

Multiplicative Consistency Ascertaining, Inconsistency Repairing, and Weights Derivation of Hesitant Multiplicative Preference Relations

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Abstract—This article investigates multiplicative consistency ascertaining, inconsistency repairing, and weights derivation for hesitant multiplicative preference relations (HMPRs). First, the completely multiplicative consistency and weakly multiplicative consistency of HMPRs are defined. Based on them, 0-1 mixed programming models and simple algebraic operations are proposed to ascertain the multiplicative consistency of HMPRs. Then, some goal programming models are developed to generate the weights from consistent HMPRs and to revise inconsistent HMPRs. An integrated procedure to manage the multiplicative consistencies of HMPRs is designed. The proposed methods are also extended to accommodate incomplete HMPRs, and to estimate missing values. Finally, some numerical examples, a comparative analysis with existent approaches, and a simulation analysis are included to illustrate the practicality and effectiveness of the developed models.

Index Terms—Consistency ascertaining, hesitant multiplicative preference relations (HMPRs), inconsistency repairing, missing values, weights derivation.

I. INTRODUCTION

IN DECISION making, the following relations are widely used to represent the preference information of decision makers: multiplicative preference relation (MPR) [1], fuzzy preference relation [2], interval preference relation [3]–[5], intuitionistic preference relation [6]–[9], and linguistic preference relation [10]–[13]. However, these preference relations

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do not allow to handle situations where decision makers ascertain the membership of elements with a set of values derived from their hesitancy among several different values. To handle these cases, Torra [14] introduced the concept of the hesitant fuzzy set with elements in the unit interval $[0, 1]$. Based on the concept of the hesitant fuzzy set, Xia and Xu [15] used Saaty's analytic hierarchy process (AHP) 1/9–9 scale [1] to further define the concept of hesitant MPR (HMPR), which can vividly simulate both the decision makers' uncertainty and hesitation by allowing preferences to be expressed with hesitant multiplicative elements (HMEs) using the AHP scale.

In recent years, HMPR research has become a hot topic [16]. In particular, it is worth mentioning the HMPR research on priority weights derivation [17]–[20], consistency analysis [21]–[25], and group consensus [21], [26]–[29].

Consistency is one of the key and challenging issues that need to be resolved in decision-making processes. Inconsistent preferences can lead to bad decisions. Thus, methods have been developed to deal with the consistencies of the various preference relations [10], [11], [30]–[39]. Consistency of HMPRs, which can help decision makers to derive reasonable weighting values and decision results, has also received great attention recently with regard to the following two aspects: 1) consistency ascertaining: how to measure the consistency level of an HMPR and 2) inconsistency repairing: how to derive an HMPR with acceptable consistency from an inconsistent HMPR.

So far, research scholars have made some suggestions regarding consistency and the priority derivation of HMPRs. Indeed, Zhang and Wu [21] defined the multiplicatively consistent HMPR and developed a decision support model for group decision making as per the group consensus level. However, their α -normalization and β -normalization processes reduce or add some additional values to an HME, respectively, which destructs and distorts the decision maker's original judgments. Furthermore, Zhang and Wu [17] introduced the definitions of consistent HMPR and acceptably consistent HMPR, and derived the interval weights from HMPRs based on the β -normalization process but no inconsistency rectification process was proposed. Meng *et al.* also defined the consistency of HMPRs in [25], which is based on the assumption of any element in the HMEs forming a consistent MPR. In real applications, it is difficult to provide fully consistent MPRs, which is even more difficult in the case of HMPRs. If the uncertain information provided by a decision maker is

consistent, then this indicates that such decision maker possesses a strong logic and is sure of his/her information [40]. In other words, he/she knows his/her preferences perfectly well, and therefore he/she is not hesitant about his/her judgments in the HMPR. Mou *et al.* [23] defined the multiplicative consistency level of HMPRs and developed a method to repair inconsistency, which included a normalized process, and an artificial threshold of acceptable consistency level. Similarly, Nie [24]'s approach is based on a randomly given threshold of the consistency index, which lacks a theoretical basis. Zhang and Guo [41] gave some formulas for calculating the weights of incomplete HMPRs, but they only considered the acceptable consistent incomplete HMPRs and ignored the inconsistent cases that occur in practical problems. Lin *et al.* [42] constructed a linear programming model to obtain priorities from HMPRs. Additionally, HMPRs have been widely utilized to handle various practical issues, such as the allocation of water conservancy investment of river basins [18], [25], logistics service provider selection [42], and city sustainable development evaluation [43].

The above analysis highlights some research achievements with regard to the consistency of HMPRs. However, there are still some issues that remain to be solved. The research motivations of this article can be summarized as follows.

- 1) Existing multiplicative consistency research approaches are often hindered with drawbacks related to the changing of the decision makers' original judgments and the optional setting of consistency thresholds. Therefore, it is necessary to answer the following question: what is the multiplicative consistency of HMPRs and how can it be verified?
- 2) When decision makers hesitate to express their opinions in decision-making problems, a precise priority vector cannot represent the decision makers' hesitation judgments accurately and naturally [17]. Consequently, the following question needs answering: how to generate suitable and realistic weights from an HMPR with multiplicative consistency?
- 3) Decision makers with allodoxophobia may hesitate to deal with decision-making problems. Thus, the development of models to help decision makers eliminate their illogical, inconsistent, or unreasonable information could be really useful to decision makers in general, and to allodoxophobia decision makers in particular. Hence, a question to address is: if an HMPR is inconsistent, how can inconsistency be repaired?
- 4) There are few papers in the literature reporting on multiplicative consistency measurement, inconsistency level improvement, and weights derivation for incomplete HMPRs, which is addressed in this article.

To answer the above questions, two new multiplicative consistencies of HMPRs, completely multiplicative consistency and weakly multiplicative consistency, respectively, are introduced. Moreover, 0-1 mixed programming models and some algebraic approaches are developed to determine the consistency type for HMPRs. Goal programming methods are proposed to 1) derive priority weights from an HMPR and 2) find the inconsistent elements in an HMPR. This new

approach allows decision makers to assign suitable weights to different stages to reflect their preferences in HMPR problems. Subsequently, an efficient and flexible integrated algorithm is designed to test consistency, obtain logical weights, and repair inconsistency of HMPRs, while a novel method to judge the consistency type, estimate missing values, and derive priority vectors from incomplete HMPRs is developed.

The remainder of this article is arranged as follows. Section II introduces the required basic concepts of MPR, hesitant multiplicative sets (HMSs), and HMPR. Two new definitions of consistency of HMPRs are introduced in Section III. Section IV develops methods to ascertain the consistency of HMPRs. In Section V, a priority weight derivation model and an inconsistency repairing method based on multiplicative consistency are proposed. These are used to obtain consistent HMPRs and the reasonable alternatives ranking results. Section VI is devoted to incomplete HMPRs, and two multiplicative consistency-based goal programming models are proposed to assess their unknown values and to ascertain their consistency. Section VII provides three examples, a discussion, and a simulation analysis to show the effectiveness of the developed approaches. Finally, some conclusions are offered in Section VIII.

II. PRELIMINARIES

In order to make this article self-contained, some concepts associated with MPRs, HMSs, and HMPRs, which are used throughout this article, are reviewed.

For simplicity, let $X = \{x_1, \dots, x_n\}$ be a finite set of alternatives, and $N = \{1, \dots, n\}$.

Definition 1 [1]: An MPR $R = (r_{ij})_{n \times n} \subset X \times X$ is reciprocal if

$$r_{ij} \cdot r_{ji} = 1, r_{ii} = 1, r_{ij} \in [1/9, 9] \quad \forall i, j \in N. \quad (1)$$

Definition 2 [1]: An MPR $R = (r_{ij})_{n \times n}$ is perfect consistent if

$$r_{ij} = r_{ik} \cdot r_{kj} \quad \forall i, j, k \in N. \quad (2)$$

Let $w = (w_1, \dots, w_n)^T$ be the weight vector of the set of alternatives X , such that $w_i > 0$, and $\sum_{i=1}^n w_i = 1$. If MPR R on X is perfect consistent, then

$$r_{ij} = \frac{w_i}{w_j} \quad \forall i, j \in N. \quad (3)$$

An MPR is incomplete when some of its elements are missing.

Definition 3 [44]: An MPR $R = (r_{ij})_{n \times n}$ is incomplete when some of its elements cannot be given by the decision maker, while the rest of provided preference values, Ω , satisfy the conditions

$$r_{ij} \cdot r_{ji} = 1, r_{ii} = 1, r_{ij} > 0, \text{ for all } r_{ij} \in \Omega. \quad (4)$$

Definition 4 [45]: An incomplete MPR $R = (r_{ij})_{n \times n}$ is consistent if

$$r_{ij} = r_{ik} \cdot r_{kj}, \text{ for all } r_{ij}, r_{ik}, r_{kj} \in \Omega. \quad (5)$$

Motivated by the concepts of the hesitant fuzzy set and MPR, Xia and Xu [15] defined the concept of HMS.

Definition 5 [15]: An HMS M on X is mathematically expressed as

$$M = \{ \langle x, b_M(x) \rangle \mid x \in X \} \quad (6)$$

where $b_M(x)$ is a subset of finite cardinality of set $[1/9, 9]$, which denotes all the possible membership degrees of the element $x \in X$ to the set M .

For convenience, $b = b_M(x)$ is often called an HME. Motivated by Torra [14], Zhang and Wu [17] defined the upper and lower bounds of an HME.

Definition 6 [17]: The upper and lower bounds of an HME are $h_{ij}^+ = \max\{h_{ij}^t \mid t = 1, \dots, l_{h_{ij}}\}$ and $h_{ij}^- = \min\{h_{ij}^t \mid t = 1, \dots, l_{h_{ij}}\}$, respectively.

Combining HMSs and MPRs, the concept of HMPCR is defined.

Definition 7 [15]: An HMPCR $H = (h_{ij})_{n \times n} \subset X \times X$ is a preference relation with HMEs, $h_{ij} = \{h_{ij}^t \mid t = 1, 2, \dots, l_{h_{ij}}\}$, indicating all the possible degrees to which alternative x_i is preferred to alternative x_j subject to the constraints

$$h_{ij}^{\sigma(t)} h_{ji}^{\sigma(l_{h_{ij}} - t + 1)} = 1, h_{ii} = \{1\}, l_{h_{ij}} = l_{h_{ji}}, i, j \in N \quad (7)$$

where $h_{ij}^{\sigma(t)}$ denotes the t th smallest element in h_{ij} .

Similar to the definition of hesitant fuzzy preference relations discussed by Xu *et al.* [46], the values in each HME are ordered from smallest to largest as per Definition 7, which may result in property (7) not to be verified. At the same time, because of the disorder of sets, there is no need to arrange h_{ij} in ascending or descending order. Thus, a revised definition of HMPCR is introduced here.

Definition 8: An HMPCR $H = (h_{ij})_{n \times n} \subset X \times X$ is a preference relation with HMEs, $h_{ij} = \{h_{ij}^t \mid t = 1, 2, \dots, l_{h_{ij}}\}$, indicating the possible degrees to which alternative x_i is preferred to alternative x_j , subject to the following constraints:

$$h_{ij}^t h_{ji}^{l_{h_{ij}} - t + 1} = 1, h_{ii} = \{1\}, l_{h_{ij}} = l_{h_{ji}}, i, j \in N. \quad (8)$$

If some elements of an HMPCR cannot be given by a decision maker, then an incomplete HMPCR results. Zhang and Guo [41] introduced the concept of acceptable incomplete HMPCR.

Definition 9 [41]: An HMPCR $H = (h_{ij})_{n \times n} \subset X \times X$ is incomplete when some of its HMEs are unknown while its known HMEs $h_{ij} = \{h_{ij}^t \mid t = 1, 2, \dots, l_{h_{ij}}\}$ satisfy the constraints

$$h_{ij}^t h_{ji}^{l_{h_{ij}} - t + 1} = 1, h_{ii} = \{1\}, l_{h_{ij}} = l_{h_{ji}}, i, j \in N. \quad (9)$$

To improve readability, Table I lists the abbreviations used in this article.

III. MULTIPLICATIVE CONSISTENCIES OF HMPCR

This section introduces two multiplicative consistency concepts for HMPCR: 1) completely multiplicative consistency and 2) weakly multiplicative consistency.

Definition 10: Let $H = (h_{ij})_{n \times n}$ be an HMPCR. If there is a complete consistent MPR $R = (r_{ij})_{n \times n}$, such that

$$r_{ij} = r_{ik} \cdot r_{kj}, r_{ij} \in h_{ij} \quad \forall i, j, k \in N \quad (10)$$

TABLE I
NOMENCLATURE

Abbreviations	Illustration
AHP	Analytic Hierarchy Process
MPRs	Multiplicative preference relations
HMPCR	Hesitant multiplicative preference relations
HMSs	Hesitant multiplicative sets
HMEs	Hesitant multiplicative elements
CMC	Completely multiplicative consistent
WMC	Weakly multiplicative consistent
LCR	Length change ratio
NAR	Numerical adjustment ratio
AD	Absolute deviation
LAD	Logarithm absolute deviation
DR	Difference ratio

then H is called a completely multiplicative consistent (CMC) HMPCR and R is a complete consistent MPR in H .

The CMC HMPCR concept extracts existing elements from the HMPCR to form an MPR that satisfies the multiplicative transitivity property (2). As the information provided by a decision maker is uncertain, our goal is “to find the reasonable information in an HMPCR.” Definition 10 does not rely on Zhang’s β -normalization [26]. Therefore, no elements are added to HMEs. In any case, completely multiplicative consistency is difficult to be verified by an HMPCR. Let us consider the following example: when evaluating a set of three alternatives $X = \{x_1, x_2, x_3\}$, a decision maker expresses that alternative x_1 is weakly less important than alternative x_2 , and gives the preference value $h_{12} = 1/2$; while x_2 is strongly more important than alternative x_3 , and gives the preference value $h_{23} = 5$. In the AHP context, if his/her information is consistent, then it should be $h_{13} = h_{12} \times h_{23} = 5/2$. However, the value $5/2$ is not one of the original scale values in the AHP scale set $\{1/9, \dots, 1/2, 1, 2, \dots, 9\}$. In addition to the above, if the decision maker is unsure about the preference of alternative x_1 over alternative x_3 but considers x_1 more important than x_3 , and gives the following HME $\{2, 3\}$, then it is obviously that his/her preferences are not CMC ($5/2$ is between 2 and 3). In this case, we could regard the decision maker’s information to be close to complete consistent. In our view, because the upper and lower bounds of HMEs produce a range containing all possible decision maker’s preference information, the extraction of a consistent MPR from the upper and lower bounds of HMEs is a viable approach. In order to accommodate this scenario, another consistency property of HMPCR is introduced here.

Definition 11: Let $H = (h_{ij})_{n \times n}$ be an HMPCR. If there is a complete consistent MPR $R = (r_{ij})_{n \times n}$ satisfying

$$r_{ij} = r_{ik} \cdot r_{kj}, h_{ij}^- \leq r_{ij} \leq h_{ij}^+ \quad \forall i, j, k \in N \quad (11)$$

then H is called a weakly multiplicative consistent (WMC) HMPCR and R is a complete consistent MPR in H .

Considering the aforementioned relationship between r_{ij} and w as per (3), an equivalent definition of WMC HMPCR is given as follows.

Definition 12: An HMPCR $H = (h_{ij})_{n \times n}$ is called a WMC HMPCR, if there exists a weight vector $w = (w_1, \dots, w_n)^T$,

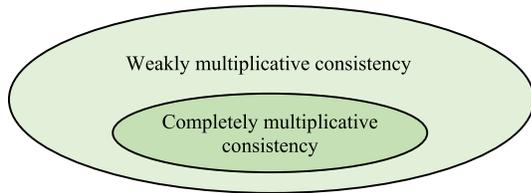


Fig. 1. Relationship of the two multiplicative consistencies for HMPRs.

such that

$$h_{ij}^- \leq \frac{w_i}{w_j} \leq h_{ij}^+ \quad \forall i, j \in N. \quad (12)$$

The reciprocity property of HMPRs allows the above definition to be rewritten equivalently as follows.

Definition 13: An HMPR $H = (h_{ij})_{n \times n}$ is called a WMC HMPR if there is a weighting vector $w = (w_1, \dots, w_n)^T$, such that

$$h_{ij}^- \leq \frac{w_i}{w_j} \leq h_{ij}^+, \quad i = 1, 2, \dots, n, j = i + 1, \dots, n. \quad (13)$$

It is obvious that a CMC HMPR is a special case of WMC HMPR, while a WMC HMPR might not necessarily be a CMC HMPR (see Fig. 1).

IV. CONSISTENCY ASCERTAINING

An important question to answer is whether an HMPR is CMC or WMC.

The direct verification of the CMC property as per Definition 11 is not an easy task. In order to facilitate calculation, the following 0-1 indicator variables of HMEs h_{ij} are introduced: $\alpha_{ij}^t = \begin{cases} 1, & \text{if } h_{ij}^t \in h_{ij} \text{ is chosen} \\ 0, & \text{otherwise} \end{cases}$. Each element in h_{ij} can be expressed as follows: $\prod_{t=1}^{l_{h_{ij}}} (h_{ij}^t)^{\alpha_{ij}^t}$ with $\sum_{t=1}^{l_{h_{ij}}} \alpha_{ij}^t = 1$.

According to Definition 10, if H is a CMC HMPR, then

$$\prod_{t=1}^{l_{h_{ij}}} (h_{ij}^t)^{\alpha_{ij}^t} = \prod_{t=1}^{l_{h_{ik}}} (h_{ik}^t)^{\alpha_{ik}^t} \times \prod_{t=1}^{l_{h_{kj}}} (h_{kj}^t)^{\alpha_{kj}^t}. \quad (14)$$

This is equivalent to

$$\sum_{t=1}^{l_{h_{ij}}} \alpha_{ij}^t \log(h_{ij}^t) - \sum_{t=1}^{l_{h_{ik}}} \alpha_{ik}^t \log(h_{ik}^t) - \sum_{t=1}^{l_{h_{kj}}} \alpha_{kj}^t \log(h_{kj}^t) = 0. \quad (15)$$

As aforementioned, (15) does not always hold. We relax (15) appropriately with the introduction of non-negative deviation numbers d_{ijk}^- and d_{ijk}^+ $\forall i, j, k \in N$

$$\sum_{t=1}^{l_{h_{ij}}} \alpha_{ij}^t \log(h_{ij}^t) - \sum_{t=1}^{l_{h_{ik}}} \alpha_{ik}^t \log(h_{ik}^t) - \sum_{t=1}^{l_{h_{kj}}} \alpha_{kj}^t \log(h_{kj}^t) - d_{ijk}^+ + d_{ijk}^- = 0. \quad (16)$$

Equation (16) becomes (15) iff $d_{ijk}^- = d_{ijk}^+ = 0$. Thus, the following 0-1 mixed programming model is established to

ascertain the completely multiplicative consistency property of HMPRs

$$\begin{aligned} \text{(M-1)} \quad J_1 = \min & \sum_{k=1}^n \sum_{i=1, i \neq k}^n \sum_{j=1, i \neq j, j \neq k}^n (d_{ijk}^- + d_{ijk}^+) \\ \text{s.t.} & \begin{cases} \sum_{t=1}^{l_{h_{ij}}} \alpha_{ij}^t \log(h_{ij}^t) - \sum_{t=1}^{l_{h_{ik}}} \alpha_{ik}^t \log(h_{ik}^t) \\ - \sum_{t=1}^{l_{h_{kj}}} \alpha_{kj}^t \log(h_{kj}^t) - d_{ijk}^+ + d_{ijk}^- = 0 \\ i, j, k \in N, i \neq k, i \neq j, j \neq k \\ \sum_{t=1}^{l_{h_{ij}}} \alpha_{ij}^t \log(h_{ij}^t) + \sum_{t=1}^{l_{h_{ji}}} \alpha_{ji}^{l_{h_{ij}}-t+1} \\ \log(h_{ji}^{l_{h_{ij}}-t+1}) = 0, i, j \in N, i \neq j \\ \sum_{t=1}^{l_{h_{ij}}} \alpha_{ij}^t = \sum_{t=1}^{l_{h_{ji}}} \alpha_{ji}^t = 1, i, j \in N, i \neq j \\ \alpha_{ij}^t = 0 \text{ or } 1, i, j \in N, i \neq j, \\ t = 1, 2, \dots, l_{h_{ij}} \\ d_{ijk}^-, d_{ijk}^+ \geq 0, i, j, k \in N, i \neq k, i \neq j, j \neq k. \end{cases} \end{aligned}$$

By solving (M-1), if $J_1 = 0$ for all i, j with $i \neq j$ and each $t = 1, 2, \dots, l_{h_{ij}}$, then H is CMC; otherwise, H is not CMC.

The reciprocity of H means that (M-1) can be equivalently rewritten as

$$\begin{aligned} \text{(M-2)} \quad J_2 = \min & \sum_{i=1}^{n-1} \sum_{k=i+1}^{j-1} \sum_{j=k+1}^n (d_{ijk}^- + d_{ijk}^+) \\ \text{s.t.} & \begin{cases} \sum_{t=1}^{l_{h_{ij}}} \alpha_{ij}^t \log(h_{ij}^t) - \sum_{t=1}^{l_{h_{ik}}} \alpha_{ik}^t \log(h_{ik}^t) \\ - \sum_{t=1}^{l_{h_{kj}}} \alpha_{kj}^t \log(h_{kj}^t) - d_{ijk}^+ + d_{ijk}^- = 0 \\ i, j, k \in N, i < k < j \\ \sum_{t=1}^{l_{h_{ij}}} \alpha_{ij}^t \log(h_{ij}^t) + \sum_{t=1}^{l_{h_{ji}}} \alpha_{ji}^{l_{h_{ij}}-t+1} \\ \log(h_{ji}^{l_{h_{ij}}-t+1}) = 0, i, j \in N, i \neq j \\ \sum_{t=1}^{l_{h_{ij}}} \alpha_{ij}^t = \sum_{t=1}^{l_{h_{ji}}} \alpha_{ji}^t = 1, i, j \in N, i < j \\ \alpha_{ij}^t = 0 \text{ or } 1, i, j \in N, i < j, \\ t = 1, 2, \dots, l_{h_{ij}} \\ d_{ijk}^-, d_{ijk}^+ \geq 0, i, j, k \in N, i < k < j. \end{cases} \end{aligned}$$

The following result proves the validity of model (M-2) to ascertain the completely multiplicative consistency property of HMPRs.

Theorem 1: An HMPR H is a CMC HMPR iff $J_2 = 0$.

Proof (Sufficiency): If $J_2 = 0$, then $d_{ijk}^- = d_{ijk}^+ = 0 \forall i, j, k \in N$ and (16) reduces to (15). Thus, H is CMC.

Necessary: If H is CMC, (15) holds and $d_{ijk}^- = d_{ijk}^+ = 0$ in (16), which implies that $J_2 = 0$. ■

When H is a CMC HMPR, a complete consistent MPR can be derived by solving (M-2). On the contrary, if H is not a CMC HMPR, in the following, some algebraic methods are proposed to detect whether it is a WMC HMPR.

Theorem 2: An HMPR $H = (h_{ij})_{n \times n}$ is a WMC HMPR iff

$$\max_k \{h_{ij}^-, h_{ik}^- h_{kj}^-\} \leq \min_k \{h_{ij}^+, h_{ik}^+ h_{kj}^+\} \quad \forall i, j, k \in N. \quad (17)$$

Proof: If H is a WMC HMPR, then there is a complete consistent MPR $R = (r_{ij})_{n \times n}$ such that

$$h_{ij}^- \leq r_{ij} \leq h_{ij}^+ \quad \forall i, j \in N \quad (18)$$

$$h_{ik}^- \leq r_{ik} \leq h_{ik}^+ \quad \forall i, k \in N \quad (19)$$

$$h_{kj}^- \leq r_{kj} \leq h_{kj}^+ \quad \forall k, j \in N. \quad (20)$$

Multiplying (19) by (20), we have

$$h_{ik}^- h_{kj}^- \leq r_{ij} \leq h_{ik}^+ h_{kj}^+ \quad \forall i, j, k \in N. \quad (21)$$

Since (21) holds for any $k \in N$, it is $\max_k \{h_{ij}^-, h_{ik}^- h_{kj}^-\} \leq \min_k \{h_{ij}^+, h_{ik}^+ h_{kj}^+\}$ for all $i, j, k \in N$.

Conversely, if (17) holds for all $i, j, k \in N$, there exists a complete consistent MPR $R = (r_{ij})_{n \times n}$ satisfying $r_{ij} = r_{ik} \cdot r_{kj}$, $h_{ij}^- \leq r_{ij} \leq h_{ij}^+ \quad \forall i, j, k \in N$. By Definition 11, H is a WMC HMPCR. ■

As per (17), we have the following equivalence theorem to ascertain the weakly multiplicative consistency property of HMPCR.

Theorem 3: An HMPCR $H = (h_{ij})_{n \times n}$ is a WMC HMPCR iff

$$\bigcap_{k=1}^n [h_{ik}^- h_{kj}^-, h_{ik}^+ h_{kj}^+] \neq \emptyset \quad \forall i, j, k \in N. \quad (22)$$

Proof: We only need to prove that (17) and (22) are equivalent. Suppose that H is a WMC HMPCR, then there is a complete consistent MPR $R = (r_{ij})_{n \times n}$ such that

$$h_{ij}^- \leq r_{ij} \leq h_{ij}^+ \quad \forall i, j \in N \quad (23)$$

$$h_{ik}^- \leq r_{ik} \leq h_{ik}^+ \quad \forall i, k \in N \quad (24)$$

$$h_{kj}^- \leq r_{kj} \leq h_{kj}^+ \quad \forall k, j \in N. \quad (25)$$

Therefore, it is

$$h_{ik}^- h_{kj}^- \leq r_{ij} \leq h_{ik}^+ h_{kj}^+ \quad \forall i, j, k \in N. \quad (26)$$

Since (26) holds for any $k \in N$, it is $r_{ij} \in \bigcap_{k=1}^n [h_{ik}^- h_{kj}^-, h_{ik}^+ h_{kj}^+] \neq \emptyset$, which is equivalent to $\max_k \{h_{ij}^-, h_{ik}^- h_{kj}^-\} \leq \min_k \{h_{ij}^+, h_{ik}^+ h_{kj}^+\}$. By Theorem 2, H is a WMC HMPCR, which completes the proof of Theorem 3. ■

The below interval MPR definition is needed for Theorem 4, which is an equivalent result to Theorems 2 and 3, to ascertain the weakly multiplicative consistency property of HMPCR. Recall that given two interval numbers $\bar{x} = [x^-, x^+]$ and $\bar{y} = [y^-, y^+]$ with $x^-, y^- > 0$, their product is $\bar{x} \cdot \bar{y} = [x^- y^-, x^+ y^+]$.

Definition 14 [47]: An interval MPR $\bar{H} = (\bar{h}_{ij})_{n \times n}$ is a preference relation with elements $\bar{h}_{ij} = [h_{ij}^-, h_{ij}^+]$ verifying: $0 < h_{ij}^- \leq h_{ij}^+$, $h_{ij}^- h_{ji}^+ = 1$, $h_{ij}^+ h_{ji}^- = 1$. The element \bar{h}_{ij} is called the interval preference ratio and denotes that alternative x_i is between h_{ij}^- and h_{ij}^+ times as important as alternative x_j .

Notice that given an HMPCR $H = (h_{ij})_{n \times n}$, the interval MPR $\bar{H} = (\bar{h}_{ij})_{n \times n}$ with elements $\bar{h}_{ij} = [h_{ij}^-, h_{ij}^+]$ can be constructed.

Theorem 4: An HMPCR $H = (h_{ij})_{n \times n}$ is a WMC HMPCR iff $\bar{H} = (\bar{h}_{ij})_{n \times n}$, $\bar{h}_{ij} = [h_{ij}^-, h_{ij}^+]$, satisfies

$$\bigcap_{k=1}^n (\bar{h}_{ik} \bar{h}_{kj}) \neq \emptyset \quad \forall i, j, k \in N. \quad (27)$$

Proof (Sufficiency): If $\bigcap_{k=1}^n (\bar{h}_{ik} \bar{h}_{kj}) \neq \emptyset$ for all $i, j, k \in N$, then it is $\bigcap_{k=1}^n (\bar{h}_{ik} \bar{h}_{kj}) = [p_{ij}^-, p_{ij}^+]$. Thus, it is $\max_k \{h_{ij}^-, h_{ik}^- h_{kj}^-\} \leq p_{ij}^+ \leq p_{ij}^- \leq \min_k \{h_{ij}^+, h_{ik}^+ h_{kj}^+\}$, i.e., Theorem 2 is true and \bar{H} is WMC.

Necessary: If H is a WMC HMPCR, then there is a complete consistent MPR $R = (r_{ij})_{n \times n}$ satisfying $h_{ij}^- \leq r_{ij} \leq h_{ij}^+$ and $r_{ij} = r_{ik} \cdot r_{kj} \in \bar{h}_{ik} \bar{h}_{kj} \quad \forall i, j, k \in N$. Therefore, $\bigcap_{k=1}^n (\bar{h}_{ik} \bar{h}_{kj}) \neq \emptyset$. ■

The reciprocity of HMPCR means that when ascertaining the validity of the above results only the elements of the upper or lower part of an HMPCR are to be considered.

V. GOAL PROGRAMMING APPROACH TO PRIORITY WEIGHT DERIVATION AND INCONSISTENCY REPAIRING OF HMPCR

Consistency is a key property of preference relations, so it is natural to generate priority weights of alternatives from consistent HMPCR. In this section, the following two research questions will be answered: 1) How to generate a priority weight vector from a consistent HMPCR? and 2) How to rectify the inconsistency of an HMPCR?

To answer these questions, effective optimization models based on multiplicative consistency are established: 1) to test the weakly multiplicative consistency property; 2) to derive priority weights of alternatives; and 3) to repair the inconsistency of a given HMPCR.

To find out whether a given HMPCR $H = (h_{ij})_{n \times n}$ is WMC, non-negative deviation values d_{ij}^- and d_{ij}^+ are introduced in (13)

$$h_{ij}^- - d_{ij}^- \leq \frac{w_i}{w_j} \leq h_{ij}^+ + d_{ij}^+, \quad i = 1, 2, \dots, n \\ j = i + 1, \dots, n. \quad (28)$$

Clearly, H is WMC iff d_{ij}^- and d_{ij}^+ are 0 in (28), for $i = 1, \dots, n$, $j = i + 1, \dots, n$. Therefore, the sum of these deviations is used as the objective function of the following optimization model:

$$(M-3) \quad J_3 = \min \sum_{i=1}^{n-1} \sum_{j=i+1}^n (d_{ij}^- + d_{ij}^+) \\ \text{s.t.} \quad \begin{cases} \frac{w_i}{w_j} + d_{ij}^- \geq h_{ij}^-, \quad i = 1, 2, \dots, n-1 \\ j = i + 1, \dots, n \\ \frac{w_i}{w_j} - d_{ij}^+ \leq h_{ij}^+, \quad i = 1, 2, \dots, n-1, \\ j = i + 1, \dots, n \\ \sum_{i=1}^n w_i = 1 \\ w_i \geq 0, \quad i = 1, 2, \dots, n \\ d_{ij}^-, d_{ij}^+ \geq 0, \quad i = 1, 2, \dots, n-1, \\ j = i + 1, \dots, n. \end{cases}$$

The following result proves the validity of model (M-3) to ascertain the weakly multiplicative consistency property of HMPCR.

Theorem 5: An HMPCR $H = (h_{ij})_{n \times n}$ is a WMC HMPCR iff $J_3 = 0$.

Proof (Necessary): If H is a WMC HMPCR, then (13) holds and it is $d_{ij}^- = d_{ij}^+ = 0$ in (28), which implies that $J_3 = 0$.

Sufficiency: If $J_3 = 0$, then $d_{ij}^- = d_{ij}^+ = 0 \quad \forall i, j \in N$, and (28) becomes (13). Hence, H is a WMC HMPCR. ■

Model (M-3) provides an alternative way, but equivalent to (13), to ascertain the weakly multiplicative consistency property of HMPCR. Unlike the algebraic operations in

Section IV, model (M-3) generates the priority weights of alternatives directly from the HMPCR. In any case, when $J_3 = 0$, H is WMC but not necessarily CMC, which can be ascertained with model (M-2).

Since a nonlinear programming model may have multiple solutions, there may be more than one set of weights w_i with $J_3 = 0$ in (M-3). As a result, (M-3) main aims are to ascertain whether an HMPCR has the weakly multiplicative consistency property and to repair inconsistency, but not to derive the priority weight vector. Hence, it is only necessary to observe the value of J_3 to test if the consistency type is WMC. Thus, a more reasonable and reliable method to derive the weights of alternatives is needed.

When an HMPCR is consistent, model (M-3) results in priority weights of alternatives as single values in the unit interval. However, following the argument provided in [17], interval priority weights are more natural and reasonable than precise weights for hesitant judgments provided by decision makers. Therefore, to generate interval priority weights of alternatives from consistent HMPRs, the below lower and upper approximation models are proposed

$$(M-4) \quad w_i^- = \min w_i$$

$$\text{s.t.} \quad \begin{cases} \frac{w_i}{w_j} \geq h_{ij}^-, i = 1, 2, \dots, n-1 \\ j = i+1, \dots, n \\ \frac{w_i}{w_j} \leq h_{ij}^+, i = 1, 2, \dots, n-1 \\ j = i+1, \dots, n \\ \sum_{i=1}^n w_i = 1 \\ w_i \geq 0, i = 1, 2, \dots, n. \end{cases}$$

$$(M-5) \quad w_i^+ = \max w_i$$

$$\text{s.t.} \quad \begin{cases} \frac{w_i}{w_j} \geq h_{ij}^-, i = 1, 2, \dots, n-1 \\ j = i+1, \dots, n \\ \frac{w_i}{w_j} \leq h_{ij}^+, i = 1, 2, \dots, n-1 \\ j = i+1, \dots, n \\ \sum_{i=1}^n w_i = 1 \\ w_i \geq 0, i = 1, 2, \dots, n. \end{cases}$$

Given a WMC HMPCR, solving models (M-4) and (M-5) will result in unique optimal interval priority weights of alternatives $w_i = [w_i^-, w_i^+] \forall i \in N$. Thus, if an HMPCR is not consistent, it is necessary first to repair its inconsistency. In the following, an inconsistency repairing method is proposed. The principles of the modification are two: 1) to reduce the total adjustments of an HMPCR, and 2) not to increase the number of the values in the adjusted HMPCR with respect to the original HMPCR.

Given an inconsistency HMPCR, model (M-3) allows to identify the inconsistent elements. Therefore, it can guide the inconsistency repairing process as described as follows.

- 1) If $J_3 \neq 0$, then there are optimal nonzero deviations d_{ij}^- and d_{ij}^+ when solving (M-3), which corresponds to HMPCR inconsistent elements. Indeed, if $d_{i_0j_0}^{+(-)} \neq 0$, then $h_{i_0j_0}$ is an inconsistent element. With regard to the inconsistent element, its range changes from $[h_{ij}^-, h_{ij}^+]$ to $[h_{ij}^- - d_{ij}^-, h_{ij}^+ + d_{ij}^+]$. In other words, the upper and lower bounds of HME are replaced by the new values $h_{ij}^+ + d_{ij}^+$ and $h_{ij}^- - d_{ij}^-$, while the other values remain unchanged,

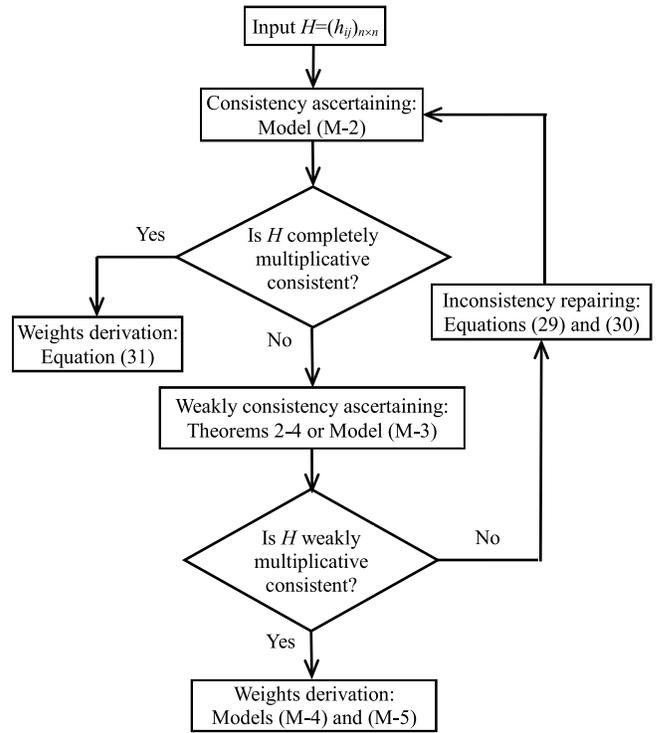


Fig. 2. Process of consistency ascertaining, inconsistency repairing, and weights derivation for HMPRs.

that is

$$\bar{h}_{ij} = \begin{cases} \left\{ h_{ij}^- - d_{ij}^- \text{ or } h_{ij}^+ + d_{ij}^+ \right\} \\ l_{h_{ij}} = 1 \\ \left\{ h_{ij}^- - d_{ij}^-, h_{ij}^{\sigma(2)}, \dots, h_{ij}^{\sigma(l_{h_{ij}}-1)}, h_{ij}^+ + d_{ij}^+ \right\} \\ l_{h_{ij}} \neq 1. \end{cases} \quad (29)$$

Thus, a new modified HMPCR \bar{H} is obtained

$$(\bar{h}_{ij}, \bar{h}_{ji}) = \begin{cases} (\bar{h}_{ij}, 1/\bar{h}_{ij}), & \text{if } h_{ij} \text{ is the inconsistent element} \\ (h_{ij}, h_{ji}), & \text{otherwise.} \end{cases} \quad (30)$$

- 2) In (29), there are two cases for adjusting the inconsistent elements. Notice that when there is only one element in the HME, the original value is replaced by the modified value. When there are two or more elements in the HME, the lower and upper bound values are replaced and the rest of values are unchanged. This approach maintains the original number of values in each HME, and preserves most of the decision maker's original preferences because only the inconsistent elements are adjusted.
- 3) After improving the consistency of the HMPCR, the priority weight vector derived from the newly adjusted HMPCR satisfies (13), and it is $J_3 = 0$. Consequently, (29) and (30) convert an inconsistent HMPCR into a consistent HMPCR.

Algorithm 1: Algorithms for consistency ascertaining, inconsistency repairing and weights derivation of HMPRS.

Step 1. Given an HMPRS H , check completely multiplicative consistency property with model (M-2). If H is CMC, go to Step 3A; otherwise, go to next step.

Step 2. Check weakly multiplicative consistency property by (17), (22), (27) or model (M-3). If H is WMC, go to Step 3B; otherwise, go to Step 4.

Step 3. Priority weights derivation and ranking of alternatives.

Step 3A. (Following Step 1).

Derive the priority weights with the Logarithmic Least Squares Method [48, 49]:

$$w_i = \left(\prod_{j=1}^n r_{ij} \right)^{1/n} / \sum_{i=1}^n \left(\prod_{j=1}^n r_{ij} \right)^{1/n}, \quad i = 1, 2, \dots, n \quad (31)$$

and go to Step 5.

Step 3B. (Following Step 2).

Generate the interval weights with models (M-4) and (M-5). Alternatives are ranked according to their priority weights ranking, via the degree of possibility of $w_i \geq w_j$ [5, 50]:

$$p(w_i \geq w_j) = \frac{\max\{0, w_i^+ - w_j^-\} - \max\{0, w_i^- - w_j^+\}}{w_i^+ - w_i^- + w_j^+ - w_j^-} \quad (32)$$

$$p_i = \sum_{j=1}^n p_{ij}, \quad i \in N \quad (33)$$

and $p_{ij} = p(w_i \geq w_j)$.

Interval weights are ranked using p_i values, i.e. $w_i \overset{p(w_i \geq w_j)}{>} w_j$ iff $p_i > p_j$. Go to Step 5.

Step 4. Solve model (M-3), and repair inconsistency with (29); construct the newly adjusted HMPRS with (30). Go to Step 1.

Step 5. End.

In what follows, an integrated algorithm to ascertain consistency, inconsistency repairing, and priority weights derivation for HMPRSs is proposed, with corresponding flowchart depicted in Fig. 2.

VI. INCOMPLETE HMPRS

In a decision-making problem, decision makers may omit some judgments, i.e., some information may be unknown. Hence, a key problem to address is the estimation of missing information. With respect to incomplete HMPRSs, this section extends two multiplicative consistency concepts of complete HMPRSs to the case of incomplete HMPRSs and utilizes two multiplicative consistency-based goal programming models: 1) to estimate their missing HME preference values, and 2) to ascertain the type of multiplicative consistency property that is verified.

Let $H = (h_{ij})_{n \times n}$ be an incomplete HMPRS. The notation $h_{ij} = x$ is used to represent that h_{ij} is not given by the decision maker. To incorporate (16) into incomplete HMPRSs, the following indicator functions for an incomplete HMPRS H are introduced:

$$\delta_{ij} = \begin{cases} 1, & h_{ij} \neq x \\ 0, & h_{ij} = x \end{cases}$$

$$\delta_{ijk} = \begin{cases} 1, & \delta_{ij}\delta_{ik}\delta_{kj} = 1 \\ 0, & \text{otherwise.} \end{cases}$$

When h_{ij} , h_{ik} , and h_{kj} are all known it is $\delta_{ijk} = 1$. Then, (16) for an incomplete HMPRS can be rewritten as

$$\delta_{ijk} \left(\sum_{t=1}^{l_{h_{ij}}} \alpha_{ij}^t \log(h_{ij}^t) - \sum_{t=1}^{l_{h_{ik}}} \alpha_{ik}^t \log(h_{ik}^t) - \sum_{t=1}^{l_{h_{kj}}} \alpha_{kj}^t \log(h_{kj}^t) \right) - \varepsilon_{ijk}^+ + \varepsilon_{ijk}^- = 0. \quad (34)$$

Consequently, to ascertain the completely multiplicative consistency property of incomplete HMPRSs, the following 0-1 mixed programming model is constructed:

$$(M-6) J_6 = \min \sum_{k=1}^n \sum_{i=1, i \neq k}^n \sum_{j=1, j \neq k}^n (\varepsilon_{ijk}^- + \varepsilon_{ijk}^+)$$

$$\text{s.t.} \begin{cases} \delta_{ijk} \left(\sum_{t=1}^{l_{h_{ij}}} \alpha_{ij}^t \log(h_{ij}^t) - \sum_{t=1}^{l_{h_{ik}}} \alpha_{ik}^t \log(h_{ik}^t) - \sum_{t=1}^{l_{h_{kj}}} \alpha_{kj}^t \log(h_{kj}^t) \right) - \varepsilon_{ijk}^+ \\ + \varepsilon_{ijk}^- = 0, \quad i, j, k \in N, \quad i \neq j, \quad i \neq k, \quad j \neq k \\ \delta_{ij} \left(\sum_{t=1}^{l_{h_{ij}}} \alpha_{ij}^t \log(h_{ij}^t) + \sum_{t=1}^{l_{h_{ji}}} \alpha_{ji}^{l_{h_{ij}}-t+1} \log(h_{ji}^{l_{h_{ij}}-t+1}) \right) = 0, \quad i, j \in N, \quad i \neq j \\ \sum_{t=1}^{l_{h_{ij}}} \alpha_{ij}^t = \sum_{t=1}^{l_{h_{ji}}} \alpha_{ji}^t = 1, \quad i, j \in N, \quad i \neq j \\ \alpha_{ij}^t = 0 \text{ or } 1, \quad i, j \in N, \quad i \neq j \\ \varepsilon_{ijk}^-, \varepsilon_{ijk}^+ \geq 0, \quad i, j, k \in N, \quad i \neq j, \quad i \neq k, \quad j \neq k \\ \delta_{ij} = \begin{cases} 1, & h_{ij} \neq x \\ 0, & h_{ij} = x \end{cases}, \quad i, j \in N \\ \delta_{ijk} = \begin{cases} 1, & \delta_{ij}\delta_{ik}\delta_{kj} = 1 \\ 0, & \text{otherwise} \end{cases}, \quad i, j, k \in N. \end{cases}$$

This model can be equivalently simplified as follows:

$$(M-7) J_7 = \min \sum_{k=1}^n \sum_{i=1}^{n-1} \sum_{j=i+1}^n (\varepsilon_{ijk}^- + \varepsilon_{ijk}^+)$$

$$\text{s.t.} \begin{cases} \delta_{ijk} \left(\sum_{t=1}^{l_{h_{ij}}} \alpha_{ij}^t \log(h_{ij}^t) - \sum_{t=1}^{l_{h_{ik}}} \alpha_{ik}^t \log(h_{ik}^t) - \sum_{t=1}^{l_{h_{kj}}} \alpha_{kj}^t \log(h_{kj}^t) \right) - \varepsilon_{ijk}^+ \\ + \varepsilon_{ijk}^- = 0, \quad i, j, k \in N, \quad i < j, \quad k \neq i, \quad k \neq j \\ \delta_{ij} \left(\sum_{t=1}^{l_{h_{ij}}} \alpha_{ij}^t \log(h_{ij}^t) + \sum_{t=1}^{l_{h_{ji}}} \alpha_{ji}^{l_{h_{ij}}-t+1} \log(h_{ji}^{l_{h_{ij}}-t+1}) \right) = 0, \quad i, j \in N, \quad i < j \\ \sum_{t=1}^{l_{h_{ij}}} \alpha_{ij}^t = \sum_{t=1}^{l_{h_{ji}}} \alpha_{ji}^t = 1, \quad i, j \in N, \quad i < j \\ \alpha_{ij}^t = 0 \text{ or } 1, \quad i, j \in N, \quad i \neq j \\ t = 1, 2, \dots, l_{h_{ij}} \\ \varepsilon_{ijk}^-, \varepsilon_{ijk}^+ \geq 0, \quad i, j, k \in N, \quad i < j \\ k \neq i, \quad k \neq j \\ \delta_{ij} = \begin{cases} 1, & h_{ij} \neq x \\ 0, & h_{ij} = x \end{cases}, \quad i, j \in N \\ \delta_{ijk} = \begin{cases} 1, & \delta_{ij}\delta_{ik}\delta_{kj} = 1 \\ 0, & \text{otherwise} \end{cases}, \quad i, j, k \in N. \end{cases}$$

The following result proves the validity of model (M-7) to ascertain the completely multiplicative consistency property of incomplete HMPRSs.

Theorem 6: An incomplete HMPR H is CMC iff $J_7 = 0$.

Proof (Necessary): If an incomplete HMPR H is CMC, then (15) holds for all known elements, that is, $\varepsilon_{ijk}^- = \varepsilon_{ijk}^+ = 0$ in (34). Therefore, $J_7 = 0$.

Sufficiency: If an incomplete HMPR H has $J_7 = 0$, then $\varepsilon_{ijk}^- = \varepsilon_{ijk}^+ = 0$ for all known elements, and (34) becomes (15). Thus, the incomplete HMPR H is CMC. ■

The following example illustrates the process of estimating missing values and determining the consistency of incomplete HMPRs with model (M-7).

Example 1: Consider the incomplete HMPR H_1 (adapted from [41])

$$H_1 = \begin{pmatrix} \{1\} & \left\{\frac{1}{2}, 1\right\} & \left\{\frac{1}{3}, \frac{1}{2}\right\} & \{1\} \\ \{1, 2\} & \{1\} & \{1, 2, 3\} & \{2\} \\ \{2, 3\} & \left\{\frac{1}{3}, \frac{1}{2}, 1\right\} & \{1\} & x \\ \{1\} & \left\{\frac{1}{2}\right\} & x & \{1\} \end{pmatrix}.$$

Solving model (M-7) gives $J_7 = 0$. Thus, the incomplete HMPR H_1 is CMC. At the same time, the missing HMEs obtained are $h_{34} = \{2\}$ and $h_{43} = \{1/2\}$, and there exists a complete consistent MPR R_1

$$R_1 = \begin{pmatrix} 1 & \frac{1}{2} & \frac{1}{2} & 1 \\ 2 & 1 & 1 & 2 \\ 2 & 1 & 1 & 2 \\ 1 & \frac{1}{2} & \frac{1}{2} & 1 \end{pmatrix}.$$

Thus, H_1 is transformed into the below complete HMPR

$$H'_1 = \begin{pmatrix} \{1\} & \left\{\frac{1}{2}, 1\right\} & \left\{\frac{1}{3}, \frac{1}{2}\right\} & \{1\} \\ \{1, 2\} & \{1\} & \{1, 2, 3\} & \{2\} \\ \{2, 3\} & \left\{\frac{1}{3}, \frac{1}{2}, 1\right\} & \{1\} & \{2\} \\ \{1\} & \left\{\frac{1}{2}\right\} & \left\{\frac{1}{2}\right\} & \{1\} \end{pmatrix}.$$

The proposed model is more reasonable and effective than Sahu and Gupta's model [22], since their β -normalization method is superfluous, and no additional elements are added to HMEs. In addition, the proposed model can determine the consistency type of incomplete HMPRs, while Sahu and Gupta's model fails to do so.

When the incomplete HMPR H is not CMC, its weakly multiplicative consistency property is considered. Similar to Theorems 2–4 of Section IV, the following results for incomplete HMPRs are provided.

Theorem 7: An incomplete HMPR $H = (h_{ij})_{n \times n}$ is WMC iff for all known elements

$$\max_k \left\{ h_{ij}^-, h_{ik}^- h_{kj}^- \right\} \leq \min_k \left\{ h_{ij}^+, h_{ik}^+ h_{kj}^+ \right\} \quad (35)$$

or, equivalently

$$\bigcap_{k=1}^n \left[h_{ik}^- h_{kj}^-, h_{ik}^+ h_{kj}^+ \right] \neq \emptyset \quad (36)$$

is verified.

Given an incomplete HMPR, $H = (h_{ij})_{n \times n}$, its associated incomplete interval MPR $\bar{H} = (\bar{h}_{ij})_{n \times n}$ has elements: $\bar{h}_{ij} = [h_{ij}^-, h_{ij}^+]$ if \bar{h}_{ij} is known; otherwise, $\bar{h}_{ij} = x$ is unknown. Let Ω be the set of all the known elements in \bar{H} .

Theorem 8: An incomplete HMPR $H = (h_{ij})_{n \times n}$ is WMC iff

$$\bigcap_{k=1}^n (\bar{h}_{ik} \bar{h}_{kj}) \neq \emptyset, \text{ for all } \bar{h}_{ij} \in \Omega. \quad (37)$$

The following optimization model for incomplete HMPRs can be established, based on the weakly multiplicative consistency property, to estimate the missing information and to test consistency:

$$\begin{aligned} \text{(M-8)} \quad J_8 = \min & \sum_{i=1}^{n-1} \sum_{j=i+1}^n (\varepsilon_{ij}^- + \varepsilon_{ij}^+) \\ \text{s.t.} & \begin{cases} \delta_{ij} \left(\frac{w_i}{w_j} + \varepsilon_{ij}^- - h_{ij}^- \right) \geq 0 \\ i = 1, 2, \dots, n-1, j = i+1, \dots, n \\ \delta_{ij} \left(\frac{w_i}{w_j} - \varepsilon_{ij}^+ - h_{ij}^+ \right) \leq 0 \\ i = 1, 2, \dots, n-1, j = i+1, \dots, n \\ \sum_{i=1}^n w_i = 1 \\ w_i \geq 0, i \in N \\ \delta_{ij} = \begin{cases} 1, & h_{ij} \neq x \\ 0, & h_{ij} = x, \end{cases} i, j \in N \\ \varepsilon_{ij}^-, \varepsilon_{ij}^+ \geq 0, i = 1, 2, \dots, n-1 \\ j = i+1, \dots, n. \end{cases} \end{cases} \end{aligned}$$

Solving model (M-8), the incomplete HMPR is WMC when $J_8 = 0$, in which case, via (3), its missing elements can be estimated. As before, an example is provided below to illustrate the weakly multiplicative consistency-based HMPR completion process.

Example 2: Consider the incomplete HMPR H_2

$$H_2 = \begin{pmatrix} \{1\} & \left\{\frac{3}{7}\right\} & \left\{\frac{3}{7}, \frac{3}{2}\right\} & \{1\} \\ \left\{\frac{7}{3}\right\} & \{1\} & \left\{\frac{3}{7}, \frac{3}{2}\right\} & x \\ \left\{\frac{2}{3}, \frac{7}{3}\right\} & \left\{\frac{2}{3}, \frac{7}{3}\right\} & \{1\} & \left\{\frac{2}{3}, \frac{7}{3}\right\} \\ \{1\} & x & \left\{\frac{3}{7}, \frac{3}{2}\right\} & \{1\} \end{pmatrix}.$$

Solving model (M-7) gives $J_7 = 2.4692 \neq 0$. Thus, H_2 is not CMC, and Theorem 7 is used to check whether H_2 is WMC. For all known elements, (36) yields

$$\begin{aligned} \bigcap_{k=1}^4 [h_{1k}^- h_{k3}^-, h_{1k}^+ h_{k3}^+] &= \left[\frac{3}{7}, \frac{3}{2} \right] \cap \left[\frac{9}{49}, \frac{9}{14} \right] \cap \left[\frac{3}{7}, \frac{3}{2} \right] \\ &= \left[\frac{3}{7}, \frac{3}{2} \right] \cap \left[\frac{9}{49}, \frac{9}{14} \right] \neq \emptyset. \end{aligned}$$

Thus, the incomplete HMPR H_2 is WMC. Notice that this can also be verified using (35) as shown in Table II.

Solving model (M-8) gives $J_8 = 0$, and the missing HMEs are estimated as $h_{24} = \{7/3\}$ and $h_{42} = \{3/7\}$. The following complete HMPR H'_2 and complete consistent MPR R_2 are obtained:

$$H'_2 = \begin{pmatrix} \{1\} & \left\{\frac{3}{7}\right\} & \left\{\frac{3}{7}, \frac{3}{2}\right\} & \{1\} \\ \left\{\frac{7}{3}\right\} & \{1\} & \left\{\frac{3}{7}, \frac{3}{2}\right\} & \left\{\frac{7}{3}\right\} \\ \left\{\frac{2}{3}, \frac{7}{3}\right\} & \left\{\frac{2}{3}, \frac{7}{3}\right\} & \{1\} & \left\{\frac{2}{3}, \frac{7}{3}\right\} \\ \{1\} & \left\{\frac{3}{7}\right\} & \left\{\frac{3}{7}, \frac{3}{2}\right\} & \{1\} \end{pmatrix}$$

TABLE II
CONSISTENCY ASCERTAINING FOR EXAMPLE 2

preferences	i	j	k	$h_{ik}^-h_{kj}^-$	$h_{ik}^+h_{kj}^+$	Consistency test
\bar{h}_{12}	1	2	1	$\frac{3}{7}$	$\frac{3}{7}$	$\max\{h_{ij}^-, h_{ik}^-h_{kj}^-\} = \frac{3}{7}$
	1	2	3	$\frac{2}{7}$	$\frac{3}{2}$	$\min\{h_{ij}^+, h_{ik}^+h_{kj}^+\} = \frac{3}{7}$
	passed					
\bar{h}_{13}	1	3	1	$\frac{3}{7}$	$\frac{3}{2}$	$\max\{h_{ij}^-, h_{ik}^-h_{kj}^-\} = \frac{3}{7}$
	1	3	2	$\frac{9}{7}$	$\frac{9}{14}$	$\min\{h_{ij}^+, h_{ik}^+h_{kj}^+\} = \frac{9}{14}$
	1	3	4	$\frac{49}{7}$	$\frac{3}{2}$	passed
\bar{h}_{14}	1	4	1	1	1	$\max\{h_{ij}^-, h_{ik}^-h_{kj}^-\} = 1$
	1	4	3	$\frac{2}{7}$	$\frac{7}{2}$	$\min\{h_{ij}^+, h_{ik}^+h_{kj}^+\} = 1$
passed						
\bar{h}_{23}	2	3	1	1	$\frac{7}{2}$	$\max\{h_{ij}^-, h_{ik}^-h_{kj}^-\} = 1$
	2	3	2	$\frac{3}{7}$	$\frac{3}{2}$	$\min\{h_{ij}^+, h_{ik}^+h_{kj}^+\} = \frac{3}{2}$
passed						
\bar{h}_{34}	3	4	1	$\frac{2}{3}$	$\frac{7}{3}$	$\max\{h_{ij}^-, h_{ik}^-h_{kj}^-\} = \frac{2}{3}$
	3	4	3	$\frac{2}{3}$	$\frac{7}{3}$	$\min\{h_{ij}^+, h_{ik}^+h_{kj}^+\} = \frac{7}{3}$
passed						

and

$$R_2 = \begin{pmatrix} 1 & \frac{3}{7} & \frac{3}{7} & 1 \\ \frac{7}{3} & 1 & 1 & \frac{7}{3} \\ \frac{7}{3} & 1 & 1 & \frac{7}{3} \\ 1 & \frac{3}{7} & \frac{3}{7} & 1 \end{pmatrix}.$$

After estimating the missing values, an incomplete HMPR is converted into a complete HMPR, and Algorithm 1 can be used to generate the priority weights of alternatives. The consistency improving method proposed in Section V can be applied to incomplete HMPRS found to be inconsistent with both models (M-7) and (M-8).

VII. ILLUSTRATIVE EXAMPLES AND COMPARATIVE ANALYSIS

A. Illustrative Examples

This section offers three examples that complement the theoretical effectiveness of the approaches presented in previous sections: Examples 3 and 4 concern with CMC and WMC HMPRS, respectively, while Example 5 verifies the practical value of our proposal.

Example 3: Consider the following HMPR on $X = \{x_1, x_2, x_3\}$ (adapted from Zhang [26]):

$$H_3 = \begin{pmatrix} \{1\} & \{\frac{1}{7}, \frac{1}{5}, \frac{1}{4}, \frac{1}{3}\} & \{\frac{1}{6}, \frac{1}{3}, 1\} \\ \{3, 4, 5, 7\} & \{1\} & \{2, 3, 5\} \\ \{1, 3, 6\} & \{\frac{1}{5}, \frac{1}{3}, \frac{1}{2}\} & \{1\} \end{pmatrix}.$$

Step 1: Solving model (M-2) gives $J_2 = 0$. Thus, H_3 is CMC. Meanwhile, the following complete consistent MPR is derived:

$$R = \begin{pmatrix} 1 & \frac{1}{3} & 1 \\ 3 & 1 & 3 \\ 1 & \frac{1}{3} & 1 \end{pmatrix}.$$

TABLE III
CONSISTENCY ASCERTAINING FOR EXAMPLE 4

preferences	i	j	k	$h_{ik}^-h_{kj}^-$	$h_{ik}^+h_{kj}^+$	Consistency test
\bar{h}_{12}	1	2	1	$\frac{2}{3}$	$\frac{5}{2}$	$\max\{h_{ij}^-, h_{ik}^-h_{kj}^-\} = \frac{2}{3}$
	1	2	3	$\frac{1}{4}$	7	$\min\{h_{ij}^+, h_{ik}^+h_{kj}^+\} = \frac{3}{2}$
	1	2	4	$\frac{4}{15}$	$\frac{3}{2}$	passed
\bar{h}_{13}	1	3	1	$\frac{3}{4}$	$\frac{7}{2}$	$\max\{h_{ij}^-, h_{ik}^-h_{kj}^-\} = \frac{3}{4}$
	1	3	2	$\frac{1}{3}$	$\frac{15}{2}$	$\min\{h_{ij}^+, h_{ik}^+h_{kj}^+\} = \frac{7}{2}$
	1	3	4	$\frac{1}{3}$	$\frac{9}{2}$	passed
\bar{h}_{14}	1	4	1	$\frac{1}{3}$	$\frac{3}{2}$	$\max\{h_{ij}^-, h_{ik}^-h_{kj}^-\} = \frac{2}{3}$
	1	4	2	$\frac{2}{3}$	$\frac{25}{4}$	$\min\{h_{ij}^+, h_{ik}^+h_{kj}^+\} = \frac{3}{2}$
	1	4	3	$\frac{1}{4}$	$\frac{7}{2}$	passed
\bar{h}_{23}	2	3	1	$\frac{3}{10}$	$\frac{21}{4}$	$\max\{h_{ij}^-, h_{ik}^-h_{kj}^-\} = 1$
	2	3	2	$\frac{1}{2}$	3	$\min\{h_{ij}^+, h_{ik}^+h_{kj}^+\} = 3$
\bar{h}_{24}	2	4	1	$\frac{2}{15}$	$\frac{9}{4}$	$\max\{h_{ij}^-, h_{ik}^-h_{kj}^-\} = 1$
	2	4	2	1	$\frac{5}{2}$	$\min\{h_{ij}^+, h_{ik}^+h_{kj}^+\} = \frac{9}{4}$
\bar{h}_{34}	3	4	1	$\frac{2}{21}$	2	$\max\{h_{ij}^-, h_{ik}^-h_{kj}^-\} = \frac{1}{3}$
	3	4	2	$\frac{1}{3}$	5	$\min\{h_{ij}^+, h_{ik}^+h_{kj}^+\} = 1$
passed						

Step 2: From (31), the following priority weight vector of alternatives is obtained: $w = (0.2, 0.6, 0.2)^T$, and the alternatives ranking would be: $x_2 \succ x_1 \sim x_3$.

Example 4: Consider the following HMPR (adapted from Lin and Wang [19]):

$$H_4 = \begin{pmatrix} \{1\} & \{\frac{2}{3}, 2, \frac{5}{2}\} & \{\frac{3}{4}, \frac{5}{2}, \frac{7}{2}\} & \{\frac{1}{3}, \frac{3}{2}\} \\ \{\frac{2}{5}, \frac{1}{2}, \frac{3}{2}\} & \{1\} & \{\frac{1}{2}, 2, 3\} & \{1, 2, \frac{5}{2}\} \\ \{\frac{2}{7}, \frac{2}{5}, \frac{4}{3}\} & \{\frac{1}{3}, \frac{1}{2}, 2\} & \{1\} & \{\frac{1}{3}, \frac{1}{2}, 1\} \\ \{\frac{2}{3}, 3\} & \{\frac{2}{5}, \frac{1}{2}, 1\} & \{1, 2, 3\} & \{1\} \end{pmatrix}.$$

Step 1: Solving model (M-2), we have $J_2 = 0.5754$, which means that HMPR H_4 is not CMC.

Step 2: Expression (17) is used to check the weakly multiplicative consistency property for H_4 , with the corresponding processes shown in Table III. It is concluded that HMPR H_4 is WMC. Notice that this could have been done using (22). Indeed, HMPR H_4 is WMC because

$$\bigcap_{k=1}^4 [h_{1k}^-h_{k2}^-, h_{1k}^+h_{k2}^+] = \left[\frac{2}{3}, \frac{5}{2}\right] \cap \left[\frac{2}{3}, \frac{5}{2}\right] \cap \left[\frac{1}{4}, 7\right] \cap \left[\frac{2}{15}, \frac{3}{2}\right] \neq \emptyset$$

$$\begin{aligned} \bigcap_{k=1}^4 [h_{1k}^- h_{k3}^-, h_{1k}^+ h_{k3}^+] &= \left[\frac{3}{4}, \frac{7}{2} \right] \cap \left[\frac{1}{3}, \frac{15}{2} \right] \cap \left[\frac{3}{4}, \frac{7}{2} \right] \\ &\quad \cap \left[\frac{1}{3}, \frac{9}{2} \right] \neq \emptyset \\ \bigcap_{k=1}^4 [h_{1k}^- h_{k4}^-, h_{1k}^+ h_{k4}^+] &= \left[\frac{1}{3}, \frac{3}{2} \right] \cap \left[\frac{2}{3}, \frac{25}{4} \right] \cap \left[\frac{1}{4}, \frac{7}{2} \right] \\ &\quad \cap \left[\frac{1}{3}, \frac{3}{2} \right] \neq \emptyset \\ \bigcap_{k=1}^4 [h_{2k}^- h_{k3}^-, h_{2k}^+ h_{k3}^+] &= \left[\frac{3}{10}, \frac{21}{4} \right] \cap \left[\frac{1}{2}, 3 \right] \cap \left[\frac{1}{2}, 3 \right] \\ &\quad \cap \left[1, \frac{15}{2} \right] \neq \emptyset \\ \bigcap_{k=1}^4 [h_{2k}^- h_{k4}^-, h_{2k}^+ h_{k4}^+] &= \left[\frac{2}{15}, \frac{9}{4} \right] \cap \left[1, \frac{5}{2} \right] \cap \left[1, \frac{5}{2} \right] \\ &\quad \cap \left[\frac{1}{6}, 3 \right] \neq \emptyset \\ \bigcap_{k=1}^4 [h_{3k}^- h_{k4}^-, h_{3k}^+ h_{k4}^+] &= \left[\frac{2}{21}, 2 \right] \cap \left[\frac{1}{3}, 5 \right] \cap \left[\frac{1}{3}, 1 \right] \\ &\quad \cap \left[\frac{1}{3}, 1 \right] \neq \emptyset. \end{aligned}$$

Since HMPR H_4 is WMC, the priority weights of alternatives are derived by solving models (M-3)–(M-5).

Step 3: Solving model (M-3) gives $J_3 = 0$, and $w = (0.25, 0.25, 0.25, 0.25)^T$. From (3), we obtain the following complete consistent MPR:

$$R = \begin{pmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{pmatrix}.$$

Solving models (M-4) and (M-5), the following interval priority vector of alternatives is obtained from H_4 : $w(H_4) = ([0.1875, 0.3818], [0.2222, 0.4091], [0.0952, 0.2667], [0.1739, 0.3333])$. Using expression (32), the ranking of the alternatives would be: $x_2 \stackrel{0.5813}{>} x_1 \stackrel{0.5878}{>} x_4 \stackrel{0.7196}{>} x_3$. Thus, alternative x_2 is superior to alternative x_1 with 58.13% possibility degree, alternative x_1 is superior to alternative x_4 with 58.78% possibility degree, while alternative x_4 is superior alternative x_3 with 71.96% possibility degree.

Example 5: A practical problem is considered where an investment company is looking to invest a sum of money in the best of the following four possible investment options.

- 1) x_1 is an energy company.
- 2) x_2 is a medical corporation.
- 3) x_3 is a high-tech company.
- 4) x_4 is a food company.

The investment company evaluates the four alternative companies with the help of a third-party evaluation agency, which

provides the following HMPR information:

$$H_5 = \begin{pmatrix} \{1\} & \{3\} & \{5, 7\} & \{3\} \\ \left\{ \frac{1}{3} \right\} & \{1\} & \left\{ \frac{1}{9}, \frac{1}{7} \right\} & \{5\} \\ \left\{ \frac{1}{7}, \frac{1}{5} \right\} & \{7, 9\} & \{1\} & \left\{ \frac{1}{7}, \frac{1}{5} \right\} \\ \left\{ \frac{1}{3} \right\} & \left\{ \frac{1}{5} \right\} & \{5, 7\} & \{1\} \end{pmatrix}.$$

Step 1: Solving model (M-2) gives $J_2 = 10.3296$. Thus, H_5 is not CMC.

Step 2: Solving model (M-3) gives $J_3 = 5.9238$. Thus, H_5 is not WMC. This means that we are in the presence of an inconsistent HMPR.

Step 3: The optimal deviation values are $d_{23}^+ = 1.5238$, $d_{34}^+ = 0.4$, and $d_{24}^- = 4$; so, h_{23} , h_{24} , and h_{34} are the inconsistent elements of HMPR H_5 . From (29), the adjusted elements are $\bar{h}_{23} = \{1/9, 1.667\}$, $\bar{h}_{24} = \{1\}$, and $\bar{h}_{34} = \{1/7, 3/5\}$. From (30), the improved HMPR \bar{H}_5 is

$$\bar{H}_5 = \begin{pmatrix} \{1\} & \{3\} & \{5, 7\} & \{3\} \\ \left\{ \frac{1}{3} \right\} & \{1\} & \left\{ \frac{1}{9}, 1.667 \right\} & \{1\} \\ \left\{ \frac{1}{7}, \frac{1}{5} \right\} & \{0.6, 9\} & \{1\} & \left\{ \frac{1}{7}, \frac{3}{5} \right\} \\ \left\{ \frac{1}{3} \right\} & \{1\} & \left\{ \frac{5}{3}, 7 \right\} & \{1\} \end{pmatrix}.$$

Step 4: Solving model (M-2) implies that \bar{H}_5 is not CMC.

Step 5: Solving model (M-3) gives $J_3 = 0$. Thus, \bar{H}_5 is WMC.

Step 6: Solving models (M-4) and (M-5), the interval priority weight vector of the alternatives for \bar{H}_5 is $w(\bar{H}_5) = ([0.5357, 0.5382], [0.1786, 0.1794], [0.1029, 0.1071], [0.1786, 0.1794])$. Applying (32) results in the following ranking of the four alternatives: $x_1 \stackrel{1}{>} x_2 \sim x_4 \stackrel{1}{>} x_3$. This means that investment options x_1 is superior to investment options x_2 with 100% possibility degree, investment options x_2 is equally preferred to investment options x_4 , and investment options x_4 is superior to investment options x_3 with 100% possibility degree. Therefore, the optimal investment would be x_1 .

In decision-making problems, the consistency problem is closely related to the reliability of preferences provided by decision makers. The rationality of the judgments determines the reliability of the final decision result. It is worth noting that the consistency improvement of HMPRs in this process plays a role in regulating the logic and rationality of the given preference information. Therefore, in practice, our proposal contributes to achieving reliable decision-making results.

In what follows, a discussion and a simulation analysis are reported to illustrate the availability and advantages of the proposed method.

B. Discussion, Simulation, and Comparative Analysis

In this section, we compare the peculiarities of existing methods and discuss the advantages of our proposed methods. A summary of the improvements of the proposed method based on the previous illustrative examples is provided. In addition, a systematic analysis with the help of simulation experiments is carried out, which clearly and intuitively highlights the superior performance of the proposed method.

1) *Discussion*: In view of the evident differences with the existing consistency studies, the proposed approach improvements can be summarized as follows.

- 1) As far as we are aware, the proposed approach is the first attempt to study simultaneously both completely multiplicative consistency and weakly multiplicative consistency properties for HMPRSs, which represents a more effective and precise way to describe and detect consistency. Meng *et al.* [25] studied the multiplicative consistency property of HMPRSs. They proposed a strict consistency concept for HMPRSs that requires the existence of multiplicative consistent MPRSs for every value in every HMEs. This means that in practice most HMPRSs will fail to verify Meng *et al.*'s [25] definition of consistency property. For example, H_3 (Example 3), which was judged to be CMC, does not satisfy Meng *et al.*'s consistency definition. Although theoretically there exist HMPRSs that verify Meng *et al.*'s consistency definition, this is not reasonable in practice. Hesitancy means that a decision maker is unsure about the preference values when comparing two alternatives, though he/she can give some possible preference values (hence the hesitation). If for every value in every HME, a consistent MPRS exists, then this would imply a level of consistency knowledge by the decision maker that would make hesitancy improbable and therefore impractical in a hesitancy environment. As the decision maker is hesitant, we should aim to find the reasonable information (i.e., consistent information) from his/her hesitant information, which is exactly the aim of the proposed method.
- 2) Zhang and Wu proposed two consistency improvement methods in [17] and [21]. These methods rely on a β -normalization process, which converts the HMEs so that they all have the same number of values, and then the HMPRS is managed as several MPRSs. The normalization process obviously distorts the DM's original information and the results obtained could be unrelated to the original information, which makes them unreliable. In this article, the proposed method does not rely on any normalization process, which translates into minimal changes of the original information of DMs and lower computational cost. Moreover, Xu *et al.* [46] pointed out that Zhang and Wu's [21] consistency process is artificial, the consistent HMPRS may not be an HMPRS because the improved MPRSs will not be arranged in ascending order. Additionally, the smaller the improvement process consistency threshold in [21] is, the larger the number of iterations and the computational cost are.
- 3) The priority weights of alternatives derived from the proposed method are of interval nature. As the DM's information is hesitant, it is more logical and natural to derive interval weights from consistent HMPRSs than exact priority weights as proposed by Zhu and Xu [18]. Although Zhang and Wu's [17] weight-derivation algorithm for HMPRSs results in an interval priority weight vector for H_5 , $w = ([0.3938, 0.4581], [0.1715, 0.1729], [0.1882, 0.2108], [0.1823, 0.2225])$, which leads to the

TABLE IV
COMPARISON BETWEEN THE EXISTING STUDIES AND OUR PROPOSAL

	The proposed method	Zhang and Wu [21]	Meng et al. [25]	Zhang and Wu [17]	Sahu and Gupta [22]
Ascertain consistency	✓	✓	✓	✓	✓
Consistency thresholds	×	✓	×	×	✓
α or β normalization	×	✓	×	✓	✓
Repair inconsistency	✓	✓	×	✓	×
Minimal deviation from decision-maker's original judgments	✓	×	×	×	×
Ability to maintain decision-makers' hesitation in weights derivation	✓	×	✓	✓	×
Ability to address incomplete HMPRSs	✓	×	✓	×	✓
Acceptable computational complexity	✓	-	-	-	-

optimal choice x_1 , which is consistent with the proposed approach, although it is based on an additional normalization process, which implies higher computational cost.

- 4) The proposed approach can be utilized to solve decision-making problems with incomplete HMPRSs via the two multiplicative consistency goal programming models developed to ascertain the consistency property and to estimate the missing values. The existent literature method by Sahu and Gupta [22] requires a normalization process to improve the consistency, and therefore is subjected to the previously mentioned drawbacks. Thus, the proposed approach can deal with incomplete information in HMPRS, which allows DMs or decision organizations to express their preferences more flexibly, and therefore more effectively.

In summary, the above analysis shows that the performance of the proposal approach can compete with other approaches. The comparative analysis, based on eight performance criteria, of these methods is summarized in Table IV. The label "✓" means that the method is very suitable, "-" means that the method is acceptable, while "×" means that the method performs poorly on the given criterion.

From Table IV, it can see that the functionality of the proposed approach is powerful, and that it can help to 1) determine the consistency type without the help of consistency threshold setting and normalization process; 2) repair inconsistency with lower information distortion and computation; 3) derive interval weights based on the decision maker's hesitation; and 4) solve decision-making problems with incomplete HMPRSs. Consequently, the proposed approach can deal

with decision-making problems with HMPRs more flexibly, reasonably, and effectively.

2) *Simulation and Comparative Analysis*: In order to further show the effectiveness and advantages of the proposed method, Monte Carlo simulation experiments are carried out and analyzed. Further, the proposed method is compared with the methods by Zhang and Wu [17] and Zhang and Wu [21], since their methods also proposed different consistency concepts and consistency improving processes. The β -normalization method is used in [17] and [21] with $\bar{h}_{ij} = (h_{ij}^+)^{\zeta} \times (h_{ij}^-)^{(1-\zeta)}$ used to add some values to the HMEs of shorter length to make all the HMEs have the same length. In this article, we assume $\zeta = 0.5$. Both Zhang and Wu [17] and Zhang and Wu [21] split the HMPR into several MPRs. Zhang and Wu [17] used Saaty's consistency ratio ($CR < 0.1$) to check whether these MPRs are of acceptable consistency. If any of the MPR is not acceptable consistent, Xu and Wei [51]'s Algorithm I (with $\lambda = 0.5$) is used to improving its consistency. Notice that Zhang and Wu [21] proposed another algorithm (referred to as [21, Algorithm 2]) to improve consistency. In the method, a consistency threshold \bar{CI} is set in advance ($\bar{CI} = 1.01$). Meng *et al.*'s [25] method only find the consistent MPRs in an HMPR, with no method to repair the inconsistency proposed when there is no such consistent MPR in an HMPR. Sahu and Gupta [22] proposed a method to estimate the missing values in an incomplete HMPR, and Zhang and Wu's [17] is adopted to check whether the complete HMPR is of acceptable consistency. If the complete HMPR is not consistent, no consistency improving method is provided. Therefore, in the following, we only do simulations and compare the proposed method with Zhang and Wu [17] and Zhang and Wu [21]'s methods.

A total of 1000 HMPRs with different dimensions, ranging from 3 to 9, are randomly generated. In order to be close to the actual decision-making scenario, we assume that the number of elements in each HME is less than 3. Furthermore, all the randomly generated values are in Saaty's scale $\{1/9, 1/8, \dots, 1/2, 1, \dots, 9\}$. In order to compare the performances of the different methods, we propose the following criteria.

1) *Length Change Ratio*:

$$LCR = \frac{2 \sum_{i=1}^{n-1} \sum_{j=i+1}^n \bar{f}_{ij}}{n(n-1)}$$

where $\bar{f}_{ij} = \begin{cases} 0, & l_{h_{ij}^{(0)}} = l_{h_{ij}^*} \\ 1, & \text{otherwise} \end{cases}$ denotes whether the length

of an HME is changed; and $H^{(0)} = (h_{ij}^{(0)})$ and $H^* = (h_{ij}^*)$ are the original and the final adjusted HMPRs, respectively.

2) *Numerical Adjustment Ratio*:

$$NAR = \frac{2 \sum_{i=1}^{n-1} \sum_{j=i+1}^n f_{ij}}{n(n-1)}$$

where $f_{ij} = \begin{cases} 0, & h_{ij}^{(0)} = h_{ij}^* \\ 1, & \text{otherwise} \end{cases}$ denotes whether the values in an HME $h_{ij}^{(0)}$ are adjusted.

TABLE V
AVERAGE LCR, NAR, AD, LAD, DR, AND ITERATION VALUES OF DIFFERENT METHODS

n	methods	LCR	NAR	AD	LAD	DR	Iterations
3	This paper	0	0.149	0.122	0.440	1.227	1
	Zhang and Wu [21]	0.4863	1	3.867	1.908	2.076	2.973
	Zhang and Wu [17]	0.4863	1	2.703	1.319	1.726	3.078
4	This paper	0	0.301	0.283	0.986	1.4223	1
	Zhang and Wu [21]	0.6213	1	4.685	2.967	2.3226	3.033
	Zhang and Wu [17]	0.6213	1	3.965	1.992	2.0718	4.557
5	This paper	0	0.436	0.407	1.46	1.603	1
	Zhang and Wu [21]	0.6565	1	5.013	3.599	2.5201	3.051
	Zhang and Wu [17]	0.6565	1	4.477	2.504	2.2276	5.257
6	This paper	0	0.518	0.524	1.848	1.743	1
	Zhang and Wu [21]	0.6684	1	5.370	4.098	2.7102	3.078
	Zhang and Wu [17]	0.6684	1	4.928	2.913	2.4092	5.652
7	This paper	0	0.636	0.603	1.963	1.7717	1
	Zhang and Wu [21]	0.6606	1	5.552	4.369	2.8243	3.123
	Zhang and Wu [17]	0.6606	1	5.114	3.120	2.5068	5.848
8	This paper	0	0.836	0.699	2.464	1.9121	1
	Zhang and Wu [21]	0.6669	1	5.654	4.611	2.9306	3.153
	Zhang and Wu [17]	0.6669	1	5.212	3.294	2.5901	5.939
9	This paper	0	0.991	0.775	2.888	2.0213	1
	Zhang and Wu [21]	0.6661	1	5.740	4.779	3.0114	3.2580
	Zhang and Wu [17]	0.6661	1	5.265	3.377	2.6375	5.972

3) *Absolute Deviation*:

$$AD = \frac{2}{n(n-1)} \sum_{i=1}^{n-1} \sum_{j=i+1}^n |h_{ij}^{(0)} - h_{ij}^*|.$$

Absolute deviation (AD) measures the average numerical difference between the original HMPR $H^{(0)}$ and the final improved HMPR H^* . Since the lengths in each h_{ij} between $H^{(0)}$ and H^* are different in Zhang and Wu [17] and Zhang and Wu [21], the β -normalization HMPR is used on the original HMPR to compute AD for the proposed approach.

4) *Logarithm Absolute Deviation*:

$$LAD = \frac{2}{n(n-1)} \sum_{i=1}^{n-1} \sum_{j=i+1}^n (\ln(h_{ij}^{(0)}) - \ln(h_{ij}^*))^2.$$

5) *Difference Ratio*: Li *et al.* [52] introduced a ratio-based concept to gauge the difference between two interval multiplicative comparison matrices. Based on this idea, the below difference ratio (DR) is proposed to measure the difference between the original HMPR and the improved HMPR

$$DR(H^{(0)}, H^*) = \left(\prod_{i < j} \left(\frac{\max\{h_{ij}^{(0)-}, h_{ij}^{*-}\}}{\min\{h_{ij}^{(0)-}, h_{ij}^{*-}\}} \right) \times \left(\frac{\max\{h_{ij}^{(0)+}, h_{ij}^{*+}\}}{\min\{h_{ij}^{(0)+}, h_{ij}^{*+}\}} \right) \right)^{\frac{1}{n(n-1)}}.$$

Obviously, $DR(H^{(0)}, H^*) \geq 1$. The smaller the ratio $DR(H^{(0)}, H^*)$, the closer $H^{(0)}$ is to H^* . In particular, if $DR(H^{(0)}, H^*) = 1$, $H^{(0)} = H^*$.

Table V lists the average values of length change ratio (LCR), numerical adjustment ratio (NAR), AD, logarithm AD (LAD), and DR for each of the three considered methods, which are represented in Fig. 3 to help visualize the different methods' performance.

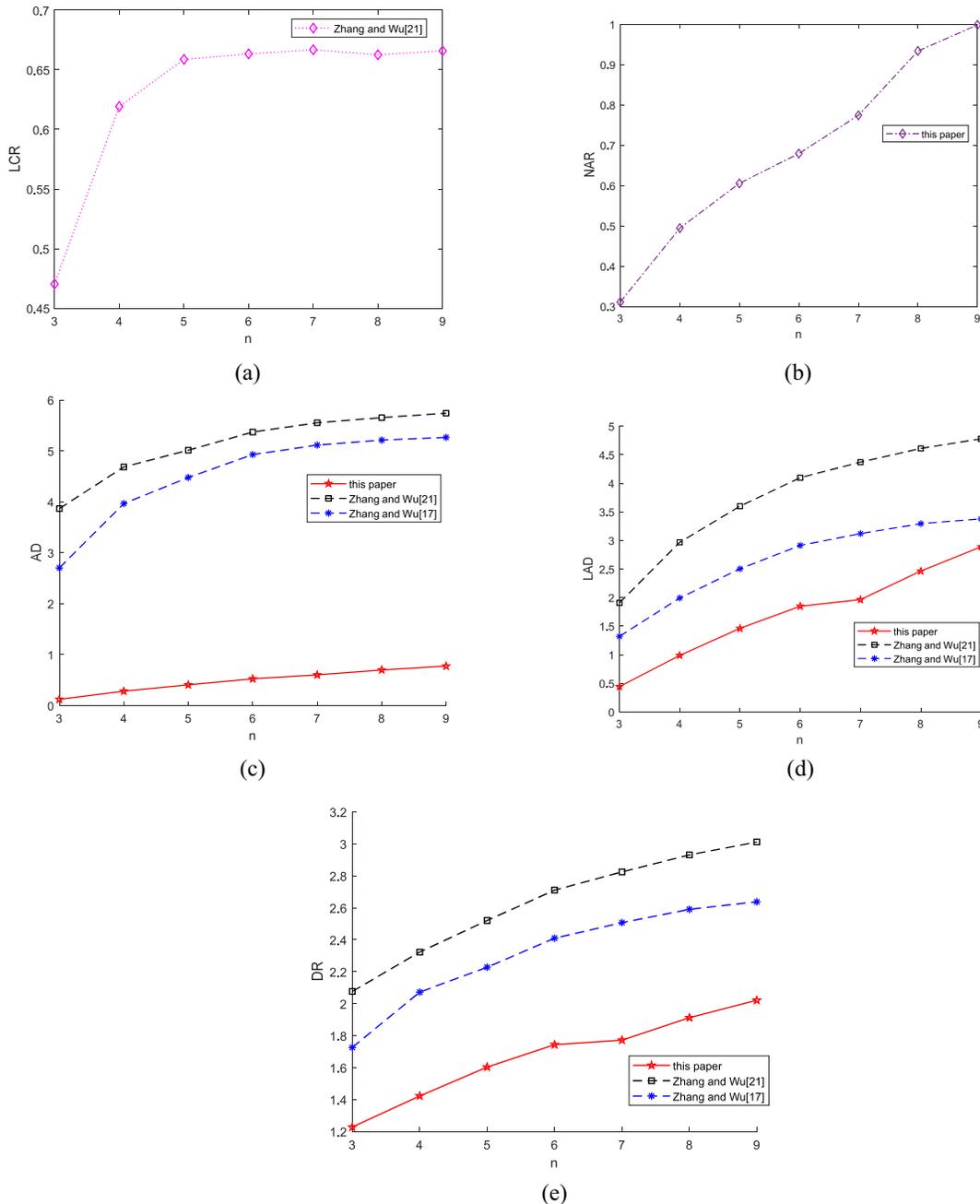


Fig. 3. (a) LCR of Zhang and Wu [17]. (b) NAR of this article. (c) AD. (d) LAD. (e) DR.

In Fig. 3(a), since the length of HMEs is not changed by the proposed method, the corresponding LCR value is always equal to 0 at every one of the considered dimensions. Zhang and Wu [17] and Zhang and Wu [21] used the same normalization methods, thus their LCR values coincide and therefore there is only need to draw the LCR values for one of them. The LCR values increase drastically from 3 to 5, while they change little when n is from 5 to 9. In Fig. 3(b), the NAR values in Zhang and Wu [17] and Zhang and Wu [21] are always equal to 1, which means that all the values are revised in their consistency improving processes. However, the NAR values increases from 0.149 ($n = 3$) to 0.991 ($n = 9$) for the proposed method. These two indexes show that the proposed

method perform best in retain the decision makers' original information as much as possible.

In Fig. 3(c)–(e), the AD, LAD, and DR values all increase with the value of n . However, in all cases, the proposed method results in the smallest values, with Zhang and Wu [21] resulting in the largest. Therefore, the proposed method produces improved consistent HMPRS closest to the original HMPRS. These results reinforce the achievement of the aim of the proposed method to retain the decision makers' original information as much as possible.

3) *Computational Complexity*: Regarding computational complexity as measured by the average number of iterations required to complete the overall process, again the proposed

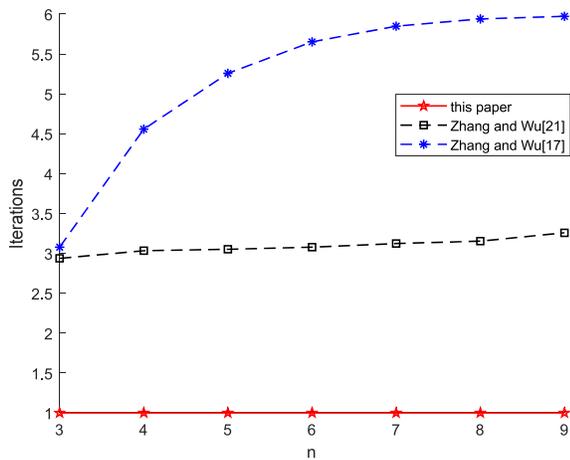


Fig. 4. Average iterations of different methods.

method is superior to the method by Zhang and Wu. This information is provided in the last column of Table V and depicted in Fig. 4. The proposed method requires in all cases 1 iteration to improve consistency, Zhang and Wu's [21] method is stable at three iterations on average, while Zhang and Wu's [17] method need 3 to 6 iterations on average increasing with the dimension value.

As mentioned earlier, Zhang and Wu [21] required that all HMEs have the same length before the process of consistency ascertaining. This normalization method, and therefore its associated complicated calculation process, is superfluous for the proposed method. Since the length of HMEs increases with the normalization process, the HMPCR will be converted into a high number of MPRs to judge its consistency, which will increase the computation cost when compared to the proposed method. On the other hand, Zhang and Wu [21] preset a consistency threshold in the process of consistency checking and improvement. Decreasing the threshold value implies an increase of the number of iterations and, as a consequence, the computational cost will increase. In contrast, the consistency properties of HMPCRs proposed in this article can directly be ascertain without the need of a normalization process or a consistency threshold, while the inconsistency repairing method only revises the inconsistent elements, and therefore most of the decision maker's judgments are unchanged. Most importantly, the proposed approach can achieve multiplicative consistency ascertaining, inconsistency repairing, and weights derivation for HMPCRs in one iteration.

Meng *et al.* [25] also implemented the consistency test based on the decision maker's original HMPCR without the normalization process. Their consistency determination and improvement process can also be completed within one iteration. However, Meng *et al.*'s approach requires to detect that for each value in each HME a multiplicatively consistent MPR needs to be detected. As the length of the HMEs increases, the number of multiplicatively consistent MPRs to be found increases. Namely, there are a total of $\prod_{i < j} l_{hij}$ MPRs that need to be judged, and at least the minimum of l_{hij} models to operate. Hence, this method may not be suitable to be

applied in practical decision-making problems due to its high computational cost.

To summarize, compared with the existing methods, the proposed method has lowest computational complexity and cost. Therefore, the proposed method is a highly functional and computationally convenient method.

VIII. CONCLUSION

In this article, two types of multiplicative consistency of HMPCRs, completely multiplicative consistency and weakly multiplicative consistency, are investigated simultaneously. A number of 0-1 mixed programming models are established to ascertain these consistency properties. The following cases are addressed.

- 1) If an HMPCR is CMC, then the corresponding multiplicative consistent MPR can be found.
- 2) If an HMPCR is not CMC but WMC, then interval priority weights of alternatives are derived, which allows to rank them.
- 3) If an HMPCR is not consistent, only the inconsistent elements are revised to repair the inconsistency, which means that most of the decision maker's judgments are unchanged.
- 4) These models have also been extended to the case of incomplete HMPCRs by estimating the missing values.

In the future, the research areas to focus on include:

- 1) how to apply the proposed method to other types of preference relations [53], [54];
- 2) in addition to the consistency analysis of individual decision makers, consensus analysis with HMPCRs is also an important research topic in group decision making [55]–[59];
- 3) investigate new algorithms for group decision-making problems to tackle practical problems [60]–[62].

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