

Comments and Corrections

Corrections to “Design and Integration of a Parallel, Soft Robotic End-Effector for Extracorporeal Ultrasound”

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In our paper [1], there are errors in several equations, (6), (7), (8), and (14), which we correct here. They should be as follows:

$$\delta V/a = \mathbf{J}_V^T \delta \mathbf{x}_{\text{tip}} \quad (6)$$

$$\delta \mathbf{x}_\theta = \mathbf{J}_\theta^T \delta \mathbf{x}_{\text{tip}} \quad (7)$$

$$\boldsymbol{\tau}_\theta = \mathbf{K}_\theta \mathbf{J}_\theta^T \delta \mathbf{x}_{\text{tip}} \quad (8)$$

$$\delta \mathbf{V}/a = {}^n \mathbf{J}_V^T \mathbf{x}_{\text{tip}} \quad (14)$$

REFERENCE

- [1] L. Lindenroth *et al.*, “Design and integration of a parallel, soft robotic end-effector for extracorporeal ultrasound,” *IEEE Trans. Biomed. Eng.*, vol. 67, no. 8, pp. 2215–2229, Aug. 2020.

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