# How Many Beamforming Vectors Generate the Same Beampattern? 

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#### Abstract

In this letter, we address the fundamental question of how many beamforming vectors exist which generate the same beampattern? The question is relevant to many fields such as, for example, array processing, radar, wireless communications, data compression, dimensionality reduction, and biomedical engineering. The desired property of having the same beampattern for different columns of a beamspace transformation matrix (beamforming vectors) often plays a key importance in practical applications. The result is that at most $2^{M-1}-1$ beamforming vectors with the same beampattern can be generated from any given beamforming vector. Here $M$ is the dimension of the beamforming vector. At the constructive side, the answer to this question allows for computationally efficient techniques for the beamspace transformation design. Indeed, one can start with a single beamforming vector, which gives a desired beampattern, and generate a number of other beamforming vectors, which give absolutely the same beampattern, in a computationally efficient way. We call the initial beamforming vector as the mother beamforming vector. One possible procedure for generating all possible new beamforming vectors with the same beampattern from the mother beamforming vector is proposed. The application of the proposed analysis to the transmit beamspace design in multiple-input multiple-output radar is also given.


## Index Terms

Array processing, beamforming, beampattern design, dimensionality reduction, multiple-input multipleoutput (MIMO) radar.

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## I. Introduction

Beamspace transformation [1], [2] and beamforming [3] techniques are the key approaches, among others, in array signal processing [4]-[6], radar [7], multiple-input multiple-output (MIMO) radar [8]-[21], wireless communications [22]-[24], data compression and dimensionality reduction [25]-[27], biomedical engineering [28], etc.

In the traditional applications in array processing and dimensionality reduction, it is often desirable to reduce the high dimensional space into a lower one by means of the beamspace transformations. In more recent applications to MIMO radar, it has been required not only to design a lower dimensional transmit beamspace but also to transmit a number of orthogonal waveforms from a larger number of transmit antenna elements while achieving transmit coherent processing gain. While designing such a transmit beamspace, certain properties have to be satisfied such as a uniform power distribution for different transmit waveforms in the desired sector where the targets are likely to be located [19]. The latter enables, for example, to enforce at the transmitter the very useful rotational invariance property [29], [30] which can significantly simplify and improve, for example, the direction-of-arrival (DOA) estimation techniques used at the receive antenna array.

From a practical point of view, generating a transmit beamspace that satisfies a number of properties is very desirable. Thus, it is of interest to look for simple design techniques allowing to start with a single beamforming vector, which we call the mother beamforming vector by analogy with mother wavelet [31] in wavelet analysis, and generate a number of other beamforming vectors that all have the same beampattern as the mother beamforming vector. Beamforming vectors that possibly satisfy some additional practically important properties can then be selected from a set of so generated beamforming vectors. In wavelets, self-similarity is an important property where basis functions are all obtained from a single prototype mother wavelet using scaling and translation. It is interesting that a similar property exists also in the beamspace design problem. To the best of the authors knowledge, this property has not been known or exploited before.

The contributions of this letter are as following.

- We first address the fundamental question of how many beamforming vectors which generate the same beampattern as the mother beamforming vector exist.
- At the constructive side, we develop a computationally efficient technique for generating all such beamforming vectors.
- The application of the proposed analysis to the transmit beamspace design in MIMO radar is also given.

The rest of the letter is organized as follows. The main results on the number of beamforming vectors, which have the same beampattern as the mother beamforming vector, and on the procedure of constructing such beamforming vectors are given in Section II. Section III is devoted to the application of the proposed analysis to the transmit beamspace design in MIMO radar, which aims at demonstrating the practical usefulness of the results obtained in Section II. The letter is completed with conclusion.

## II. Main Results

Let us consider a uniform linear array (ULA) with $M$ antenna elements. The steering vector of the array towards direction $\theta$ is denoted as $\mathbf{a}(\theta)$. The transmit array beampattern can be expressed as

$$
\begin{equation*}
p(\theta)=\left\|\mathbf{w}^{H} \mathbf{d}(\theta)\right\|^{2} \tag{1}
\end{equation*}
$$

where $\mathbf{w}$ is a beamforming vector, $\mathbf{d}(\theta)=\mathbf{a}^{*}(\theta)$, and $\|\cdot\|$ and $(\cdot)^{*}$ stand for the Euclidian norm of a vector and conjugation, respectively. Let the beampattern corresponding to a given beamforming vector w , referred to as the mother beamforming vector, satisfies certain shape design requirements, but it does not satisfy other practically important requirements. Such a requirement is, for example, a uniform power distribution across the antenna elements. The question then arises about existence of other distinct beamforming vectors which generate the same exact beampattern as the mother beamforming vector w and which in addition satisfy other possible design requirements. The following theorem states the total number of distinct beamforming vectors with the same exact beampattern as the mother beamforming vector w .

Theorem 1: For an arbitrary transmit beamforming vector $\mathbf{w}$ that corresponds to a ULA of size $M$, there are at most $2^{M-1}-1$ other different beamforming vectors which have the same exact beampattern as $\mathbf{w}$. A constructive solution for obtaining all possible beamforming vectors is given in the proof.

Proof: Let $\mathbf{w}$ and v be two beamforming vectors with the exact same transmit beampattern. The latter implies that

$$
\begin{equation*}
\mathbf{w}^{H} \mathbf{D}(\theta) \mathbf{w}=\mathbf{v}^{H} \mathbf{D}(\theta) \mathbf{v}, \quad \forall \theta \in[-\pi / 2, \pi / 2] \tag{2}
\end{equation*}
$$

where the matrix $\mathbf{D}(\theta)$ is defined as $\mathbf{D}(\theta) \triangleq \mathbf{d}(\theta) \mathbf{d}^{H}(\theta)$. It can be easily verified that the matrix $\mathbf{D}(\theta)$ has Toeplitz structure.

In the rest of this proof, we will refer to the descending diagonals of a matrix from left to right as the first, second, and up to $(2 M+1)$ th off-diagonal, respectively. For the notation simplicity, let us define the following vector

$$
\begin{equation*}
\mathbf{z}(\theta) \triangleq\left(e^{j 2 \pi(M-1) d \sin (\theta)}, \cdots, e^{j 2 \pi(2) d \sin (\theta)}, e^{j 2 \pi d \sin (\theta)}, 1, e^{-j 2 \pi d \sin (\theta)}, \cdots, e^{-j 2 \pi d(M-1) \sin (\theta)}\right)^{T} \tag{3}
\end{equation*}
$$

whose $i$ th element is equal to $i$ th off-diagonal elements of $\mathbf{D}(\theta)$. Moreover, we will express the Toeplitz matrix $\mathbf{D}(\theta)$ with the diagonal and off-diagonal elements defined in $\mathbf{z}(\theta)$ as $\mathbf{T}(\mathbf{z}(\theta))$ where $\mathbf{T}(\cdot)$ is an operator which generates a Toeplitz matrix.

Since equation (2) holds valid in all directions, the following set of equations can be resulted by fixing $\theta$ to an arbitrary set of angles dented as $\theta_{k}, k=1, \cdots, 2 M+1$

$$
\begin{equation*}
\mathbf{w}^{H} \mathbf{D}\left(\theta_{k}\right) \mathbf{w}=\mathbf{v}^{H} \mathbf{D}\left(\theta_{k}\right) \mathbf{v}, \quad k=1, \cdots, 2 M+1 \tag{4}
\end{equation*}
$$

By linearly combining the set of equations in (4) using an arbitrary set of coefficients denoted as $c_{k}, k=1, \cdots, 2 M+1$, the following equality can be concluded

$$
\begin{equation*}
\mathbf{w}^{H}\left(\sum_{k=1}^{2 M+1} c_{k} \mathbf{D}\left(\theta_{k}\right)\right) \mathbf{w}=\mathbf{v}^{H}\left(\sum_{k=1}^{2 M+1} c_{k} \mathbf{D}\left(\theta_{k}\right)\right) \mathbf{v} \tag{5}
\end{equation*}
$$

In what follows, we will show that by the proper selection of the coefficients $c_{k}$ and angles $\theta_{k}$, it is possible to make all the off-diagonal and diagonal elements of the new Toeplitz matrix $\sum_{k=1}^{2 M+1} c_{k} \mathbf{D}\left(\theta_{k}\right)$ equal to zero except for a desired one.

First, note that the new Toeplitz matrix $\sum_{k=1}^{2 M+1} c_{k} \mathbf{D}\left(\theta_{k}\right)$ can be expressed as $\mathbf{T}\left(\sum_{k=1}^{2 M+1} c_{k} \mathbf{z}\left(\theta_{k}\right)\right)$. Based on the latter observation, we conclude that all the off-diagonal elements of the matrix $\sum_{k=1}^{2 M+1} c_{k} \mathbf{D}\left(\theta_{k}\right)$ are equal to zero except for $j$ th off-diagonal element if and only if all the elements of the vector $\sum_{k=1}^{2 M+1} c_{k} \mathbf{Z}\left(\theta_{k}\right)$ are equal to zero except for the $j$ th one. Therefore, let us consider the following set of linear equations

$$
\left[\begin{array}{llll}
\mathbf{z}\left(\theta_{1}\right) & \mathbf{z}\left(\theta_{2}\right) & \cdots & \mathbf{z}\left(\theta_{2 M+1}\right) \tag{6}
\end{array}\right] \mathbf{c}=\mathbf{e}_{j} .
$$

where $\mathbf{c} \triangleq\left[c_{1}, \cdots, c_{2 M+1}\right]$ and $\mathbf{e}_{j}$ is the unit vector whose $j$ th element is equal to one. Since the newly defined matrix $\mathbf{Z} \triangleq\left[\mathbf{z}\left(\theta_{1}\right) \mathbf{z}\left(\theta_{2}\right) \cdots \mathbf{z}\left(\theta_{2 M+1}\right)\right]$ has the Vandermonde structure, it is invertible under the condition that the angles $\theta_{k}, k=1, \cdots, 2 M+1$ are chosen to be distinct.

In what follows, it is assumed that

$$
\begin{equation*}
\theta_{k}=(k-1) \frac{\pi}{2 M+1}, k=1, \cdots, 2 M+1 \tag{7}
\end{equation*}
$$

and, thus, Z is invertible. Therefore, by selecting the coefficient vector $\mathbf{c}$ in (6) as $\mathbf{c}=\mathbf{Z}^{-1} \mathbf{e}_{j}, j=$ $1, \cdots, 2 M+1$, the vector $\sum_{k=1}^{K} c_{k} \mathbf{z}\left(\theta_{k}\right)$ can be set equal to $\mathbf{e}_{j}$. It implies that in terms of the aforementioned selection of the coefficient vector $\mathbf{c}$ and angles $\theta_{k}, k=1, \cdots, 2 M+1$, it is possible to make all the off-diagonal and diagonal elements of the new Toeplitz matrix $\sum_{k=1}^{K} c_{k} \mathbf{D}\left(\theta_{k}\right)$ equal to zero except for the $j$ th one. Using (5) and selecting $\mathbf{c}=\mathbf{Z}^{-1} \mathbf{e}_{j}, j=$ $1, \cdots, 2 M+1$, it can be resulted that $\sum_{k=1}^{2 M+1} c_{k} \mathbf{D}\left(\theta_{k}\right)=\mathbf{T}\left(\mathbf{e}_{j}\right)$ which, in turn, implies that

$$
\begin{equation*}
\mathbf{w}^{H} \mathbf{T}\left(\mathbf{e}_{j}\right) \mathbf{w}=\mathbf{v}^{H} \mathbf{T}\left(\mathbf{e}_{j}\right) \mathbf{v}, \quad j=1, \cdots, 2 M+1 . \tag{8}
\end{equation*}
$$

The set of equations in (8) can equivalently be expressed as follows

$$
\begin{align*}
& \left|w_{1}\right|^{2}+\left|w_{2}\right|^{2}+\cdots+\left|w_{M}\right|^{2}=\left|v_{1}\right|^{2}+\left|v_{2}\right|^{2}+\cdots+\left|v_{M}\right|^{2}  \tag{9}\\
& w_{1} w_{2}^{*}+w_{2} w_{3}^{*}+\cdots+w_{M-1} w_{M}^{*}=v_{1} v_{2}^{*}+v_{2} v_{3}^{*}+\cdots+v_{M-1} v_{M}^{*}  \tag{10}\\
& w_{1} w_{3}^{*}+w_{2} w_{4}^{*}+\cdots+w_{M-2} w_{M}^{*}=v_{1} v_{3}^{*}+v_{2} v_{4}^{*}+\cdots+v_{M-2} v_{M}^{*}  \tag{11}\\
& \vdots \\
& \vdots  \tag{12}\\
& w_{1} w_{M-1}^{*}+w_{2} w_{M}^{*}=v_{1} v_{M-1}^{*}+v_{2} v_{M}^{*}  \tag{13}\\
& w_{1} w_{M}^{*}=v_{1} v_{M}^{*} .
\end{align*}
$$

Since any arbitrary Toeplitz matrix can be constructed by linearly combining the matrices $\mathbf{T}\left(\mathbf{e}_{j}\right), j=1, \cdots, 2 M+1$, equivalently, it can be concluded that by linearly combining the equations (9)-(13), the equation (2) can be resulted. Thus, the beamforming vectors $\mathbf{w}$ and $\mathbf{v}$ have the same transmit beampattern if and only if the equations (9)-(13) are satisfied.

For a mother beamforming vector $\mathbf{w}$, we can construct the set of all possible beamforming vectors that have the same beampattern as w through solving the equations (9)-(13). For this
goal, let us define the following two functions of a single variable $x$

$$
\begin{align*}
& f(x) \triangleq \overbrace{\left(w_{1}+w_{2} x+w_{3} x^{2}+\cdots+w_{M} x^{M-1}\right)}^{\text {First Multiplicative Term }} \overbrace{\left(w_{1}^{*}+w_{2}^{*} x^{-1}+w_{3}^{*} x^{-2}+\cdots+w_{M}^{*} x^{-M+1}\right)}^{\text {Second Multiplicative Term }}\left(\begin{array}{l}
\text { ( } x) \triangleq\left(v_{1}+v_{2} x+v_{3} x^{2}+\cdots+v_{M} x^{M-1}\right)\left(v_{1}^{*}+v_{2}^{*} x^{-1}+v_{3}^{*} x^{-2}+\cdots+v_{M}^{*} x^{-M+1}\right) .
\end{array}\right. \tag{14}
\end{align*}
$$

By expanding the multiplicative terms in the definitions of $f(x)$ and $g(x)$, it can be verified that the equations (9)-(13) hold true if and only if $f(x)$ is equal to $g(x)$. Let $x_{0}$ be a non-zero root of the first multiplicative term in the definition of $f(x)$, i.e., $w_{1}+w_{2} x+w_{3} x^{2}+\cdots+$ $w_{M} x^{M-1}$. Then it is simple to verify that $1 / x_{o}^{*}$ is also a root of the second multiplicative term $w_{1}^{*}+w_{2}^{*} x^{-1}+w_{3}^{*} x^{-2}+\cdots+w_{M}^{*} x^{-M+1}$ of $f(x)$. One implication of this observation is that the inverse conjugate of every root of $f(x)$ is also a root of $f(x)$ and, therefore, the roots of $f(x)$ can be denoted as $x_{i}$ and $1 / x_{i}^{*}, i=1, \cdots, M-1$ and $f(x)$ can be decomposed as

$$
\begin{align*}
f(x) & =\left|w_{M}\right|^{2}\left(\frac{w_{1}}{w_{M}}+\frac{w_{2}}{w_{M}} x+\frac{w_{3}}{w_{M}} x^{2}+\cdots+x^{M-1}\right)\left(\frac{w_{1}^{*}}{w_{M}^{*}}+\frac{w_{2}^{*}}{w_{M}^{*}} x^{-1}+\frac{w_{3}^{*}}{w_{M}^{*}}+\cdots+x^{-M+1}\right) \\
& =\left|w_{M}\right|^{2} \prod_{i=1}^{M-1}\left(x-x_{i}\right) \times \prod_{i=1}^{M-1}\left(x^{-1}-x_{i}^{*}\right) . \tag{16}
\end{align*}
$$

Furthermore, it is easy to verify that the product $\left(x-x_{i}\right)\left(x^{-1}-x_{i}^{*}\right)$ can be equivalently expressed as

$$
\begin{equation*}
\left(x-x_{i}\right)\left(x^{-1}-x_{i}^{*}\right)=\left|x_{i}\right|^{2}\left(x-\frac{1}{x_{i}^{*}}\right)\left(x^{-1}-\frac{1}{x_{i}}\right) . \tag{17}
\end{equation*}
$$

Note that the product terms $\prod_{i=1}^{M-1}\left(x-a_{i}\right)$ and $\prod_{i=1}^{M-1}\left(x^{-1}-a_{i}^{*}\right)$ that appear in (16) preserve the structure of the first and second multiplicative terms in the definition of $f(x)$ ( see (14)) for any arbitrary $a_{i}, i=1, \cdots, M-1$. Based on these observations, $f(x)$ can be decomposed as the multiplication of two terms in the form of $v_{1}+v_{2} x+v_{3} x^{2}+\cdots+v_{M} x^{M-1}$ and $v_{1}^{*}+$ $v_{2}^{*} x^{-1}+v_{3}^{*} x^{-2}+\cdots+v_{M}^{*} x^{-M+1}$ in $2^{M-1}$ different ways depending on whether $x_{i}$ (or $1 / x_{i}^{*}$,) $i=1, \cdots, M-1$ is the root of the first polynomial. The corresponding coefficients of the first multiplicative term in each decomposition correspond to a new beamforming vector dented as $\mathbf{v}$ which has the same exact beampattern as $\mathbf{w}$. This completes the proof.

## III. Application to Transmit Beamspace Design in MiMO Radar

Consider a MIMO radar with transmit ULA of $M=10$ antennas spaced half a wavelength apart. The total transmit power is normalized to $P_{t}=M$. Two mother transmit beamforming


Fig. 1. Transmit beampattern using spheroidal sequences and convex optimization based designs.
weight vectors are designed to focus the transmit energy within the sector $\Theta=\left[-10^{\circ}, 10^{\circ}\right]$. The first mother beamforming weight vector is designed using spheroidal sequences [2], [19]. Specifically, it is computed as $\mathbf{w}_{\mathrm{SPH}}=\sqrt{P_{t} / 2}\left(\mathbf{u}_{1}+\mathbf{u}_{2}\right)$, where $\mathbf{u}_{1}$ and $\mathbf{u}_{2}$ are the two principle eigenvectors of the matrix $\mathbf{A}=\int_{\Theta} \mathbf{a}(\theta) \mathbf{a}^{H}(\theta) d \theta$. The second mother beamforming weight vector is designed using convex optimization to control the sidelobe levels. In particular, it is obtained by solving the following convex optimization problem [19]

$$
\begin{align*}
& \min _{\mathbf{w}} \max _{i}\left\|\mathbf{w}^{H} \mathbf{a}\left(\theta_{i}\right)-e^{-j \phi_{i}}\right\|, \quad \theta_{i} \in \boldsymbol{\Theta}, i=1, \ldots, I  \tag{18}\\
& \text { subject to }\left\|\mathbf{w}^{H} \mathbf{a}\left(\theta_{k}\right)\right\| \leq \delta, \quad \theta_{k} \in \overline{\boldsymbol{\Theta}}, k=1, \ldots, K \tag{19}
\end{align*}
$$

where $\bar{\Theta}$ combines a continuum of all out-of-sector directions, i.e., directions lying outside the sector-of-interest $\Theta ; \phi_{i}, i=1, \ldots, I$ is the desired transmit phase profile of user choice; and $\delta>0$ is the parameter of the user choice that characterizes the worst acceptable level of transmit power radiation in the out-of-sector region $\bar{\Theta}$. The phase $\phi_{i}=2 \pi \sin \left(\theta_{i}\right)$ and the parameter $\delta=0.1$ are chosen, i.e, the sidelobe levels are kept below $20 \log \delta=-20 \mathrm{~dB}$. The mother beamforming weight vector obtained by solving the problem (18)-(19) is referred to hereafter as $\mathbf{w}_{\mathrm{CVX}}$. The transmit beampatterns associated with mother beamforming weight vectors $\mathbf{w}_{\mathrm{SPH}}$ and $\mathbf{w}_{\mathrm{CVX}}$ are shown as the dotted and solid curves in Fig. 1, respectively.


Fig. 2. Transmit power distribution across the transmit array elements for spheroidal sequences based transmit beamforming design.

The mother weight vector $\mathbf{w}_{\text {SPH }}$ is used to generate a population of $2^{M-1}=512$ weight vectors (including $\mathbf{w}_{\mathrm{SPH}}$ ) of dimension $M \times 1$. To implement a MIMO radar system with four orthogonal transmit waveforms, the four beamforming weight vectors among the population that achieve the best transmit power distribution across the transmit array elements are chosen. The mother weight vector $\mathbf{w}_{\text {SPH }}$ and the four chosen weight vectors denoted as $\mathbf{w}_{\mathrm{SPH}}^{(j)}, j=1, \ldots, 4$ are given in Table 1. Since the sector $\Theta$ is symmetric around 0 , the mother beamforming vectors are real-valied. The four chosen vectors are scaled such that $\sum_{j}\left\|\mathbf{w}_{\mathrm{SPH}}^{(j)}\right\|^{2}=P_{t}$.

It is worth noting that each of the four chosen vectors has the same beampattern as the mother beamforming vector except for the magnitude scaling factor of $1 / 4$. Note that the beampattern magnitude in the mainlobe as well as in the sidelobe regions is scaled by the same scaling factor, i.e., the relative attenuation of the sidelobes with respect to the mainlobe remains unchanged. The transmit power distribution across the transmit array elements for the mother transmit beamforming weight vector operated in the SIMO radar mode and the four chosen weight vectors operated in the MIMO radar mode are shown in Fig. 2] It can be seen from the figure that the

Table 1: Spheroidal sequences based mother transmit beamforming vector and a subset of four vectors chosen from the $2^{M-1}$ population.

| $\mathbf{w}_{\text {SPH }}$ | $\mathbf{w}_{\text {SPH }}^{(1)}$ | $\mathbf{w}_{\text {SPH }}^{(2)}$ | $\mathbf{w}_{\text {SPH }}^{(3)}$ | $\mathbf{w}_{\text {SPH }}^{(4)}$ |
| :---: | :---: | :---: | :---: | :---: |
| 0.5178 | 0.2589 | $0.2740-0.0000 \mathrm{i}$ | $0.6061-0.0000 \mathrm{i}$ | 0.6414 |
| 0.3408 | 0.1704 | $0.1980+0.0255 \mathrm{i}$ | $0.6490-0.0563 \mathrm{i}$ | 0.7281 |
| 0.0472 | 0.0236 | $0.0251+0.0475 \mathrm{i}$ | $0.6791-0.1247 \mathrm{i}$ | 0.7415 |
| -0.3263 | -0.1632 | $-0.2122+0.0311 \mathrm{i}$ | $0.6797-0.1491 \mathrm{i}$ | 0.6770 |
| -0.7253 | -0.3627 | $-0.4458-0.0317 \mathrm{i}$ | $0.6098-0.1087 \mathrm{i}$ | 0.5437 |
| -1.0873 | -0.5437 | $-0.6098-0.1087 \mathrm{i}$ | $0.4458-0.0317 \mathrm{i}$ | 0.3627 |
| -1.3540 | -0.6770 | $-0.6797-0.1491 \mathrm{i}$ | $0.2122+0.0311 \mathrm{i}$ | 0.1632 |
| -1.4830 | -0.7415 | $-0.6791-0.1247 \mathrm{i}$ | $-0.0251+0.0475 \mathrm{i}$ | -0.0236 |
| -1.4562 | -0.7281 | $-0.6490-0.0563 \mathrm{i}$ | $-0.1980+0.0255 \mathrm{i}$ | -0.1704 |
| -1.2828 | -0.6414 | $-0.6061-0.0000 \mathrm{i}$ | $-0.2740+0.0000 \mathrm{i}$ | -0.2589 |

mother beamforming weight vector has very poor transmit power distribution. For example, the power radiated by the third transmit array element is over 25 dB less than the average transmit power per transmit array element. On the other hand, the four chosen beamforming vectors exhibit transmit power distribution that is almost uniform, which is desirable in practice.

Similarly, the mother weight vector $\mathbf{w}_{\mathrm{CVX}}$ is used to generate a population of $2^{M-1}=512$ beamforming vectors (including $\mathbf{w}_{\mathrm{CVX}}$ ) which have the exact same beampattern. The four beamforming weight vectors among the population that achieve the best transmit power distribution across the transmit array elements are chosen. The mother weight vector $\mathbf{w}_{\text {SPH }}$ and the four chosen weight vectors denoted as $\mathbf{w}_{\mathrm{CVX}}^{(j)}, j=1, \ldots, 4$ are given in Table 2. The transmit power distributions across the transmit array elements for the mother weight vector and the four chosen weight vectors are shown in Fig. 3. It can be seen from the figure that the four chosen vectors yield much better transmit power distribution as compared to the mother weight vector.


Fig. 3. Transmit power distribution across the transmit array elements for convex optimization based transmit beamforming design.

Table 2: Convex optimization based mother transmit beamforming vector and a subset of four vectors chosen from the $2^{M-1}$ population.

| $\mathbf{w}_{\mathrm{CVX}}$ | $\mathbf{w}_{\mathrm{CVX}}^{(1)}$ | $\mathrm{w}_{\mathrm{CVX}}^{(2)}$ | $\mathbf{w}_{\mathrm{CVX}}^{(3)}$ | $\mathbf{w}_{\mathrm{CVX}}^{(4)}$ |
| :---: | :---: | :---: | :---: | :---: |
| -0.1702 | 0.0011 | 0.0005 | 0.5412 | 0.2438 |
| 0.8093 | -0.0661 | -0.0303 | 0.7829 | 0.0930 |
| 1.4003 | 0.2481 | 0.1432 | 0.9311 | -0.1178 |
| 1.8485 | 0.6505 | 0.1931 | 0.7435 | -0.6407 |
| 1.6711 | 0.8511 | 0.0333 | 0.3386 | -0.8910 |
| 0.9506 | 0.8910 | -0.3386 | -0.0333 | -0.8511 |
| 0.1437 | 0.6407 | -0.7435 | -0.1931 | -0.6505 |
| -0.3186 | 0.1178 | -0.9311 | -0.1432 | -0.2481 |
| -0.3459 | -0.0930 | -0.7829 | 0.0303 | 0.0661 |
| 0.0063 | -0.2438 | -0.5412 | -0.0005 | -0.0011 |

## IV. Conclusion

The important question regarding the existence of other beamforming vectors whose transmit beampatterns are the exact same as the transmit beampattern of a given beamforming vector has been addressed. It has been proven that at most $2^{M-1}-1$ other beamforming vectors with the same beampattern can be generated from any given beamforming vector. The method for constructing the set of all possible beamforming vectors from a given mother beamforming vector has been also developed. Moreover, it has been shown how this result can be utilized in the actively developing field of transmit beamspace design for MIMO radar systems, where it is desirable to have different transmit waveforms to be radiated with the same transmit beampattern.

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