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# Note on the shape circularity measure method based on radial moments 

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#### Abstract

In this note we show that the, so called, circularity measures based on radial moments, as defined in [1], are a particular case of the circularity measures introduced by [2].

Keywords: Shape, Circularity measure, Hu moment invariants, Pattern recognition, Image processing.


## 1 Introduction

A family of circularity measures $\mathcal{C}_{\beta}(S)$ was introduced recently in [2]. More precisely, if $S$ denotes a planar shape, $\mu_{0,0}(S)$ is the area of $S$, and $\beta$ is a number from the interval $(-1, \infty)$, then the quantities $\mathcal{C}_{\beta}(S)$ indicate/measure how much the considered shape $S$ differs from a planar circular disc, of the same area as the given shape $S$. The formal definition, of the circularity measures $\mathcal{C}_{\beta}(S)$, is as follows.

Definition 1 Let $S$ be a given shape whose centroid coincides with the origin and a real $\beta$ such that $-1<\beta$ and $\beta \neq 0$. Then the circularity measure $\mathcal{C}_{\beta}(S)$ is defined as

$$
\mathcal{C}_{\beta}(S)= \begin{cases}\frac{\mu_{0,0}(S)^{\beta+1}}{(\beta+1) \pi^{\beta} \iint_{S}\left(x^{2}+y^{2}\right)^{\beta} d x d y}, & \beta>0  \tag{1}\\ \frac{(\beta+1) \pi^{\beta} \iint_{S}\left(x^{2}+y^{2}\right)^{\beta} d x d y}{\mu_{0,0}(S)^{\beta+1}}, & \beta \in(-1,0) .\end{cases}
$$

[^0]The formula in (1) is given in Cartesian coordinates. If the polar coordinate system is involved (instead of the Cartesian coordinate system):
$x=r \cdot \cos \theta, \quad y=r \cdot \sin \theta \quad($ the Jacobian for this coordinate transformation is $|J|=r)$
then

$$
\iint_{S}\left(x^{2}+y^{2}\right)^{\beta} d x d y=\int_{\theta} \int_{r}\left((r \cdot \cos \theta)^{2}+(r \cdot \sin \theta)^{2}\right)^{\beta} \cdot r d r d \theta=\int_{\theta} \int_{r} r^{2 \beta+1} d r d \theta
$$

and consequently (1) becomes

$$
\mathcal{C}_{\beta}(S)= \begin{cases}\frac{\mu_{0,0}(S)^{\beta+1}}{(\beta+1) \pi^{\beta} \int_{\theta} \int_{r} r^{2 \beta+1} d r d \theta}, & \beta>0  \tag{2}\\ \frac{(\beta+1) \pi^{\beta} \int_{\theta} \int_{r} r^{2 \beta+1} d r d \theta}{\mu_{0,0}(S)^{\beta+1}}, & \beta \in(-1,0)\end{cases}
$$

Now, by setting $\beta=\frac{p}{2}$, the first expression (for $\beta>0$ ) in (2) becomes

$$
\begin{equation*}
\mathcal{C}_{\beta}(S)=\mathcal{C}_{p / 2}(S)=\frac{\frac{2}{p+2} \cdot \pi^{-p / 2} \cdot \mu_{0,0}(S)^{\frac{p+2}{2}}}{\int_{\theta} \int_{r} r^{p+1} d r d \theta} \tag{3}
\end{equation*}
$$

Circularity measures based on radial moments, introduced in [1], are denoted by $\zeta_{p}(D)$ and formally defined, by the expression in (9) from [1], as

$$
\begin{equation*}
\zeta_{p}(D)=\frac{\frac{2}{p+2} \cdot \pi^{-p / 2} \cdot\left[u_{0}(D)\right]^{\frac{p+2}{2}}}{u_{p}(D)} \tag{4}
\end{equation*}
$$

Further, [1] uses the following denotation

- $u_{p}(D)=\iint_{D}(r-\bar{r})^{p} d s, \quad$ with $\quad d s=r \cdot d r \cdot d \theta \quad \bar{r}=\sqrt{x_{c}^{2}+y_{c}^{2}}, \quad$ and $\left(x_{c}, y_{c}\right)=\left(\frac{\iint_{D} x d s}{\iint_{D} d s}, \frac{\iint_{D} y d s}{\iint_{D} d s}\right) \quad$ being the centroid of the considered shape $D$.
(Notice: $u_{0}(D)=\mu_{0,0}(D)$ and $u_{p}(D)=\int_{\theta} \int_{r} r^{p+1} d r d \theta$, if $\bar{r}=0$, i.e. $\left(x_{c}, y_{c}\right)=(0,0)$.)
Finally, since $\zeta_{p}(D)$ is translation invariant (see Theorem 2 from [1]) we can set $\bar{r}=0$ (i.e we can assume that the shape $D$ is translated such that its gravity center $\left(x_{c}, y_{c}\right)$ coincides with the origin $(0,0)$ ), and deduce that (for $p>0$ )

$$
\begin{equation*}
\zeta_{p}(D)=\mathcal{C}_{p / 2}(D) \tag{5}
\end{equation*}
$$

In other words, the formula in (4) is equivalent to the formula in (3), and further, shape circularity measures $\zeta_{p}(D)$ based on radial moments, from [1], are particular subcases of the family of circularity measures $\mathcal{C}_{\beta}(S)$, introduced by [2] (measures from [2] are defined for $\beta=\frac{p}{2}$ negative, as well).

It is worth mentioning that the identity in (5) is evident in the experimental results from Table 1 in [1], which includes $\mathcal{C}_{p}(D)$ denoted by $H_{p}(D)$. Although there is a systematic offset between $\zeta_{p}(D)$ and $\mathcal{C}_{p / 2}(D)$, possibly caused by digitization and numerical errors, the results for $\zeta_{p=2}(D)$ are similar to $\mathcal{C}_{p=1}(D)$, such that their ratios are all the same to within 3 significant places. Likewise, the ratios of $\zeta_{p=4}(D)$ and $\mathcal{C}_{p=2}(D)$ are the same to within 3 significant places.

## References

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