

The interval constrained 3-coloring problem

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Abstract

In this paper, we settle the open complexity status of interval constrained coloring with a fixed number of colors. We prove that the problem is already NP-complete if the number of different colors is 3. Previously, it has only been known that it is NP-complete, if the number of colors is part of the input and that the problem is solvable in polynomial time, if the number of colors is at most 2. We also show that it is hard to satisfy almost all of the constraints for a feasible instance.

1 Introduction

In the interval constrained 3-coloring problem, we are given a set \mathcal{I} of intervals defined on $[n] := \{1, \dots, n\}$ and a *requirement* function $r : \mathcal{I} \rightarrow \mathbb{Z}_{\geq 0}^3$, which maps each interval to a triple of non-negative integers. The objective is to determine a coloring $\chi : [n] \rightarrow \{1, 2, 3\}$ such that each interval gets the proper colors as specified by the requirements, i.e. $\sum_{i \in I} e_{\chi(i)} = r(I)$ where e_1, e_2, e_3 are the three unit vectors of \mathbb{Z}^3 .

This problem is motivated by an application in biochemistry to investigate the tertiary structure of proteins as shown in the following illustration. More precisely, in Hydrogen-Deuterium-Exchange

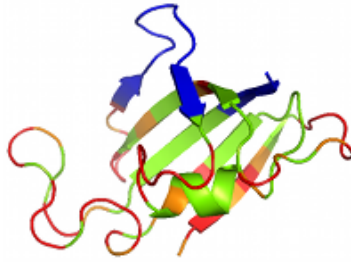


Figure 1: Coloring of the residues of a protein chain according to their exchange rates.

(HDX) experiments proteins are put into a solvent of heavy water (D_2O) for a certain time after which the amount of residual hydrogen atoms, that have exchanged with deuterium atoms, is measured [1]. Doing this experiment for several timesteps, one can determine the exchange rate of the

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residues. These exchange rates indicate the solvent accessibility of the residues and hence they provide information about the spatial structure of the protein. Mass spectroscopy is one of the methods for measuring these exchange rates. To this end, the proteins are digested, i.e. cut into parts which can be considered as intervals of the protein chain, and the mass uptake of each interval is measured. But thereby only bulk information about each interval can be obtained. Since there is not only one protein in the solvent but millions and they are not always cut in the same manner, we have this bulk information on overlapping fragments. That is, we are given the number of slow, medium, and fast exchanging residues for each of these intervals and our goal is to find a feasible assignment of these three exchange rates to residues such that for each interval the numbers match with the bulk information.

Though the interval constrained 3-coloring problem is motivated by a particular application, its mathematical abstraction appears quite simple and more general. In terms of integer linear programming, the problem can be equivalently formulated as follows. Given a matrix $A \in \{0, 1\}^{m \times n}$ with the *row-wise consecutive-ones property* and three vectors $b_{1,2,3} \in \mathbb{Z}_{\geq 0}^m$, the constraints

$$\begin{pmatrix} A & 0 & 0 \\ 0 & A & 0 \\ 0 & 0 & A \\ I & I & I \end{pmatrix} \cdot \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \\ 1 \end{pmatrix} \quad (1)$$

have a binary solution, i.e. $x_{1,2,3} \in \{0, 1\}^n$, if and only if the corresponding interval constrained 3-coloring problem has a feasible solution. We may assume w.l.o.g. that the requirements are consistent with the interval lengths, i.e. $A \cdot 1 = b_1 + b_2 + b_3$, since otherwise we can easily reject the instance as infeasible. Hence, we could treat x_3 as slack variables and reformulate the constraints as

$$Ax_1 = b_1, \quad Ax_2 = b_2, \quad x_1 + x_2 \leq 1. \quad (2)$$

It is known that if the matrix A has the *column-wise consecutive ones property* (instead of *row-wise*), then there is a reduction from the two-commodity integral flow problem, which has been proven to be NP-complete in [2]. However, the NP-completeness w.r.t. row-wise consecutive ones matrices has been an open problem in a series of papers as outlined in the following subsection.

1.1 Related Work

The problem of assigning exchange rates to single residues has first been considered in [3]. In that paper, the authors presented a branch-and-bound framework for solving the corresponding coloring problem with k color classes. They showed that there is a combinatorial polynomial time algorithm for the case of $k = 2$. Moreover, they asked the question about the complexity for $k > 2$. In [4], the problem has been called *interval constrained coloring*. It has been shown that the problem is NP-hard if the parameter k is part of the input. Moreover, approximation algorithms have been presented that allow violations of the requirements. Most notable with respect to our own results is their rounding scheme based on a technique introduced in [5]. It implies that if the LP relaxation of (1) is feasible, then there is a coloring satisfying at least $\frac{5}{16}$ of the requirements. But still, the question about the complexity for fixed $k \geq 3$ has been left open. In [6], several fixed parameter tractability results have been given. However, the authors state that they do not know whether the problem is tractable for fixed k .

1.2 Our contribution

In this paper, we prove the hardness of the interval constrained k -coloring problem for fixed parameter k . In fact, we completely settle the complexity status of the problem, since we show that already the

interval constrained 3-coloring problem is NP-hard by a reduction from 3-SAT. This hardness result holds more generally for any problem that can be formulated like (1). Moreover, we even show the stronger result, that it is still difficult to satisfy almost all of the constraints for a feasible instance. More precisely, we prove that there is a constant $\epsilon > 0$ such that it is NP-hard to distinguish between instances where all constraints can be satisfied and those where only a $(1 - \epsilon)$ fraction of constraints can be simultaneously satisfied. To this end, we extend our reduction using expander graphs. This gap hardness result implies APX-hardness of the problem of maximizing the number of satisfied constraints.

2 NP-hardness

Theorem 1. *It is NP-hard to decide whether there exists a feasible coloring χ for an instance (\mathcal{I}, r) of the interval constrained 3-coloring problem.*

Proof. The proof is by reduction from the 3-SAT problem.

Suppose to be given an instance of the 3-SAT problem, defined by q clauses C_1, \dots, C_q and p variables x_1, \dots, x_p . Each clause C_i ($i = 1, \dots, q$) contains 3 literals, namely $y_1(i), y_2(i), y_3(i)$. Each literal $y_h(i)$ ($i = 1, \dots, q$ and $h = 1, 2, 3$) refers to a variable x_j , that means, it is equal to either x_j or \bar{x}_j for some j in $1, \dots, p$. A truth assignment for the variables x_1, \dots, x_p satisfies the 3-SAT instance if and only if, for each clause, at least one literal takes the value *true*.

We now construct an instance of the interval constrained 3-coloring problem. For each clause C_i we introduce a sequence of consecutive nodes. This sequence is, in its turn, the union of three subsequences, one for each of the three literals (see Fig. 2). In the following, for the clarity of presentation,

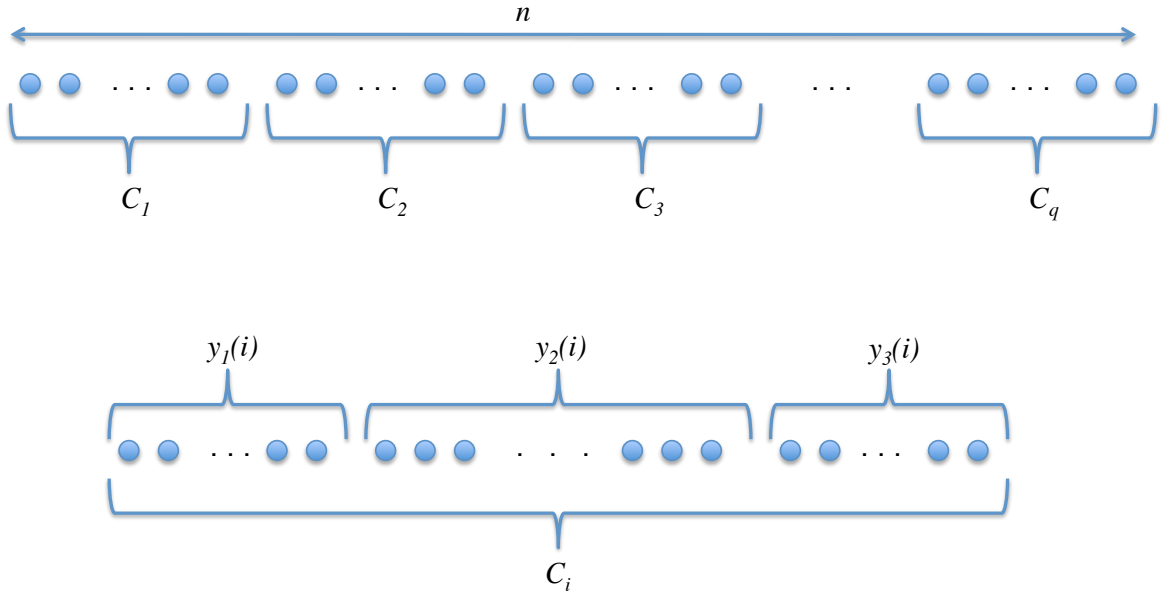


Figure 2: The sequence of nodes in an instance of the interval constrained 3-coloring problem.

we drop the index i , if it is clear from the context. We denote color 1 by RED, color 2 by BLACK and color 3 by WHITE.

Literal $y_1(i)$. The subsequence representing literal y_1 is composed of 8 nodes. Among them, there are three special nodes, namely t_1 , f_1 and a_1 , that play a key role since they encode the information about the truth value of the literal and of the variable x_j it refers to. The basic idea is to achieve the following two goals: 1) given a feasible coloring, if $\chi(t_1)$ is BLACK, we want to be able to construct a truth assignment setting x_j to *true*, while if $\chi(f_1)$ is BLACK, we want to be able to construct a truth assignment setting the variable x_j to *false*; 2) given a feasible coloring, if $\chi(a_1)$ is RED, we want to be able to construct a truth assignment where y_1 is *true*.

To achieve the first goal, we will impose the following property:

Property 1. *In any feasible coloring, exactly one among t_1 and f_1 will be BLACK.*

To achieve the second goal, and being consistent with the first one, we must have the property that:

Property 2. *In any feasible coloring, if $\chi(a_1) = \text{RED}$, then $\chi(t_1) = \text{BLACK}$ if $y_1 = x_j$, while $\chi(f_1) = \text{BLACK}$ if $y_1 = \bar{x}_j$.*

To guarantee properties (1) and (2), we introduce a suitable set $\mathcal{I}(y_1)$ of six intervals¹, shown in Fig. 3a.

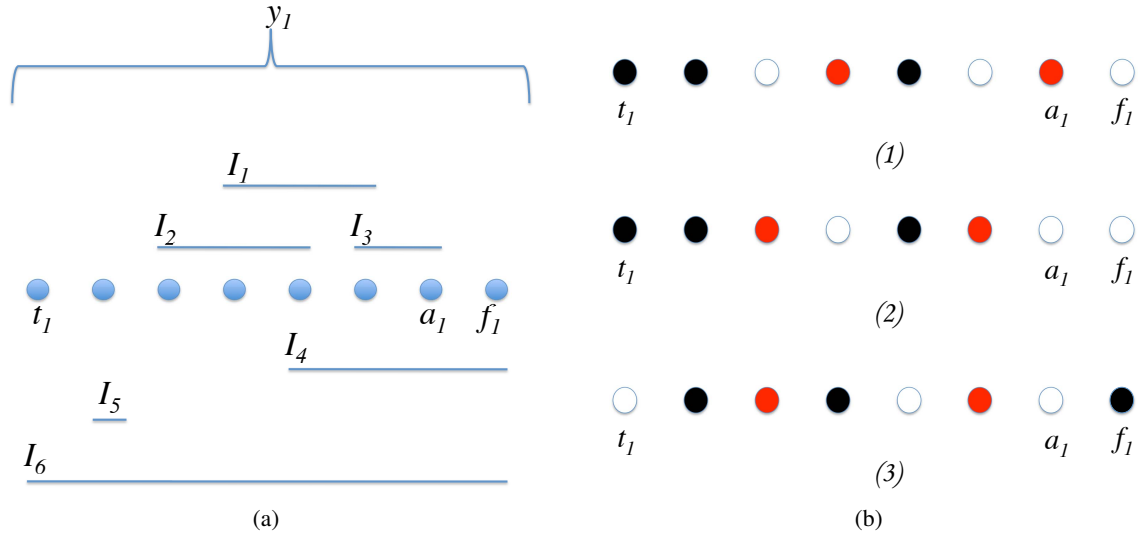


Figure 3: Literal y_1 . The picture on the right shows the three feasible colorings. On a black and white printout red color appears as grey.

The requirement function for such intervals changes whether $y_1 = x_j$ or $y_1 = \bar{x}_j$. If $y_1 = x_j$, we let $r(I_1) = (1, 1, 1)$; $r(I_2) = (1, 1, 1)$; $r(I_3) = (1, 0, 1)$; $r(I_4) = (1, 1, 2)$; $r(I_5) = (0, 1, 0)$; $r(I_6) = (2, 3, 3)$. For any feasible coloring there are only three possible outcomes for such sequence, reported in Fig. 3b. Observe that the properties (1) and (2) are enforced.

Now suppose that $y_1 = \bar{x}_j$: then we switch the requirement function with respect to WHITE and BLACK, i.e. define it as follows: $r(I_1) = (1, 1, 1)$; $r(I_2) = (1, 1, 1)$; $r(I_3) = (1, 1, 0)$; $r(I_4) = (1, 2, 1)$; $r(I_5) = (0, 0, 1)$; $r(I_6) = (2, 3, 3)$. Trivially, the possible outcomes for such sequence are exactly the ones in Fig. 3b but exchanging the BLACK and WHITE colors.

¹In principle, interval I_5 and the node it contains are not needed. However, this allows to have the same number of WHITE and BLACK colored nodes for the sake of exposition.

Literal $y_3(i)$. The sequence of nodes representing literal y_3 is similar to the one representing y_1 . We still have a sequence of 8 nodes, and three special nodes t_3 , f_3 and a_3 . As before, we let t_3 and f_3 encode the truth value of the variable x_j that is referred to by y_3 , while a_3 encodes the truth value of the literal y_3 itself. Therefore, we introduce a set $\mathcal{I}(y_3)$ of intervals in order to enforce the following properties:

Property 3. In any feasible coloring, exactly one among t_3 and f_3 will receive color BLACK.

Property 4. In any feasible coloring, if $\chi(a_3) = \text{RED}$, then $\chi(t_3) = \text{BLACK}$ if $y_3 = x_j$, while $\chi(f_3) = \text{BLACK}$ if $y_3 = \bar{x}_j$.

Fig. 4a shows the nodes and the six intervals that belong to $\mathcal{I}(y_3)$: observe that the sequence is similar to the one representing y_1 , but the position of node a_3 and the intervals are now "mirrored". If $y_3 = \bar{x}_j$, we let $r(I_1) = (1, 1, 1)$; $r(I_2) = (1, 1, 1)$; $r(I_3) = (1, 0, 1)$; $r(I_4) = (1, 1, 2)$; $r(I_5) = (0, 1, 0)$; $r(I_6) = (2, 3, 3)$. Fig. 4b reports the three possible outcomes for such sequence in a feasible coloring. Note that properties (3) and (4) hold.

Now suppose that $y_3 = x_j$: once again, we switch the requirement function with respect to WHITE and BLACK.

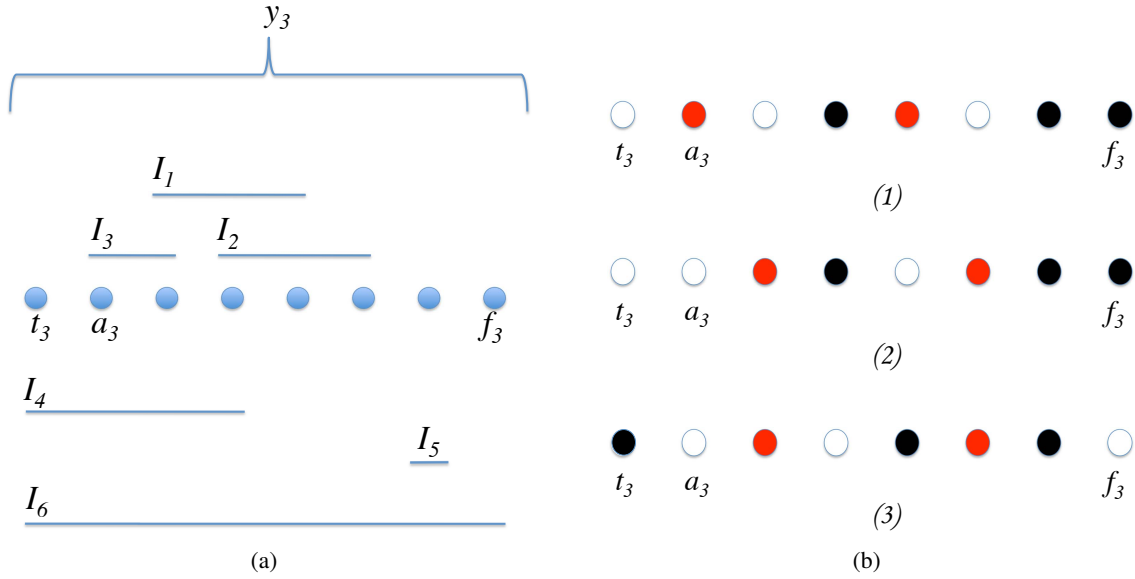


Figure 4: Literal y_3

Literal $y_2(i)$. The sequence of nodes representing literal y_2 is slightly more complicated. It is composed of 36 nodes, and among them there are 4 special nodes, namely t_2 , f_2 , a_2^ℓ and a_2^r (see Fig. 5). Still, we let t_2 and f_2 encode the truth value of the variable x_j that is referred to by y_2 , while a_2^ℓ and a_2^r encode the truth value of the literal.

Similarly to the previous cases, we want to achieve the following goals: 1) given a feasible coloring, if $\chi(t_2)$ is BLACK, we want to be able to construct a truth assignment setting the variable x_j to *true*, while if $\chi(f_2)$ is BLACK, we want to be able to construct a truth assignment setting the variable x_j to *false*; 2) given a feasible coloring, if $\chi(a_2^\ell) = \chi(a_2^r) = \text{RED}$, we want to be able to construct a truth assignment where the literal y_2 is *true*. We are therefore interested in the following properties:

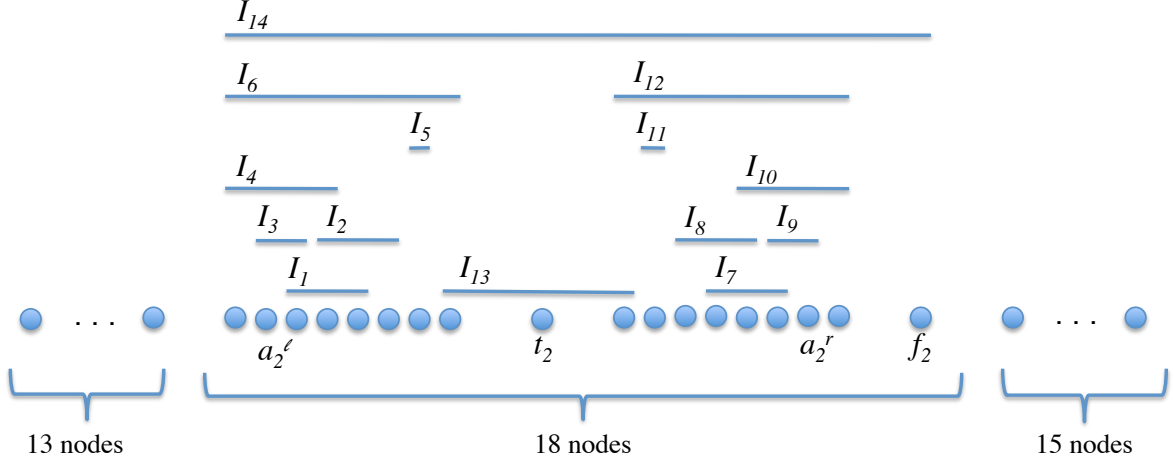


Figure 5: Literal y_2

Property 5. In any feasible coloring, exactly one among t_2 and f_2 will receive color *BLACK*.

Property 6. In any feasible coloring, if $\chi(a_2^l) = \text{RED}$ and $\chi(a_2^r) = \text{RED}$, then $\chi(t_2) = \text{BLACK}$ if $y_2 = x_j$, and $\chi(f_2) = \text{BLACK}$ if $y_2 = \bar{x}_j$.

In this case, we introduce a set $\mathcal{I}(y_2)$ of 14 suitable intervals, shown in Fig. 5. The requirements for the case $y_2 = \bar{x}_j$ are given in the following table.

| | I_1 | I_2 | I_3 | I_4 | I_5 | I_6 | I_7 | I_8 | I_9 | I_{10} | I_{11} | I_{12} | I_{13} | I_{14} |
|--------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|----------|----------|----------|----------|----------|
| <i>RED</i> | 1 | 1 | 1 | 1 | 0 | 2 | 1 | 1 | 1 | 1 | 0 | 2 | 0 | 4 |
| <i>BLACK</i> | 1 | 1 | 0 | 1 | 1 | 3 | 1 | 1 | 0 | 1 | 1 | 3 | 2 | 7 |
| <i>WHITE</i> | 1 | 1 | 1 | 2 | 0 | 3 | 1 | 1 | 1 | 2 | 0 | 3 | 1 | 7 |

Observe that the set of intervals $\{I_1, \dots, I_6\}$ is defined exactly as the set $\mathcal{I}(y_3)$, therefore the possible outcomes for the sequence of 8 nodes covered by such intervals are as in Fig. 4b. Similarly, the set of intervals $\{I_7, \dots, I_{12}\}$ is defined exactly as the set $\mathcal{I}(y_1)$, therefore the possible outcomes for the sequence of 8 nodes covered by such intervals are as in Fig. 3b.

One checks that properties (5) and (6) hold. In case $y_2 = x_j$, once again we switch the requirement function with respect to *WHITE* and *BLACK*.

It remains to describe the role played by the first 13 nodes and the last 15 nodes of the sequence, that so far we did not consider. We are going to do it in the next paragraph.

Intervals encoding truth values of literals. For each clause C_i , we add another set $\mathcal{I}(C_i)$ of intervals, in order to link the nodes encoding the truth values of its three literals. The main goal we pursue is the following: given a feasible coloring, we want to be able to construct a truth assignment such that at least one of the three literals is *true*. To achieve this, already having properties (2), (4) and (6), we only need the following property:

Property 7. For any feasible coloring, if $\chi(a_1) \neq \text{RED}$ and $\chi(a_3) \neq \text{RED}$, then $\chi(a_2^l) = \chi(a_2^r) = \text{RED}$.

Fig. 6 shows the six intervals that belong to $\mathcal{I}(C_i)$. The requirement function is: $r(I_1) = (1, 2, 2)$; $r(I_2) = (1, 2, 2)$; $r(I_3) = (1, 6, 6)$; $r(I_4) = (1, 3, 3)$; $r(I_5) = (1, 2, 2)$; $r(I_6) = (1, 7, 7)$. We now show that Property (7) holds. Suppose χ is a feasible coloring, and let v_1, \dots, v_{13} be the first 13 nodes of the sequence introduced for literal y_2 . By construction, if $\chi(a_1) \neq RED$, then there is a node $v_j : \chi(v_j) = RED$ and $j \in \{1, 2, 3\}$, otherwise $r(I_1)$ is violated. Similarly, if $\chi(a_2^\ell) \neq RED$, then there is a node $v_j : \chi(v_j) = RED$ and $j \in \{11, 12, 13\}$, otherwise $r(I_2)$ is violated. On the other hand, this subsequence contains exactly one node with RED color, otherwise $r(I_3)$ is violated. It follows that at least one among a_1 and a_2^ℓ has RED color. The same conclusions can be stated for nodes a_2^r and a_3 . Putting all together, it follows that the property (7) holds.

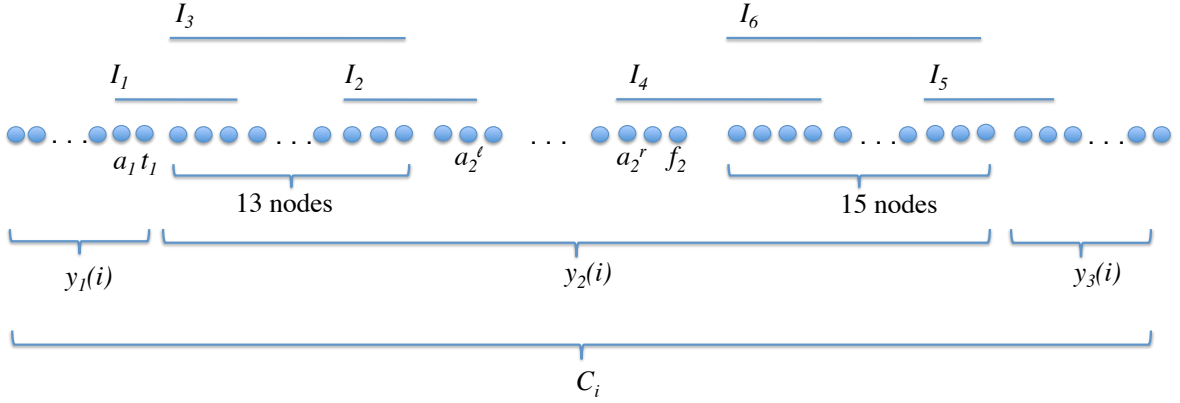


Figure 6: Set of intervals $\mathcal{I}(C_i)$.

Intervals encoding truth value of variables (later also called: variable intervals). Our last set of intervals will force different nodes to take the same color, if they encode the truth value of the same variable. In particular, we aim at having the following property:

Property 8. *In any feasible coloring, $\chi(t_h(i)) = \chi(f_k(i'))$ if both literals $y_h(i)$ and $y_k(i')$ refer to the same variable x_j .*

To achieve this, for each pair of such literals we add a big interval $I(y_h(i), y_k(i'))$ from $f_k(i')$ to $t_h(i)$ (assuming $i' < i$ without loss of generality). Note that, by construction, there is a subset of intervals that partitions all the internal nodes covered by the interval. That means, we know exactly the number of such nodes that must be colored with color RED, BLACK and WHITE (say z_1, z_2, z_3 respectively). Then, we let the requirement function be $r(I(y_h(i), y_k(i')))) = (z_1, z_2 + 1, z_3 + 1)$. Under these assumptions, if χ is a feasible coloring then $\chi(t_h(i)) \neq \chi(f_k(i'))$, and in particular one node will have WHITE color and the other one BLACK color. Combining this with properties (1),(3) and (5), the result follows.

Notice that such an interval constrained 3-coloring instance can clearly be constructed in polynomial time. Now we discuss the following claim in more details.

Claim 2. *There exists a truth assignment satisfying the 3-SAT instance if and only if there exists a feasible coloring χ for the interval constrained 3-coloring instance.*

First, suppose there exists a feasible coloring. We construct a truth assignment as follows. We set a variable x_j to *true* if $\chi(t_h(i)) = BLACK$, and to *false* otherwise, where $y_h(i)$ is any literal

referring to x_j . Note that, by Property (8), the resulting truth value does not depend on the literal we take. Still, combining Property (7) with properties (2),(4) and (6), we conclude that, for each clause, at least one literal will be *true*. By construction, we therefore end up with a truth assignment satisfying the 3-SAT instance. The result follows.

Now suppose that there is a truth assignment satisfying the 3-SAT instance. The basic idea, is to construct a coloring χ such that the following property holds for all literals:

Property 9. $\chi(t_h(i)) = \text{BLACK}$ (resp. *WHITE*) if and only if $y_h(i)$ refers to a *true*-variable (resp. *false*-variable).

Consider the sequence of nodes representing literal $y_1(i)$, and suppose $y_1(i) = x_j$ for some j . We color such nodes as in Fig. 3b-(1) if the literal is *true* in the truth assignment, and as in Fig. 3b-(3) otherwise. If $y_1(i) = \bar{x}_j$, switch BLACK and WHITE colors, in both previous cases. Now focus on the sequence of nodes representing literal $y_3(i)$. If $y_3(i) = \bar{x}_j$ for some j , we color such nodes as in Fig. 4b-(1) if the literal is *true*, and as in Fig. 4b-(3) otherwise. If $y_3(i) = x_j$, switch BLACK and WHITE colors, in both previous cases. Finally, consider the sequence of nodes representing literal $y_2(i)$. Suppose $y_2(i) = \bar{x}_j$. We color the 18 nodes in the middle of the sequence as in Fig. 7-(1) if $y_2(i)$ is *true*, as in Fig. 7-(2) if both $y_2(i)$ and $y_1(i)$ are *false*, and as in Fig. 7-(3) otherwise. Once again, if $y_2(i) = x_j$, we switch BLACK and WHITE colors, in all the previous three cases. Notice that, by construction, Property (9) holds, and all requirements for the intervals in $\mathcal{I}(y_h(i))$ ($i = 1, \dots, q$ and $h = 1, 2, 3$) are not violated.

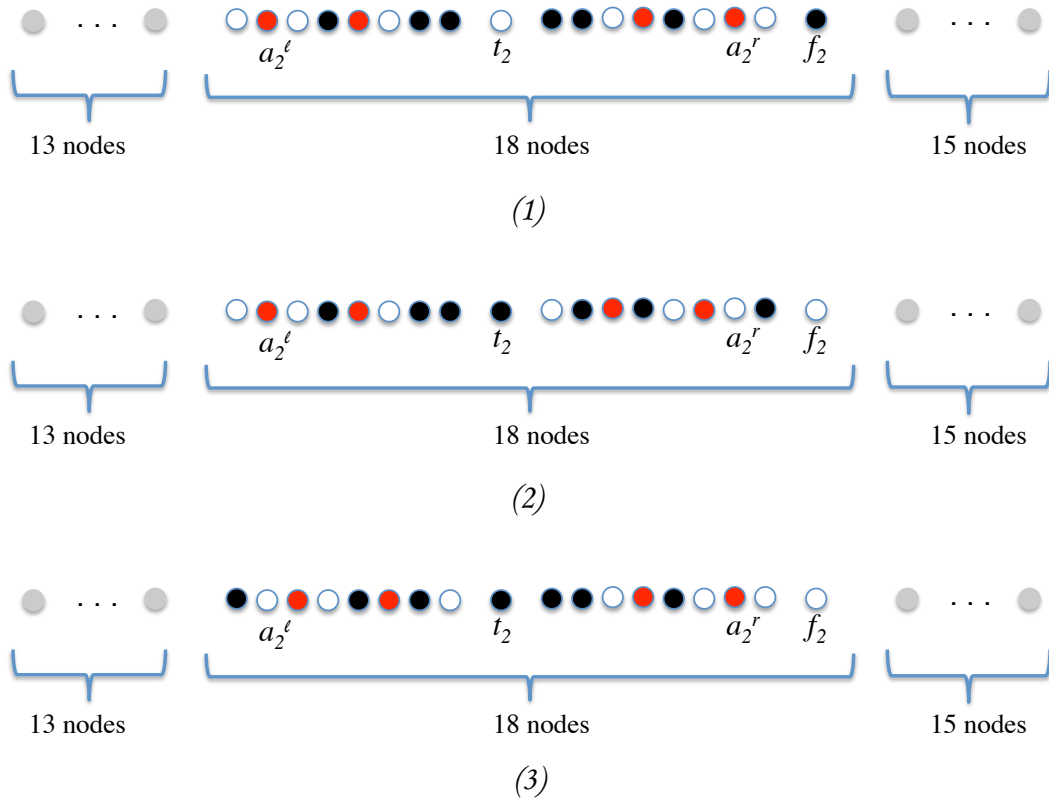


Figure 7: Coloring of nodes representing literal y_2

Now we show how to color the first 13 nodes (v_1, \dots, v_{13}) and the last 15 nodes (w_1, \dots, w_{15}) of the sequence representing literal $y_2(i)$, in such a way that the requirements of the intervals I_1, \dots, I_6 in $\mathcal{I}(C_i)$ are not violated ($i = 1, \dots, q$). Note that, by construction, at least one node among a_1 and a_2^ℓ is colored with RED. In fact, if $y_1(i)$ is *true* then $\chi(a_1) = \text{RED}$, while if $y_1(i) = \text{false}$ then a_2^ℓ is colored with RED. Similarly, at least one node among a_3 and a_2^r is colored with RED, since $\chi(a_2^r) \neq \text{RED}$ only if both literals $y_1(i)$ and $y_2(i)$ are *false*: then, necessarily $y_3(i)$ is *true*, and therefore $\chi(a_3) = \text{RED}$. Let us focus on the nodes v_1, \dots, v_{13} , and let u be the node in between v_{13} and a_2^ℓ . In the following, we refer to WHITE as the *opposite* color of BLACK and vice versa. As we already discuss, we can have only two cases:

Case 1: $\chi(a_1) = \chi(a_2^\ell) = \text{RED}$. We color v_1 with the opposite color of f_1 , and the nodes v_2 and v_3 with BLACK and WHITE. Note that $r(I_1)$ is not violated. We then color v_4, v_5, v_6 with the opposite color of v_1, v_2, v_3 respectively. Similarly, we color v_{13} with the opposite color of u . Then, we color v_{12} and v_{11} with BLACK and WHITE, so that $r(I_2)$ is not violated. Once again, we assign to v_{10}, v_9, v_8 the opposite color of v_{13}, v_{12}, v_{11} respectively. Finally, we let $\chi(v_7) = \text{RED}$. Note that $r(I_3)$ is not violated.

Case 2: $\chi(a_1) \neq \text{RED}$ and $\chi(a_2^\ell) = \text{RED}$, or vice versa. Suppose $\chi(a_1) \neq \text{RED}$ (the other case is similar). Both nodes a_1 and f_1 can have only BLACK or WHITE colors. Then, we can color v_1 and v_2 with the opposite color of a_1 and f_1 respectively, and v_3 with color RED, so that $r(I_1)$ is not violated. Still, we color v_4 and v_5 with the opposite color of v_1 and v_2 . Finally, we color v_6 and v_7 with BLACK and WHITE. To the remaining nodes v_8, \dots, v_{13} we assign the same colors as in Case 1. One checks that requirements of intervals I_2 and I_3 are not violated.

Finally, since Property (9) holds, it is easy to see that, for each couple of literals $y_h(i), y_k(i')$, the requirement $r(I(y_h(i), y_k(i')))$ is also not violated. The result then follows. \square

3 Gap hardness

We will now argue that not only the interval constrained 3-coloring problem but also its gap version is NP-hard, i.e. it is hard to distinguish between satisfiable instances and instances where only up to $1 - \epsilon$ fraction of the constraints may be simultaneously satisfied.

For the purpose of our argument we will use the following, rather restricted, definition of gap hardness. We will only talk about maximization versions of constraint satisfaction problems. Think of an instance of the problem as being equipped with an additional parameter t called threshold. We ask for a polynomial time algorithm which given the instance answers:

- “YES” if all the constraints can be satisfied,
- “NO” if there is no solution satisfying more than t constraints.

Note that for instances, where more than t but not all constraints can be simultaneously satisfied, any answer is acceptable. We will now restrict our attention to the case where the threshold is a fixed fraction of the total amount of constraints in the instance. We call problem A to be *gap NP-hard* if there exists a positive ϵ such that the existence of a polynomial time algorithm to separate feasible instances from those where only at most $(1 - \epsilon)$ fraction of the constraint can be simultaneously satisfied would imply $P = NP$.

Observe that gap NP-hardness implies APX-hardness, but not vice versa. For example the linear ordering problem (also known as max-subdag) is APX-hard [7], but is not gap NP-hard, since feasible instances may be found by topological sorting.

Let us first note that the 3-SAT problem, which we used in the reduction from the previous section, has the gap hardness property. It is the essence of the famous PCP theorems that problems with such gap hardness exist. For a proof of the gap hardness of 3-SAT see [8].

Before we show how to modify our reduction to prove gap hardness of the interval constraint coloring problem, we need to introduce the notion of *expander graphs*. For brevity we will only give the following extract from [8].

Definition 3. Let $G = (V, E)$ be a d -regular graph. Let $E(S, \bar{S}) = |(S \times \bar{S}) \cap E|$ equal the number of edges from a subset $S \subseteq V$ to its complement. The edge expansion of G is defined as

$$h(G) = \min_{S: |S| \leq |V|/2} \frac{E(S, \bar{S})}{|S|}.$$

Lemma 1. There exists $d_0 \in \mathbb{Z}$ and $h_0 > 0$, such that there is a polynomial-time constructible family $\{X_n\}_{n \in \mathbb{Z}}$ of d_0 -regular graphs X_n on n vertices with $h(X_n) \geq h_0$. (Such graphs are called *expanders*).

Let us now give a “gap preserving” reduction from gap 3-SAT to gap interval constrained 3-coloring. Consider the reduction from the previous section. Observe that the amount of intervals in each literal gadget, and therefore also in each clause gadget, is constant. The remaining intervals are the variable intervals. While it is sufficient for the NP-hardness proof to connect occurrences of the same variable in a “clique” fashion with variable intervals, it produces a potentially quadratic number of intervals. Alternatively, one could connect these occurrences in a “path” fashion, but it would give too little connectivity for the gap reduction. The path-like connection has the desired property of using only linear amount of intervals, since each occurrence of a variable is linked with at most two other ones. We aim at providing more connectivity while not increasing the amount of intervals too much. A perfect tool to achieve this goal is a family of expander graphs.

Consider the instance of the interval coloring problem obtained by the reduction from the previous section, but without any variable intervals yet. Consider literal gadgets corresponding to occurrences of a particular variable x . Think of these occurrences as of vertices of a graph G . Take an expander graph $X_{|V(G)|}$ and connect two occurrences of x if the corresponding vertices in the expander are connected. For each such connection use a pair of intervals. These intervals should be the original variable interval and an interval that is one element shorter on each of the sides. We will call this pair of intervals a variable link. Repeat this procedure for each of the variables.

Observe that the number of variable links that we added is linear since all the used expander graphs are d_0 regular. By contrast to the simple path-like connection, we now have the property, that different occurrences of the same variable have high edge connectivity. This can be turned into high penalty for inconsistent valuations of literals in an imperfect solution.

Theorem 4. *Constrained interval 3-coloring is gap NP-hard.*

Proof. We will argue that the above described reduction is a gap-preserving reduction from the gap 3-SAT problem to the gap interval 3-coloring problem. We need to prove that there exists a positive ϵ such that feasible instances are hard to separate from those less than $(1 - \epsilon)$ satisfiable.

Let ϵ_0 be the constant in the gap hardness of gap 3-SAT. We need to show two properties: that the “yes” instances of the gap 3-SAT problem are transferred to “YES” instances of our problem, and also that the “NO” instances are mapped into “NO” instances. There is no need to care about almost satisfiable instances of 3-SAT.

The first property is simple, already in the NP-hardness proof in the previous section it was shown that feasible instances are mapped by our reduction into feasible ones. To show the second property, we will take the reverse direction and argue that an almost feasible solution to the coloring instance can be transformed into an almost feasible solution to the SAT instance.

Suppose we are given a coloring χ that violates at most ϵ fraction of the constraints. Suppose the original 3-SAT instance has q clauses, then our interval coloring instance has at most $c \cdot q$ intervals for some constant c . The number of unsatisfied intervals in the coloring χ is then at most ϵqc .

We will say that a clause is *broken* if at least one of the intervals encoding it is not satisfied by χ . We will say that a variable link is broken if one of its intervals is not satisfied or one of the clauses it connects is broken. An unsatisfied variable link interval contributes a single broken link; an unsatisfied interval within a clause breaks at most $3d_0$ intervals connected to the clause. Therefore, there is at most $3d_0\epsilon qc$ broken variable links in total.

Recall that each variable link that is not broken connects occurrences of the same variable in two different not broken clauses. Moreover, by the construction of the variable link, these two occurrences display the same logical value of the variable.

Consider the truth assignment ϕ obtained as follows. For each variable consider its occurrences in the not broken clauses. Each occurrence associates a logical value to the variable. Take for this variable the value that is displayed in the bigger set of not broken clauses, break ties arbitrarily.

We will now argue, that ϕ satisfies a big fraction of clauses. Call a clause *bad* if it is not broken, but it contains a literal such that in the coloring χ this literal was active, but ϕ evaluates this literal to false. Observe that if a clause is neither broken nor bad, then it is satisfied by ϕ . It remains to bound the amount of bad clauses.

Consider the clauses that become bad from the choice of a value that ϕ assigns to a particular variable x . Let b_x be the number of such clauses. By the connectivity property of expanders, the amount of variable links connecting these occurrences of x with other occurrences is at least $h_0 b_x$. As we observed above, all these variable links are broken. Since there is in total at most $3d_0\epsilon qc$ broken links, we obtain that there is at most $\frac{3}{h_0}d_0\epsilon qc$ bad clauses. Hence, there is at most $(\frac{3}{h_0}d_0 + 1)\epsilon qc$ clauses that are either bad or broken and they cover all the clauses not satisfied by ϕ .

It remains to fix $\epsilon = \frac{h_0}{(3d_0+h_0)c}\epsilon_0$ to obtain the property, that more than ϵ_0 unsatisfiable instances of 3-SAT are mapped to more than ϵ unsatisfiable instances of the constrained interval 3-coloring problem. \square

Note that the above theorem implies APX-hardness of the studied problem.

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