}$ can also be stabilized through \mathcal{R} and q_r , a fact explained by the closeness between $P_{n,p}^{\text{CvM}}$ and $N_{n,p}$ when $p \neq 3$ and its equivalence when p = 3. Empirical investigations suggested the following saturated model for q_r , for each $r \in \mathcal{R}$:

$$q_r(p) = \frac{\beta_{r,1}}{\sqrt{p}} + \frac{\beta_{r,2}}{p}.$$

Thus, the resulting saturated model for g is set as

$$g(n, p, \alpha) = 1 + q_{1/n}(p) \cdot \frac{1}{n} + q_{1/(n\alpha)}(p) \cdot \frac{1}{n\alpha} + q_{1/(n\sqrt{\alpha})}(p) \cdot \frac{1}{n\sqrt{\alpha}}.$$
(8)

Once training samples of the form $\{(n_j, \alpha_j, p_j, Y_j)\}_{j=1}^J$, $Y_j := T_{\infty, p_j; \alpha_j}/T_{n_j, p_j; \alpha_j}$, are available, model (8) is estimated following the same methodology described in Section 2.2. For each of the three test statistics $P_{n,p}^{\text{CvM}}$, $P_{n,p}^{\text{AD}}$, and $N_{n,p}$, we obtained $M = 10^7$ Monte Carlo random samples for each sample size n in $\mathcal{N} := \{5, \ldots, 100, 102, \ldots, 200, 204, \ldots, 300, 308, \ldots, 404, 420, \ldots, 500\}$ and for each dimension p in $\mathcal{P} := \{2, \ldots, 11, 21, 31, 41, 51, 61, 71, 81, 91, 101, 151, 201, 251, 301\}$. We then summarized these statistics as the quantiles $\{T_{n_j, p_j; \alpha_j} : n_j \in \mathcal{N}, p_j \in \mathcal{P}, \alpha_j \in \mathcal{A}\}$ for $\mathcal{A} := \{a/A :$ $a = 1, \ldots, A\}$, $A = 10^3$. The asymptotic α -quantiles $T_{\infty, p; \alpha}$ were approximated through $T_{500, p; \alpha}$ due to the accuracy limitations on inverting the asymptotic cdfs of the three statistics for large dimensions. Table 6 lists the approximated $T_{\infty, p; \alpha}$ for the first ten dimensions.

						p)				
Critical value	α	2	3	4	5	6	7	8	9	10	11
	0.10	0.3035	0.2768	0.2606	0.2500	0.2421	0.2361	0.2312	0.2272	0.2239	0.2210
DCvM	0.05	0.3735	0.3288	0.3027	0.2858	0.2735	0.2641	0.2568	0.2508	0.2458	0.2416
$P_{\infty,p;\alpha}^{\circ\circ\circ\circ\circ}$	0.01	0.5358	0.4461	0.3960	0.3638	0.3413	0.3244	0.3115	0.3008	0.2922	0.2849
	0.10	1.6871	1.5604	1.4816	1.4279	1.3883	1.3576	1.3327	1.3124	1.2957	1.2809
DAD	0.05	2.0293	1.8214	1.6951	1.6106	1.5494	1.5023	1.4651	1.4347	1.4092	1.3875
$\Gamma_{\infty,p;\alpha}$	0.01	2.8197	2.4096	2.1679	2.0090	1.8969	1.8126	1.7471	1.6931	1.6493	1.6121
	0.10	2.4034	2.2141	2.1003	2.0231	1.9673	1.9238	1.8887	1.8601	1.8367	1.8158
$N_{\infty,p;\alpha}$	0.05	2.9906	2.6305	2.4320	2.3034	2.2119	2.1423	2.0879	2.0437	2.0067	1.9752
	0.01	4.3495	3.5687	3.1669	2.9136	2.7402	2.6112	2.5124	2.4314	2.3661	2.3108

Table 6: Asymptotic critical values for modified uniformity statistics with dimension p, sample size n, and significance level α .

$T_{n,p}$	$T_{n,p}\left(1+q_{1/n}\cdot\frac{1}{n}\right)$	$+ q_{1/(n\alpha)} \cdot \frac{1}{n\alpha} -$	$+ q_{1/(n\sqrt{\alpha})} \cdot \frac{1}{n\sqrt{\alpha}} \Big)$
	$q_{1/n}$	$q_{1/(n\alpha)}$	$q_{1/(n\sqrt{\alpha})}$
$P_{n,p}^{\rm CvM}$	$\frac{0.1130}{\sqrt{p}} - \frac{0.5415}{p}$	$-\frac{0.0031}{\sqrt{p}}$	$\frac{0.1438}{\sqrt{p}}$
$P^{\rm AD}_{n,p}$	$\frac{0.0978}{\sqrt{p}} - \frac{0.3596}{p}$	$-\frac{0.0025}{\sqrt{p}}$	$\frac{0.1126}{\sqrt{p}}$
$N_{n,p}$	$\frac{0.1189}{\sqrt{p}} - \frac{0.5838}{p}$	$-rac{0.0030}{\sqrt{p}}$	$\frac{0.1210}{\sqrt{p}} + \frac{0.0385}{p}$

Table 7: Modified uniformity statistics for dimension p, sample size n, and significance level α . Modified forms are valid for $2 \le p \le 300$, $n \ge 5$, and $\alpha \le 0.25$. \mathcal{H}_0 is rejected at significance level α if $T^*_{n,p}(\alpha) > T_{\infty,p;\alpha}$, where $T_{\infty,p;\alpha}$ is given in Table 6 for p = 2, ..., 11.

The resulting modified forms for $P_{n,p}^{\text{CvM}}$, $P_{n,p}^{\text{AD}}$, and $N_{n,p}$ are presented in Table 7, where each fitted q_r is shown for each predictor $r \in \mathcal{R}$. An algorithm similar to Algorithm 1 for computing an approximated *p*-value has been implemented for these statistics, with the only difference being that the modified statistic function in lines 3 and 11 is the corresponding dimension-dependent version which also includes the parameter p as an input.

3.3 Simulation study

In the same manner as in Section 2.3, the empirical stabilization of the modified forms of the projected-ecdf statistics is investigated (Figure 3) in terms of the relative error between the significance level and the empirical rejection rate of the $T_{n,p}^*(\alpha)$ -test for sample sizes $n \in \mathcal{N}_{\text{test}}$ and dimensions $p \in \mathcal{P}_{\text{test}}$, where $\mathcal{N}_{\text{test}}$ was defined in Section 2.3 and $\mathcal{P}_{\text{test}} := \{2, \ldots, 11, 21, 51, 101, 151, 201, 301\}$. As for most non-heavily studied test statistics, Monte Carlo is the only method readily available to approximate the exact-n p-values of $P_{n,p}^{\text{CvM}}$, $P_{n,p}^{\text{AD}}$, and $N_{n,p}$. Figure 3 shows an average improvement of our stabilizations' accuracy over Monte Carlo approximations (using 10^4 trials) of $\times 3$, $\times 4$, and $\times 4$, for each of the three statistics, respectively. We point out the steadiness of our relative errors regardless of the significance level and the dimension p (except for $\alpha = 0.01$, which increases for large p's), which on average are 1.3%, 0.9%, and 1% respectively. In almost all circumstances, our relative errors are largely below those obtained by Monte Carlo (except for $\alpha = 0.25$ when p > 10 in $P_{n,p}^{\text{CvM}}$ and $N_{n,p}$).

We conclude this section by summarizing in Table 8 a comparison of the modified forms found by Stephens (1970) and our results, for each of the classical ecdf-based statistics, and their corresponding versions for circular data, along with the circular particularizations of the projected-ecdf statistics. We emphasize the simplicity of the formulae in both approaches, with the Mean Relative Error (MRE) being reduced for the second by $\times 2$ for D_n and U_n^2 , by $\times 9$ for W_n^2 , and by $\times 4$ for A_n^2 and V_n . The stabilizations for the projected-ecdf statistics are such MRE < 0.9% for the circular case, which aligns with the results specifically attained for U_n^2 and $P_{n,2}^{AD}$, and supports the convenience of the extension proposed in this section for the (n, α) -stabilization.

T_n	Stephens' T_n^\ast	MRE	$T_n^*(lpha)$	MRE
D_n	$D_n \left(1 + \frac{0.12}{\sqrt{n}} + \frac{0.11}{n} \right)$	1.44%	$D_n \left(1 + \frac{0.1575}{\sqrt{n}} + \frac{0.0192}{n\sqrt{\alpha}} - \frac{0.0051}{\sqrt{n\alpha}} \right)$	0.63%
W_n^2	$\left(W_n^2 - \frac{0.4}{n} + \frac{0.6}{n^2}\right)\left(1 + \frac{1}{n}\right)$	3.28%	$W_n^2 \left(1 - \frac{0.1651}{n} + \frac{0.0749}{n\sqrt{\alpha}} - \frac{0.0014}{n\alpha} \right)$	0.36%
A_n^2	A_n^2 (*)	1.42%	$A_n^2 \left(1 + \frac{0.0360}{n} - \frac{0.0234}{n\sqrt{\alpha}} + \frac{0.0006}{n\alpha} \right)$	0.38%
V_n	$V_n\left(1 + \frac{0.155}{\sqrt{n}} + \frac{0.24}{n}\right)$	3.40%	$V_n \left(1 + \frac{0.2330}{\sqrt{n}} + \frac{0.0276}{n\sqrt{\alpha}} - \frac{0.0068}{\sqrt{n\alpha}} \right)$	0.85%
$U_n^2 \equiv P_{n,2}^{\rm CvM}$	$\left(U_n^2 - \frac{0.1}{n} + \frac{0.1}{n^2}\right)\left(1 + \frac{0.8}{n}\right)$	1.62%	$U_n^2 \left(1 - \frac{0.1505}{n} + \frac{0.0917}{n\sqrt{\alpha}} - \frac{0.0018}{n\alpha} \right)$	0.63%
	_	_	$P_{n,2}^{\text{CvM}}\left(1 - \frac{0.1908}{n} + \frac{0.1017}{n\sqrt{\alpha}} - \frac{0.0022}{n\alpha}\right)$	0.88%
$P_{n,2}^{\mathrm{AD}}\ (^{\dagger})$	_	_	$P_{n,2}^{\text{AD}} \left(1 - \frac{0.0751}{n} + \frac{0.0692}{n\sqrt{\alpha}} - \frac{0.0014}{n\alpha} \right)$	0.74%
	_	_	$P_{n,2}^{\text{AD}}\left(1 - \frac{0.1106}{n} + \frac{0.0796}{n\sqrt{\alpha}} - \frac{0.0018}{n\alpha}\right)$	0.83%

Table 8: Modified forms of ecdf-based statistics for sample size n and significance level α . MRE refers to the Mean Relative Error between the expected rejection proportion and the approximated proportion for each pair of (n, α) with $n \in \mathcal{N}_{\text{test}}$ and $\alpha \in \{0.25, 0.2, 0.15, 0.1, 0.05, 0.02, 0.01\}$. The $T_n^*(\alpha)$ forms are valid for $n \geq 5$ and $\alpha \leq 0.25$. (*) Stephens (1974) states the best modification for Anderson–Darling statistic for $n \geq 5$ is its asymptotic distribution. (†) Both the modified form estimated for p = 2 (top row) and the (n, p, α) -modification particularized for p = 2 (bottom row) are given for $P_{n,2}^{\text{CvM}}$ and $P_{n,2}^{\text{AD}}$.



Figure 3: Relative error (in %) $|\alpha - \tilde{\alpha}|/\alpha$ between the significance level α and $\tilde{\alpha}$, the empirical rejection rate using an approximated exact-*n* critical value, averaged over $5 \le n \le 300$. For the Monte Carlo approximation method, a regression fit is shown for each significance level α to show no trend on the error with respect to p. The legend in Figure 3a details the approximation methods considered and significance levels, and applies to the rest of the panels.

4 Detecting temporal longitudinal non-uniformity in sunspots

The Sun's magnetic field presents periodic behavioral patterns of about 11 years. During this period, the magnetic field is pulled around the Sun's surface as the solar plasma rotates. Near the equator this pull is stronger due to the Sun's differential rotation (equatorial latitudes rotate faster than poles), causing the field to wrap in a spiral-like shape until its polarity is eventually reversed and the wrapping restarts, indicating the beginning of a new solar cycle (see, e.g., Babcock, 1961). Sunspots

are created by high-intensity magnetic loops emerging from the Sun's interior convection zone to the surface, producing darker, cooler regions on the Sun's photosphere. Through their lifespans, which can last from hours to days, they experience continuous changes in shape, area, and location. The total number of active sunspots varies throughout the cycle, showing the maximum activity during the middle years (see Figure 4). Sunspots appear in a marked rotationally symmetric fashion: they are mainly distributed in latitudinal belts that are initially situated at $\pm 30^{\circ}$ and that decay to the equator as the solar cycle advances (a phenomenon known as the *Spörer's law*).

Sunspots also appear to cluster in *active longitudes*. Non-uniform patterns may appear by *pre-ferred zones of occurrence* where sunspots had originated previously, as early described by Babcock (1961, pages 574 and 581). The existence of active longitudes was also suggested in Bogart (1982) upon inspection of the significant autocorrelation of daily sunspot numbers. Since daily sunspot numbers have no positional information, such analysis shows either there is one active longitude band or there are two active longitude bands separated by 180° , as Berdyugina and Usoskin (2003) concluded in both hemispheres, observing the alternation of major solar activity between both longitudes in about 1.5 to 3 years. This is known as the *flip-flop* phenomenon (Elstner and Korhonen, 2005).

Analyzing the presence of solar active longitudes requires knowledge from the Carrington period (or solar rotation period). It corresponds to the mean synodic rotation period of sunspots, which is about 27.275 days. Differential rotation causes the migration of active longitudes in the Carrington reference frame, causing a lag of 2.5 Carrington rotations per solar cycle that blurs the longitudinal pattern if more than one solar cycle is analyzed at once (Berdyugina and Usoskin, 2003). In order to ensure the adequate detection of active longitudes, a sequential analysis of data limited to a certain number of Carrington rotations, from 3–7 (Bogart, 1982; de Toma et al., 2000) to 10–15 (Pelt et al., 2010), is preferable.

The data we analyze is based on the Debrecen Photoheliographic Data (DPD) sunspot catalog (Baranyi et al., 2016; Győri et al., 2016). It contains observations of sunspots locations since 1974 and is a continuation of the Greenwich Photoheliographic Results (GPR) catalog, which spanned 1872–1976. The dataset sunspots_births, available in the R package rotasym (García-Portugués et al., 2021), accounts just for the first-ever observation (referred to as "birth" henceforth) of a group of sunspots.

In our analysis, summarized in Figure 4, we first applied the $P_{n,2}^{AD}$ -based uniformity test sequentially to the longitudes of sunspot births —which include a total of 6195, 4551, and 5373 observations for the 21st, 22nd, and 23rd cycle, respectively— within a rolling window whose size is 10-Carrington rotations (approximately, nine months). The corresponding *p*-values were computed using Algorithm 1 for northern (blue), southern (red), and both (black) hemispheres. In addition, the p-value was also computed by Monte Carlo with 5×10^3 samples, in order to compare the running times between the two methods. Our method runs in an average of 1.6 s per solar cycle, while Monte Carlo completes it in 1600 s per solar cycle. In order to account for dependency between sequential tests, Benjamini and Yekutieli (2001)'s FDR correction was applied to the *p*-values obtained with the test based on $P_{n,2}^{AD}$. These corrected *p*-values are shown in the top row of Figure 4. Second, circular-linear kernel density estimation (García-Portugués et al., 2013) of sunspot births for northern (middle-top figure) and southern (middle-bottom) hemispheres allowed us to compute several level sets, represented as contour lines labeled as "100p%". Each of these sets is the smallest set containing 1-pof the probability of the estimated density function. Hence, darker sets represent higher-density zones of sunspot births, both through time and longitude. Third, a scatter plot of sunspot births is shown in the bottom figures, along with the circular Nadaraya–Watson (Di Marzio et al., 2012) regression for northern (blue), southern (red), and both (black) hemispheres. The Nadarava–Watson regression gives a moving circular mean of the longitudes of sunspot births through time. Both density and regression kernel estimates use "rule-of-thumb" bandwidths for normal (Silverman, 1986) and von Mises–Fisher (García-Portugués, 2013) distributions, given the similarity of marginal distributions with these respective distributions and the marked undersmoothing that resulted from

cross-validation bandwidths.

We draw the following conclusions from the analysis:

- (i) In general, the two hemispheres seem to have different behavioral patterns, both in terms of longitudinal non-uniformities and sunspots activity level, along solar cycles. During the 21st cycle, the northern hemisphere presents 33% of the tests rejected at significance level $\alpha = 0.05$. In cycles 22 and 23, the southern hemisphere presents more non-uniform periods (9% and 10% of the tests are rejected for $\alpha = 0.05$, respectively) than the northern hemisphere (5% and 3% are rejected, respectively).
- (ii) Non-uniformity periods are intermittent during the lifetime of the solar cycle, without a clear association with the intensity of the sunspots appearance. The length and quantity of non-uniformity periods differ between solar cycles.
- (*iii*) Sunspots seem to appear in preferred zones of occurrence. Highest density sets, together with Nadaraya–Watson regressions, show consistent patterns of activity within certain longitudinal zones. In particular, periods in which uniformity is rejected at significance level $\alpha = 0.05$, the northern sunspot births seem to cluster around 0° (1982, 1990, 2000), 135° (1983–1984), and 180° (1977–1978, 1979–1980), while the southern hemisphere sunspot births cluster around -135° (1991, 2004, 2008). However, non-uniformity periods are too few to claim the existence of active longitudes.
- (iv) The flip-flop phenomenon between 180° active longitudes is not obvious throughout all the cycles. Although longitudes 0 and 180° seem to accumulate more sunspots in the northern hemisphere, the alternation between supplementary longitudes is not a clear, fixed-duration pattern.

5 Discussion

We have presented a general, automated approach to construct simple yet effective approximations for the upper tail of the exact-n null distribution of numerous goodness-of-fit statistics. The simulation results demonstrate that these approximations are accurate enough for practical applications of several upper-tail tests, even when these depend on a varying (yet known) parameter.

Although state-of-the-art statistic-specific algorithms like those of Marsaglia et al. (2003), Csörgö and Faraway (1996), and Marsaglia and Marsaglia (2004) provide arbitrarily accurate upper-tail pvalues for the D_n , W_n^2 , and A_n^2 statistics, respectively, our p-value approximation method offers significant computational improvements, has a reasonable precision (mean relative errors below 1%), and, most importantly, can be applied to a wide range of statistics. Compared to the general and omnipresent p-value approximation by M Monte Carlo trials, our method presents two key advantages: (i) more accurate results (at least, when $M = 10^4$); and (ii) faster running times by several orders of magnitude. This computational expediency makes the stabilized statistic especially convenient for sequential tests, as illustrated in the data application.

The (n, α) -stabilization significantly extends the scope of applicability of stabilizations like those of Stephens (1970). The stabilization focuses only on the upper tail of T_n , as this is usually the most useful in practice. However, stabilizations for the lower tail can be analogously derived. Obtaining modifications that stabilize the whole distribution, while still retaining simplicity, would offer the advantage of having approximated *p*-values that are roughly uniformly distributed under the null hypothesis. This task is left for future research.





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Supplementary material for "Data-driven stabilizations of goodness-of-fit tests"

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Abstract

This supplementary material is divided into two sections. Appendix A contains an analysis of regression metrics for different polynomial forms of (6) in Section 2.2. Appendix B presents an analysis of different weight functions for the regression in Section 2.2.

A Selection of (n, α) -model form

In order to choose and justify the final form of model (6), an analysis of different models is presented in Tables 9 and 10. The explored model specifications are

$$g_{\lambda,\mu}(n,\alpha) := 1 + \{\beta_{l,m} n^{-l/2} \alpha^{-m/2}\}_{l=1,m=0}^{\lambda,\mu},\tag{9}$$

where $\lambda, \mu \in \mathbb{N}$ are to be tuned. With this notation, the model considered in (6) in Section 2.2 is $g_{2,2}$.

Table 9 shows a comparative study of the performance of $g_{\lambda,2}(n,\alpha)$ for $\lambda = 2, \ldots, 5$, in order to determine the optimal power of n predictors, while keeping the α -predictors unchanged. Conversely, Table 10 shows the performance of models $g_{2,\mu}(n,\alpha)$ where $\mu = 2, \ldots, 5$ to analyze the effect of α , while not varying the n-predictors. In both tables the same main model-selection procedure applied in Section 2.2 is carried out: forward-backward model selection is run from Stephens' set of predictors, using weighted least squares with weights $w_j = n_j^{-1/2} \mathbb{1}_{\{0 < \alpha_j \leq 0.25\}}$, and with extended scope given by (9) (interactions are included). The last dropping step is excluded from the analysis.

Table 9 shows that, when increasing λ the BIC decreases marginally. The standard deviation of the residuals $\hat{\sigma}$ only decreases in the sixth decimal, while the R_{adj}^2 remains almost constant for D_n , and W_n^2 . Moreover, the multicollinearity present in the model increases by an order of magnitude per unit increment in λ , with high values of MVIF. In the case of A_n^2 , the BIC-optimal model equals that with $\lambda = 2$ — including more powers of n does not improve it.

Regarding the influence of the powers of α , Table 10 shows similar patterns to those in Table 9 for the three statistics D_n , W_n^2 , and A_n^2 . For D_n and W_n^2 , when including more powers of α , the BIC and $\hat{\sigma}$ decrease marginally, and R_{adj}^2 increases marginally. In exchange, the multicollinearity increases by an order of magnitude per unit increment in μ , also attaining high values of MVIF. For A_n^2 the situation is somehow different: from $\mu = 2$ to $\mu = 4$ there is a significant increase in R_{adj}^2 , yet at expenses of a ×100 increase in MVIF and a more convoluted model.

From the analyzed test statistics, the final form of the saturated model is chosen to be $g_{2,2}(n,\alpha)$ due to the general small increase in the goodness-of-fit metrics for more complex models and the increment in multicollinearity when increasing λ and μ . Importantly, the choice of $g_{2,2}(n,\alpha)$ allows having a single generic approach for any statistic and provides parsimonious stabilizing transformations.

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T_n	λ	$\hat{\sigma}$	BIC	$R^2_{\rm adj}$	MVIF	$\mathrm{pred}_\mathrm{MVIF}$
	2	$7.57\cdot 10^{-4}$	-397236	0.9993	$1\cdot 10^2$	$n^{-1/2}\alpha^{-1/2}$
Л	3	$7.50\cdot 10^{-4}$	-398020	0.9993	$4 \cdot 10^3$	$n^{-1}\alpha^{-1/2}$
D_n	4	$7.48\cdot10^{-4}$	-398184	0.9993	$1\cdot 10^5$	$n^{-3/2} \alpha^{-1/2}$
	5	$7.48\cdot10^{-4}$	-398212	0.9993	$3 \cdot 10^5$	n^{-2}
	2	$9.06\cdot10^{-4}$	-369813	0.9835	$1 \cdot 10^2$	$n^{-1/2} \alpha^{-1/2}$
W^2	3	$8.84\cdot10^{-4}$	-371092	0.9841	$8\cdot 10^2$	$n^{-1}\alpha^{-1/2}$
w n	4	$8.83\cdot 10^{-4}$	-371112	0.9841	$7\cdot 10^3$	$n^{-3/2}$
	5	$8.83\cdot10^{-4}$	-371119	0.9841	$2 \cdot 10^5$	n^{-2}
	2	$8.11 \cdot 10^{-4}$	-376072	0.8722	$2 \cdot 10^1$	$n^{-1} \alpha^{-1/2}$
Δ^2	3	$8.11\cdot10^{-4}$	-376072	0.8722	$2\cdot 10^1$	$n^{-1}\alpha^{-1/2}$
^{21}n	4	$8.11\cdot 10^{-4}$	-376072	0.8722	$2\cdot 10^1$	$n^{-1} \alpha^{-1/2}$
	5	$8.11\cdot 10^{-4}$	-376072	0.8722	$2\cdot 10^1$	$n^{-1}\alpha^{-1/2}$

Table 9: BIC-optimal $g_{\lambda,2}(n,\alpha)$ for statistics D_n , W_n^2 , and A_n^2 , obtained from weighted least squares and forward-backward model selection with scope (9) and $\lambda = 2, \ldots, 5$. The following goodness-of-fit measures are presented for each selected model: standard deviation $\hat{\sigma}$ of the residuals of upper-tail observations (i.e., $\{\hat{\varepsilon}_j \mid \alpha_j \leq 0.25\}_{j=1}^J$), BIC, and R_{adj}^2 . In addition, the MVIF and pred_{MVIF}, the predictor that takes the maximum variance inflation factor, inform on the multicollinearity of the selected model.

T_n	μ	$\hat{\sigma}$	BIC	$R^2_{\rm adj}$	MVIF	$\mathrm{pred}_\mathrm{MVIF}$
	2	$7.57\cdot 10^{-4}$	-397236	0.9993	$1\cdot 10^2$	$n^{-1/2}\alpha^{-1/2}$
ת	3	$5.22\cdot 10^{-4}$	-421343	0.9996	$2\cdot 10^3$	$n^{-1/2}\alpha^{-1}$
D_n	4	$3.68\cdot 10^{-4}$	-444816	0.9998	$5\cdot 10^4$	$n^{-1/2} \alpha^{-3/2}$
	5	$2.83\cdot 10^{-4}$	-462192	0.9999	$2\cdot 10^6$	$n^{-1}\alpha^{-2}$
	2	$9.06 \cdot 10^{-4}$	-369813	0.9835	$1 \cdot 10^2$	$n^{-1/2} \alpha^{-1/2}$
W^2	3	$5.85 \cdot 10^{-4}$	-411594	0.9949	$2 \cdot 10^3$	$n^{-1/2} \alpha^{-1}$
vv _n	4	$5.13\cdot10^{-4}$	-427884	0.9968	$5\cdot 10^4$	$n^{-1} \alpha^{-3/2}$
	5	$4.94 \cdot 10^{-4}$	-433359	0.9972	$4 \cdot 10^5$	$n^{-1}\alpha^{-2}$
	2	$8.11 \cdot 10^{-4}$	-376072	0.8722	$2\cdot 10^1$	$n^{-1} \alpha^{-1/2}$
Δ^2	3	$5.99 \cdot 10^{-4}$	-403690	0.9414	$2 \cdot 10^3$	$n^{-1/2} \alpha^{-1}$
^{11}n	4	$4.67 \cdot 10^{-4}$	-430707	0.9726	$7 \cdot 10^3$	$n^{-1} \alpha^{-3/2}$
	5	$4.15 \cdot 10^{-4}$	-447192	0.9828	$3 \cdot 10^5$	$n^{-1}\alpha^{-2}$

Table 10: BIC-optimal $g_{2,\mu}(n,\alpha)$ for statistics D_n , W_n^2 , and A_n^2 , obtained from weighted least squares and forward-backward model selection with scope (9) and $\mu = 2, \ldots, 5$. The table entries are analogous to those of Table 9.

B Selection of the weight function

Model (6) is estimated through weighted least squares using the samples $\{(n_j, \alpha_j, Y_j)\}_{j=1}^J$, $Y_j := T_{\infty;\alpha_j}/T_{n_j;\alpha_j}$. The weights considered in Section 2.2 are $w_j := n_j^{-1/2} \mathbb{1}_{\{0 < \alpha_j \leq 0.25\}}$. The term $n_j^{-1/2}$ gives heavier weight to the approximation error on lower sample sizes, while the indicator $\mathbb{1}_{\{0 < \alpha_j \leq 0.25\}}$ reflects the interest in prioritizing the stabilization of the upper tail of the test statistic T_n , where accuracy on the determination of exact-*n* quantiles is crucial for a precise test decision in the standard significance levels.

The effect of adding other factors to the weights is investigated in this section. First, instead of considering a hard thresholding by $1_{\{0 < \alpha_j \le 0.25\}}$, the factor $\alpha_j^{-1/2}$ can be introduced to place more weight on the upper quantiles while still incorporating the remaining quantiles. Second, in order to

mitigate the heteroscedasticity of the observations, the asymptotic variance of Y_i ,

$$A\mathbb{V}ar[Y_j] = \frac{T^2_{\infty;\alpha_j}\alpha_j (1-\alpha_j)}{M \cdot T^4_{n_j;\alpha_j} \cdot \left(f_n(T_{n_j;\alpha_j})\right)^2},\tag{10}$$

where M is the number of Monte Carlo samples and f_n is the density of T_n , can be incorporated to give more weight to ratios with smaller variances. Expression (10) is obtained with the delta method from the standard errors of sample quantiles (see, e.g., Serfling, 1980, Section 2.3.3). The evaluation of f_n can be done by differentiating a monotone spline interpolation of its cdf based on the saved quantiles $\{T_{n_j;\alpha_j} : n_j \in \mathcal{N}, \alpha_j \in \mathcal{A}\}$ (see Section 2.2).

Different combinations of the previous factors shape the following candidates for weight functions:

- $w_{1,j}(\alpha_j, Y_j) := 1_{\{0 < \alpha_j \le 0.25\}}$.
- $w_{2,j}(n_j, \alpha_j) := n_j^{-1/2} \mathbb{1}_{\{0 < \alpha_j \le 0.25\}}.$
- $w_{3,j}(\alpha_j, Y_j) := A \mathbb{V}ar^{-1/2}[Y_j] \mathbf{1}_{\{0 < \alpha_j \le 0.25\}}$
- $w_{4,j}(n_j, \alpha_j, Y_j) := n_j^{-1/2} \operatorname{AVar}^{-1/2}[Y_j] \mathbb{1}_{\{0 < \alpha_j \le 0.25\}}$
- $w_{5,j}(\alpha_j, Y_j) := A \mathbb{V}ar^{-1/2}[Y_j].$
- $w_{6,j}(n_j, \alpha_j, Y_j) := n_j^{-1/2} \operatorname{AVar}^{-1/2}[Y_j].$
- $w_{7,j}(n_j, \alpha_j) := (n_j \cdot \alpha_j)^{-1/2}.$

The following analysis compares the results of the weighted least squares regression on model (6) with weights computed by $w_{k,j}$, k = 1, ..., 7, according to the methodology described in Section 2.2, except for the last dropping step. The standard deviation of the residuals for the statistics D_n , W_n^2 , and A_n^2 is presented from two perspectives: Table 11 shows the residuals based on the α_j value, while in Table 12 the residuals are divided according to the sample size n_j . In addition, Table 13 shows the residuals depending on n_j only for upper-tail observations.

First, we analyze weights w_1 , w_2 , w_3 , and w_4 , all of which have the factor $1_{\{0 < \alpha_j \le 0.25\}}$ in common. As expected, they present the lowest errors for the upper tail $\alpha \le 0.25$. Despite presenting higher residual deviation for $\alpha > 0.25$, the errors differ only by about $\times 2$ with respect to w_5 and w_6 in average (Table 11). More importantly, w_1 and w_2 produce the smallest residuals for all sample sizes in the upper tail, w_2 exhibiting slightly smaller values for small sample sizes, $n \in [5, 10)$ (Table 13).

Second, w_5 and w_6 factor in the asymptotic variance, showing both similar results. In particular, they attain the lowest errors for $\alpha > 0.25$ (Table 11) and small-to-moderate sample sizes (Table 12). However, the standard deviation of upper-tail residuals is one order of magnitude higher than w_1 , w_2 , w_3 , and w_4 (Table 11).

Finally, w_7 weights observations by $\alpha_j^{-1/2}$. Its behavior is similar to w_5 and w_6 for $\alpha > 0.25$ and all sample sizes. Yet, errors in the upper tail are lower, but still about $\times 3$ higher than w_1 and w_2 .

From the previous observations, the final weight function chosen to fit model (6) is w_2 due to two main reasons: (i) the significant difference of errors for $\alpha \leq 0.25$ against w_5 , w_6 , and w_7 ; and (ii) the lower residual deviation in the upper tail for small sample sizes when compared to w_1 , w_3 , and w_4 .

References

Serfling, R. J. (1980). Approximation Theorems of Mathematical Statistics. Wiley Series in Probability and Statistics. New York: Wiley.

	T		Standard deviation				
w_k	I_n	$\alpha \in (0, 0.25]$	$\alpha \in (0.25, 0.5]$	$\alpha \in (0.5, 0.75]$	$\alpha \in (0.75, 1)$		
	D_n	$7.55\cdot 10^{-4}$	$1.66 \cdot 10^{-3}$	$3.11\cdot 10^{-3}$	$7.24\cdot 10^{-3}$		
w_1	W_n^2	$9.03\cdot10^{-4}$	$1.90 \cdot 10^{-3}$	$4.08 \cdot 10^{-3}$	$1.01 \cdot 10^{-2}$		
	A_n^2	$8.11\cdot 10^{-4}$	$1.50\cdot 10^{-3}$	$2.13\cdot 10^{-3}$	$2.76 \cdot 10^{-3}$		
	D_n	$7.57 \cdot 10^{-4}$	$1.67 \cdot 10^{-3}$	$3.13 \cdot 10^{-3}$	$7.25 \cdot 10^{-3}$		
w_2	W_n^2	$9.06\cdot10^{-4}$	$1.90\cdot10^{-3}$	$4.07 \cdot 10^{-3}$	$1.01 \cdot 10^{-2}$		
	A_n^2	$8.11\cdot 10^{-4}$	$1.50\cdot10^{-3}$	$2.13\cdot 10^{-3}$	$2.76 \cdot 10^{-3}$		
	D_n	$8.03 \cdot 10^{-4}$	$1.60 \cdot 10^{-3}$	$3.05 \cdot 10^{-3}$	$7.18 \cdot 10^{-3}$		
w_3	W_n^2	$9.43\cdot10^{-4}$	$1.71\cdot10^{-3}$	$3.83\cdot10^{-3}$	$9.84 \cdot 10^{-3}$		
	A_n^2	$8.53\cdot 10^{-4}$	$1.30 \cdot 10^{-3}$	$1.88 \cdot 10^{-3}$	$2.69 \cdot 10^{-3}$		
	D_n	$8.10 \cdot 10^{-4}$	$1.61 \cdot 10^{-3}$	$3.06 \cdot 10^{-3}$	$7.19 \cdot 10^{-3}$		
w_4	W_n^2	$9.46\cdot 10^{-4}$	$1.71 \cdot 10^{-3}$	$3.83 \cdot 10^{-3}$	$9.83 \cdot 10^{-3}$		
	A_n^2	$8.54\cdot10^{-4}$	$1.30\cdot 10^{-3}$	$1.87\cdot 10^{-3}$	$2.69\cdot 10^{-3}$		
	D_n	$6.26 \cdot 10^{-3}$	$1.27\cdot 10^{-3}$	$1.24\cdot 10^{-3}$	$5.07\cdot 10^{-3}$		
w_5	W_n^2	$4.45 \cdot 10^{-3}$	$2.07 \cdot 10^{-3}$	$1.17 \cdot 10^{-3}$	$5.79\cdot 10^{-3}$		
	A_n^2	$1.47 \cdot 10^{-3}$	$3.73\cdot10^{-4}$	$6.42\cdot10^{-4}$	$2.73 \cdot 10^{-3}$		
	D_n	$6.27 \cdot 10^{-3}$	$1.27\cdot 10^{-3}$	$1.24\cdot10^{-3}$	$5.08 \cdot 10^{-3}$		
w_6	W_n^2	$4.45 \cdot 10^{-3}$	$2.05\cdot10^{-3}$	$1.16\cdot 10^{-3}$	$5.80 \cdot 10^{-3}$		
	A_n^2	$1.48 \cdot 10^{-3}$	$3.73\cdot10^{-4}$	$6.46 \cdot 10^{-4}$	$2.73 \cdot 10^{-3}$		
	D_n	$2.52 \cdot 10^{-3}$	$1.28 \cdot 10^{-3}$	$1.55 \cdot 10^{-3}$	$5.66 \cdot 10^{-3}$		
w_7	W_n^2	$2.42\cdot10^{-3}$	$1.39\cdot 10^{-3}$	$1.24 \cdot 10^{-3}$	$7.21 \cdot 10^{-3}$		
	A_n^2	$1.15\cdot 10^{-3}$	$6.36\cdot 10^{-4}$	$1.14\cdot 10^{-3}$	$2.61\cdot 10^{-3}$		

Table 11: Standard deviation of residuals $\{\hat{\varepsilon}_j\}_{j=1}^J$ of the weighted least squares regression of (6) with weights $\{w_{k,j}\}_{j=1}^J$, k = 1, ..., 7, for statistics D_n , W_n^2 , and A_n^2 . Residuals are presented in four blocks, each one considering the residuals of the observations whose α value lies within the interval in the column header. Bold highlights the best-performing weight per statistic and α -block.

	T	St	tandard deviati	on
w_k	I_n	$n \in [5, 10)$	$n \in [10, 100)$	$n \in [100, 300)$
	D_n	$1.28\cdot 10^{-2}$	$7.25\cdot 10^{-3}$	$4.11\cdot 10^{-3}$
w_1	W_n^2	$1.96 \cdot 10^{-2}$	$4.54\cdot10^{-3}$	$8.21\cdot 10^{-4}$
	A_n^2	$7.40 \cdot 10^{-3}$	$1.43 \cdot 10^{-3}$	$4.19 \cdot 10^{-4}$
	D_n	$1.28 \cdot 10^{-2}$	$7.24 \cdot 10^{-3}$	$4.10 \cdot 10^{-3}$
w_2	W_n^2	$1.96 \cdot 10^{-2}$	$4.55 \cdot 10^{-3}$	$8.37\cdot10^{-4}$
	A_n^2	$7.40 \cdot 10^{-3}$	$1.43 \cdot 10^{-3}$	$4.19\cdot 10^{-4}$
	D_n	$1.26 \cdot 10^{-2}$	$7.13 \cdot 10^{-3}$	$4.03 \cdot 10^{-3}$
w_3	W_n^2	$1.92 \cdot 10^{-2}$	$4.41 \cdot 10^{-3}$	$8.03\cdot10^{-4}$
	A_n^2	$7.19 \cdot 10^{-3}$	$1.32 \cdot 10^{-3}$	$4.07 \cdot 10^{-4}$
	D_n	$1.27 \cdot 10^{-2}$	$7.12 \cdot 10^{-3}$	$4.02 \cdot 10^{-3}$
w_4	W_n^2	$1.92 \cdot 10^{-2}$	$4.41 \cdot 10^{-3}$	$8.17\cdot 10^{-4}$
	A_n^2	$7.19 \cdot 10^{-3}$	$1.32\cdot 10^{-3}$	$4.07\cdot 10^{-4}$
	D_n	$1.07\cdot 10^{-2}$	$5.84\cdot10^{-3}$	$3.44\cdot10^{-3}$
w_5	W_n^2	$1.66\cdot10^{-2}$	$3.34\cdot 10^{-3}$	$7.35\cdot 10^{-4}$
	A_n^2	$7.08 \cdot 10^{-3}$	$1.12\cdot 10^{-3}$	$3.91\cdot 10^{-4}$
	D_n	$1.07\cdot 10^{-2}$	$5.84\cdot10^{-3}$	$3.44\cdot10^{-3}$
w_6	W_n^2	$1.66\cdot10^{-2}$	$3.35\cdot10^{-3}$	$7.39\cdot10^{-4}$
	A_n^2	$7.07\cdot 10^{-3}$	$1.12\cdot 10^{-3}$	$3.95\cdot10^{-4}$
	\overline{D}_n	$1.13 \cdot 10^{-2}$	$6.23 \cdot 10^{-3}$	$3.64 \cdot 10^{-3}$
w_7	W_n^2	$1.76 \cdot 10^{-2}$	$3.59 \cdot 10^{-3}$	$7.75\cdot10^{-4}$
	A_n^2	$7.13 \cdot 10^{-3}$	$1.16\cdot 10^{-3}$	$3.91\cdot 10^{-4}$

Table 12: Standard deviation of residuals $\{\hat{\varepsilon}_j\}_{j=1}^J$ of the weighted least squares regression of (6) with weights $\{w_{k,j}\}_{j=1}^J$, $k = 1, \ldots, 7$, for statistics D_n , W_n^2 , and A_n^2 . The results are divided into three blocks, each one considering the residuals of the observations whose n value lies within the interval in the column header. Bold highlights the best-performing weight per statistic and n-block.

w_k	T_n	Standard deviation		
		$n \in [5, 10)$	$n \in [10, 100)$	$n \in [100, 300)$
w_1	D_n	$1.21\cdot 10^{-3}$	$8.21\cdot 10^{-4}$	$5.23\cdot\mathbf{10^{-4}}$
	W_n^2	$3.03\cdot 10^{-3}$	$7.93\cdot 10^{-4}$	$5.09\cdot 10^{-4}$
	A_n^2	$2.84\cdot 10^{-3}$	$6.96\cdot10^{-4}$	$4.41\cdot 10^{-4}$
w_2	D_n	$1.19\cdot 10^{-3}$	$8.22 \cdot 10^{-4}$	$5.29 \cdot 10^{-4}$
	W_n^2	$3.01\cdot 10^{-3}$	$7.98\cdot10^{-4}$	$5.25\cdot10^{-4}$
	A_n^2	$2.84\cdot10^{-3}$	$6.96\cdot10^{-4}$	$4.41\cdot 10^{-4}$
w_3	D_n	$1.26 \cdot 10^{-3}$	$8.71 \cdot 10^{-4}$	$5.67 \cdot 10^{-4}$
	W_n^2	$3.19 \cdot 10^{-3}$	$8.32\cdot10^{-4}$	$5.11 \cdot 10^{-4}$
	A_n^2	$3.02 \cdot 10^{-3}$	$7.33 \cdot 10^{-4}$	$4.42 \cdot 10^{-4}$
w_4	D_n	$1.23 \cdot 10^{-3}$	$8.80 \cdot 10^{-4}$	$5.80 \cdot 10^{-4}$
	W_n^2	$3.17 \cdot 10^{-3}$	$8.35 \cdot 10^{-4}$	$5.26 \cdot 10^{-4}$
	A_n^2	$3.02 \cdot 10^{-3}$	$7.33\cdot10^{-4}$	$4.43 \cdot 10^{-4}$
w_5	D_n	$1.18 \cdot 10^{-2}$	$6.74 \cdot 10^{-3}$	$4.05 \cdot 10^{-3}$
	W_n^2	$1.78 \cdot 10^{-2}$	$3.63 \cdot 10^{-3}$	$7.71 \cdot 10^{-4}$
	A_n^2	$5.24 \cdot 10^{-3}$	$1.26 \cdot 10^{-3}$	$5.15 \cdot 10^{-4}$
w_6	D_n	$1.17 \cdot 10^{-2}$	$6.76 \cdot 10^{-3}$	$4.07 \cdot 10^{-3}$
	W_n^2	$1.79 \cdot 10^{-2}$	$3.63\cdot10^{-3}$	$7.77\cdot10^{-4}$
	A_n^2	$5.19\cdot10^{-3}$	$1.27\cdot 10^{-3}$	$5.27\cdot10^{-4}$
w_7	D_n	$4.34 \cdot 10^{-3}$	$2.54 \cdot 10^{-3}$	$1.47 \cdot 10^{-3}$
	W_n^2	$6.30 \cdot 10^{-3}$	$1.76 \cdot 10^{-3}$	$5.32\cdot10^{-4}$
	A_n^2	$3.18\cdot 10^{-3}$	$8.83\cdot10^{-4}$	$4.41\cdot 10^{-4}$

Table 13: Standard deviation of upper-tail residuals $\{\hat{\varepsilon}_j \mid \alpha_j \leq 0.25\}_{j=1}^J$ of the weighted least squares regression of (6) with weights $\{w_{k,j}\}_{j=1}^J$, k = 1, ..., 7, for statistics D_n, W_n^2 , and A_n^2 . Residuals are presented in three blocks, each one considering the residuals of the observations whose n value lies within the interval in the column header. Bold highlights the best-performing weight per statistic and n-block.