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Analytical approximate solutions for conservative nonlinear oscillators by modified rational harmonic balance method

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An analytical approximate technique for conservative nonlinear oscillators is proposed. This method is a modification of the generalized harmonic balance method in which analytical approximate solutions have a rational form. This approach gives us not only a truly periodic solution but also the frequency of motion as a function of the amplitude of oscillation. Three truly nonlinear oscillators including the cubic Duffing oscillator, fractional-power restoring force and anti-symmetric quadratic nonlinear oscillators are presented to illustrate the usefulness and effectiveness of the proposed technique. We find that this method works very well for the cubic oscillator, and excellent agreement of the approximate frequencies with the exact one has been demonstrated and discussed. For the second-order approximation, we have shown that the relative error in the analytical approximate frequency is as low as 0.0046%. We also compared the Fourier series expansions of the analytical approximate solution and the exact one. This has allowed us to compare the coefficients for the different harmonic terms in these solutions. For the other two nonlinear oscillators considered, the relative errors in the analytical approximate frequencies are 0.098 and 0.066%, respectively. The most significant features of this method are its simplicity and its excellent accuracy for the whole range of oscillation amplitude values, and the results reveal that this technique is very effective and convenient for solving conservative truly nonlinear oscillatory systems.

Keywords: truly nonlinear oscillators; approximate solutions; generalized harmonic balance method

AMS Subject Classification:

Q1

1. Introduction

Nonlinear oscillator models have been widely used in many areas not only in physics and engineering, but also they are of significant importance in other areas. Physical and mechanical oscillatory systems are often governed by nonlinear differential equations. In many cases, it is possible to replace a nonlinear differential equation by a corresponding linear differential equation that approximates the original nonlinear equation closely to give useful results [34]. Often such linearization is not feasible and for this situation the original nonlinear differential equation itself must be directly dealt with. There are a large variety of approximate methods commonly used for solving nonlinear oscillatory systems. The most common and most widely studied of all approximation methods for nonlinear differential equations are perturbation methods [1,2,25,34,38,47]. Some of the other techniques include variational [18,20,28,30,41,44], decomposition [42], homotopy perturbation [5,6,8,11–13,15,19,24,26,39,45], homotopy analysis [31,51], harmonic balance [34],

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standard and modified Lindstedt–Poincaré [21–23,27,34,40,43], artificial parameter [27,43],
parameter expanding [29,49], equivalent linearization [7,16], linearized and quasilinearized harmonic balance [3,4,9,14,32,50] methods, etc. Surveys of the literature with numerous references
and useful bibliography and a review of these methods can be found in detail in [1,2,25,27,32,34].
These nonlinear equations can be also solved using an exponential fitting method proposed by
Vigo-Aguiar *et al.* [46–48].

The method of harmonic balance is a well-established procedure for determining analytical 57 58 approximations to the solutions of differential equations, the time domain response of which can 59 be expressed as a Fourier series. In the usual harmonic balance methods (HBM), the solution of a 60 nonlinear system is assumed to be of the form of a truncated Fourier series [34]. This method can 61 be applied to nonlinear oscillatory systems where the nonlinear terms are not small and no pertur-62 bation parameter is required. Being different from the other nonlinear analytical methods, such as perturbation techniques, the HBM does not depend on small parameters, such that it can find a 63 64 wide application in nonlinear problems without linearization or small perturbations. Various gen-65 eralizations of the HBM have been made and one of them is the rational representation proposed 66 by Mickens and coworkers [17, 33, 34, 36]. In this paper, a modified generalized, rational HBM is proposed for constructing approximate analytical solutions to conservative nonlinear oscillations 67 68 in which the nonlinear restoring-force f(x) is an odd function of x (*i.e.*, f(-x) = -f(-x)); 69 here x represents the displacement measured from the stable equilibrium position. In this method, 70 the approximate solution obtained approximates all of the harmonics in the exact solution [36], 71 whereas the usual harmonic balance techniques provide an approximation to only the lowest 72 harmonic components. For most cases, the application of the rational HBM leads to very com-73 plicated sets of algebraic equations with a very complex nonlinearity that have to be solved even 74 for the second-order approximation. In an attempt to provide a better solution methodology, a 75 modification in this technique is proposed for constructing the second-order analytical approx-76 imate solution to conservative nonlinear oscillators governed by differential equations with odd 77 nonlinearity. The most interesting features of the proposed method are its simplicity and its 78 excellent accuracy in a wide range of values of oscillation amplitude. We present three exam-79 ples to illustrate the applicability and the effectiveness of the proposed approximate analytical 80 solutions.

2. Formulation and solution method

Consider a single-degree-of-freedom, conservative nonlinear oscillator governed by the following dimensionless differential equation

$$\frac{t^2 x}{dt^2} + f(x) = 0 \tag{1}$$

subject to the initial conditions

$$x(0) = A, \quad \frac{\mathrm{d}x}{\mathrm{d}t}(0) = 0,$$
 (2)

97 where the nonlinear restoring-force function f(x) is odd, *i.e.* f(-x) = -f(-x), and satisfies 98 xf(x) > 0 for $x \in [-A, A], x \neq 0$. It is obvious that x = 0 is the equilibrium position. The system 99 oscillates between the symmetric bounds [-A, A]. The period and the corresponding solution are 100 dependent on the oscillation amplitude *A*.

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A new independent veriable $\tau = \alpha t$ is introduced. Then Equations (1) and (2) can be rewritten as

A new independent variable
$$t = \omega t$$
 is introduced. Then Equations (1) and (2) can be rewritten as

$$\omega^2 \frac{d^2 x}{d\tau^2} + f(x) = 0, \qquad (3)$$

$$x(0) = A, \quad \frac{dx}{d\tau}(0) = 0. \qquad (4)$$

108 The new independent variable is chosen in such a way that the solution of Equation (3) is a periodic 109 function of τ of period 2π . The corresponding frequency of the nonlinear oscillator is ω and both 110 periodic solution $x(\tau)$ and frequency ω depend on the initial amplitude A.

Following the lowest order harmonic balance approximation, we set

$$x_1(\tau) = A \cos \tau, \tag{5}$$

which satisfies the initial conditions in Equation (4). Substituting Equation (5) into Equation (3) and setting the coefficient of the resulting $\cos \tau$ to zero yield the first approximation to the frequency in terms of A

$$\omega_1(A) = \sqrt{\frac{c_1}{A}},\tag{6}$$

where

$$c_1 = \frac{4}{\pi} \int_0^{\pi/2} f(x_1(\tau)) \cos \tau \, \mathrm{d}\tau$$
(7)

is the first coefficient of the Fourier series expansion of function $f(x_1(\tau))$

$$f(x_1(\tau)) = \sum_{n=0}^{\infty} c_{2n+1} \cos[(2n+1)\tau],$$
(8)

where only the odd multiples of are presented because the nonlinear function f(x) is odd. Q2 In order to determine an improved approximation, we use a generalized, rational form given by the following expression [34,36]:

$$x_2(\tau) = \frac{A_1 \cos \tau}{1 + B_2 \cos 2\tau}.$$
 (9)

In this equation, A_1 , B_2 and ω are to be determined as functions of the initial conditions expressed in Equation (4) and $|B_1| < 1$. From Equation (4), we obtain $A_1 = (1 + B_2)A$, and Equation (9) can be rewritten as follows:

$$x_2(\tau) = \frac{(1+B_2)A\cos\tau}{1+B_2\cos 2\tau}.$$
 (10)

Substituting Equation (10) into Equation (3) leads to

$$\omega^2 h(\tau) + f(x_2(\tau)) = 0, \tag{11}$$

where

$$h(\tau) = \frac{d^2 x_2(\tau)}{\tau} = \frac{4AB_2(1+B_2)\cos\tau\cos2\tau}{A(1+B_2)\cos\tau} - \frac{A(1+B_2)\cos\tau}{A(1+B_2)\cos\tau}$$

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$$h(\tau) = \frac{1}{d\tau^2} = \frac{1}{(1+B_2\cos 2\tau)^2} - \frac{1}{1+B_2\cos 2\tau}$$

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$$\begin{array}{c}
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\end{array} - \frac{4AB_2(1+B_2)\sin\tau\sin2\tau}{(1+B_2\cos2\tau)^2} + \frac{8AB_2^2(1+B_2)\cos\tau\sin^22\tau}{(1+B_2\cos2\tau)^3}
\end{array} \tag{12}$$

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4 and $f(x_2(\tau)) = f\left(\frac{(1+B_2)A\cos\tau}{1+B_2\cos 2\tau}\right).$ (13)As $|B_2| < 1$, we can do the following Taylor series expansions $h(\tau) = \sum_{n=0}^{\infty} \alpha_n(\tau) B_2^n,$ (14) $f(x_2(\tau)) = \sum_{n=0}^{\infty} \beta_n(\tau) B_2^n.$ (15) Before applying the HBM to Equation (11), we consider the following approximation in Equations (14) and (15) $h(\tau) \approx h_2(\tau) = \alpha_0(\tau) + \alpha_1(\tau)B_2 + \alpha_0(\tau)B_2^2$ (16) $f(x_2(\tau)) \approx f_2(x_2(\tau)) = \beta_0(\tau) + \beta_1(\tau)B_2 + \beta_0(\tau)B_2^2,$ (17)where $\alpha_0(\tau) = -A\cos\tau,$ (18a) $\alpha_1(\tau) = A(9\cos 2\tau - 5)\cos \tau,$ (18b) $\alpha_2(\tau) = -\frac{1}{2}A(17 - 34\cos 2\tau + 25\cos 4\tau)\cos \tau,$ (18c) $\beta_0(\tau) = f(A\cos\tau),$ (19a) $\beta_1(\tau) = A\cos\tau(1-\cos 2\tau) f_x(A\cos\tau),$ (19b) $\beta_2(\tau) = -A\cos\tau\cos 2\tau (1-\cos 2\tau) f_x(A\cos\tau)$ $+\frac{1}{2}A^2\cos^2\tau(1-\cos 2\tau)^2f_{xx}(A\cos\tau),$ (19c)where the subscript x denotes the derivative of f(x) with respect to x. Substituting Equations (16) and (17) into Equation (11) gives $G_2(A, B_2, \omega, \tau) = \omega^2 h_2(A, B_2, \tau) + f_2(A, B_2, \tau) \approx 0.$ (20)Expanding $F_2(A, B_2, \tau)$ in a trigonometric series yields $G_2(A, B_2, \omega, \tau) = [\omega^2 H_{20}(A, B_2) + F_{20}(A, B_2)] \cos \tau$ + $[\omega^2 H_{21}(A, B_2) + F_{21}(A, B_2)] \cos 3\tau$ + HOH, (21)where HOH stands for higher-order harmonics, and $H_{20}(A, B_2) = \frac{4}{\pi} \int_0^{\pi/2} h_2(A, B_2, \tau) \cos \tau d\tau = -\frac{1}{2} (2 + B_2) A,$ (22)

$$H_{21}(A, B_2) = \frac{4}{\pi} \int_0^{\pi/2} h_2(A, B_2, \tau) \cos 3\tau d\tau = \frac{9}{4} (2 + B_2) A B_2, \tag{23}$$

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$$F_{20}(A, B_2) = \frac{4}{\pi} \int_0^{\pi/2} f_2(A, B_2, \tau) \cos \tau d\tau,$$
(24)

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$$F_{21}(A, B_2) = \frac{4}{\pi} \int_0^{\pi/2} f_2(A, B_2, \tau) \cos 3\tau d\tau.$$
(25)

201 Substituting Equations (22)–(25) into Equation (21) and setting the coefficients of $\cos \tau$ and $\cos 3\tau$ 202 to zeros, respectively, yield

$$-\frac{1}{2}(2+B_2)A\omega^2 + F_{20}(A, B_2) = 0,$$
(26)

$$\frac{9}{4}(2+B_2)AB_2\omega^2 + F_{21}(A,B_2) = 0.$$
(27)

Solving Equations (26) and (27), we can obtain B_2 and the second-order approximate frequency ω as a function of A. It should be clear how the procedure works for constructing the second-order analytical approximate solution. We will show in the following examples that this technique provides excellent analytical approximations to frequency and corresponding periodic solutions of conservative nonlinear oscillators.

3. Illustrative examples

In this section, we present three examples to illustrate the usefulness and effectiveness of the proposed technique.

Example 1 Truly nonlinear cubic Duffing oscillator. This oscillator is governed by the following differential equation with initial conditions

$$\frac{d^2 x(t)}{dt^2} + x^3(t) = 0, \quad x(0) = A, \quad \frac{dx}{dt}(0) = 0.$$
(28)

For the oscillator above, one has $f(x) = x^3$, $f_x(x) = 3x^2$ and $f_{xx}(x) = 6x$. Equation (28) corresponds to a mechanical oscillator for which the restoring force is proportional to the cube of the displacement. As we can see, the linear term, x, is omitted in the equation and for all values of x, the motion is always nonlinear. One example of this nonlinear oscillator is the motion of a **Q3** ball-bearing oscillating in a glass tube that is bent into a curve [27] is another example, as well as the motion of a mass attached to two identical stretched elastic wires for small amplitudes when the length of each wire without tension is the same as half the distance between the ends of the wires [4].

From Equations (5)–(7), we obtain the first analytical approximate formula for the frequency as

$$\omega_1(A) = \frac{\sqrt{3}}{2} A \approx 0.866025 A.$$
⁽²⁹⁾

From Equations (19), (24) and (25), we obtain

$$F_{20}(A, B_2) = \frac{3}{8}(2 + 2B_2 + B_2^2)A^3, \tag{30}$$

$$F_{21}(A, B_2) = -\frac{1}{8}(2 - 3B_2 - 6B_2^2)A^3.$$
(31)

Substituting Equations (30) and (31) into Equations (26) and (27) and solving for B_2 and ω yield the second analytical expression for the frequency as

$$B_2 = \frac{1}{27} \left[-14 - \frac{118(4)^{1/3}}{\left(2435 + 27\sqrt{12641}\right)^{1/3}} + \left(4870 + 54\sqrt{12641}\right)^{1/3} \right]^{1/3} \approx -0.0900126,$$
(32)

$$\omega_2(A) = A \sqrt{\frac{3(2+2B_2+B_2^2)}{4(2+B_2)}} \approx 0.84725206A.$$
(33)

Therefore, the second approximation to the periodic solution of the nonlinear oscillator is given by the following equation:

$$\frac{x_2(t)}{A} = \frac{0.9099874\cos(0.84725206At)}{1 - 0.0900126\cos(1.69450412At)}.$$
(34)

This periodic solution has the following Fourier series expansion:

$$\frac{x_2(t)}{A} = \sum_{n=0}^{\infty} a_{2n+1} \cos[(2n+1)\omega_2 t],$$
(35)

where

$$a_{2n+1} = \frac{4}{\pi} \int_0^{\pi/2} \frac{0.9099874\cos\tau}{1 - 0.0900126\cos 2\tau} \cos[(2n+1)\tau] d\tau.$$
(36)

As we can see, Equation (34) gives an expression that approximates all of the harmonics in the exact solution, whereas the usual harmonic balancing techniques provide an approximation to only the lowest harmonic components.

We illustrate the accuracy of the modified approach by comparing the approximate solutions previously obtained with the exact frequency ω_{ex} and other results in the literature. In particular, we will consider the solution of Equation (28) by means of the homotopy perturbation method (HPM) [6], the standard HBM [34] and a linearized HBM [50]. The last method incorporates salient features of both Newton's method and the HBM.

Direct integration of Equation (1) yields the exact frequency as [6]

$$\omega_{\rm ex}(A) = \frac{\pi A}{2K(1/2)} = 0.847213085A,\tag{37}$$

where K(m) is the complete elliptical integral of the first kind [37]. The exact solution to Equation (28) is [6]

$$\frac{x_{\rm ex}(t)}{A} = \operatorname{cn}\left(At; \frac{1}{2}\right) \tag{38}$$

where cn is the Jacobi elliptic function which has the following Fourier expansion [6,34]:

$$\operatorname{cn}(u;m) = \frac{2\pi}{\sqrt{m} K(m)} \sum_{n=0}^{\infty} \frac{q^{n+1/2}}{1+q^{2n+1}} \cos\left[\frac{(2n+1)\pi u}{2K(m)}\right],\tag{39}$$

298 where

$$q(m) = \exp\left[-\frac{\pi K(m')}{K(m)}\right],\tag{40}$$

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$$m' = 1 - m$$
. With these results, the Fourier expansion of Equation (40) becomes
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304 $\frac{x_{ex}(t)}{A} = cn\left(At; \frac{1}{2}\right) = \frac{2\pi\sqrt{2}}{K(1/2)} \sum_{n=0}^{\infty} \left(\frac{exp[(n+1/2)\pi]}{1 + exp[(2n+1)\pi]}\right) cos[(2n+1)\omega_{ex}t]$
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306 $= 0.95501 cos \,\omega_{ex}t + 0.043050 cos \, 3\omega_{ex}t + 0.0018605 cos \, 5\omega_{ex}t$
 $+ 0.0000804 cos \, 7\omega_{ex}t + \cdot$. (41)

By applying the first and the second approximation based on the HBM, Mickens [34] achieved the following expressions for the frequency:

$$\omega_{M1}(A) = \frac{\sqrt{3}}{2}A = 0.86602540A$$
, Relative error = 2.2%, (42)

$$\omega_{M2}(A) = 0.8507A$$
, Relative error = 0.41%, (43)

and for the second-order approximate solution, he obtained

$$x_{M2}(t) = 0.9569A\cos\omega_{M2}t + 0.0431A\cos3\omega_{M2}t.$$
(44)

Wu et al. [50] approximately solved Equation (28) using an improved harmonic balance method (LHBM), which incorporates salient features of both Newton's method and the HBM. They achieved the following results for the first, second and third approximation orders

$$\omega_{\text{WSL1}}(A) = \frac{\sqrt{3}}{2}A = 0.86602540A, \quad \text{Relative error} = 2.2\%,$$
 (45)

$$\omega_{\text{WSL2}}(A) = \sqrt{\frac{23}{32}}A = 0.84779125A, \text{ Relative error} = 0.068\%,$$
 (46)

$$\omega_{\rm WSL3}(A) = \sqrt{\frac{65856986475}{91739270448}} A = 0.84727284A, \quad \text{Relative error} = 0.0070\%, \tag{47}$$

and for the second-order approximate solution, they obtained

$$\frac{x_{\text{WSL2}}(t)}{A} = \frac{23}{24} \cos \omega_{\text{WSL2}} t + \frac{1}{24} \cos 3\omega_{\text{WSL2}} t$$
$$= 0.958333 \cos \omega_{\text{WSL2}} t + 0.041667 \cos 3\omega_{\text{WSL2}} t.$$
(48)

Beléndez et al. [6] approximately solved Equation (28) using He's HPM. They achieved the following results for the first, second and third approximation orders:

$$\omega_{B1}(A) = \frac{\sqrt{3}}{2}A = 0.86602540A, \quad \text{Relative error} = 2.2\%,$$
 (49)

$$\omega_{B2}(A) = \frac{1}{4}\sqrt{6 + \sqrt{30}}A = 0.84695136A, \text{ Relative error} = 0.031\%,$$
 (50)

$$\omega_{B3}(A) = \frac{1}{4}\sqrt{6 + \sqrt{30}}A = 0.84695136A$$
, Relative error = 0.031%. (51)

The approximate solution they obtained for the second approximation was

$$\frac{x_{B2}(t)}{A} = 0.954538 \cos \omega_{B2}t + 0.043564 \cos 3\omega_{B2}t + 0.0018979 \cos 5\omega_{B2}t.$$
(52)

The frequency values and their relative errors obtained in this paper applying a modified generalized harmonic balance method (GHBM) are the following:

$$\omega_1(A) = \frac{\sqrt{3}}{2}A = 0.86602540A$$
, Relative error = 2.2%, (53)

$$\omega_2(A) = 0.84725206A$$
, Relative error $= 0.0046\%$. (54)

From Equations (35) and (36), the Fourier series expansion for the second-order approximate solution obtained in this paper is

$$\frac{x_2(t)}{A} = 0.954902 \cos \omega_2 t + 0.043064 \cos 3\omega_2 t + 0.00194209 \cos 5\omega_2 t + 0.0000875842 \cos 7\omega_2 t + \dots$$
(55)

364 which has an infinite number of harmonics.

Q4 365 In Table 1, we present, for the second-order approximation, the comparison between the approximate and exact frequencies and the first four coefficients of the Fourier series expansions of the 366 exact solution and the second-order the analytical approximate solution using different methods. 367 Note that for HBM, LHBM and HPM, the number of Fourier coefficients is finite. It is clear 368 that the second-order approximate frequency obtained in this paper is better not only than the 369 second-order approximate frequency obtained using other approximate techniques but also than 370 the third-order approximate frequency obtained using these methods. The normalized periodic 371 exact solution, x_{ex}/A , achieved using Equation (38) and the proposed second-order approximate 372 solution, x_2/A (Equation (34)), are plotted in Figure 1, whereas in Figure 2, we plotted the 373 difference $(x_{ex} - x_2)/A$. In these figures, h is defined as follows: 374

$$h = \frac{t}{T_{\rm ex}}.$$
(56)

As we can see, $x_2(t)/A$ coincides with the exact solution x_{ex}/A . Figures 1 and 2 show that Equations (33) and (34) can provide high accurate approximations to the exact frequency and the exact periodic solution. These results are an indication of the accuracy of the proposed modified GHBM as applied to this particular problem, and show that it provides an excellent approximation to the solution of Equation (28).

Example 2 Oscillator with fractional-power restoring force. This oscillator is governed by the following differential equation with initial conditions

$$\frac{\mathrm{d}^2 x(t)}{\mathrm{d}t^2} + x^{1/3}(t) = 0, \quad x(0) = A, \quad \frac{\mathrm{d}x}{\mathrm{d}t}(0) = 0.$$
(57)

For this problem, we have $f(x) = x^{1/3}$, $f_x(x) = (1/3)x^{-2/3}$ and $f_{xx}(x) = -(2/9)x^{-5/3}$. This system was introduced as a model 'truly nonlinear oscillator' by Mickens [35].

Table 1. Comparison of the exact and approximate frequencies and the first four coefficients for the Fourier expansions of the exact and the second-order approximate solutions obtained using different methods.

	Exact solution	GHBM (this paper)	HBM [34] [†]	LHBM [50] [‡]	HPM [6]§
ω/A (% error)	0.847213	0.847252 (0.0046%)	0.8507 (0.41%)	0.846779 (0.068%)	0.846951 (0.031%)
$a_1(\% \text{ error})$	0.955010	0.954902 (0.011%)	0.9569 (0.20%)	0.958333 (0.35%)	0.954538 (0.049%)
$a_3(\% \text{ error})$	0.043050	0.043064 (0.033%)	0.0431 (0.12%)	0.041667 (3.2%)	0.043564 (1.2%)
$a_5(\% \text{ error})$	0.0018605	0.00194209 (4.4%)	0	0	0.0018979 (2.0%)
$a_7(\% \text{ error})$	0.0000804	0.00008758 (8.9%)	0	0	0

[†] $a_{2n+1} = 0 \ (n \ge 2)$. [‡] $a_{2n+1} = 0 \ (n \ge 2)$. $a_{2n+1} = 0 \ (n \ge 3)$.

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451 Substituting Equations (59) and (60) into Equations (26) and (27) and solving for B_2 and ω yield 452 the second analytical expression for the frequency as

$$B_2 \approx 0.0466088,$$
 (61)

$$\omega_2(A) = \sqrt{\frac{3(20+4B_2-B_2^2)\Gamma(7/6)}{10A^{2/3}(2+B_2)\Gamma(2/3)}} \approx \frac{1.0694051}{A^{1/3}}.$$
(62)

Therefore, the second approximation to the periodic solution of the nonlinear oscillator is given by the following equation:

$$\frac{x_2(t)}{A} = \frac{1.0466088\cos(1.0694051A^{-1/3}t)}{1+0.0466088\cos(2.1388102A^{-1/3}t)}.$$
(63)

464 Direct integration of Equation (57) yields the exact frequency as [12]

$$\omega_{\rm ex}(A) = \frac{2\sqrt{\pi}\Gamma(5/4)}{\sqrt{6}\Gamma(3/4)A^{1/3}} \approx \frac{1.0704505}{A^{1/3}}.$$
(64)

By applying the first and the second approximation based on the HBM, Mickens [35] achieved the following expressions for the frequency

$$\omega_{M1}(A) = \frac{1.04912}{A^{1/3}}, \quad \text{Relative error} = 2.0\%,$$
 (65)

$$\omega_{M2}(A) = \frac{1.06341}{A^{1/3}}, \quad \text{Relative error} = 0.70\%.$$
 (66)

Wu *et al.* [50] approximately solved Equation (57) using an LHBM. They achieved the following results for the first and second approximation orders

$$\omega_{\text{WSL1}}(A) = \frac{1.07685}{A^{1/3}}, \quad \text{Relative error} = 0.60\%,$$
(67)

$$\omega_{\text{WSL2}}(A) = \frac{1.06922}{A^{1/3}}, \quad \text{Relative error} = 0.12\%.$$
 (68)

Beléndez *et al.* [12] approximately solved Equation (57) using a modified He's homotopy perturbation method (MHPM). They achieved the following results for the first and second approximation orders:

$$\omega_{B1}(A) = \frac{1.07685}{A^{1/3}}, \quad \text{Relative error} = 0.60\%$$
 (69)

$$\omega_{B2}(A) = \frac{1.06861}{A^{1/3}}, \quad \text{Relative error} = 0.17\%.$$
 (70)

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493 The frequency values and their relative errors obtained in this paper applying a modified GHBM are the following:

$$\omega_1(A) = \frac{1.07685}{A^{1/3}}, \quad \text{Relative error} = 0.60\%,$$
 (71)

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$$\omega_2(A) = \frac{1.06941}{A^{1/3}}, \quad \text{Relative error} = 0.098\%.$$
 (72)

It is clear that the second-order approximate frequency obtained in this paper is better than that obtained using other approximate techniques. The comparison of the (numerical) exact normalized



Figure 3. Comparison of normalized second-order approximate solution (circles) with the exact solution (continuous line) in Example 2.

periodic solution, x_{ex}/A , obtained by numerically integrating Equation (57) and the proposed second-order approximate solution, x_2/A (Equation (63)), is shown in Figure 3. This figure shows that the second approximation obtained in this paper is excellent as compared with the exact periodic solution.

Example 3 Anti-symmetric quadratic nonlinear oscillator. The anti-symmetric quadratic nonlinear oscillator is governed by the following differential equation with initial conditions

$$\frac{d^2 x(t)}{dt^2} + |x(t)|x(t) = 0, \quad x(0) = A, \quad \frac{dx}{dt}(0) = 0,$$
(73)

which is an example of a nonsmooth oscillator for which f(x) is a nonlinear, nonsmooth function of x. For this problem, we have f(x) = |x|x, $f_x(x) = 2|x|$ and $f_{xx}(x) = 2 \operatorname{sgn}(x)$, where

$$\operatorname{sgn}(x) = \begin{cases} -1, & x < 0, \\ +1, & x > 0. \end{cases}$$
(74)

From Equations (5)–(7), we can easily find that the first-order approximate frequency for this oscillator is

$$\omega_1(A) = \sqrt{\frac{8A}{2\pi}} = 0.921318\sqrt{A}.$$
(75)

Applying Equations (19), (24) and (25) to this oscillator, we obtain

$$F_{20}(A, B_2) = \frac{8}{105\pi} (35 + 28B_2 + 8B_2^2)A^2, \tag{76}$$

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$$F_{21}(A, B_2) = \frac{8}{105\pi} (7 - 20B_2 - 24B_2^2)A^2.$$
(77)

Substituting Equations (76) and (77) into Equations (26) and (27) and solving for B_2 and ω yield the second analytical expression for the frequency as

 $B_{2} = -\frac{17}{18} + \frac{\left(20155 + 9\sqrt{5387191}\right)^{1/3}}{4^{1/3}18} - \frac{247}{18\left(40310 + 18\sqrt{5387191}\right)^{1/3}} \approx -0.0529501,$ (78)

$$\omega_2(A) = \sqrt{\frac{16(35 + 28B_2 + 8B_2^2)A}{105\pi(2 + B_2)}} \approx 0.9140759\sqrt{A}.$$
(79)

Therefore, the second approximation to the periodic solution of the nonlinear oscillator is given by the following equation:

$$\frac{x_2(t)}{A} = \frac{0.9470499\cos(0.9140759\sqrt{A}t)}{1 - 0.0529501\cos(1.828152\sqrt{A}t)}.$$
(80)

Direct integration of Equation (73) yields the exact frequency as [10]

$$\omega_{\rm ex}(A) = \sqrt{\frac{3\pi}{2}} \frac{\Gamma(5/6)}{\Gamma(1/3)} \sqrt{A} = 0.914681 \sqrt{A}.$$
(81)

By applying the first approximation based on the HBM and a second-order rational HBM, Mickens [10,34] achieved the following expressions for the frequency:

$$\omega_{M1}(A) = \sqrt{\frac{8A}{2\pi}} = 0.921318\sqrt{A}, \quad \text{Relative error} = 0.73\%,$$
(82)

$$\omega_{M2}(A) = 0.914044\sqrt{A}$$
, Relative error = 0.070%. (83)

Beléndez *et al.* [10] approximately solved Equation (73) using an MHPM. They achieved the following results for the first and second approximation orders:

$$\omega_{B1}(A) = \sqrt{\frac{8A}{2\pi}} = 0.921318\sqrt{A}, \quad \text{Relative error} = 0.73\%,$$
 (84)

$$\omega_{B2}(A) = 0.914274\sqrt{A}, \quad \text{Relative error} = 0.045\%.$$
 (85)

The frequency values and their relative errors obtained in this paper applying a modified GHBM are the following:

$$\omega_1(A) = \sqrt{\frac{8A}{2\pi}} = 0.921318\sqrt{A}, \quad \text{Relative error} = 0.73\%,$$
 (86)

$$\omega_2(A) = 0.914076\sqrt{A}$$
, Relative error = 0.066%. (87)

599 For this nonlinear oscillator, the second-order approximate frequency obtained using the HPM 600 is a little better than that obtained using the rational HBM.



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Figure 4. Comparison of normalized second-order approximate solution (circles) with the exact solution (continuous line) in Example 3.

The comparison of the (numerical) exact normalized periodic solution, x_{ex}/A , obtained by numerically integrating Equation (73) and the proposed second-order approximate solution, x_2/A , computed by Equation (80) is shown in Figure 4. This figure show that the second approximation obtained in this paper is excellent as compared with the exact periodic solution.

4. Conclusions

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626 A modified generalized, rational HBM has been applied to obtain analytical approximate solu-627 tions for nonlinear problems that are conservative and periodic. The major conclusion is that 628 this scheme provides excellent approximations to the solution of these nonlinear systems with 629 high accuracy. Three examples have been presented to illustrate the excellent accuracy of the 630 analytical approximate frequencies. The analytical representations obtained using this technique give excellent approximations to the exact solutions for the whole range of values of oscillation 632 amplitudes. For the cubic oscillator, these approximate solutions are better than that obtained 633 using other approximate methods presented in the literature. For the second-order approximation, 634 the relative error of the analytical approximate frequency obtained using the approach considered 635 in this paper for the cubic oscillator is 0.0046%. An interesting feature considered in this paper is 636 the comparison between the analytical approximate solutions and the Fourier series expansion of the exact solution. This has allowed us to compare the coefficients for the different harmonics. In 638 summary, this modified GHBM is very simple in its principle, and it can be used to solve other 639 conservative truly nonlinear oscillators with complex nonlinearities.

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