

Errata for “Comments on Truncation Errors for Polynomial Chaos Expansions”

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Abstract—We fix errata encountered in letter T. Mühlpfordt *et al.* “Comments on truncation errors for polynomial chaos expansions,” *IEEE Control Systems Letters*, 2.1, Jan. 2018, pp. 169–174.

I. PROOF OF THEOREM 1

The content of Theorem 1 remains untouched. It is only its preceding assumption and the proof itself that we rectify.

First, we make Assumption 1 more precise.

Assumption 1 (Exact PCE Input): For a given n_ξ -variate orthogonal polynomial basis $\{\phi_j\}_{j=0}^{\ell_z}$, the PCE of the real-valued random variable $\mathbf{z} \in L^2(\Omega, \mu; \mathbb{R})$ has the known and finite minimum degree $d_z \in \mathbb{N}_0$, and $\ell_z + 1 \geq (n_\xi + d_z)! / (n_\xi! d_z!)$ PCE coefficients, see (6). Unless stated otherwise we assume $\ell_z + 1 = (n_\xi + d_z)! / (n_\xi! d_z!)$.

With this we correct the proof of Theorem 1 as follows.

Proof: The PCE for \mathbf{z}_i is given by

$$\mathbf{z}_i = \sum_{j=0}^{\ell_z} z_{i,j} \phi_j,$$

where $\ell_z + 1 = (n_\xi + d_z)! / (n_\xi! d_z!)$. Without loss of generality we assume that

$$f(\mathbf{z}_1, \dots, \mathbf{z}_{n_z}) = \mathbf{z}_1^{\alpha_1} \cdots \mathbf{z}_{n_z}^{\alpha_{n_z}} + \dots,$$

where $\alpha = [\alpha_1 \cdots \alpha_{n_z}]^\top \in \mathbb{N}_0^{n_z}$ is a multi-index with $|\alpha| = d_f$. We insert the PCE for every \mathbf{z}_i

$$\begin{aligned} & f\left(\sum_{j=0}^{\ell_z} z_{1,j} \phi_j, \dots, \sum_{j=0}^{\ell_z} z_{n_z,j} \phi_j\right) \\ &= \left(\sum_{j=0}^{\ell_z} z_{1,j} \phi_j\right)^{\alpha_1} \cdots \left(\sum_{j=0}^{\ell_z} z_{n_z,j} \phi_j\right)^{\alpha_{n_z}} + \dots \\ &= \gamma \xi_1^{\beta_1} \cdots \xi_{n_\xi}^{\beta_{n_\xi}} + \dots, \end{aligned}$$

where γ is some constant, and the multi-index $\beta = [\beta_1 \cdots \beta_{n_\xi}]^\top \in \mathbb{N}_0^{n_\xi}$ satisfies $d_z |\alpha| = d_z d_f$. Hence, the highest-degree polynomial term of \mathbf{y} has degree $d_z d_f$, yielding a total number of $\ell + 1$ basis elements given by (6) with $d \leftarrow d_z d_f$, thus enlarging the basis by $\ell - \ell_z$ elements. The orthogonal projection of \mathbf{y} onto \mathbf{Z} yields $\mathbf{P}_n \mathbf{y} = \sum_{j=0}^n y_j \phi_j$. Consequently, the truncation error \mathbf{e}_n becomes $\mathbf{e}_n = \sum_{j=n+1}^{\ell} y_j \phi_j$, which is zero in case of $n \geq \ell$. For $n < \ell$, apply Parseval's identity to obtain $\|\mathbf{e}_n\|$ (equation (9) in the original reference [1]), see [2]. ■

II. PROOF OF THEOREM 2

The first part of Theorem 2 was misleading. We revise Theorem 2 as follows.

Theorem 2 (Uncertainty Quantification for Problem 1): For all realizations of \mathbf{z} , let the active constraints in Problem 1 satisfy the linear inequality constraint qualification (LICQ) at the optimal solution \mathbf{y} . If the set of active constraints $\mathcal{A} = \{a_1, \dots, a_{n_{\text{act}}}\} \subseteq \{1, \dots, n_{\text{con}}\}$ is the same for all realizations of $\mathbf{z} = [\mathbf{h}^\top \ \mathbf{b}^\top]^\top$, then the element-wise truncation error becomes

$$\|\mathbf{y}_i - \mathbf{P}_n \mathbf{y}_i\| = \begin{cases} \sqrt{\sum_{j=n+1}^d (w_i^h h_j + w_i^b b_j)^\top M_{\mathcal{A}} b_j} \|\phi_j\|^2, & \text{if } n < d, \\ 0, & \text{if } n \geq d, \end{cases}$$

where w_i^h , w_i^b are the i th rows with $i = 1, \dots, n_\chi$ of the matrices W^h , W^b that satisfy

$$\begin{bmatrix} W^h & W^b \\ V^h & V^b \end{bmatrix} = - \begin{bmatrix} H & A^\top M_{\mathcal{A}}^\top \\ M_{\mathcal{A}} A & 0 \end{bmatrix}^{-1}.$$

The active constraint selection matrix $M_{\mathcal{A}} \in \mathbb{N}_0^{n_{\text{act}} \times n_{\text{con}}}$ is constructed from the active set \mathcal{A} and has elements $(M_{\mathcal{A}})_{ia_i} = 1$ for $i = 1, \dots, n_{\text{act}}$, zero elsewhere.

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Proof: Because the set of active constraints is supposed to be \mathcal{A} for all realizations, the Karush-Kuhn-Tucker conditions hold in terms of a function of random variables

$$\begin{bmatrix} \mathbf{y} \\ \lambda^* \end{bmatrix} = \begin{bmatrix} W^h & W^b \\ V^h & V^b \end{bmatrix} \begin{bmatrix} \mathbf{h} \\ M_{\mathcal{A}}\mathbf{b} \end{bmatrix},$$

where (2) and $\mathbf{z} = [\mathbf{z}_1^\top \mathbf{z}_2^\top]^\top = [\mathbf{h}^\top \mathbf{b}^\top]^\top$ are used. Invertibility follows from LICQ. Consequently for all $i = 1, \dots, n_\chi$,

$$y_i = w_i^{h^\top} \mathbf{h} + w_i^{b^\top} M_{\mathcal{A}}\mathbf{b} = \sum_{j=0}^d (w_i^{h^\top} h_j + w_i^{b^\top} M_{\mathcal{A}} b_j) \phi_j,$$

and the result follows from Theorem 1 with $d_f = 1$. ■

With the new version of Theorem 2, the related remark reads.

Remark 2 (Extension to Changes in the Active Set): Note that even if the active set changes, Theorem 2 still holds locally on a polytope. Recall that multiparametric QPs admit locally affine solutions defined on polytopes [3]. Furthermore, the error description from can be turned into an upper bound by considering the *worst case* active set, which maximizes $\|\mathbf{y}_i - \mathbf{P}_n \mathbf{y}_i\|$. Due to space limitations, we leave the details to future work.

REFERENCES

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