A Novel Image-based Homomorphic Approach for Preserving the Privacy of Autonomous Vehicles Connected to the Cloud

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***Abstract*—The necessity for IoTs and automation systems is set to revolutionize our lives. Autonomous vehicles are taking a leap forward by performing operations without human intervention through continuous monitoring of their surroundings using multiple sensors. The images gathered through vehicles' mounted cameras are large, requiring specialized storage such as cloud. However, cloud is prone to security and privacy challenges. This paper, for the first time proposes a partial image-based homomorphic searchable encryption scheme. The scheme uses pixel-level homomorphic encryption to identify the encrypted objects within encrypted images and provides Object-Trapdoor and Trapdoor-Image Indistinguishability as the trapdoors are probabilistic. The proposed scheme is deployed on the cloud and tested over a real data set. The performance analysis highlights the necessity of cloud-based computations and illustrates the effectiveness of the system. The proposed scheme reduces the storage overhead by approximately 20 times and is nearly 33 times more efficient as compared to the generic Paillier homomorphic searchable encryption scheme. The security analysis yields the scheme maintains high levels of security and privacy.**

***Index Terms*—Paillier homomorphic encryption, partial image encryption, Searchable Encryption.**

I. Introduction

THE necessity for Internet of Things (IoTs) in industrial production has been rising in tandem with the industrial IoTs' exponential development [1]. With a shift to automation from manual operations, self driving vehicles are a contemporary development. A self-driving automobile travels from one location to another with minimum driver intervention. This is possible due to multi-sensory input from cameras, sensors, lidar, and radars to supply the necessary technology, thus enabling vehicle operation on public roads [2]. Figure 1 shows different sensors in an autonomous car. To be automated, automobiles must be capable of detecting multiple objects such as cars, trucks, traffic signals, animals, lanes, pedestrians etc. and action a viable response accordingly.

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There are, however, several obstacles in regards to the transitioning from non-autonomous to fully autonomous vehicles, such as the danger of accidents, establishing road traffic rules and accountability. The combination of human drivers and self-driving automobiles might pose a risk at certain hazardous angles and lightening conditions where accidents are likely to take place [3]. There are several legal concerns for law enforcement agencies when it comes to tracking autonomous automobiles or having significant surveillance data as a result of artificial intelligence [4]. The automated vehicles are able to provide their services due to multi-sensory inputs and various cameras hosted on their exterior which leads to generation of a significant amount of data. This data can be in the form of images / videos and / or real time webcam feed that needs to be stored and processed for further use *e.g.* for surveillance, location tracking, keeping record of vehicle movements and protection of owners etc. Local storage and management of this data poses a challenge to vehicle owner(s) and raises concerns regarding security and privacy of autonomous vehicles' data and calls for the need of third party storage.

Cloud computing is the provision of on-demand computation and storage resources through the internet on a pay-as-you-go basis. To decrease the expenses of local maintenance, an increasing number of users opt for outsourcing their data to the cloud server [5]. However, outsourcing of data comes with its own challenges, the foremost of which is data confidentiality. Moreover, there remains the need to ensure integrity of data, its authenticity of access control in communication as well as its storage. It implies that data should be secured against unauthentic modification and scheme(s) should be employed to ensure legitimate access control and authorization. One of the major problems for cloud computing is data privacy, since the cloud server is not considered a fully trusted entity and assumed to be *honest but curious* to gain information about the outsourced data. Although end-to-end encryption ensures the security of users' data, it eliminates the ability to carry out searching over it.

Homomorphic encryption schemes enable the users to process and work on the data without decryption, thus saving resources and time in terms of efficiency [6]. Mathematically, it means that the processing done on plaintext after encryption will yield the same result as if the same process was done before on the plaintext and then it was encrypted afterwards. In this way, the underlying plaintext remains unchanged with no threat to its integrity even after performing various operations.

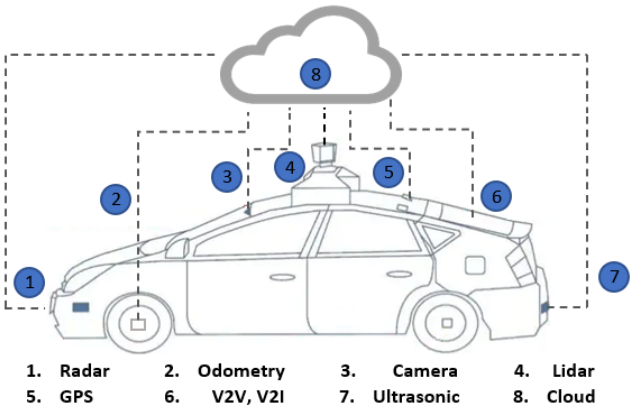

Fig. 1. Autonomous Vehicle Multi-Sensory Inputs and Cloud Connectivity

The data generated by the multi-sensor cameras of autonomous vehicles, as discussed, is so extensive that it needs to be outsourced yet be secured so that it is not accessible to unauthorized users. For that, all the searching needs to be carried out over encrypted images stored on cloud. In addition to that, search pattern security should be ensured so that no information is revealed about the encrypted image data from the searching history. A searching query should be randomized so that trapdoors are generated probabilistically and no two similar trapdoors are generated even for the same query. The capability of searching over homomorphically encrypted data with privacy preserving mechanisms by probabilistic trapdoors along with the need for autonomous vehicles' big data storage forms the motivation of this research.

A. Contributions

The following contributions are made in this research:

- The prevalent issue of security and privacy associated with autonomous vehicles connected to the cloud is addressed for the first time through homomorphic-based searchable encryption.
- For the first time, a novel partial image-based homomorphic scheme is proposed for preserving the privacy of autonomous vehicles, which carries encrypted searching over encrypted image data (at pixel level) gathered from the camera embodied within an autonomous vehicle. The Searching is carried out over probabilistic trapdoors so to provide security against search pattern leakage.
- The scheme is deployed in a real cloud environment "Contabo" and tested on a real world data set to evaluate the effectiveness of the proposed approach. The proposed scheme reduces the storage overhead by approximately 20 times and is nearly 33 times more efficient as compared to generic Paillier HE based searching scheme.

B. Outline

The rest of the paper is organized as follows: Related work is discussed in Section II. Section III presents the preliminaries. Section IV discusses the system model. Section V revisits the security definitions. Section VI put forwards the proposed methodology. Security and performance analysis are discussed in Section VII and VIII respectively while Section IX concludes the paper and explores future works.

II. Related Work

Over the years, research on image processing algorithms and searchable encryption (SE) systems for encrypted image data has highlighted its high computational and resource requirements. There are different image processing techniques and thus provide for a vast ground for image searching mechanisms *i.e.* feature detection, content based searching and digital watermarking etc [7]. For the past few years, research scholars working in the field of image processing have been working on extracting features from heavily encrypted image data sets. Different searchable encryption schemes [8] are employed for encrypted image searching over cloud *i.e.* homomorphic encryption, asymmetric watermarking, zero knowledge proofs and zero knowledge watermarking detection to name a few. Application of existing techniques over encrypted images has been an open challenge for data owners over the past few years and many different theoretical proposals as well as mathematical models have been presented to counter issues in this domain [8] [9].

The initial presentation of searchable encryption over image data was claimed to be carried out by [10] with the help of Scale Invariant Feature Transform (SIFT) [28] and homomorphic encryption. The research lacked the property of privacy preservation and had the drawback of huge overhead at user's end. These vulnerabilities were addressed in [11] using multi-cloud model incorporating user's privacy preservation of data while retaining the image's original SIFT features. An image feature extraction scheme privacy preservation using SIFT (PPSIFT) was proposed in [12] based on Paillier cryptosystem. The design goals and technological problems of implementing a cloud-based privacy-preserving image processing system were examined in [13]. An approach based on Hahn Moment [29] was put forward by [14] using somewhat homomorphic encryption (SHE) and claimed that its model provided confidentiality and privacy preservation of reconstructed images. Another scheme for images' feature similarity searching over cloud environment was presented in [15]. It tackled both local and global feature extraction / retrieval under Earth mover's distance metric [30] and searchable generation of indices. An alternative technique for privacy preservation of image data based on Linear Binary Pattern (LBP) was put forward in [16] to retrieve features from images after encryption using Image Plane Encoding algorithm with most significant bit (MSB) and converting images into matrices. A cloud-assisted efficient and privacy-preserving CBIR (EPCBIR) technique was suggested in [17]. The authors based their scheme on LSH and kNN algorithms for indexing and image feature security respectively. While their scheme provides a ranked based image searching scheme, it calls for high computational resources. For the encryption and security of images and their pertinent attributes, the approach in [31] employs the same LSH and kNN algorithms as [17].

The authors in [18] put forward a scheme for user's privacy in outsourcing image data using K-means for generation of

TABLE I
COMPARATIVE ANALYSIS OF IMAGE BASED SEARCHING SCHEMES

Research Paper	Technique Used	Index based	HE based	Search Pattern Security	Probabilistic Trapdoor	Privacy Preservation
Secure searching over encrypted images [10]	SIFT	✓				
Multi-cloud model for user's privacy preservation [11]	SIFT	✓	✓			✓
Privacy preserving searching over encrypted images [12]	PPSIFT & RSA		✓		✓	✓
Cloud-based privacy-preserving image processing system [13]	SIFT, HOG & SHE		✓			✓
Privacy-preserving of reconstructed images [14]	Hahn Moment & SHE		✓			✓
Image feature based similarity searching scheme [15]	Earth Mover Distance Metric	✓				
Image features based technique for privacy preservation [16]	Linear Binary Pattern	✓				
Ranked searchable encryption scheme [17]	LSH & kNN	✓				
Privacy-preserving of Image data [18]	K-means for Indices generation	✓				✓
Content Based Image Retrieval (CBIR) scheme [19]	DCT	✓				
Privacy preservation CBIR (PIC) [20]	kNN means & Multilevel Homomorphic Encryption	✓	✓			✓
CBIR over Mobile Cloud Computing [21]	LSH & SIFT	✓				✓
Privacy Preserving Searching over Encrypted Medical Image data [22]	CNN & PHE		✓	✓		✓
Efficient Privacy Preserving Image Similarity Detection [23]	PHE & Euclidean distance		✓			✓
CBIR scheme over Cloud [24]	Inception with ResNet v2 (SIRS-IR) & Multiple Share Creation (MSC)					✓
Privacy Preserving Image retrieval scheme [25]	4D chaotic map & AES	✓				✓
Privacy preserving medical IR scheme [26]	CNN & Random Number Generator	✓		✓	✓	✓
TDHPPIR [27]	CNN based Hash	✓				✓
Proposed Scheme	PHE & Partial Image Encryption		✓	✓	✓	✓

indices. An encrypted images based secure retrieval scheme was presented in [19] where index generation and content based searching is carried out at CSP by carrying out Discrete Cosine Transform (DCT). Yuan *et al.* proposed a Secure and Efficient Encrypted Image Search with Access Control (SEISA) in [32]. The scheme, based on LSH kNN algorithms, claims to be lightweight and provisions searching access control for image retrieval over cloud storage. Another scheme for privacy preservation CBIR for large scale data over cloud was discussed in PIC [20]. PIC enables users to search over encrypted images with efficient access controls defined by data owners. Encrypted image searching in mobile cloud domain was discussed in [21]. A Privacy-preserving image search (PPIS) was presented in [22] for large scale medical image data using convolutional neural network (CNN). The authors claimed secure search queries and privacy preservation of image data.

A scheme for partial image encryption for Internet of Things (IoTs) was initially proposed by Jang and Lee [33]. The proposed scheme was based on format preserving encryption algorithms of FF1 and FF3-1. Hybrid schemes for image encryption are discussed in [34] [35]. A partial image encryption scheme for medical image data was proposed in [36] which incorporates Discrete Cosine Transform (DCT) along with the encryption algorithm. Panduranga and Naveenkumar [37] put forward a selective encryption methodology for securing satellite and medical images. Partially encrypting RGB image data with pixel position modification based on region of interest is presented in [38]. It claimed security features of partial encryption and the scheme partially reconstructs the images. The scheme also offers the storage of encrypted data indefinitely using the SMART (Self Monitoring Analysis and Reporting Technology Copyback) method. In [39], design and implementation of a system that uses a dynamic privacy-preserving partial image sharing technique (PUPPIES) was proposed. The scheme allows data owners to specify specific private regions (e.g. face, SSN number) in an image and to set different privacy policies for each user as a result. A novel scheme for partial image encryption of medical media data was discussed in [40]. A variety of partially encrypted images were obtained by altering the DNA patterns of a chaotic DNA sequence and performing DNA addition. Various partial image encryption techniques are discussed in [41] for smart camera and in [42] for wireless multimedia sensor networks.

Some of the existing schemes for image-based searching are given in table I. It is evident from the table that while some

existing image based schemes [11], [12], [14], [20] and [22] are based on homomorphic cryptosystems, they neither operate on partial images nor do they offer the feature of probabilistic trapdoors. Moreover, the schemes that are dealing with partial image encryption [33], [36], [37], [39]–[42] are based on non-homomorphic schemes without probabilistic trapdoors. To the best of our knowledge, there is no existing scheme dealing with partial image processing, homomorphic searchable encryption with probabilistic trapdoors. This further highlights the claim that the scheme presented in this research is a novel development in the case of partial image encryption technique based on homomorphic encryption and enables searching over the cloud with no threat to data security or privacy.

Algorithms for object detection can be classified on the basis of their approach *i.e.* machine learning and deep learning; as well as their stages *i.e.* single and dual stage detection. Dual stage detection implies object location and classification. Different object detection algorithms are discussed in [43] [44]. The development of YOLO version 4 has reevaluated the performance and accuracy of object detection. It is based on the CSPDarkent53 architecture. Spatial pooling is utilised in the backbone to enhance receptiveness and to locate the necessary characteristics of data images / video frames [45]. It boasts of lesser requirement of storage and computational time. YOLO version 5 was released not long after YOLO v4 with 4 different models having different accuracy levels. However, YOLO v4 is by far considered the fastest real-time model for object detection till date.

III. Preliminaries

A. Paillier Homomorphic Cryptosystem

In 1999, Paillier cryptosystem [46] was proposed by Pascal Paillier with features of asymmetric probabilistic encryption and additive homomorphic property. This partial homomorphic encryption scheme is IND-CPA secure. The basic structure of Paillier cryptosystem consists of the following three phases: *i.e.* key pair generation, encryption and decryption.

1) **Key Pair Generation:** It consists of computing n by $n = pq$ and $\lambda = lcm(p-1, q-1)$ where p and q are two independent large prime numbers. A generator g is then selected such that $g \in Z^*_{n^2}$; with order of g being a multiple of n *i.e.* $gcd(n, \lambda) = 1$. The key pair are secret key = (p, q) and public key = (n, g).
2) **Encryption:** A random integer $r \in Z^*_n$ is chosen such that $r < n$ and a message $m \in Z_n$ is encrypted by: $E(m) = g^m.r^n \ mod \ n^2$
3) **Decryption:** A ciphertext c_T is decrypted by taking discrete logarithm of $c^\lambda \in Z_n$ to obtain λ. Since $gcd(n, \lambda) = 1$, thus inverse $\lambda^{-1} \ mod \ n$ is calculated to retrieve message m.

IV. System Model

A. Network Model

The network model comprises of three entities *i.e.* an autonomous vehicle, data owner and a cloud server (CS). The autonomous vehicle, while on road, generates a lot of data through its cameras and sensors; and responds accordingly. The data generated through the mounted camera can be stored locally or transmitted at run time to the owner where it is processed and encrypted before being outsourced to CS. The term 'images/ image data' here refers generally to all footage / video frames / images etc. The network model, however, deals with the secrecy and storage of image data as well as capability of an owner to securely search over encrypted image files. The system flow diagram is shown in figure 2.

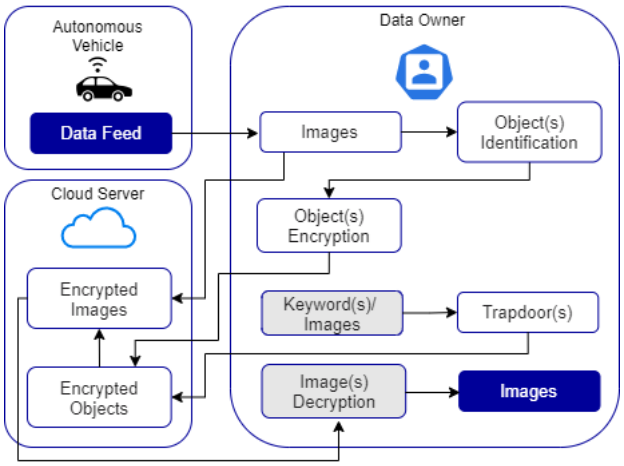

Fig. 2. System Flow Diagram

The owner is the entity that, upon receiving the data, encrypts all images using a standard encryption algorithm such as AES and stores them on CS. It also processes the images for object identification and classification based on image processing techniques such as YOLO v4 whereas encryption of image objects at pixel level is carried out by Paillier homomorphic encryption. All those encrypted objects are then outsourced to the CS. Any user can request access to any image through a trapdoor generated by a specific query and can decrypt the image provided he has the secret key. The user can also be the data owner in proposed case. A trapdoor is generated by Paillier homomorphic scheme when a user inputs a query image object and requests an image containing that particular object. The CS carries out the search and returns a set of encrypted image(s) containing the encrypted object. The user / data owner can decrypt the encrypted image(s) with the secret key to retrieve the original image. Figure 3 represents different phases of proposed scheme. Figure 3 (a) presents the image encryption phase whereas figure 3 (b) exhibits the image decryption phase. Figure 3 (c) shows the object(s) encryption where the detected objects in an image, are pixelated and pixel values are encrypted by Paillier HE after flatting their RGB values. Figure 3 (d) shows the trapdoor generation from an image where the exact same process is carried out as figure 3 (c). However, in the case of trapdoor generation, even for the same object, query yields a different set of encrypted pixel values of trapdoor as the searched object(s).

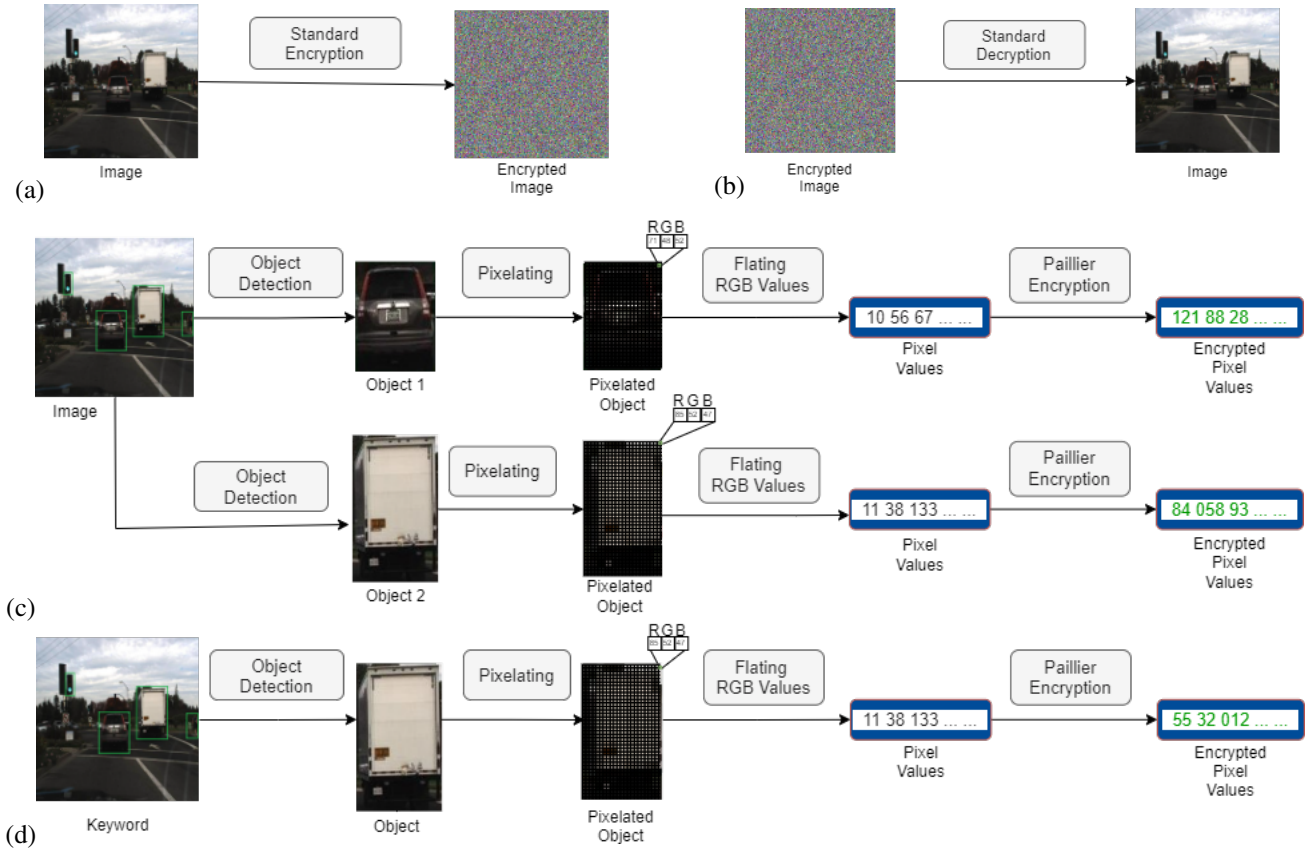

Fig. 3. The Proposed Scheme (a) Image Encryption (b) Image Decryption (c) Object(s) Encryption (d) Trapdoor Generation

B. Threat Model

The threat model is established with 2 entities *i.e.* data owner / user and CS, where data is images in the proposed case. An adversary's main aim is to gain unauthorized access to images stored on CS. Since all the communication between owner and CS is carried out via public channel, an adversary can easily intercept and launch attack(s) to uncover the underlying data. Adversary in the proposed case could be an outsider or the *honest but curious* CS with the following capabilities / conditions:

- Only passive attacks can be launched by the CS to analyse data or to follow network activity in order to detect any data or information that might be linked to the encrypted content of images outsourced to the CS.
- Only a polynomially limited number of operations *i.e.* encryption, decryption and / or passive attacks *etc.* may be performed by the attacker. The adversary is not permitted to make a limitless number of attempts or deduce the actual image in an unlimited amount of time.
- The adversary can track the past search queries, search results and the communication pattern of data owner with CS and can utilize this information to its advantage.

C. Assumptions

In this research, the following assumptions are made:

- The image feed generated by the autonomous automobile is communicated to the data owner over a secure channel that can not be intercepted by any adversary.
- The owner is presumed to be completely trustworthy and poses no harm to the system's security.

D. Security Goals

Following security goals are defined for this research:

- Search pattern hiding, trapdoor unlinkability and mitigating distinguishability attacks: Search pattern refers to the leakage associated with the search queries. It reveals to the adversary if the same object is being searched repeatedly. This requires to have probabilistic / randomized trapdoors. Such trapdoors prevent the distinguishability attacks.
- Adaptive Security: In the known ciphertext model, the scheme should be proven secure. This means that the CS should not be able to extract anything about the query terms, even if they are aware of the history of previously searched trapdoors in an adaptive adversarial model.
- Secure Trapdoor Generation: Only an authorized person having the correct secret keys should be able to generate a meaningful trapdoor.

V. Security Definitions

In this section, the current SE security definitions are revisited to establish the security of the proposed scheme.

These definitions are aligned with the definitions proposed in [47] which are widely accepted and employed in case of probabilistic trapdoor-based searchable encryption schemes.

SD_1: Object - Trapdoor Indistinguishability

Object - Trapdoor Indistinguishability is defined as the process of searching carried out by encrypted trapdoors generated by unencrypted queries. For every query, a trapdoor is generated which is randomized and probabilistic in nature such that the same query being searched twice will yield two trapdoors entirely different from each other and no trapdoor will reveal any information about the underlying query. An adversary $\mathcal{A}$ is unable to distinguish between the trapdoors even if provided with adaptive history of queries and their associated trapdoors. To forecast contextually relevant query information, the adversary $\mathcal{A}$ must execute a large number of operations in polynomial time and record a massive volume of data.

The challenger initiates the process by generating multiple encrypted image objects' trapdoors against image data Img_i. The adversary sends a query object Q_{obj_i} and challenger returns the encrypted trapdoor T_{obj_i}. This process continues until the adversary has accumulated polynomial many query object-trapdoor pairs. After this, the adversary chooses two query objects Q_{obj_a} and Q_{obj_b} and sends them over to the challenger. The challenger after tossing a fair coin $a \leftarrow \{0,1\}$; generates trapdoor T_{obj_a} for Q_{obj_a} and sends it to the adversary. The adversary has to make correct guess of query object associated to the received trapdoor *a* or *b* with a probability of higher than 1/2 to win the challenge otherwise the scheme is said to be secure with respect to Object - Trapdoor Indistinguishability.

Let $KeyGen, Enc_s, Enc, TrG, SearchOut, Dec$ be a partial image based homomorphic searchable encryption scheme over a set of images Img_i, image objects I_{obj_i}, query image object Q_{obj_i} security parameter λ and adversary $\mathcal{A}$ over *'N'* no of image objects respectively. A probabilistic experimental function is as follows:

$(k_s, k_p) \leftarrow KeyGen(primebits)$
$\mathrm{E}_{Img_i} \leftarrow Enc_s(Img_i, k_s)$
$\mathrm{E}_{obj_i} \leftarrow Enc(k_p, I_{obj_i})$
$for\ 0 < i < N:$
$(s_{\mathcal{A}}, Q_{obj_i}) \leftarrow \mathcal{A}(s_{\mathcal{A}}, T_{obj_1}, T_{obj_2}, ...T_{obj_i})$
$T_{obj_i} \leftarrow TrG(Q_{obj_i}, k_p)$
$a \leftarrow \{0,1\};$
$(s_{\mathcal{A}}, Q_{obj_0}, Q_{obj_1} \leftarrow \mathcal{A}(k_s, k_p)$
$T_{obj_a} \leftarrow TrG(Q_{obj_i}, k_p)$
$a' \leftarrow \mathcal{A}_{N+1}(s_{\mathcal{A}}, T_{obj_a})$
$T_{obj'_a} \leftarrow TrG(Q_{obj_j}, k_p); j \in N$
$if a' = a;\ output\ 1;$
$otherwise\ output\ 0$

where $s_{\mathcal{A}}$ shows the adversary A's state. The scheme is said to be secure with respect to Object - Trapdoor Indistinguishability if the following hold true.

$$Pr[Obj\_Trap_{\mathcal{A}}(\lambda) = 1] \leq \frac{1}{2} + ngl(\lambda)$$

SD_2: Trapdoor - Image Indistinguishability

The complexity of a homomorphic based searchable encryption protocol is related to trapdoor-image indistinguishability. The queries, trapdoors, and associated object searching should be complicated enough that the trapdoor does not reveal any information about the associated image objects prior to the search. As a result, even if the history (query, trapdoor, image object) is created adaptively, the trapdoor should be indistinguishable when the same search term appears again. Furthermore, a minute change occurring in the query should significantly alter the trapdoor and thus, the searching over it should yield an altogether different result than before and vice versa. An adversary should not be able to predict the trapdoor leading to the retrieved image from the list of encrypted objects. Thus, query security and users privacy are ensured throughout in an adaptive adversarial model.

The challenger initiates the process by generating multiple encrypted image objects against against image data Img_i. The adversary sends an encrypted trapdoor T_{obj_i} and challenger returns the corresponding image object. This process continues until the adversary has accumulated polynomial many trapdoor-image object pairs. After this, the adversary chooses two new trapdoors T_{obj_a} and T_{obj_b} and sends them over to the challenger. The challenger after tossing a fair coin $a \leftarrow \{0,1\}$; carries out searching among the encrypted image objects, selects a E_{Obj_a} and sends it to the adversary. The adversary has to make correct guess of image where it was the search result of trapdoor *a* or *b* with a probability of higher than 1/2 to win the challenge otherwise the scheme is said to be secure with respect to Trapdoor - Image Indistinguishability.

Let $KeyGen, Enc_s, Enc, TrG, SearchOut, Dec$ be a partial image based homomorphic searchable encryption scheme over a set of images Img_i, image objects I_{obj_i}, security parameter λ and adversary $\mathcal{A}$ over *'M'* no of images respectively. A probabilistic experimental function is as follows:

$(k_s, k_p) \leftarrow KeyGen(primebits)$
$\mathrm{E}_{Img_i} \leftarrow Enc_s(Img_i, k_s)$
$\mathrm{E}_{obj_i} \leftarrow Enc(k_p, I_{obj_i})$
$for\ 0 < i < M:$
$(s_{\mathcal{A}}, T_{obj_i}) \leftarrow \mathcal{A}(s_{\mathcal{A}}, Img_1, Img_2, ...Img_i)$
$Img_i \leftarrow SearchOut(E_{obj_i}, T_{obj_i})$
$a \leftarrow \{0,1\};$
$(s_{\mathcal{A}}, T_{obj_0}, T_{obj_1} \leftarrow \mathcal{A}(Img_i, k_p)$
$Img_a \leftarrow searchOut(E_{obj_a}, T_{obj_a})$
$a' \leftarrow \mathcal{A}_{N+1}(s_{\mathcal{A}}, Img_a)$
$T_{obj'_a} \leftarrow TrG(Q_{obj_j}, k_p); j \in N$
$if a' = a;\ output\ 1;$
$otherwise\ output\ 0$

where $s_{\mathcal{A}}$ shows the adversary A's state. The scheme is said to be secure with respect to Trapdoor - Image Indistinguishability if the following hold true.

$$Pr[Trap\_Img_{\mathcal{A}}(\lambda) = 1] \leq \frac{1}{2} + ngl(\lambda)$$

VI. Proposed Methodology

The image searching algorithm is twofold where an object is identified using an image detection algorithm such as YOLO

v4. The image is then encrypted with a standard encryption such as AES encryption. The object(s) identified are converted to pixels and these pixel values are then encrypted using Paillier homomorphic encryption scheme. The image search is based on those encrypted image objects. The notations and abbreviations used in the definitions and algorithms are mentioned in table II. The proposed scheme consists of following phases:

TABLE II
NOTATIONS AND ABBREVIATIONS

Ntn. / Abb.	Explanations
CS	cloud server
Enc()	the encryption function
Dec()	the decryption function
p, q	denote prime numbers
primebits	Number of bits
k_p	Public Key
k_s	Secret (private) Key
GCD()	Greatest common divisor function
LCM()	Least common multiple function
glambda (λ)	λ = LCM(p-1,q-1)
gmu (μ)	Modular Multiplicative Inverse
RN()	returns a random number
getprime()	returns the N-bit prime number
S_{ub}	subtraction function
S_a	results of the Subtraction function
R_V	result dictionary containing Obj IDs & S_a
T_{obj_i}	trapdoor image object
Q_{obj_i}	query image object
I_{obj_i}	Image object(s)
E_{Img_i}	Encrypted Image(s)
E_{obj_i}	Encrypted Object(s)
E_{F_i}	Encrypted File(s)
D_{Img_i}	Decrypted Image

1) **Key Generation** $(k_s, k_p) \leftarrow KGen(primebits)$**:** It is a probabilistic algorithm that returns a Public Key and Secret (Private) Key based on key pair generation phase of Paillier cryptosystem [46]. The algorithm takes a parameter of primebits which determine the number of bits for generating a prime number. The algorithm returns a k_s and k_p. The input parameter "primebits" is used to generate two random prime numbers p & q independent of each other, through which k_s and k_p is generated. The k_s is kept secret and is used for decryption, whereas the k_p can be shared and is used for encryption.

Algorithm 1 Key Generation $(k_s, k_p) \leftarrow KGen(primebits)$

Generate p = getprime (primebits,RN)
Generate q = getprime (primebits,RN)
Let $n = p * q$
while $g = RN()$; $GCD(g, n^2) \neq 1$ **do**
  Compute λ = LCM (p-1,q-1)
  Compute Modular Multiplicative Inverse:
  $\mu = (L(g^{\lambda}) mod n^2)^{-1} mod\ n$
  Compute: $l = (pow(g, \lambda, n^2) - 1)/n$
  Calculate: $gmu = libnum.invmod\ (l, n)$
end
return k_s = (λ, μ), k_p = (n, g)

2) **Image Encryption** $E_{Img_i} \leftarrow Enc_s(Img_i, k_s)$**:** The images Img_i are encrypted by AES using secret key k_s and returns encrypted images E_{Img_i}.

Algorithm 2 Image Encryption $E_{Img_i} \leftarrow Enc_s(Img_i, k_s)$

for $i \leftarrow 0$ **to** *M; M are number of images* **do**
  $Enc_s(Img_i, k_s)$ = E_{Img_i}
end
return E_{Img_i}

3) **Object Encryption** $E_{obj_i} \leftarrow Enc(k_p, I_{obj_i})$**:** This phase, first identifies the objects Obj_i available in images Img_i and returns the object class name and then encrypts those image objects. The encryption process is based on encryption phase of Paillier cryptosystem [46] where ciphertexts are generated by an encrypting image objects I_{obj_i} using public key k_p in a *for loop* using *pow() function*. The power function is a simple exponential that will raise the input parameters i.e. g, Obj_i, n^2 to yield the encrypted objects E_{Obj_i}.

Algorithm 3 Object Encryption $E_{obj_i} \leftarrow Enc(k_p, I_{obj_i})$

for $i \leftarrow 0$ **to** *N; N are the number of objects* **do**
  for $i \leftarrow 0$ **to** Obj_i **do**
    Enc $(g^{I_{obj_i}}.r^n)$ % n^2
    E_{Obj_i} = $pow(g, Obj_i, n^2)$
    E_{F_i} = write (E_{Obj_i})
  end
end
return E_{F_i}

4) **Trapdoor Generation** $T_{obj_i} \leftarrow TrG(k_p, Q_{obj_i})$**:** This phase takes a query as input where the query is in the form of an image object. A trapdoor T_{obj_i} is generated by object identification of the query image and encryption of that object Q_{obj_i} using public key k_p in a *for loop* using *pow() function*. The encrypted value of trapdoor will be different for every instance if the same object is encrypted again such that $E_{Obj_i} \neq E'_{Q_{obj_i}}$ if the underlying object is same. The algorithm for generation of trapdoors is based on encryption phase of Paillier cryptosystem [46].

Algorithm 4 Trapdoor Generation $T_{obj_i} \leftarrow TrG(k_p, Q_{obj_i})$

for $i \leftarrow 0$ **to** *K; K are the number of objects pixels* **do**
  Enc $(g^{Q_{obj_i}}.r^n)$ % n^2
  $E'_{Q_{obj_i}}$ = $pow(g, Q_{obj_i}, n^2)$
  T_{obj_i} = write $(E'_{Q_{obj_i}})$
end
return T_{obj_i}

5) **Search Out** $E_{Img_i} \leftarrow SearchOut(E_{obj_i}, T_{obj_i})$**:** The searching algorithm takes a set of encrypted files E_{obj_i} and a trapdoor T_{obj_i} as an input. Firstly, the trapdoor T_{obj_i} is subtracted from the E_{obj_i} pixel by pixel through the subtraction function S_{ub}; the values are then accumulated as S_a. A result dictionary R_V containing S_a

values and encrypted objects' IDs is sent to the user. The user decrypts the R_V values and occurrence of zero corresponds to a match *i.e.* requested image being stored over cloud. The user then requests explicitly with the image's ID with respect to the object's ID mapping and the corresponding E_{Img_i} is sent over to the user by CS.

Algorithm 5 Search Out $E_{Img_i} \leftarrow SearchOut(E_{obj_i}, T_{obj_i})$

for $i \leftarrow 0$ **to** E_{F_i} **do**
  $S_a = S_{ub}(T_{I_i}, E_{F_i})$;
  $R\_V = \sum_{a=1}^{i} S_a$
end
return *R_V*
At User's End:
for $y \leftarrow 0$ **to** R_V **do**
  if Dec $(R\_V_y, k_s).get(R\_V_y) == 0$
  $E_{Img_i} = getImage(R\_V_y)$
end
return E_{Img_i}

6) **Image Decryption** $Img_i \leftarrow Dec(E_{Img_i}, k_{aes})$**:** It is the decryption process where user decrypts the encrypted image E_{Img_i} retrieved from CS with private AES key k_{aes} and gets the original image data Img_i.

Algorithm 6 Image Decryption $Img_i \leftarrow Dec(E_{Img_i}, k_{aes})$

for $i \leftarrow 0$ **to** *N; N are number of encrypted images* **do**
  $Dec\ (E_{Img_i},\ k_{aes})$ = D_{Img_i}
end
return Img_i

A. Correctness

The correctness of a scheme specifies that decryption of a homomorphic evaluation on a ciphertext must be identical to evaluation on the underlying plaintext message. Thus, the proposed scheme is deemed correct if the security parameters (g, λ, μ) and key pair k_p, k_s for encrypted image objects E_{Obj_i} by $Enc(k_p, Obj_i)$, the searching by trapdoors T_{I_i} always results in return of corresponding image objects present. Following conditions are met in the proposed scheme with significant probability:

- For $Q_{obj_i} \in I_{Obj_i}$;

$$SearchOut\ (k_p, T_{obj_i}, E_{obj_i}) = I_{Obj_i} \cap Dec(k_s, R\_V) = I_{Obj_i}$$

- For $Q_{obj_i} \notin I_{Obj_i}$;

$$SearchOut\ (k_p, T_{obj_i}, E_{obj_i}) = I_{Obj_i} \cap Dec(k_s, R\_V) = 0$$

B. Soundness

The soundness of a scheme entails that searching phase of a homomorphic evaluation on an encrypted query must be identical to evaluation on the underlying keyword and produce sound encrypted results. A scheme is considered sound if the security parameters (g, λ, μ) and key pair k_p, k_s for encrypted image objects E_{Obj_i} by $Enc(k_p, Obj_i)$, the searching by trapdoors T_{I_i} never produce false positives and always produce substantial search outcomes. Following conditions are met in the proposed scheme with significant probability:

- For $Q_{obj_i} \in I_{Obj_i}$;

$$SearchOut\ (k_p, T_{obj_i}, E_{obj_i}) = 1$$

- For $Q_{obj_i} \notin I_{Obj_i}$;

$$SearchOut\ (k_p, T_{obj_i}, E_{obj_i}) = 0$$

VII. Security Analysis

The proposed scheme's phases of key generation, object encryption, and trapdoor generation are based on Paillier cryptosystem's key generation and encryption phases respectively. The proposed scheme yields different encrypted image objects by probabilistic encryption and generates a different trapdoor for the same query on every repetition. The mapping to a trapdoor to an encrypted image object is carried out over a probabilistic searching algorithm leaving the adversary $\mathcal{A}$ with no possible means to correctly guess the underlying image and / or image objects from an encrypted retrieved result. It is also not possible for an adversary $\mathcal{A}$ or CS to guess or predict the search pattern. Thus, due to the probabilistic trapdoors, the proposed scheme fulfils security definition SD_1.

Searching in the proposed scheme is carried out at the pixel level of images. This implies that two seemingly identical images with a difference of only one pixel will not be matched and only exact search results will be returned to the user. Prior to the search, it is difficult for an adversary $\mathcal{A}$ to create a link between the query images, trapdoors and search outcomes. This is also true even if the adversary $\mathcal{A}$ keeps a track of the search history and its results. Therefore, the chance of predicting the right outcome of an adversary $\mathcal{A}$ is less than 1/2 since the object queries to trapdoors are produced using probabilistic encryption and each encrypted trapdoor is unique. Hence, the proposed scheme fulfils security definition SD_2.

In a typical model, it is assumed that the attack is initiated by adversary $\mathcal{A}$, thus the adversary is not restricted by substituting any weak structure for the proposed method. The information that is exposed within polynomial time is the focus of the leakages described below:

- Leakage L_1: It is associated with data stored on CS. *i.e.* number of encrypted images and number of encrypted image objects. All image data outsourced on CS is stored after encryption so the CS can have no information about the underlying plaintexts but only about the number of files being stored on it.

$$L_1 = \begin{Bmatrix} E_{Img_i}, E_{obj_i}, (number\ of\ E_{Img_i}), \\ (number\ of\ E_{Obj_i}) \end{Bmatrix}$$

- Leakage L_2: It is associated with the generation of trapdoors from queries. The trapdoor is probabilistically

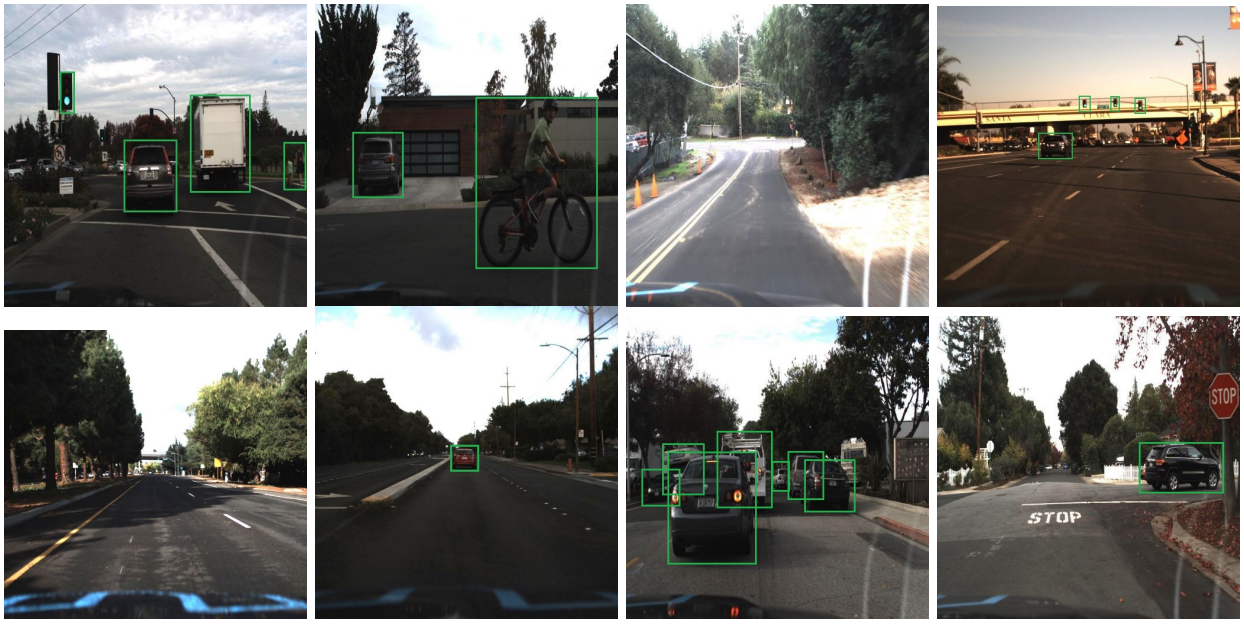

Fig. 4. Multiple Images from Dataset Representing the Presence of Non-uniform Objects

generated by Paillier encryption and reveals no information about the underlying query image object.

$$L_2 = \left\{((g^{Q_{obj_i}}) * (r^n))(modn^2)\right\}$$

- Leakage L_3: It is associated with the proposed scheme's search outcome. The searching is carried out at CS and its results are accessible to all entities including CS, data owner as well as adversary $\mathcal{A}$. The search outcomes are encrypted results of a subtraction operation and can only be decrypted by data owner (in possession of the secret key) and reveal no information about the underlying search queries or image objects.

$$L_3 = \left\{S_{ub}(T_{obj_i}, E_{obj_i}), (R\_V)\right\}$$

The assumptions and leakages described above are interconnected and interdependent. As a result, to achieve the highest level of security, it is required that all security assumptions are scrupulously observed. Furthermore, none of the leakages are giving away the plaintext or any information about the characteristics of plaintext; therefore the proposed scheme strengths and align with the security definitions. Also, such a scheme can be called as a privacy-preserving searchable encryption scheme as per the Corollary 1 presented in [47].

VIII. Performance Analysis

The simulations were carried out in a client-cloud scenario where the standard encryption / decryption (AES in this case) of images, Paillier HE for image objects is carried out at client's end and Paillier HE searching is done over at CS.

A. System Specification

- **Client Side:** The client's side simulations were carried out on OS Ubuntu 18.04.5 LTS (64 bits) with 16 GB RAM, Intel Core i7-7700 CPU @ 3.6 GHz x 8 and 1 TB SSD storage.
- **Server Side:** The simulations were carried out on the Contabo Cloud Platform running an operating system Ubuntu 20.04 with CPU having 10 vCPU Cores, 60 GB RAM, 1.6 TB SSD storage, 1 Gbit/s port and data transfer rate of 32 TB traffic (100 Mbps).

B. Dataset Description

The images were taken from dataset [48]. The dataset, shared by Roboflow in April 2020, has been generated by a webcam mounted on a car with video frames from its feed treated as images. The data set contains more than 15000 images and labels of objects include car, truck, pedestrian, traffic lights etc. Object detection was carried by YOLO v4 on Google Colab. The images are diverse and non-uniform as evident from figure 4, with some having multiple detectable objects, some having objects far away from the detection range, some objects out of the car's driveway and some having no detectable object.

C. Performance Metrics

To measure the performance of the proposed scheme, tests were conducted over a total of 70 images. Figure 5 (a) represents the graphical representation of the results of standard encryption that was AES encryption of image data in proposed scheme. The encryption was performed by the client in iterations of 10 images to plot results easily in graphical representation. The graph is plotted with iteration of 10 images on x-axis against time in seconds on y-axis. It can be seen that the image encryption takes a linear time with the increase in the number of images and takes approximately 0.8 seconds to encrypt 70 images.

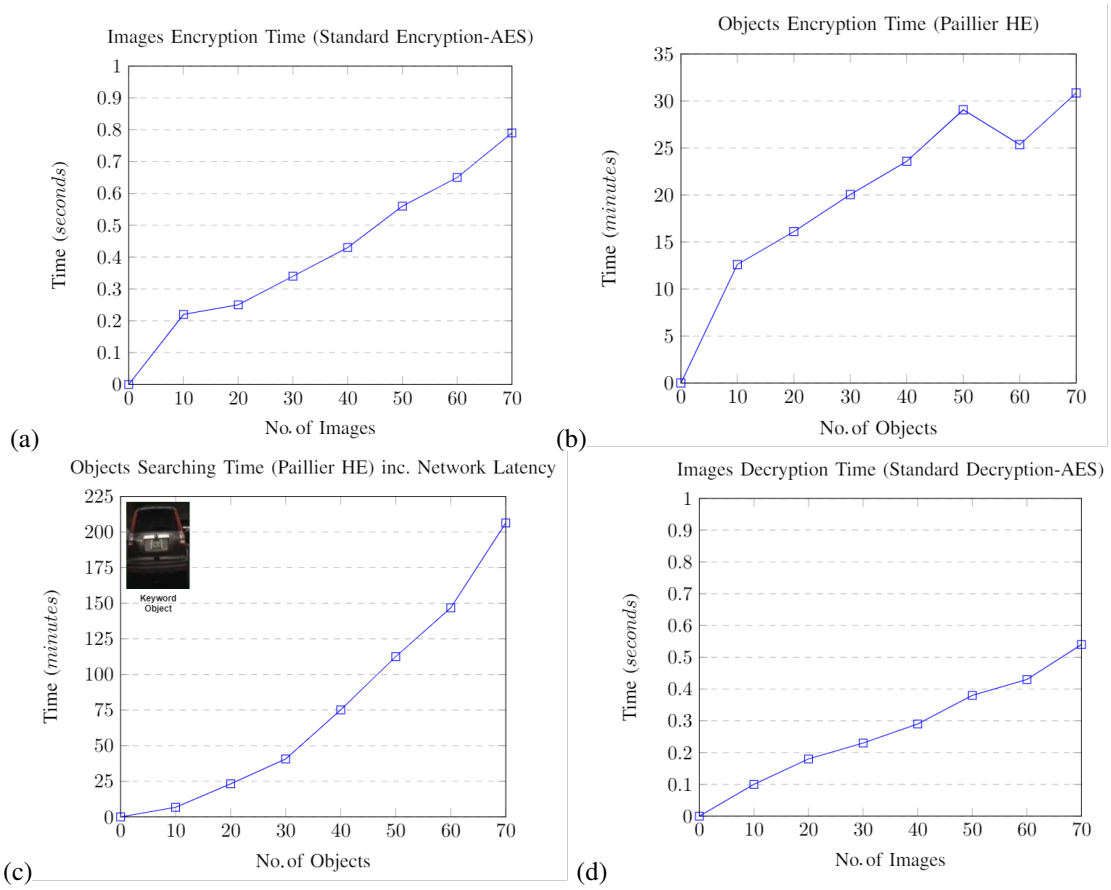

Fig. 5. (a) Image Encryption Time (Standard Encryption-AES) (b) Object Encryption Time (Paillier HE) (c) Object Searching Time (Paillier HE) including Network Latency (d) Image Decryption Time (Standard Decryption-AES)

Figure 5 (b) shows the image objects encryption time using Paillier homomorphic encryption performed on the client side. The image objects encryption was also carried out at client's end. A graph is plotted with iteration of 10 objects on x-axis against time in minutes on y-axis. A slight non-uniformity is observed due to the non-uniformity of the number of objects within the dataset. This has already been highlighted in the dataset description. The dip in the graph is due to the non uniform presence of objects in the images as shown in figure 4. For a total of 70 objects, the proposed scheme takes a total of 30 minutes. A trapdoor was generated by a query image of 85 Kbs in 21.23 seconds. The trapdoor was generated for the object "car" that has been shown within the 5 (c).

The object searching time is carried out on the Cloud Server. Since this is a true deployment, it also includes the network latency. As shown in 5 (c), a graph is plotted with number of images over which the searching is being conducted is plotted on x-axis and time in minutes is plotted on y-axis. It is evident that the searching is the most resource intensive task that requires some alternative resources such as the cloud. This is inline with the proposed assumption of importance of connecting autonomous vehicles to the cloud and to further emphasize on this, the cloud was configured to provide us the minimum resources. It is observed that to search against the previously generated trapdoor, the time required in 205 minutes. It is acknowledged that the searching is consuming too much time which is by virtue of not incorporating any mechanisms to enhance the performance such as multi-core processing and parallel threading (that will be done in the future). Figure 5 (d) shows the results of AES decryption of image data with no of images on x-axis and time in seconds on y-axis. The slope of which is linear, i.e. for 70 images the decryption time is approximately 0.55 seconds.

D. Performance Complexity

E. Performance Enhancements

The simulations were carried out of the proposed scheme with comparison against generic Paillier based homomorphic searchable encryption scheme [46] for 1 image containing 1 object as been shown within the 5 (c). The proposed scheme consists of image encryption and decryption by AES, object encryption and searching by Paillier homomorphic encryption and decryption of images is by carried out via AES. The AES encryption and decryption time for 1 image was carried out in 0.025 and 0.021 seconds respectively. The 2.55 MBs sized image was compressed to 770 Kbs after AES encryption and format was changed from 'jpeg' to 'png' to retain its original features. The size of object detected from the image was 146 Kbs and was increased to 1.79 MBs after Paillier encryption. Object encryption and searching by Paillier encryption was carried out in 21.68 and 21.04 seconds respectively. The

overall storage overhead of the proposed scheme comes out to be 2.54 MBs and takes up a total of 42.766 seconds.

The encryption, searching and decrytion of same image of 2.55 MBs by Paillier based homomorphic searchable encryption scheme, took 633.03, 263.31 and 507.11 seconds respectively. The storage overhead in this case came out to be 49.496 MBs. The total time for the execution of this scheme was calculated to be 1403.45 seconds. By this comparison, the proposed scheme reduces storage overhead by approximately 20 times and is nearly 33 times more efficient as compared to generic Paillier HE based searching scheme.

Another important metric to emphasize on the requirement of the cloud is the change in the size of image object data before and after Paillier HE encryption is performed. It can be seen in table III that for 70 images, the unencrypted image data size is 8.1 MBs which increases to 4.3 GBs after encryption. The data generated after encryption is so enormous that its local management and storage is a challenge and thus, the need arises for outsourcing it over at cloud. In future, we will also work on the compression of these encrypted images.

TABLE III
SIZE COMPARISON OF IMAGE OBJECTS BEFORE AND AFTER ENCRYPTION WITH PALLIER HE

No. of Objects	Unencrypted Image Objects Size	Encrypted Image Objects Size
10	2.8 MBs	261 MBs
20	4.8 MBs	808 MBs
30	5.4 MBs	1.3 GBs
40	6.3 MBs	2.1 GBs
50	7.3 MBs	2.7 GBs
60	7.0 MBs	3.6 GBs
70	8.1 MBs	4.3 GBs

IX. CONCLUSIONS AND FUTURE WORK

The data generated by the camera sensors of autonomous vehicles is extensive and poses a challenge for its local management and storage. The security challenges regarding data stored in the cloud leads to the requirement of searchable encryption techniques to search over the outsourced encrypted images. To this end, a novel partial image-based homomorphic scheme is proposed for preserving the privacy of data of autonomous vehicles. The proposed scheme allows search at the pixel level and uses Paillier homomorphic encryption. The generated search query / trapdoor is also probabilistic that leads to maintaining indistinguishability and hence the proposed scheme is termed as a privacy-preserving searchable encryption scheme. The proposed scheme is implemented and deployed in real cloud environment "Contabo" and tested over a real world data set to evaluate the effectiveness of the proposed approach. The proposed scheme reduces storage overhead by approximately 20 times and is nearly 33 times more efficient in performance as compared to generic Paillier HE based searching scheme. The results also demonstrate the correctness of the scheme and also highlight the requirement of connecting the autonomous vehicles to the cloud to achieve elevated levels of security and privacy. Since this work is the first of its kind, techniques towards improving the efficiency of the scheme by introducing parallel processing along with proposing mechanisms for compressing the images to reduce the required storage and shift from Paillier HE to other partial homomorphic and fully homomorphic approaches are prospective future research areas.

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