Effect of field spread on resting-state MEG functional network 1 analysis: a computational modeling study 2 Silva Pereira¹, S., Hindriks¹, R., Mühlberg¹, S., Maris², E., van Ede², F., 3 Griffa^{3,4}, A., Hagmann^{3,4}, P., Deco^{1,5}, G. May 20, 2017 4 1. Center for Brain and Cognition, Computational Neuroscience Group, Department of Information 5 and Communication Technologies, Universitat Pompeu Fabra, Barcelona, Spain. 6 2. Radboud University Nijmegen, Nijmegen, The Netherlands. 8 9 3. Department of Radiology, Lausanne University Hospital and University of Lausanne, 1011 Lau-10 sanne, Switzerland. 11 12 4. Signal Processing Laboratory 5, Ecole Polytechnique Federale de Lausanne, 1015 Lausanne, Switzer-13 land. 14 15 5. Instituciò Catalana de la Recerca i Estudis Avanats (ICREA), Universitat Pompeu Fabra, Barcelona, 16

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Abstract

A popular way to analyze resting-state EEG and MEG data is to treat them as a functional network 19 in which sensors are identified with nodes and the interaction between channel time-series with the 20 network connections. Although conceptually appealing, the network-theoretical approach to sensor-21 level EEG and MEG data is challenged by the fact that EEG and MEG time-series are mixtures of 22 source activity. It is therefore of interest to assess the relationship between functional networks of 23 source activity and the ensuing sensor-level networks. Since these topological features are of high 24 interest in experimental studies, we address the question of to what extent the network topology can 25 be reconstructed from sensor-level FC measures in case of MEG data. Simple simulations that consider 26 only a small number of regions do not allow to assess network properties; therefore, we use a diffusion 27 MRI-constrained whole-brain computational model of resting-state activity. Our motivation lies behind 28 the fact that still many contributions found in the literature perform network analysis at sensor level, 29 and we aim at showing the discrepancies between source- and sensor-level network topologies using 30 realistic simulations of resting-state cortical activity. Our main findings are that the effect of field 31 spread on network topology depends on the type of interaction (instantaneous or lagged) and leads 32 to an underestimation of lagged FC at sensor level due to instantaneous mixing of cortical signals, 33 instantaneous interaction is more sensitive to field spread than lagged interaction, and discrepancies 34 are reduced when using planar gradiometers rather than axial gradiometers. We therefore recommend 35 to use lagged interaction measures on planar gradiometer data when investigating network properties 36 of resting-state sensor-level MEG data. 37

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38 1 Introduction

Electroencephalography (EEG) and magnetoencephalography (MEG) allow for non-invasive monitor-39 ing of electrical activity in the human brain at a time-scale of milliseconds [21]. EEG and MEG have 40 been used extensively to characterize functional connectivity (FC) underlying healthy and impaired 41 cognitive processes, and promoted the development of methods for characterizing FC in electrophysi-42 ological recordings (EEG/MEG). Today, one can choose from a wide variety of FC measures based on 43 different mathematical theories, such as chaotic systems, weakly-coupled oscillators, linear stochastic 44 processes, and information theory [36, 40, 44]. In applications to EEG and MEG data, it is common 45 practice to calculate the FC measure for all channel-pairs, resulting in an FC matrix with the corre-46 sponding one-to-one relationships. The obtained FC matrices of different subjects are subsequently 47 analyzed and can be used to characterize different cognitive states or pathological conditions. In this 48 study, we focus on the fundamental question of what it is that sensor-level FC matrices say about the 49 dynamical structure of the data, and to what extent the network topology can be reconstructed from 50 sensor-level FC measures in case of MEG data. To that end, we compare sensor-level FC matrices 51 with the underlying cortical FC matrices. 52

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The most common way to think about EEG/MEG FC matrices is in terms of functional networks 54 [8,23,39]. Viewed as such, network nodes are assumed to correspond to cortical circuits underlying the 55 EEG/MEG channels and network connections are assumed to correspond to functional dependencies 56 between these circuits. Analysis of the network is typically carried out using graph-theoretic measures 57 such as the clustering coefficient, degree distribution, and average path length. The network approach 58 to EEG/MEG brain dynamics has demonstrated that resting-state functional networks at sensor level 59 posses small-world properties in several frequency bands [1, 46], which would enable fast and robust 60 integration and segregation of information [2]. Moreover, graph-theoretic measures are able to dis-61 criminate between the ongoing brain dynamics of healthy individuals and those of psychiatric and 62 neurological patients [29, 30, 37, 38]. 63

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Although these results are encouraging and clinically relevant, by themselves they do not validate 65 the network-theoretic view on sensor-level EEG/MEG brain dynamics. In addition, the network ap-66 proach to EEG/MEG brain dynamics is questionable from a physical perspective. Concerning the 67 physics, because EEG/MEG channels register source activity not only from tissue directly underly-68 ing the channels but from distant sources as well, they cannot directly be associated with nodes of 69 a functional network and the FC measures suffer from spurious correlations due to the superposition 70 of sources [22]. Moreover, scalp-based EEG connectivity estimates like vector autoregressive models 71 have been shown to be highly affected by volume conduction [7]. To isolate true FC from spurious 72 FC due to volume-conduction (EEG) or field spread (MEG), several approaches have been proposed. 73 Since volume-conduction/field spread is instantaneous, an alternative is to focus on time-lagged inter-74 actions between EEG/MEG channels [26, 32, 33, 47], which necessarily reflect time-lagged interactions 75 between sources. However, although these FC measures reduce spurious correlations and might lead to 76 more faithful networks [5, 19, 45], it remains unclear weather such measures actually reflect functional 77 interaction between local circuits. Another alternative is to perform a source space projection prior 78 to calculation. Source reconstruction techniques like beamforming have become standard for source 79 space projection of EEG/MEG sensor data, and recent studies have proposed methods to mitigate the 80 effects of volume-conduction/field spread [10, 18, 41, 49]. Although these techniques have been shown 81 to ease the effects of field spread, still several contributions continue applying network theory to sensor 82 level data, and in this study we highlight the consequences of carrying out such an analysis. 83 84

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Motivated by the existence of several fundamental methodological difficulties [22], we use models based on empirical data to uncover a discrepancy between cortical FC matrices and those computed

at channel level. Whereas the authors in [22] focused on a single minimalistic scenario, the authors

in [10] studied the performance of a novel connectivity measure on both simulated and real data at 89 source-level using simple networks composed of only a few nodes (five), without performing realistic 90 simulations of resting-state cortical activity and without reporting results on sensor-level connectivity 91 studies. The extended analysis we perform on simulated data can be contrasted with those based on a 92 network view on EEG/MEG brain dynamics, e.g. [6,15,16,29,45,46]. To this extent, we focus on both 93 real and complex-valued correlation measurements (or coherence), and argue that treating sensor-level 94 resting-state EEG/MEG recordings as comprising a discrete network of interacting systems might not 95 be appropriate and obscures rather than clarifies the true brain dynamics, since after all, the recorded 96 electric and magnetic fields are continuous in space [42]. To demonstrate this, we use a diffusion MRI-97 constrained whole-brain computational model of resting-state activity, where the activity at different 98 areas of the brain emerges through long-range synchronization of Hopf oscillators. We stress that in 99 contrast to existing simulation studies on sensor-level FC which typically use simple network models, 100 we perform realistic simulations based on empirical data. The measured MEG signals are obtained 101 from a forward model assuming two different systems: sensors with axial gradiometers and sensors 102 with planar gradiometers, the latter obtained synthetically using the Fieldtrip toolbox [35]. Then, 103 we perform a network analysis at both source level and sensor level, and contrast the results showing 104 that they can lead to wrong interpretations. A Louvain modularity study is included, which sheds 105 additional light on the results from the standard network analyses performed. 106

¹⁰⁷ 2 Materials and Methods

¹⁰⁸ 2.1 Cortical parcellation and white-matter tractography

For the estimation of the whole-brain structural connectivity matrix S, we considered ten male healthy 109 subjects aged 22.5 ± 1.8 years, nine right-handed and one left-handed. Each subject underwent a 110 magnetic resonance imaging (MRI) session on a 3 Tesla scanner (Magnetom TrioTim, Siemens Medical 111 Solutions), equipped with a 32-channel head coil. Each MRI session included a magnetization-prepared 112 rapid acquisition gradient echo (MPRAGE) and a diffusion spectrum imaging (DSI [52]) sequence. 113 The MPRAGE acquisition had 1 mm in-plane resolution and 1.2 mm slice thickness, covering $240 \times$ 114 257×160 voxels. The TR, TE and TI were 2300, 2.98 and 900 ms. The DSI acquisition had $2.2 \times$ 115 2.2×3 mm resolution, covering $96 \times 96 \times 34$ voxels, and it included 256 diffusion-weighted volumes 116 (with maximum b-value 8000 s/mm²) and one b0 volume. The TR and TE were 6100 and 144 ms. 117 Informed written consent in accordance with institutional guidelines was obtained for all participants. 118 Subject-wise MPRAGE volumes were segmented into white-matter, grey-matter and cerebrospinal-119 fluid compartments using FreeSurfer software [12], and linearly registered to the diffusion space (b0 120 volume) [20]. The grey-matter cortical volumes were segmented into 219 regions of interest (ROIs), 121 according to the atlas described in [9] and using the Connectome Mapper Toolkit [11]. DSI data 122 were reconstructed according to [52]. Deterministic streamline tractography [27] was performed on 123 reconstructed DSI data, initiating 32 streamline propagations per voxel and per diffusion direction. A 124 representative structural connectivity matrix S was estimated by combining tractography and cortical 125 parcellation results from the ten subjects. 126

¹²⁷ 2.2 Computational model of resting-state cortical dynamics

Recently, it has been reported that the dynamics of resting-state cortical fluctuations is poised at the transition between asynchronous to oscillatory behavior [14]. We use the model proposed in [14] to simulate resting-state cortical activity, where a general neural mass model based on the normal form of a Hopf bifurcation was proposed. The model describes the dynamics of n coupled brain areas (nodes). The global dynamics emerges through the mutual interactions between the nodes, which are coupled through a connectivity matrix S. The local dynamics are modeled by the normal form of a supercritical Hopf bifurcation, which describes the transition from asynchronous noisy behavior to self-sustained oscillations, as controlled by the bifurcation parameter, denoted a. The complexvalued cortical activity at every node j is modeled by the following set of coupled non-linear stochastic differential equations:

$$\frac{d}{dt}z_j(t) = (a+i\,\omega_0)z_j(t) - z_j(t)|z_j(t)|^2 + g\sum_{k=1}^n S_{j,k}\left(z_k(t-t_{j,k}) - z_j(t)\right) + \eta_j(t),\tag{1}$$

where *i* is the imaginary unit, ω_0 is the intrinsic frequency, η_j is additive Gaussian white noise with intensity σ_j , and $t_{j,k}$ denotes the axonal delay between node *j* and node *k*. The parameter *g* globally scales the synaptic connections and is used to control the correlation between regions. When the nodes are uncoupled (i.e., g = 0), the local dynamics bifurcate when *a* crosses zero. Specifically, for a < 0, the local dynamics have a stable fixed point at $z_j = 0$, which corresponds to a low-activity asynchronous state due to the additive noise. For a > 0, there exists a stable limit-cycle with angular frequency ω_0 . The effect of the bifurcation parameter value *a* on the local dynamics is illustrated in Fig. 1.

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The complex-valued variable z_j can be decomposed into a real part x_j and imaginary part y_j as $z_j = x_j + iy_j$. In terms of x_j and y_j , Eq. (1) takes the form

$$\frac{d}{dt}x_j = ax_j - \omega_0 y_j - x_j (x_j^2 + y_j^2) + g \sum_{k=1}^n S_c(j,k)(x_k - x_j) + \eta_j,$$
(2)

$$\frac{d}{dt}y_j = ay_j - \omega_0 x_j - y_j (x_j^2 + y_j^2) + g \sum_{k=1}^n S_c(j,k)(y_k - y_j) + \eta_j,$$
(3)

where we have suppressed the time-dependence of x and y. Cortical activity at node j is thus modeled by the real-valued variable x_j .

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To simulate realistic cortical resting-state activity, the nodes of the computational model are taken to be the ROIs in the surface-based cortical atlas described in Sec. 2.1, and the connectivity matrix is taken to be the group-averaged structural connectivity matrix obtained from diffusion MRI tractography. To obtained activity in each vertex of the cortical mesh, the activity for each ROI is copied to all vertices within that ROI. This effectively means that we assume cortical activity to be locally synchronous over several squared centimeters, which is consistent with empirical estimates of the spatial extent of cortical activity underlying resting-state EEG and MEG recordings [21, 24, 34].

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From the simulated cortical activity, MEG sensor data was computed by constructing a leadfield 159 matrix for the 275-channel MEG gradiometer system (CTF Systems Inc., Port Coquitlam, Canada) 160 using a single-sphere head model in the Fieldtrip toolbox [35]. The source space was restricted to the 161 vertices of the left and right Freesurfer cortical template meshes, which were manually positioned inside 162 the MEG helmet. The single-sphere had a radius of 10 cm and was manually positioned to enclose the 163 source space. Dipoles were assumed to be oriented perpendicular to the local cortical surface. This 164 yielded leadfield matrices of dimensions 273×130385 for the left hemisphere and 273×131547 for the 165 right hemisphere (the system has two reference channels not used for recording). Besides these axial 166 gradiometer data, we computed the corresponding planar gradiometer data using Fieldtrip [35]. 167

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Noisy MEG data is obtained by adding correlated Gaussian noise to the simulated signals, for dif ferent values of the peak signal-to-noise ratio (PSNR), given by

$$PSNR = 20\log\frac{\max_{i,t}|s_i(t)|}{\sigma_N},\tag{4}$$

where $s_i(t)$ is the noise-free MEG signal at channel *i* at time *t*. The noise covariance matrix was obtained from an empty-room MEG recording and further scaled by a factor $\sigma_N^2/\bar{\sigma}^2$ to obtain the desired PSNR values, where $\bar{\sigma}^2$ is the mean of the entries of its main diagonal.

174 2.3 Functional connectivity matrices

There exist a wide range of measures to characterize functional connectivity between two simulta-175 neously recorded time-series [36] and most of them have been applied to sensor-level EEG and MEG 176 recordings [40]. Since EEG and MEG sensor-level time-series are linear superpositions of cortical time-177 series (volume-conduction/field spread), the results of sensor-level FC analyses are generally difficult 178 to interpret. This motivated the development of FC measures that are based on time-lagged inter-179 actions, since these cannot be explained by field spread. Examples of such measures are imaginary 180 coherency [33], phase-slope-index [32], phase-lag-index [47], and the (symmetric part of the) phase-181 modulation function [26]. In the current study we consider two such measures: the imaginary part of 182 the complex-valued Pearson correlation coefficient (IC) and the phase-lag index (PLI). For comparison, 183 we also use the real part of the (complex-valued) Pearson correlation, which quantifies instantaneous 184 FC. Below, a short description of these three measures is given. 185

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Given two oscillatory time-series $x = (x_1, \dots, x_n)$ and $y = (y_1, \dots, y_n)$, the complex-valued Pearson correlation coefficient $r_{x,y}$ between x and y is defined as the Pearson correlation coefficient between the analytic signals x^A and y^A of x and y, respectively. Thus, let $x^A = x + ix^H$ and $y^A = y + iy^H$ denote the analytic signals of x and y, respectively, where x^H and y^H denote the Hilbert transforms of x and y, then

$$r_{x,y} = \frac{\sum_{k=1}^{n} \left(x_k^A - \bar{x}^A \right) \left(y_k^A - \bar{y}^A \right)^*}{\left(\sum_{k=1}^{n} \left| x_k^A - \bar{x}^A \right|^2 \right)^{1/2} \left(\sum_{k=1}^{n} \left| y_k^A - \bar{y}^A \right|^2 \right)^{1/2}},$$
(5)

where \bar{x}^A denotes the mean of x^A , $|\cdot|$ denotes absolute value, and (*) denotes complex conjugation. Note that $r_{x,y}$ is complex-valued and that $|r_{x,y}| \leq 1$, where an absolute value of 0 and 1 correspond to uncorrelated and completely correlated, respectively. Also, its angle corresponds to the phase-delay between x and y. It particular, $r_{y,x} = r_{x,y}^*$, where * denotes complex conjugation. The *absolute imaginary Pearson correlation coefficient* between x and y, denoted by $r_{x,y}^{imag}$, is obtained by taking the absolute value of the imaginary part of $r_{x,y}$:

$$r_{x,y}^{\text{imag}} = |\text{Im}(r_{x,y})|. \tag{6}$$

Similarly, the absolute real Pearson correlation coefficient between x and y, denoted by $r_{x,y}^{\text{real}}$, is obtained by taking the absolute value of the real part of $r_{x,y}$:

$$r_{x,y}^{\text{real}} = |\text{Re}(r_{x,y})|. \tag{7}$$

Note that $r_{x,y}^{\text{real}}$ and $r_{x,y}^{\text{imag}}$ measure the instantaneous and lagged functional connectivity respectively, and take values within the interval [0, 1]. By calculating the real and imaginary Pearson correlation coefficients for all pairs of cortical regions, we obtained *n*-dimensional cortical FC matrices RC_{cortex} and IC_{cortex}, respectively, where *n* is the number of cortical regions. Furthermore, by calculating the real and imaginary Pearson correlation coefficients between the time-series of every pair of MEG channels, we obtained *s*-dimensional sensor FC matrices, denoted by RC_{sensor} and IC_{sensor}, respectively, where *s* is the number of sensors. In fact, we obtained two sensor FC matrices, corresponding to axial and planar gradiometer data.

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As a third measure, we take the *phase-lag index* (PLI), which is a measure of the asymmetry of the distribution of phase-differences between x and y and takes values in the interval [0, 1]. A value of 0 corresponds to no coupling or instantaneous coupling (that is, phase-difference centered around $0 \mod \pi$), and a value of 1 corresponds to perfect phase locking at an angle $\neq 0 \mod \pi$ [47]. Let $\psi = (\psi_1, \dots, \psi_n)$ denote the phase-differences between x_A and y_A The phase-lag index between x and y is then defined as

$$\rho_{x,y} = |\langle \operatorname{sign}(\psi_k) \rangle|,\tag{8}$$

where $\langle \cdot \rangle$ denotes the average over k. By calculating $\rho_{x,y}$ between the time-series of every pair of cortical regions or MEG sensors, we obtain FC matrices PLI_{cortex} and PLI_{sensor}. As for the Pearson correlation coefficient, we calculated the sensor-level FC matrix for both the axial and planar gradiometer data. In the two following sections, we describe the methods we used for characterizing the FC matrices described above and for comparing corresponding cortical and sensor FC matrices.

²²⁰ 2.4 Network analysis

We characterize and compare the topological features of the cortical and MEG sensor-level FC matrices, considering commonly used indices in MEG (and EEG) sensor-level network-theoretical studies as in e.g. [45].

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²²⁵ Clustering coefficient: The clustering coefficient is the likelihood that neighbors of a given node will be ²²⁶ connected to each other [51]. This measure reflects the organization of the network: whereas a random ²²⁷ network will have clustering coefficient equal or close to 0, one with a high degree of organization (e.g. ²²⁸ a small-world network) will have a large clustering coefficient. Consider a matrix C whose (i, j)th entry ²²⁹ c_{ij} specifies the correlation measure between point *i* and point *j*. The weighted clustering index of ²³⁰ node *i* is defined as

$$c_{i} = \frac{\sum_{k \neq i} \sum_{\substack{l \neq i \\ l \neq k}} c_{ik} c_{il} c_{kl}}{\sum_{\substack{k \neq i \\ l \neq k}} \sum_{\substack{l \neq i \\ l \neq k}} c_{ik} c_{il}}$$
(9)

²³¹ whereas the mean clustering coefficient is given by

$$c_w = \frac{1}{N} \sum_{i=1}^{N} c_i.$$
 (10)

To highlight the differences with respect to a random network, we compute the absolute difference $|c_w - \bar{c}_w|$, where the value \bar{c}_w is the clustering coefficient of a random network, which is equal to the network density.

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Average path length: this measure is the average number of steps along the shortest paths for all possible pairs of nodes in the network, and is a measure of the efficiency of information transport on the network [39]. The average path length depends on the network size but does not change drastically with it. We define the length of an edge as

$$l_{ij} = \frac{1}{c_{ij}}, \quad \text{if } c_{ij} \neq 0,$$
$$l_{ij} = \infty, \quad \text{if } c_{ij} = 0$$

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²⁴¹ The average weighted path length is given by

$$l_w = \left(\frac{1}{N(N-1)} \sum_{i=1}^N \sum_{j \neq i}^N l(i,j)^{-1}\right)^{-1}$$
(11)

242 Global efficiency: efficiency is a measure of how efficiently the network exchanges information, it quan-

tifies the exchange of information across the network. The global efficiency is computed as the average of the inverse shortest path length [39].

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²⁴⁶ Communities are groups of nodes within a network that are more densely connected to one another than

to other nodes. The metric modularity quantifies the quality of an assignment of nodes to communities by evaluating how much more densely connected the nodes within a community are compared to how ²⁴⁹ connected they would be, on average, in a random network. We consider therefore an analysis which
 ²⁵⁰ may shed additional light on the group organization of the network: the Louvain community detection.

Louvain community detection: The Louvain method is an algorithm for detecting communities in networks that relies upon heuristics for maximizing the modularity [3]. The optimal community structure returned by the algorithm is a subdivision of the network into non-overlapping groups of nodes, such that the number of within-group edges is maximized, whereas the number of between-group edges is minimized. The size and the number of communities detected is controlled by the resolution parameter, with standard value equal to 1. Whereas resolutions higher than 1 produce larger number of clusters, resolutions lower than 1 produce lower number of clusters.

259 **3** Results

²⁶⁰ 3.1 Simulated resting-state cortical activity

We simulate resting-state cortical oscillations in the alpha frequency band (≈ 10 Hz) for a total of five 261 minutes using the Hopf oscillators coupled through the structural connectivity matrix S, obtained from 262 diffusion MRI fiber-tracking (see Section 2.1). We want to investigate whether there is a correlation 263 between the FC matrices at source level and the FC matrices at sensor level; therefore, to fit the 273 264 sensors of the MEG helmet we choose a brain parcellation composed of n = 219 ROIs, listed in Table 1. 265 Fig. 2 (a) shows the empirical structural connectivity matrix S, which exhibits a sparse connectivity, 266 whereas Fig. 2 (b) shows the instantaneous FC matrix, denoted RC_{cortex} . Observe that the first 267 quadrant of the matrix S contains the connectivity information from the right hemisphere, whereas 268 the fourth contains the connectivity information from the left hemisphere. Moreover, the second and 269 third quadrants of the matrix show the connections between the left and right hemispheres. The brain 270 model described in Sec. 2.1 is implemented with the parameter values listed in Table 2, and a time 271 sample of brain activity is shown in Fig. 2 (c) where different colors are used to distinguish between 272 nodes with different activity. A seed-based RC_{cortex} matrix has been computed for the right Caudal 273 Middle Frontal 1 region and mapped onto the different brain areas, as shown in Fig. 2 (d). 274

Fig. 3 (a) depicts the time series generated for 10 seconds of brain activity at one node of the brain 275 model, and Fig. 3 (b) shows the MEG signal obtained with axial gradiometer sensors for consecutive 276 time samples as measured at sensor level (plots are read from left to right and top to bottom). The 277 propagation patterns observed in Fig. 3 (b) suggest a spatial organization of the relative latencies in 278 the oscillations recorded at the different sensors. From these images we may infer that a more natural 279 way to conceptualize sensor-level resting-state MEG brain dynamics is as a spatiotemporal continuum 280 sampled in space and time by the channels [24]. Motivated by these observations, we investigate if a 281 network-theoretical approach might be appropriate to characterize them. 282

3.2 Comparison of cortical and MEG functional networks

In this section we systematically compare the network-theoretical properties of the simulated FC ma-284 trices at the cortical- and sensor-level using the network indices described in Sec. 2.4. As outlined in 285 Section 2.3, we use FC matrices computed using three different measures: instantaneous/real correla-286 tion (RC), lagged/imaginary correlation (IC), and the phase-lag index (PLI). Moreover, sensor-level 287 activity is computed assuming either axial or planar gradiometer MEG sensors. After considering 288 some general properties of the cortical and sensor functional networks in Sec. 3.2.1, we characterize 289 and compare their clustering coefficients and global efficiency in Sections 3.2.2 and 3.2.3, respectively. 290 Finally, in Sec. 3.2.4 we compare their community structure. 291

| | RIGHT hemisphere | | RIGHT hemisphere | | LEFT hemisphere | | LEFT hemisphere |
|----|---|--|----------------------|-----------------------|----------------------------|------------|----------------------|
| 1 | lateralorbitofrontal 1 | 57 | superiorparietal 4 | 109 | lateralorbitofrontal 1 | 165 | superiorparietal 1 |
| 2 | lateralorbitofrontal 2 | 58 | superiorparietal 5 | 110 | lateralorbitofrontal 2 | 166 | superiorparietal 2 |
| 3 | lateralorbitofrontal 3 | 59 | superiorparietal 6 | 111 | 111 lateralorbitofrontal 3 | | superiorparietal 3 |
| 4 | lateralorbitofrontal 4 | 60 | superiorparietal 7 | 112 | 112 lateralorbitofrontal 4 | | superiorparietal 4 |
| 5 | parsorbitalis 1 | 61 | inferiorparietal 1 | 113 | parsorbitalis 1 | 169 | superiorparietal 5 |
| 6 | frontalpole 1 | 62 | inferiorparietal 2 | 114 | frontalpole 1 | 170 | superiorparietal 6 |
| 7 | medialorbitofrontal 1 | 63 | inferiorparietal 3 | 115 | medialorbitofrontal 1 | 171 | superiorparietal 7 |
| 8 | medialorbitofrontal 2 | 64 | inferiorparietal 4 | 116 | medialorbitofrontal 2 | 172 | inferiorparietal 1 |
| 9 | medialorbitofrontal 3 | 65 | inferiorparietal 5 | 117 | 117 parstriangularis 1 | | inferiorparietal 2 |
| 10 | parstriangularis 1 | 66 | inferiorparietal 6 | 118 parsopercularis 1 | | 174 | inferiorparietal 3 |
| 11 | parstriangularis 2 | 67 | precuneus 1 | 119 parsopercularis 2 | | 175 | inferiorparietal 4 |
| 12 | parsopercularis 1 | 68 | precuneus 2 | 120 | rostralmiddlefrontal 1 | 176 | inferiorparietal 5 |
| 13 | parsopercularis 2 | 69 | precuneus 3 | 121 | rostralmiddlefrontal 2 | 177 | precuneus 1 |
| 14 | rostralmiddlefrontal 1 | 70 | precuneus 4 | 122 | rostralmiddlefrontal 3 | 178 | precuneus 2 |
| 15 | rostralmiddlefrontal 2 | 71 | precuneus 5 | 123 | rostralmiddlefrontal 4 | 179 | precuneus 3 |
| 16 | rostralmiddlefrontal 3 | 72 | cuneus 1 | 124 | rostralmiddlefrontal 5 | 180 | precuneus 4 |
| 17 | rostralmiddlefrontal 4 | 73 | cuneus 2 | 125 | rostralmiddlefrontal 6 | 181 | precuneus 5 |
| 18 | rostralmiddlefrontal 5 | 74 | pericalcarine 1 | 126 | superiorfrontal 1 | 182 | cuneus 1 |
| 19 | rostralmiddlefrontal 6 | 75 | pericalcarine 2 | 127 | superiorfrontal 2 | 183 | pericalcarine 1 |
| 20 | superiorfrontal 1 70 | | lateraloccipital 1 | 128 | superiorfrontal 3 | 184 | lateraloccipital 1 |
| 21 | superiorfrontal 2 | 77 | lateraloccipital 2 | 129 | superiorfrontal 4 | 185 | lateraloccipital 2 |
| 22 | superiorfrontal 3 | 78 | lateraloccipital 3 | 130 | superiorfrontal 5 | 186 | lateraloccipital 3 |
| 23 | superiorfrontal 4 | 79 | lateraloccipital 4 | 131 | superiorfrontal 6 | 187 | lateraloccipital 4 |
| 24 | superiorfrontal 5 | 80 | lateraloccipital 5 | 132 | superiorfrontal 7 | 188 | lateraloccipital 5 |
| 25 | superiorfrontal 6 | 81 | lingual 1 | 133 | superiorfrontal 8 | 189 | lingual 1 |
| 26 | superiorfrontal 7 | 82 | lingual 2 | 134 | superiorfrontal 9 | 190 | lingual 2 |
| 27 | superiorfrontal 8 | superiorfrontal 8 83 | | 135 | caudalmiddlefrontal 1 | 191 | lingual 3 |
| 28 | caudalmiddlefrontal 1 | 84 | fusiform 1 | 136 | caudalmiddlefrontal 2 | | lingual 4 |
| 29 | caudalmiddlefrontal 2 | 85 | fusiform 2 | 137 | caudalmiddlefrontal 3 | 193 | fusiform 1 |
| 30 | caudalmiddlefrontal 3 | 86 | fusiform 3 | 138 | precentral 1 | 194 | fusiform 2 |
| 31 | precentral 1 | 87 | fusiform 4 | 139 | precentral 2 | 195 | fusiform 3 |
| 32 | precentral 2 | 88 | parahippocampal 1 | 140 | precentral 3 | 196 | fusiform 4 |
| 33 | precentral 3 | 89 | entorhinal 1 | 141 | precentral 4 | 197 | parahippocampal 1 |
| 34 | precentral 4 | 90 | temporalpole 1 | 142 | precentral 5 | 198 | entorhinal 1 |
| 35 | precentral 5 | 91 | inferiortemporal 1 | 143 | precentral 6 | 199 | temporalpole 1 |
| 36 | precentral 6 | 92 | inferiortemporal 2 | 144 | precentral 7 | 200 | inferiortemporal 1 |
| 37 | paracentral 1 | 93 | inferiortemporal 3 | 145 | precentral 8 | 201 | inferiortemporal 2 |
| 38 | paracentral 2 94 inferiortemporal 4 146 paracentral 1 | | paracentral 1 | 202 | inferiortemporal 3 | | |
| 39 | paracentral 3 | | middletemporal 1 | 147 | paracentral 2 | 203 | interfortemporal 4 |
| 40 | rostralanteriorcingulate 1 96 | | middletemporal 2 | 148 | rostralanteriorcingulate 1 | 204 | middletemporal 1 |
| 41 | caudalanteriorcingulate 1 | 97 | middletemporal 3 | 149 | caudalanteriorcingulate 1 | 205 | middletemporal 2 |
| 42 | posteriorcingulate 1 | 98 | hombosta 1 | 150 | posteriorcingulate 1 | 200 | middletemporal 3 |
| 43 | isthere in mulate 1 | 100 | Dankssts I | 151 | isthere in rule to 1 | 207 | hambaata 1 |
| 44 | stimuscingulate 1 | 100 | superiortemporal 1 | 152 | nstninuscingulate 1 | 208 | bankssts 1 |
| 40 | postcentral 1 | 101 superiortemporal 2 153 postcentral 1 | | postcentral 1 | 209 | Dankssts 2 | |
| 40 | postcentral 2 | 102 | superior temporal 4 | 154 | postcentral 2 | 210 | superior temporal 2 |
| 41 | postcentral 4 | 103 | superiortemporal 5 | 156 | postcentral 4 | 211 | superiortemporal 2 |
| 40 | postcentral 5 | 104 | transversetemporal 1 | 150 | postcentral 5 | 212 | superiortemporal 4 |
| 50 | supremarginal 1 | 105 | insula 1 | 158 | postcentral 6 | 213 | superiortemporal 5 |
| 51 | supramarginal 1 | 107 | insula 2 | 150 | postcentral 7 | 214 | transversetemporal 1 |
| 52 | supramarginal 2 | 108 | insula 3 | 160 | supramarginal 1 | 216 | insula 1 |
| 53 | supramarginal 4 | 100 | mouta o | 161 | supramarginal 2 | 217 | insula 2 |
| 54 | superiorparietal 1 | | | 162 | supramarginal 2 | 218 | insula 3 |
| 55 | superiorparietal 2 | | | 163 | supramarginal 4 | 219 | insula 4 |
| 56 | superiorparietal 3 | | | 164 | supramarginal 5 | 210 | mouter i |
| 1 | | 1 | | | | | |

Table 1: Brain parcellation composed of 219 ROIs.

| Parameter | symbol | value |
|-----------------------------|-------------------------|--------------------|
| Number of areas | n | 219 |
| Bifurcation parameter | a | 10 |
| Global coupling constant | g | 50 - 100 |
| Areal oscillation frequency | f_0 | $10\pm1~{\rm Hz}$ |
| Areal noise intensity | σ | 1×10^{-3} |
| sampling frequency | f_s | 100 Hz |
| time | t | $300 \mathrm{\ s}$ |
| peak SNR of MEG data | PSNR | $0-30~\mathrm{dB}$ |

Table 2: Parameters of the cortical Hopf model, their symbols, and nominal values.

²⁹² 3.2.1 General properties

Fig. 4(a)-(c) show the cortical FC matrices RC_{cortex}, IC_{cortex}, PLI_{cortex}, and the ensuing sensor FC 293 matrices RC_{sensor}, IC_{sensor}, PLI_{sensor}, for both axial (Fig. 4(d)-(f)) and planar (Fig. 4(g)-(i)) gra-294 diometer MEG sensors. Moreover, Fig. 4(i)-(l) depict the distributions of FC values for each of the 295 three FC types. We can make a number of observations. First, notice that the RC cortical FC exhibits 296 a similar structure than IC and PLI cortico FC, but significantly higher values. Furthermore, this is 297 approximately true for the sensor activity as well, which agrees with experimental observations [33]. 298 It means that latencies between oscillations at different areas or sensors are much smaller than the 299 oscillation period (which is about 100 ms for alpha oscillations). Lagged cortical FC (IC and PLI) 300 values, however, are larger than lagged sensor FC values, which means that sensor FC matrices un-301 derestimate lagged FC. The main cause of this reduction in lagged FC is the instantaneous mixing of 302 cortical signals through field spread. This phenomena is not unique to MEG recordings but can be 303 observed in EEG and local field potential (LFP) recordings as well [25]. Second, lagged functional 304 networks as measured with PLI are sparser than as measured with IC, and the distribution of their 305 values is less spread for the planar gradiometer system. 306

307

³⁰⁸ Concerning the gradiometer type, notice that the instantaneous functional network (RC) is sparser for ³⁰⁹ planar gradiometers (Fig. 4(g)) than for axial gradiometers (Fig. 4(d)). This is to be expected since ³¹⁰ planar gradiometers yield the highest signal intensities right above active cortical tissue and integrate ³¹¹ source activity over smaller regions of cortex [21]. We observe that the matrices at sensor level (Fig. ³¹² 4 (d)-(i)) show more modularity and a higher level of organization, and as expected, from the first ³¹³ column (Fig. 4(a), (d), (g)) we can see that the real correlation matrix RC is more sensitive to field ³¹⁴ spread.

315 **3.2.2** Topology of resting-state networks I: MEG axial gradiometers

The network indices computed from the FC matrices at source level are compared here with those 316 obtained from the FC matrices at sensor level assuming the MEG system with axial gradiometers. In 317 order to do so, we apply a threshold and compute the binary FC matrices to analyze their organization 318 structure for different threshold values. Fig. 5 (a) shows the clustering coefficient for RC computed 319 with (9) as a function of the binarization threshold, along with the density. Observe that for values 320 in the range [0.2, 0.9] the clustering coefficient of RC_{sensor} exhibits a sort of flooring effect, showing 321 that, although the total number of connections decreases, the number of 3-dimensional cliques remains 322 almost unchanged within that range. This is equivalent to say that the links connecting three nodes 323 are robust. However, this effect is not observed in the RC_{cortex} where the clustering coefficient curve 324 shows a decreasing trend more similar to the one for the density at sensor level. Fig. 5 (b) shows the 325 absolute difference $|c_w - \bar{c}_w|$ for both RC_{cortex} and RC_{sensor}, where \bar{c}_w denotes the average clustering 326 coefficient of a random network, which in this case is equal to the density. In other words, this measure 327 quantifies the difference in clustering with respect to a random network. The larger the value obtained 328

is, the higher the organization of the network (for that particular threshold value). We identify (and 329 highlight) an optimum value for each curve, which clearly do not coincide at source and at sensor level. 330 Fig. 5 (c) shows the efficiency of the network as a function of the binarization threshold. Again, the 331 efficiency computed for RC_{cortex} evidences a different organization than the one for RC_{sensor}. From 332 these results we can infer that RC_{sensor} exhibits a higher level of organization than RC_{cortex} for values 333 above 0.35, or equivalently, less randomness. Different results are obtained for IC and PLI matrices, 334 where both IC_{cortex} and PLI_{cortex} exhibit larger clustering coefficients than those at source level in 335 IC_{sensor} and PLI_{sensor}. Note that the FC matrix exhibiting largest distance with respect to a random 336 network in this case is PLI_{sensor} followed by PLI_{cortex} , as shown in Fig. 5 (e). On the other hand, the 337 global efficiency for these matrices is highest for IC_{cortex} (see Fig. 5 (f)), followed by PLI_{cortex}. 338

339

The results presented so far are obtained considering noise-free measurements. To asses the impact 340 of measurement noise, we perform simulations for several values of PSNR, as defined in (4). Fig. 6 341 plots the results vs. PSNR values in the range [0, 30] dB: (a) and (b) show respectively the clustering 342 coefficient and the global efficiency vs. PSNR for the real correlation matrix RC_{sensor} , along with 343 the results for its randomized counterparts, obtained by randomly shuffling the entries of the upper 344 triangular part of the matrix. Fig. 6 (c) and (d) show the same results for IC and PLI. As expected, 345 the clustering coefficient is slightly larger for the FC matrices than their random versions in all cases, 346 while the global efficiency is slightly higher for the random versions in all the PSNR spectrum. In all 347 cases, we observe that the network indices increase with high PSNR, with a clear transition starting 348 from 10 dB. These incremental behaviors are also observed in the number of communities detected, as 349 explained in Sec. 3.2.4. 350

351 3.2.3 Topology of resting-state networks II: MEG planar gradiometers

In this section we compare the network indices assuming the MEG system with planar gradiometers. 352 Fig. 7 (a) shows the clustering coefficient for RC_{cortex} and RC_{sensor} as functions of the binarization 353 threshold. For the sake of clarity, we include again the curve for the density. Moreover, Fig. 7 (b) 354 shows the absolute difference $|c_w - \bar{c}_w|$ computed for both RC_{cortex} and RC_{sensor}. As expected, the 355 results obtained for the RC matrices are similar to those obtained with the axial gradiometer sensors, 356 whereas the results for IC and PLI matrices are slightly different. In Fig. 7 (e) we can see that in 357 this case, IC_{cortex} and PLI_{cortex} show less distance with respect to a random network than IC_{sensor} 358 and PLI_{sensor}. Regarding noisy data, Fig. 8 (a) and (b) show the clustering coefficient and the global 359 efficiency vs. PSNR in the range [0, 30] for the real correlation matrices RC, along with the results 360 for their randomized counterparts. Fig. 8 (c) and (d) show the same results for IC and PLI at both 361 source and sensor level. The clustering coefficient and the efficiency increase with PSNR for all FC 362 matrices. From Fig. 8 (c) and (d) we can see that both the clustering coefficient and the global 363 efficiency are higher for IC_{sensor} than for PLI_{sensor} . From all the results presented, we can infer that 364 the FC matrices at sensor level show a different level of organization than the FC matrices at source 365 level, independently of the gradiometer system used. 366

367 **3.2.4** Community structure

The Louvain modularity analysis performed for all FC matrices and assuming different values of the 368 resolution parameter yields more interesting results. Table 3 lists the number of detected communities for each network assuming the standard value of the resolution parameter (i.e., 1), and Fig. 9 provides 370 a graphical representation of these results, where the nodes belonging to the same community are 371 rearranged and the communities are reordered by size within the respective matrix. Note that a large 372 number of communities at the cortex are composed of only a few elements, whereas at sensor level, 373 the planar matrices have a smaller number of communities (last row of Fig. 9). Moreover, the axial 374 IC_{sensor} and PLI_{sensor} have a large number of communities with only one element. Fig. 10 shows the 375 results of mapping the Louvain communities detected onto the MEG helmet, where only the most six 376

| $RC_{cortex} = 28$ | $IC_{cortex} = 18$ | $PLI_{cortex} = 20$ |
|--------------------------|---------------------------|---------------------------|
| RC_{sensor} axial = 6 | IC_{sensor} axial = 51 | PLI_{sensor} axial = 28 |
| RC_{sensor} planar = 4 | IC_{sensor} planar = 14 | PLI_{sensor} planar = 8 |

Table 3: Number of communities detected for each FC matrix.

significant communities are highlighted in colors (the remaining communities are all colored in black). 377 The first row of Fig. 10 depicts the distribution of communities for RC_{sensor}, IC_{sensor} and PLI_{sensor} 378 for the MEG system with axial gradiometer sensors, whereas the second row shows the distribution of 379 communities for RC_{sensor}, IC_{sensor} and PLI_{sensor} assuming the MEG system with planar gradiometer 380 sensors. Except for the case of RC (first column of Fig. 10), no particular patterns can be identified 381 for the imaginary correlation matrices, and the communities seem to follow a radial distribution rather 382 than a well-defined network. These images reveal that we should be careful in order not to draw wrong 383 conclusions about the underlying structure of the brain. 384

385

We investigate next the impact of the resolution parameter of the Louvain method on the number of 386 detected communities for all matrices. Fig. 11 (a) depicts the number of communities detected as a 387 function of the resolution parameter in the range [0.5, 1.5] for all FC matrices with the axial gradiome-388 ter system, where the results have been obtained averaging 500 independent realizations. Analogously, 389 Fig. 11 (b) shows the results obtained with the planar gradiometer system. As expected, the number 390 of communities detected increases with increasing resolution parameter in both cases. Except for RC, 391 the number of communities detected at the cortex is smaller than the number of communities detected 392 at sensor level, and this difference is more evident for RC and PLI matrices in both MEG systems. 393 The difference at source and sensor level for RC remains almost constant for the entire resolution range 394 for the axial gradiometer system. This might be interpreted as the planar system having a greater 395 impact on the RC measures as the resolution parameter of the algorithm is increased, and less on the 396 IC measures. 397

398

From these results we can see that, increasing the resolution we systematically obtain a larger number 399 of communities for all matrices. We can also observe that the number of communities is larger at 400 sensor level than at source level for lagged correlations, as shown by the curves. The implications of 401 the results in Fig. 11 (a)-(b) are: first, we observe a discrepancy between the community structure of 402 cortical resting-state activity and that of the ensuing sensor level measurements (namely a different 403 number of communities). Second, it shows that this discrepancy is systematic, that is, at source level 404 the number of communities is always larger than at sensor level. Third, this observation holds for 405 lagged FC matrices (IC and PLI) and different gradiometer systems (axial/planar). 406

407

Analyzing the impact of noise in the number of detected communities, we observe from Fig. 11 (c)-(d) that noise has greater impact on the IC_{sensor} , as more communities are detected with higher PSNR for both systems. The impact of noise is lower for RC_{cortex} , where the number of communities detected does not change significantly with PSNR.

412 4 Discussion

A common way to conceptualize and analyze sensor-level EEG and MEG resting-state data is in terms of functional networks [1,4,19,29,38,43,45,46]. In this approach, the nodes of the network correspond to EEG or MEG sensors and (the strength of its) links correspond to the estimated values of an interaction measure between the time-series recorded at the corresponding nodes. The functional network is subsequently analyzed using graph-theoretical indices [8,23,39]. Although the network-theoretical approach to sensor-level EEG/MEG data is potentially interesting since resting-state cortical dynamics is known to be comprised of a number of functional networks [1,2,46], it is not without methodolog-

ical challenges [28, 50]. One of these challenges, which has received surprisingly little attention, is 420 the fact that EEG/MEG record linear superpositions of cortical activity [21]. Although this nature 421 of EEG/MEG signals has motived the development of interaction measures that are less affected by 422 volume-conduction/field spread [7,26,32,33,47], as well as the use of source reconstruction using tech-423 niques such as beamforming [10, 18, 41, 49], surprisingly few studies have investigated the relationship 424 between cortical and sensor-level EEG/MEG networks [22, 41], despite the fact that these topologi-425 cal features are of high interest in experimental studies [4–6, 15, 16, 19, 29, 45, 46]. Moreover, simple 426 simulations that consider only a small number of regions do not allow to assess network properties. 427 In this study we used a whole-brain computational modeling approach to resting-state dynamics [13] 428 to compare cortical and sensor-level resting-state MEG networks, and considering two different MEG 429 systems: sensors with axial gradiometers and sensors with planar gradiometers. In our simulations, 430 431 we included both instantaneous interaction, as measured by real-valued correlation, as well as lagged interaction, as measured by imaginary-valued correlation and the phase lag index (PLI) [47]. In ad-432 dition to the commonly studied network measures, we performed a Louvain community analysis and 433 we studied the impact of noise in the measurements using empty-room MEG recordings. Below, we 434 discuss our main findings and their implications for network-based analysis of MEG sensor-level data. 435 436

One of our main findings is that the effect of field spread on network topology depends on the type 437 of interaction (instantaneous or lagged), measured by different interaction measures. This holds both 438 for the magnitude of the effect as well as for how field spread changes network topology. In particu-439 lar, instantaneous correlations are more susceptible for field spread than lagged correlations, which is 440 not surprising because field spread is instantaneous [21]. In fact, the interaction measures that have 441 been proposed to deal with volume-conduction or field spread [26, 32, 33, 47] all are based on lagged 442 correlations, in one way or another. But field spread also affects instantaneous and lagged interac-443 tion in different ways: for instantaneous interaction, it leads to a "flooring" of the mean clustering 444 coefficient and global efficiency (as a function of binarization threshold) and to an increased threshold 445 for maximal distance to a random network. For lagged interaction, the mean clustering coefficient 446 and global efficiency descrease (for any given threshold). Thus, our simulations suggest that lagged 447 interactions are more easily assessed from sensor-level MEG data, a finding that generalizes previous 448 studies [26, 32, 33, 47] to large-scale functional networks. 449

450

The Louvain community analysis yields interesting results. First of all, at source level there is a 451 large number of modules with few elements, a particularity not observed at sensor level. For imagi-452 nary correlation (IC) and phase-lag index (PLI) at source level there is only one big community. These 453 organizations do not reflect the coupling among nodes due to the structural connectivity matrix, but 454 rather reflect the spatial low-pass properties of the MEG forward model. The same effect is captured 455 by the axial system at sensor level. On the other hand, a significantly smaller number of communities 456 is detected by the algorithm for the planar system, which may lead to the conclusion of a more orga-457 nized underlying structure. In general, the number of communities at source and sensor level do not 458 match, and the results suggest a different structural organization of the functional connectivity (FC) 459 matrices. Similar conclusions can be drawn from the case of noisy MEG measurements: as the peak 460 signal-to-noise (PSNR) increases, the number of communities increases and the results approach the 461 noise-free case. Regarding the network indices studied, their values are also affected by noise, showing 462 a discrepancy with respect to the noise-free case. 463

464

Another main finding is that the discrepancy between (sensor-level) MEG and cortical networks is larger when using axial gradiometers than when using planar gradiometers. This holds for both instantaneous and lagged interaction and for all studied network-theoretical measures (mean clustering coefficient, network density, average path-length, and global efficiency). Most network-theoretical studies using sensor-level MEG, however, have used axial gradiometers [1,5,17,45], and (as far as we know), (virtual) planar gradiometers have not yet been used for this purpose. To understand why planar gradiometer data is less affected by field spread, recall that the (virtual) planar transformation ⁴⁷² is the sum of the squared magnetic fluxes through two perpendicular directions that are (approxi-⁴⁷³ mately) perpendicular to the skull. This transformation, which is called the Laplacian, behaves like a ⁴⁷⁴ spatial high-pass filter. It hence reduces the MEG sensor's sensitivity to distant sources because the ⁴⁷⁵ source's magnetic fields contains predominantly low spatial frequencies. In contrast to MEG studies, ⁴⁷⁶ the Laplacian has been used frequently applied to (scalp) EEG data [48] as well as to local field po-⁴⁷⁷ tential recordings [25, 31] to increase spatial resolution. Based on our findings, we recommend using ⁴⁷⁸ (virtual) planar gradiometer data when assessing network properties from sensor-level MEG data.

479 5 Conclusions

Functional networks constitute a common way to conceptualize and analyze sensor-level EEG and 480 MEG resting-state data, in which sensors are identified with nodes and the interaction between chan-481 nel time-series with the network connections. The network-theoretical approach is however challenged 482 by the fact that EEG and MEG time-series are mixtures of source activity. Since still many contri-483 butions found in the literature perform network analysis at sensor level, in this study we address the 484 question of to what extent the network topology can be reconstructed from sensor-level FC measures 485 in case of MEG data. Using a diffusion MRI-constrained whole-brain computational model of resting-486 state cortical activity, we report discrepancies between source- and sensor-level network topologies, 487 and observe that the effect of field spread on network topology depends on the type of interaction 488 (instantaneous or lagged). Moreover, we found that instantaneous interaction is more sensitive to field spread than lagged interaction, and that the discrepancies are reduced when using planar gradiometers 490 rather than axial gradiometers. We therefore recommend to use lagged interaction measures on planar 491 gradiometer data when investigating network properties of resting-state sensor-level MEG data. 492

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