

Corrections to “Robust Image-Based Water-Level Estimation Using Single-Camera Monitoring”

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IN THE above article, we find that formula (11) has an error. It was introduced during the manuscript editing process and did not affect the results. We are sorry for this error and have corrected it. The corrected formula (11) is as follows:

$$T = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & \frac{-l}{\sin \theta} \\ 0 & 0 & 0 & 1 \end{bmatrix}. \quad (11)$$

REFERENCES

- [1] L.-C. Kuo and C.-C. Tai, “Robust image-based water-level estimation using single-camera monitoring,” *IEEE Trans. Instrum. Meas.*, vol. 71, pp. 1–11, 2022.

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