

The DoF of Network MIMO with Backhaul Delays

Xinping Yi, Paul de Kerret, and David Gesbert

Mobile Communications Department

EURECOM

06560, Sophia Antipolis, France

Email: {xinping.yi, paul.dekerret, david.gesbert}@eurecom.fr

Abstract—We consider the problem of downlink precoding for Network (multi-cell) MIMO networks where Transmitters (TXs) are provided with imperfect Channel State Information (CSI). Specifically, each TX receives a delayed channel estimate with the delay being specific to *each channel component*. This model is particularly adapted to the scenarios where a user feeds back its CSI to its serving base only as it is envisioned in future LTE networks. We analyze the impact of the delay during the backhaul-based CSI exchange on the rate performance achieved by Network MIMO. We highlight how delay can dramatically degrade system performance if existing precoding methods are to be used. We propose an alternative robust beamforming strategy which achieves the maximal performance, in DoF sense. We verify by simulations that the theoretical DoF improvement translates into a performance increase at finite Signal-to-Noise Ratio (SNR) as well.

I. INTRODUCTION

The recent years have witnessed considerable work and progress related to the use of multiple-antenna strategies in interference-limited wireless networks. In particular multiple-antenna schemes have proved quite powerful when combined with some form of cooperation or coordination across interfering devices [1, 2]. Nevertheless, some cost must be paid for extracting cooperation gains, in the form of information exchange, where such information can be CSI or user data related. In the case the network's backhaul (or specific privacy regulations) do not support the sharing of user data, a so-called interference channel arises whereby cooperative beamforming strategies can be implemented provided shared CSI is made available at the TXs. The strategies differ whether interference canceling is available at the user terminals (see e.g., spatial interference alignment [3, 4]) or is not [5]. Substantial gains can be offered in the case user data sharing is allowed among transmitters (so-called Network or multi-cell MIMO), in particular in the sense that interference avoidance at transmitter alone is made possible with a reduced overall number of antennas [2]. Nevertheless real-time CSI sharing remains an important practical challenge for such systems. Previous work on limited CSI feedback model include the case of finite quantizing [6, 7] and, recently, delayed feedback.

In [8], it was shown that even completely stale channel feedback, referred to as “delayed CSIT”, could be used to achieve a larger degrees of freedom (DoF), or pre-log factor. This is achieved by using a novel space-time interference

alignment technique, referred to as “MAT alignment”. One feature of this scheme is that the transmitter treats the delayed feedback as it is fully uncorrelated with the current channel (i.e., worst case scenario). This work was later extended to take into account the possible temporal correlation in the fading channel [9, 10], resulting in a scheme (referred to in the following as the “ α -MAT alignment”) bridging between conventional zero-forcing and the MAT algorithm (when delays exceed the channel's coherence period). All these works apply to uniform feedback delay settings, i.e. whereby all channel components are delayed by the same amount.

In the context of Network MIMO, as specified by current 4G standards, the situation is different as the standards impose that a user feeds back directly to its serving base only, while any further inter-cell CSI exchange must take place over some specific backhaul signaling channels. In reality, signaling over the backhaul introduces additional delays which further degrade the CSI reliability. Thus any CSIT pertaining to an interfering user is subject to a larger delay than that of the served user. The analysis of Network MIMO with heterogeneous CSI delays does not follow from the homogeneous broadcast setting of [8, 9, 11, 12] in any straightforward manner. Instead, a novel specific study of this problem is addressed in this paper.

More specifically, our contributions are as follows:

- We adapt the α -MAT alignment developed in [9, 10] to this heterogeneous delay scenario, and show that the DoF achieved is then limited by the worst delay after which a channel estimate is obtained at the TX.
- Adapting a modified zero-forcing beamforming (ZF-BF) scheme [13], we overcome the CSI discrepancy created by the backhaul delay and propose a DoF-optimal beamforming scheme for the specific two-cell setting.

Notation: Matrices and vectors are represented as upper-case and lowercase letters, and matrix transport and Hermitian transport are denoted by \mathbf{A}^\top , \mathbf{A}^H , respectively. \mathbf{h}^\perp is the normalized orthogonal component of any nonzero vector \mathbf{h} . The approximation $f(P) \sim g(P)$ is in the sense of $\lim_{P \rightarrow \infty} \frac{f(P)}{g(P)} = C$, where C is a constant that does not scale as P .

II. SYSTEM MODEL

A. Channel Model

We consider a two-cell network, where in each cell the transmitter (TX) with single-antenna serves one single-antenna receiver (RX). Both TXs share the user's data symbols and transmit jointly to the two RXs in a BC mode. The RXs are assumed to have perfect instantaneous CSI relative to the multiuser channel. The discrete time baseband signal received at RX- j is given by

$$y_j(t) = \mathbf{h}_j^H(t) \mathbf{x}(t) + z_j(t) \quad (1)$$

for any time instant t , where $\mathbf{h}_j^H(t) = [h_{j1}(t) \ h_{j2}(t)]$ is the concatenated channel vector from the two TXs to RX- j , $z_j(t) \sim \mathcal{N}_{\mathbb{C}}(0, 1)$ is the normalized additive white Gaussian noise at RX- j , $\mathbf{x}(t) = [x_1(t) \ x_2(t)]^T$ is the input signal, where x_i is sent from TX- i and subject to the power constraint $\mathbb{E} \|\mathbf{x}(t)\|^2 \leq P, \forall t$.

We assume the channel to be temporally-correlated. Under the first-order Gauss-Markov model, the channel evolves as [14]

$$\mathbf{h}_j(t) = \rho \mathbf{h}_j(t - \tau) - \sqrt{1 - \rho^2} \mathbf{e}(t) \quad (2)$$

where $\rho \triangleq \mathbb{E}[\mathbf{h}^H(t) \mathbf{h}(t - \tau)] \in [0, 1]$ is the channel correlation coefficient, and $\mathbf{e}(t)$ is a zero-mean unit-variance complex Gaussian process, i.i.d. across time. To “fit” the classical Clarke's isotropic scattering model [14, 15], we let $\rho = J_0(2\pi f_d \tau)$, where f_d is the Doppler spread, τ is the time lapse till the prediction, and $J_0(\cdot)$ is the zero-th order Bessel function of the first-kind.

B. CSI Feedback Model

The CSI feedback is first performed within one cell from RX to its own TX via a feedback link, followed by exchanging CSI between TXs over a backhaul link. We consider a symmetric setting such that there exist two kinds of delays in the CSI flow: the feedback delay, τ_{fb} , from the RX to its own TX, and the backhaul delay, τ_{bh} , between TXs. We define τ_{jk} as the total amount of delays from RX- j to TX- k , such that

$$\tau_{jk} = \begin{cases} \tau_{fb}, & j = k \\ \tau_{fb} + \tau_{bh}, & j \neq k \end{cases} \quad (3)$$

Further, τ_{fb} and τ_{bh} are assumed to be known at both TXs. The network model is schematized in Fig. 1.

At each time instant t , we assume TX- k knows perfectly \mathbf{h}_j with delay τ_{jk} , referred to as “delayed CSIT”. Based on the delayed feedback, TX- k predicts/estimates imperfectly the current channel $\mathbf{h}_j(t)$, which can be modeled as

$$\mathbf{h}_j(t) = \hat{\mathbf{h}}_j^{[k]}(t) + \tilde{\mathbf{h}}_j^{[k]}(t) \quad (4)$$

where the estimate $\hat{\mathbf{h}}_j^{[k]}(t)$ and estimation error $\tilde{\mathbf{h}}_j^{[k]}(t)$ are independent and assumed to be zero-mean and with variance $(1 - \sigma_{jk}^2), \sigma_{jk}^2$, respectively ($0 \leq \sigma_{jk}^2 \leq 1$).

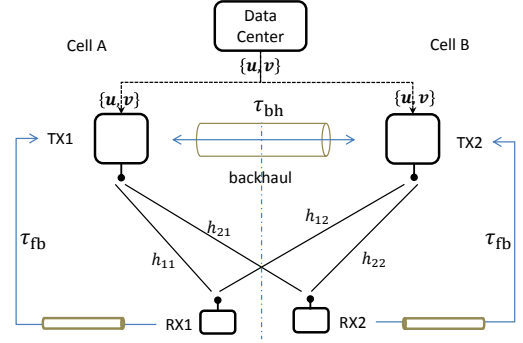


Fig. 1: Network model.

Using (2), we can then write the estimation error as

$$\sigma_{jk}^2(\tau_{jk}) = 1 - J_0^2(2\pi f_d \tau_{jk}), \quad (5)$$

where $J_0(\cdot)$ is a monotonic decreasing function of τ_{jk} in the region of interest such that larger delay τ_{jk} results in less correlation, and hence a larger estimation error $\sigma_{jk}^2(\tau_{jk})$. We are interested in the design requirements for the feedback and backhaul delays as function of the power P . If $\sigma_{jk}^2(\tau_{jk})$ decreases as $1/P$ or faster as P grows, the channel estimate is essentially perfect in terms of DoF and does not lead to any DoF loss even with conventional zero-forcing beamforming (ZFBF) [15]. On the contrary, if $\sigma_{jk}^2(\tau_{jk})$ decreases as or slower than P^0 , e.g., a constant estimation error, then the DoF collapses to zero [16]. Hence, to investigate the impact of the delay on the DoF, we assume that the estimation error $\sigma_{jk}^2(\tau_{jk})$ can be parameterized as an exponential function of the power P , e.g., $\sigma_{jk}^2(\tau_{jk}) \sim P^{-\alpha}$ for some $\alpha \in [0, 1]$. More specifically, we introduce a parameter $\alpha_{jk}(\tau_{jk}) \in [0, 1]$, such that

$$\alpha_{jk}(\tau_{jk}) \triangleq - \lim_{P \rightarrow \infty} \frac{\log \sigma_{jk}^2(\tau_{jk})}{\log P}, \quad (6)$$

to indicate the quality of current CSIT estimate known at high SNR.

In this paper, we consider the symmetric case as in (3) for simplicity, where the current CSIT $\mathbf{h}_j(t)$ is known by TX- k , i.e., $\hat{\mathbf{h}}_j^{[k]}(t)$, with quality of

$$\alpha_{jk}(\tau_{jk}) = \begin{cases} \alpha_1, & \tau_{jk} = \tau_{fb} \\ \alpha_2, & \tau_{jk} = \tau_{fb} + \tau_{bh} \end{cases} \quad (7)$$

where $0 \leq \alpha_2 < \alpha_1 \leq 1$. We henceforth use α_1 and α_2 to represent respectively the estimation quality of current CSIT with better (i.e. less delay) and worse (i.e. more delay) qualities.

III. EXPLOITING EITHER IMPERFECT CURRENT OR PURE DELAYED CSIT

Following the prediction step described in the previous section, we consider now that each TX has both access to the perfect delayed CSIT and an imperfect estimate of the

current CSIT. In the following, we first consider the two known solutions corresponding to the extreme cases where one exploits solely the imperfect current CSIT and the other one utilizes merely the perfect delayed one.

A. ZFBF with Imperfect Current CSIT

One extreme approach is to perform ZF beamforming by utilizing solely the imperfect current CSIT. As mentioned in the previous section, due to the backhaul delay, different TXs have access to the imperfect current CSIT with different estimation qualities. More specifically, TX- k applies ZFBF only based on its own channel estimates $\hat{\mathbf{h}}_1^{[k]}(t)$ and $\hat{\mathbf{h}}_2^{[k]}(t)$, and hence the effective precoder takes the form of

$$\mathbf{q}_i(t) = \begin{bmatrix} \left\{ \hat{\mathbf{h}}_i^{[1]}(t)^\perp \right\}_1 \\ \left\{ \hat{\mathbf{h}}_i^{[2]}(t)^\perp \right\}_2 \end{bmatrix} \quad (8)$$

where $\bar{i} = i \bmod 2 + 1$, and q_{i1} is from the first element of the orthogonal component of $\hat{\mathbf{h}}_i^{[1]}(t)$, whereas q_{i2} is from the second element of the orthogonal component of $\hat{\mathbf{h}}_i^{[2]}(t)$. With such beamformer, we have the following proposition.

Proposition 1. *For the two-cell Network MIMO with feed-back and backhaul delays, the conventional ZFBF based on the imperfect current CSIT achieves a sum DoF of*

$$\text{DoF}_{\text{ZF}} = 2 \min\{\alpha_1, \alpha_2\} = 2\alpha_2. \quad (9)$$

Proof: The result is directly obtained from [13], where $\mathbb{E}|\mathbf{h}_i^H(t)\mathbf{q}_i(t)|^2 \sim P^{-\alpha_2}$, and the residual interference is of power, e.g., $\mathbb{E}|\mathbf{h}_1^H(t)\mathbf{q}_2(t)v(t)|^2 \sim P^{1-\alpha_2}$ at RX-1, where $v(t)$ is the data symbol intended to RX-2 and satisfies $\mathbb{E}|v(t)|^2 \leq P$. Hence, the DoF for each RX is α_2 for symmetry. ■

The estimation error in either link reduces the DoF at both RXs, which is clearly a very detrimental property. Note furthermore that conventional robust precoding such as regularized ZFBF does not lead to any DoF improvement.

B. MAT Alignment with Delayed CSIT

In the other extreme, it has been recently shown in [8] that it is possible to achieve a larger DoF by exploiting solely the delayed CSIT in single-cell MISO BC by a three-slotted protocol (referred to as ‘‘MAT alignment’’). Since the delayed CSIT is equally available at both TXs, the MAT alignment can be applied in our setting with backhaul delay without any modification. For brevity, we describe solely in the following the main steps of a variant of the MAT alignment, which is detailed in [8, 9].

1) *Slot-1:* 4 symbols are sent jointly from the two TXs without precoding

$$\mathbf{x}(1) = \mathbf{u}(1) + \mathbf{v}(1) \quad (10)$$

where $\mathbf{u}(1), \mathbf{v}(1) \in \mathbb{C}^{2 \times 1}$ are each made of two user’s data symbols intended to RX-1 and RX-2, respectively, and

satisfy $\mathbb{E}\|\mathbf{u}(1)\|^2 = \mathbb{E}\|\mathbf{v}(1)\|^2 \leq P$. The interferences $\eta_1 \triangleq \mathbf{h}_1^H(1)\mathbf{v}(1)$ and $\eta_2 \triangleq \mathbf{h}_2^H(1)\mathbf{u}(1)$ are overheard at RX-1 and RX-2, respectively.

2) *Slot-2 & 3:* In these two slots, the overheard interferences are directly retransmitted by time division, i.e.,

$$\mathbf{x}(2) = \begin{bmatrix} \eta_1 \\ 0 \end{bmatrix}, \quad \mathbf{x}(3) = \begin{bmatrix} \eta_2 \\ 0 \end{bmatrix}. \quad (11)$$

The signal vector received over the three time slots at RX-1 is given by¹:

$$\mathbf{y}_1 = \underbrace{\begin{bmatrix} \mathbf{h}_1^H(1) \\ \mathbf{0} \\ h_{11}^*(3)\mathbf{h}_2^H(1) \end{bmatrix}}_{\text{rank}=2} \mathbf{u}(1) + \underbrace{\begin{bmatrix} \mathbf{h}_1^H(1) \\ h_{11}^*(2)\mathbf{h}_1^H(1) \\ \mathbf{0} \end{bmatrix}}_{\text{rank}=1} \mathbf{v}(1). \quad (12)$$

Note that the interference carrying $\mathbf{v}(1)$ is aligned in one-dimension, leaving 2-dimensional interference-free subspace for the desired signal $\mathbf{u}(1)$. Consequently, $\mathbf{u}(1)$ can be successfully recovered at RX-1. The same rule applies to RX-2 as well. Hence, the total 4 symbols are delivered over 3 time slots, yielding a sum DoF of

$$\text{DoF}_{\text{MAT}} = \frac{4}{3}. \quad (13)$$

Albeit fascinating in nature, MAT alignment cannot exploit the channel temporal correlation, no matter how perfect the current CSIT can be predicted from the past ones. This leads intuitively to the question: *Can the imperfect current CSIT be exploited together with the delayed one to gain larger DoF?*

IV. OPTIMAL USE OF BOTH DELAYED AND IMPERFECT CURRENT CSIT

A. The α -MAT Alignment

More recently, a modified MAT alignment developed in [9, 10] has been shown to optimally exploit both the delayed and imperfect current CSIT in terms of DoF in the single-cell two-user MISO BC. The differences with the original MAT alignment are two-fold. First, the imperfect current CSIT is exploited in Slot-1 to minimize the power of overheard interference. Particularly, by balancing the transmitting power of two symbols, with respective power P and $P^{1-\alpha}$, and aligning the symbol with higher power to the null space of the estimated current channel vector, the power of the overheard interference can be reduced from P to $P^{1-\alpha}$. Second, a *compressed/quantized* version of the overheard interferences are retransmitted in Slot-2 and Slot-3 by time division, allowing for new symbols being superposed on them to get extra DoF. We refer to this scheme as ‘‘ α -MAT alignment’’ hereafter.

¹The noise term is omitted hereafter for conciseness, since it does not matter in the sense of DoF.

B. The α -MAT Alignment in Network MIMO

When it comes to the two-cell network, however, such a scheme cannot be directly applied. With heterogeneous CSI delays, the TX in neighboring cell has access to a worse estimate of current CSIT than the TX in home cell. It results in two obstacles to the implementation of the α -MAT alignment: (1) how to zero-force the interference, and (2) how to retransmit the residual interference. For the first point, since the TXs do not share the same channel estimate, it is not clear how well the interference can be zero-forced. Regarding the second aspect, the overheard interferences η_k , $k = 1, 2$ can be reconstructed at any TX, only when the beamformer $\mathbf{q}_i(t)$ that contains the current channel estimate:

$$q_{ik}(t) = f_i(\{\hat{\mathbf{h}}_j^{[k]}(\tau), j = 1, 2\}_{\tau=1}^t) \quad (14)$$

is also available at TX- k , where $q_{ik}(t)$ is the k -th element of $\mathbf{q}_i(t)$. It is unfortunately not the case with heterogeneous CSI delays.

To overcome these two obstacles, we develop here a new version of the α -MAT alignment being more robust to the CSI discrepancy in this scenario.

1) *Slot-1*: With imperfect current CSIT, 4 symbols are sent from two TXs *with* precoding, such that

$$\mathbf{x}(1) = [\mathbf{p}_1(1) \ \mathbf{q}_1(1)]\mathbf{u}(1) + [\mathbf{p}_2(1) \ \mathbf{q}_2(1)]\mathbf{v}(1) \quad (15)$$

where $\mathbf{u}(1), \mathbf{v}(1) \in \mathbb{C}^{2 \times 1}$. The received signals are

$$\begin{aligned} y_1(1) &= \mathbf{h}_1^H(1)[\mathbf{p}_1(1) \ \mathbf{q}_1(1)]\mathbf{u}(1) + \underbrace{\mathbf{h}_1^H(1)[\mathbf{p}_2(1) \ \mathbf{q}_2(1)]\mathbf{v}(1)}_{\eta_1} \\ y_2(1) &= \underbrace{\mathbf{h}_2^H(1)[\mathbf{p}_1(1) \ \mathbf{q}_1(1)]\mathbf{u}(1)}_{\eta_2} + \mathbf{h}_2^H(1)[\mathbf{p}_2(1) \ \mathbf{q}_2(1)]\mathbf{v}(1) \end{aligned}$$

where $\mathbf{p}_i(t), \mathbf{q}_i(t) \in \mathbb{C}^{2 \times 1}$, $i = 1, 2$ are beamformers. While $\mathbf{p}_i(t)$ can be taken randomly, $\mathbf{q}_i(t)$ is designed to be a ZF-type beamformer for minimizing the power of overheard interferences η_k , $k = 1, 2$. The design of the ZF-type beamformer is a critical design parameter. With TXs having different CSI, this choice becomes non-trivial and is discussed in the following.

Conventional ZFBF: One of the possible choice consists in using the conventional ZFBF described in (8). Using the previous results, we know that $\mathbb{E}|\mathbf{h}_i^H(t)\mathbf{q}_i(t)|^2 \sim P^{-\alpha_2}$. The interference terms can then be written as $\eta_1 = \eta_{11} + \eta_{12}$ and $\eta_2 = \eta_{21} + \eta_{22}$ where

$$\eta_{11} = h_{11}^*(1) [p_{21}(1) \ q_{21}(1)] \mathbf{v}(1) \quad (16)$$

$$\eta_{12} = h_{12}^*(1) [p_{22}(1) \ q_{22}(1)] \mathbf{v}(1) \quad (17)$$

$$\eta_{21} = h_{21}^*(1) [p_{11}(1) \ q_{11}(1)] \mathbf{u}(1) \quad (18)$$

$$\eta_{22} = h_{22}^*(1) [p_{12}(1) \ q_{12}(1)] \mathbf{u}(1). \quad (19)$$

Let, for instance, η_1 and η_2 be generated by TX-2 and TX-1 respectively, the reconstruction of η_{11} at TX-2 and η_{22} at TX-1 is a problem.

To solve this problem, we resort to a modification of conventional ZFBF. Note that the TX- k possessing $\hat{\mathbf{h}}_k^{[k]}(t)$ (c.f. the estimate with less delay τ_{fb}), can somehow, e.g., waiting for a moment of τ_{bh} , estimate a worse version of $\mathbf{h}_k(t)$, i.e., $\hat{\mathbf{h}}_k^{[j]}(t)$, the estimate also held by TX- j , with estimation error of $P^{-\alpha_2}$. Thus, $\hat{\mathbf{h}}_k^{[j]}(t)$ is available at both TXs. Hence, the modified ZFBF can be designed as

$$\bar{\mathbf{q}}_1(t) = \begin{bmatrix} \left\{ \hat{\mathbf{h}}_2^{[1]}(t)^\perp \right\}_1 \\ \left\{ \hat{\mathbf{h}}_2^{[1]}(t)^\perp \right\}_2 \end{bmatrix} \quad \bar{\mathbf{q}}_2(t) = \begin{bmatrix} \left\{ \hat{\mathbf{h}}_1^{[2]}(t)^\perp \right\}_1 \\ \left\{ \hat{\mathbf{h}}_1^{[2]}(t)^\perp \right\}_2 \end{bmatrix} \quad (20)$$

making the interference power of $\mathbb{E}|\eta_k|^2 \sim P^{1-\alpha_2}$, determined by the worse quality of current CSIT.

Further, the interference terms in (16) and (19) become

$$\begin{aligned} \bar{\eta}_{11} &= h_{11}^*(1) [p_{21}(1) \ \bar{q}_{21}(1)] \mathbf{v}(1) \\ \bar{\eta}_{22} &= h_{22}^*(1) [p_{12}(1) \ \bar{q}_{12}(1)] \mathbf{u}(1) \end{aligned} \quad (21)$$

which are reconstructible at TX-2 and TX-1, respectively, such that η_k ($k = 1, 2$) can be retransmitted in the ensuing two slots.

Active/Passive-ZFBF: To improve over the conventional ZF beamforming, a so-called *Active/Passive ZFBF* (referred to as “A/P-ZFBF”) developed in [13] for the case of distributed CSIT can be applied here. Differently from the conventional ZFBF, the A/P-ZFBF takes the form of

$$\mathbf{q}_1(t) = \begin{bmatrix} 1 \\ -\frac{\hat{h}_{21}^{[2]*}(t)}{\hat{h}_{22}^{[2]*}(t)} \end{bmatrix} \quad \mathbf{q}_2(t) = \begin{bmatrix} -\frac{\hat{h}_{12}^{[1]*}(t)}{\hat{h}_{11}^{[1]*}(t)} \\ 1 \end{bmatrix} \quad (22)$$

where one element in $\mathbf{q}_i(t)$ is set independently of the channel realization and the other one is chosen so as to satisfy the orthogonality constraint. Thus, we have

$$\mathbb{E}|\mathbf{h}_1^H(t)\mathbf{q}_2(t)|^2 \quad (23)$$

$$= \mathbb{E} \left| \begin{bmatrix} \hat{h}_{11}^{[1]*}(t) + \tilde{h}_{11}^{[1]*}(t) & \hat{h}_{12}^{[1]*}(t) + \tilde{h}_{12}^{[1]*}(t) \end{bmatrix} \begin{bmatrix} -\frac{\hat{h}_{12}^{[1]*}(t)}{\hat{h}_{11}^{[1]*}(t)} \\ 1 \end{bmatrix} \right|^2$$

$$= \mathbb{E} \left| \tilde{h}_{11}^{[1]*}(t) \left(-\frac{\hat{h}_{12}^{[1]*}(t)}{\hat{h}_{11}^{[1]*}(t)} \right) + \tilde{h}_{12}^{[1]*}(t) \right|^2 \quad (24)$$

$$\sim P^{-\alpha_1}. \quad (25)$$

Symmetrically, it also holds $\mathbb{E}|\mathbf{h}_2^H(t)\mathbf{q}_1(t)|^2 \sim P^{-\alpha_1}$. Hence, the power of the interference has been reduced to $\mathbb{E}|\eta_k|^2 \sim P^{1-\alpha_1}$.

Recall that $\mathbf{q}_1(t)$ only depends on $\hat{\mathbf{h}}_2^{[2]}(t)$ and $\mathbf{q}_2(t)$ only on $\hat{\mathbf{h}}_1^{[1]}(t)$. Thus, the interference overheard by both RXs, which can be written as

$$\begin{aligned} \eta_1 &= \mathbf{h}_1^H(1)\mathbf{q}_2(1)\mathbf{v}(1) \\ \eta_2 &= \mathbf{h}_2^H(1)\mathbf{q}_1(1)\mathbf{u}(1) \end{aligned} \quad (26)$$

are reconstructible at TX-1 and TX-2, respectively.

2) *Slot-2 & 3*: Instead of forwarding η_k ($k = 1, 2$) directly, we quantize them to $\hat{\eta}_k$ ($k = 1, 2$) with source codebook size $(1 - \alpha) \log P$ bits each, which makes the quantization error negligible provided that the power of η_k ($k = 1, 2$) is smaller or equal to $P^{1-\alpha}$ [9]. Subsequently, we can retransmit their indices, denoted by c_k ($k = 1, 2$), in a digital fashion, expecting less channel resource to be consumed.

The Slot-2 and 3 consist of the broadcasting of the digitalized interferences $\hat{\eta}_1$ and $\hat{\eta}_2$ where in addition to this broadcasting new private symbols are sent with a power such that they do not lead to any additional interference. Here, we face with the same problem of how to design the ZF-type beamformer as in Slot-1. For instance with A/P-ZFBBF, together with the codewords of the digitalized interferences c_k ($k = 1, 2$) (c.f. common message) with rate $(1 - \alpha_1) \log P$ but power P , another precoded fresh symbols (c.f. private message) are sent with rate $\alpha_1 \log P$ and power scaling as P^{α_1} . Then, the common and private messages are encoded by using superposition coding techniques [17], i.e.,

$$\text{ZFBBF: } \begin{cases} \mathbf{x}(2) = \begin{bmatrix} 0 \\ c_1 \end{bmatrix} + \bar{\mathbf{q}}_2(2)u(2) + \bar{\mathbf{q}}_1(2)v(2) \\ \mathbf{x}(3) = \begin{bmatrix} c_2 \\ 0 \end{bmatrix} + \bar{\mathbf{q}}_2(3)u(3) + \bar{\mathbf{q}}_1(3)v(3) \end{cases} \quad (27)$$

$$\text{A/P-ZFBBF: } \begin{cases} \mathbf{x}(2) = \begin{bmatrix} c_1 \\ 0 \end{bmatrix} + \mathbf{q}_2(2)u(2) + \mathbf{q}_1(2)v(2) \\ \mathbf{x}(3) = \begin{bmatrix} 0 \\ c_2 \end{bmatrix} + \mathbf{q}_2(3)u(3) + \mathbf{q}_1(3)v(3) \end{cases} \quad (28)$$

where $u(t), v(t)$ ($t = 2, 3$) are private messages intended to RX-1 and RX-2 respectively, with rate $\alpha_1 \log P$ each and power constraint $\mathbb{E}|u(t)|^2 = \mathbb{E}|v(t)|^2 \leq P^{\alpha_1}$.

In Slot-2, the received signals are given by (those in Slot-3 can be similarly obtained)

$$\begin{aligned} y_1(2) &= \underbrace{h_{11}^*(2)c_1}_P + \underbrace{h_{11}^*(2)\mathbf{q}_1(2)u(2)}_{P^{\alpha_1}} + \underbrace{h_{11}^*(2)\mathbf{q}_2(2)v(2)}_{P^0} \\ y_2(2) &= \underbrace{h_{21}^*(2)c_1}_P + \underbrace{h_{21}^*(2)\mathbf{q}_1(2)u(2)}_{P^0} + \underbrace{h_{21}^*(2)\mathbf{q}_2(2)v(2)}_{P^{\alpha_1}} \end{aligned}$$

Applying successive decoding², the common message (c.f. c_1) is first decoded, followed by the private message (c.f. $u(2)$ for RX-1 and $v(2)$ for RX-2). Thus, a extra DoF of α_1 from each symbol $u(2), v(2)$ is yielded. Then, the overheard interference η_k can be reconstructed from c_k with the distortion error drown in the noise [9]. Note that η_k provides not only the interference cancelation for one RX, but also another linearly independent equation for the other RX, making $\mathbf{u}(1)$ and $\mathbf{v}(1)$ retrievable, and hence, yielding

²The common message is firstly decoded by treating other lower power interferences as noise, then with its entire term reconstructed and subtracted from the received signal, and finally the private message is subsequently decoded from the remaining signal [17].

$2 - \alpha_1$ DoF for each RX. As a result, all the data symbols can be decoded such that each RX obtains $2 - \alpha_1 + 2\alpha_1 = 2 + \alpha_1$ DoF over three slots. To sum up, we have the following results:

Proposition 2. *For the two-cell Network MIMO with feedback and backhaul delays, the conventional ZFBBF and A/P-ZFBBF with both delayed and imperfect current CSIT achieve sum DoF of, respectively,*

$$\text{DoF}_{\alpha\text{-MAT}}^{\text{ZF}} = \frac{4 + 2 \min\{\alpha_1, \alpha_2\}}{3} = \frac{4 + 2\alpha_2}{3} \quad (29)$$

$$\text{DoF}_{\alpha\text{-MAT}}^{\text{A/P-ZF}} = \frac{4 + 2 \max\{\alpha_1, \alpha_2\}}{3} = \frac{4 + 2\alpha_1}{3}. \quad (30)$$

It is worth noting that the sum DoF with conventional ZFBBF limited by the worst quality of current CSIT (c.f. longest delay), while that with A/P-ZFBBF is solely determined by the least delayed version, meaning that the impact of the backhaul delay could be mitigated³.

In fact, A/P-ZFBBF also verifies the following result.

Theorem 1 (Optimal DoF Region). *The A/P-ZFBBF achieves the optimal DoF region for the two-cell Network MIMO with feedback and backhaul delays, which can be characterized by*

$$\begin{aligned} d_1 &\leq 1 \\ d_2 &\leq 1 \\ 2d_1 + d_2 &\leq 2 + \max\{\alpha_1, \alpha_2\} \\ d_1 + 2d_2 &\leq 2 + \max\{\alpha_1, \alpha_2\}. \end{aligned} \quad (31)$$

Proof: See Appendix. ■

V. NUMERICAL RESULTS

In the following, we provide simulations to verify the efficiency of the proposed schemes. We consider a temporally-correlated rayleigh fading channel and average the sum rate in bits/s/Hz over 1000 random channel realizations. The qualities of imperfect current CSIT are set to be $\alpha_1 = 1$ and $\alpha_2 = 0.5$. In Fig. 2, the sum rate curves of the aforementioned schemes (i.e., conventional ZFBBF, MAT-alignment, and the α -MAT alignment with conventional ZFBBF and A/P-ZFBBF) are plotted with regard to SNR. We also provide the sum rate of conventional ZFBBF with perfect CSIT for comparison. As shown in the figure, the α -MAT alignment with conventional ZFBBF achieves a better DoF (slope of sum rate curve at high SNR) than the original MAT alignment but is limited by the estimation quality with the longest delay (i.e., α_2), while the A/P-ZFBBF achieves the maximal DoF of 2 (i.e., holding the same slope as the perfect CSIT case), since it is solely determined by the best accuracy (i.e., $\alpha_1 = 1$) of the current CSIT estimate.

³The A/P-ZFBBF is better in the sense of DoF, however, it meets some practical issues, e.g., power unbalance, which are addressed in [13].

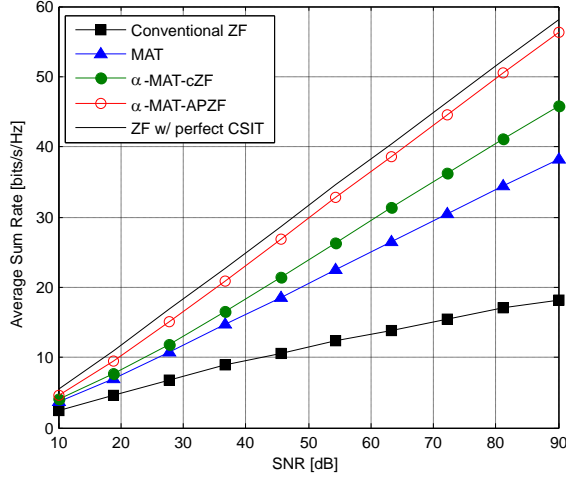


Fig. 2: Average Sum Rate vs. SNR.

VI. CONCLUSION

We address the performance of Network MIMO accounting for the practical constraint that CSI sharing over the backhaul entails additional delays compared with the over-the-air feedback delay. We show that conventional strategies, including recent delayed CSIT-based schemes, fail to maximize DoF. An alternative optimal strategy is given for the specific two-cell case.

APPENDIX

A. Achievability

The achievability is provided by the α -MAT alignment with A/P-ZFBBF, where the vertices $(1, \max\{\alpha_1, \alpha_2\})$, $(\max\{\alpha_1, \alpha_2\}, 1)$ and $(\frac{2+\max\{\alpha_1, \alpha_2\}}{3}, \frac{2+\max\{\alpha_1, \alpha_2\}}{3})$ are achievable.

As the vertex $(\frac{2+\max\{\alpha_1, \alpha_2\}}{3}, \frac{2+\max\{\alpha_1, \alpha_2\}}{3})$ is demonstrated to be achievable in the previous section, in the following, we present the achievable scheme for the vertex $(1, \max\{\alpha_1, \alpha_2\})$. This vertex can be achieved within one single slot. The transmission with superposition coding can be given by

$$\mathbf{x} = \begin{bmatrix} u_c \\ 0 \end{bmatrix} + \mathbf{q}_2 u_p + \mathbf{q}_1 v_p \quad (32)$$

where u_c is a common message and decodable by both RXs but only desirable by RX-1, and u_p , v_p are private messages which can only be seen and decoded by their corresponding RXs. These transmitted symbols are assumed to satisfy the power constraints $\mathbb{E}|u_c|^2 \leq P$ with rate $(1 - \alpha_1) \log P$, and $\mathbb{E}|u_p|^2 = \mathbb{E}|v_p|^2 \leq P^{\alpha_1}$ with each symbol of rate $\alpha_1 \log P$. At the receiver side, similarly to the procedure in Slot-2 & 3, both the common (c.f. u_c) and private (c.f. u_p , v_p) messages can be subsequently decoded by successive decoding, yielding total 1 and $\max\{\alpha_1, \alpha_2\}$ DoF for Rx-1 and Rx-2, respectively.

By swapping the roles of two RXs, its counterpart $(\max\{\alpha_1, \alpha_2\}, 1)$ can be similarly achieved. Hence, with all the vertices achievable, the entire DoF region can be achieved by time sharing.

B. Converse

Before proceeding further, we present the definition of DoF region.

We denote $\mathbf{H} = \{\mathbf{h}_1, \mathbf{h}_2\}$ and $\hat{\mathbf{H}}^{[k]}(t) \triangleq \{\hat{\mathbf{h}}_1^{[k]}(t), \hat{\mathbf{h}}_2^{[k]}(t)\}$. A $(2^{nR_1}, 2^{nR_2}, n)$ code scheme is defined to be comprise of:

- two message sets, from which two independent messages W_1 and W_2 intended respectively to the RX-1 and RX-2 are uniformly chosen;
- one encoding function at k -th BS:

$$x_k(t) = f_k \left(W_1, W_2, \{\mathbf{h}_j(\tau)\}_{\tau=1}^{t-\tau_{jk}}, \{\hat{\mathbf{H}}^{[k]}(\tau)\}_{\tau=1}^t, j = 1, 2 \right)$$

which means the TX can have access to the delayed CSIT of its served RX with less delay and imperfect current CSIT with higher quality;

- and one decoding function at j -th RX:

$$\hat{W}_j = g_j \left(\{y_j(t)\}_{t=1}^n, \{\mathbf{H}(t)\}_{t=1}^n, \{\hat{\mathbf{H}}^{[k]}(t), k = 1, 2\}_{t=1}^n \right)$$

A rate pair (R_1, R_2) is said to be achievable if there exists a code scheme $(2^{nR_1}, 2^{nR_2}, n)$, such that the average decoding error probability $P_e^{(n)}$, defined as $P_e^{(n)} \triangleq \mathbb{P} \left((W_1, W_2) \neq (\hat{W}_1, \hat{W}_2) \right)$ vanishes as the code length $n \rightarrow \infty$. The capacity region \mathcal{C} is defined as the set of all achievable rate pairs. Accordingly, we have the following definition:

Definition 1 (the DoF region). *The DoF region for two-cell network MIMO is defined as*

$$\mathcal{D} = \left\{ (d_1, d_2) \in \mathbb{R}_+^2 \mid \forall (w_1, w_2) \in \mathbb{R}_+^2, w_1 d_1 + w_2 d_2 \leq \limsup_{P \rightarrow \infty} \left(\sup_{(R_1, R_2) \in \mathcal{C}} \frac{w_1 R_1 + w_2 R_2}{\log P} \right) \right\}.$$

where R_i , d_i are the achievable rate and DoF for the i -th RX, respectively.

To obtain the outer bound, we follow the strategy reminiscenced in [9] to obtain the genie-aided outer bound, by assuming that (a) TX-1 and TX-2 are perfectly cooperated to form a virtual BC, and (c) the RX-2 has the instantaneous knowledge of the RX-1's received signal $y_1(t)$ and also W_1 . According to the techniques developed in [9], we have the following lemmas:

Lemma 1 (weighted sum rate bounds [9]). *The weighted sum rate of two RXs for the genie-aided model can be bounded as*

$$n(2R_1 + R_2) \leq 2n \log P + \sum_{t=1}^n (h(y_1(t), y_2(t) | \mathcal{U}(t), \mathbf{H}(t)))$$

$$-2h(y_1(t)|\mathcal{U}(t), \mathbf{H}(t))) + n \cdot O(1) + n\epsilon_n$$

where

$$\mathcal{U}(t) \triangleq \{ \{y_1(k)\}_{k=1}^{t-1}, \{y_2(k)\}_{k=1}^{t-1}, \{ \mathbf{H}(\tau) \}_{\tau=1}^{t-1}, \{ \hat{\mathbf{H}}^{[1]}(\tau) \}_{\tau=1}^t, \{ \hat{\mathbf{H}}^{[2]}(\tau) \}_{\tau=1}^t, W_1 \}.$$

Lemma 2 (extremal inequality [9]). *The weighted difference of two differential entropies above can be further bounded as*

$$\begin{aligned} & h(y_1(t), y_2(t)|\mathcal{U}(t), \mathbf{H}(t)) - 2h(y_1(t)|\mathcal{U}(t), \mathbf{H}(t)) \\ & \leq \mathbb{E}_{\hat{\mathbf{h}}_1^{[1]}, \hat{\mathbf{h}}_1^{[2]}, \hat{\mathbf{h}}_2^{[1]}, \hat{\mathbf{h}}_2^{[2]}} \max_{\mathbf{K} \succeq 0, \text{tr}(\mathbf{K}) \leq P} \left(\mathbb{E}_{\hat{\mathbf{h}}_1^{[1]}, \hat{\mathbf{h}}_1^{[2]}} \log(1 + \mathbf{h}_1^H \mathbf{K} \mathbf{h}_1) \right. \\ & \quad \left. - \mathbb{E}_{\hat{\mathbf{h}}_2^{[1]}, \hat{\mathbf{h}}_2^{[2]}} \log(1 + \mathbf{h}_2^H \mathbf{K} \mathbf{h}_2) \right) \end{aligned} \quad (33)$$

$$\leq \max\{\alpha_1, \alpha_2\} \log P + O(1) \quad (34)$$

where \mathbf{K} is the covariance matrix of channel input.

Proof: The proof can be straightforwardly extended from [9] but with a little modification. The upper bound takes the looser form as in [9], i.e.,

$$\mathbb{E}_{\hat{\mathbf{h}}_1^{[1]}, \hat{\mathbf{h}}_1^{[2]}} \log(1 + \mathbf{h}_1^H \mathbf{K} \mathbf{h}_1) \quad (35)$$

$$\leq \log(1 + \max\{\|\hat{\mathbf{h}}_1^{[1]}\|^2, \|\hat{\mathbf{h}}_1^{[2]}\|^2\} \lambda_1) + O(1) \quad (36)$$

while the lower bound can be further loosed as

$$\mathbb{E}_{\hat{\mathbf{h}}_2^{[1]}, \hat{\mathbf{h}}_2^{[2]}} \log(1 + \mathbf{h}_2^H \mathbf{K} \mathbf{h}_2) \quad (37)$$

$$\geq \log(1 + 2^\gamma \min\{\sigma_{kk}^2, \sigma_{jk}^2\} \lambda_1) + O(1) \quad (38)$$

$$= \log(1 + 2^\gamma \sigma_{kk}^2 \lambda_1) + O(1) \quad (39)$$

where $j \neq k$, $\sigma_{kk}^2 \sim P^{-\max\{\alpha_1, \alpha_2\}}$, and γ defined in [9] is finite. Substituting the above upper and lower bounds into (33), we obtain

$$\begin{aligned} & \mathbb{E}_{\hat{\mathbf{h}}_1^{[1]}, \hat{\mathbf{h}}_1^{[2]}} \log(1 + \mathbf{h}_1^H \mathbf{K} \mathbf{h}_1) - \mathbb{E}_{\hat{\mathbf{h}}_2^{[1]}, \hat{\mathbf{h}}_2^{[2]}} \log(1 + \mathbf{h}_2^H \mathbf{K} \mathbf{h}_2) \\ & \leq \log(1 + \max\{\|\hat{\mathbf{h}}_1^{[1]}\|^2, \|\hat{\mathbf{h}}_1^{[2]}\|^2\} \lambda_1) - \log(1 + 2^\gamma \sigma_{kk}^2 \lambda_1) \end{aligned} \quad (40)$$

$$\leq \log \left(1 + \frac{\max\{\|\hat{\mathbf{h}}_1^{[1]}\|^2, \|\hat{\mathbf{h}}_1^{[2]}\|^2\}}{2^\gamma \sigma_{kk}^2} \right) + O(1) \quad (41)$$

$$\leq -\log(\sigma_{kk}^2) + O(1) \quad (42)$$

where (40) follows the inequality $\log\left(\frac{1+a}{1+b}\right) \leq \log\left(1 + \frac{a}{b}\right)$, $\forall a, b > 0$, and (42) is obtained by noticing $0 \leq \sigma_{kk}^2 \leq 1$. This completes the proof. ■

Hence, we have

$$2R_1 + R_2 \leq (2 + \max\{\alpha_1, \alpha_2\}) \log P + O(1) + \epsilon_n$$

The weighted DoF bound can be obtained according to the definition. It applies to another bound by swapping the role of RX-1 and RX-2.

REFERENCES

- [1] M. K. Karakayali, G. J. Foschini, and R. A. Valenzuela, "Network coordination for spectrally efficient communications in cellular systems," *IEEE Wireless Communications*, vol. 13, no. 4, pp. 56–61, Aug. 2006.
- [2] D. Gesbert, S. Hanly, H. Huang, S. Shamai, O. Simeone, and W. Yu, "Multi-cell mimo cooperative networks: A new look at interference," *IEEE Journal on Sel. Areas in Communications*, vol. 28, no. 9, pp. 1380–1408, Dec. 2010.
- [3] M. A. Maddah-Ali, A. S. Motahari, and A. K. Khandani, "Communication over MIMO X channels: interference alignment, decomposition, and performance analysis," *IEEE Trans. Inf. Theory*, vol. 54, no. 8, pp. 3457–3470, Aug. 2008.
- [4] V. Cadambe and S. Jafar, "Interference alignment and degrees of freedom of the K-user interference channel," *IEEE Trans. Inf. Theory*, vol. 54, pp. 3425–3441, Aug. 2008.
- [5] E. Jorswieck, E. Larsson, and D. Danev, "Complete characterization of the Pareto boundary for the MISO interference channel," *IEEE Trans. Sig. Process.*, vol. 56, no. 10, pp. 5292–5296, Oct. 2008.
- [6] D. J. Love, R. W. Heath Jr., V. K. N. Lau, D. Gesbert, B. D. Rao, and M. Andrews, "An overview of limited feedback in wireless communication systems," *IEEE J. Select. Areas Commun.*, vol. 26, no. 8, pp. 1341–1365, Oct. 2008.
- [7] R. Bhagavatula and R. W. Heath, Jr., "Adaptive bit partitioning for multicell intercell interference nulling with delayed limited feedback," *IEEE Trans. Signal Processing*, vol. 59, no. 8, pp. 3824–3836, Aug. 2011.
- [8] M. Maddah-Ali and D. Tse, "Completely stale transmitter channel state information is still very useful," *IEEE Trans. Inf. Theory*, vol. 58, no. 7, pp. 4418–4431, Jul. 2012.
- [9] S. Yang, M. Kobayashi, D. Gesbert, X. Yi, "Degrees of freedom of time correlated MISO broadcast channel with delayed CSIT," *to appear in IEEE Trans. Inf. Theory*, Arxiv preprint arXiv:1203.2550, March 2012.
- [10] T. Gou and S. A. Jafar, "Optimal use of current and outdated channel state information—Degrees of freedom of the MISO BC with mixed CSIT," *IEEE Communications Letters*, vol. 16, no. 7, Jul. 2012, pp. 1084–1087.
- [11] H. Maleki, S. A. Jafar, and S. Shamai, "Retrospective interference alignment over interference networks," *IEEE Journal of Selected Topics in Signal Processing*, vol. 6, no. 3, pp. 228–240, Jun. 2012.
- [12] J. Xu, J. Andrews, and S. Jafar, "MISO broadcast channels with delayed finite-rate feedback: Predict or observe?" *IEEE Trans. Wireless Commun.*, vol. 11, no. 4, pp. 1456–1467, Apr. 2012.
- [13] P. de Kerret, D. Gesbert, "The Degree of Freedom of the network MIMO channel with distributed CSI," *to appear in IEEE Trans. Inf. Theory*, Arxiv preprint arXiv: 1108.3742, Jun. 2012.
- [14] D. Tse and P. Viswanath, *Fundamentals of Wireless Communication*. Cambridge, U.K.: Cambridge Univ. Press, 2005.
- [15] G. Caire, N. Jindal, M. Kobayashi, and N. Ravindran, "Multiuser MIMO achievable rates with downlink training and channel state feedback," *IEEE Trans. Inf. Theory*, vol. 56, no. 6, pp. 2845–2866, June 2010.
- [16] J. Zhang, M. Kountouris, J. G. Andrews, and R. W. Heath Jr., "Multi-mode transmission for the MIMO broadcast channel with imperfect channel state information," *IEEE Trans. Commun.*, vol. 59, no. 3, pp. 803–814, Mar. 2011.
- [17] T. Cover and J. Thomas, *Elements of Information Theory*, New York: Wiley, 2006.
- [18] X. Yi, P. de Kerret and D. Gesbert, "The DoF of network MIMO with backhaul delays," *submitted to IEEE ICC 2013*, Oct. 2012.