



Shape from planar curves: a linear escape from Flatland

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Introduction

We revisit the problem of recovering 3D shape from a single photo containing planar curves. Previous work [1,2,3] did not explicitly explore the space of flat solutions and its orthogonal complement

- For **intersecting planar curves**, we study the space of solutions and derive a stable linear method
- For **parallel planar curves**, we demonstrate special cases where the shape is similarly solved
- Our work **unifies relevant literature** on shape from contour, single view modeling and structured light

Intersecting curves

Consider planar curves

$$z_i(x, y) = a_i x + b_i y + d_i$$

At intersection points

$$z_i(x_{ij}, y_{ij}) - z_j(x_{ij}, y_{ij}) = 0$$

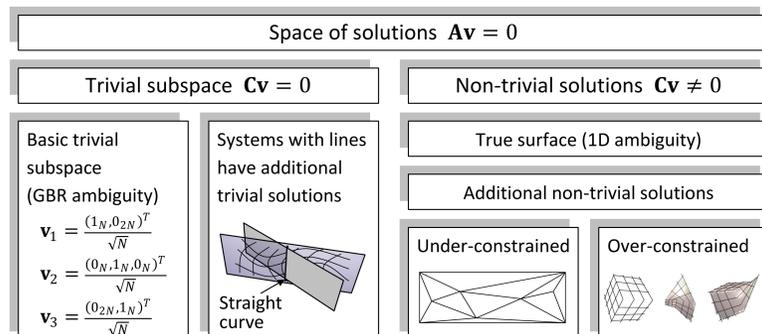
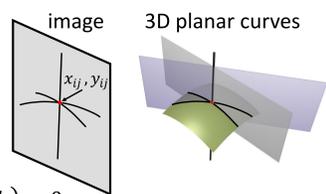
$$(a_i - a_j)x_{ij} + (b_i - b_j)y_{ij} + (d_i - d_j) = 0$$

The homogenous linear system in vector form

$$\mathbf{A}\mathbf{v} = 0$$

$$\mathbf{v} = (a_1, \dots, a_N, b_1, \dots, b_N, d_1, \dots, d_N)^T$$

Let \mathbf{C} be a matrix so that $\|\mathbf{C}\mathbf{v}\|^2$ is the linear regression residue of fitting a plane to a sample of 3D points on the curves



Ambiguity resolution: pick a vector orthogonal to the trivial subspace

- For a large number of random planes, the relative magnitude of the trivial component is likely to be small $\frac{1}{\sqrt{N}} \left\| \left(\sum a_i, \sum b_i \right) \right\| / \left\| (a_1, \dots, a_N, b_1, \dots, b_N) \right\|$

Simple linear method

$$\underset{\mathbf{v}}{\operatorname{argmin}} \|\mathbf{A}\mathbf{v}\| \text{ s.t. } \|\mathbf{v}\| = 1, \mathbf{v} \perp \operatorname{Span}\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$$

- Breaks in presence of straight lines
- May collapse to a nearly-flat solution

Our method

$$\underset{\mathbf{v}}{\operatorname{argmin}} \|\mathbf{A}\mathbf{v}\| \text{ s.t. } \|\mathbf{C}\mathbf{v}\| = 1, \mathbf{v} \perp \operatorname{Null}(\mathbf{C})$$

$$\mathbf{v} = \mathbf{C}^+ \mathbf{w}, \text{ where } \mathbf{w} \text{ is the last right singular vector of } \mathbf{A}\mathbf{C}^+$$

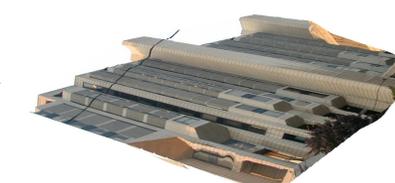
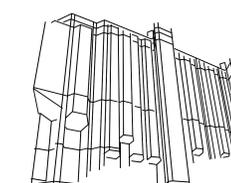
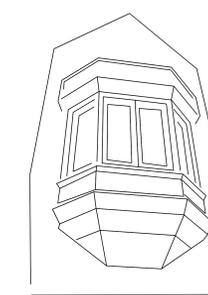
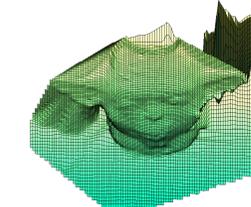
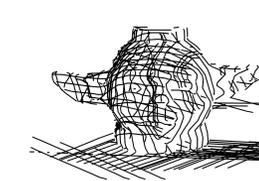
Similar linear formulation for perspective projection

- Singular values are independent of the focal length

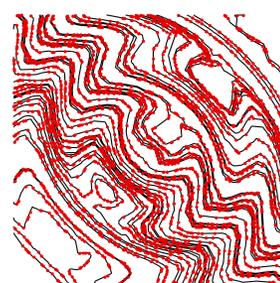
image

intersecting 2D curves

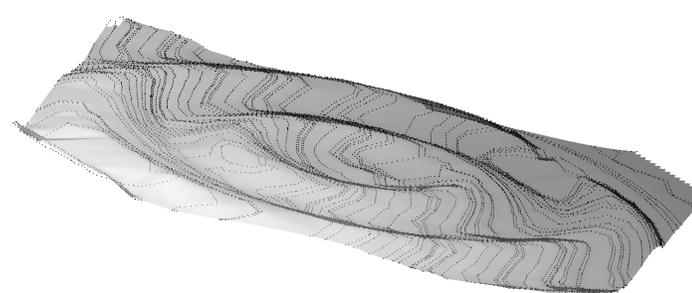
computed 3D surface



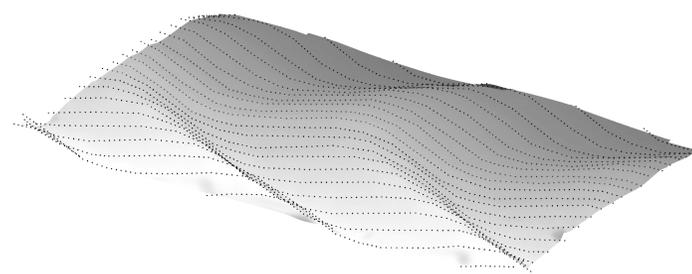
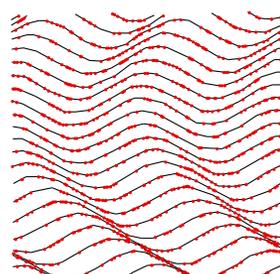
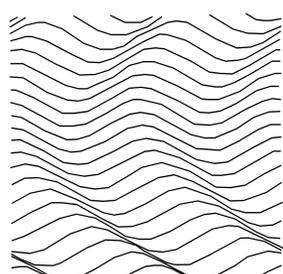
parallel curves



sampled points



computed 3D surface

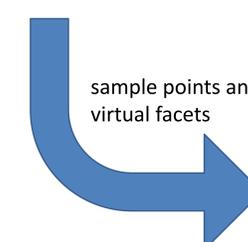
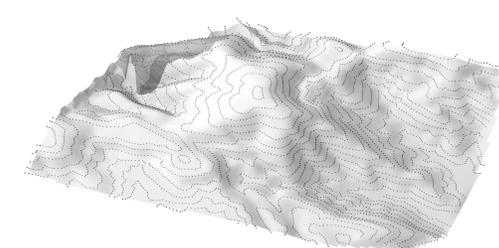
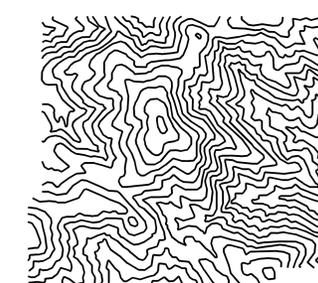


Parallel curves

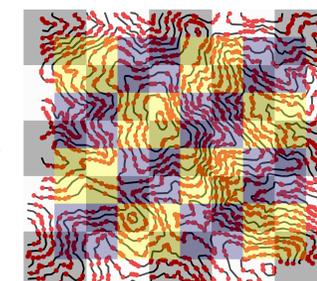
- Humans can perceive 3D from parallel planar cross sections
- Do not assume fixed gaps between the planes. Not standard shape from texture
- We demonstrate reconstructions in special cases

Global planarity

- For curves arranged around a principle plane, the shape might be a singular vector of $\begin{bmatrix} \mathbf{R} \\ \mathbf{C} \end{bmatrix}$
- $$\|\mathbf{R}\mathbf{v}\|^2 = \lambda(\operatorname{Var}(a_i) + \operatorname{Var}(b_i))$$



sample points and virtual facets



solve the linear system

Local planarity

- Reduce to the intersecting case by assuming virtual planar facets

References

- [1] K. Sugihara. *Machine Interpretation of Line Drawings*. MIT press, 1986
- [2] C. Rothwell and J. Stern. Understanding the shape properties of trihedral polyhedra. Technical Report 2661, INRIA, 1995
- [3] J.-Y. Bouguet, M. Weber, and P. Perona. What do planar shadows tell us about scene geometry? In *Proc. CVPR'99*, pages 514–520, 1999