

An Active Concentric Electrode for Concurrent EEG Recording and Body-Coupled Communication (BCC) Data Transmission

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Abstract—This paper presents a wearable active concentric electrode for concurrent EEG monitoring and Body-Coupled Communication (BCC) data transmission. A three-layer concentric electrode eliminates the usage of wires. A common mode averaging unit (CMAU) is proposed to cancel not only the continuous common-mode interference (CMI) but also the instantaneous CMI of up to $51V_{pp}$. The localized potential matching technique removes the ground electrode. An open-loop programmable gain amplifier (OPPGA) with the pseudo-resistor-based RC-divider block is presented to save the silicon area. The presented work is the first reported so far to achieve the concurrent EEG signal recording and BCC-based data transmission. The proposed chip achieves 100 dB CMRR and 110 dB PSRR, occupies 0.044 mm^2 , and consumes $7.4\text{ }\mu\text{W}$ with an input-referred noise density of $26\text{ nV}/\sqrt{\text{Hz}}$.

Index Terms—Active electrode, concentric electrode, common-mode interference, common-mode averaging, concurrent recording/transmitting, EEG recording, instantaneous common-mode interference rejection, localized potential matching.

I. INTRODUCTION

EEG RECORDING creates an opportunity to sense human brain activity in a non-invasive manner [1]–[4]. Quantitative EEG analysis or brain mapping, which is based on multiple EEG sensing channels, provides the patient’s mental and

physiological information for monitoring purposes. However, conventional multi-channel EEG requires various wire connections, making it difficult to be portable/wearable. The wearable EEG environment also suffers from environmental/common-mode interference (CMI), such as 50/60 Hz power line coupling, making it even more challenging for daily EEG monitoring. In particular, a wearable environment faces continuous CMI and instantaneous CMI (that happens, for example, when touching the laptop case or pulling the power plug), which must be addressed to achieve stable monitoring in daily life.

In efforts to mitigate such huge common-mode environmental interference, the works [5], [6] claimed that improving the CMRR from the instrumentation amplifier (IA) was the key. The work in [5] improved the IA’s CMRR to be more than 115 dB by using tunable capacitors to compensate for the mismatches. [6] boosted the IA’s CMRR by common-mode feedback (CMFB) circuit. Also, [7] developed a ping-pong auto zeroing and chopper-stabilized IA to achieve a CMRR of 140 dB. Although the reported CMRR was theoretically high enough to suppress CMI of up to $51V_{pp}$, the work in [8] derived the CMRR relationship for a multi-channel system. Even with a more than 100 dB CMRR for the IA itself, the *system-level* CMRR can be as low as 60 dB for a multi-channel application. Therefore, previous works tried to compensate for the CMRR degradation from a system-level perspective. The system-level CMFB [9] or system-level common-mode feedforward (CMFF) [10] technique was proposed, which required extra hardware resources and consumed additional power. To improve system-level CMRR, the driven-right leg (DRL) circuit [11] could be used, but at the cost of system instability. Dedicated DRL works [12]–[15] tried to stabilize the system, but the extra DRL electrode coupled additional powerline interference and was inconvenient for wearable devices. The work in [16] discovered the imbalanced load issue and proposed an inverter-based preamp to solve the problem, while the other work [17] presented a TDM-based modulation scheme to obtain a balanced structure for multi-channel input. The reported works in [16], [17] improved the system-level CMRR to be more than 80 dB at the cost of additional preamp stages or fuzzy control strategies.

Besides improving the CMRR or solving the imbalanced load problem, reducing the number of transmission wire was

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another method to effectively suppress the CMI. The work in [18] proposed an active electrode concept to remove the transmission wire between the chip and electrodes. However, the cables between the recording electrode and reference electrode, and the ground electrode wire still existed and coupled a huge amount of CMI from the environment. The work in [19] proposed a charge pump technique to reduce the ground electrode's use, so the number of wires was further reduced; this method successfully compensated for the continuous CMI, but the charge pump would not be fast enough to compensate for the instantaneous CMI.

The silicon area of the AFE is another important issue for a multi-channel recording system because it directly determines the number of channels integrated into one chip; the works [2], [20], [21] reported to shrink the size of the IA with various techniques. The work in [2] proposed a group-chopping technique so that the open-loop amplifier could be used while minimizing the between-channel gain mismatch, and the work in [20] utilized an intrinsic capacitance as a feedback capacitor to save the silicon area. The work in [21] proposed an orthogonal chopping scheme for the inputs of 15 channels to share the same IA. Therefore, the area per channel was dramatically reduced. However, all of these works focused on the area of first stage IA, while the second stage of the AFE, normally the programmable gain amplifier (PGA), still occupied a large area due to the function of programmable gain.

Human biological data security is yet another important issue when designing wearable bio-potential recording devices. To achieve wireless transmitting among electrodes, the work [22] tried to send the information to each electrode by Bluetooth, which was power hungry and could be hacked for illegal purposes. The body channel communication (BCC) [23]–[32] provided a power-efficient and secure interface for data transmission through the user's body so that data security was well maintained. Moreover, when the human body was used as a communication interface, the transmission power was reduced compared with radio wave communication for wearable devices [29]–[30]. The work [31] tried to develop a human body model to optimize the BCC transceiver's power, and previous work proposed a mask-shaping technique to suppress interference with biological signals [32]. The work in [25] presented the integration of recording and BCC in a System-on-Chip (SoC). However, the concurrent recording/transmitting was not verified yet; to acquire the real-time data by the BCC technique, the system must transmit the bio-potential data while concurrently recording it.

To overcome the design difficulties mentioned above, we propose a concurrent EEG recording/transmitting wireless active concentric electrode [33].

II. THE PROPOSED ACTIVE CONCENTRIC ELECTRODE

The proposed active concentric electrode is shown in Fig. 1. This is the first distributed EEG recording system with BCC-based concurrent recording/transmitting reported so far.

A. Active Concentric Electrode Architecture

There are two functions in each sensor node: 1) EEG signal recording; 2) digitized EEG data transmission. In the recording

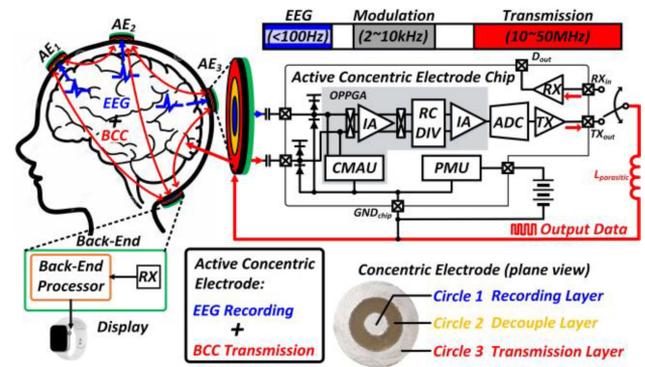


Fig. 1. System architecture of the active concentric electrode.

part, the EEG signal is captured by the active concentric electrode's inner layer. The proposed two-stage open-loop programmable gain amplifier (OPPGA) amplifies the signal, and followed by a 10-bit SAR ADC for digitization. The environmental continuous and instantaneous CMI, which is up to $51V_{pp}$, is dynamically suppressed by a common mode averaging unit (CMAU). The CMAU's output is directly connected to the chip's ground, as shown in Fig. 1, which is defined as the ground node for all blocks. In the data transmission part, the TX/RX can be alternatively selected for data transmission/receiving with the body channel communication (BCC) technique. An on-board trace (equivalent model of a 75 nH inductance $L_{parasitic}$) couples the TX/RX signals to the chip's ground and transmits it to the transmission layer. The OOK-based TX is used to transmit data to another active concentric electrode for the average montage. Once the RX block in each active concentric electrode is enabled to receive data, the two electrodes can communicate with each other. An active concentric electrode is proposed to integrate the two functions, as shown in Fig. 1. Data is transmitted using the outer layer while the internal round area is used for EEG recording; an isolation gap is filled between the two layers. For an average montage, the common reference in the recorded signals is obtained from all active concentric electrodes. By combining recording and transmission, the ground electrode and transmission wires are removed. This allows for a secure bio-data delivery within the user's human body during EEG recording. The measured EEG data can be recorded and transmitted via BCC to the user's electrode which is integrated into the wearable devices, so the user's privacy is protected by the localized data transmission method.

In this active concentric electrode, the ground electrode has been removed by the localized potential matching technique. Additionally, the active concentric electrode is used to reduce the transmission wire from the working electrode. Therefore, the number of transmission wires has been reduced to the minimal. The coupled CMI from the environment has been reduced to the minimum as well.

The innovative concept of the active concentric electrode is utilizing a wide-bandwidth (1 Hz to 50 MHz) concurrently. The EEG signal (normally less than 100 Hz) is located in the base-band, while the chopping stabilization, which is necessary for reducing flicker noise in the IA part, occupies the bandwidth of 2 to 10 kHz, and the BCC TX transmission signal is modulated at 10 to 50 MHz. The use of full-bandwidth operation dramatically

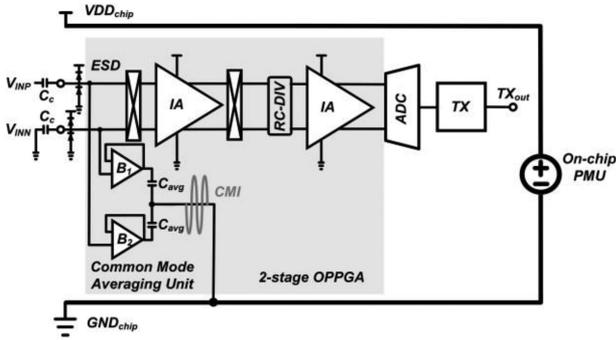


Fig. 2. Schematic of the proposed AFE.

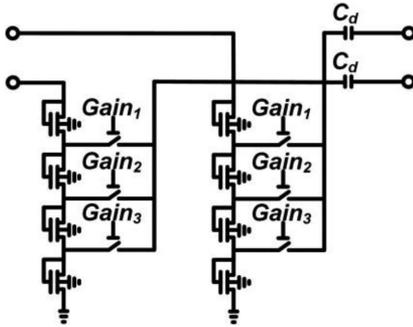


Fig. 3. Schematic of the RC-DIV.

reduces the need for transmission wires. Since the spectrum distance of the EEG signal, chopping stabilization, and BCC TX transmission is wide enough, the active concentric electrode achieves concurrent recording/transmitting without crosstalk of any signal.

B. Open-Loop Programmable Amplifier (OPPGA)

The schematic of the proposed AFE is shown in Fig. 2. To save the silicon area, a two-stage open-loop programmable gain amplifier (OPPGA) has been implemented. The proposed AFE consists of a 2-stage OPPGA, 10-bit ADC, TX, and on-chip PMU. The CMAU output is directly connected with the chip ground (GND_{chip}). Two averaging capacitors (C_{avg} in Fig. 2) average out the CMI and pass it to the ground (GND_{chip}). Conventional open-loop amplifiers [34], [35] with fixed gain are not suitable for bio-potential signal acquisition. A pseudo-resistor-based RC-divider (RC-DIV) block is developed to provide programmable gain, as shown in Fig. 3. Hence, the open-loop gain can be adjusted without any extra capacitor bank. Moreover, the pseudo resistor in the RC-DIV together with the small coupling capacitor C_d (3pF), forms a low -3 dB corner of 140/104/102 Hz for high/mid/low gain setting, respectively, which helps to filter out the unwanted chopping ripples from the first stage and transmission signal when TX for BCC is on, only leaving the recorded EEG signal for the second-stage amplification. Therefore, the RC-DIV unit provides two functions of both programmable gain and low-pass filtering, which saves significant area. The schematic of the IA is shown in Fig. 4. The proposed IA adopts the open-loop gain amplifier consuming only $2.1 \mu W$ while occupying 0.017 mm^2 . The current-reuse technique is employed

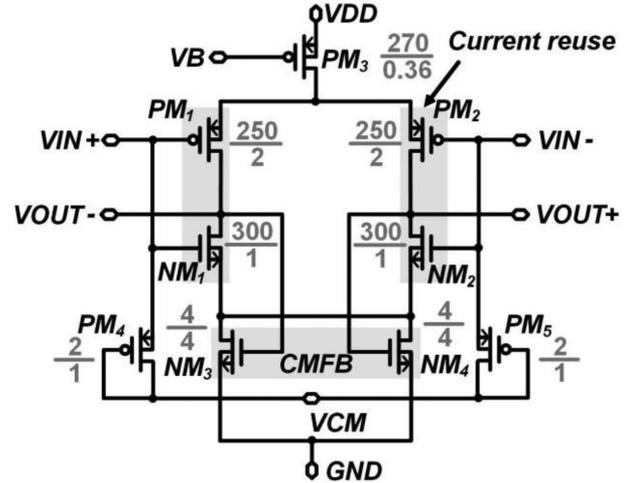


Fig. 4. Schematic of RC-free open loop amplifier and sizing of transistors.

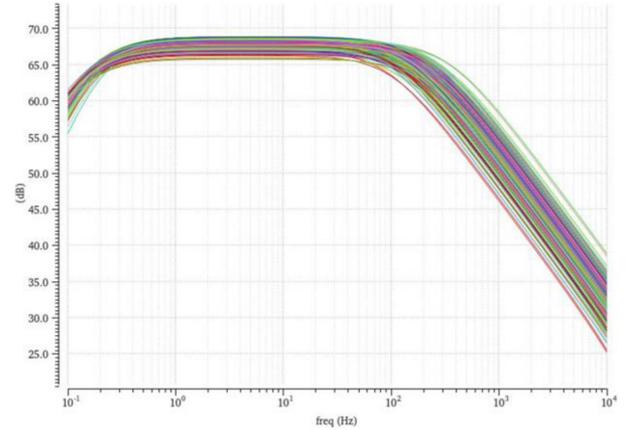


Fig. 5. Monte Carlo simulation of gain and bandwidth of the OPPGA.

at the input stage to obtain high transconductance, which reduces the thermal noise floor with minimum current consumption. The transistor size (W/L) is listed in Fig. 4, where the two input transistor pairs (PM_1/NM_1 and PM_2/NM_2) are biased in a weak inversion region to maximize the transconductance efficiency. Transistors NM_3 and NM_4 provide the common-mode feedback to fix the output DC level. In contrast, two PMOS transistors (PM_4 and PM_5) are chosen as pseudo resistors to set the DC bias for the inputs, occupying a much smaller on-chip area than CMFB or other techniques. Two 100nF decoupling capacitors (C_c) are put in front of the choppers to ensure rail-to-rail DC offset cancellation. The Monte Carlo simulation result of the gain and bandwidth of the OPPGA is shown in Fig. 5. The gain/bandwidth variation, which is shown in Fig. 5, can be calibrated at the back-end to save the on-chip silicon area.

C. Common Mode Averaging Unit (CMAU)

There are considerable environmental interference, especially the 50/60 Hz powerline interference, as the main hazard for the recording AFE in the active concentric electrode. Techniques should be developed to suppress such huge instantaneous CMI. The work [19] proposed a common mode charge pump (CMCP)

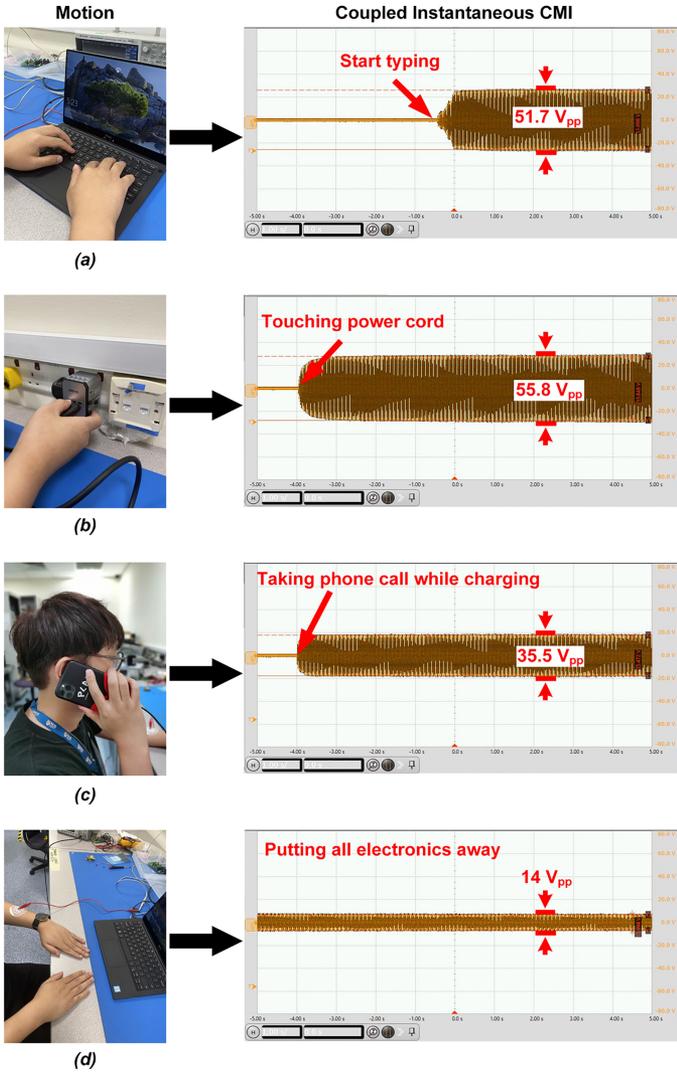


Fig. 6. Instantaneous/Continuous CMI coupling in daily life: (a) typing on a laptop; (b) unplugging power; (c) making phone call while charging; (d) leaving all electronics away.

technique to suppress the common mode interference from power line coupling, while cancelling out a certain amount of common mode voltage. However, when the coupled common mode potential changes over time and environment, the capacitor's charging speed will be the bottleneck of the reported design. Another work [36] proposed the floating power system with an on-chip power unit. However, the floating power system is designed for multi-channel neural recording applications, and all channels are tied together to average out the common-mode potential, which is not suitable for a widespread distributed EEG recording system.

To quantify the amount of possible instantaneous/continuous CMI coupled to our body in daily life, a CMI coupling experiment was done to discover the dynamic change of the CMI. In this experiment, an electrode is attached to a subject's left arm and connected to the oscilloscope to show the amount of CMI. As shown in Fig. 6, when the subject is typing on a laptop, the coupled CMI is $51.7V_{pp}$ while touching the power rails to unplug the

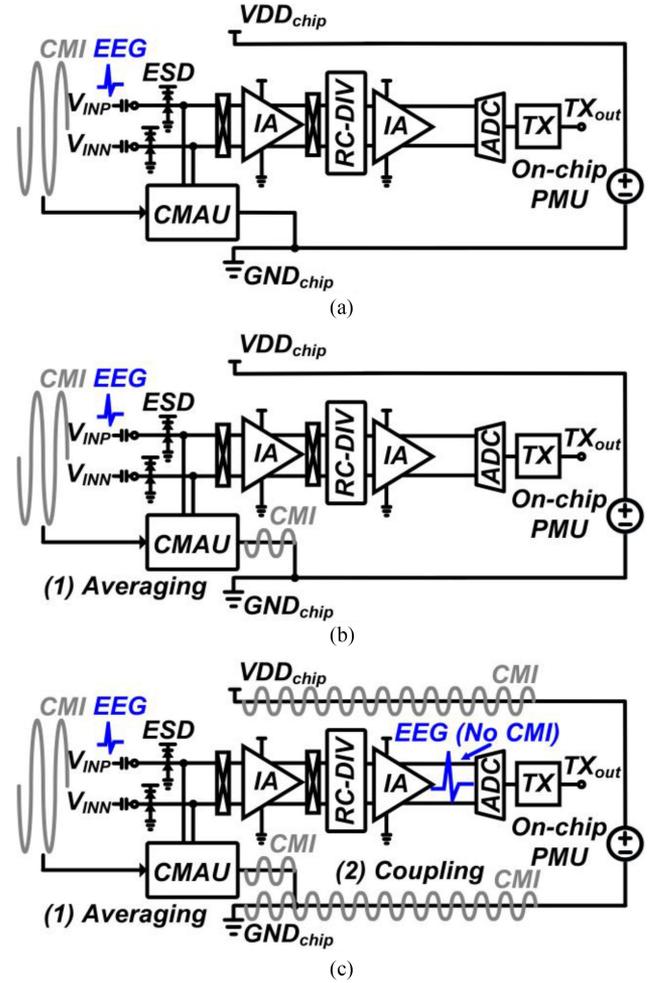


Fig. 7. Working principle of CMAU: (a) CMI and EEG coming in; (b) CMI averaging in CMAU; (c) averaged CMI coupling to circuit supply rails.

power, showing the coupled CMI suddenly changed to $55.8V_{pp}$. The CMI suddenly changes to $35.5V_{pp}$ when the subject makes a phone call (the phone is connected to a charger). Finally, the CMI becomes $14V_{pp}$ when the subject keeps all electronic devices away. From this experiment, we can observe that the amount of coupled CMI may dynamically change in daily life, and when people get closer to the power rails, the coupled CMI becomes higher. Therefore, we propose a common-mode averaging unit (CMAU) in this design to suppress the instantaneous CMI from the environment.

Fig. 7 depicts the working principle of the CMAU. When CMI (shown in grey) and EEG signal (shown in blue) come into the circuit part from the input nodes of the IA, as shown in Fig. 7(a). Then the CMAU, which consists of the unity gain buffers and two capacitors, averages out the CMI, as shown in Fig. 7(b). The buffers provide a high impedance node for the CMAU part to avoid the interference coupled back to the input side. The averaged CMI is sent to the circuit ground of the IA, as shown in Fig. 7(c). Since an on-chip power management unit (PMU) is implemented, the averaged CMI in the circuit ground will be passed to the supply rail. Therefore, the averaged

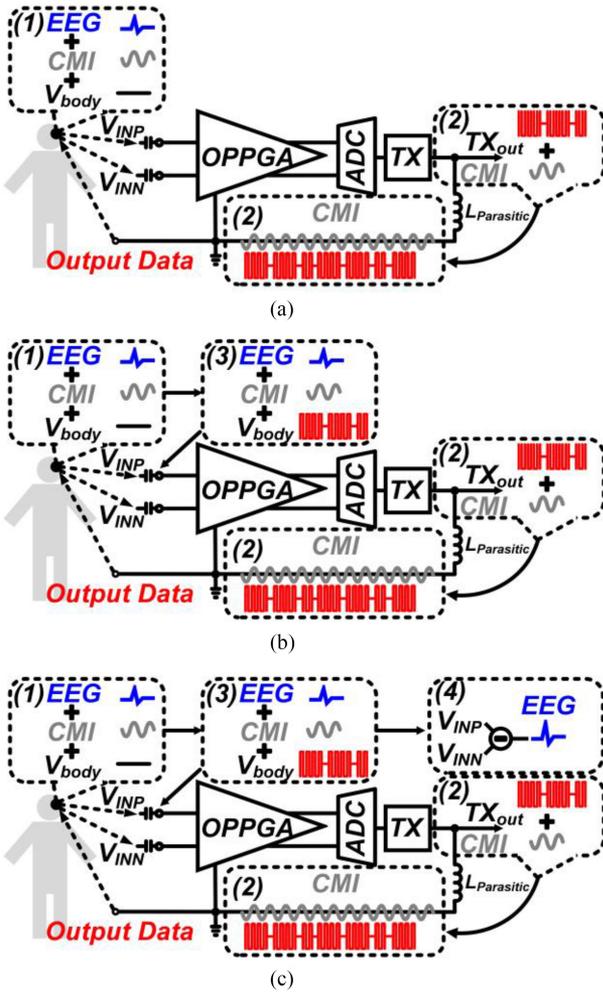


Fig. 8. Working principle of localized potential matching technique: (a) signal amplification and digitization; (b) TX transmission; (c) CMI and body potential cancellation.

CMI is dynamically coupled to the circuit ground and supply. Moreover, to avoid ESD latch-up, due to the huge instantaneous CMI, the ESD cells' supply/ground is tied to the main chip's supply/ground, respectively. Then the CMI coupled to the chip's supply/ground will be the same as the environmental CMI, so the bio-potential signal remains without the crosstalk from CMI.

D. Localized Potential Matching

To reduce the ground electrode as well as the transmission wire, the localized potential matching technique is proposed. The working principle of the localized potential matching is shown in Fig. 8. In step (1), the EEG signal is sensed between the two inputs of IA (V_{INP} and V_{INN}), coming with the CMI and the body potential, which is amplified and digitized by the OPPGA and ADC, respectively. Thereafter the digital signal is transmitted by the TX to the transmission layer of the active concentric electrode through the coupling inductance L_P (75 nH) in step (2), as shown in Fig. 8 (a). The TX signal ($1.2V_{pp}$) is sent into the human body around the recording area and forces the body's potential in this area to be the same as

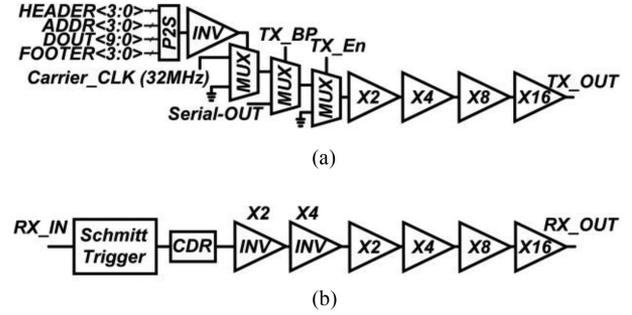


Fig. 9. The schematic of BCC blocks: (a) TX with P2S encoder; (b) RX block.

the TX signal, shown in Fig. 8 (b). Hence the signal sensed by V_{INP} is the sum of the EEG signal, CMI, and TX signal, while the negative input is connected with the transmission layer, so the signal sensed by V_{INN} is the CMI and TX signal. Therefore, the only signal amplified by the OPPGA is the EEG signal, as shown in Fig. 8 (c). Moreover, since the TX signal is at 40 MHz, which is far beyond the bandwidth of the proposed IA ($f_{corner} < 150$ Hz), the TX signal will not saturate the IA's output. With the proposed localized potential matching technique, the system can transmit the TX signal while concurrently recording the EEG signal. Therefore, the EEG signal can be recorded without the ground electrode and achieves the concurrent recording/transmitting.

E. BCC TX and RX

The schematic of the BCC TX is shown as Fig. 9(a). A parallel-to-serial encoder is applied to convert the 10-bit parallel output from the ADC to the encoded bitstream. A 4-bit header and a 4-bit footer are used to encode the bitstream, and there is a 4-bit address used to differentiate outputs from various active concentric electrodes. The P2S encoder serializes the 4-bit header, 4-bit footer, 4-bit address, and 10-bit digitized signal from ADC, so the entire active concentric electrode system supports up to 16 channels' communication. Moreover, the TX_BP provides the bypass function for the TX part. The encoded signal can be directly sent out when the TX_BP is enabled. Once the TX_En is high, the TX part turns to sleep mode, and output will be kept to ground. The output of the TX part is based on OOK modulation. The active "high" is modulated to be a 40 MHz pulse while the active "low" is kept to ground and the modulated signal will be buffered-out.

The BCC RX consists of a Schmitt trigger, a clock data recovery (CDR) circuit, and the output buffers, as shown in Fig. 9(b). When the BCC signal is transmitted by the human body and sensed by an active concentric electrode, the signal is first reconstructed as a full-swing signal by the Schmitt trigger and recovered to be the encoded bitstream by the CDR block.

III. MEASUREMENT RESULTS

The proposed active concentric electrode was fabricated in a $0.18\text{-}\mu\text{m}$ 1P6M CMOS process. The die photo is shown in Fig. 10, and the total area of the chip is 1.6 mm^2 while the area of

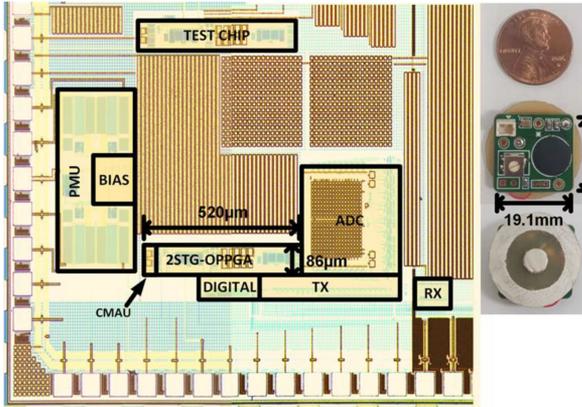


Fig. 10. Die photo of the proposed active concentric electrode and the prototype.

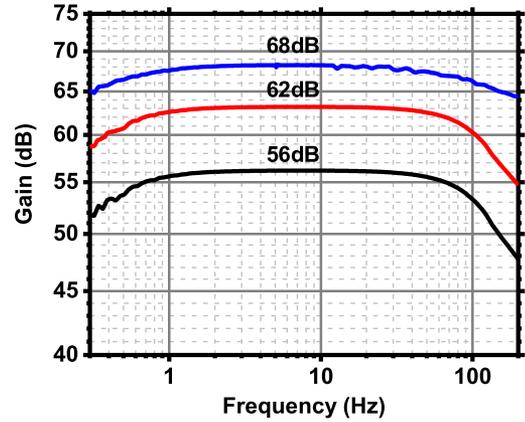


Fig. 12. The measured AC response of the AFE.

Power breakdown of the active concentric electrode

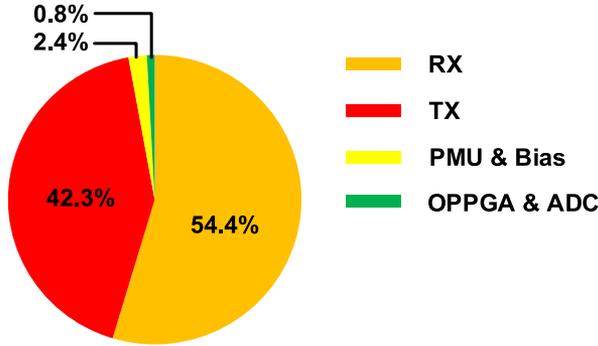


Fig. 11. Power breakdown of the proposed active concentric electrode.

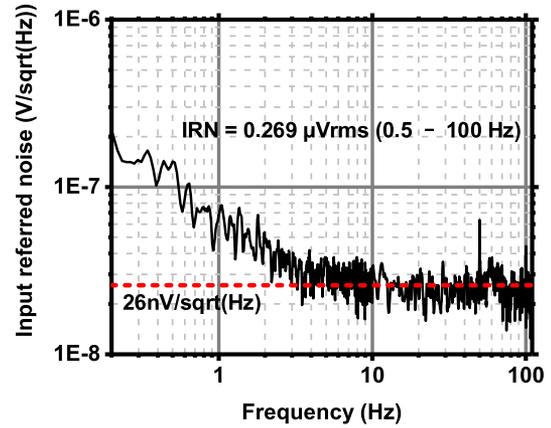


Fig. 13. The measured input-referred noise of the AFE.

the OPPGA is only 0.044 mm^2 . The active concentric electrode size is only 18.5 mm by 19.1 mm , which is comparable to that of a US penny. The total power consumption of the proposed active concentric electrode is 1 mW while the OPPGA consumes $7.4 \text{ } \mu\text{W}$, and the power breakdown of the active concentric electrode is shown in Fig. 11.

A. Performance Measurement Results

The measured AC response of the proposed OPPGA is shown in Fig. 12. With the help of the RC-DIV block, the OPPGA provides a programmable gain of 68/62/56 dB, which is controlled by the 3-bit control signal. The corresponding low/high cut-off frequencies are 0.33/140 Hz, 0.40/104 Hz and 0.38/102 Hz for 68 dB, 62 dB and 56 dB, respectively. Compared with the design values, the high pass corner is slightly higher than the simulation result due to the parasitic capacitance coupled to the input end. The measured input-referred noise is shown in Fig. 13. As the chopping stabilization is implemented to suppress the IA's flicker noise, the noise density of the proposed IA is only $26 \text{ nV}/\sqrt{\text{Hz}}$, and the input-referred noise is only $0.269 \text{ } \mu\text{Vrms}$ integrated from 0.5 to 100 Hz.

By adopting the CMAU to cancel the instantaneous CMI, the measured CMRR result is shown in Fig. 14. The measured CMRR is more than 100 dB over the frequency range of 100 Hz,

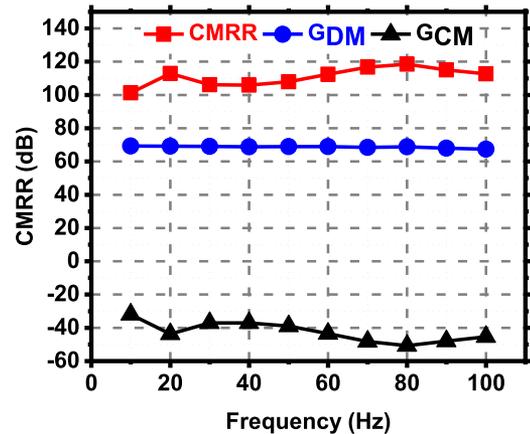


Fig. 14. The measured CMRR of the AFE.

which is the bandwidth of the EEG signal. Moreover, with the help of CMAU and on-chip PMU, the PSRR of the IA is measured to be more than 110 dB as shown in Fig. 15.

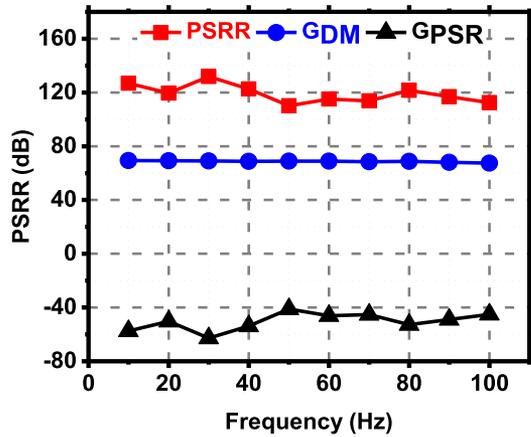


Fig. 15. The measured PSRR of the AFE.

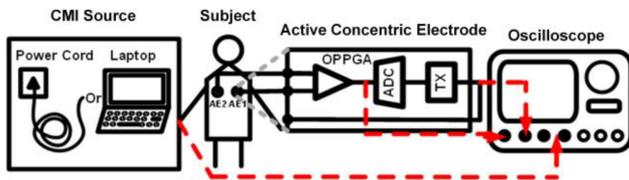


Fig. 16. Test set-up for measuring instantaneous common-mode interference (CMI) by touching laptop.

B. In-Vivo Measurement Results

The test set-up for measuring the instantaneous CMI at the working status of the proposed work is shown in Fig. 16. Since the periodical ECG signal with PQRST features is easier than the EEG signal to be recognized in the time-domain, an ECG measurement has been set up to check the system response towards instantaneous CMI. The subject who wears the active concentric electrode touches the laptop's surface to see the instantaneous CMI changes.

To verify the functionality of the CMAU block, a comparison is made between two sets of ECG recording set-up to the same subject. One set is the proposed active concentric electrode, and the other is the commercial chipset (Intan RHD 2132) [38]. For a fair comparison, the conventional 3M electrodes are used for both of the recording sets. By touching the laptop's surface, the simultaneously recorded ECG signals from both the active concentric electrode testing board and RHD 2132 are shown in Fig. 17. The recorded ECG signal on the left of the screen is from the active concentric electrode testing chip, while the right is from RHD 2132. The normal ECG waveform in the left indicates that the proposed active concentric electrode chip, which is equipped with CMAU block, withstands the huge *instantaneous and continuous* CMI injected by touching the laptop. In contrast, the commercial chipset is immediately saturated by the CMI and no useful ECG signal is shown on the right side of the screen.

To verify the amount of the instantaneous CMI suppressed by the active concentric electrode, both ECG and EEG's measurement results are shown in Fig. 18. When the subject touches a charging laptop at $t = 4$ s, we can observe the CMI of $51V_{PP}$ showing up instantly; even with such high instantaneous CMI,

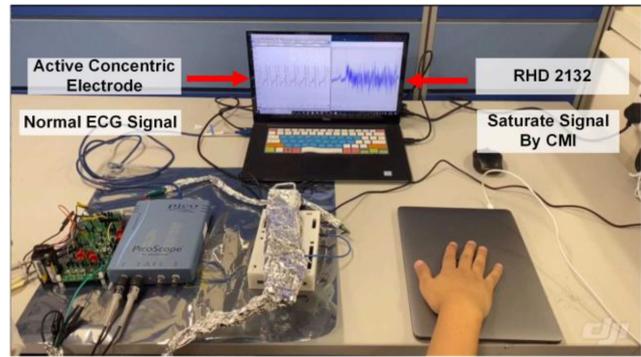


Fig. 17. Comparative testing result for active concentric electrode and Intan RHD 2132 by touching the surface of laptop.

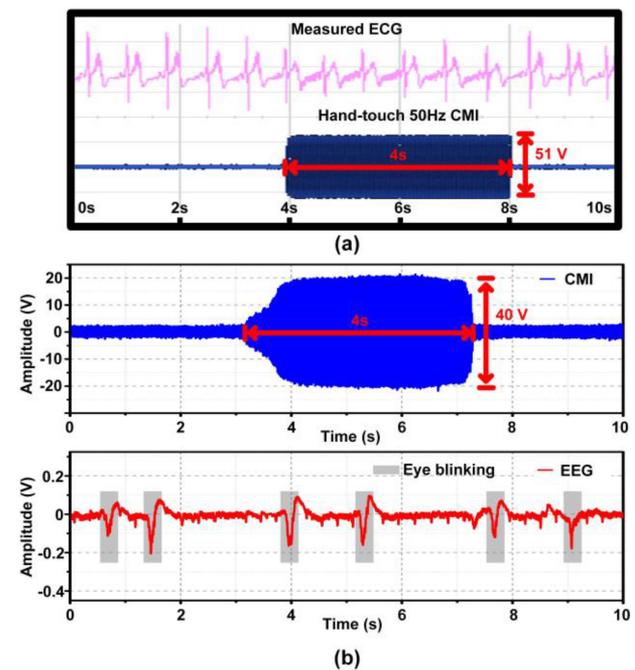


Fig. 18. Human-trial measurement result: (a) ECG recording result with the $51V_{PP}$ instantaneous CMI, (b) EEG recording result with the $40V_{PP}$ instantaneous CMI.

the ECG is successfully amplified without saturation. The EEG recording is clear to see the eye blinking despite the hand touches the power cord, coupling a CMI of $40V_{PP}$ for 4 s.

Concurrent recording/transmission of signals is another important performance required for such an active concentric electrode. As shown in Fig. 19, the proposed localized potential matching successfully shows the *concurrent* recording of the ECG signal (Fig. 19(a)) and the transmission of BCC data (Fig. 19(b)), while the concurrent recording of the EEG signal is shown in Fig. 19(c). The recovered data stream at a distance of 15 cm (electrode at the forehead to the electrode at the neck) is shown in Fig. 19(d). Therefore, the active concentric electrode fully supports concurrent signal recording/data transmitting without the ground electrode. An SNR measurement is conducted when the TX/RX distance varies. The measured

TABLE I
COMPARISON WITH THE STATE-OF-THE-ART WORKS

Parameters	ISSCC '19 [19]	ISSCC '18 [36]	VLSI'18 [37]	VLSI'18 [25]	This work
Technology	0.18 μm	0.18 μm	65 nm	65nm	0.18 μm
No. of channels	1	16	2	2	Scalable (1-16)
Active Electrode	Y	N	Y	Y	Y
Tolerance to CMI (V)	30	NA	2.8	NA	51
Instantaneous CMI Suppression	NA	NA	NA	NA	Y
Ground Electrode	N	Y	Y	Y	N
Data Transmission	Wired	Wired	Wired	BCC	BCC Network
Concurrent Recording/Transmission	N	N	N	N	Y
BCC Modulation	NA	NA	NA	Super Regenerative OOK	OOK
BCC TRX Power (μW)	NA	NA	NA	79.4	960
BCC Carrier Frequency (Hz)	NA	NA	NA	13.56M	40M
BCC Data Rate	NA	NA	NA	100kbps	512kbps
IA + PGA Area (mm^2)	0.271	0.075	1.230	1.630	0.044
Supply Voltage (V)	1.2	1.5	5	0.8	0.9/1.2
Powerper IA+PGA (μW)	27.8	3.23	90	4.16	7.4
Gain (dB)	35	39.8	20/13/9/0	NA	68/62/56
Input-referred noise (μV_{rms}) (0.5 ~100 Hz)	5.05	3 (10~10kHz)	3.7	0.38	0.269
Bandwidth (Hz)	15k	10k	10k	100	100
NEF	NA	1.69	NA	3.32	2.9
CMRR (dB)	68	>110	70	>95	>100
PSRR (dB)	NA	101	NA	NA	>110
EDO Tolerance	NA	NA	Rail-to-Rail	350mV	Rail-to-Rail
Application	ECG	ECG	ECG	EEG/BCC	EEG

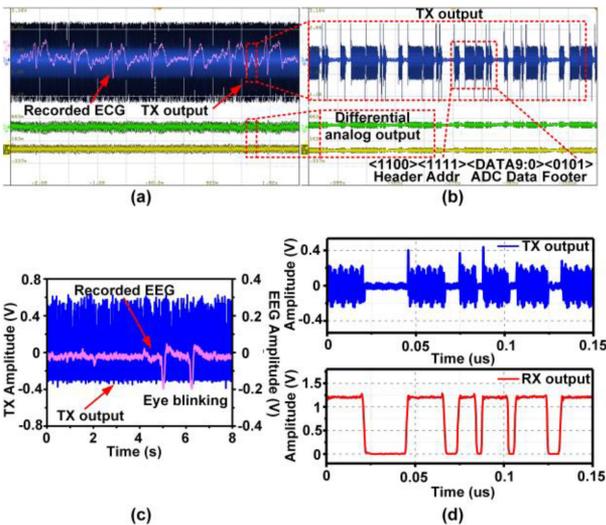


Fig. 19. Human-trial measurement results: (a) Concurrent ECG recording/BCC transmitting; (b) zoom-in view of the TX output; (c) Concurrent EEG recording/BCC transmitting; (d) BCC TX and RX output signals.

SNR (as shown in Fig. 20) of the received signal in the RX side is inversely proportional to the distance between TX and RX.

The performance summary is shown in Table I. With the unique circuit configuration of the active concentric electrode, the presented work is the first reported so far to achieve the concurrent EEG signal recording and BCC-based data transmission. A CMAU block is implemented to support $51V_{pp}$ instantaneous CMI fluctuation and achieves 100 dB CMRR and 110 dB PSRR. Moreover, the OPPGA, equipped with RC-DIV block, only occupies 0.044 mm^2 . With the help of localized potential

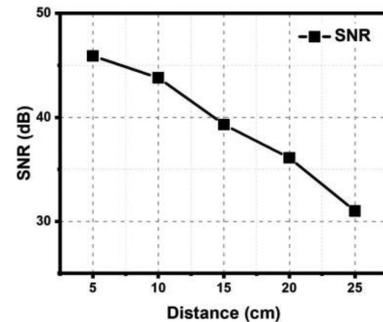


Fig. 20. Measured SNR of the received BCC RX signal vs distance.

matching technique, there is no need for ground electrode in the active concentric electrode. Therefore, the CMI coupled with the transmission wire is further reduced. The IA's power consumption is $7.4 \mu\text{W}$, and the input-referred noise density is only $26 \text{ nV}/\sqrt{\text{Hz}}$. The calculated NEF of the design is 2.9 and the chip supports rail-to-rail electrode dc offset tolerance.

IV. CONCLUSION

We presented an active concentric electrode for wearable EEG recording. The innovative combination of the EEG recording chip with the 3-layer concentric electrode provides a wearable EEG monitoring solution. The coin-size chip tolerates $51V_{pp}$ instantaneous CMI with the proposed CMAU block. The localized potential matching technique eliminates ground electrode and transmission wire, so the possibly coupled CMI from the environment is further reduced. The OPPGA that adopts the pseudo-resistor-based RC-DIV block provides the programmable gain and low-pass filtering, and saves the on-chip

silicon area. The chip is capable of concurrent EEG recording and BCC transmission. The chip's power consumption is $7.4 \mu\text{W}$ while the input-referred noise is only $0.269 \mu\text{Vrms}$ integrated from 0.5 to 100 Hz. The measured CMRR and PSRR of the IA are more than 100 dB and 110 dB, respectively.

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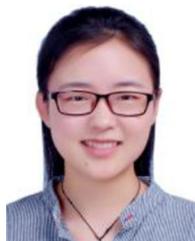


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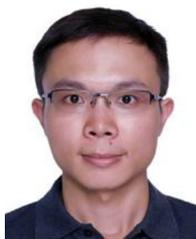
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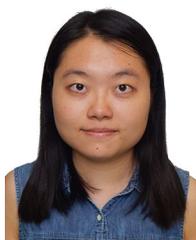
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