ENUMERATION OF LEFT BRACES WITH ADDITIVE GROUP $C_4 \times C_4 \times C_4$

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ABSTRACT. We show that the number of isomorphism classes of left braces of order 64 with additive group isomorphic to $C_4 \times C_4 \times C_4$ is 1515429.

1. INTRODUCTION

The notion of skew left brace was introduced by Guarnieri and Vendramin in [9]. A skew left brace is a triple $(B, +, \cdot)$ where B is a set and $+, \cdot$ are two binary operations on B such that (B, +) and (B, \cdot) are groups and that are related by the distributive-like law a(b + c) = ab - a + ac. As it is common in the theory of skew left braces, we omit the sign \cdot and we write ab instead of $a \cdot b$ and we use -a to denote the inverse of a in the group (B, +); the expression a - b means a + (-b). When, in addition, (B, +) is an abelian group, then we speak of a left brace, a notion introduced by Rump in his seminal paper [12].

One of the most natural problems in the theory of skew left braces is the determination of skew left braces of a given finite order. Guarnieri and Vendramin present in [9, Algorithm 5.1] an algorithm to enumerate all skew left braces with a given finite additive group A. They presented in [9] the numbers of isomorphism classes of left braces of order n for $n \leq 120$ except for $n \in \{32, 64, 81, 96\}$ obtained with their implementation of this algorithm in Magma [6]. In fact, they claim in their paper: "With current computational resources, we were not able to compute the number of non-isomorphic left braces of orders 32, 64, 81 and 96." This computation appears open as [9, Problem 6.1]. Vendramin posed in [13, Problem 2.13] the problem of constructing all left braces of order 32, for which he presented some partial results on [13, Table 2.3]. He also wrote as a comment to this problem: "The number of (skew) left braces of size 64, 96 or 128 seems to be extremely large and our computational methods are not strong enough to construct them all."

Bardakov, Neshchadim, and Yadav presented in [5, Algorithm 2.4] a modification of [9, Algorithm 5.1] for the computation of finite skew left braces with a given additive group. They were able to enumerate the isomorphisms classes of skew left braces of orders 32 and 81, as well as the left braces of order 96. With respect to the isomorphism classes of left braces of order 64, they were able to enumerate them in [5, Table 6] for all isomorphism classes of abelian groups of order 64, except for the cases of additive group isomorphic to $C_4 \times C_4 \times C_4$ (SmallGroup(64, 55) in the notation of GAP [8]) and to $C_2 \times C_2 \times C_4 \times C_4$ (SmallGroup(64, 192)).

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In this paper we obtain the isomorphism classes of left braces with additive group isomorphic to $C_4 \times C_4 \times C_4$.

Theorem 1.1. There are 1515429 isomorphism classes of left braces of order 64 whose additive group is isomorphic to $C_4 \times C_4 \times C_4$.

Table 1 summarises these isomorphism classes by the isomorphism class of the multiplicative group. For instance, the first two entries of the first row of the table (4, 42) mean that there are two isomorphism classes of braces with additive group $C_4 \times C_4 \times C_4$ and multiplicative group isomorphic to SmallGroup(64, 4).

The study of the left braces with additive group isomorphic to $C_2 \times C_2 \times C_4 \times C_4$ has been the object of a later research in [4], after the submission of this paper. That article has been accepted for publication while writing the revised version for this paper. We must indicate that the techniques used in this paper to classify the left braces with additive group $C_4 \times C_4 \times C_4$ up to isomorphism are not enough to solve the corresponding problem for the additive group $C_2 \times C_2 \times C_4 \times C_4$ due mainly to the high number of intermediate subgroups needed in the algorithm and we have had to use new ideas that are described with detail in [4]. The main results of that paper are the following ones.

Theorem 1.2 ([4, Theorem 1.1]). The number of isomorphism classes of left braces of order 64 with additive group isomorphic to $C_2 \times C_2 \times C_4 \times C_4$ is 10 326 821.

Corollary 1.3 ([4, Corollary 1.2]). The number of isomorphism classes of left braces of order 64 is 15 095 601.

2. The holomorph of a group

Most of the results in this section can be considered as folklore. We present them here for the sake of completeness.

Let (G, +) be a group. The holomorph of G is

$$Hol(G, +) = \{(g, \alpha) \mid g \in G, \alpha \in Aut(G)\}\$$

with the operation given by

$$(g,\alpha)(h,\beta) = (g + \alpha(h), \alpha \circ \beta).$$

The identity element of $\operatorname{Hol}(G, +)$ is (0, 1) and the inverse of the element $(g, \alpha) \in \operatorname{Hol}(G, +)$ is

$$(g, \alpha)^{-1} = (-\alpha^{-1}(g), \alpha^{-1}).$$

The subgroup $A = \{(0, \alpha) \mid \alpha \in Aut(G, +)\}$ is isomorphic to Aut(G, +). We identify A with Aut(G, +).

The group Hol(G, +) acts on (G, +) by means of

$$(g, \alpha) * h = g + \alpha(h), \qquad g, h \in G.$$

Note that when (G, +) is the additive group of a vector space, then Hol(G, +) can be identified with the affine group on the vector space G and this corresponds to the natural action of the affine group on G.

Furthermore, let us show that this action is faithful: If $(g, \alpha) * h = (k, \beta) * h$ for all $h \in G$, then $g + \alpha(h) = k + \beta(h)$ for all $h \in G$. In particular, taking h = 0, we obtain that g = k. Consequently, $\alpha(h) = \beta(h)$ for all $h \in G$ and so $\alpha = \beta$. Hence, this action is faithful. Therefore, we can identify $\operatorname{Hol}(G, +)$ with a subgroup of the group Σ_G of all permutations of the set G.

id	#	id	#	id	#	id	#	id	#
4	42	75	43525	119	67	165	81	221	26932
5	40	76	14422	120	66	166	130	222	5404
6	4	77	28837	121	67	167	1	223	32308
7	22	78	43304	122	66	168	47	224	2763
8	74	79	43180	123	1	169	46	225	2731
9	64	80	14420	124	40	170	47	226	21671
10	16	81	43123	125	40	172	46	227	64744
13	2	82	4118	128	63	173	34	228	21644
14	16	83	32	129	135	175	34	229	14412
17	50	84	33	130	163	176	48	230	3618
18	82	85	42	131	92	177	34	231	10802
19	12	86	32	132	164	178	82	232	43179
20	156	87	102	133	224	179	1	233	21576
21	36	88	93	134	287	181	1	234	43092
22	24	89	112	135	98	182	1	235	10786
23	406	90	947	136	326	192	976	236	10794
24	48	91	266	137	130	193	3453	237	10790
25	106	92	149	138	485	194	2826	240	10828
32	294	93	58	139	515	195	6945	241	21686
33	283	94	164	140	1	196	16440	242	3664
34	133	95	57	141	42	197	3624	243	21516
35	160	96	101	142	73	198	5468	244	10820
36	2	97	109	143	114	199	6987	246	13
37	10	98	135	144	73	200	489	247	55
55	567	99	65	145	138	201	5430	248	56
56	3757	100	105	146	131	202	7632	249	66
57	3640	101	316	147	35	203	19248	250	12
58	21838	102	280	148	96	204	13610	251	43
59	21628	103	39	149	131	205	16629	252	31
60	3908	104	42	150	35	206	27099	253	120
61	21812	105	32	151	96	207	8277	254	147
62	11052	106	17	152	64	208	5407	255	203
63	10850	107	17	153	16	209	9052	256	246
64	7193	108	21	154	48	210	32312	257	52
65	3682	109	67	155	2	211	1919	258	144
66	43617	110	24	156	43	212	2763	259	92
67	43927	111	24	157	2	213	13608	260	193
68	86 219	112	52	158	43	214	2758	261	1011
69	87 259	113	54	159	1	215	19242	262	173
70	43 183	114	46	160	66	216	19 092	263	2 052
71	21837	115	68	161	52	217	8 253	264	1921
72	21725	116	140	162	52	218	13543	265	489
73	14 585	117	68	163	69	219	53 836	266	503
14	14 420	118		164	81	220	32333	267	10

TABLE 1. Number of isomorphism classes of left braces with additive group $C_4 \times C_4 \times C_4$ by multiplicative group

Given $g \in G$, let $\tau_g \colon G \longrightarrow G$ be given by $\tau_g(h) = g + h$, the *left translation* of G defined by g. It is clear that $T = \{\tau_g \mid g \in G\}$ is a subgroup of Σ_G isomorphic to G. Furthermore, we can identify τ_g with $(g, 1) \in \operatorname{Hol}(G, +)$. The proof of the following proposition can be found, for instance, in [11, Application 1.5.2].

Proposition 2.1. The normaliser in Σ_G of T coincides with the holomorph of (G, +).

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We now present some characterisations of regular subgroups that are useful for our purposes.

First of all, note that a subgroup H of $\operatorname{Hol}(G, +) \leq \Sigma_G$ is regular if, and only if, it acts transitively on G and the stabiliser H_g of each element $g \in G$ is trivial. In other words, given $h, k \in G$, there exists a unique $(g, \alpha) \in H$ such that $(g, \alpha) * k = h$. Suppose that H is a regular subgroup of $\operatorname{Hol}(G, +)$. Given $h \in G$, there exists a unique $(g, \alpha) \in H$ such that $(g, \alpha) * 0 = h$. Consequently, $g + \alpha(0) = g = h$. Suppose that $(g, \alpha), (g, \beta) \in H$. Since $g = (g, \alpha) * 0 = (g, \beta) * 0 = g$, the regularity of the action of H on G shows that $\alpha = \beta$. Hence, α is uniquely determined by $g \in G$, let us call $\alpha = \lambda_g$. Consequently $H = \{(g, \lambda_g) \mid g \in G\}$, where the map $\lambda: G \longrightarrow G, \lambda(g) = \lambda_g$ depends on H. Furthermore, since the action is transitive, the "projection" of H on the G-component of $\operatorname{Hol}(G, +)$ is surjective.

Note that (0,1) * 0 = 0, therefore $\lambda_0 = 1$ and so $H \cap Aut(G, +) = \{(0,1)\}$.

Remark 2.2. Other authors have considered the regularity of a subgroup H of $\operatorname{Hol}(G)$ in the following equivalent way: given $k \in G$, there exists a unique $(h, \beta) \in H$ such that $(h, \beta) * k = 0$, that is, for every $k \in G$ there exists a unique $(h, \beta) \in H$ such that $h + \beta(k) = 0$. We have preferred the opposite point of view because we obtain more easily the expression $H = \{(g, \lambda_g) \mid g \in G\}$ for a regular subgroup H of $\operatorname{Hol}(G)$ (cf. [9, Lemma 4.1]).

In the following proposition, we assume that (G, +) is a finite group.

Proposition 2.3. Let (G, +) be a finite group and let H be a subgroup of Hol(G, +). Let us denote by π_G the "projection" of Hol(G, +) on G. Then $|H| = |\pi_G(H)||H \cap Aut(G, +)|$.

Proof. The orbit of $0 \in G$ with respect to the action of $\operatorname{Hol}(G)$ on G is $\{(g, \alpha) * 0 \mid (g, \alpha) \in H\} = \pi_G(H)$ and the stabiliser of 0 is $\{(g, \alpha) \in H \mid (g, \alpha) * 0 = 0\} = \{(g, \alpha) \in H \mid g = 0\} = \operatorname{Aut}(G) \cap H$. The result follows as an application of the orbit-stabiliser theorem.

Proposition 2.3 is useful in the finite case to discard subgroups whose subgroups cannot contain regular subgroups because the "projection" to G is not surjective in the computation of all regular subgroups of the holomorph of a given finite group (G, +). We can do it by means of the following result.

Proposition 2.4. Let (G, +) be a finite group and let H be a subgroup of $\operatorname{Hol}(G, +)$. The restriction of the "projection" π_G of $\operatorname{Hol}(G, +)$ to H is surjective if, and only if, $|H| = |G||H \cap \operatorname{Aut}(G, +)|$.

Another consequence of Proposition 2.3 is the following characterisation of regular subgroups of Hol(G, +) for a finite group (G, +).

Proposition 2.5 (cf. [1]). Let (G, +) be a finite group. Every two of the following three statements about a subgroup H of Hol(G, +) imply the other one.

- (1) |H| = |G|.
- (2) $H \cap \operatorname{Aut}(G, +) = \{(0, 1)\}.$
- (3) The restriction to H of the "projection" π_G of $\operatorname{Hol}(G, +)$ on G is surjective.

Moreover, a subgroup H of Hol(G, +) satisfying two of the three previous properties (and so the other one) is regular.

Proof. The fact that every two of the three statements imply the other one is an immediate consequence of Proposition 2.4. As in the proof of Proposition 2.3, $\pi_G(H)$ is the orbit of 0 under the action of H and $H \cap \operatorname{Aut}(G)$ is the stabiliser of 0. If H satisfies all these properties, then the orbit of 0 is G and its stabiliser is trivial, that is, H is regular.

Proposition 2.6. Let H be a regular subgroup of Hol(G), say $H = \{(g, \lambda_g) \mid g \in G\}$. Then, given $g, k \in G, \lambda_{g+\lambda_g(k)} = \lambda_g \circ \lambda_k$ and $\lambda_g^{-1} = \lambda_{\lambda_g^{-1}(-g)}$

Proof. Note that $(g, \lambda_g)(k, \lambda_k) = (g + \lambda_g(k), \lambda_g \circ \lambda_k) = (g + \lambda_g(k), \lambda_{g+\lambda_g(k)}) \in H$. When we apply this to $k = \lambda_g^{-1}(-g)$, we obtain that $1 = \lambda_0 = \lambda_g \circ \lambda_{\lambda_g^{-1}(-g)}$. The result follows.

The following fact is mentioned in [5] and used to improve the algorithms to obtain all skew left braces with a given additive group.

Proposition 2.7. Let H be a regular subgroup of $\operatorname{Hol}(G, +)$ with (G, +) a group and let $(g, \alpha) \in \operatorname{Hol}(G, +)$. Then $(g, \alpha)H(g, \alpha)^{-1}$ is again a regular subgroup of $\operatorname{Hol}(G, +)$. Furthermore, there exists $\beta \in \operatorname{Aut}(G, +)$ such that $(g, \alpha)H(g, \alpha)^{-1} =$ $(0, \beta)H(0, \beta)^{-1}$.

3. Regular subgroups and skew left braces

We present now the result that allows us to construct all skew left braces with a given additive group (G, +). All these results are well known (see, for instance, [9, Section 4]) and we present them here for completeness.

Proposition 3.1. Let $(B, +, \cdot)$ be a skew left brace. Given $a \in B$, let $\lambda_a : B \longrightarrow B$ be the lambda map given by $\lambda_a(b) = -a + ab$. Then $H = \{(a, \lambda_a) \mid a \in B\}$ is a regular subgroup of Hol(B, +).

Proof. It is well known that $\lambda_a \in Aut(B, +)$ for all $a \in A$. Since

$$(a, \lambda_a)(b, \lambda_b) = (a + \lambda_a(b), \lambda_a \lambda_b) = (a + \lambda_a(b), \lambda_{a+\lambda_a(b)}) \in H$$

by Proposition 2.6 and, by the same result, $\lambda_a^{-1} = \lambda_{\lambda_a^{-1}(-a)}$ and so $(a, \lambda_a)^{-1} = (\lambda_a^{-1}(-a), \lambda_a^{-1}) = (\lambda_a^{-1}(-a), \lambda_{\lambda_a^{-1}(-a)}) \in H$, H is a subgroup of $\operatorname{Hol}(B, +)$. Given $a \in G$, there exists a unique element (g, α) in H such that $(g, \alpha) * 0 = a$, namely $(g, \alpha) = (a, \lambda_a)$. Therefore, H is regular.

The proof of the following proposition can be found in [9, Theorem 4.2].

Proposition 3.2. Given a regular subgroup H of Hol(G, +), with (G, +) a group, then H admits a structure of skew left brace whose additive group is isomorphic to (G, +).

The following result combines Lemma 2.1 and Theorem 2.2 of [5].

Proposition 3.3. Two regular subgroups H_1 and H_2 of Hol(G, +) induce isomorphic skew left braces if, and only if, they are conjugate by an element of Aut(G, +).

Note that, by Proposition 2.7, the condition of Proposition 3.3 can be replaced by conjugation in Hol(G, +).

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4. Computational challenges

By Section 3, the problem of determining the skew left braces with additive group isomorphic to $G = C_4 \times C_4 \times C_4$ up to isomorphism is reduced to determining the conjugacy classes of regular subgroups of Hol(G). Furthermore, since G is a 2group, every regular subgroup H of Hol(G) has order |H| = |G| = 64 and so a conjugate of H is contained in a fixed Sylow 2-subgroup of Hol(G). Hence it is enough to determine all regular subgroups of a Sylow 2-subgroup of Hol(G).

Hulpke [10] has developed an algorithm to determine the lattice of subgroups of a finite soluble group S. This algorithm is implemented by means of the function SubgroupsSolvableGroup of GAP [8]. We summarise this algorithm as follows:

- (1) We compute a normal series $S \ge N_1 \ge \cdots \ge N_r = 1$ with elementary abelian factors.
- (2) We construct by induction the subgroups of S/N_{i+1} from the subgroups of S/N_i . Without loss of generality, we assume that $N_{i+1} = 1$, $N = N_i$, and we know the subgroups of S/N. We have the following possibilities for a subgroup U of S:
 - (a) U contains N and thus U is the full preimage of a subgroup of S/N under the natural epimorphism;
 - (b) U is contained in N and so U is a subspace of the vector space N, or
 - (c) $B := U \cap N$ is a proper subgroup of N and A = NU is a subgroup of G that contains properly N.

The subgroups of the first type are simply the preimages of the subgroups of S/N, that have been computed by induction. The subgroups of the second type are the subspaces of the vector space N. Hence it is enough to consider the third case. In the third case, $B \leq U$ and $B \leq N$. Therefore $B \leq NU = A$ and $A \leq N_S(A) \cap N_S(B)$. It follows that U/B can be computed as a complement of N/B in A/B.

We cannot apply this algorithm directly to S = Hol(G) since Hol(G) is not soluble, but we can apply it to a Sylow 2-subgroup of Hol(G). The implementation of SubgroupsSolvableGroup in GAP includes the possibility of adding restrictions like ExactSizeConsiderFunction to avoid the computation of subgroups that do not lead to subgroups of the specified order. This is useful since regular subgroups of Hol(G) have the same order as G. We also note that regular subgroups of Hol(G)must have a surjective "projection" onto G and so we can add the restriction of Proposition 2.4 to discard all subgroups leading only to non-regular subgroups.

In the GAP implementation of SubgroupsSolvableGroup, the list of all conjugacy classes of subgroups of G/N_i (layer *i*) and all computed conjugacy classes of G/N_{i+1} (layer i+1) are stored at each layer. However, only one group of the layer *i* is needed at each step and the groups obtained for the layer i+1 will not be used until advancing to the next layer. Furthermore, they can be a lot of subgroups and they can use a large amount of memory, that could eventually exhaust the physical memory. Our approach is to replace saving these subgroups to the memory by saving them to a hard disk at the obvious drawback of speed. Furthermore, in the event of a power loss, we could restart the computation at the exact point it was stopped. We have also modified the algorithm to use space on a hard disk instead of the RAM. We note that the GAP function SubgroupsSolvableGroup, when it is applied with some restrictions like ExactSizeConsiderFunction, returns all subgroups satisfying these restrictions, but it might return other subgroups. Our implementation includes a final check to remove these eventually extra subgroups.

5. Our computations

The implementation of this modified algorithm for the computation of the regular subgroups of a Sylow 2-subgroup of $\operatorname{Hol}(C_4 \times C_4 \times C_4)$ produced 31 367 678 conjugacy classes. Of course, some of these classes can have representatives that are not conjugate in the Sylow 2-subgroup, but can be conjugate in $\operatorname{Hol}(C_4 \times C_4 \times C_4)$. Consequently, the next natural step is to classify their representatives by conjugation in $\operatorname{Hol}(C_4 \times C_4 \times C_4)$. Since we were expecting many regular subgroups to be compared by conjugation in $\operatorname{Hol}(C_4 \times C_4 \times C_4)$, in the last step of the algorithm we classify the regular groups by their isomorphism class, the isomorphism class of the kernel of the action of the brace on the additive group (the set of all elements of the regular subgroup that stabilise all elements of $C_4 \times C_4 \times C_4$, that coincides with the centraliser of the normal subgroup $C_4 \times C_4 \times C_4$ in the holomorph as a semidirect product with respect to this action) and the isomorphism class of the quotient by this normal subgroup. We have obtained an overall number of 1 442 equivalence classes.

Our idea is to reduce the checking of conjugation to each of these 1 442 equivalence classes. The comparisons of different equivalence classes can be performed in parallel by using different processors. Some of these equivalence classes turn out to be small, for example, 74 of them have only one element and 1 055 have at most 100 elements. In all these classes the comparison by conjugation is fast. However, 63 equivalence classes have more than 100 000 subgroups, 19 equivalence classes have more than 500 000 subgroups, 13 equivalence classes have more than 1 000 000 subgroups, and the 4 largest equivalence classes have more than 1 000 000 subgroups. The largest one has 1 782 312 subgroups.

We have decided to refine the 63 largest equivalence classes by means of the length of the conjugacy class in $\operatorname{Hol}(C_4 \times C_4 \times C_4)$. This refinement applied to all equivalence classes gives a total number of 2 353 equivalence classes. In some cases, this has allowed us to obtain some small numbers of subgroups that can be easily compared by conjugation, but for the largest conjugacy class lengths the computations were still slow. The execution of these comparisons on a computer with an Intel processor i7-11700 that allows the execution of 16 parallel tasks and 32 Gb of RAM running GNU/Linux during a couple of months made us guess that we would need more than two years to perform the task.

At that time we applied for the use of the scientific supercomputer *Lluís Vives* to the Computer Service of the Universitat de València (see [7]). We thank the Computer Service for granting an immediate access to this machine and for their help installing GAP and solving our doubts. On this machine, we were able to complete the computations in less than two months by running several comparisons in parallel. Our implementation of parallelism in this setting has consisted of running several instances of GAP that select from a list of regular subgroups a unique representative of each conjugacy class in $Hol(C_4 \times C_4 \times C_4)$ or select from two lists of regular subgroups for which two elements in the same list are not conjugate in $Hol(C_4 \times C_4 \times C_4)$ a list of the subgroups of both lists that contain no pairs of

conjugate subgroups. We have not used any particular computer package to run GAP in parallel mode, as our setting has been enough for our purposes. The total number of conjugacy classes of regular subgroups of $Hol(C_4 \times C_4 \times C_4)$ we have found is 1515429. Table 1 summarises the numbers of conjugacy classes by the first invariant we consider, the isomorphism class of the multiplicative group of the resulting left brace.

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DATA AVAILABILITY

The complete list of left braces or order 64 is available for use in GAP [8] on https://github.com/RamonEstebanRomero/braces64 [3]. It also includes the left braces with additive group $C_2 \times C_2 \times C_4 \times C_4$ computed by the authors in [4]. The storage of these left braces follows the ideas of [2] of representing them as triply factorised groups. This repository also includes some GAP functions to use these left braces with the help of the YangBaxter package [14] for GAP.

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