

# Comments and Corrections

## Correction to Section V-B of “Contraction Theory and the Master Stability Function: Linking Two Approaches to Study Synchronization in Complex Networks”

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**Abstract**—This document contains corrections to the paper entitled “Contraction Theory and the Master Stability Function: Linking Two Approaches to Study Synchronization in Complex Networks.” The results reported here should substitute those included in Section V-B therein.

**A**S shown in [2], we can associate to a generic connected network of the form:

$$\dot{X} = F(X) - \alpha(L \otimes I_n)X \quad (1)$$

the following auxiliary virtual system:

$$\dot{Y} = F(Y) - \alpha(L \otimes I_n)Y - (1_{N \times N} \otimes K_0)(Y - X) \quad (2)$$

where  $Y := [y_1^T, \dots, y_N^T]^T$  is the set of virtual state variables,  $K_0$  is some symmetric positive definite matrix, and  $1_{N \times N}$  is the  $N \times N$  matrix whose elements are all equal to 1. (For further details on the notation and terminology used here the reader is referred to [1], [2].)

System (2) has  $Y = X$  as a solution and admits the particular solution  $y_1 = \dots = y_N = y_\infty$ , with  $y_\infty$  such that [2]

$$\dot{y}_\infty = f(y_\infty) - nK_0y_\infty + K_0 \sum_{j=1}^N x_j(t).$$

Thus, contraction of system (2) in the Euclidean norm immediately implies that network (1) achieves synchronization (see, e.g., [2]). We can then state the following result.

**Theorem 1:** Consider a network with  $N$  identical nodes. If 1) the network is connected, 2) the coupling functions are linear and increasing, and 3) the auxiliary system (2) is contracting in the Euclidean norm w.r.t.  $Y$  for all  $X$  for some range of the coupling strength,  $\alpha \in A$ ; then, the master stability function (MSF) of (1) will be negative in  $A$ , i.e., the network locally synchronizes for  $\alpha \in A$ .

**Proof:** From the hypotheses, we have that system (2) is contracting in the Euclidean norm, i.e., the symmetric part of its Jacobian, e.g.,  $J_s$ , given by

$$J_s := \left[ \frac{\partial F}{\partial y} \right]_s - \alpha(L \otimes I_n) - 1_{N \times N} \otimes K_0$$

is negative definite  $\forall \alpha \in A$ .

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Let  $J_r = -\alpha(L \otimes I_n) - 1_{N \times N} \otimes K_0$ . Its maximum eigenvalue can be computed, as shown in [2], using the Courant–Fischer theorem (see, e.g., [3]) as

$$\lambda_{\max}(J_r) = -\lambda_{m+1}(\alpha(L \otimes I_n)).$$

with  $\lambda_{m+1}$  being the first eigenvalue associated to the transversal dynamics. Thus, if the auxiliary system is contracting, then

$$\lambda_{m+1}(\alpha(L \otimes I_n)) > \max_i \lambda_{\max} \left( \left[ \frac{\partial f}{\partial y_i} \right]_s \right) \quad (3)$$

$\forall \alpha \in A$ . We can then conclude that the matrix

$$\frac{\partial F}{\partial y} - \alpha(L \otimes I_n) \quad (4)$$

is negative definite  $\forall \alpha \in A$ . Hence, the linear system

$$\dot{\xi} = \left( \frac{\partial F}{\partial y} - \alpha(L \otimes I_n) \right) \xi$$

is contracting. The proof is then concluded by noticing that the dynamics of the previously mentioned system around the synchronization manifold yield the variational equation used, according to the MSF approach [4], to calculate the Lyapunov exponents. Now, since the system is contracting, then its Lyapunov exponents will be negative, as shown in [1], immediately implying negativity of the MSF. ■

## REFERENCES

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