# Bivariate Generalized Exponential Distribution 

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#### Abstract

Recently it is observed that the generalized exponential distribution can be used quite effectively to analyze lifetime data in one dimension. The main aim of this paper is to define a bivariate generalized exponential distribution so that the marginals have generalized exponential distributions. It is observed that the joint probability density function, the joint cumulative distribution function and the joint survival distribution function can be expressed in compact forms. Several properties of this distribution have been discussed. We suggest to use the EM algorithm to compute the maximum likelihood estimators of the unknown parameters and also obtain the observed and expected Fisher information matrices. One data set has been re-analyzed and it is observed that the bivariate generalized exponential distribution provides a better fit than the bivariate exponential distribution.


Keywords: Joint probability density function; Conditional probability density function; Maximum likelihood estimators; Fisher information matrix; EM algorithm.
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## 1 Introduction

Gupta and Kundu (1999) introduced the generalized exponential (GE) distribution as a possible alternative to the well known gamma or Weibull distribution. The generalized exponential distribution has lots of interesting properties and it can be used quite effectively to analyze several skewed life time data. In many cases it is observed that it provides better fit than Weibull or gamma distributions. Since the distribution function of the GE is in closed form, it can be used quite easily for analyzing censored data also. The frequentest and Bayesian inferences have been developed for the unknown parameters of the GE distribution. The readers are referred to the review article of Gupta and Kundu (2007) for a current account on GE distribution.

Although quite a bit of work has been done in the recent years on GE distribution, but not much attempt has been made to extend this to the multivariate set up. Recently Sarhan and Balakrishnan (2007) has defined a new bivariate distribution using the GE distribution and exponential distribution and derived several interesting properties of this new distribution. Although they obtained the new bivariate distribution from the GE and exponential distributions, but the marginal distributions are not in known forms. In fact it is not known to the authors the existence of any bivariate distribution whose marginals are generalized exponential distributions.

The main aim of this paper is to provide a bivariate generalized exponential (BVGE) distribution so that the marginal distributions are GE distributions. In this connection, it may be mentioned here that Arnold (1967) provided some general techniques to construct multivarite distribution with specified marginals. We have adopted one of those techniques. The proposed BVGE distribution has three parameters but the scale and location parameters can be easily introduced. The joint cumulative distribution function (CDF), the joint
probability density function (PDF) and the joint survival distribution function (SDF) are in closed forms, which make it convenient to use in practice.

The maximum likelihood estimators (MLEs) can be used to estimate the four unknown parameters when the scale parameter is also present. Although, the MLEs as expected can not be obtained in explicit forms, but the EM algorithm can be used quite effectively to obtain the MLEs. We also provide the observed and expected Fisher information matrices for practical users. Recently Meintanis (2007) analyzed one data and concluded that bivariate Marshal and Olkin (1967) exponential distribution provided a very good fit. We have reanalyzed the same data set and it is observed that the proposed BVGE distribution provides a much better fit than the Marshal and Olkin bivariate exponential model and provided some justification also.

The rest of the paper is organized as follows. In section 2, we define the BVGE distribution and discuss its different properties. The EM algorithm to compute the MLEs of the unknown parameters is provided in section 3. The analysis of a data set is provided in section 4 . Finally we conclude the paper in section 5.

## 2 Bivariate Generalized Exponential Distribution

The univariate GE distribution has the following CDF and PDF respectively for $x>0$;

$$
\begin{equation*}
F_{G E}(x ; \alpha, \lambda)=\left(1-e^{-\lambda x}\right)^{\alpha}, \quad f_{G E}(x ; \alpha, \lambda)=\alpha \lambda e^{-\lambda x}\left(1-e^{-\lambda x}\right)^{\alpha-1} \tag{1}
\end{equation*}
$$

Here $\alpha>0$ and $\lambda>0$ are the shape and scale parameters respectively. It is clear that for $\alpha=1$, it coincides with the exponential distribution. From now on a GE distribution with the shape parameter $\alpha$ and the scale parameter $\lambda$ will be denoted by $\operatorname{GE}(\alpha, \lambda)$. For brevity when $\lambda=1$, we will denote it by $\operatorname{GE}(\alpha)$ and for $\alpha=1$, it will be denoted by $\operatorname{Exp}(\lambda)$.

From now on unless otherwise mentioned, it is assumed that $\alpha_{1}>0, \alpha_{2}>0, \alpha_{3}>0, \lambda>0$. Suppose $U_{1} \sim \operatorname{GE}\left(\alpha_{1}, \lambda\right), U_{1} \sim \operatorname{GE}\left(\alpha_{2}, \lambda\right)$ and $U_{3} \sim \operatorname{GE}\left(\alpha_{3}, \lambda\right)$ and they are mutually independent. Here ' $\sim$ ' means follows or has the distribution. Now define $X_{1}=\max \left\{U_{1}, U_{3}\right\}$ and $X_{2}=\max \left\{U_{2}, U_{3}\right\}$. Then we say that the bivariate vector $\left(X_{1}, X_{2}\right)$ has a bivariate generalized exponential distribution with the shape parameters $\alpha_{1}, \alpha_{2}$ and $\alpha_{3}$ and the scale parameter $\lambda$. We will denote it by $\operatorname{BVGE}\left(\alpha_{1}, \alpha_{2}, \alpha_{3}, \lambda\right)$. Now for the rest of the discussions for brevity, we assume that $\lambda=1$, although the results are true for general $\lambda$ also. The BVGE distribution with $\lambda=1$ will be denoted by $\operatorname{BVGE}\left(\alpha_{1}, \alpha_{2}, \alpha_{3}\right)$. Before providing the joint CDF or PDF, we first mention how it may occur in practice.

Stress Model: Suppose a system has two components. Each component is subject to individual independent stress say $U_{1}$ and $U_{2}$ respectively. The system has an overall stress $U_{3}$ which has been transmitted to both the components equally, independent of their individual stresses. Therefore, the observed stress at the two components are $X_{1}=\max \left\{U_{1}, U_{3}\right\}$ and $X_{2}=\max \left\{U_{2}, U_{3}\right\}$ respectively.

Maintenance Model: Suppose a system has two components and it is assumed that each component has been maintained independently and also there is an overall maintenance. Due to component maintenance, suppose the lifetime of the individual component is increased by $U_{i}$ amount and because of the overall maintenance, the lifetime of each component is increased by $U_{3}$ amount. Therefore, the increased lifetimes of the two component are $X_{1}=$ $\max \left\{U_{1}, U_{3}\right\}$ and $X_{2}=\max \left\{U_{2}, U_{3}\right\}$ respectively.

The following results will provide the joint CDF, joint PDF and conditional PDF.

Theorem 2.1: If $\left(X_{1}, X_{2}\right) \sim \operatorname{BVGE}\left(\alpha_{1}, \alpha_{2}, \alpha_{3}\right)$, then the joint $\operatorname{CDF}$ of $\left(X_{1}, X_{2}\right)$ for $x_{1}>0$, $x_{2}>0$, is

$$
\begin{equation*}
F_{X_{1}, X_{2}}\left(x_{1}, x_{2}\right)=\left(1-e^{-x_{1}}\right)^{\alpha_{1}}\left(1-e^{-x_{2}}\right)^{\alpha_{2}}\left(1-e^{-z}\right)^{\alpha_{3}} \tag{2}
\end{equation*}
$$

where $z=\min \left\{x_{1}, x_{2}\right\}$.

Proof: Trivial and therefore it is omitted.

Corollary 2.1: The joint $\operatorname{CDF}$ of the $\operatorname{BVGE}\left(\alpha_{1}, \alpha_{2}, \alpha_{3}\right)$ can also be written as

$$
\begin{aligned}
F_{X_{1}, X_{2}}\left(x_{1}, x_{2}\right) & =F_{G E}\left(x_{1} ; \alpha_{1}\right) F_{G E}\left(x_{2}, \alpha_{2}\right) F_{G E}\left(z ; \alpha_{3}\right) \\
& =F_{G E}\left(x_{1} ; \alpha_{1}+\alpha_{3}\right) F_{G E}\left(x_{2}, \alpha_{2}\right) \quad \text { if } x_{1}<x_{2} \\
& =F_{G E}\left(x_{1} ; \alpha_{1}\right) F_{G E}\left(x_{2}, \alpha_{2}+\alpha_{3}\right) \quad \text { if } x_{2}<x_{1} \\
& =F_{G E}\left(x ; \alpha_{1}+\alpha_{2}+\alpha_{3}\right) \quad \text { if } x_{1}=x_{2}=x .
\end{aligned}
$$

Theorem 2.2: If $\left(X_{1}, X_{2}\right) \sim \operatorname{BVGE}\left(\alpha_{1}, \alpha_{2}, \alpha_{3}\right)$, then the joint $\operatorname{PDF}$ of $\left(X_{1}, X_{2}\right)$ for $x_{1}>0$, $x_{2}>0$, is

$$
f_{X_{1}, X_{2}}\left(x_{1}, x_{2}\right)=\left\{\begin{array}{ccc}
f_{1}\left(x_{1}, x_{2}\right) & \text { if } & 0<x_{1}<x_{2}<\infty \\
f_{2}\left(x_{1}, x_{2}\right) & \text { if } & 0<x_{2}<x_{1}<\infty \\
f_{0}(x) & \text { if } & 0<x_{1}=x_{2}=x<\infty
\end{array}\right.
$$

where

$$
\begin{aligned}
f_{1}\left(x_{1}, x_{2}\right) & =f_{G E}\left(x_{1} ; \alpha_{1}+\alpha_{3}\right) f_{G E}\left(x_{2} ; \alpha_{2}\right) \\
& =\left(\alpha_{1}+\alpha_{3}\right) \alpha_{2}\left(1-e^{-x_{1}}\right)^{\alpha_{1}+\alpha_{3}-1}\left(1-e^{-x_{2}}\right)^{\alpha_{2}-1} e^{-x_{1}-x_{2}} \\
f_{2}\left(x_{1}, x_{2}\right) & =f_{G E}\left(x_{1} ; \alpha_{1}\right) f_{G E}\left(x_{2} ; \alpha_{2}+\alpha_{3}\right) \\
& =\left(\alpha_{2}+\alpha_{3}\right) \alpha_{1}\left(1-e^{-x_{1}}\right)^{\alpha_{1}-1}\left(1-e^{-x_{2}}\right)^{\alpha_{2}+\alpha_{3}-1} e^{-x_{1}-x_{2}} \\
f_{0}(x) & =\frac{\alpha_{3}}{\alpha_{1}+\alpha_{2}+\alpha_{3}} f_{G E}\left(x ; \alpha_{1}+\alpha_{2}+\alpha_{3}\right) \\
& =\alpha_{3}\left(1-e^{-x}\right)^{\alpha_{1}+\alpha_{2}+\alpha_{3}-1} e^{-x} .
\end{aligned}
$$

Proof: The expressions for $f_{1}(\cdot, \cdot)$ and $f_{2}(\cdot, \cdot)$ can be obtained simply by taking $\frac{\partial^{2} F_{X_{1}, X_{2}}\left(x_{1}, x_{2}\right)}{\partial x_{1} \partial x_{2}}$ for $x_{1}<x_{2}$ and $x_{2}<x_{1}$ respectively. But $f_{0}(\cdot)$ can not be obtained in the same way. Using
the facts that

$$
\begin{gather*}
\int_{0}^{\infty} \int_{0}^{x_{2}} f_{1}\left(x_{1}, x_{2}\right) d x_{1} d x_{2}+\int_{0}^{\infty} \int_{0}^{x_{1}} f_{2}\left(x_{1}, x_{2}\right) d x_{2} d x_{1}+\int_{0}^{\infty} f_{0}(x) d x=1  \tag{3}\\
\int_{0}^{\infty} \int_{0}^{x_{2}} f_{1}\left(x_{1}, x_{2}\right) d x_{1} d x_{2}=\alpha_{2} \int_{0}^{\infty}\left(1-e^{-x}\right)^{\alpha_{1}+\alpha_{2}+\alpha_{3}-1} e^{-x} d x \tag{4}
\end{gather*}
$$

and

$$
\begin{equation*}
\int_{0}^{\infty} \int_{0}^{x_{1}} f_{2}\left(x_{1}, x_{2}\right) d x_{2} d x_{1}=\alpha_{1} \int_{0}^{\infty}\left(1-e^{-x}\right)^{\alpha_{1}+\alpha_{2}+\alpha_{3}-1} e^{-x} d x \tag{5}
\end{equation*}
$$

note that

$$
\begin{equation*}
\int_{0}^{\infty} f_{0}(x) d x=\alpha_{3} \int_{0}^{\infty}\left(1-e^{-x}\right)^{\alpha_{1}+\alpha_{2}+\alpha_{3}-1} e^{-x} d x=\frac{\alpha_{3}}{\alpha_{1}+\alpha_{2}+\alpha_{3}} \tag{6}
\end{equation*}
$$

Therefore, the result follows.

Comment 2.1: From Theorem 2.2 and Theorem 2.3, it easily follows that if we take $0<$ $\alpha_{i}<1, i=1,2,3$, and $\alpha_{1}+\alpha_{3}=\alpha_{2}+\alpha_{3}=1$, then both $X_{1}$ and $X_{2}$ are exponentially distributed. Let, $\alpha_{3}=\alpha$ and $\alpha_{1}=1-\alpha$ and $\alpha_{2}=1-\alpha$, then the joint PDF of ( $X_{1}, X_{2}$ ) takes the form;

$$
f_{X_{1}, X_{2}}\left(x_{1}, x_{2}\right)=\left\{\begin{array}{clc}
f_{G E}\left(x_{1} ; 1\right) f_{G E}\left(x_{2} ; 1-\alpha\right) & \text { if } & x_{1}<x_{2}  \tag{7}\\
f_{G E}\left(x_{1} ; 1-\alpha\right) f_{G E}\left(x_{2} ; 1\right) & \text { if } & x_{1}>x_{2} \\
\frac{\alpha}{2-\alpha} f_{G E}(x ; 2-\alpha) & \text { if } & x_{1}=x_{2}=x
\end{array}\right.
$$

Therefore the joint PDF as given in (7) has exponential marginals.

The BVGE distribution has both an absolute continuous part and an singular part, similar to Marshall and Olkin's bivariate exponential model. The function $f_{X_{1}, X_{2}}(\cdot, \cdot)$ may be considered to be a density function for the BVGE distribution if it is understood that the first two terms are densities with respect to two-dimensional Lebesgue measure and the third term is a density function with respect to one dimensional Lebesgue measure, see for example Bemis, Bain and Higgins (1972). It is well known that although in one dimension the practical use of a distribution with this property is usually pathological, but they do
arise quite naturally in higher dimension. In case of BVGE distribution, the presence of a singular part means that if $X_{1}$ and $X_{2}$ are BVGE distribution, then $X_{1}=X_{2}$ has a positive probability. In many practical situations it may happen that $X_{1}$ and $X_{2}$ both are continuous random variables, but $X_{1}=X_{2}$ has a positive probability, see Marshall and Olkin (1967) in this connection. The following result will provide explicitly the absolute continuous part and the singular part of the BVGE distribution function.

Theorem 2.3: If $\left(X_{1}, X_{2}\right) \sim \operatorname{BVGE}\left(\alpha_{1}, \alpha_{2}, \alpha_{3}\right)$, then

$$
F_{X_{1}, X_{2}}\left(x_{1}, x_{2}\right)=\frac{\alpha_{1}+\alpha_{2}}{\alpha_{1}+\alpha_{2}+\alpha_{3}} F_{a}\left(x_{1}, x_{2}\right)+\frac{\alpha_{3}}{\alpha_{1}+\alpha_{2}+\alpha_{3}} F_{s}\left(x_{1}, x_{2}\right),
$$

where for $z=\min \left\{x_{1}, x_{2}\right\}$,

$$
F_{s}\left(x_{1}, x_{2}\right)=\left(1-e^{-z}\right)^{\alpha_{1}+\alpha_{2}+\alpha_{3}}
$$

and

$$
F_{a}\left(x_{1}, x_{2}\right)=\frac{\alpha_{1}+\alpha_{2}+\alpha_{3}}{\alpha_{1}+\alpha_{2}}\left(1-e^{-x_{1}}\right)^{\alpha_{1}}\left(1-e^{-x_{2}}\right)^{\alpha_{2}}\left(1-e^{-z}\right)^{\alpha_{3}}-\frac{\alpha_{3}}{\alpha_{1}+\alpha_{2}}\left(1-e^{-z}\right)^{\alpha_{1}+\alpha_{2}+\alpha_{3}},
$$

here $F_{s}(\cdot, \cdot)$ and $F_{a}(\cdot, \cdot)$ are the singular and the absolute continuous parts respectively.

Proof: To find $F_{a}\left(x_{1}, x_{2}\right)$ from $F_{X_{1}, X_{2}}\left(x_{1}, x_{2}\right)=p F_{a}\left(x_{1}, x_{2}\right)+(1-p) F_{s}\left(x_{1}, x_{2}\right), 0 \leq p \leq 1$, we compute

$$
\frac{\partial^{2} F_{X_{1}, X_{2}}\left(x_{1}, x_{2}\right)}{\partial x_{1} \partial x_{2}}=p f_{a}\left(x_{1}, x_{2}\right)=\left\{\begin{array}{lll}
f_{1}\left(x_{1}, x_{2}\right) & \text { if } & x_{1}<x_{2} \\
f_{2}\left(x_{1}, x_{2}\right) & \text { if } & x_{1}>x_{2}
\end{array}\right.
$$

from which $p$ may be obtained as

$$
p=\int_{0}^{\infty} \int_{0}^{x_{2}} f_{1}\left(x_{1}, x_{2}\right) d x_{1} d x_{2}+\int_{0}^{\infty} \int_{0}^{x_{1}} f_{2}\left(x_{1}, x_{2}\right) d x_{2} d x_{1}=\frac{\alpha_{1}+\alpha_{2}}{\alpha_{1}+\alpha_{2}+\alpha_{3}}
$$

and

$$
F_{a}\left(x_{1}, x_{2}\right)=\int_{0}^{x_{1}} \int_{0}^{x_{2}} f_{a}(u, v) d u d v
$$

Once $p$ and $F_{a}(\cdot, \cdot)$ are determined, $F_{s}(\cdot, \cdot)$ can be obtained by subtraction.

Alternatively, probabilistic arguments are also can be provided as follows. Suppose $A$ is the following event: $A=\left\{U_{1}<U_{3}\right\} \cap\left\{U_{2}<U_{3}\right\}$, then $P(A)=\frac{\alpha_{3}}{\alpha_{1}+\alpha_{2}+\alpha_{3}}$.

Therefore,

$$
\begin{equation*}
F_{X_{1}, X_{2}}\left(x_{1}, x_{2}\right)=P\left(X_{1} \leq x_{1}, X_{2} \leq x_{2} \mid A\right) P(A)+P\left(X_{1} \leq x_{1}, X_{2} \leq x_{2} \mid A^{\prime}\right) P\left(A^{\prime}\right) \tag{8}
\end{equation*}
$$

Moreover for $z$ as defined before,

$$
\begin{equation*}
P\left(X_{1} \leq x_{1}, X_{2} \leq x_{2} \mid A\right)=\left(1-e^{-z}\right)^{\alpha_{1}+\alpha_{2}+\alpha_{3}} \tag{9}
\end{equation*}
$$

and $P\left(X_{1} \leq x_{1}, X_{2} \leq x_{2} \mid A^{\prime}\right)$ can be obtained by subtraction.
Clearly, $\left(1-e^{-z}\right)^{\alpha_{1}+\alpha_{2}+\alpha_{3}}$ is the singular part as its mixed second partial derivative is zero when $x_{1} \neq x_{2}$, and $P\left(X_{1} \leq x_{1}, X_{2} \leq x_{2} \mid A^{\prime}\right)$ is the absolute continuous part as its mixed partial derivative is a density function.

Corollary 2.2: The joint PDF of $X_{1}$ and $X_{2}$ can be written as follows for $z=\min \left\{x_{1}, x_{2}\right\}$;

$$
f_{X_{1}, X_{2}}\left(x_{1}, x_{2}\right)=\frac{\alpha_{1}+\alpha_{2}}{\alpha_{1}+\alpha_{2}+\alpha_{3}} f_{a}\left(x_{1}, x_{2}\right)+\frac{\alpha_{3}}{\alpha_{1}+\alpha_{2}+\alpha_{3}} f_{s}(z)
$$

where

$$
f_{a}\left(x_{1}, x_{2}\right)=\frac{\alpha_{1}+\alpha_{2}+\alpha_{3}}{\alpha_{1}+\alpha_{2}} \times\left\{\begin{array}{lll}
f_{G E}\left(x_{1} ; \alpha_{1}+\alpha_{3}\right) f_{G E}\left(x_{2} ; \alpha_{2}\right) & \text { if } & x_{1}<x_{2} \\
f_{G E}\left(x_{1} ; \alpha_{1}\right) f_{G E}\left(x_{2} ; \alpha_{2}+\alpha_{3}\right) & \text { if } & x_{1}>x_{2}
\end{array}\right.
$$

and

$$
f_{s}(x)=\left(\alpha_{1}+\alpha_{2}+\alpha_{3}\right) e^{-x}\left(1-e^{-x}\right)^{\alpha_{1}+\alpha_{2}+\alpha_{3}-1}=f_{G E}\left(x ; \alpha_{1}+\alpha_{2}+\alpha_{3}\right)
$$

Clearly, here $f_{a}\left(x_{1}, x_{2}\right)$ and $f_{s}(z)$ are the absolute continuous part and singular part respectively.

Comment 2.2: Using the joint PDF of $X_{1}$ and $X_{2}$, the different product moments $X_{1}^{m} X_{2}^{n}$ can be obtained in terms of infinite series similar to the one dimensional GE distribution, see Gupta and Kundu (1999).

From Theorem 2.3, it is clear that as $\alpha_{3} \rightarrow 0, F_{X_{1}, X_{2}}\left(x_{1}, x_{2}\right) \rightarrow\left(1-e^{-x_{1}}\right)^{\alpha_{1}}\left(1-e^{-x_{2}}\right)^{\alpha_{2}}$, i.e., $X_{1}$ and $X_{2}$ become independent. Moreover, since

$$
A=\left(U_{1}<U_{3}\right) \cap\left(U_{2}<U_{3}\right)=\left\{\max \left\{U_{1}, U_{2}\right\}<U_{3}\right\}=\left\{X_{1}=X_{2}\right\},
$$

and $P(A)=\frac{\alpha_{3}}{\alpha_{1}+\alpha_{2}+\alpha_{3}}$, therefore, as $\alpha_{3} \rightarrow \infty, P(A)=P\left(X_{1}=X_{2}\right) \rightarrow 1$. It implies that for fixed $\alpha_{1}$ and $\alpha_{2}$, as $\alpha_{3}$ varies from 0 to $\infty$, the correlation between $X_{1}$ and $X_{2}$ varies from 0 to 1.

The following theorem provides the marginal and the conditional results of the BVGE distribution.

Theorem 2.4: If $\left(X_{1}, X_{2}\right) \sim \operatorname{BVGE}\left(\alpha_{1}, \alpha_{2}, \alpha_{3}\right)$, then
(a) $X_{1} \sim \operatorname{GE}\left(\alpha_{1}+\alpha_{3}\right)$ and $X_{2} \sim \operatorname{GE}\left(\alpha_{2}+\alpha_{3}\right)$
(b) The conditional distribution of $X_{1}$ given $X_{2}=x_{2}$, say $F_{X_{1} \mid X_{2}=x_{2}}\left(x_{1}\right)$, is a convex combination of an absolute continuous distribution function and a discrete (degenerate) distribution function as follows;

$$
F_{X_{1} \mid X_{2}=x_{2}}\left(x_{1}\right)=p_{2} G_{2}\left(x_{1}\right)+\left(1-p_{2}\right) H_{2}\left(x_{1}\right),
$$

where

$$
\begin{aligned}
& G_{2}\left(x_{1}\right)=\frac{1}{p_{2}} \times\left\{\begin{array}{lll}
\frac{\alpha_{2}}{\alpha_{2}+\alpha_{3}}\left(1-e^{-x_{2}}\right)^{-\alpha_{3}} \times\left(1-e^{-x_{1}}\right)^{\alpha_{1}+\alpha_{3}} & \text { if } & x_{1}<x_{2} \\
\left(1-e^{-x_{1}}\right)^{\alpha_{1}}-\frac{\alpha_{3}}{\alpha_{2}+\alpha_{3}}\left(1-e^{-x_{2}}\right)^{\alpha_{1}} & \text { if } & x_{1}>x_{2},
\end{array}\right. \\
& H_{2}(x)=\left\{\begin{array}{lll}
0 & \text { if } & x<x_{2} \\
1 & \text { if } & x \geq x_{2}
\end{array}\right.
\end{aligned}
$$

and

$$
p_{2}=1-\frac{\alpha_{3}}{\alpha_{2}+\alpha_{3}}\left(1-e^{-x_{2}}\right)^{\alpha_{1}} .
$$

(c) The conditional distribution of $X_{1}$ given $X_{2} \leq x_{2}$, say $F_{X_{1} \mid X_{2} \leq x_{2}}\left(x_{1}\right)$, is an absolute
continuous distribution function as follows;

$$
P\left(X_{1} \leq x_{1} \mid X_{2} \leq x_{2}\right)=F_{X_{1} \mid X_{2} \leq x_{2}}\left(x_{1}\right)=\left\{\begin{array}{ccc}
\left(1-e^{-x_{1}}\right)^{\alpha_{1}+\alpha_{3}}\left(1-e^{-x_{2}}\right)^{-\alpha_{3}} & \text { if } x_{1} \leq x_{2} \\
\left(1-e^{-x_{1}}\right)^{\alpha_{1}} & \text { if } x_{1}>x_{2}
\end{array}\right.
$$

Proof: Trivial and therefore it is omitted.

Comment 2.3: Since the joint survival function and the joint CDF have the following relation

$$
S_{X_{1}, X_{2}}\left(x_{1}, x_{2}\right)=1-F_{X_{1}}\left(x_{1}\right)-F_{X_{2}}\left(x_{2}\right)+F_{X_{1}, X_{2}}\left(x_{1}, x_{2}\right),
$$

therefore, the joint survival function of $X_{1}$ and $X_{2}$ also can be expressed in a compact form.

Comment 2.4: Using Theorem 2.4, different moments of $X_{1}, X_{2}$, and conditional moments of $X_{1} \mid X_{2}=x_{2}$ or $X_{1} \mid X_{2} \leq x_{2}$ can be obtained in terms of infinite series.

An important property of the independent GE random variables $X_{1}$ and $X_{2}$ is that $\max \left\{X_{1}, X_{2}\right\}$ is also GE. If $X_{1}$ and $X_{2}$ are dependent but $\left(X_{1}, X_{2}\right)$ is BVGE, then
$P\left(\max \left\{X_{1}, X_{2}\right\} \leq x\right)=P\left(X_{1} \leq x, X_{2} \leq x\right)=P\left(U_{1} \leq x, U_{2} \leq x, U_{3} \leq x\right)=\left(1-e^{-x}\right)^{\alpha_{1}+\alpha_{2}+\alpha_{3}}$,
that is the maximum of $X_{1}$ and $X_{2}$ is also GE.

It is also interesting to observe that for all $0<x_{1}, x_{2}<\infty$,

$$
F_{X_{1}, X_{2}}\left(x_{1}, x_{2}\right) \geq F_{X_{1}}\left(x_{1}\right) F_{X_{2}}\left(x_{2}\right)
$$

Since

$$
\bar{F}_{X_{1}, X_{2}}\left(x_{1}, x_{2}\right)-\bar{F}_{X_{1}}\left(x_{1}\right) \bar{F}_{X_{2}}\left(x_{2}\right)=F_{X_{1}, X_{2}}\left(x_{1}, x_{2}\right)-F_{X_{1}}\left(x_{1}\right) F_{X_{2}}\left(x_{2}\right),
$$

therefore,

$$
\bar{F}_{X_{1}, X_{2}}\left(x_{1}, x_{2}\right) \geq \bar{F}_{X_{1}}\left(x_{1}\right) \bar{F}_{X_{2}}\left(x_{2}\right)
$$

Now we discuss the dependency properties of $X_{1}$ and $X_{2}$.
(i) Since $F_{X_{1}, X_{2}}\left(x_{1}, x_{2}\right) \geq F_{X_{1}}\left(x_{1}\right) F_{X_{2}}\left(x_{2}\right)$ for all $x_{1}, x_{2}$, therefore, they will be positive quadrant dependent, i.e, for every pair of increasing functions $h_{1}(\cdot)$ and $h_{2}(\cdot)$,

$$
\operatorname{Cov}\left(h_{1}\left(X_{1}\right), h_{2}\left(X_{2}\right)\right) \geq 0
$$

(ii) From part (b) of Theorem 2.4 it easily follows that for every $x_{1}, P\left(X_{1} \leq x_{1} \mid X_{2}=x_{2}\right)$ is a decreasing function of $x_{2}$, therefore $X_{2}$ is positive regression dependent of $X_{1}$. By symmetry it follows that $X_{1}$ is positive regression dependent of $X_{2}$.
(iii) From part (c) of Theorem 2.4 it easily follows that for every $x_{1}, P\left(X_{1} \leq x_{1} \mid X_{2} \leq x_{2}\right)$ is a decreasing function of $x_{2}$, therefore $X_{1}$ is left tail decreasing in $X_{2}$. By symmetry it follows that $X_{2}$ is left tail decreasing in $X_{1}$.

## 3 Maximum Likelihood Estimation

In this section we address the problem of computing the maximum likelihood estimators (MLEs) of the unknown parameters of BVGE distribution based on a random sample. The problem can be written as follows: Suppose $\left\{\left(X_{11}, X_{21}\right), \ldots,\left(X_{1 n}, X_{2 n}\right)\right\}$ is a random sample from $\operatorname{BVGE}\left(\alpha_{1}, \alpha_{2}, \alpha_{3}, \lambda\right)$, the problem is to find the MLEs of the unknown parameters. We consider two cases separately, (a) $\alpha_{3}$ is known, (b) $\alpha_{3}$ is unknown. We use the following notation

$$
\begin{gathered}
I_{1}=\left\{i ; X_{1 i}<X_{2 i}\right\}, \quad I_{2}=\left\{X_{1 i}>X_{2 i}\right\}, \quad I_{0}=\left\{X_{1 i}=X_{2 i}=Y_{i}\right\}, \quad I=I_{1} \cup I_{2} \cup I_{3}, \\
\left|I_{1}\right|=n_{1}, \quad\left|I_{2}\right|=n_{2}, \quad\left|I_{0}\right|=n_{0}, \quad \text { and } n_{0}+n_{1}+n_{2}=n .
\end{gathered}
$$

Based on the observations, the log-likelihood function can be written as

$$
l\left(\alpha_{1}, \alpha_{2}, \alpha_{3}, \lambda\right)=n \ln \lambda+n_{1} \ln \left(\alpha_{1}+\alpha_{3}\right)+n_{1} \ln \alpha_{2}+\left(\alpha_{1}+\alpha_{3}-1\right) \sum_{i \in I_{1}} \ln \left(1-e^{-\lambda x_{1 i}}\right)
$$

$$
\begin{aligned}
& +\left(\alpha_{2}-1\right) \sum_{i \in I_{1}} \ln \left(1-e^{-\lambda x_{2 i}}\right)+n_{2} \ln \alpha_{1}+n_{2} \ln \left(\alpha_{2}+\alpha_{3}\right) \\
& +\left(\alpha_{1}-1\right) \sum_{i \in I_{2}} \ln \left(1-e^{-\lambda x_{1 i}}\right)+\left(\alpha_{2}+\alpha_{3}-1\right) \sum_{i \in I_{2}} \ln \left(1-e^{-\lambda x_{2 i}}\right) \\
& +n_{0} \ln \alpha_{3}+\left(\alpha_{1}+\alpha_{2}+\alpha_{3}-1\right) \sum_{i \in I_{0}} \ln \left(1-e^{-\lambda y_{i}}\right) \\
& -\lambda\left(\sum_{i \in I_{0}} y_{i}+\sum_{i \in I_{1} \cup I_{2}} x_{1 i}+\sum_{i \in I_{2} \cup I_{2}} x_{2 i}\right) .
\end{aligned}
$$

CASE 1: $\alpha_{3}$ is known.

In this case for fixed $\lambda$, the MLEs of $\alpha_{1}$ and $\alpha_{2}$, say $\widehat{\alpha}_{1}(\lambda)$ and $\widehat{\alpha}_{2}(\lambda)$ respectively, can be obtained as the solutions of the following equations;

$$
\begin{align*}
\frac{n_{1}}{\left(\alpha_{1}+\alpha_{3}\right)}+\frac{n_{2}}{\alpha_{1}} & =-\sum_{i \in I_{0}} \ln \left(1-\exp \left(-\lambda y_{i}\right)\right)-\sum_{i \in I_{1} \cup I_{2}} \ln \left(1-e^{-\lambda x_{1 i}}\right)  \tag{10}\\
\frac{n_{2}}{\left(\alpha_{2}+\alpha_{3}\right)}+\frac{n_{1}}{\alpha_{2}} & =-\sum_{i \in I_{0}} \ln \left(1-\exp \left(-\lambda y_{i}\right)\right)-\sum_{i \in I_{1} \cup I_{2}} \ln \left(1-e^{-\lambda x_{2 i}}\right) \tag{11}
\end{align*}
$$

It is not difficult to show that both the quadratic equations (10) and (11) have exactly one positive root each and they are

$$
\begin{align*}
& \widehat{\alpha}_{1}(\lambda)=\frac{\left(-k_{1} \alpha_{3}+n_{1}+n_{2}\right)+\sqrt{\left(-k_{1} \alpha_{3}+n_{1}+n_{2}\right)^{2}+4 k_{1} n_{2} \alpha_{3}}}{2 k_{1}}  \tag{12}\\
& \widehat{\alpha}_{2}(\lambda)=\frac{\left(-k_{2} \alpha_{3}+n_{1}+n_{2}\right)+\sqrt{\left(-k_{2} \alpha_{3}+n_{1}+n_{2}\right)^{2}+4 k_{2} n_{1} \alpha_{3}}}{2 k_{2}} \tag{13}
\end{align*}
$$

where

$$
\begin{aligned}
& k_{1}=-\left(\sum_{i \in I_{0}} \ln \left(1-\exp \left(-\lambda y_{i}\right)\right)+\sum_{i \in I_{1}} \ln \left(1-\exp \left(-\lambda x_{1 i}\right)\right)+\sum_{i \in I_{2}} \ln \left(1-\exp \left(-\lambda x_{1 i}\right)\right)\right), \\
& k_{2}=-\left(\sum_{i \in I_{0}} \ln \left(1-\exp \left(-\lambda y_{i}\right)\right)+\sum_{i \in I_{1}} \ln \left(1-\exp \left(-\lambda x_{2 i}\right)\right)+\sum_{i \in I_{2}} \ln \left(1-\exp \left(-\lambda x_{2 i}\right)\right)\right) .
\end{aligned}
$$

Once $\widehat{\alpha}_{1}(\lambda)$ and $\widehat{\alpha}_{2}(\lambda)$ are obtained, the MLE of $\lambda$ can be obtained by maximizing the profile $\log$-likelihood of $\lambda$. It can be obtained as a solution of the following fixed point type equation;

$$
\begin{equation*}
g(\lambda)=\lambda, \tag{14}
\end{equation*}
$$

where

$$
\begin{align*}
g(\lambda)= & n\left[\sum_{i \in I_{0}} y_{i}+\sum_{i \in I_{1} \cup I_{2}} x_{1 i}+\sum_{i \in I_{1} \cup I_{2}} x_{2 i}-\widehat{\alpha}_{1}(\lambda) \sum_{i \in I_{1}} \frac{x_{1 i} e^{-\lambda x_{1 i}}}{\left(1-e^{-\lambda x_{1 i}}\right)}\right. \\
& -\left(\widehat{\alpha}_{2}(\lambda)-1\right) \sum_{i \in I_{1}} \frac{x_{2 i} e^{-\lambda x_{2 i}}}{\left(1-e^{-\lambda x_{2 i}}\right)}-\left(\widehat{\alpha}_{1}(\lambda)-1\right) \sum_{i \in I_{2}} \frac{x_{1 i} e^{-\lambda x_{1 i}}}{\left(1-e^{-\lambda x_{1 i}}\right)} \\
& \left.-\widehat{\alpha}_{2}(\lambda) \sum_{i \in I_{2}} \frac{x_{2 i} e^{-\lambda x_{2 i}}}{\left(1-e^{-\lambda x_{2 i}}\right)}-\left(\widehat{\alpha}_{1}(\lambda)+\widehat{\alpha}_{2}(\lambda)\right) \sum_{i \in I_{1}} \frac{x_{1 i} e^{-\lambda x_{1 i}}}{\left(1-e^{-\lambda x_{1 i}}\right)}\right]^{-1} . \tag{15}
\end{align*}
$$

Simple iterative procedure as follows can be used to compute the MLEs. We start with the initial guess of $\lambda$ as $\lambda^{(0)}$. Obtain $\widehat{\alpha}_{1}\left(\lambda_{0}\right)$ and $\widehat{\alpha}_{2}\left(\lambda_{0}\right)$ from (12) and (13). Compute $\lambda^{(1)}=g\left(\lambda^{(0)}\right)$ using (15). Replace $\lambda^{(0)}$ by $\lambda^{(1)}$ and repeat the process. The process continues until $\left|\lambda^{(i)}-\lambda^{(i+1)}\right|<\epsilon$, where $\epsilon$ is some pre-assigned tolerance level.

Case 2: $\alpha_{3}$ is also unknown.

In this case we suggest EM algorithm to compute the MLEs of the unknown parameters. We treat this as a missing value problem as follows. Assume that for a bivariate random $\operatorname{vector}\left(X_{1}, X_{2}\right)$, there is an associate random vector $\left(\Delta_{1}, \Delta_{2}\right), \Delta_{1}=1$ or 3 , if $U_{1}>U_{3}$ or $U_{1}<U_{3}$ and similarly, $\Delta_{2}=2$ or 3 , if $U_{2}>U_{3}$ or $U_{2}<U_{3}$ respectively. Therefore, if $X_{1}=X_{2}$, then $\Delta_{1}=\Delta_{2}=3$, but if $X_{1}<X_{2}$ or $X_{1}>X_{2}$, then $\left(\Delta_{1}, \Delta_{2}\right)$ is missing. If $\left(x_{1}, x_{2}\right) \in I_{1}$, then the possible values of $\left(\Delta_{1}, \Delta_{2}\right)$ are (1,2) and (3,2), similarly, if $\left(x_{1}, x_{2}\right) \in I_{2}$, then $\left(\Delta_{1}, \Delta_{2}\right)$ can take $(1,3)$ and $(1,2)$ with non-zero probabilities.

Now we provide the ' $E$ '-step and ' M '-step of the EM algorithm. In the ' E '-step, we treat the observations belong to $I_{0}$ as the complete observations. If the observation $\left(x_{1}, x_{2}\right)$ belongs to either $I_{1}$ or $I_{2}$, we treat it as a missing observation. If $\left(x_{1}, x_{2}\right) \in I_{1}$, we form the 'pseudo observation' by fractioning ( $x_{1}, x_{2}$ ) to two partially complete 'pseudo observation' of the form $\left(x_{1}, x_{2}, u_{1}(\gamma)\right)$ and $\left(x_{1}, x_{2}, u_{2}(\gamma)\right)$. Here $\gamma=\left(\alpha_{1}, \alpha_{2}, \alpha_{3}, \lambda\right)$, and the fractional mass $u_{1}(\gamma), u_{2}(\gamma)$ assigned to the 'pseudo observation' $\left(x_{1}, x_{2}\right)$ is the conditional probability that the random vector $\left(\Delta_{1}, \Delta_{2}\right)$ takes the values $(1,2)$ and $(3,2)$ respectively, given that $X_{1}<X_{2}$.

Similarly, if $\left(x_{1}, x_{2}\right) \in I_{2}$, we form the 'pseudo observation' of the form $\left(x_{1}, x_{2}, w_{1}(\gamma)\right)$ and $\left(x_{1}, x_{2}, w_{2}(\gamma)\right)$. Here the fractional mass $w_{1}(\gamma), w_{2}(\gamma)$ assigned to the 'pseudo observation' $\left(x_{1}, x_{2}\right)$ is the conditional probability that the random vector $\left(\Delta_{1}, \Delta_{2}\right)$ takes the values $(1,2)$ and $(1,3)$ respectively, given that $X_{1}>X_{2}$. Since

$$
P\left(U_{3}<U_{1}<U_{2}\right)=\frac{\alpha_{1} \alpha_{2}}{\left(\alpha_{1}+\alpha_{3}\right)\left(\alpha_{1}+\alpha_{2}+\alpha_{3}\right)}, \quad P\left(U_{1}<U_{3}<U_{2}\right)=\frac{\alpha_{2} \alpha_{3}}{\left(\alpha_{1}+\alpha_{3}\right)\left(\alpha_{1}+\alpha_{2}+\alpha_{3}\right)},
$$

therefore,

$$
u_{1}(\gamma)=\frac{\alpha_{1}}{\alpha_{1}+\alpha_{3}} \quad \text { and } \quad u_{2}(\gamma)=\frac{\alpha_{3}}{\alpha_{1}+\alpha_{3}}
$$

Similarly,

$$
w_{1}(\gamma)=\frac{\alpha_{2}}{\alpha_{2}+\alpha_{3}} \quad \text { and } \quad w_{2}(\gamma)=\frac{\alpha_{3}}{\alpha_{2}+\alpha_{3}}
$$

From now on we write $u_{1}(\gamma), u_{2}(\gamma), w_{1}(\gamma), w_{2}(\gamma)$ as $u_{1}, u_{2}, w_{1}, w_{2}$ respectively. The loglikelihood function of the 'pseudo data' can be written as

$$
\begin{aligned}
l_{\text {pseudo }}\left(\alpha_{1}, \alpha_{2}, \alpha_{3}, \lambda\right) & =n_{0} \ln \alpha_{3}+n_{0} \ln \lambda+\left(\alpha_{1}+\alpha_{2}+\alpha_{3}-1\right) \sum_{i \in I_{0}} \ln \left(1-e^{-\lambda y_{i}}\right)-\lambda \sum_{i \in I_{0}} x_{1 i} \\
& +u_{1}\left[n_{1} \ln \alpha_{1}+2 n_{1} \ln \lambda-\lambda \sum_{i \in I_{1}} x_{1 i}+\left(\alpha_{1}+\alpha_{3}-1\right) \sum_{i \in I_{1}} \ln \left(1-e^{-\lambda x_{1 i}}\right)\right] \\
& +u_{2}\left[n_{1} \ln \alpha_{3}+2 n_{1} \ln \lambda-\lambda \sum_{i \in I_{1}} x_{1 i}+\left(\alpha_{1}+\alpha_{3}-1\right) \sum_{i \in I_{1}} \ln \left(1-e^{-\lambda x_{1 i}}\right)\right] \\
& +n_{1} \ln \alpha_{2}-\lambda \sum_{i \in I_{1}} x_{2 i}+\left(\alpha_{2}-1\right) \sum_{i \in I_{1}} \ln \left(1-e^{-\lambda x_{2 i}}\right) \\
& +w_{1}\left[n_{2} \ln \alpha_{2}+2 n_{2} \ln \lambda-\lambda \sum_{i \in I_{2}} x_{2 i}+\left(\alpha_{2}+\alpha_{3}-1\right) \sum_{i \in I_{2}} \ln \left(1-e^{-\lambda x_{2 i}}\right)\right] \\
& +w_{2}\left[n_{2} \ln \alpha_{3}+2 n_{2} \ln \lambda-\lambda \sum_{i \in I_{2}} x_{2 i}+\left(\alpha_{2}+\alpha_{3}-1\right) \sum_{i \in I_{2}} \ln \left(1-e^{-\lambda x_{2 i}}\right)\right] \\
& +n_{2} \ln \alpha_{1}-\lambda \sum_{i \in I_{2}} x_{1 i}+\left(\alpha_{1}-1\right) \sum_{i \in I_{2}} \ln \left(1-e^{-\lambda x_{1 i}}\right) \\
& =n_{0} \ln \alpha_{3}+\ln \lambda\left(n_{0}+2\left(n_{1}+n_{2}\right)\right)+\left(\alpha_{1}+\alpha_{2}+\alpha_{3}-1\right) \sum_{i \in I_{0}} \ln \left(1-e^{-\lambda x_{1 i}}\right) \\
& -\lambda\left(\sum_{i \in I_{0}} y_{i}+\sum_{i \in I_{1} \cup I_{2}} x_{1 i}+\sum_{i \in I_{1} \cup I_{2}} x_{2 i}\right)+\ln \alpha_{1}\left(u_{1} n_{1}+n_{2}\right)+\ln \alpha_{2}\left(w_{1} n_{2}+n_{1}\right) \\
& +\left(\alpha_{1}+\alpha_{3}-1\right) \sum_{i \in I_{1}} \ln \left(1-e^{-\lambda x_{1 i}}\right)+\left(\alpha_{2}+\alpha_{3}-1\right) \sum_{i \in I_{2}} \ln \left(1-e^{-\lambda x_{2 i}}\right)
\end{aligned}
$$

$$
+\left(\alpha_{2}-1\right) \sum_{i \in I_{1}} \ln \left(1-e^{-\lambda x_{2 i}}\right)+\left(\alpha_{1}-1\right) \sum_{i \in I_{2}} \ln \left(1-e^{-\lambda x_{1 i}}\right) .
$$

Now the ' M ' step involves the maximization of the $l_{\text {pseudo }}\left(\alpha_{1}, \alpha_{2}, \alpha_{3}, \lambda\right)$ with respect to $\alpha_{1}, \alpha_{2}, \alpha_{3}$ and $\lambda$ at each step. For fixed $\lambda$, the maximization of $l_{\text {pseudo }}\left(\alpha_{1}, \alpha_{2}, \alpha_{3}, \lambda\right)$ occurs at

$$
\begin{aligned}
\widehat{\alpha}_{1}(\lambda) & =\frac{n_{1} u_{1}+u_{2}}{\sum_{i \in I_{0}} \ln \left(1-e^{-\lambda y_{i}}\right)+\sum_{i \in I_{1} \cup I_{2}} \ln \left(1-e^{-\lambda x_{1 i}}\right)} \\
\widehat{\alpha}_{2}(\lambda) & =\frac{n_{1}+w_{1} n_{2}}{\sum_{i \in I_{0}} \ln \left(1-e^{-\lambda y_{i}}\right)+\sum_{i \in I_{1} \cup I_{2}} \ln \left(1-e^{-\lambda x_{2 i}}\right)} \\
\widehat{\alpha}_{3}(\lambda) & =\frac{n_{0}+n_{1} u_{2}+n_{2} w_{2}}{\sum_{i \in I_{0}} \ln \left(1-e^{-\lambda y_{i}}\right)+\sum_{i \in I_{1}} \ln \left(1-e^{-\lambda x_{1 i}}\right)+\sum_{i \in I_{2}} \ln \left(1-e^{-\lambda x_{2 i}}\right)},
\end{aligned}
$$

and $\hat{\lambda}$, which maximizes $l_{\text {pseudo }}\left(\alpha_{1}, \alpha_{2}, \alpha_{3}, \lambda\right)$ can be obtained as a solution of the following fixed point equation;

$$
\begin{equation*}
g(\lambda)=\lambda, \tag{16}
\end{equation*}
$$

where

$$
\begin{aligned}
g(\lambda)= & {\left[\sum_{i \in I_{0}} y_{i}+\sum_{i \in I_{1} \cup I_{2}} x_{1 i}+\sum_{i \in I_{1} \cup I_{2}} x_{2 i}-\left(\widehat{\alpha}_{1}(\lambda)+\widehat{\alpha}_{2}(\lambda)+\widehat{\alpha}_{3}(\lambda)-1\right) \sum_{i \in I_{0}} \frac{y_{i} e^{-\lambda y_{i}}}{\left(1-e^{-\lambda y_{i}}\right)}\right.} \\
& -\left(\widehat{\alpha}_{1}(\lambda)+\widehat{\alpha}_{3}(\lambda)-1\right) \sum_{i \in I_{1}} \frac{x_{1 i} e^{-\lambda x_{1 i}}}{\left(1-e^{-\lambda x_{1 i}}\right)}-\left(\widehat{\alpha}_{2}(\lambda)+\widehat{\alpha}_{3}(\lambda)-1\right) \sum_{i \in I_{2}} \frac{x_{2 i} e^{-\lambda x_{2 i}}}{\left(1-e^{-\lambda x_{2 i}}\right)} \\
& \left.-\left(\widehat{\alpha}_{2}(\lambda)-1\right) \sum_{i \in I_{1}} \frac{x_{2 i} e^{-\lambda x_{2 i}}}{\left(1-e^{-\lambda x_{2 i}}\right)}-\left(\widehat{\alpha}_{1}(\lambda)-1\right) \sum_{i \in I_{2}} \frac{x_{1 i} e^{-\lambda x_{1 i}}}{\left(1-e^{-\lambda x_{1 i}}\right)}\right]\left(n_{0}+2 n_{1}+2 n_{2}\right) .
\end{aligned}
$$

Now we describe how to compute $(i+1)$-th step from the $i$-th step in the EM algorithm.

- Step 1: Suppose at the $i$-th step the estimates of $\alpha_{1}, \alpha_{2}, \alpha_{3}$ and $\lambda$ are $\alpha_{1}^{(i)}, \alpha_{2}^{(i)}, \alpha_{3}^{(i)}$ and $\lambda^{(i)}$ respectively.
- Step 2: Compute $u_{1}, u_{2}, w_{1}, w_{2} \operatorname{using} \alpha_{1}^{(i)}, \alpha_{2}^{(i)}, \alpha_{3}^{(i)}$ and $\lambda^{(i)}$.
- Step 3: Find $\lambda^{(i+1)}$ by solving (16) similarly as (14).
- Step 4: Once $\lambda^{(i+1)}$ is obtained, compute $\alpha_{1}^{(i+1)}=\widehat{\alpha}_{1}\left(\lambda^{(i+1)}\right)$, $\alpha_{2}^{(i+1)}=\widehat{\alpha}_{2}\left(\lambda^{(i+1)}\right)$, $\alpha_{3}^{(i+1)}=\widehat{\alpha}_{3}\left(\lambda^{(i+1)}\right)$.


## 4 Data Analysis

For illustrative purposes we have analyzed one data set to see how the proposed model and the EM algorithm works in practice. The data set has been obtained from Meintanis (2007) and it is presented in Table 1. The data represent the football (soccer) data where at least one goal scored by the home team and at least one goal scored directly from a penalty kick, foul kick or any other direct kick (all of them together will be called as kick goal) by any team have been considered. Here $X_{1}$ represents the time in minutes of the first kick goal scored by any team and $X_{2}$ represents the first goal of any type scored by the home team. In this case all possibilities are open, for example $X_{1}<X_{2}$, or $X_{1}>X_{2}$ or $X_{1}=X_{2}=Y$ (say). Meintanis (2007) used the Marshal-Olkin distribution to analyze the data. We would like to analyze the data using BVGE model.

Before going to analyze the data using BVGE model, we fit the GE distribution to $X_{1}$ and $X_{2}$ separately. The MLEs of the shape and scale parameters of the respective GE distribution for $X_{1}$ and $X_{2}$ are $(3.121,0.0449)$ and (1.678, 0.0413) respectively. The Kolmogorov-Smirnov distances between the fitted distribution and the empirical distribution function and the corresponding $p$ values (in brackets) for $X_{1}$ and $X_{2}$ are 0.119 (0.667) and $0.121(0.654)$ respectively. Based on the $p$ values GE distribution can not be rejected for the marginals.

First we try to fit the model under the assumption that $U_{3}$ is exponentially distributed, i.e. $\alpha_{3}=1$. In this case using the iterative algorithm (15), the MLEs of $\alpha_{1}, \alpha_{2}$ and $\lambda$ are $1.385,0.477$ and 0.0373 respectively. Here, we started the iteration with the initial guess of

| 2005-2006 | $X_{1}$ | $X_{2}$ | $2004-2005$ | X1 | X2 |
| :--- | :---: | :---: | :--- | :---: | :---: |
|  |  |  |  |  |  |
| Lyon-Real Madrid | 26 | 20 | Internazionale-Bremen | 34 | 34 |
| Milan-Fenerbahce | 63 | 18 | Real Madrid-Roma | 53 | 39 |
| Chelsea-Anderlecht | 19 | 19 | Man. United-Fenerbahce | 54 | 7 |
| Club Brugge-Juventus | 66 | 85 | Bayern-Ajax | 51 | 28 |
| Fenerbahce-PSV | 40 | 40 | Moscow-PSG | 76 | 64 |
| Internazionale-Rangers | 49 | 49 | Barcelona-Shakhtar | 64 | 15 |
| Panathinaikos-Bremen | 8 | 8 | Leverkusen-Roma | 26 | 48 |
| Ajax-Arsenal | 69 | 71 | Arsenal-Panathinaikos | 16 | 16 |
| Man. United-Benfica | 39 | 39 | Dynamo Kyiv-Real Madrid | 44 | 13 |
| Real Madrid-Rosenborg | 82 | 48 | Man. United-Sparta | 25 | 14 |
| Villarreal-Benfica | 72 | 72 | Bayern-M. TelAviv | 55 | 11 |
| Juventus-Bayern | 66 | 62 | Bremen-Internazionale | 49 | 49 |
| Club Brugge-Rapid | 25 | 9 | Anderlecht-Valencia | 24 | 24 |
| Olympiacos-Lyon | 41 | 3 | Panathinaikos-PSV | 44 | 30 |
| Internazionale-Porto | 16 | 75 | Arsenal-Rosenborg | 42 | 3 |
| Schalke-PSV | 18 | 18 | Liverpool-Olympiacos | 27 | 47 |
| Barcelona-Bremen | 22 | 14 | M. Tel-Aviv-Juventus | 28 | 28 |
| Milan-Schalke | 42 | 42 | Bremen-Panathinaikos | 2 | 2 |
| Rapid-Juventus | 36 | 52 |  |  |  |

Table 1: UEFA Champion's League data
$\alpha$ as one and the iteration converges in 6 steps.

Now we fit the BVGE model under the assumptions that all the four parameters are unknown. Although we have some ideas about the values of $\alpha_{1}+\alpha_{3}$ and $\alpha_{2}+\alpha_{3}$, but we do not know about their individual values. We have an idea about the value of $\lambda$ from the marginal $\lambda$ 's. For $\lambda=(0.0449+0.0413) / 2=0.0431$, we plot the profile log-likelihood function of $\alpha_{3}$ in Figure 1 and it is clear that the approximate value of $\alpha_{3}$ should be close to one. Therefore, we get initial guesses of $\alpha_{1}$ and $\alpha_{2}$ also. We start the EM algorithm with the initial guesses of $\alpha_{1}, \alpha_{2}, \alpha_{3}$ and $\lambda$ as 2.0, $0.5,1.0$ and 0.04 respectively. The EM algorithm converges in 6 -steps and MLEs of $\alpha_{1}, \alpha_{2}, \alpha_{3}$ and $\lambda$ are $1.445,0.468,1.170$ and 0.0390 . Since $\operatorname{Max}\left\{X_{1}, X_{2}\right\}$ also follows $\operatorname{GE}\left(\alpha_{1}+\alpha_{2}+\alpha_{3}\right)$, we can obtain the initial guesses as follows. We fit GE distributions to $X_{1}, X_{2}$ and to $\max \left\{X_{1}, X_{2}\right\}$ and take the initial estimates of $\lambda$


Figure 1: Profile log-likelihood function of $\alpha_{3}$.
as the average of the three estimates. Once we get the estimates of $\lambda$ we can obtain initial estimates of $\alpha_{1}, \alpha_{2}$ and $\alpha_{3}$ from three linear equations. We obtain the initial estimates of $\lambda$ in this case as 0.043 and using this value of $\lambda$ we obtain the initial estimates of $\alpha_{1}, \alpha_{2}$ and $\alpha_{3}$ as $2.55,0.35$ and 1.37 respectively. Using these initial values the EM algorithm converges to the same values after 11 iterations. We have computed the MLEs using direct maximization also (using grid search method) and we obtained the same estimates. Therefore, the EM algorithm works quite well in this case.

The corresponding $95 \%$ confidence intervals are obtained from the EM algorithm as suggested by Louis (1982) and they are as follows: (0.657, 2.233), (0.167, 0.769), (0.651, $1.689)$ and $(0.028,0.050)$ for $\alpha_{1}, \alpha_{2}, \alpha_{3}$ and $\lambda$ respectively. We have computed the KS distance and the corresponding $p$ values also (reported in brackets) between the fitted the $\operatorname{GE}(1.445+1.170=2.615,0.0390)$ and $\operatorname{GE}(0.468+1.170=1.638,0.0390)$ to the empirical distribution functions of $X_{1}$ and $X_{2}$ respectively. They are 0.103 (0.824) and 0.100 (0.852) respectively. Therefore, based on the marginals we can say that the BVGE distribution can
be used quite effectively in this case.

Now we try to test whether BVGE or Marshal-Olkin (MO) provides better fit to the above data set. It may be mentioned that the MO model can not be obtained as a sub model from BVGE model. Therefore, the standard chi-square test can not be applied. We use the AIC and BIC to check the model validity. In case of BVGE, based on the above estimates the log-likelihood value is -20.59 and in case of MO model, using the estimates obtained by Meintanis (2007), the log-likelihood value becomes -44.57 . The corresponding AIC (BIC) values are 49.18 (48.40) and 95.14 (94.56) respectively. Therefore, both the criteria suggest that BVGE provides a better fit than the MO model.

To see further why BVGE provides a better fit than the MO model, we look at the scaled TTT plot as suggested by Aarset (1987), which provides an idea of the shape of the hazard function of a distribution. For a family with the survival function $S(y)=1-F(y)$, the scaled TTT transform, with $H^{-1}(u)=\int_{0}^{F^{-1}(u)} S(y) d y$ defined for $0<u<1$ is $g(u)=$ $H^{-1}(u) / H^{-1}(1)$. The corresponding empirical version of the scaled TTT transform is given by $g_{n}(r / n)=H_{n}^{-1}(r / n) / H_{n}^{-1}(1)=\left[\left(\sum_{i=1}^{r} y_{i: n}\right)+(n-r) y_{r: n}\right] /\left(\sum_{i=1}^{n} y_{i: n}\right)$, where $r=1, \ldots, n$ and $y_{i: n}, i=1, \ldots, n$ represent the order statistics of the sample. It has been shown by Aarset (1987) that the scaled TTT transform is convex (concave) if the hazard rate is decreasing (increasing), and for bathtub (unimodal) hazard rates, the scaled TTT transform is first convex (concave) and then concave (convex). We plot the scaled TTT transform for $X_{1}$ and $X_{2}$ separately in Figure 2. From the Figure 2 it is quite apparent that both $X_{1}$ and $X_{2}$ have increasing hazard function and that also explains why BVGE, which may have increasing hazard functions for the marginals, provides better fit than MO model, which has only constant hazard functions for the marginals.


Figure 2: Scaled TTT transform for $X_{1}$ and $X_{2}$.

## 5 CONCLUSIONS

In this paper we have proposed bivariate generalized exponential distribution function whose marginals are generalized exponential distributions. It is observed that the BVGE distribution is a singular distribution and it has an absolute continuous part and a singular part. Since the joint distribution function and the joint density function are in closed forms, therefore this distribution can be used in practice for non-negative and positively correlated random variables. Although the maximum likelihood estimators of the unknown parameters can not be obtained in closed form but the EM algorithm works quite well and it can be effectively used to compute the MLEs. It may be mentioned that along the same line as Block and Basu (1974) bivariate exponential model, an absolute continuous version of the BVGE also can be obtained. Work is in progress in this direction and it will be reported else where.

## ACKNOWLEDGEMENTS:

The authors would like to thank the two referees for several constructive suggestions.

## Appendix

## Expected Fisher Information Matrix

Let the Fisher Information matrix be;

$$
I=E\left[\begin{array}{cccc}
\frac{\partial^{2} L}{\partial \alpha_{1}^{2}} & \frac{\partial^{2} L}{\partial \alpha_{1} \partial \alpha_{2}} & \frac{\partial^{2} L}{\partial \alpha_{1} \partial \alpha_{3}} & \frac{\partial^{2} L}{\partial \alpha_{1} \partial \lambda}  \tag{17}\\
\frac{\partial^{2} L}{\partial \alpha_{2} \partial \alpha_{1}} & \frac{\partial^{2} L}{\partial \alpha_{2}^{2}} & \frac{\partial^{2} L}{\partial \alpha_{2} L \alpha_{3}} & \frac{\partial^{2} L}{\partial \alpha_{2} \partial \lambda} \\
\frac{\partial^{2} L}{\partial \alpha_{3} \partial \alpha_{1}} & \frac{\partial^{2} L}{\partial \alpha \alpha_{3}} & \frac{\partial^{2} L}{\partial \alpha_{3}^{2}} & \frac{\partial^{2} L}{\partial \alpha_{3} \partial \lambda} \\
\frac{\partial^{2} L}{\partial \lambda \partial \alpha_{1}} & \frac{\partial^{2} L}{\partial \lambda \partial \alpha_{2}} & \frac{\partial^{2} L}{\partial \lambda \partial \alpha_{3}} & \frac{\partial^{2} L}{\partial \lambda^{2}}
\end{array}\right]
$$

Before providing the all the elements of the Fisher information matrix, we introduce the following notation. If $Z \sim \operatorname{GE}(\alpha, \lambda)$, then

$$
\begin{aligned}
\xi(\alpha)= & E\left[\frac{Z^{2} e^{-\lambda Z}}{\left(1-e^{-\lambda Z}\right)^{2}}\right] \\
= & \frac{\alpha}{(\alpha-2) \lambda^{2}}\left[\psi^{\prime}(1)-\psi^{\prime}(\alpha-1)+(\psi(\alpha)-\psi(1))^{2}\right] \\
& +\frac{\alpha}{(\alpha-1) \lambda^{2}}\left[\psi^{\prime}(1)-\psi(\alpha)+(\psi(\alpha)-\psi(1))^{2}\right] \quad \text { if } \quad \alpha>2 \\
= & \alpha \lambda \int_{0}^{\infty} z^{2} e^{-2 \lambda z}\left(1-e^{-\lambda z}\right)^{\alpha-3} d z \quad \text { if } \quad 0<\alpha \leq 2, \\
\eta(\alpha)= & E\left[\frac{Z e^{-\lambda Z}}{\left(1-e^{-\lambda Z}\right)}\right] \\
= & \frac{1}{\lambda}\left[\frac{\alpha}{\alpha-1}(\psi(\alpha)-\psi(1))-(\psi(\alpha+1)-\psi(1))\right] \quad \text { if } \quad \alpha>2 \\
= & \alpha \lambda \int_{0}^{\infty} z e^{-2 \lambda z}\left(1-e^{-\lambda z}\right)^{\alpha-2} d z \quad \text { if } \quad 0<\alpha \leq 1,
\end{aligned}
$$

where $\psi(\cdot)$ and $\psi^{\prime}(\cdot)$ are the digamma function and its derivative respectively, see Gupta and Kundu (1999) for details. Suppose $\left(X_{11}, X_{21}\right), \ldots,\left(X_{1 n}, X_{2 n}\right)$ is a random sample from
$\operatorname{BVGE}\left(\alpha_{1}, \alpha_{2}, \alpha_{3}, \lambda\right)$ and $n_{0}, n_{1}, n_{2}, I_{0}, I_{1}$ and $I_{2}$ are same as defined in section 4 . For brevity we further denote $\widetilde{\alpha}=\alpha_{1}+\alpha_{2}+\alpha_{3}$. We need the following results;
$E\left(n_{1}\right)=n P\left(X_{1}<X_{2}\right)=n \frac{\alpha_{2}}{\widetilde{\alpha}}, \quad E\left(n_{2}\right)=n P\left(X_{2}<X_{1}\right)=n \frac{\alpha_{1}}{\widetilde{\alpha}}, \quad E\left(n_{0}\right)=n P\left(X_{1}=X_{2}\right)=n \frac{\alpha_{3}}{\widetilde{\alpha}}$.

Lemma A.1: Let $V_{0} \sim \operatorname{GE}(\widetilde{\alpha}, \lambda), V_{1} \sim \operatorname{GE}\left(\alpha_{1}+\alpha_{3}, \lambda\right)$ and $V_{2} \sim \operatorname{GE}\left(\alpha_{2}+\alpha_{3}, \lambda\right)$ be three independent random variables and $g(\cdot)$ is a Borel measurable function, then

$$
\begin{aligned}
E\left(g\left(X_{i}\right) \mid i \in I_{1}\right) & =E\left(g\left(V_{1}\right)\right)-\frac{\alpha_{1}+\alpha_{3}}{\widetilde{\alpha}} E\left(g\left(V_{0}\right)\right) \\
E\left(g\left(X_{i}\right) \mid i \in I_{2}\right) & =\frac{\alpha_{1}}{\widetilde{\alpha}} E\left(g\left(V_{0}\right)\right) \\
E\left(g\left(X_{i}\right) \mid i \in I_{0}\right) & =\frac{\alpha_{3}}{\widetilde{\alpha}} E\left(g\left(V_{0}\right)\right) \\
E\left(g\left(Y_{i}\right) \mid i \in I_{1}\right) & =\frac{\alpha_{2}}{\widetilde{\alpha}} E\left(g\left(V_{0}\right)\right) \\
E\left(g\left(Y_{i}\right) \mid i \in I_{2}\right) & =E\left(g\left(V_{2}\right)\right)-\frac{\alpha_{2}+\alpha_{3}}{\widetilde{\alpha}} E\left(g\left(V_{0}\right)\right) .
\end{aligned}
$$

Proof of Lemma A.1: Note that

$$
\begin{aligned}
E\left(g\left(X_{i}\right) \mid i \in I_{1}\right) & =\left(\alpha_{1}+\alpha_{3}\right) \alpha_{2} \int_{0}^{\infty} \int_{x}^{\infty} g(x)\left(1-e^{-\lambda x}\right)^{\alpha_{1}+\alpha_{3}-1}\left(1-e^{-\lambda y}\right)^{\alpha_{2}-1} e^{-\lambda x} e^{-\lambda y} d y d x \\
& =\left(\alpha_{1}+\alpha_{3}\right) \int_{0}^{\infty} g(x)\left(1-e^{-\lambda x}\right)^{\alpha_{1}+\alpha_{3}-1} e^{-\lambda x}\left[1-\left(1-e^{-\lambda x}\right)^{\alpha_{2}}\right] d x \\
& =E\left(g\left(V_{1}\right)\right)-\frac{\alpha_{1}+\alpha_{3}}{\widetilde{\alpha}} E\left(g\left(V_{0}\right)\right)
\end{aligned}
$$

The others also can be obtained similarly.

Now we obtain

$$
\begin{aligned}
E\left[\frac{\partial^{2} L}{\partial \alpha_{1}^{2}}\right] & =-E\left[\frac{n_{1}}{\left(\alpha_{1}+\alpha_{3}\right)^{2}}+\frac{n_{2}}{\alpha_{1}^{2}}\right]=-\frac{n}{\widetilde{\alpha}}\left[\frac{\alpha_{2}}{\left(\alpha_{1}+\alpha_{3}\right)^{2}}+\frac{1}{\alpha_{1}}\right] \\
E\left[\frac{\partial^{2} L}{\partial \alpha_{2}^{2}}\right] & =-E\left[\frac{n_{2}}{\left(\alpha_{2}+\alpha_{3}\right)^{2}}+\frac{n_{1}}{\alpha_{2}^{2}}\right]=-\frac{n}{\widetilde{\alpha}}\left[\frac{\alpha_{1}}{\left(\alpha_{2}+\alpha_{3}\right)^{2}}+\frac{1}{\alpha_{2}}\right] \\
E\left[\frac{\partial^{2} L}{\partial \alpha_{3}^{2}}\right] & =-E\left[\frac{n_{1}}{\left(\alpha_{1}+\alpha_{3}\right)^{2}}+\frac{n_{2}}{\left(\alpha_{2}+\alpha_{3}\right)^{2}}+\frac{n_{0}}{\alpha_{3}^{2}}\right]=-\frac{n}{\widetilde{\alpha}}\left[\frac{\alpha_{2}}{\left(\alpha_{1}+\alpha_{3}\right)^{2}}+\frac{\alpha_{1}}{\left(\alpha_{2}+\alpha_{3}\right)^{2}}+\frac{1}{\alpha_{3}}\right] \\
E\left[\frac{\partial^{2} L}{\partial \lambda^{2}}\right] & =-E\left[\frac{1}{\lambda^{2}}+\left(\alpha_{1}+\alpha_{3}-1\right) \sum_{i \in I_{1}} \frac{X_{1 i}^{2} e^{-\lambda X_{1 i}}}{\left(1-e^{\left.-\lambda X_{1 i}\right)^{2}}\right.}+\left(\alpha_{2}-1\right) \sum_{i \in I_{1}} \frac{X_{2 i}^{2} e^{-\lambda X_{2 i}}}{\left(1-e^{\left.-\lambda X_{2 i}\right)^{2}}\right.}\right.
\end{aligned}
$$

$$
\begin{aligned}
& +\left(\alpha_{1}-1\right) \sum_{i \in I_{2}} \frac{X_{1 i}^{2} e^{-\lambda X_{1 i}}}{\left(1-e^{-\lambda X_{1 i}}\right)^{2}}+\left(\alpha_{2}+\alpha_{3}-1\right) \sum_{i \in I_{2}} \frac{X_{2 i}^{2} e^{-\lambda X_{2 i}}}{\left(1-e^{-\lambda X_{2 i}}\right)^{2}} \\
& \left.+(\widetilde{\alpha}-1) \sum_{i \in I_{0}} \frac{Y_{i}^{2} e^{-\lambda Y_{i}}}{\left(1-e^{-\lambda Y_{i}}\right)^{2}}\right] \\
& =-n\left[\frac{1}{\lambda^{2}}+\frac{\alpha_{2}\left(\alpha_{1}+\alpha_{3}-1\right)}{\widetilde{\alpha}}\left[\xi\left(\alpha_{1}+\alpha_{3}\right)-\frac{\alpha_{1}+\alpha_{3}}{\widetilde{\alpha}} \xi(\widetilde{\alpha})\right]+\left(\alpha_{2}-1\right)\left(\frac{\alpha_{2}}{\widetilde{\alpha}}\right)^{2} \xi(\widetilde{\alpha})\right. \\
& +\left(\alpha_{1}-1\right)\left(\frac{\alpha_{1}}{\widetilde{\alpha}}\right)^{2} \xi(\widetilde{\alpha})+\frac{\alpha_{1}\left(\alpha_{2}+\alpha_{3}-1\right)}{\widetilde{\alpha}}\left[\xi\left(\alpha_{2}+\alpha_{3}\right)-\frac{\alpha_{2}+\alpha_{3}}{\widetilde{\alpha}} \xi(\widetilde{\alpha})\right] \\
& \left.+(\widetilde{\alpha}-1)\left(\frac{\alpha_{3}}{\widetilde{\alpha}}\right)^{2} \xi(\widetilde{\alpha})\right] \\
& E\left[\frac{\partial^{2} L}{\partial \alpha_{1} \partial \lambda}\right]=E\left[\sum_{i \in I_{0}} \frac{Y_{i} e^{-\lambda Y_{i}}}{\left(1-e^{-\lambda Y_{i}}\right)}\right]+E\left[\sum_{i \in \cup I_{1} \cup I_{2}} \frac{X_{1 i} e^{-\lambda X_{1 i}}}{\left(1-e^{-\lambda X_{1 i}}\right)}\right] \\
& =n\left[\eta\left(\alpha_{1}+\alpha_{3}\right)-\frac{\alpha_{1}+\alpha_{3}}{\widetilde{\alpha}} \eta(\widetilde{\alpha})+\frac{\alpha_{1}}{\widetilde{\alpha}} \eta(\widetilde{\alpha})+\frac{\alpha_{3}}{\widetilde{\alpha}} \eta(\widetilde{\alpha})\right]=n \eta\left(\alpha_{1}+\alpha_{3}\right) \\
& E\left[\frac{\partial^{2} L}{\partial \alpha_{2} \partial \lambda}\right]=E\left[\sum_{i \in I_{1} \cup I_{2}} \frac{X_{2 i} e^{-\lambda X_{2 i}}}{\left(1-e^{-\lambda X_{2 i}}\right)}+\sum_{i \in I_{0}} \frac{Y_{i} e^{-\lambda Y_{i}}}{\left(1-e^{-\lambda Y_{i}}\right)}\right] \\
& =n\left[\frac{\alpha_{2}}{\widetilde{\alpha}} \eta(\widetilde{\alpha})+\eta\left(\alpha_{2}+\alpha_{3}\right)-\frac{\alpha_{2}+\alpha_{3}}{\widetilde{\alpha}} \eta(\widetilde{\alpha})+\frac{\alpha_{3}}{\widetilde{\alpha}} \eta(\widetilde{\alpha})\right]=n \eta\left(\alpha_{2}+\alpha_{3}\right) \\
& E\left[\frac{\partial^{2} L}{\partial \alpha_{3} \partial \lambda}\right]=E\left[\sum_{i \in I_{0}} \frac{Y_{i} e^{-\lambda Y_{i}}}{\left(1-e^{-\lambda Y_{i}}\right)}+\sum_{i I_{1}} \frac{X_{1 i} e^{-\lambda X_{1 i}}}{\left(1-e^{-\lambda X_{1 i}}\right)}+\sum_{i \in I_{2}} \frac{X_{2 i} e^{-\lambda X_{2 i}}}{\left(1-e^{-\lambda X_{2 i}}\right)}\right] \\
& =n\left[\eta\left(\alpha_{2}+\alpha_{3}\right)-\frac{\alpha_{2}+\alpha_{3}}{\widetilde{\alpha}} \eta(\widetilde{\alpha})+\eta\left(\alpha_{1}+\alpha_{3}\right)-\frac{\alpha_{1}+\alpha_{3}}{\widetilde{\alpha}} \eta(\widetilde{\alpha})+\frac{\alpha_{3}}{\widetilde{\alpha}} \eta(\widetilde{\alpha})\right] \\
& =n\left(\eta\left(\alpha_{1}+\alpha_{3}\right)+n \eta\left(\alpha_{2}+\alpha_{3}\right)\right) \\
& E\left[\frac{\partial^{2} L}{\partial \alpha_{1} \partial \alpha_{2}}\right]=E\left[\frac{\partial^{2} L}{\partial \alpha_{1} \partial \alpha_{3}}\right]=E\left[\frac{\partial^{2} L}{\partial \alpha_{2} \partial \alpha_{3}}\right]=0 .
\end{aligned}
$$

## Observed Fisher Information Matrix

For convenience we just present the observed Fisher information matrix obtained from the EM algorithm using the idea of Louis (1982). Using the same notation as Louis (1982), the observed Fisher information matrix can be written

$$
F_{o b s}=B-S S^{T},
$$

here $B$ is the negative of the second derivative of the log-likelihood function and $S$ is the derivative vector. We just provide the elements of the matrix $B$ and the vector $S$. We use
the following notation for brevity;

$$
\begin{gathered}
a_{0}=\sum_{i \in I_{0}} \ln \left(1-e^{-\widehat{\lambda} y_{i}}\right), a_{11}=\sum_{i \in I_{1}} \ln \left(1-e^{-\widehat{\lambda} x_{1 i}}\right), \quad a_{12}=\sum_{i \in I_{2}} \ln \left(1-e^{-\widehat{\lambda} x_{1 i}}\right), \quad a_{21}=\sum_{i \in I_{1}} \ln \left(1-e^{-\widehat{\lambda} x_{2 i}}\right), \\
a_{22}=\sum_{i \in I_{2}} \ln \left(1-e^{-\widehat{\lambda} x_{2 i}}\right), \quad b_{0}=\sum_{i \in I_{0}} \frac{y_{i} e^{-\widehat{\lambda} y_{i}}}{1-e^{-\widehat{\lambda} y_{i}}}, \quad b_{11}=\sum_{i \in I_{1}} \frac{x_{1 i} e^{-\widehat{\lambda} x_{1 i}}}{1-e^{-\widehat{\lambda} x_{1 i}}}, \quad b_{12}=\sum_{i \in I_{2}} \frac{x_{1 i} e^{-\widehat{\lambda} x_{1 i}}}{1-e^{-\widehat{\lambda} x_{1 i}}}, \\
b_{21}=\sum_{i \in I_{1}} \frac{x_{2 i} e^{-\widehat{\lambda} x_{2 i}}}{1-e^{-\widehat{\lambda} x_{2 i}}}, \quad b_{22}=\sum_{i \in I_{2}} \frac{x_{2 i} e^{-\widehat{\lambda} x_{2 i}}}{1-e^{-\widehat{\lambda} x_{2 i}}}, \quad c_{0}=\sum_{i \in I_{0}} \frac{y_{i}^{2} e^{-\widehat{\lambda} y_{i}}}{1-e^{-\widehat{\lambda} y_{i}}}, \quad c_{11}=\sum_{i \in I_{1}} \frac{x_{1 i}^{2} e^{-\widehat{\lambda} x_{1 i}}}{1-e^{-\widehat{\lambda} x_{1 i}}}, \\
c_{12}=\sum_{i \in I_{2}} \frac{x_{1 i}^{2} e^{-\widehat{\lambda} x_{1 i}}}{1-e^{-\widehat{\lambda} x_{1 i}}}, \quad c_{21}=\sum_{i \in I_{1}} \frac{x_{2 i}^{2} e^{-\widehat{\lambda} x_{2 i}}}{1-e^{-\widehat{\lambda} x_{2 i}}}, \quad c_{22}=\sum_{i \in I_{2}} \frac{x_{2 i}^{2} e^{-\widehat{\lambda} x_{2 i}}}{1-e^{-\widehat{\lambda} x_{2 i}}}, \quad d_{0}=\sum_{i \in I_{0}} y_{i}, \quad d_{11}=\sum_{i \in I_{1}} x_{1 i}, \\
d_{12}=\sum_{i \in I_{2}} x_{1 i}, \quad d_{21}=\sum_{i \in I_{1}} x_{2 i}, \quad d_{22}=\sum_{i \in I_{2}} x_{2 i} .
\end{gathered}
$$

Using the above notations we obtain;

$$
\begin{gathered}
S(1)=a_{0}+\frac{n_{1} u_{1}+n_{2}}{\widehat{\alpha}_{1}}+a_{11}+a_{12}, \quad S(2)=a_{0}+\frac{w_{1} n_{2}+n_{1}}{\widehat{\alpha}_{2}}+a_{21}+a_{22}, \\
S(3)=\frac{1}{\widehat{\alpha}_{3}}\left(n_{0}+n_{1} u_{1}+n_{2} w_{2}\right)+a_{0}+a_{11}+a_{22} \\
\left.S(4)=\frac{1}{\widehat{\lambda}}\left(n_{0}+2 n_{1}+2 n_{2}\right)+b_{0}\left(\widehat{\alpha}_{1}+\widehat{\alpha}_{2}+\widehat{\alpha}_{3}\right)+\left(d_{0}+d_{11}+d_{12}+d_{21}+d_{22}\right)+b_{11}\left(\widehat{\alpha}_{1}+\widehat{\alpha}_{3}-1\right)\right)+ \\
b_{22}\left(\widehat{\alpha}_{1}+\widehat{\alpha}_{3}-1\right)+b_{21}\left(\widehat{\alpha}_{1}-1\right)+b_{12}\left(\widehat{\alpha}_{2}-1\right),
\end{gathered}
$$

and

$$
\begin{gathered}
B(1,1)=\frac{\left(n_{1} u_{1}+n_{2}\right)}{\widehat{\alpha}_{1}^{2}}, \quad B(2,2)=\frac{\left(w_{1} n_{2}+n_{1}\right)}{\widehat{\alpha}_{2}^{2}}, \quad B(3,3)=\frac{\left(n_{0}+n_{1} u_{1}+n_{2} w_{2}\right)}{\widehat{\alpha}_{3}^{2}} \\
B(4,4)=\frac{1}{\widehat{\lambda}^{2}}+c_{0}\left(\widehat{\alpha}_{1}+\widehat{\alpha}_{2}+\widehat{\alpha}_{3}-1\right)+c_{11}\left(\widehat{\alpha}_{1}+\widehat{\alpha}_{3}-1\right)+c_{22}\left(\widehat{\alpha}_{2}+\widehat{\alpha}_{3}-1\right)+c_{21}\left(\widehat{\alpha}_{1}-1\right)+c_{12}\left(\widehat{\alpha}_{2}-1\right) \\
B(1,4)=B(4,1)=b_{0}+b_{11}+b_{21}, \quad B(2,4)=B(4,2)=b_{0}+b_{12}+b_{22} \\
B(3,4)=B(4,3)=b_{0}+b_{11}+b_{22}, B(1,2)=B(2,1)=B(1,3)=b(3,1)=B(2,3)=B(3,2)=0
\end{gathered}
$$

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