

Comments and Corrections

Corrections to “UWB-VIO Fusion for Accurate and Robust Relative Localization of Round Robotic Teams”

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There is a wrong word in the title, which needs to be changed from “Round” to “Ground”.

The original title is “UWB-VIO Fusion for Accurate and Robust Relative Localization of Round Robotic Teams”.

The correct title should be “UWB-VIO Fusion for Accurate and Robust Relative Localization of Ground Robotic Teams”.

REFERENCE

- [1] S. Zheng et al., “UWB-VIO fusion for accurate and robust relative localization of round robotic teams,” *IEEE Robot. Automat. Lett.*, vol. 7, no. 4, pp. 11950–11957, Oct. 2022.

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